

## FEATURES

- 8-Channel Independent Step-Down DC/DCs
- Master-Slave Configurable for Up to 4A Per Output Channel with a Single Inductor
- Independent  $V_{IN}$  Supply for Each DC/DC (2.25V to 5.5V)
- All DC/DCs Have 0.425V to  $V_{IN}$  Output Voltage Range
- Precision Enable Pin Thresholds for Autonomous Sequencing (or I<sup>2</sup>C Control)
- 1MHz to 3MHz Programmable/Synchronizable Oscillator Frequency (2MHz Default)
- I<sup>2</sup>C Selectable Phasing (90° Steps) Per Channel
- Programmable Power-On Reset/Watch Dog/ Pushbutton Timing
- Die Temperature Monitor Output
- 48-Lead (7mm × 7mm) QFN Package

## APPLICATIONS

- General Purpose Multichannel Power Supplies
- Industrial/Automotive/Communications

## DESCRIPTION

The **LTC<sup>®</sup>3375** is a digitally programmable high efficiency multioutput power supply IC. The DC/DCs consist of eight synchronous buck converters ( $I_{OUT}$  up to 1A each) all powered from independent 2.25V to 5.5V input supplies.

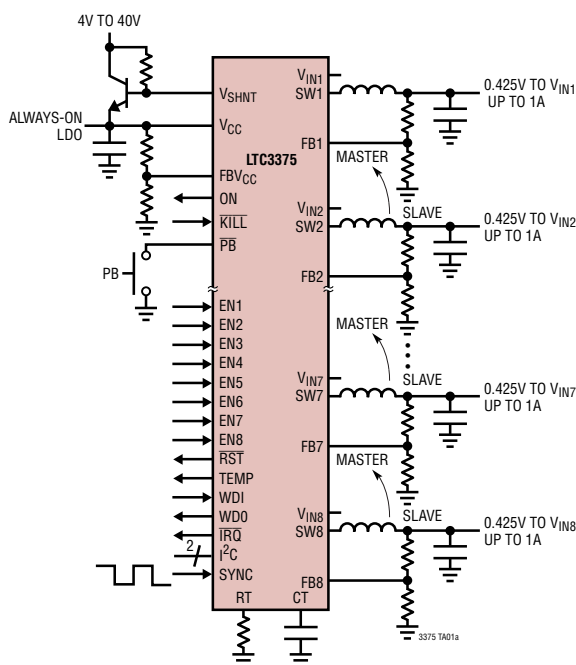
DC/DC enables, output voltages, operating modes, and phasing may all be independently programmed over I<sup>2</sup>C or used in standalone mode via simple I/O with power-up defaults. The DC/DCs may be used independently or in parallel to achieve higher output currents of up to 4A per output with a shared inductor. Alarm levels for high die temperature may also be programmed via I<sup>2</sup>C with a maskable IRQ output for monitoring DC/DC and system faults.

Pushbutton ON/OFF/RESET control, power-on reset, and a watchdog timer provide flexible and reliable power-up sequencing and system monitoring. The LTC3375 is available in a low profile 48-lead 7mm × 7mm QFN package.

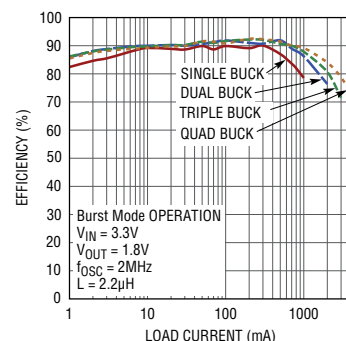
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## TYPICAL APPLICATION

**8-Channel 1A Multioutput Buck Regulator**



**Buck Efficiency vs Load**



3375 TA01b

## TABLE OF CONTENTS

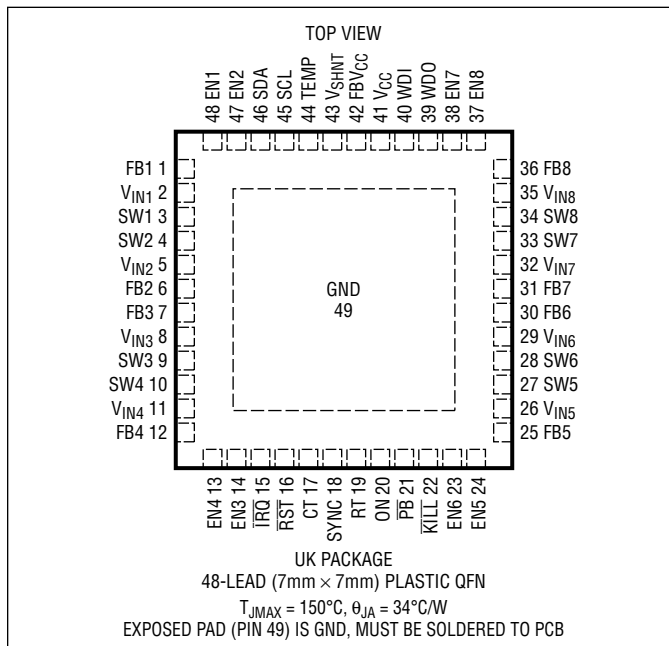
|  |           |   |           |
|--|-----------|---|-----------|
| <b>Features</b> .....  | <b>1</b>  | <b>Applications Information</b> .....                                 | <b>26</b> |
| <b>Applications</b> .....  | <b>1</b>  | Buck Switching Regulator Output Voltage and<br>Feedback Network ..... | 26        |
| <b>Typical Application</b> .....                                 | <b>1</b>  | Buck Regulators .....   | 26        |
| <b>Description</b> .....   | <b>1</b>  | Combined Buck Regulators.....   | 26        |
| <b>Absolute Maximum Ratings</b> .....                            | <b>3</b>  | V <sub>CC</sub> Shunt Regulator .....                                 | 28        |
| <b>Order Information</b> .....                                   | <b>3</b>  | Input and Output Decoupling Capacitor Selection ..                    | 29        |
| <b>Pin Configuration</b> .....                                   | <b>3</b>  | Choosing the C <sub>T</sub> Capacitor .....                           | 29        |
| <b>Electrical Characteristics</b> .....                          | <b>4</b>  | Programming the Global Register.....                                  | 29        |
| <b>Typical Performance Characteristics</b> .....                 | <b>7</b>  | Programming the <b>RST</b> and <b>IRQ</b> Mask Registers .....        | 29        |
| <b>Pin Functions</b> .....                                       | <b>12</b> | Status Byte Read Back .....   | 29        |
| <b>Block Diagram</b> .....                                       | <b>15</b> | PCB Considerations .....  | 31        |
| <b>Operation</b> .....   | <b>16</b> | <b>Typical Applications</b> .....                                     | <b>32</b> |
| Buck Switching Regulators .....                                  | 16        | <b>Package Description</b> .....                                      | <b>35</b> |
| Buck Regulators with Combined Power Stages .....                 | 16        | <b>Typical Application</b> .....                                      | <b>36</b> |
| Pushbutton Interface .....                                       | 17        | <b>Related Parts</b> .....  | <b>36</b> |
| Power-Up and Power-Down Via Pushbutton.....                      | 17        |   |           |
| Power-Up and Power-Down Via Enable Pin or I <sup>2</sup> C ..    | 19        |   |           |
| I <sup>2</sup> C Interface .....                                 | 20        |   |           |
| I <sup>2</sup> C Bus Speed.....                                  | 20        |   |           |
| I <sup>2</sup> C Start and Stop Conditions.....                  | 20        |   |           |
| I <sup>2</sup> C Byte Format .....                               | 20        |   |           |
| I <sup>2</sup> C Acknowledge .....                               | 20        |   |           |
| I <sup>2</sup> C Slave Address .....                             | 21        |   |           |
| I <sup>2</sup> C Sub-Addressed Writing.....                      | 22        |   |           |
| I <sup>2</sup> C Bus Write Operation .....                       | 22        |   |           |
| I <sup>2</sup> C Bus Read Operation .....                        | 22        |   |           |
| Error Condition Reporting Via <b>RST</b> and <b>IRQ</b> Pins.... | 22        |   |           |
| Temperature Monitoring and<br>Overtemperature Protection .....   | 23        |   |           |
| RESET_ALL Functionality .....                                    | 24        |   |           |
| Programming the Operating Frequency .....                        | 24        |   |           |
| V <sub>CC</sub> Shunt Regulator .....                            | 25        |   |           |
| Watchdog Timer .....   | 25        |   |           |

## ABSOLUTE MAXIMUM RATINGS

(Note 1)

$V_{IN1-8}$ ,  $FB1-8$ ,  $EN1-8$ ,  $V_{CC}$ ,  $V_{SHNT}$ ,  $FBV_{CC}$ ,  $CT$ ,  
 $ON$ ,  $KILL$ ,  $\overline{IRQ}$ ,  $\overline{RST}$ ,  $\overline{PB}$ ,  $WDI$ ,  $WDO$ ,  $SYNC$ ,  $RT$ ,  
 $SDA$ ,  $SCL$  ..... -0.3V to 6V  
 $TEMP$  ..... -0.3V to Lesser of ( $V_{CC} + 0.3V$ ) or 6V  
 $I_{\overline{IRQ}}$ ,  $I_{\overline{RST}}$ ,  $I_{WDO}$ ,  $I_{ON}$  ..... 5mA  
 $I_{VSHNT}$  ..... 3mA  
 Operating Junction Temperature Range  
 (Notes 2, 3) ..... -40°C to 150°C  
 Storage Temperature Range ..... -65°C to 150°C

## PIN CONFIGURATION



## ORDER INFORMATION

| LEAD FREE FINISH | TAPE AND REEL    | PART MARKING* | PACKAGE DESCRIPTION             | TEMPERATURE RANGE |
|------------------|------------------|---------------|---------------------------------|-------------------|
| LTC3375EUK#PBF   | LTC3375EUK#TRPBF | LTC3375UK     | 48-Lead (7mm × 7mm) Plastic QFN | -40°C to 125°C    |
| LTC3375IUK#PBF   | LTC3375IUK#TRPBF | LTC3375UK     | 48-Lead (7mm × 7mm) Plastic QFN | -40°C to 125°C    |
| LTC3375HUK#PBF   | LTC3375HUK#TRPBF | LTC3375UK     | 48-Lead (7mm × 7mm) Plastic QFN | -40°C to 150°C    |

Consult LTC Marketing for parts specified with wider operating temperature ranges. \*The temperature grade is identified by a label on the shipping container. Consult LTC Marketing for information on non-standard lead based finish parts.

