FEATURES

- N-Channel MOSFET Drive
- Implements Boost, Step-Down, SEPIC and Inverting Regulators
- Wide VIN Range: 3.5V to 36V Operation
- Wide VOUT Range: 1.19V to 30V in Step-Down Configuration
- ±1% 1.19V Reference
- Low Dropout Operation: 95% Duty Cycle
- 200kHz Fixed Frequency
- Low Standby Current
- Very High Efficiency
- Remote Output Voltage Sense
- Logic-Controlled Micropower Shutdown
- Internal Diode for Bootstrapped Gate Drive
- Current Mode Operation for Excellent Line and Load Transient Response
- Available in an 8-Lead SO Package

APPLICATIONS

- Notebook and Palmtop Computers, PDAs
- Cellular Telephones and Wireless Modems
- Battery-Operated Digital Devices
- DC Power Distribution Systems
- Battery Chargers

DESCRIPTION

The LTC®1624 is a current mode switching regulator controller that drives an external N-channel power MOSFET using a fixed frequency architecture. It can be operated in all standard switching configurations including boost, step-down, inverting and SEPIC. Burst Mode™ operation provides high efficiency at low load currents. A maximum high duty cycle limit of 95% provides low dropout operation which extends operating time in battery-operated systems.

The operating frequency is internally set to 200kHz, allowing small inductor values and minimizing PC board space. The operating current level is user-programmable via an external current sense resistor. Wide input supply range allows operation from 3.5V to 36V (absolute maximum).

A multifunction pin (ITH/RUN) allows external compensation for optimum load step response plus shutdown. Soft start can also be implemented with the ITH/RUN pin to properly sequence supplies.

![Figure 1. High Efficiency Step-Down Converter](image-url)
**ABSOlUTE MAXIMUM RATINGS**

Input Supply Voltage \((V_{IN})\) ......................... 36V to –0.3V  
Topside Driver Supply Voltage (BOOST) .... 42V to –0.3V  
Switch Voltage (SW) ................................. 36V to –0.6V  
Differential Boost Voltage  

\((\text{BOOST to SW}) \) ............................. 7.8V to –0.3V  
SENSE\(^–\) Voltage  

\(V_{IN} < 15\text{V}\) .......................... \((V_{IN} + 0.3\text{V})\) to –0.3V  
\(V_{IN} \geq 15\text{V}\) .......................... \((V_{IN} + 0.3\text{V})\) to \((V_{IN} – 15\text{V})\)  
\(I_{TH/RUN}, V_{FB}\) Voltages .......................... 2.7V to –0.3V  
Peak Driver Output Current < 10\(\mu\text{s}\) (TG) ............. 2A  
Operating Temperature Range  

LTC1624CS ............................................ 0\(^\circ\)C to 70\(^\circ\)C  
LTC1624IS ......................................... –40\(^\circ\)C to 85\(^\circ\)C  
Junction Temperature (Note 1)............................. 125\(^\circ\)C  
Storage Temperature Range .......................... –65\(^\circ\)C to 150\(^\circ\)C  
Lead Temperature (Soldering, 10 sec)............. 300\(^\circ\)C

**PACKAGE/ORDER INFORMATION**

<table>
<thead>
<tr>
<th>ORDER PART NUMBER</th>
</tr>
</thead>
<tbody>
<tr>
<td>LTC1624CS8</td>
</tr>
<tr>
<td>LTC1624IS8</td>
</tr>
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</table>

**Consult factory for Military grade parts.**

**ELECTRICAL CHARACTERISTICS** \(T_A = 25\(^\circ\)C, V_{IN} = 15\text{V}, \text{unless otherwise noted.} \)

<table>
<thead>
<tr>
<th>SYMBOL</th>
<th>PARAMETER</th>
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<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNITS</th>
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<tr>
<td>(I_{IN}V_{FB})</td>
<td>Feedback Current</td>
<td>(Note 2)</td>
<td>10</td>
<td>50</td>
<td>nA</td>
<td></td>
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<td>(V_{FB})</td>
<td>Feedback Voltage</td>
<td>(Note 2)</td>
<td>1.1781</td>
<td>1.19</td>
<td>1.2019</td>
<td>V</td>
</tr>
<tr>
<td>(\Delta V_{\text{LINE REG}})</td>
<td>Reference Voltage Line Regulation</td>
<td>(V_{IN} = 3.6\text{V} ) to 20\text{V} (Note 2)</td>
<td>0.002</td>
<td>0.01</td>
<td>%/V</td>
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<tr>
<td>(\Delta V_{\text{LOAD REG}})</td>
<td>Output Voltage Load Regulation</td>
<td>(Note 2)</td>
<td>0.5</td>
<td>0.8</td>
<td>%</td>
<td></td>
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<tr>
<td>(I_{ITH})</td>
<td>Output Overvoltage Lockout</td>
<td>1.24</td>
<td>1.28</td>
<td>1.32</td>
<td>V</td>
<td></td>
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<tr>
<td>(I_{OC})</td>
<td>Input DC Supply Current</td>
<td>Normal Mode</td>
<td>550</td>
<td>900</td>
<td>(\mu\text{A})</td>
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<td></td>
<td>Shutdown</td>
<td>(V_{ITH/RUN} = 0\text{V})</td>
<td>16</td>
<td>30</td>
<td>(\mu\text{A})</td>
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<tr>
<td>(V_{ITH/RUN})</td>
<td>Run Threshold</td>
<td>0.6</td>
<td>0.8</td>
<td>V</td>
<td></td>
<td></td>
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<td>(I_{ITH/RUN})</td>
<td>Run Current Source</td>
<td>(V_{ITH/RUN} = 0.3\text{V})</td>
<td>–0.8</td>
<td>–2.5</td>
<td>–5.0</td>
<td>(\mu\text{A})</td>
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<td></td>
<td>Run Pullup Current</td>
<td>(V_{ITH/RUN} = 1\text{V})</td>
<td>–5.0</td>
<td>–160</td>
<td>–350</td>
<td>(\mu\text{A})</td>
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<td>(\Delta V_{\text{SENSE(MAX)}})</td>
<td>Maximum Current Sense Threshold</td>
<td>(V_{FB} = 1.0\text{V})</td>
<td>145</td>
<td>160</td>
<td>185</td>
<td>mV</td>
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<td>(T_{G_T})</td>
<td>TG Transition Time</td>
<td>Rise Time</td>
<td>(C_{LOAD} = 30000\text{pF})</td>
<td>50</td>
<td>150</td>
<td>ns</td>
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<tr>
<td></td>
<td></td>
<td>Fall Time</td>
<td>(C_{LOAD} = 30000\text{pF})</td>
<td>50</td>
<td>150</td>
<td>ns</td>
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<tr>
<td>(f_{\text{OSCC}})</td>
<td>Oscillator Frequency</td>
<td>175</td>
<td>200</td>
<td>225</td>
<td>kHz</td>
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<tr>
<td>(V_{\text{BOOST}})</td>
<td>Boost Voltage</td>
<td>(SW = 0\text{V}, I_{\text{BOOST}} = 5\text{mA}, V_{IN} = 8\text{V})</td>
<td>4.8</td>
<td>5.15</td>
<td>5.5</td>
<td>V</td>
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<td>(\Delta V_{\text{BOOST}})</td>
<td>Boost Load Regulation</td>
<td>(SW = 0\text{V}, I_{\text{BOOST}} = 2\text{mA} ) to 20\text{mA}</td>
<td>3</td>
<td>5</td>
<td>%</td>
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</tbody>
</table>

The \(\bullet\) denotes specifications which apply over the full operating temperature range.  
LTC1624CS: 0\(^\circ\)C \(\leq T_A \leq 70\(^\circ\)C\)  
LTC1624IS: –40\(^\circ\)C \(\leq T_A \leq 85\(^\circ\)C\)  

**Note 1:** \(T_J \) is calculated from the ambient temperature \(T_A\) and power dissipation \(P_D\) according to the following formula: 
\[ T_J = T_A + (P_D \cdot 110\text{C/W}) \]

**Note 2:** The LTC1624 is tested in a feedback loop which servos \(V_{FB}\) to the midpoint for the error amplifier \((V_{ITH} = 1.8\text{V})\).