For more information on lead free part marking, go to: <http://www.linear.com/leadfree/>

For more information on tape and reel specifications, go to: <http://www.linear.com/tapeandreeel/>

## ELECTRICAL CHARACTERISTICS

The ● denotes the specifications which apply over the specified operating junction temperature range, otherwise specifications are at  $T_A = 25^\circ\text{C}$  (Note 2).  $V_{CC} = V_{IN1-8} = 3.3\text{V}$ , unless otherwise specified.

| SYMBOL                           | PARAMETER   | CONDITIONS  | MIN        | TYP      | MAX      | UNITS                |
|----------------------------------|---|---|------------|----------|----------|----------------------|
| $V_{VCC}$                        | $V_{CC}$ Voltage Range  |   | ● 2.7      |          | 5.5      | V                    |
| $V_{VCC\_UVLO}$                  | Undervoltage Threshold on $V_{CC}$  | $V_{CC}$ Voltage Falling  | ● 2.35     | 2.45     | 2.55     | V                    |
|                                  |   | $V_{CC}$ Voltage Rising   | ● 2.45     | 2.55     | 2.65     | V                    |
| $I_{VCC\_ALLOFF}$                | $V_{CC}$ Input Supply Current   | All Switching Regulators in Shutdown, $\overline{PB} = \text{HIGH}$                                     |            | 11       | 25       | $\mu\text{A}$        |
| $I_{VCC}$                        | $V_{CC}$ Input Supply Current   | At Least 1 Buck Active, $\text{SYNC} = 0\text{V}$ , $R_T = 400\text{k}$ , $V_{FB\_BUCK} = 0.85\text{V}$ |            | 50       | 85       | $\mu\text{A}$        |
|                                  |   | At Least 1 Buck Active, $\text{SYNC} = 2\text{MHz}$   |            | 200      | 325      | $\mu\text{A}$        |
| $f_{OSC}$                        | Internal Oscillator Frequency   | $V_{RT} = V_{CC}$ , $\text{SYNC} = 0\text{V}$   | ● 1.8      | 2        | 2.2      | MHz                  |
|                                  |   | $V_{RT} = V_{CC}$ , $\text{SYNC} = 0\text{V}$   | ● 1.75     | 2        | 2.25     | MHz                  |
|                                  |   | $R_{RT} = 400\text{k}$ , $\text{SYNC} = 0\text{V}$  | ● 1.8      | 2        | 2.2      | MHz                  |
| $f_{SYNC}$                       | Synchronization Frequency   | $t_{LOW}$ , $t_{HIGH} > 40\text{ns}$  |            | 1        | 3        | MHz                  |
| $V_{SYNC}$                       | SYNC Level High   |   | ● 1.2      |          |          | V                    |
|                                  | SYNC Level Low  |   | ●          |          | 0.4      | V                    |
| $V_{RT}$                         | RT Servo Voltage  | $R_{RT} = 400\text{k}$  | ● 780      | 800      | 820      | mV                   |
| <b>Temperature Monitor</b>       |   |   |            |          |          |                      |
| $V_{TEMP(\text{ROOM})}$          | TEMP Voltage at $25^\circ\text{C}$  |   |            | 150      |          | mV                   |
| $\Delta V_{TEMP/^\circ\text{C}}$ | $V_{TEMP}$ Slope  |   | ●          | 6.75     |          | mV/ $^\circ\text{C}$ |
| OT                               | Overtemperature Shutdown  | Temperature Rising  |            | 165      |          | $^\circ\text{C}$     |
| OT_HYST                          | Overtemperature Hysteresis  |   |            | 10       |          | $^\circ\text{C}$     |
| DT_WARN                          | Die Temperature Warning Threshold (Die Temperature that Causes $\text{IRQ} = 0$ ) | $\text{DT}[1], \text{DT}[0] = 00$   |            | Inactive |          | $^\circ\text{C}$     |
|                                  |   | $\text{DT}[1], \text{DT}[0] = 01$   |            | 140      |          | $^\circ\text{C}$     |
|                                  |   | $\text{DT}[1], \text{DT}[0] = 10$   |            | 125      |          | $^\circ\text{C}$     |
|                                  |   | $\text{DT}[1], \text{DT}[0] = 11$   |            | 110      |          | $^\circ\text{C}$     |
| <b>1A Buck Regulators</b>        |   |   |            |          |          |                      |
| $V_{BUCK}$                       | Buck Input Voltage Range  |   | ● 2.25     |          | 5.5      | V                    |
| $V_{OUT}$                        |   |   | ● $V_{FB}$ |          | $V_{IN}$ | V                    |
| $V_{IN\_UVLO}$                   | Undervoltage Threshold on $V_{IN}$  | $V_{IN}$ Voltage Falling  | ● 1.95     | 2.05     | 2.15     | V                    |
|                                  |   | $V_{IN}$ Voltage Rising   | ● 2.05     | 2.15     | 2.25     | V                    |
| $I_{VIN\_BUCK}$                  | Burst Mode <sup>®</sup> Operation   | $V_{FB\_BUCK} = 0.85\text{V}$ (Note 4)  |            | 18       | 50       | $\mu\text{A}$        |
|                                  | Forced Continuous Mode Operation  | $I_{SW\_BUCK} = 0\mu\text{A}$ , $V_{FB\_BUCK} = 0\text{V}$  |            | 400      | 550      | $\mu\text{A}$        |
|                                  | Shutdown Input Current  | All Switching Regulators in Shutdown  |            | 0        | 1        | $\mu\text{A}$        |
|                                  | Shutdown Input Current  | At Least One Other Buck Active  |            | 1        | 2        | $\mu\text{A}$        |
| $I_{FWD}$                        | PMOS Current Limit  | (Note 5)  |            | 2.0      | 2.3      | A                    |
| $V_{FB}$ (Default)               | Feedback Regulation Voltage   | Forced Continuous Mode Default (1, 1, 0, 0)   | ● 705      | 725      | 745      | mV                   |
| $V_{FB}$ (High)                  | Feedback Regulation Voltage   | Forced Continuous Mode Full Scale (1, 1, 1, 1)  | ● 780      | 800      | 820      | mV                   |
| $V_{FB}$ (Low)                   | Feedback Regulation Voltage   | Forced Continuous Mode Zero Scale (0, 0, 0, 0)  | ● 405      | 425      | 445      | mV                   |
| $V_{LSB}$                        | $V_{FB}$ Servo Voltage Step Size  |   |            | 25       |          | mV                   |
| $I_{FB}$                         | Feedback Leakage Current  | $V_{FB\_BUCK} = 0.85\text{V}$   |            | -50      | 50       | nA                   |
| DMAX                             | Maximum Duty Cycle  | $V_{FB\_BUCK} = 0\text{V}$  | ● 100      |          |          | %                    |
| $R_{PMOS}$                       | PMOS On-Resistance  | $I_{SW\_BUCK} = 100\text{mA}$   |            | 265      |          | $\text{m}\Omega$     |
| $R_{NMOS}$                       | NMOS On-Resistance  | $I_{SW\_BUCK} = -100\text{mA}$  |            | 280      |          | $\text{m}\Omega$     |
| $I_{LEAKP}$                      | PMOS Leakage Current  | $\text{EN\_BUCK} = 0$   |            | -2       | 2        | $\mu\text{A}$        |
| $I_{LEAKN}$                      | NMOS Leakage Current  | $\text{EN\_BUCK} = 0$   |            | -2       | 2        | $\mu\text{A}$        |
| $R_{SWPD}$                       | Output Pull-Down Resistance in Shutdown   | $\text{EN\_BUCK} = 0$ ( $I^2\text{C}$ Bit Set)  |            | 1        |          | $\text{k}\Omega$     |
| $t_{SS}$                         | Soft-Start Time   | Default (1, 1, 0, 0) Reference Voltage  |            | 1        |          | ms                   |

3375fc

## ELECTRICAL CHARACTERISTICS

The ● denotes the specifications which apply over the specified operating junction temperature range, otherwise specifications are at  $T_A = 25^\circ\text{C}$  (Note 2).  $V_{CC} = V_{IN1-8} = 3.3\text{V}$ , unless otherwise specified.

| SYMBOL   | PARAMETER  | CONDITIONS                                       | MIN  | TYP           | MAX  | UNITS         |
|--|--|--|------|---------------|------|---------------|
| $V_{PGOOD(FALL)}$  | Falling PGOOD Threshold Voltage                        | Full-Scale (1, 1, 1, 1) Reference Voltage        |      | 92.5          |      | %             |
| $V_{PGOOD(HYS)}$   | PGOOD Hysteresis                                       |  |      | 1             |      | %             |
| <b>Buck Regulators Combined</b>                                |  |  |      |               |      |               |
| $I_{FWD2}$   | PMOS Current Limit                                     | 2 Buck Converters Combined (Note 5)              |      | 4.6           |      | A             |
| $I_{FWD3}$   | PMOS Current Limit                                     | 3 Buck Converters Combined (Note 5)              |      | 6.9           |      | A             |
| $I_{FWD4}$   | PMOS Current Limit                                     | 4 Buck Converters Combined (Note 5)              |      | 9.2           |      | A             |
| <b>V<sub>CC</sub> Regulator</b>                                |  |  |      |               |      |               |
| $V_{FBVCC}$  | FBV <sub>CC</sub> Regulation Voltage                   |  | 1.17 | 1.2           | 1.23 | V             |
| $R_{REG}$  | Pull-Down Resistance for V <sub>CC</sub> (Regulator)   |  |      | 200           |      | $\Omega$      |
| $V_{SHNT\_MAX}$  | V <sub>SHNT</sub> Clamp Voltage                        | $I_{SHNT} = 2\text{mA}$ , $FBV_{CC} = 0\text{V}$ |      | 6.1           |      | V             |
| $R_{CLAMP}$  | Pull-Down Resistance for V <sub>SHNT</sub> (Clamp)     |  |      | 200           |      | $\Omega$      |
| <b>I<sup>2</sup>C Port</b>                                     |  |  |      |               |      |               |
| ADDRESS  | I <sup>2</sup> C Address                               |  | ●    | 0110100[R/WB] |      |               |
| $V_{IH}$   | Input High Voltage                                     | SDA/SCL  | ●    | 1.2           |      | V             |
| $V_{IL}$   | Input Low Voltage                                      | SDA/SCL  | ●    |               | 0.4  | V             |
| $I_{IH}$   | Input High Current                                     | SDA/SCL  |      |               | 50   | nA            |
| $I_{IL}$   | Input Low Current                                      | SDA/SCL  |      |               | 50   | nA            |
| $V_{OL\_SDA}$  | SDA Output Low Voltage                                 | $I_{SDA} = 3\text{mA}$                           |      |               | 0.4  | V             |
| $f_{SCL}$  | Clock Operating Frequency                              |  |      |               | 400  | kHz           |
| $t_{BUF}$  | Bus Free Time Between Stop and Start Condition         |  |      | 1.3           |      | $\mu\text{s}$ |
| $t_{HD\_SDA}$  | Hold Time After Repeated Start Condition               |  |      | 0.6           |      | $\mu\text{s}$ |
| $t_{SU\_STA}$  | Repeated Start Condition Set-Up Time                   |  |      | 0.6           |      | $\mu\text{s}$ |
| $t_{SU\_STO}$  | Stop Condition Set-Up Time                             |  |      | 0.6           |      | $\mu\text{s}$ |
| $t_{HD\_DAT(O)}$   | Data Hold Time Output                                  |  |      | 0             | 900  | ns            |
| $t_{HD\_DAT(I)}$   | Data Hold Time Input                                   |  |      | 0             |      | ns            |
| $t_{SU\_DAT}$  | Data Set-Up Time                                       |  |      | 250           |      | ns            |
| $t_{LOW}$  | SCL Clock Low Period                                   |  |      | 1.3           |      | $\mu\text{s}$ |
| $t_{HIGH}$   | SCL Clock High Period                                  |  |      | 0.6           |      | $\mu\text{s}$ |
| $t_f$  | Clock/Data Fall Time                                   | $C_B = \text{Capacitance of One Bus Line (pF)}$  |      | $20+0.1C_B$   | 300  | ns            |
| $t_r$  | Clock/Data Rise Time                                   | $C_B = \text{Capacitance of One Bus Line (pF)}$  |      | $20+0.1C_B$   | 300  | ns            |
| <b>Interface Logic Pins (ON, KILL, RST, IRQ, PB, WDI, WDO)</b> |  |  |      |               |      |               |
| $I_{OH}$   | Output High Leakage Current                            | ON, RST, IRQ, WDO 5.5V at Pin                    |      | -1            | 1    | $\mu\text{A}$ |
| $V_{OL}$   | Output Low Voltage                                     | ON, RST, IRQ, WDO 3mA Into Pin                   |      | 0.1           | 0.4  | V             |
| $V_{IH}$   | Input High Threshold                                   | KILL, PB, WDI                                    | ●    | 1.2           |      | V             |
| $V_{IL}$   | Input Low Threshold                                    | KILL, PB, WDI                                    | ●    |               | 0.4  | V             |
| $t_{WDI}$  | Time From Last WDI                                     |  |      | 1.5           |      | sec           |
| $t_{WDO}$  | WDO Low Time Absent a Transition at WDI                |  |      | 200           |      | ms            |
| $t_{WDRESET}$  | Time From a WDI Transition Until the WD Timer Is Reset |  |      |               | 2    | $\mu\text{s}$ |

## ELECTRICAL CHARACTERISTICS

The ● denotes the specifications which apply over the specified operating junction temperature range, otherwise specifications are at  $T_A = 25^\circ\text{C}$  (Note 2).  $V_{CC} = V_{IN1-8} = 3.3\text{V}$ , unless otherwise specified.

| SYMBOL   | PARAMETER   | CONDITIONS                           |   | MIN | TYP | MAX  | UNITS         |
|--|---|--------------------------------------|---|-----|-----|------|---------------|
| <b>Interface Logic Pins (EN1, EN2, EN3, EN4, EN5, EN6, EN7, EN8)</b> |   |                                      |   |     |     |      |               |
| $V_{HI\_ALLOFF}$   | Enable Rising Threshold   | All Regulators Disabled              | ● | 400 | 730 | 1200 | mV            |
| $V_{EN\_HYS}$  | Enable Hysteresis   |                                      |   |     | 60  |      | mV            |
| $V_{HI}$   | Enable Rising Threshold   | At Least One Regulator Enabled       | ● | 380 | 400 | 420  | mV            |
| $I_{EN}$   | Enable Pin Leakage Current  | $EN = V_{CC} = V_{IN} = 5.5\text{V}$ |   | -1  |     | 1    | $\mu\text{A}$ |
| <b>Pushbutton Parameters, <math>C_T = 0.01\mu\text{F}</math></b>     |   |                                      |   |     |     |      |               |
| $t_{PB\_LO}$   | $\overline{PB}$ Low Time to $\overline{IRQ}$ Low  | ON High                              |   | 28  | 50  | 72   | ms            |
| $t_{PB\_ON}$   | $\overline{PB}$ Low Time to ON High   |                                      |   | 140 | 200 | 260  | ms            |
| $t_{PB\_OFF}$  | $\overline{PB}$ Low to ON Forced Low  |                                      |   | 7   | 10  | 13   | sec           |
| $t_{HR}$   | Time for Which All Enabled Regulators Are Disabled After $\overline{KILL}$ is Asserted High | ON High                              |   | 0.7 | 1   | 1.3  | sec           |
| $t_{\overline{IRQ}\_PW}$   | $\overline{IRQ}$ Minimum Pulse Width  | ON High                              |   | 28  | 50  | 72   | ms            |
| $t_{KILLH}$  | Time in Which $\overline{KILL}$ Must Be Asserted High                                       | After ON Rising Edge                 |   | 7   | 10  | 13   | sec           |
| $t_{KILLL}$  | $\overline{KILL}$ Low Time to ON Low  | ON High                              |   | 28  | 50  | 72   | ms            |
| $t_{RST}$  | $\overline{RST}$ Assertion Delay  |                                      |   | 160 | 230 | 300  | ms            |

**Note 1:** Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

**Note 2:** The LTC3375 is tested under pulsed load conditions such that  $T_J \approx T_A$ . The LTC3375E is guaranteed to meet specifications from  $0^\circ\text{C}$  to  $85^\circ\text{C}$  junction temperature. Specifications over the  $-40^\circ\text{C}$  to  $125^\circ\text{C}$  operating junction temperature range are assured by design, characterization and correlation with statistical process controls. The LTC3375I is guaranteed over the  $-40^\circ\text{C}$  to  $125^\circ\text{C}$  operating junction temperature range. The LTC3375H is guaranteed over the  $-40^\circ\text{C}$  to  $150^\circ\text{C}$  operating junction temperature range. High junction temperatures degrade operating lifetimes; operating lifetime is derated for junction temperatures greater than  $125^\circ\text{C}$ . Note that the maximum ambient temperature consistent with these specifications is determined by specific operating conditions in conjunction with board layout, the rated package thermal impedance and other environmental factors. The junction temperature

( $T_J$  in  $^\circ\text{C}$ ) is calculated from the ambient temperature ( $T_A$  in  $^\circ\text{C}$ ) and power dissipation ( $P_D$  in Watts) according to the formula:

$$T_J = T_A + (P_D \cdot \theta_{JA})$$

where  $\theta_{JA}$  (in  $^\circ\text{C}/\text{W}$ ) is the package thermal impedance.

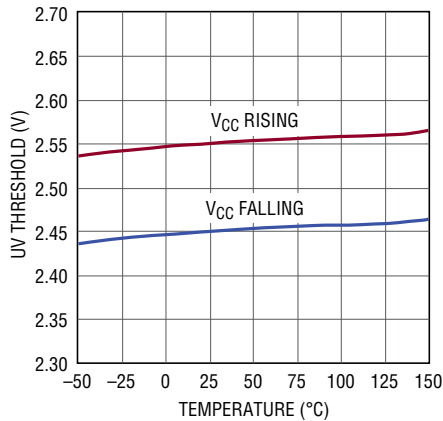
**Note 3:** The LTC3375 includes overtemperature protection which protects the device during momentary overload conditions. Junction temperatures will exceed  $150^\circ\text{C}$  when overtemperature protection is active. Continuous operation above the specified maximum operating junction temperature may impair device reliability.

**Note 4:** Static current, switches not switching. Actual current may be higher due to gate charge losses at the switching frequency.

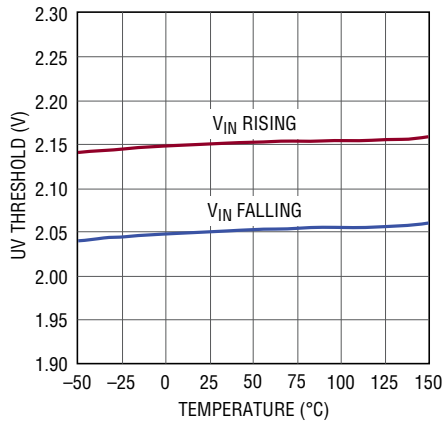
**Note 5:** The current limit features of this part are intended to protect the IC from short term or intermittent fault conditions. Continuous operation above the maximum specified pin current rating may result in device degradation over time.

# TYPICAL PERFORMANCE CHARACTERISTICS

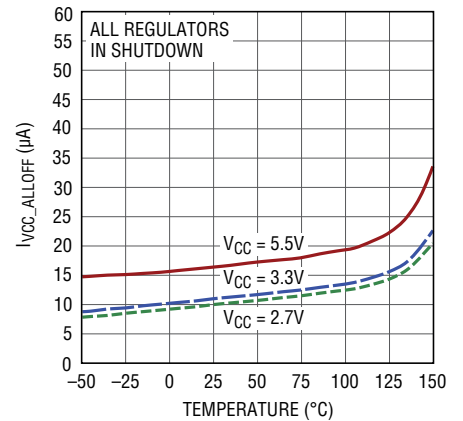
**V<sub>CC</sub> Undervoltage Threshold vs Temperature**



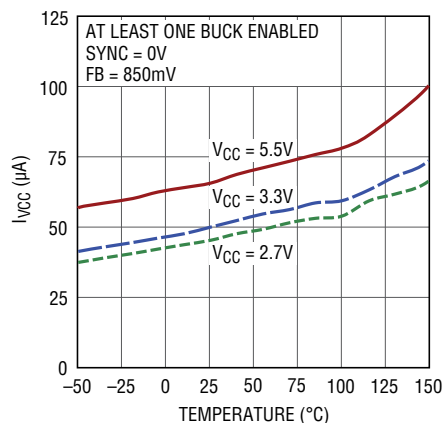
**Buck V<sub>IN</sub> Undervoltage Threshold vs Temperature**



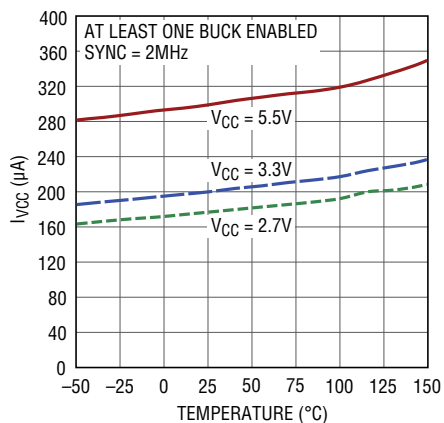
**V<sub>CC</sub> Supply Current vs Temperature**



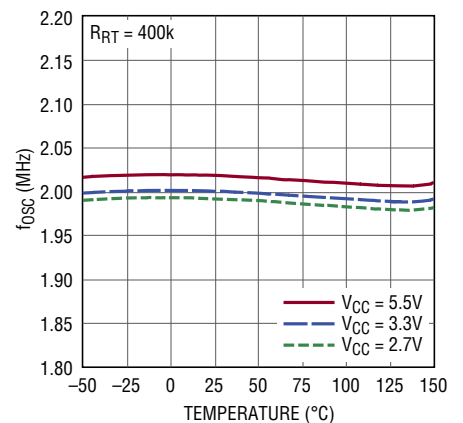
**V<sub>CC</sub> Supply Current vs Temperature**



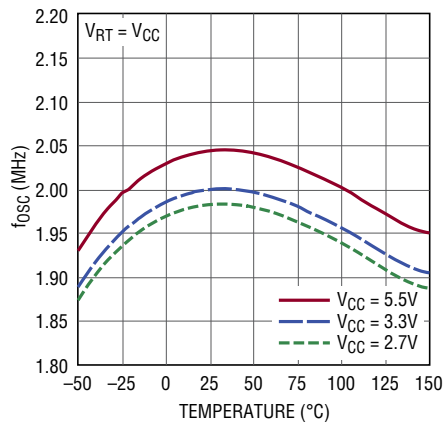
**V<sub>CC</sub> Supply Current vs Temperature**



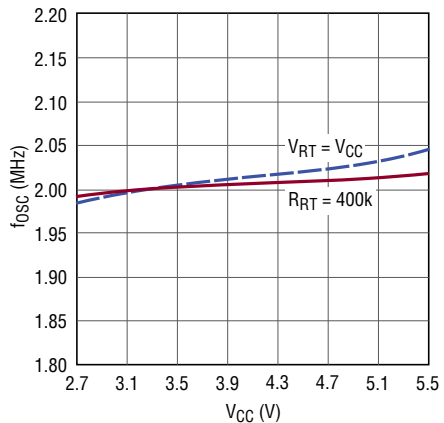
**RT Programmed Oscillator Frequency vs Temperature**



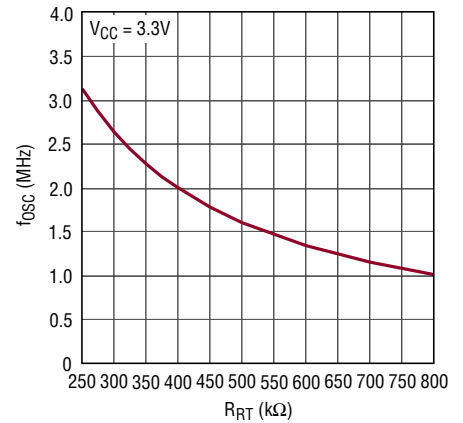
**Default Oscillator Frequency vs Temperature**