**Note 3:** Dynamic supply current is higher due to the gate charge being delivered at the switching frequency. See Applications Information.
**TYPICAL PERFORMANCE CHARACTERISTICS**

### Efficiency vs Load Current

- **V<sub>OUT</sub> = 3.3V**
  - Load Current (A) vs Efficiency (%)
  - Efficiency: 100%, 95%, 90%, 85%, 80%, 75%
  - Load Current: 0.001, 0.01, 0.1, 1, 10

- **V<sub>OUT</sub> = 5V**
  - Load Current (A) vs Efficiency (%)
  - Efficiency: 100%, 95%, 90%, 85%, 80%, 75%
  - Load Current: 0.001, 0.01, 0.1, 1, 10

### Efficiency vs Input Voltage

- **V<sub>OUT</sub> = 3.3V**, **R<sub>SENSE</sub> = 0.033Ω**
  - Input Voltage (V) vs Efficiency (%)
  - Efficiency: 100%, 95%, 90%, 85%, 80%, 75%
  - Input Voltage: 0, 5, 10, 15, 20, 25, 30

- **V<sub>OUT</sub> = 5V**
  - Input Voltage (V) vs Efficiency (%)
  - Efficiency: 100%, 95%, 90%, 85%, 80%, 75%
  - Input Voltage: 0, 5, 10, 15, 20, 25, 30

### VIN – V<sub>OUT</sub> Dropout Voltage vs Load Current

- **V<sub>OUT</sub> DROPOUT OF 5%**
  - Load Current (A) vs Dropout Voltage (V)
  - Dropout Voltage: 0.1, 0.2, 0.3, 0.4, 0.5, 0.6

### Boost Line Regulation

- **I<sub>BOOST</sub> = 1mA**, **V<sub>SW</sub> = 0V**
  - Input Voltage (V) vs Boost Voltage (V)
  - Boost Voltage: 0, 1, 2, 3, 4, 5, 6

### Boost Load Regulation

- **VIN = 15V**, **VIN = 5V**
  - Boost Load Current (mA) vs Boost Voltage (V)
  - Boost Voltage: 0, 1, 2, 3, 4, 5, 6

### Boost Voltage vs Temperature

- **I<sub>LOAD</sub> = 1mA**
  - Temperature (°C) vs Boost Voltage (V)
  - Boost Voltage: 4.0, 4.5, 5.0, 5.5, 6.0

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**Notes:**
- **VIN** = Input Voltage
- **I<sub>LOAD</sub>** = Load Current
- **V<sub>OUT</sub>** = Output Voltage
- **R<sub>SENSE</sub>** = Sense Resistance
- **V<sub>SW</sub>** = Switching Voltage
- **Efficiency** is defined as **(V<sub>OUT</sub> – V<sub>IN</sub>) / V<sub>IN</sub>**

**Diagrams and Graphs:**
- Shows typical performance characteristics for different conditions of input and output voltages, loads, and temperatures.

**Legend:**
- Graphs and curves illustrate the relationship between various electrical parameters under different operating conditions.
**TYPICAL PERFORMANCE CHARACTERISTICS**

**V\textsubscript{ITH} vs Output Current**

**ITH vs V\textsubscript{ITH}**

**I\textsubscript{TH}/RUN Pin Source Current vs Temperature**

**Frequency vs Feedback Voltage**

**Operating Frequency vs Temperature**

**Maximum Current Sense Threshold vs Temperature**

**PIN FUNCTIONS**

**SENSE\textsuperscript{–} (Pin 1):** Connects to the (–) input for the current comparator. Built-in offsets between the SENSE\textsuperscript{–} and V\textsubscript{IN} pins in conjunction with R\textsubscript{SENSE} set the current trip thresholds. Do not pull this pin more than 15V below V\textsubscript{IN} or more than 0.3V below ground.

**I\textsubscript{TH}/RUN (Pin 2):** Combination of Error Amplifier Compensation Point and Run Control Inputs. The current comparator threshold increases with this control voltage. Nominal voltage range for this pin is 1.19V to 2.4V. Forcing this pin below 0.8V causes the device to be shut down. In shutdown all functions are disabled and TG pin is held low.

**V\textsubscript{FB} (Pin 3):** Receives the feedback voltage from an external resistive divider across the output.

**GND (Pin 4):** Ground. Connect to the (–) terminal of C\textsubscript{OUT}, the Schottky diode and the (–) terminal of C\textsubscript{IN}.

**SW (Pin 5):** Switch Node Connection to Inductor. In step-down applications the voltage swing at this pin is from a Schottky diode (external) voltage drop below ground to V\textsubscript{IN}.
PIN FUNCTIONS

TG (Pin 6): High Current Gate Drive for Top N-Channel MOSFET. This is the output of a floating driver with a voltage swing equal to INTV_{CC} superimposed on the switch node voltage SW.

BOOST (Pin 7): Supply to Topside Floating Driver. The bootstrap capacitor C_B is returned to this pin. Voltage swing at this pin is from INTV_{CC} to V_{IN} + INTV_{CC} in step-down applications. In non step-down topologies the voltage at this pin is constant and equal to INTV_{CC} if SW = 0V.

V_{IN} (Pin 8): Main Supply Pin and the (+) Input to the Current Comparator. Must be closely decoupled to ground.

OPERATION (Refer to Functional Diagram)

Main Control Loop
The LTC1624 uses a constant frequency, current mode architecture. During normal operation, the top MOSFET is turned on each cycle when the oscillator sets the RS latch and turned off when the main current comparator I_1 resets the RS latch. The peak inductor current at which I_1 resets the RS latch is controlled by the voltage on the I_{TH}/RUN pin, which is the output of error amplifier EA. The V_{FB} pin, described in the pin functions, allows EA to receive an output feedback voltage from an external resistive divider.

When the load current increases, it causes a slight decrease in V_{FB} relative to the 1.19V reference, which in turn causes the I_{TH}/RUN voltage to increase until the average inductor current matches the new load current. While the top MOSFET is off, the internal bottom MOSFET is turned on for approximately 300ns to 400ns to recharge the bootstrap capacitor C_B.

The top MOSFET driver is biased from the floating bootstrap capacitor C_B that is recharged during each off cycle. The dropout detector counts the number of oscillator cycles that the top MOSFET remains on and periodically forces a brief off period to allow C_B to recharge.

The main control loop is shut down by pulling the I_{TH}/RUN pin below its 1.19V clamp voltage. Releasing I_{TH}/RUN allows an internal 2.5µA current source to charge compensation capacitor C_C. When the I_{TH}/RUN pin voltage reaches 0.8V the main control loop is enabled with the I_{TH}/RUN voltage pulled up by the error amp. Soft start can be implemented by ramping the voltage on the I_{TH}/RUN pin from 1.19V to its 2.4V maximum (see Applications Information section).

Comparator OV guards against transient output overshoots >7.5% by turning off the top MOSFET and keeping it off until the fault is removed.

Low Current Operation
The LTC1624 is capable of Burst Mode operation in which the external MOSFET operates intermittently based on load demand. The transition to low current operation begins when comparator B detects when the I_{TH}/RUN voltage is below 1.5V. If the voltage across R_{SENSE} does not exceed the offset of I_2 (approximately 20mV) for one full cycle, then on following cycles the top and internal bottom drives are disabled. This continues until the I_{TH} voltage exceeds 1.5V, which causes drive to be returned to the TG pin on the next cycle.

INTV_{CC} Power/Boost Supply
Power for the top and internal bottom MOSFET drivers is derived from V_{IN}. An internal regulator supplies INTV_{CC} power. To power the top driver in step-down applications an internal high voltage diode recharges the bootstrap capacitor C_B during each off cycle from the INTV_{CC} supply. A small internal N-channel MOSFET pulls the switch node (SW) to ground each cycle after the top MOSFET has turned off ensuring the bootstrap capacitor is kept fully charged.
FUNCTIONAL DIAGRAM (Shown in a step-down application)
The LTC1624 can be used in a wide variety of switching regulator applications, the most common being the step-down converter. Other switching regulator architectures include step-up, SEPIC and positive-to-negative converters.

The basic LTC1624 step-down application circuit is shown in Figure 1 on the first page. External component selection is driven by the load requirement and begins with the selection of RSENSE. Once RSENSE is known, the inductor can be chosen. Next, the power MOSFET and D1 are selected. Finally, CIN and COUT are selected. The circuit shown in Figure 1 can be configured for operation up to an input voltage of 28V (limited by the external MOSFETs).

**Step-Down Converter: RSENSE Selection for Output Current**

RSENSE is chosen based on the required output current. The LTC1624 current comparator has a maximum threshold of 160mV/RSENSE. The current comparator threshold sets the peak of the inductor current, yielding a maximum average output current IMAX equal to the peak value less half the peak-to-peak ripple current, ΔIL.

Allowing a margin for variations in the LTC1624 and external component values yields:

\[
R_{SENSE} = \frac{100\text{mV}}{I_{MAX}}
\]

The LTC1624 works well with values of RSENSE from 0.005Ω to 0.5Ω.

**Step-Down Converter: Inductor Value Calculation**

With the operating frequency fixed at 200kHz smaller inductor values are favored. Operating at higher frequencies generally results in lower efficiency because of MOSFET gate charge losses. In addition to this basic trade-off, the effect of inductor value on ripple current and low current operation must also be considered.