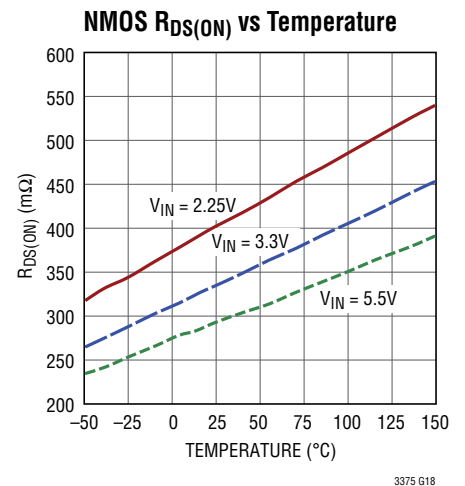
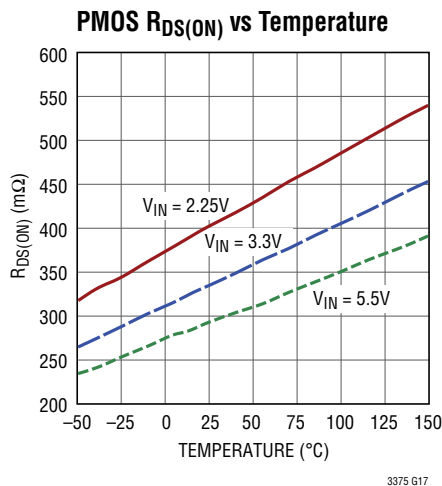
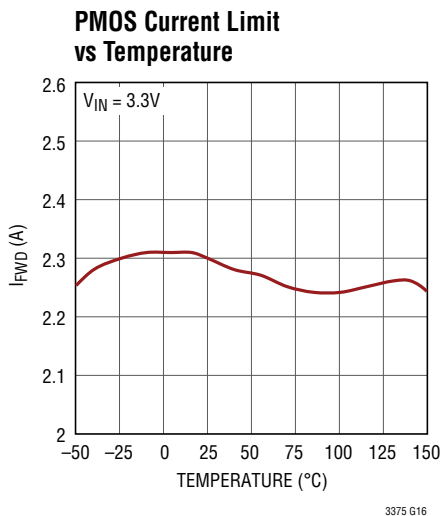
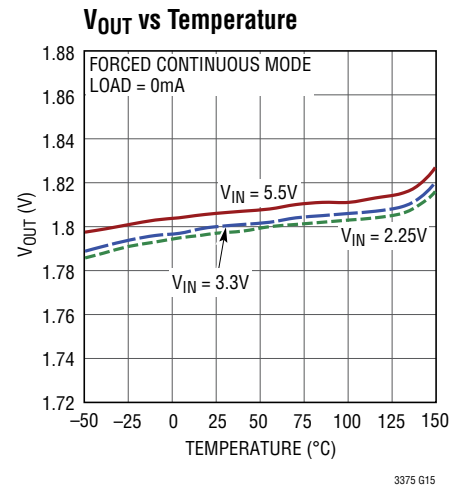
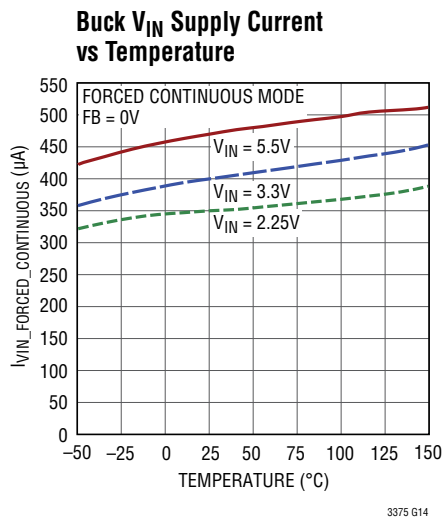
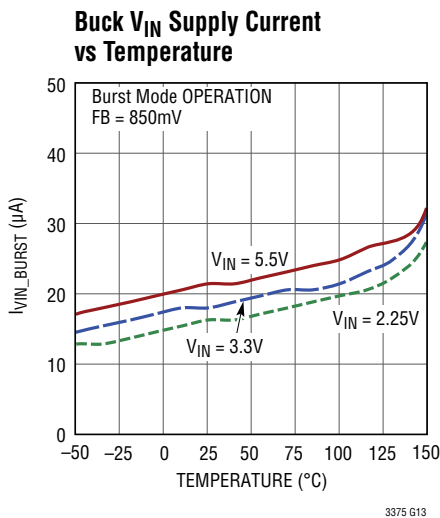
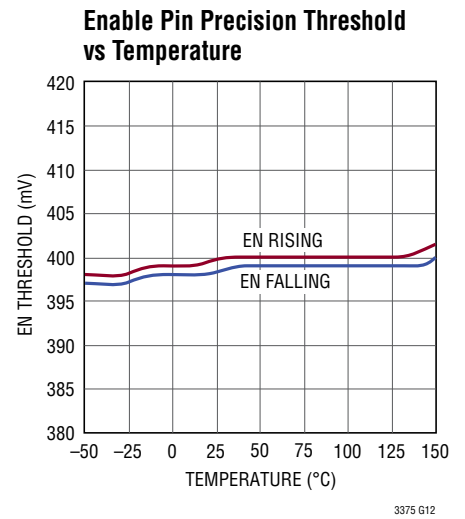
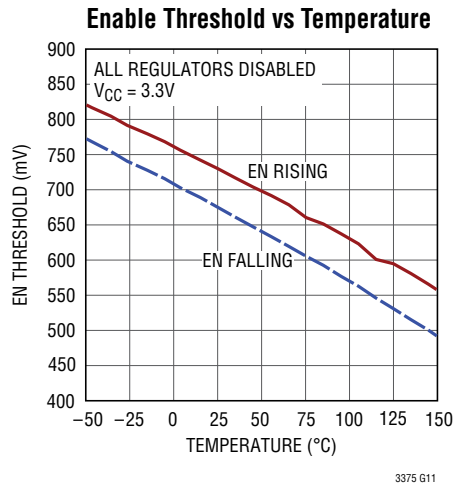
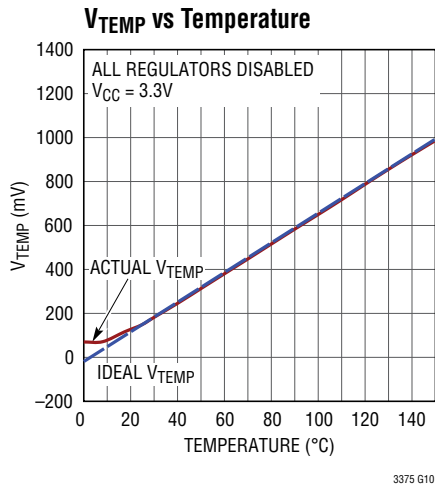
**Oscillator Frequency vs V<sub>CC</sub>**



**Oscillator Frequency vs R<sub>T</sub>**

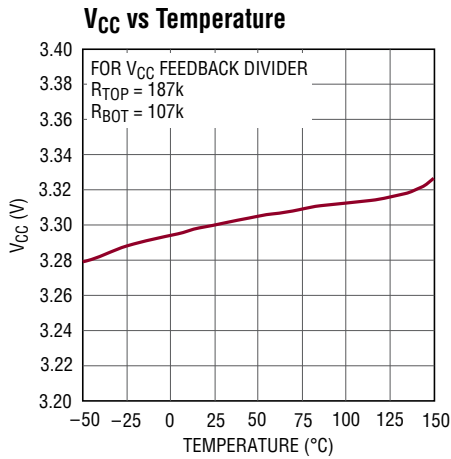


## TYPICAL PERFORMANCE CHARACTERISTICS

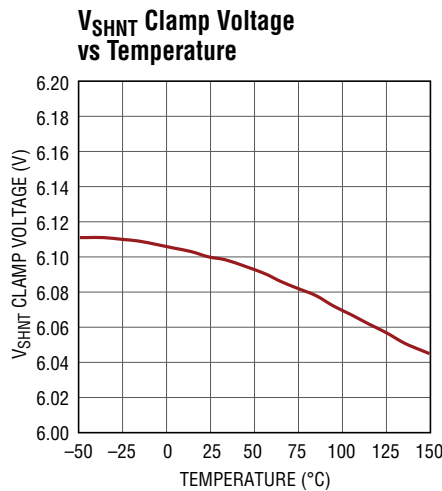




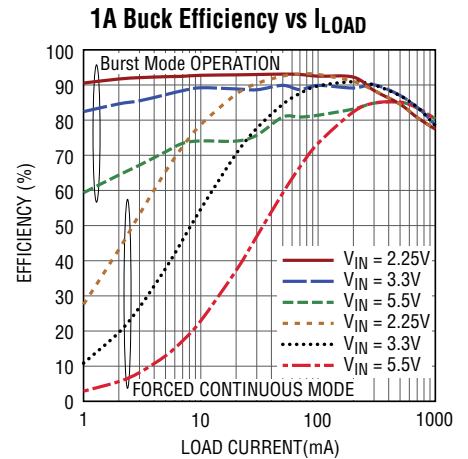
# TYPICAL PERFORMANCE CHARACTERISTICS



3375 G19

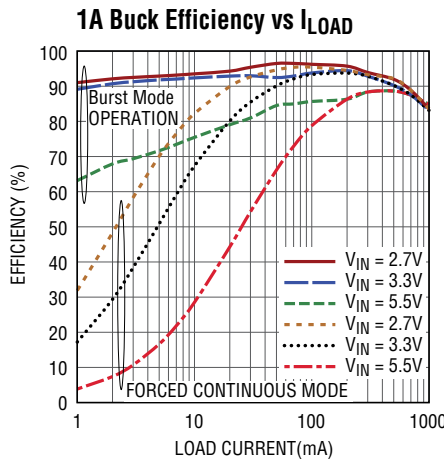


3375 G20



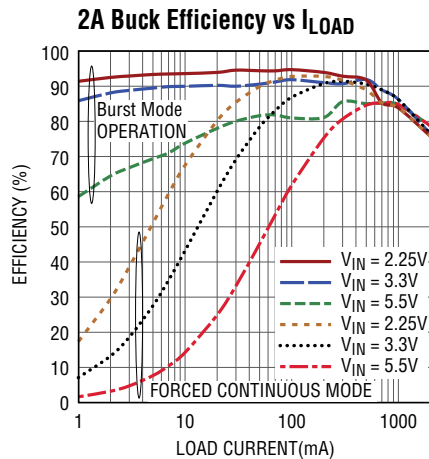
$V_{OUT} = 1.8V$   
 $f_{OSC} = 2MHz$   
 $L = 2.2\mu H$

3375 G21



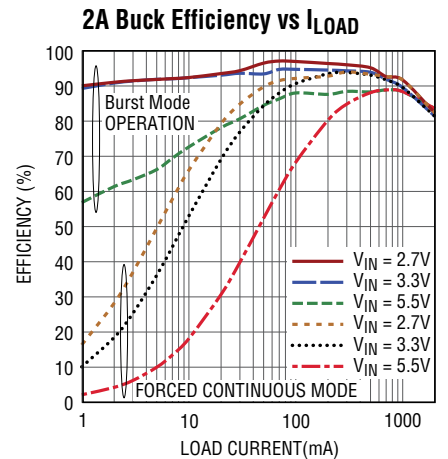
$V_{OUT} = 2.5V$   
 $f_{OSC} = 2MHz$   
 $L = 2.2\mu H$

3375 G22



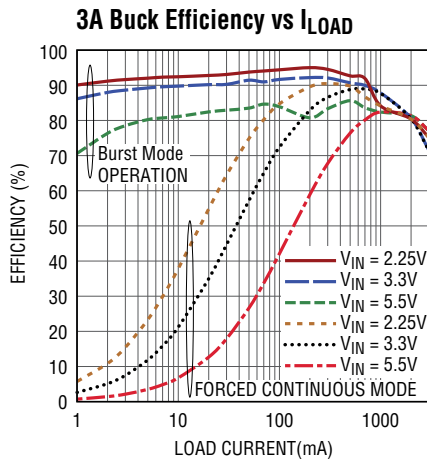
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 $f_{OSC} = 2MHz$   
 $L = 2.2\mu H$

3375 G23



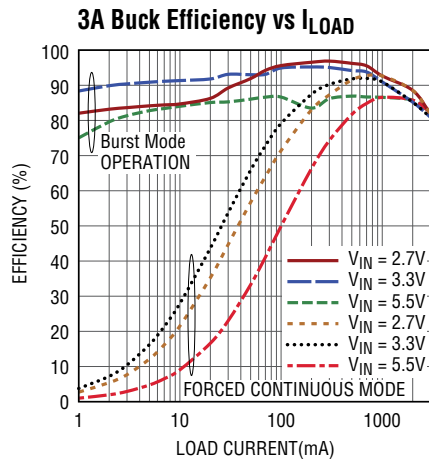
$V_{OUT} = 2.5V$   
 $f_{OSC} = 2MHz$   
 $L = 2.2\mu H$

3375 G24



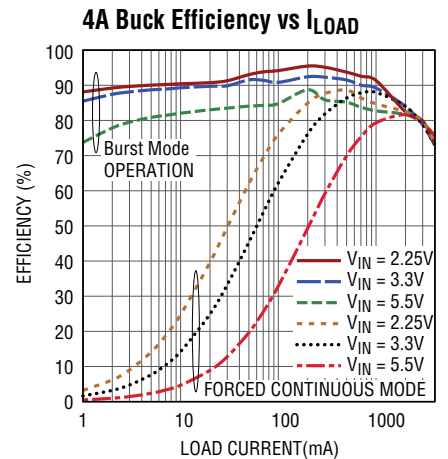
$V_{OUT} = 1.8V$   
 $f_{OSC} = 2MHz$   
 $L = 2.2\mu H$

3375 G25



$V_{OUT} = 2.5V$   
 $f_{OSC} = 2MHz$   
 $L = 2.2\mu H$

3375 G26

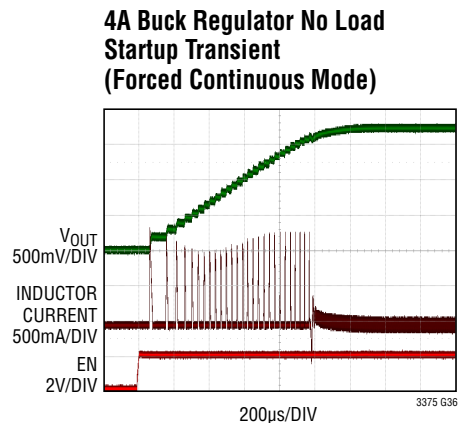
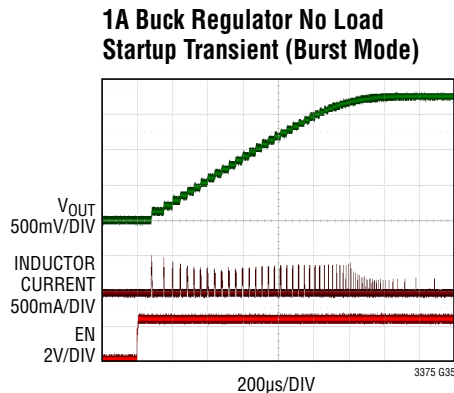
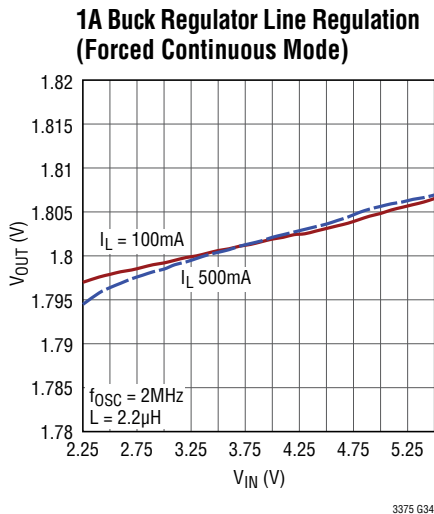
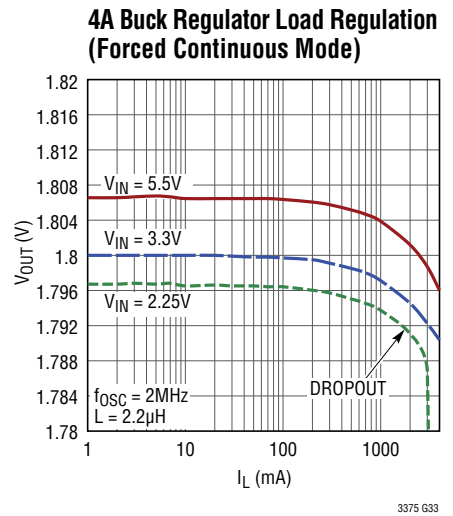
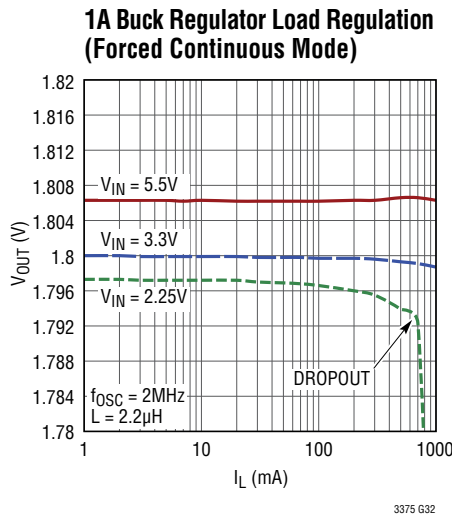
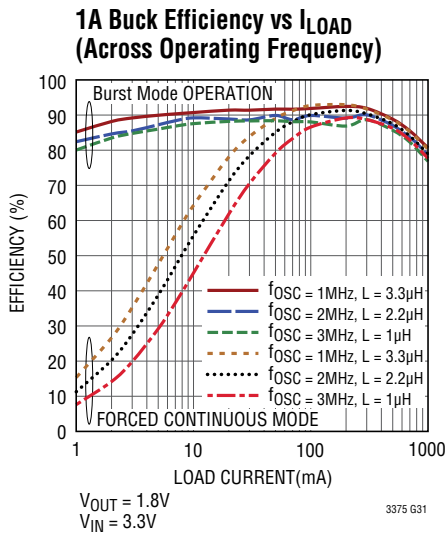
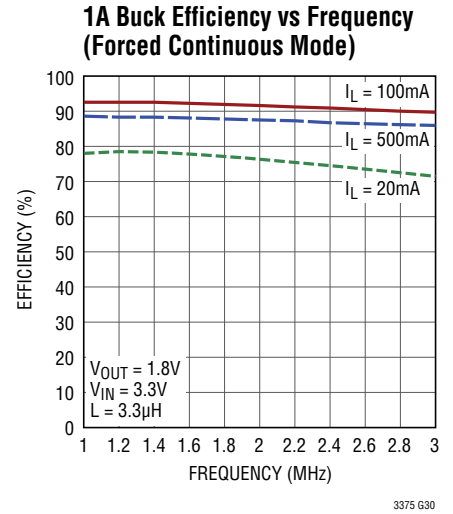
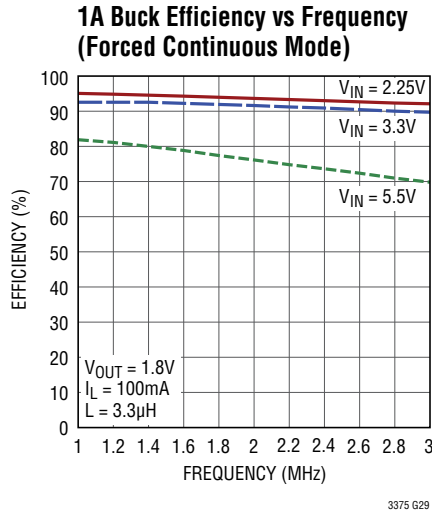
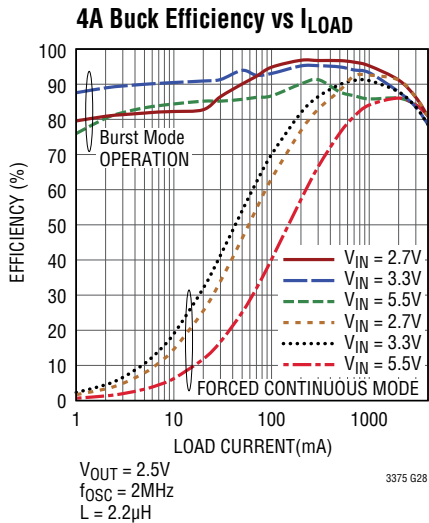


$V_{OUT} = 1.8V$   
 $f_{OSC} = 2MHz$   
 $L = 2.2\mu H$

3375 G27

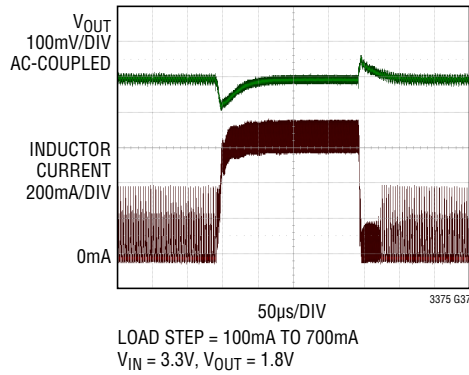
3375fc

# TYPICAL PERFORMANCE CHARACTERISTICS

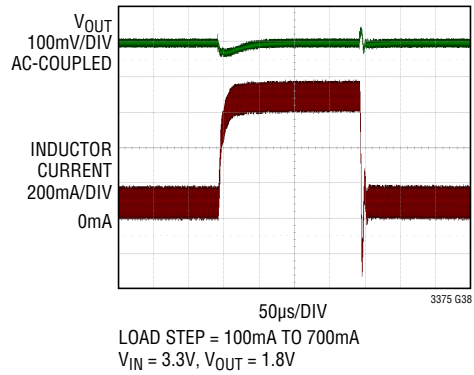


# TYPICAL PERFORMANCE CHARACTERISTICS

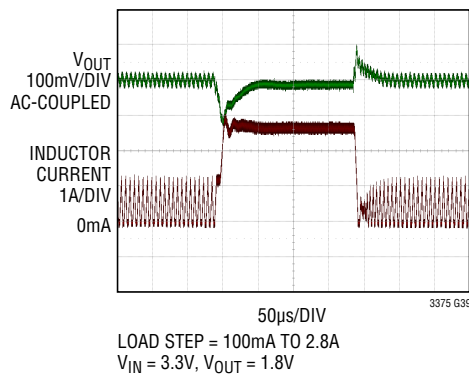
**1A Buck Regulator, Transient Response (Burst Mode)**



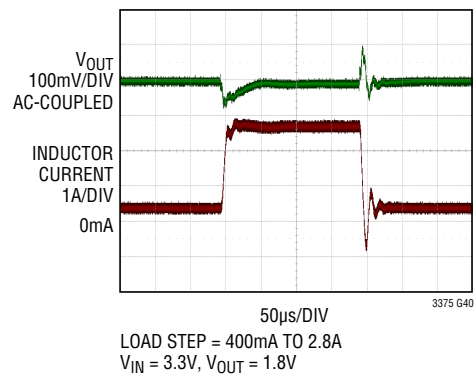
**1A Buck Regulator, Transient Response (Forced Continuous Mode)**



**4A Buck Regulator, Transient Response (Burst Mode)**



**4A Buck Regulator, Transient Response (Forced Continuous Mode)**



## PIN FUNCTIONS

**FB1 (Pin 1):** Buck Regulator 1 Feedback Pin. Receives feedback by a resistor divider connected across the output.

**V<sub>IN1</sub> (Pin 2):** Buck Regulator 1 Input Supply. Bypass to GND with a 10 $\mu$ F or larger ceramic capacitor.

**SW1 (Pin 3):** Buck Regulator 1 Switch Node. External inductor connects to this pin.

**SW2 (Pin 4):** Buck Regulator 2 Switch Node. External inductor connects to this pin.

**V<sub>IN2</sub> (Pin 5):** Buck Regulator 2 Input Supply. Bypass to GND with a 10 $\mu$ F or larger ceramic capacitor. May be driven by an independent supply or must be shorted to V<sub>IN1</sub> when buck regulator 2 is combined with buck regulator 1 for higher current.

**FB2 (Pin 6):** Buck Regulator 2 Feedback Pin. Receives feedback by a resistor divider connected across the output. Connecting FB2 to V<sub>IN2</sub> combines buck regulator 2 with buck regulator 1 for higher current. Up to 4 converters may be combined in this way.

**FB3 (Pin 7):** Buck Regulator 3 Feedback Pin. Receives feedback by a resistor divider connected across the output. Connecting FB3 to V<sub>IN3</sub> combines buck regulator 3 with buck regulator 2 for higher current. Up to 4 converters may be combined in this way.

**V<sub>IN3</sub> (Pin 8):** Buck Regulator 3 Input Supply. Bypass to GND with a 10 $\mu$ F or larger ceramic capacitor. May be driven by an independent supply or must be shorted to V<sub>IN2</sub> when buck regulator 3 is combined with buck regulator 2 for higher current.

**SW3 (Pin 9):** Buck Regulator 3 Switch Node. External inductor connects to this pin.

**SW4 (Pin 10):** Buck Regulator 4 Switch Node. External inductor connects to this pin.

**V<sub>IN4</sub> (Pin 11):** Buck Regulator 4 Input Supply. Bypass to GND with a 10 $\mu$ F or larger ceramic capacitor. May be driven by an independent supply or must be shorted to V<sub>IN3</sub> when buck regulator 4 is combined with buck regulator 3 for higher current.

**FB4 (Pin 12):** Buck Regulator 4 Feedback Pin. Receives feedback by a resistor divider connected across the output. Connecting FB4 to V<sub>IN4</sub> combines buck regulator 4 with buck regulator 3 for higher current. Up to 4 converters may be combined in this way.