The inductor value has a direct effect on ripple current. The inductor ripple current ΔIL decreases with higher inductance and increases with higher VIN or VOUT:

\[
\Delta I_L = \frac{V_{IN} - V_{OUT}}{(f)(L)} \left( \frac{V_{OUT} + V_D}{V_{IN} + V_D} \right)
\]

where VD is the output Schottky diode forward drop.

Accepting larger values of ΔIL allows the use of low inductances, but results in higher output voltage ripple and greater core losses. A reasonable starting point for setting ripple current is ΔIL = 0.4(I_MAX). Remember, the maximum ΔIL occurs at the maximum input voltage.

The inductor value also has an effect on low current operation. Lower inductor values (higher ΔIL) will cause Burst Mode operation to begin at higher load currents, which can cause a dip in efficiency in the upper range of low current operation. In Burst Mode operation lower inductance values will cause the burst frequency to decrease. In general, inductor values from 5µH to 68µH are typical depending on the maximum input voltage and output current. See also Modifying Burst Mode Operation section.

**Step-Down Converter: Inductor Core Selection**

Once the value for L is known, the type of inductor must be selected. High efficiency converters generally cannot afford the core loss found in low cost powdered iron cores, forcing the use of more expensive ferrite, molypermalloy or Kool Mu® cores. Actual core loss is independent of core size for a fixed inductor value, but it is very dependent on inductance selected. As inductance increases, core losses go down. Unfortunately, increased inductance requires more turns of wire and, therefore, copper losses will increase.

Ferrite designs have very low core loss and are preferred at high switching frequencies, so design goals can concentrate on copper loss and preventing saturation. Ferrite core material saturates “hard,” which means that inductance collapses abruptly when the peak design current is exceeded. This results in an abrupt increase in inductor ripple current and consequent output voltage ripple. Do not allow the core to saturate!

Molypermalloy (from Magnetics, Inc.) is a very good, low loss core material for toroids, but it is more expensive than ferrite. A reasonable compromise from the same manufacturer is Kool Mu. Toroids are very space efficient, especially when you can use several layers of wire. Because they generally lack a bobbin, mounting is more difficult. However, designs for surface mount that do not increase the height significantly are available.
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Step-Down Converter: Power MOSFET Selection

One external N-channel power MOSFET must be selected for use with the LTC1624 for the top (main) switch. The peak-to-peak gate drive levels are set by the INTVCC voltage. This voltage is typically 5V. Consequently, logic level threshold MOSFETs must be used in most LTC1624 applications. If low input voltage operation is expected (VIN < 5V) sublogic level threshold MOSFETs should be used. Pay close attention to the BVDS specification for the MOSFETs as well; many of the logic level MOSFETs are limited to 30V or less.

Selection criteria for the power MOSFET include the “ON” resistance RDSON, reverse transfer capacitance CRSS, input voltage and maximum output current. When the LTC1624 is operating in continuous mode the duty cycle for the top MOSFET is given by:

\[
\text{Main Switch Duty Cycle} = \frac{V_{OUT} + V_D}{V_{IN} + V_D}
\]

The MOSFET power dissipation at maximum output current is given by:

\[
P_{\text{MAIN}} = \frac{V_{OUT} + V_D}{V_{IN} + V_D} (I_{MAX})^2 (1 + \delta) R_{DS(ON)} + k(V_{IN})^{1.85} (I_{MAX}) (C_{RSS})(f)
\]

where \(\delta\) is the temperature dependency of RDSON and \(k\) is a constant inversely related to the gate drive current.

MOSFETs have I^2R losses, plus the P_{\text{MAIN}} equation includes an additional term for transition losses that are highest at high output voltages. For VIN < 20V the high current efficiency generally improves with larger MOSFETs, while for VIN > 20V the transition losses rapidly increase to the point that the use of a higher RDSON device with lower CRSS actual provides higher efficiency. The diode losses are greatest at high input voltage or during a short circuit when the diode duty cycle is nearly 100%.

The term \((1 + \delta)\) is generally given for a MOSFET in the form of a normalized RDSON vs Temperature curve, but \(\delta = 0.005/°\text{C}\) can be used as an approximation for low voltage MOSFETs. CRSS is usually specified in the MOSFET characteristics. The constant \(k = 2.5\) can be used to estimate the contributions of the two terms in the P_{\text{MAIN}} dissipation equation.

Step-Down Converter: Output Diode Selection (D1)

The Schottky diode D1 shown in Figure 1 conducts during the off-time. It is important to adequately specify the diode peak current and average power dissipation so as not to exceed the diode ratings.

The most stressful condition for the output diode is under short circuit (VOUT = 0V). Under this condition, the diode must safely handle ISC(PK) at close to 100% duty cycle. Under normal load conditions, the average current conducted by the diode is simply:

\[
I_{\text{DIODE(AVG)}} = I_{\text{LOAD(AVG)}} \left(\frac{V_{IN} - V_{OUT}}{V_{IN} + V_D}\right)
\]

Remember to keep lead lengths short and observe proper grounding (see Board Layout Checklist) to avoid ringing and increased dissipation.

The forward voltage drop allowable in the diode is calculated from the maximum short-circuit current as:

\[
V_D = \frac{P_D}{I_{SC(AVG)}} \left(\frac{V_{IN} + V_D}{V_{IN}}\right)
\]

where \(P_D\) is the allowable diode power dissipation and will be determined by efficiency and/or thermal requirements (see Efficiency Considerations).

Step-Down Converter: CIN and COUT Selection

In continuous mode the source current of the top N-channel MOSFET is a square wave of approximate duty cycle VOUT/VIN. To prevent large voltage transients, a low ESR input capacitor sized for the maximum RMS current must be used. The maximum RMS capacitor current is given by:

\[
I_{\text{RMS}} = \frac{I_{\text{MAX}}}{V_{IN}} \sqrt{\frac{V_{OUT}(V_{IN} - V_{OUT})}{V_{IN}}}
\]

This formula has a maximum at VIN = 2VOUT, where I_{RMS} = IOUT/2. This simple worst-case condition is com-
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ratings that are ideal for input capacitor applications. Consult the manufacturer for other specific recommendations.

INTVCC Regulator

An internal regulator produces the 5V supply that powers the drivers and internal circuitry within the LTC1624. Good V_IN bypassing is necessary to supply the high transient currents required by the MOSFET gate drivers.

High input voltage applications in which large MOSFETs are being driven at high frequencies may cause the maximum junction temperature rating for the LTC1624 to be exceeded. The supply current is dominated by the gate charge supply current as discussed in the Efficiency Considerations section. The junction temperature can be estimated by using the equations given in Note 1 of the Electrical Characteristics table. For example, the LTC1624 is limited to less than 17mA from a 30V supply:

\[
T_J = 70 \degree C + (17 mA)(30V)(110 \degree C/W) = 126 \degree C
\]

To prevent maximum junction temperature from being exceeded, the input supply current must be checked operating in continuous mode at maximum VIN.

Step-Down Converter: Topside MOSFET Driver Supply (C_B, D_B)

An external bootstrap capacitor C_B connected to the BOOST pin supplies the gate drive voltage for the topside MOSFET. Capacitor C_B in the functional diagram is charged through internal diode D_B from INTVCC when the SW pin is low. When the topside MOSFET is to be turned on, the driver places the C_B voltage across the gate to source of the MOSFET. This enhances the MOSFET and turns on the topside switch. The switch node voltage SW rises to VIN and the BOOST pin rises to V_IN + INTVCC. The value of the boost capacitor C_B needs to be 50 times greater than the total input capacitance of the topside MOSFET. In most applications 0.1 \mu F is adequate.

Significant efficiency gains can be realized by supplying topside driver operating voltage from the output, since the V_IN current resulting from the driver and control currents will be scaled by a factor of (Duty Cycle)/(Efficiency). For 5V regulators this simply means connecting the BOOST...
APPLICATIONS INFORMATION

pin through a small Schottky diode (like a Central CMDSH-3) to VOUT as shown in Figure 10. However, for 3.3V and other lower voltage regulators, additional circuitry is required to derive boost supply power from the output.

For low input voltage operation (VIN < 7V), a Schottky diode can be connected from VIN to BOOST to increase the external MOSFET gate drive voltage. Be careful not to exceed the maximum voltage on BOOST to SW pins of 7.8V.

Output Voltage Programming

The output voltage is set by a resistive divider according to the following formula:

\[ V_{OUT} = 1.19V \left(1 + \frac{R2}{R1}\right) \]

The external resistive divider is connected to the output as shown in Figure 2, allowing remote voltage sensing. When using remote sensing, a local 100Ω resistor should be connected from L1 to R2 to prevent VOUT from running away if the sense lead is disconnected.

Soft start can be implemented by ramping the voltage on ITH/RUN during start-up as shown in Figure 3(c). As the voltage on ITH/RUN ramps from 1.19V to 2.4V the internal peak current limit is also ramped at a proportional linear rate. The peak current limit begins at approximately 10mV/RSENSE (at VITH/RUN = 1.4V) and ends at:

\[ 160mV/RSENSE \text{ (VITH/RUN = 2.4V)} \]

The output current thus ramps up slowly, charging the output capacitor. The peak inductor current and maximum output current are as follows:

\[ I_{L(PEAK)} = \frac{(VITH/RUN - 1.3V)}{(6.8RSENSE)} \]
\[ I_{OUT(MAX)} = I_{L(PEAK)} - \frac{\Delta I}{2} \]

with \( \Delta I \) = ripple current in the inductor.

During normal operation the voltage on the ITH/RUN pin will vary from 1.19V to 2.4V depending on the load current. Pulling the ITH/RUN pin below 0.8V puts the LTC1624 into a low quiescent current shutdown (IQ < 30µA). This pin can be driven directly from logic as shown in Figures 3(a) and 3(b).

Efficiency Considerations

The percent efficiency of a switching regulator is equal to the output power divided by the input power times 100%. It is often useful to analyze individual losses to determine...
what is limiting the efficiency and which change would produce the most improvement. Percent efficiency can be expressed as:

\[
\text{%Efficiency} = 100% - (L1 + L2 + L3 + ...) 
\]

where L1, L2, etc. are the individual losses as a percentage of input power.

Although all dissipative elements in the circuit produce losses, four main sources usually account for most of the losses in LTC1624 circuits:

1. LTC1624 $V_{\text{IN}}$ current
2. $I^2R$ losses
3. Topside MOSFET transition losses
4. Voltage drop of the Schottky diode

1. The $V_{\text{IN}}$ current is the sum of the DC supply current $I_Q$, given in the Electrical Characteristics table, and the MOSFET driver and control currents. The MOSFET driver current results from switching the gate capacitance of the power MOSFET. Each time a MOSFET gate is switched from low to high to low again, a packet of charge $dQ$ moves from $\text{INTV}_{\text{CC}}$ to ground. The resulting $dQ/dt$ is a current out of $V_{\text{IN}}$ which is typically much larger than the control circuit current. In continuous mode, $I_{\text{GATECHG}} = f (Q_T + Q_B)$, where $Q_T$ and $Q_B$ are the gate charges of the topside and internal bottom side MOSFETs.

By powering BOOST from an output-derived source (Figure 10 application), the additional $V_{\text{IN}}$ current resulting from the topside driver will be scaled by a factor of $(\text{Duty Cycle})/\text{(Efficiency)}$. For example, in a 20V to 5V application, 5mA of $\text{INTV}_{\text{CC}}$ current results in approximately 1.5mA of $V_{\text{IN}}$ current. This reduces the midcurrent loss from 5% or more (if the driver was powered directly from $V_{\text{IN}}$) to only a few percent.

2. $I^2R$ losses are predicted from the DC resistances of the MOSFET, inductor and current shunt. In continuous mode the average output current flows through $L$ but is “chopped” between the topside main MOSFET/current shunt and the Schottky diode. The resistances of the topside MOSFET and $R_{\text{SENSE}}$ multiplied by the duty cycle can simply be summed with the resistance of $L$ to obtain $I^2R$ losses. (Power is dissipated in the sense resistor only when the topside MOSFET is on. The $I^2R$ loss is thus reduced by the duty cycle.) For example, at 50% DC, if $R_{\text{DS(ON)}} = 0.05\Omega$, $R_L = 0.15\Omega$ and $R_{\text{SENSE}} = 0.05\Omega$, then the effective total resistance is $0.2\Omega$. This results in losses ranging from 2% to 8% for $V_{\text{OUT}} = 5V$ as the output current increases from 0.5A to 2A. $I^2R$ losses cause the efficiency to drop at high output currents.

3. Transition losses apply only to the topside MOSFET(s), and only when operating at high input voltages (typically 20V or greater). Transition losses can be estimated from:

\[
\text{Transition Loss} = 2.5(V_{\text{IN}})^{1.85} (I_{\text{MAX}})(C_{\text{RSS}})(f)
\]

4. The Schottky diode is a major source of power loss at high currents and gets worse at high input voltages. The diode loss is calculated by multiplying the forward voltage drop times the diode duty cycle multiplied by the load current. For example, assuming a duty cycle of 50% with a Schottky diode forward voltage drop of 0.5V, the loss is a relatively constant 5%.

As expected, the $I^2R$ losses and Schottky diode loss dominate at high load currents. Other losses including $C_{\text{IN}}$ and $C_{\text{OUT}}$ ESR dissipative losses and inductor core losses generally account for less than 2% total additional loss.

**Checking Transient Response**

The regulator loop response can be checked by looking at the load transient response. Switching regulators take several cycles to respond to a step in DC (resistive) load current. When a load step occurs, $V_{\text{OUT}}$ immediately shifts by an amount equal to $(\Delta I_{\text{LOAD}} \cdot \text{ESR})$, where ESR is the effective series resistance of $C_{\text{OUT}}$. $\Delta I_{\text{LOAD}}$ also begins to charge or discharge $C_{\text{OUT}}$ which generates a feedback error signal. The regulator loop then acts to return $V_{\text{OUT}}$ to its steady-state value. During this recovery time $V_{\text{OUT}}$ can be monitored for overshoot or ringing that would indicate a stability problem. The $I_{\text{TH}}$ external components shown in the Figure 1 circuit will provide adequate compensation for most applications.

A second, more severe transient, is caused by switching in loads with large (>1µF) supply bypass capacitors. The discharged bypass capacitors are effectively put in parallel...
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with \( C_{\text{OUT}} \), causing a rapid drop in \( V_{\text{OUT}} \). No regulator can deliver enough current to prevent this problem if the load switch resistance is low and it is driven quickly. The only solution is to limit the rise time of the switch drive so that the load rise time is limited to approximately \((25 \times C_{\text{LOAD}})\). Thus a 10\( \mu \)F capacitor would require a 250\( \mu \)s rise time, limiting the charging current to about 200mA.

Automotive Considerations: Plugging into the Cigarette Lighter

As battery-powered devices go mobile there is a natural interest in plugging into the cigarette lighter in order to conserve or even recharge battery packs during operation. But before you connect, be advised: you are plugging into the supply from hell. The main battery line in an automobile is the source of a number of nasty potential transients, including load dump, reverse battery and double battery.

Load dump is the result of a loose battery cable. When the cable breaks connection, the field collapse in the alternator can cause a positive spike as high as 60V which takes several hundred milliseconds to decay. Reverse battery is just what it says, while double battery is a consequence of tow-truck operators finding that a 24V jump start cranks cold engines faster than 12V.

The network shown in Figure 4 is the most straightforward approach to protect a DC/DC converter from the ravages of an automotive battery line. The series diode prevents current from flowing during reverse battery, while the transient suppressor clamps the input voltage during load dump. Note that the transient suppressor should not conduct during double battery operation, but must still clamp the input voltage below breakdown of the converter. Although the LTC1624 has a maximum input voltage of 36V, most applications will be limited to 30V by the MOSFET \( B\text{V}_{\text{DSS}} \).

Modifying Burst Mode Operation

The LTC1624 automatically enters Burst Mode operation at low output currents to boost efficiency. The point when continuous mode operation changes to Burst Mode operation scales as a function of maximum output current. The output current when Burst Mode operation commences is approximately 8mV/R\(_{\text{SENSE}}\) (8% of maximum output current).

With the additional circuitry shown in Figure 5 the LTC1624 can be forced to stay in continuous mode longer at low output currents. Since the LTC1624 is not a fully synchronous architecture, it will eventually start to skip cycles as the load current drops low enough. The point when the minimum on-time (450ns) is reached determines the load current when cycle skipping begins at approximately 1% of maximum output current. Using the circuit in Figure 5 the LTC1624 will begin to skip cycles but stays in regulation when \( I_{\text{OUT}} \) is less than \( I_{\text{OUT(MIN)}} \):

\[
I_{\text{OUT(MIN)}} = \frac{t_{\text{ON(MIN)}}^2 f}{2L} \left( V_{\text{IN}} - V_{\text{OUT}} \right) \left( \frac{V_{\text{IN}} + V_{\text{D}}}{V_{\text{OUT}} + V_{\text{D}}} \right)
\]

where \( t_{\text{ON(MIN)}} = 450\text{ns} \), \( f = 200\text{kHz} \).

The transistor \( Q1 \) in the circuit of Figure 5 operates as a current source developing an 18mV offset across the
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100Ω resistor in series with the SENSE− pin. This offset cancels the internal offset in current comparator I2 (refer to Functional Diagram). This comparator in conjunction with the voltage on the ITH/RUN pin determines when to enter into Burst Mode operation (refer to Low Current Operation in Operation section). With the additional external offset present, the drive to the topside MOSFET is always enabled every cycle and constant frequency operation occurs for IOUT > IOUT(MIN).