**EN4 (Pin 13):** Buck Regulator 4 Enable Input. Active high.

**EN3 (Pin 14):** Buck Regulator 3 Enable Input. Active high.

**IRQ (Pin 15):** Interrupt Pin (Active Low). Open-drain output. When an undervoltage, die temperature, or unmasked error condition is detected, this pin is driven LOW.

**RST (Pin 16):** Reset Pin (Active Low). Open-drain output. When the regulated output voltage of any unmasked enabled switching regulator is more than 7.5% below its programmed level, this pin is driven LOW. Assertion delay is scaled by the C<sub>T</sub> capacitor. When all buck regulators are disabled  $\overline{\text{RST}}$  is driven LOW.

**CT (Pin 17):** Timing Capacitor Pin. A capacitor connected to GND sets a time constant which is scaled for use by the ON, KILL,  $\overline{\text{PB}}$ ,  $\overline{\text{RST}}$  and  $\overline{\text{IRQ}}$  pins.

**SYNC (Pin 18):** Oscillator Synchronization Pin. Driving SYNC with an external clock signal will synchronize all switchers to the applied frequency. The slope compensation is automatically adapted to the external clock frequency. The absence of an external clock signal will enable the frequency programmed by the RT pin. Do not float. SYNC should be held at ground if not used.

**RT (Pin 19):** Oscillator Frequency Pin. This pin provides two modes of setting the switching frequency. Connecting a resistor from RT to ground will set the switching frequency based on the resistor value. If RT is tied to V<sub>CC</sub> the default internal 2MHz oscillator will be used. Do not float.

## PIN FUNCTIONS

**ON (Pin 20):** Open-Drain Output. When the  $\overline{\text{PB}}$  pin is pressed and released, the signal is debounced and the ON signal is held HIGH for a minimum time period that is scaled by the  $C_T$  capacitor. ON is forced low if: a)  $\overline{\text{KILL}}$  is not driven high (by  $\mu\text{P}$ ) within 10 seconds of the initial valid  $\overline{\text{PB}}$  power turn-on event, b)  $\overline{\text{KILL}}$  is driven low during normal operation, c)  $\overline{\text{PB}}$  is pressed and held low for 10 seconds during normal operation, d) a RESET\_ALL I<sup>2</sup>C command is written. This pin can connect directly to a DC/DC converter enable pin that provides an internal pull-up. Otherwise a pull-up resistor to an external supply is required. All associated times are scaled by the  $C_T$  capacitor.

**$\overline{\text{PB}}$  (Pin 21):** Pushbutton Input. Active low.  $\overline{\text{PB}}$  is internally pulled to  $V_{\text{CC}}$  through a 420k (typical) resistor.

**$\overline{\text{KILL}}$  (Pin 22):** Kill Input Pin. Forcing  $\overline{\text{KILL}}$  low releases the ON output which in turn is forced low. While  $\overline{\text{KILL}}$  is low, the buck converters will be forced to power down and will remain powered down for 1 second (scaled by the  $C_T$  capacitor) after  $\overline{\text{KILL}}$  returns high. During system turn-on, this pin is blanked by a 10 second (scaled by the  $C_T$  capacitor) ( $t_{\text{KILLH}}$ ) to allow the system to pull  $\overline{\text{KILL}}$  high. If unused, connect to  $V_{\text{CC}}$ .

**EN6 (Pin 23):** Buck Regulator 6 Enable Input. Active high.

**EN5 (Pin 24):** Buck Regulator 5 Enable Input. Active high.

**FB5 (Pin 25):** Buck Regulator 5 Feedback Pin. Receives feedback by a resistor divider connected across the output. Connecting FB5 to  $V_{\text{IN5}}$  combines buck regulator 5 with buck regulator 4 for higher current. Up to 4 converters may be combined in this way.

**$V_{\text{IN5}}$  (Pin 26):** Buck Regulator 5 Input Supply. Bypass to GND with a 10 $\mu\text{F}$  or larger ceramic capacitor. May be driven by an independent supply or must be shorted to  $V_{\text{IN4}}$  when buck regulator 5 is combined with buck regulator 4 for higher current.

**SW5 (Pin 27):** Buck Regulator 5 Switch Node. External inductor connects to this pin.

**SW6 (Pin 28):** Buck Regulator 6 Switch Node. External inductor connects to this pin.

**$V_{\text{IN6}}$  (Pin 29):** Buck Regulator 6 Input Supply. Bypass to GND with a 10 $\mu\text{F}$  or larger ceramic capacitor. May be driven by an independent supply or must be shorted to  $V_{\text{IN5}}$  when buck regulator 6 is combined with buck regulator 5 for higher current.

**FB6 (Pin 30):** Buck Regulator 6 Feedback Pin. Receives feedback by a resistor divider connected across the output. Connecting FB6 to  $V_{\text{IN6}}$  combines buck regulator 6 with buck regulator 5 for higher current. Up to 4 converters may be combined in this way.

**FB7 (Pin 31):** Buck Regulator 7 Feedback Pin. Receives feedback by a resistor divider connected across the output. Connecting FB7 to  $V_{\text{IN7}}$  combines buck regulator 7 with buck regulator 6 for higher current. Up to 4 converters may be combined in this way.

**$V_{\text{IN7}}$  (Pin 32):** Buck Regulator 7 Input Supply. Bypass to GND with a 10 $\mu\text{F}$  or larger ceramic capacitor. May be driven by an independent supply or must be shorted to  $V_{\text{IN6}}$  when buck regulator 7 is combined with buck regulator 6 for higher current.

**SW7 (Pin 33):** Buck Regulator 7 Switch Node. External inductor connects to this pin.

**SW8 (Pin 34):** Buck Regulator 8 Switch Node. External inductor connects to this pin.

**$V_{\text{IN8}}$  (Pin 35):** Buck Regulator 8 Input Supply. Bypass to GND with a 10 $\mu\text{F}$  or larger ceramic capacitor. May be driven by an independent supply or must be shorted to  $V_{\text{IN7}}$  when buck regulator 8 is combined with buck regulator 7 for higher current.

**FB8 (Pin 36):** Buck Regulator 8 Feedback Pin. Receives feedback by a resistor divider connected across the output. Connecting FB8 to  $V_{\text{IN8}}$  combines buck regulator 8 with buck regulator 7 for higher current. Up to 4 converters may be combined in this way.

**EN8 (Pin 37):** Buck Regulator 8 Enable Input. Active high.

**EN7 (Pin 38):** Buck Regulator 7 Enable Input. Active high.

## PIN FUNCTIONS

**WDO (Pin 39):** Watchdog Timer Output. Open-drain output. WDO is pulled low for 200ms during a watchdog timer failure.

**WDI (Pin 40):** Watchdog Timer Input. The WDI pin must be toggled either low to high or high to low every 1.5 seconds. Failure to toggle WDI results in the WDO pin being pulled low for 200ms.

**V<sub>CC</sub> (Pin 41):** Always-On LDO Output Voltage/Internal Bias Supply. When used as a regulator, V<sub>CC</sub> should be connected to the emitter/source of the external LDO NPN/NFET transistor. V<sub>CC</sub> serves as a low voltage rail that may be used to provide power to external circuitry, and is also used to power the internal top level circuitry of the LTC3375. Alternatively the V<sub>CC</sub> pin may be connected to a 2.7V to 5.5V external power supply. In this case FBV<sub>CC</sub> and V<sub>SHNT</sub> should be tied to ground.

**FBV<sub>CC</sub> (Pin 42):** Always-On LDO Feedback Pin. Receives feedback by a resistor divider connected across V<sub>CC</sub>.

**V<sub>SHNT</sub> (Pin 43):** Shunt Regulator Base Control Voltage. V<sub>SHNT</sub> should be connected to the base/gate of an external high voltage NPN/NFET transistor and to its collector/drain through a resistor.

**TEMP (Pin 44):** Temperature Indication Pin. TEMP outputs a voltage of 150mV (typical) at room temperature. The TEMP voltage will change by 6.75mV/°C (typical) giving an external indication of the LTC3375 internal die temperature.

**SCL (Pin 45):** Serial Clock Line for I<sup>2</sup>C Port.

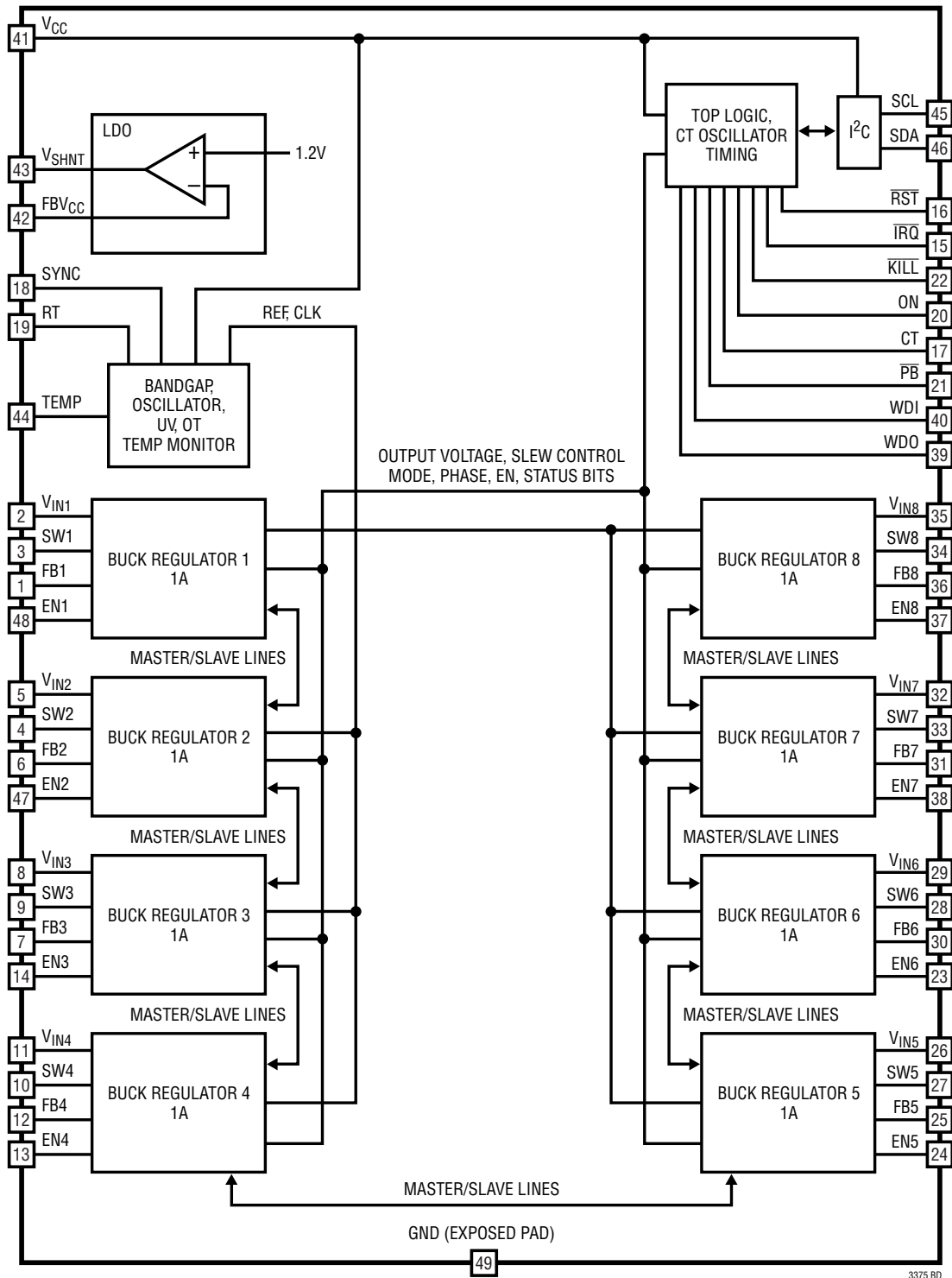
**SDA (Pin 46):** Serial Data Line for I<sup>2</sup>C Port. Open-drain output during read back.

**EN2 (Pin 47):** Buck Regulator 2 Enable Input. Active high.

**EN1 (Pin 48):** Buck Regulator 1 Enable Input. Active high.

**GND (Exposed Pad Pin 49):** Ground. The exposed pad must be connected to a continuous ground plane on the printed circuit board directly under the LTC3375 for electrical contact and rated thermal performance.