**Step-Down Converter: Design Example**

As a design example, assume VIN = 12V(nominal), VIN = 22V(max), VOUT = 3.3V and IMAX = 2A. RSENSE can immediately be calculated:

RSENSE = 100mV/2A = 0.05Ω

Assume a 10µH inductor. To check the actual value of the ripple current the following equation is used:

\[
\Delta I_L = \frac{V_{IN} - V_{OUT}}{(t)(L)} \left( \frac{V_{OUT} + V_D}{V_{IN} + V_D} \right)
\]

The highest value of the ripple current occurs at the maximum input voltage:

\[
\Delta I_L = \frac{22V - 3.3V}{200kHz(10\mu H)} \left( \frac{3.3V + 0.5V}{22V + 0.5V} \right) = 1.58A_{P-P}
\]

The power dissipation on the topside MOSFET can be easily estimated. Choosing a Siliconix Si4412DY results in: RDS(ON) = 0.042Ω, CRESS = 100pF. At maximum input voltage with T(estimated) = 50°C:

\[
P_{MAIN} = \frac{3.3V + 0.5V}{22V + 0.5V} \left(2A\right)^2 \left[1 + (0.005)(50°C − 25°C)\right] \left(0.042Ω\right)
\]

\[
+ 2.5(22V)^{1.85} \left(2A\right) \left(100pF\right) \left(200kHz\right) = 62mW
\]

The most stringent requirement for the Schottky diode occurs when VOUT = 0V (i.e. short circuit) at maximum VIN. In this case the worst-case dissipation rises to:

\[
P_D = I_{SC(AVG)} \left( \frac{V_{IN}}{V_{IN} + V_D} \right)
\]

With the 0.05Ω sense resistor I_{SC(AVG)} = 2A will result, increasing the 0.5V Schottky diode dissipation to 0.98W. CIN is chosen for an RMS current rating of at least 1.0A at temperature. COUT is chosen with an ESR of 0.03Ω for low output ripple. The output ripple in continuous mode will be highest at the maximum input voltage. The output voltage ripple due to ESR is approximately:

\[
V_{ORRIPPLE} = R_{ESR} \Delta I_L = 0.03Ω \left(1.58A_{P-P}\right) = 47mV_{P-P}
\]

**Step-Down Converter: Duty Cycle Limitations**

At high input to output differential voltages the on-time gets very small. Due to internal gate delays and response times of the internal circuitry the minimum recommended on-time is 450ns. Since the LTC1624’s frequency is internally set to 200kHz a potential duty cycle limitation exists. When the duty cycle is less than 9%, cycle skipping may occur which increases the inductor ripple current but does not cause VOUT to lose regulation. Avoiding cycle skipping imposes a limit on the input voltage for a given output voltage only when VOUT < 2.2V using 30V MOSFETs. (Remember not to exceed the absolute maximum voltage of 36V.)

\[
V_{IN(MAX)} = 11.1V_{OUT} + 5V \quad \text{For DC > 9%}
\]

**Boost Converter Applications**

The LTC1624 is also well-suited to boost converter applications. A boost converter steps up the input voltage to a higher voltage as shown in Figure 6.
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Boost Converters: Power MOSFET Selection

One external N-channel power MOSFET must be selected for use with the LTC1624 for the switch. In boost applications the source of the power MOSFET is grounded along with the SW pin. The peak-to-peak gate drive levels are set by the INTVCC voltage. The gate drive voltage is equal to approximately 5V for VIN > 5.6V and a logic level MOSFET can be used. At VIN voltages below 5V the gate drive voltage is equal to VIN – 0.6V and a sublogic level MOSFET should be used.

Selection criteria for the power MOSFET include the “ON” resistance R_DS(ON), reverse transfer capacitance C_RSS, input voltage and maximum output current. When the LTC1624 is operating in continuous mode the duty cycle for the MOSFET is given by:

\[ \text{Main Switch Duty Cycle} = 1 - \frac{V_{IN}}{V_{OUT} + V_D} \]

The MOSFET power dissipation at maximum output current is given by:

\[ P_{MAIN} = \left( I_{IN(MAX)} \right)^2 \left( 1 - \frac{V_{IN(MIN)}}{V_{OUT} + V_D} \right) \left( 1 + \delta \right) R_{DS(ON)} + \frac{k \left( V_{OUT} \right)^{1.85} \left( I_{IN(MAX)} \right) \left( C_{RSS} \right) \left( 200kHz \right) \Delta I_L \left( P-P \right) \Delta I_L \left( MAX \right) \]

where \( I_{IN(MAX)} = I_{OUT(MAX)} \left( \frac{V_{OUT} + V_D}{V_{IN(MIN)}} \right) \)

\( \delta \) is the temperature dependency of R_DS(ON) and \( k \) is a constant inversely related to the gate drive current.

MOSFETs have \( I^2R \) losses, plus the \( P_{MAIN} \) equation includes an additional term for transition losses that are highest at high output voltages. For \( V_{OUT} < 20V \) the high current efficiency generally improves with larger MOSFETs, while for \( V_{OUT} > 20V \) the transition losses rapidly increase to the point that the use of a higher R_DS(ON) device with lower C_RSS actual provides higher efficiency. For additional information refer to Step-Down Converter: Power MOSFET Selection in the Applications Information section.

Boost Converter: Inductor Selection

For most applications the inductor will fall in the range of 10\( \mu \)H to 100\( \mu \)H. Higher values reduce the input ripple voltage and reduce core loss. Lower inductor values are chosen to reduce physical size.

The input current of the boost converter is calculated at full load current. Peak inductor current can be significantly higher than output current, especially with smaller inductors and lighter loads. The following formula assumes continuous mode operation and calculates maximum peak inductor current at minimum VIN:

\[ I_L(PEAK) = I_{OUT(MAX)} \left( \frac{V_{OUT}}{V_{IN(MIN)}} \right) + \frac{\Delta I_L(MAX)}{2} \]

The ripple current in the inductor (\( \Delta I_L \)) is typically 20% to 30% of the peak inductor current occurring at \( V_{IN(MIN)} \) and \( I_{OUT(MAX)} \).

\[ \Delta I_L(P-P) = \frac{V_{IN}(V_{OUT} + V_D - V_IN)}{(200kHz)(L)(V_{OUT} + V_D)} \]

with \( \Delta I_L(MAX) = \Delta I_L(P-P) \) at \( V_{IN} = V_{IN(MIN)} \).

Remember boost converters are not short-circuit protected, and that under output short conditions, inductor current is limited only by the available current of the input supply, \( I_{OUT(OVERLOAD)} \). Specify the maximum inductor current to safely handle the greater of \( I_L(PEAK) \) or \( I_{OUT(OVERLOAD)} \). Make sure the inductor’s saturation current rating (current when inductance begins to fall) exceeds the maximum current rating set by RSENSE.

Boost Converter: RSENSE Selection for Maximum Output Current

RSENSE is chosen based on the required output current. Remember the LTC1624 current comparator has a maximum threshold of 160mV/RSENSE. The current comparator threshold sets the peak of the inductor current, yielding a maximum average output current \( I_{OUT(MAX)} \) equal to \( I_L(PEAK) \) less half the peak-to-peak ripple current (\( \Delta I_L \)), divided by the output-input voltage ratio (see equation for \( I_L(PEAK) \)).
Allowing a margin for variations in the LTC1624 (without considering variation in $R_{\text{SENSE}}$), assuming 30% ripple current in the inductor, yields:

$$R_{\text{SENSE}} = \frac{100\text{mV}}{I_{\text{OUT}(\text{MAX})}} \left( \frac{V_{\text{IN}(\text{MIN})}}{V_{\text{OUT}} + V_D} \right)$$

**Boost Converter: Output Diode**

The output diode conducts current only during the switch off-time. Peak reverse voltage for boost converters is equal to the regulator output voltage. Average forward current in normal operation is equal to output current. Remember boost converters are not short-circuit protected. Check to be sure the diode’s current rating exceeds the maximum current set by $R_{\text{SENSE}}$. Schottky diodes such as Motorola MBR130LT3 are recommended.

**Boost Converter: Output Capacitors**

The output capacitor is normally chosen by its effective series resistance (ESR), because this is what determines output ripple voltage.

Since the output capacitor’s ESR affects efficiency, use low ESR capacitors for best performance. Boost regulators have large RMS ripple current in the output capacitor that must be rated to handle the current. The output capacitor ripple current (RMS) is:

$$C_{\text{OUT}} I_{\text{RIPPLE(RMS)}} = I_{\text{OUT}} \sqrt{\frac{V_{\text{OUT}} - V_{\text{IN}}}{V_{\text{IN}}}}$$

Output ripple is then simply: $V_{\text{OUT}} = R_{\text{ESR}} (\Delta I_{\text{L(RMS)}})$.

**Boost Converter: Input Capacitors**

The input capacitor of a boost converter is less critical due to the fact that the input current waveform is triangular, and does not contain large square wave currents as found in the output capacitor. The input voltage source impedance determines the size of the capacitor that is typically 10μF to 100μF. A low ESR is recommended although not as critical as the output capacitor and can be on the order of 0.3Ω. Input capacitor ripple current for the LTC1624 used as a boost converter is:

$$C_{\text{IN}} I_{\text{RIPPLE}} \approx \frac{0.3(V_{\text{IN}})(V_{\text{OUT}} - V_{\text{IN}})}{(200\text{kHz})(L)(V_{\text{OUT}})}$$

The input capacitor can see a very high surge current when a battery is suddenly connected and solid tantalum capacitors can fail under this condition. Be sure to specify surge tested capacitors.

**Boost Converter: Duty Cycle Limitations**

The minimum on-time of 450ns sets a limit on how close $V_{\text{IN}}$ can approach $V_{\text{OUT}}$ without the output voltage overshooting and tripping the overvoltage comparator. Unless very low values of inductances are used, this should never be a problem. The maximum input voltage in continuous mode is:

$$V_{\text{IN(MAX)}} = 0.91V_{\text{OUT}} + 0.5V \quad \text{For DC = 9%}$$

**SEPIC Converter Applications**

The LTC1624 is also well-suited to SEPIC (Single Ended Primary Inductance Converter) converter applications. The SEPIC converter shown in Figure 7 uses two inductors. The advantage of the SEPIC converter is the input voltage may be higher or lower than the output voltage.

The first inductor L1 together with the main N-channel MOSFET switch resemble a boost converter. The second inductor L2 and output diode D1 resemble a flyback or buck-boost converter. The two inductors L1 and L2 can be independent but also can be wound on the same core since...
identical voltages are applied to L1 and L2 throughout the switching cycle. By making L1 = L2 and wound on the same core the input ripple is reduced along with cost and size. All SEPIC applications information that follows assumes L1 = L2 = L.

SEPIC Converter: Power MOSFET Selection

One external N-channel power MOSFET must be selected for use with the LTC1624 for the switch. As in boost applications the source of the power MOSFET is grounded along with the SW pin. The peak-to-peak gate drive levels are set by the INTVCC voltage. This voltage is equal to approximately 5V for VIN > 5.6V and a logic level MOSFET can be used. At VIN voltages below 5V the INTVCC voltage is equal to VIN – 0.6V and a sublogic level MOSFET should be used.

Selection criteria for the power MOSFET include the “ON” resistance RDS(ON), reverse transfer capacitance CRSS, input voltage and maximum output current. When the LTC1624 is operating in continuous mode the duty cycle for the MOSFET is given by:

\[
\text{Main Switch Duty Cycle} = \frac{V_{OUT} + V_D}{V_{IN} + V_{OUT} + V_D}
\]

The MOSFET power dissipation and maximum switch current at maximum output current are given by:

\[
P_{\text{MAIN}} = \left( I_{SW(\text{MAX})} \right)^2 \left( \frac{V_{OUT} + V_D}{V_{IN(\text{MIN})} + V_{OUT} + V_D} \right) \left( 1 + \delta \right) R_{DS(\text{ON})} + k \left( V_{IN(\text{MIN})} + V_{OUT} \right)^{1.85} \left( I_{SW(\text{MAX})} \right) \left( CRSS \right) \left( 200kHz \right)
\]

where \( I_{SW(\text{MAX})} = I_{OUT(\text{MAX})} \left( \frac{V_{OUT} + V_D}{V_{IN(\text{MIN})}} + 1 \right) \)

\( \delta \) is the temperature dependency of RDS(ON) and k is a constant inversely related to the gate drive current. The peak switch current is \( I_{SW(\text{MAX})} + \Delta I_L \).

MOSFETs have \( I^2R \) losses plus the \( P_{\text{MAIN}} \) equation includes an additional term for transition losses that are highest at high total input plus output voltages. For \( (V_{IN} + V_{OUT}) < 20V \) the high current efficiency generally improves with larger MOSFETs, while for \( (V_{IN} + V_{OUT}) > 20V \) the transition losses rapidly increase to the point that the use of a higher RDS(ON) device with lower CRSS actual provides higher efficiency. For additional information refer to the Step-Down Converter: Power MOSFET Selection in the Applications Information section.

SEPIC Converter: Inductor Selection

For most applications the equal inductor values will fall in the range of 10\( \mu \)H to 100\( \mu \)H. Higher values reduce the input ripple voltage and reduce core loss. Lower inductor values are chosen to reduce physical size and improve transient response.

Like the boost converter the input current of the SEPIC converter is calculated at full load current. Peak inductor current can be significantly higher than output current, especially with smaller inductors and lighter loads. The following formula assumes continuous mode operation and calculates maximum peak inductor current at minimum \( V_{IN} \):

\[
I_{L1(\text{PEAK})} = I_{OUT(\text{MAX})} \left( \frac{V_{OUT}}{V_{IN(\text{MIN})}} \right) + \frac{\Delta I_{L1}}{2}
\]

\[
I_{L2(\text{PEAK})} = I_{OUT(\text{MAX})} \left( \frac{V_{IN(\text{MIN})} + V_D}{V_{IN(\text{MIN})}} \right) + \frac{\Delta I_{L2}}{2}
\]

The ripple current in the inductor (\( \Delta I_L \)) is typically 20% to 30% of the peak current occurring at \( V_{IN(\text{MIN})} \) and \( I_{OUT(\text{MAX})} \), and \( \Delta I_{L1} = \Delta I_{L2} \). Maximum \( \Delta I_L \) occurs at maximum \( V_{IN} \).

\[
\Delta I_L(\text{P-P}) = \frac{\left( V_{IN} \right) \left( V_{OUT} + V_D \right)}{\left( 200kHz \right) \left( I \right) \left( V_{IN} + V_{OUT} + V_D \right)}
\]

By making L1 = L2 and wound on the same core the value of inductance in all the above equations are replaced by 2L due to their mutual inductance. Doing this maintains the same ripple current and inductive energy storage in the inductors. For example a Coiltronix CTX10-4 is a 10\( \mu \)H inductor with two windings. With the windings in parallel
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10 μH inductance is obtained with a current rating of 4A. Splitting the two windings creates two 10 μH inductors with a current rating of 2A each. Therefore substitute (2)(10 μH) = 20 μH for L in the equations.

Specify the maximum inductor current to safely handle $I_{L(PEAK)}$. Make sure the inductor’s saturation current rating (current when inductance begins to fall) exceeds the maximum current rating set by $R_{SENSE}$.

SEPIC Converter: $R_{SENSE}$ Selection for Maximum Output Current

$R_{SENSE}$ is chosen based on the required output current. Remember the LTC1624 current comparator has a maximum threshold of 160mV/$R_{SENSE}$. The current comparator threshold sets the peak of the inductor current, yielding a maximum average output current $I_{OUT(MAX)}$ equal to $I_{L(1(PEAK))}$ less half the peak-to-peak ripple current, $\Delta I_L$, divided by the output-input voltage ratio (see equation for $I_{L(1(PEAK))}$).

Allowing a margin for variations in the LTC1624 (without considering variation in $R_{SENSE}$), assuming 30% ripple current in the inductor, yields:

$$R_{SENSE} = \frac{100mV}{I_{OUT(MAX)}} \left( \frac{V_{IN(MIN)}}{V_{OUT} + V_D} \right)$$

SEPIC Converter: Output Diode

The output diode conducts current only during the switch off-time. Peak reverse voltage for SEPIC converters is equal to $V_{OUT} + V_{IN}$. Average forward current in normal operation is equal to output current. Peak current is:

$$I_{D1(PEAK)} = I_{OUT(MAX)} \left( \frac{V_{OUT} + V_D}{V_{IN(MIN)}} + 1 \right) + \Delta I_L$$

Schottky diodes such as MBR130LT3 are recommended.

SEPIC Converter: Input and Output Capacitors

The output capacitor is normally chosen by its effective series resistance (ESR), because this is what determines output ripple voltage. The input capacitor needs to be sized to handle the ripple current safely.

Since the output capacitor’s ESR affects efficiency, use low ESR capacitors for best performance. SEPIC regulators, like step-down regulators, have a triangular current waveform but have maximum ripple at $V_{IN(MAX)}$. The input capacitor ripple current is:

$$I_{RIPPLE(RMS)} = \frac{\Delta I_L}{\sqrt{12}}$$

The output capacitor ripple current is:

$$I_{RIPPLE(RMS)} = I_{OUT} \frac{V_{OUT}}{\sqrt{V_{IN}}}$$

The output capacitor ripple voltage (RMS) is:

$$V_{OUT(RIPPLE)} = 2(\Delta I_L)(ESR)$$

The input capacitor can see a very high surge current when a battery is suddenly connected, and solid tantalum capacitors can fail under this condition. Be sure to specify surge tested capacitors.