# BLOCK DIAGRAM



3375 BD

## OPERATION

### Buck Switching Regulators

The LTC3375 contains eight monolithic 1A synchronous buck switching regulators. All of the switching regulators are internally compensated and need only external feedback resistors to set the output voltage. The switching regulators offer two operating modes: Burst Mode operation (power-up default mode) for higher efficiency at light loads and forced continuous PWM mode for lower noise at light loads. In Burst Mode operation at light loads, the output capacitor is charged to a voltage slightly higher than its regulation point. The regulator then goes into sleep mode, during which time the output capacitor provides the load current. In sleep most of the regulator's circuitry is powered down, helping conserve input power. When the output capacitor droops below its programmed value, the circuitry is powered on and another burst cycle begins. The sleep time decreases as load current increases. In Burst Mode operation, the regulator will burst at light loads whereas at higher loads it will operate at constant frequency PWM mode operation. In forced continuous mode (selectable via I<sup>2</sup>C command), the oscillator runs continuously and the buck switch currents are allowed to reverse under very light load conditions to maintain regulation. This mode allows the buck to run at a fixed frequency with minimal output ripple.

Each buck switching regulator has its own V<sub>IN</sub>, SW, FB and EN pin to maximize flexibility. The enable pins have two different enable threshold voltages that depend on the operating state of the LTC3375. With all regulators disabled, the enable pin threshold is set to 730mV (typical). Once any regulator is enabled, the enable pin thresholds of the remaining regulators are set to a bandgap-based 400mV and the EN pins are each monitored by a precision comparator. This precision EN threshold may be used to provide event-based sequencing via feedback from other previously enabled regulators. All buck regulators have forward and reverse-current limiting, soft-start to limit inrush current during start-up, and short-circuit protection.

Each buck can operate in standalone mode using the EN pin in its default MODE and FB reference settings, or be fully controlled using the I<sup>2</sup>C port. I<sup>2</sup>C commands may be used to independently program each buck regulators' operating mode, oscillator phase, and reference voltage in

addition to simple ON/OFF control. Each buck may have its phase programmed in 90° phase steps via I<sup>2</sup>C. The phase step command programs the fixed edge of the switching sequence, which is when the PMOS turns on. The PMOS off (NMOS on) phase is subject to the duty cycle demanded by the regulator. Bucks 1 and 2 default to 0°, bucks 3 and 4 default to 90°, bucks 5 and 6 default to 180°, and bucks 7 and 8 default to 270°. Each buck can have its feedback voltage independently programmed in 25mV increments from 425mV to 800mV. All regulators' feedback voltages default to 725mV at initial power-up. In cases where power stages are combined, the register content of the master program the combined buck regulator's behavior and the register contents of the slave are ignored.

Two additional I<sup>2</sup>C commands act on all the buck switching regulators together. In shutdown, an I<sup>2</sup>C control bit keeps all the SW nodes in a high impedance state (default) or forces all the SW nodes to decay to GND through 1k (typical) resistors. Also, the slew rate of the SW nodes may be switched from the default value to a lower value for reduced radiated EMI at the cost of a small drop in efficiency.

Each buck regulator may be enabled via its enable pin or I<sup>2</sup>C. The buck regulator enable pins may be tied to V<sub>OUT</sub> voltages, through a resistor divider, to program power-up sequencing. If a different power-down sequence is required, the enables can be redundantly written via I<sup>2</sup>C. The EN pins can then be ignored via an I<sup>2</sup>C command, and the switching regulators may be powered down via I<sup>2</sup>C while the EN pins remain tied to the output voltages of other regulators.

In addition to many programming options, there are also 17 bits of data that may be read back to report fault conditions on the LTC3375, and all I<sup>2</sup>C commands can be read back prior to executing.

### Buck Regulators with Combined Power Stages

Up to four adjacent buck regulators may be combined in a master-slave configuration by connecting their SW pins together, connecting their V<sub>IN</sub> pins together, and connecting the higher numbered bucks' FB pin(s) to the input supply. The lowest numbered buck is always the master. In Figure 1, buck regulator 1 is the master. The



## OPERATION

feedback network connected to the FB1 pin programs the output voltage to 1.2V. The FB2 pin is tied to  $V_{IN1}/2$ , which configures buck regulator 2 as the slave. The SW1 and SW2 pins must be tied together, as must the  $V_{IN1}$  and  $V_{IN2}$  pins. The register contents of the master program, the combined buck regulator's behavior, and the register contents of the slave are ignored. The slave buck control circuitry draws no current. The enable of the master buck (EN1) controls the operation of the combined bucks; the enable of the slave regulator (EN2) must be tied to ground.

Any combination of 2, 3, or 4 adjacent buck regulators may be combined to provide either 2A, 3A, or 4A of average output load current. For example, buck regulator 1 and buck regulator 2 may run independently, while buck regulators 3 and 4 may be combined to provide 2A, while buck regulators 5 through 8 may be combined to provide 4A. Buck regulator 1 is never a slave, and buck regulator 8 is never a master. 15 unique output power stage configurations are possible to maximize application flexibility.

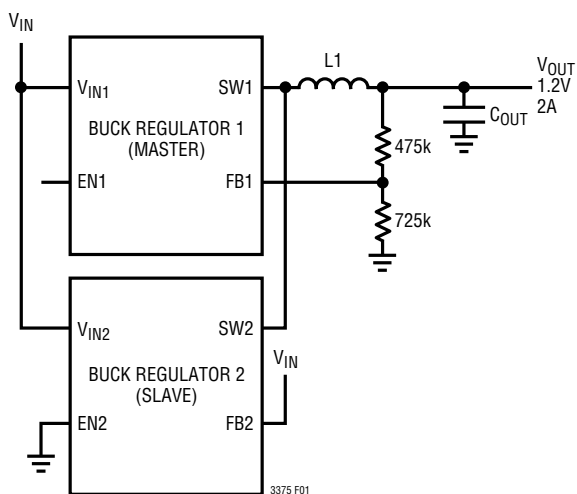


Figure 1. Buck Regulators Configured as Master-Slave

### Pushbutton Interface

The LTC3375 includes a pushbutton interface which can be used to provide power-up or power-down control for either the part or the application. The  $\overline{PB}$ ,  $\overline{KILL}$ , and ON pins provide the user with flexibility to power-up or power-down the part in addition to having I<sup>2</sup>C control. All  $\overline{PB}$  timing parameters are scaled using the CT pin. Times described below apply to a nominal  $C_T$  capacitor of 0.01 $\mu$ F.

The LTC3375 is in an off state when it is powered up with all regulators in shutdown. The ON pin is LOW in the off state. The ON pin will go HIGH if  $\overline{PB}$  is pulled LOW for 200ms. The ON pin stays in its HIGH state for 10 seconds and then returns LOW unless  $\overline{KILL}$  is asserted HIGH in this time in which case ON will remain HIGH. If  $\overline{KILL}$  goes LOW, for longer than a 50ms debounce time, while ON is HIGH after the 10 second time has expired, ON will again go to its LOW state.  $\overline{PB}$  being held low causes the  $\overline{KILL}$  pin to be ignored.

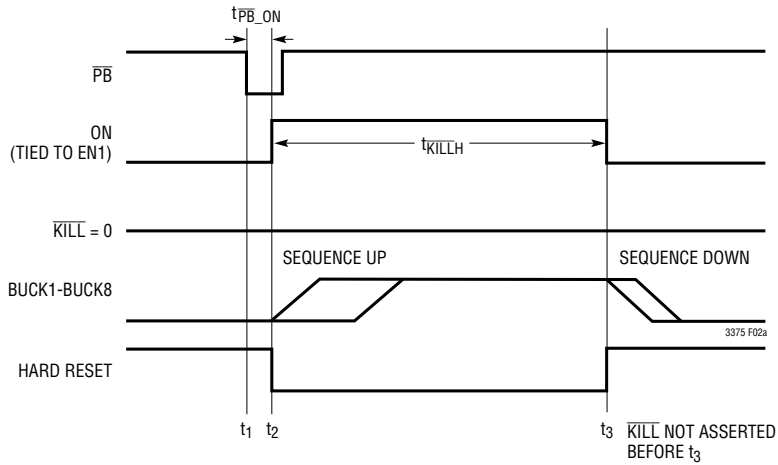
Once in the “on” state (ON pin is HIGH), the LTC3375 can be powered down in one of three ways that allow for flexibility between hardware and software system resets. First, if  $\overline{PB}$  is held LOW for at least 10 seconds, then ON will be driven LOW. This will not force a hard reset on any of the buck switching regulators. The ON pin, however, may be used to either drive the EN pin of the first sequenced buck converter or that of an upstream high voltage buck switching regulator. In this case the  $\overline{IRQ}$  pin is latched to its LOW state to indicate a  $\overline{PB}$  induced reset. Second, if the  $\overline{PB}$  pin is driven LOW for longer than 50ms but less than 10 seconds, the  $\overline{IRQ}$  pin will be pulled LOW for as long as the  $\overline{PB}$  pin remains LOW. If a microcontroller sees a transient  $\overline{IRQ}$  LOW signal, then this should signal that the user has pressed the PB. A software power-down may then be initiated if so desired. Finally, if the  $\overline{KILL}$  input is driven LOW for longer than 50ms, then a hard reset will be initiated. All enabled buck switching regulators will be turned off while  $\overline{KILL}$  is low and will remain powered down for 1 second after  $\overline{KILL}$  returns high.  $\overline{KILL}$  being low also forces a hard reset while the pushbutton is in the “off” state. A hard reset may also be generated by using the RESET\_ALL I<sup>2</sup>C command that will last for 1 second. The pushbutton will return to the “off” state.  $\overline{KILL}$  must be high to power-up using EN pins or I<sup>2</sup>C. In any hard reset event all buck regulator I<sup>2</sup>C bits are set low.

### Power-Up and Power-Down Via Pushbutton

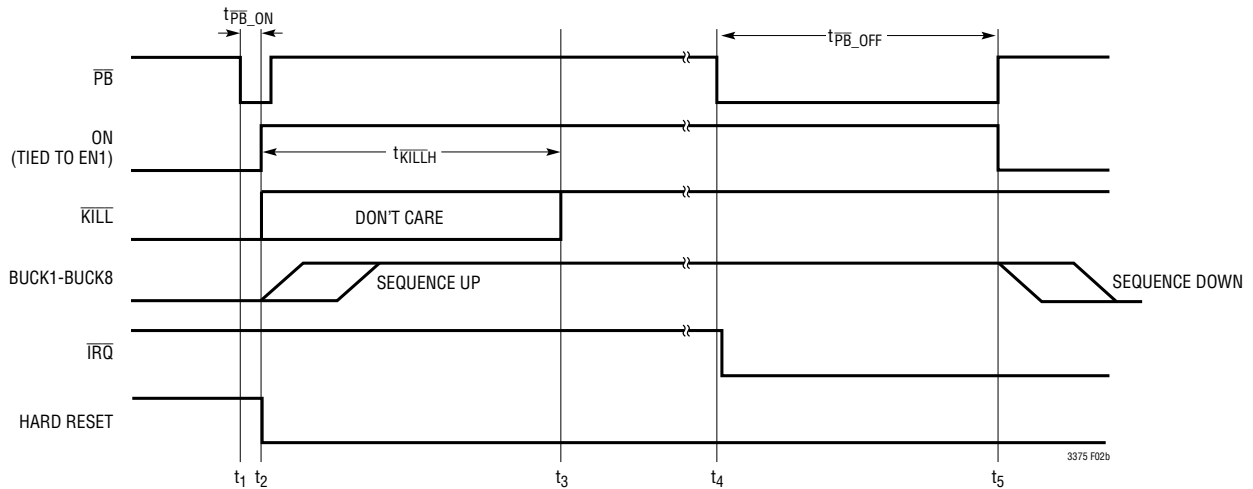
The LTC3375 may be turned on and off using the  $\overline{PB}$ ,  $\overline{KILL}$ , and ON pins as shown in Figures 2a and 2b. In Figures 2a and 2b, pressing  $\overline{PB}$  LOW at time  $t_1$ , causes the ON pin to go HIGH at time  $t_2$  and stay HIGH for at least 10 seconds after which ON will go LOW unless  $\overline{KILL}$  has been asserted high. ON can be connected to the EN pin