SEPIC Converter: Coupling Capacitor (C1)

The coupling capacitor $C_{1}$ in Figure 7 sees a nearly rectangular current waveform. During the off-time the current through $C_1$ is $I_{OUT}(V_{OUT}/V_{IN})$ while approximately $-I_{OUT}$ flows though $C_1$ during the on-time. This current waveform creates a triangular ripple voltage on $C_1$:

$$\Delta V_{C1} = \left( \frac{I_{OUT}}{200kHz(C1)} \right) \left( \frac{V_{OUT}}{V_{IN} + V_{OUT} + V_D} \right)$$

The maximum voltage on $C_1$ is then:

$$V_{C1(MAX)} = V_{IN} + \Delta V_{C1}/2$$

The ripple current though $C_1$ is:

$$I_{RIPPLE(C1)} = I_{OUT} \frac{V_{OUT}}{V_{IN}}$$

The maximum ripple current occurs at $I_{OUT(MAX)}$ and $V_{IN(MIN)}$. The capacitance of $C_1$ should be large enough so
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that the voltage across C1 is constant such that \( V_{C1} = V_{IN} \) at full load over the entire \( V_{IN} \) range. Assuming the energy storage in the coupling capacitor C1 must be equal to the energy stored in L1, the minimum capacitance of C1 is:

\[
C_{1(\text{MIN})} = \frac{L1(I_{OUT})^2 (V_{OUT})^2}{V_{IN(\text{MIN})}^4}
\]

SEPIC Converter: Duty Cycle Limitations

The minimum on-time of 450ns sets a limit on how high an input-to-output ratio can be tolerated while not skipping cycles. This only impacts designs when very low output voltages (\( V_{OUT} < 2.5V \)) are needed. Note that a SEPIC converter would not be appropriate at these low output voltages. The maximum input voltage is (remember not to exceed the absolute maximum limit of 36V):

\[
V_{IN(\text{MAX})} = 10.1V_{OUT} + 5V \quad \text{For DC > 9%}
\]

Positive-to-Negative Converter Applications

The LTC1624 can also be used as a positive-to-negative converter with a grounded inductor shown in Figure 8. Since the LTC1624 requires a positive feedback signal relative to device ground, Pin 4 must be tied to the regulated negative output. A resistive divider from the negative output to ground sets the output voltage. Remember not to exceed maximum \( V_{IN} \) ratings \( V_{IN} + |V_{OUT}| \leq 36V \).

Positive-to-Negative Converter: Output Voltage Programming

Setting the output voltage for a positive-to-negative converter is different from other architectures since the feedback voltage is referenced to the LTC1624 ground pin and the ground pin is referenced to \(-V_{OUT}\). The output voltage is set by a resistive divider according to the following formula:

\[
V_{OUT} = 1.19V \left(1 + \frac{R1}{R2}\right) = -V_{IN} \left(\frac{DC}{1-DC}\right)
\]

The external resistive divider is connected to the output as shown in Figure 8.

Positive-to-Negative Converter: Power MOSFET Selection

One external N-channel power MOSFET must be selected for use with the LTC1624 for the switch. As in step-down applications the source of the power MOSFET is connected to the Schottky diode and inductor. The peak-to-peak gate drive levels are set by the INTVCC voltage. The gate drive voltage is equal to approximately 5V for \( V_{IN} > 5.6V \) and a logic level MOSFET can be used. At \( V_{IN} \) voltages below 5V the INTVCC voltage is equal to \( V_{IN} - 0.6V \) and a sublogic level MOSFET should be used.

Selection criteria for the power MOSFET include the “ON” resistance \( R_{DS(ON)} \), reverse transfer capacitance \( C_{RSS} \), input voltage and maximum output current. When the LTC1624 is operating in continuous mode the duty cycle for the MOSFET is given by:

\[
\text{Main Switch Duty Cycle} = \frac{n}{V_{IN} + |V_{OUT}| + V_{D}}
\]

with \(|V_{OUT}|\) being the absolute value of \( V_{OUT} \).

The MOSFET power dissipation and maximum switch current are given by:

\[
P_{\text{MAIN}} = I_{SW(\text{MAX})} \times \left\{ \frac{\text{OUT}(\text{MAX}) (1 + \delta) R_{DS(ON)} + k (\text{VIN}(\text{MAX}) + |V_{OUT}|)^{1.85} C_{RSS}(200kHz)}{V_{OUT}} \right\}
\]
Where: $I_{SW(MAX)} = I_{OUT(MAX)} \left( \frac{V_{IN} + |V_{OUT}| + V_D}{V_{IN}} \right)$

$\delta$ is the temperature dependency of $R_{DS(ON)}$ and $k$ is a constant inversely related to the gate drive current. The maximum switch current occurs at $V_{IN(MIN)}$ and the peak switch current is $I_{SW(MAX)} + \Delta I_L/2$. The maximum voltage across the switch is $V_{IN(MAX)} + |V_{OUT}|$.

MOSFETs have $I^2R$ losses plus the $P_{MAIN}$ equation includes an additional term for transition losses that are highest at high total input plus output voltages. For $(|V_{OUT}| + V_{IN}) < 20V$ the high current efficiency generally improves with larger MOSFETs, while for $(|V_{OUT}| + V_{IN}) > 20V$ the transition losses rapidly increase to the point that the use of a higher $R_{DS(ON)}$ device with lower $C_{RSS}$ actual provides higher efficiency. For additional information refer to the Step-Down Converter: Power MOSFET Selection in the Applications Information section.

### Positive-to-Negative Converter: Inductor Selection

For most applications the inductor will fall in the range of 10$\mu$H to 100$\mu$H. Higher values reduce the input and output ripple voltage (although not as much as step-down converters) and also reduce core loss. Lower inductor values are chosen to reduce physical size and improve transient response but do increase output ripple.

Like the boost converter, the input current of the positive-to-negative converter is calculated at full load current. Peak inductor current can be significantly higher than output current, especially with smaller inductors (with high $\Delta I_L$ values). The following formula assumes continuous mode operation and calculates maximum peak inductor current at minimum $V_{IN}$:

$$I_L(PEAK) = I_{OUT(MAX)} \left( \frac{V_{IN} + |V_{OUT}| + V_D}{V_{IN}} \right) + \frac{\Delta I_L}{2}$$

The ripple current in the inductor ($\Delta I_L$) is typically 20% to 50% of the peak inductor current occurring at $V_{IN(MIN)}$ and $I_{OUT(MAX)}$ to minimize output ripple. Maximum $\Delta I_L$ occurs at minimum $V_{IN}$.

$$\Delta I_{L(P-P)} = \frac{(V_{IN})(|V_{OUT}| + V_D)}{(200kHz)(L)(V_{IN} + |V_{OUT}| + V_D)}$$

Specify the maximum inductor current to safely handle $I_L(PEAK)$. Make sure the inductor’s saturation current rating (current when inductance begins to fall) exceeds the maximum current rating set by $R_{SENSE}$.

### Positive-to-Negative Converter: $R_{SENSE}$ Selection for Maximum Output Current

$R_{SENSE}$ is chosen based on the required output current. Remember the LTC1624 current comparator has a maximum threshold of 160mV/$R_{SENSE}$. The current comparator threshold sets the peak of the inductor current, yielding a maximum average output current $I_{OUT(MAX)}$ equal to $I_L(PEAK)$ less half the peak-to-peak ripple current with the remainder divided by the duty cycle.

Allowing a margin for variations in the LTC1624 (without considering variation in $R_{SENSE}$) and assuming 30% ripple current in the inductor, yields:

$$R_{SENSE} = \frac{100mV}{I_{OUT(MAX)} \left( \frac{V_{IN(MIN)}}{V_{IN(MIN)} + |V_{OUT}| + V_D} \right)}$$

### Positive-to-Negative Converter: Output Diode

The output diode conducts current only during the switch off-time. Peak reverse voltage for positive-to-negative converters is equal to $|V_{OUT}| + V_{IN}$. Average forward current in normal operation is equal to $I_{D(PEAK)} - \Delta I_L/2$. Peak diode current (occurring at $V_{IN(MIN)}$) is:

$$I_{D(PEAK)} = I_{OUT(MAX)} \left( \frac{|V_{OUT}| + V_D}{V_{IN}} + 1 \right) + \frac{\Delta I_L}{2}$$

### Positive-to-Negative Converter: Input and Output Capacitors

The output capacitor is normally chosen by its effective series resistance (ESR), because this is what determines output ripple voltage. Both input and output capacitors need to be sized to handle the ripple current safely.
APPLICATIONS INFORMATION

Positive-to-negative converters have high ripple current in both the input and output capacitors. For long capacitor lifetime, the RMS value of this current must be less than the high frequency ripple rating of the capacitor.

The following formula gives an approximate value for RMS ripple current. This formula assumes continuous mode and low current ripple. Small inductors will give somewhat higher ripple current, especially in discontinuous mode. For the exact formulas refer to Application Note 44, pages 28 to 30. The input and output capacitor ripple current (occurring at VIN(MIN)) is:

\[
\text{Capacitor } I_{\text{RMS}} = \left( ff \right) \left( I_{\text{OUT}} \right) \sqrt{\frac{V_{\text{OUT}}}{V_{\text{IN}}}}
\]

\( ff = \text{Fudge factor (1.2 to 2.0)} \)

The output peak-to-peak ripple voltage is:

\[ V_{\text{OUT(P-P)}} = R_{\text{ESR}} \left( I_{\text{D(MAX)}} \right) \]

The input capacitor can also see a very high surge current when a battery is suddenly connected, and solid tantalum capacitors can fail under this condition. Be sure to specify surge tested capacitors.

Positive-to-Negative Converter: Duty Cycle Limitations

The minimum on-time of 450ns sets a limit on how high of input-to-output ratio can be tolerated while not skipping cycles. This only impacts designs when very low output voltages (\(|V_{\text{OUT}}| < 2.5V\)) are needed. The maximum input voltage is:

\[ V_{\text{IN(MAX)}} < 10.1V_{\text{OUT}} + 5V \quad \text{For } DC > 9\% \]

\[ V_{\text{IN(MAX)}} < 36V - |V_{\text{OUT}}| \quad \text{For absolute maximum ratings} \]

Positive-to-Negative Converter: Shutdown Considerations

Since the ground pin on the LTC1624 is referenced to \(-V_{\text{OUT}}\), additional circuitry is needed to put the LTC1624 into shutdown. Shutdown is enabled by pulling the I\text{TH/RUN} pin below 0.8V relative to the LTC1624 ground pin. With the LTC1624 ground pin referenced to \(-V_{\text{OUT}}\), the nominal range on the I\text{TH/RUN} pin is \(-V_{\text{OUT}}\) (in shutdown) to \((-V_{\text{OUT}} + 2.4V)\) (at Max I\text{OUT}). Referring to Figure 15, M2, M3 and R3 provide a level shift from typical TTL levels to the LTC1624 operating as positive-to-negative converter. MOSFET M3 supplies gate drive to M2 during shutdown, while M2 pulls the I\text{TH/RUN} pin voltage to \(-V_{\text{OUT}}\), shutting down the LTC1624.

Step-Down Converters: PC Board Layout Checklist

When laying out the printed circuit board, the following checklist should be used to ensure proper operation of the LTC1624. These items are also illustrated graphically in the layout diagram of Figure 9. Check the following in your layout:

1. Are the signal and power grounds segregated? The LTC1624 ground (Pin 4) must return to the (–) plate of C\text{OUT}.
2. Does the V\text{FB} (Pin 3) connect directly to the feedback resistors? The resistive divider R1, R2 must be connected between the (+) plate of C\text{OUT} and signal ground. The 100pF capacitor should be as close as possible to the LTC1624.
3. Does the V\text{IN} lead connect to the input voltage at the same point as R\text{SENSE} and are the SENSE– and V\text{IN} leads routed together with minimum PC trace spacing? The filter capacitor between V\text{IN} and SENSE– should be as close as possible to the LTC1624.
4. Does the (+) plate of C\text{IN} connect to R\text{SENSE} as closely as possible? This capacitor provides the AC current to the MOSFET(s). Also, does C\text{IN} connect as close as possible to the V\text{IN} and ground pin of the LTC1624? This capacitor also supplies the energy required to recharge the bootstrap capacitor. Adequate input decoupling is critical for proper operation.
5. Keep the switch node SW away from sensitive small-signal nodes. Ideally, M1, L1 and D1 should be connected as closely as possible at the switch node.
Figure 9. LTC1624 Layout Diagram (See Board Layout Checklist)

Figure 10. 5V/3A Converter with Output Derived Boost Voltage
TYPICAL APPLICATIONS

Figure 11. Wide Input Range 1.8V/1.5A Converter

Figure 12. 12V/1A Low Dropout Converter

Figure 13. 12V/0.75A Boost Converter
TYPICAL APPLICATIONS

Figure 14. 12V/0.4A SEPIC Converter

Figure 15. Inverting –5V/2A Converter

Figure 16. Low Dropout 3.3V/1.5A Converter
Figure 17. 5V/1A SEPIC Converter with Output Derived Boost Voltage

Figure 18. 24V to 12V/10A Buck Converter with Output-Derived Boost Voltage

Component Descriptions:
- C1, C2, C3, C4 = SANYO 35MV1000GX
- C5, C7 = WIMA MKS2
- COUT = SANYO 16MV2700GX
- D1 = MOTOROLA MBR2535CT
- L1 = PULSE ENGINEERING PS472
- M1 = INTERNATIONAL RECTIFIER IRL3803
- RSENSE1, RSENSE2 = IRC LR2010-01-R015-F
- * BOTH D1 AND M1 MOUNTED TO SAME THERMALLOY #6399B HEAT SINK
TYPICAL APPLICATIONS

Figure 19. 24V to 90V at 0.5A Boost Converter

Figure 20. 12V to 24V/5A Boost Converter
Figure 21. 12V/3A Adjustable Current Power Supply for Battery Charger or Current Source Applications
**TYPICAL APPLICATIONS**

![Diagram of LTC1624 High Current 3.3V/6.5A Converter]

**PACKAGE DESCRIPTION** Dimensions in inches (millimeters) unless otherwise noted.

**S8 Package**
8-Lead Plastic Small Outline (Narrow 0.150)
(LTC DWG # 05-08-1610)

- **Sense**
- **V_IN**
- **En/Run**
- **Boost**
- **LTC1624**
- **Vin**
- **1000pF**
- **0.1µF**
- **0.1µF**
- **VOUT**
- **3.3V**
- **6.5A**
- **CIN**
- **22µF**
- **35V**
- **× 3**
- **COUT**
- **100µF**
- **10V**
- **× 3**
- **RSENSE**
- **0.015Ω**
- **D1**
- **MBRD835L**
- **R1**
- **20k**
- **1%**
- **L1**
- **35.7µH**
- **1%**
- **M1**
- ****
- **Panasonic 12TS-7ROLB**
- **Siliconix SUD50N03-10**

* *DIMENSION DOES NOT INCLUDE MOLD FLASH. MOLD FLASH SHALL NOT EXCEED 0.006" (0.152mm) PER SIDE
** *DIMENSION DOES NOT INCLUDE INTERLEAD FLASH. INTERLEAD FLASH SHALL NOT EXCEED 0.010" (0.254mm) PER SIDE

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## TYPICAL APPLICATION

![TYPICAL APPLICATION Diagram](image)

**Figure 23. 5V to 3.3V/10A Converter (Surface Mount)**

### RELATED PARTS

<table>
<thead>
<tr>
<th>PART NUMBER</th>
<th>DESCRIPTION</th>
<th>COMMENTS</th>
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<tbody>
<tr>
<td>LTC1147</td>
<td>High Efficiency Step-Down Controller</td>
<td>100% DC, Burst Mode Operation, 8-Pin SO and PDIP</td>
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<tr>
<td>LTC1148HV/LTC1148</td>
<td>High Efficiency Synchronous Step-Down Controllers</td>
<td>100% DC, Burst Mode Operation, V_IN &lt; 20V</td>
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<td>High Efficiency Synchronous Step-Down Controller</td>
<td>100% DC, Std Threshold MOSFETs, V_IN &lt; 48V</td>
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<td>High Efficiency Synchronous Step-Down Controller</td>
<td>100% DC, Logic Level MOSFETs, V_IN &lt; 40V</td>
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<tr>
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<td>Monolithic 0.6A Step-Down Switching Regulator</td>
<td>100% DC, Burst Mode Operation, 8-Pin SO</td>
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<tr>
<td>LTC1265</td>
<td>1.2A Monolithic High Efficiency Step-Down Switching Regulator</td>
<td>100% DC, Burst Mode Operation, 14-Pin SO</td>
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<td>High Efficiency Synchronous Step-Down Controller, N-Channel Drive</td>
<td>100% DC, Burst Mode Operation, V_IN &lt; 20V</td>
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<tr>
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<td>1.5A, 500kHz Step-Down Switching Regulators</td>
<td>100% DC, Burst Mode Operation, V_IN &lt; 20V</td>
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<tr>
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<td>Monolithic 0.45A Low Noise Current Mode Step-Down Switching Regulators</td>
<td>16- and 20-Pin Narrow SSOP</td>
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<td>Burst Mode Operation, 16-Pin Narrow SO</td>
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<td>Adaptive Power™ Mode, 20- and 24-Pin SSOP</td>
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