3375fc

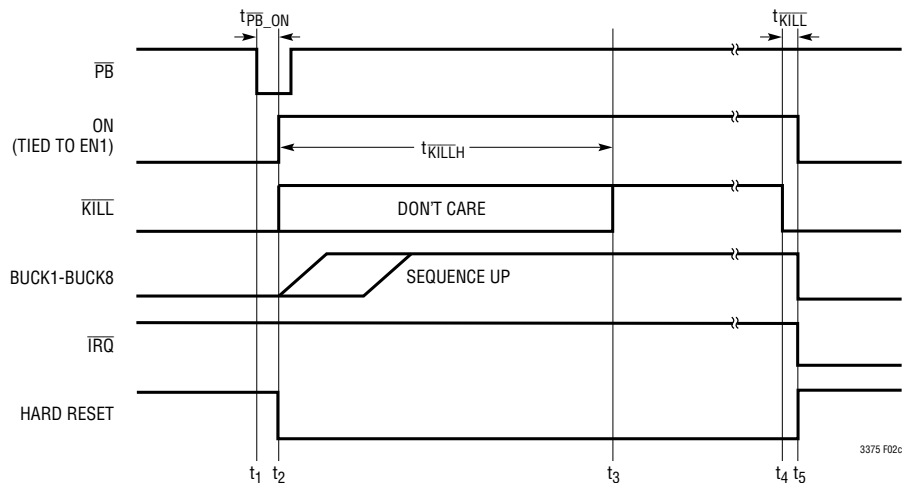
**OPERATION**



**Figure 2a. Power-Up Using  $\overline{PB}$  (Sequenced Power-Up, Figure 8)**



**Figure 2b. Power-Up and Power-Down Using  $\overline{PB}$  (Sequenced Power-Up, Figure 8)**



**Figure 2c. Power-Up Using  $\overline{PB}$  and Power-Down Using  $\overline{KILL}$**

## OPERATION

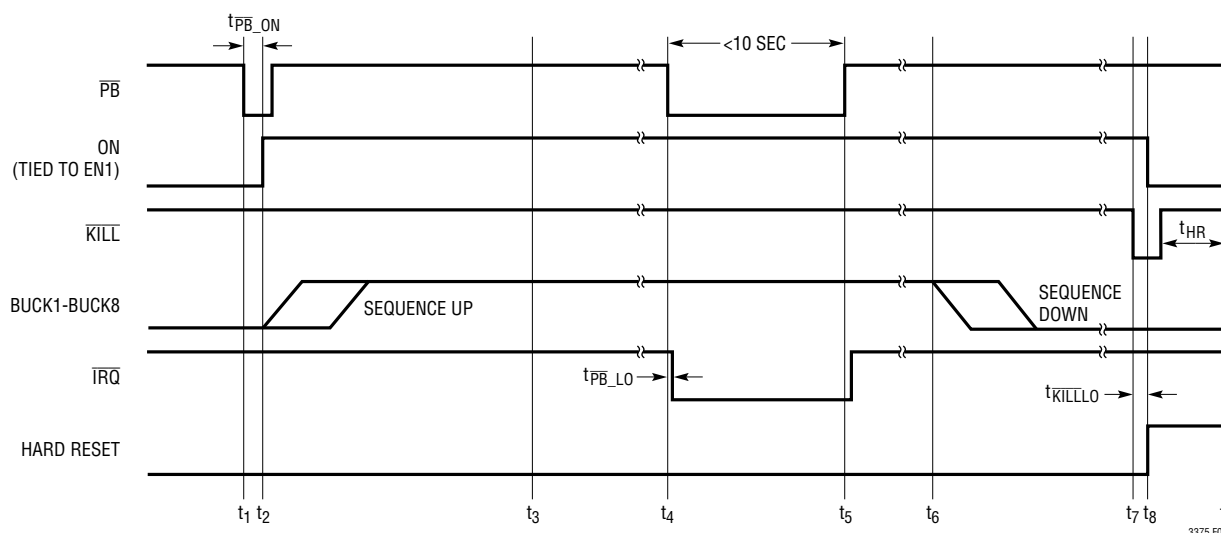


Figure 2d. Power-Up Using  $\overline{\text{PB}}$  and Power-Down Using a “Soft” Reset

of either an upstream high voltage buck regulator, or any EN pin causing its associated buck switching regulator to power-up, which can sequentially power-up the other buck regulators. The  $\overline{\text{RST}}$  pin gets pulled HIGH 230ms after the last enabled buck is in its PGOOD state. An application showing sequential regulator start-up is shown in the Typical Applications section (Figure 8).

In Figure 2b,  $\overline{\text{PB}}$  is held LOW at instant  $t_4$  for 10 seconds. This causes ON to return to a LOW state, which can sequence a power-down by either shutting down an upstream high voltage buck, or by shutting down one of the internal buck switching regulators.

In Figure 2c,  $\overline{\text{KILL}}$  is pulled LOW while the pushbutton is in the “on” state. This causes a hard reset to be generated at  $t_4$ , all regulators are powered down 50ms later at time  $t_5$ . An I<sup>2</sup>C signaled reset will have the same effect as pulling  $\overline{\text{KILL}}$  low momentarily.

In Figure 2d,  $\overline{\text{PB}}$  is held LOW at instant  $t_4$  for a time greater than 50ms but less than 10 seconds. This causes a transient  $\overline{\text{IRQ}}$  signal. This unlatched interrupt can be used to signal a user pushbutton request. In this case a software reset may be initiated if so desired. In Figure 2d, the microprocessor initiates the power-down sequencing after the user pushbutton signal at time  $t_6$ . At time  $t_7$ , once all the converters are powered down, the micro

brings  $\overline{\text{KILL}}$  LOW. 50ms later at time  $t_8$  ON goes LOW. In this case, a hard reset is issued until 1 second after  $\overline{\text{KILL}}$  returns high at  $t_9$ .

None of the pushbutton based  $\overline{\text{IRQ}}$  signals are reported in an I<sup>2</sup>C register. As such, any  $\overline{\text{IRQ}}$  signals that are not revealed by polling the I<sup>2</sup>C read back may be interpreted as caused by the pushbutton.

### Power-Up and Power-Down Via Enable Pin or I<sup>2</sup>C

All regulators can be enabled either via its enable pin or I<sup>2</sup>C. If the use of the pushbutton interface is not desired  $\overline{\text{PB}}$  and  $\overline{\text{KILL}}$  should be tied to  $V_{\text{CC}}$ , and the user may simply enable any of the buck switching regulators by asserting a HIGH signal on any of the EN pins or by writing a buck switching regulator EN command to the I<sup>2</sup>C. If no I<sup>2</sup>C enable has been written, the buck switching regulator may be powered down by simply returning its EN pin to a LOW state. If it is wished to power-down the converters via I<sup>2</sup>C, an IGNORE\_EN command may be written causing the LTC3375 to treat the state of the EN pin as LOW regardless of its input. Then, the buck switching converters can be powered down via I<sup>2</sup>C regardless of their associated EN pin. Alternatively a RESET\_ALL command may be written that will force all the buck switching regulators to power-down and remain powered down for a minimum of one second before they are allowed to be re-enabled.

## OPERATION

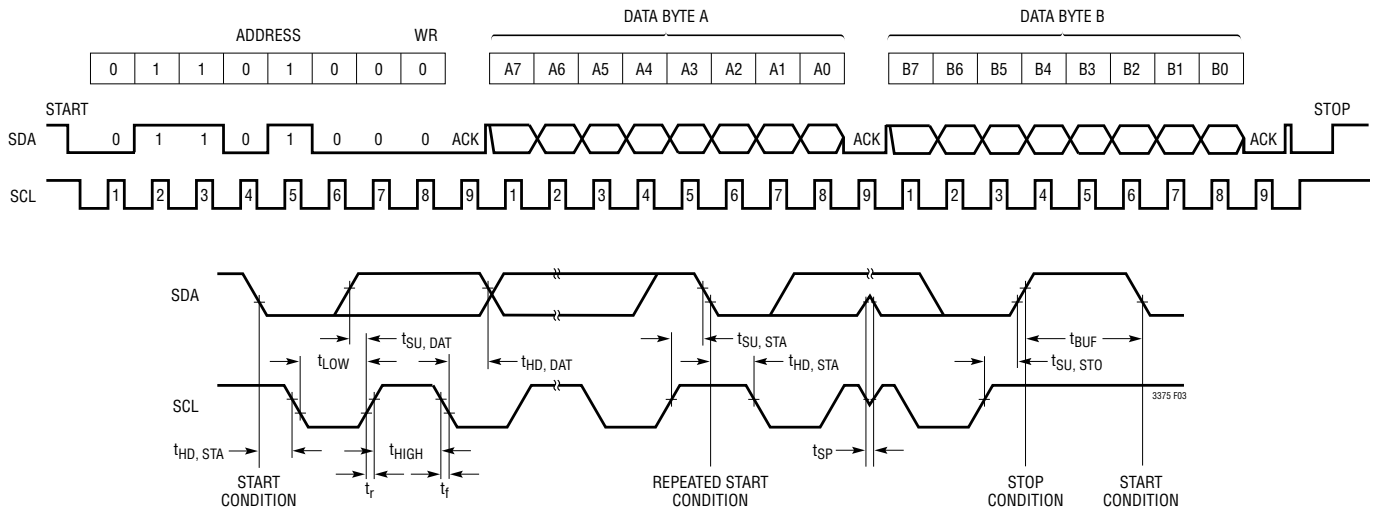


Figure 3. I<sup>2</sup>C Bus Operation

### I<sup>2</sup>C Interface

The LTC3375 may communicate with a bus master using the standard I<sup>2</sup>C 2-wire interface. The timing diagram (Figure 3) shows the relationship of the signals on the bus. The two bus lines, SDA and SCL, must be high when the bus is not in use. External pull-up resistors or current sources, such as the LTC1694 SMBus accelerator, are required on these lines. The LTC3375 is both a slave receiver and slave transmitter. The I<sup>2</sup>C control signals, SDA and SCL are scaled internally to the V<sub>CC</sub> supply.

The I<sup>2</sup>C port has an undervoltage lockout on the V<sub>CC</sub> pin. When V<sub>CC</sub> is below 1.8V, the I<sup>2</sup>C serial port is cleared and the LTC3375 registers are set to their default configurations.

### I<sup>2</sup>C Bus Speed

The I<sup>2</sup>C port is designed to be operated at speeds of up to 400kHz. It has built-in timing delays to ensure correct operation when addressed from the I<sup>2</sup>C compatible master device.

### I<sup>2</sup>C Start and Stop Conditions

A bus master signals the beginning of communications by transmitting a START condition. A START condition is generated by transitioning SDA from HIGH to LOW while SCL is HIGH. The master may transmit either the slave write or the slave read address. Once data is written to the LTC3375, the master may transmit a STOP condition which

commands the LTC3375 to act upon its new command set. A STOP condition is sent by the master by transitioning SDA from LOW to HIGH while SCL is HIGH. The bus is then free for communication with another I<sup>2</sup>C device.

### I<sup>2</sup>C Byte Format

Each byte sent to or received from the LTC3375 must be 8 bits long followed by an extra clock cycle for the acknowledge bit. The data should be sent to the LTC3375 most significant bit (MSB) first.

### I<sup>2</sup>C Acknowledge

The acknowledge signal is used for handshaking between the master and the slave. When the LTC3375 is written to (write address), it acknowledges its write address as well as the subsequent two data bytes. When it is read from (read address), the LTC3375 acknowledges its read address only. The bus master should acknowledge receipt of information from the LTC3375.

An acknowledge (active LOW) generated by the LTC3375 lets the master know that the latest byte of information was received. The acknowledge related clock pulse is generated by the master. The master releases the SDA line (HIGH) during the acknowledge clock cycle. The LTC3375 pulls down the SDA line during the write acknowledge clock pulse so that it is a stable LOW during the HIGH period of this clock pulse.

## OPERATION

**Table 1. Summary of I<sup>2</sup>C Sub-Addresses and Byte Formats. Bits A7, A6, A5, A4 of Sub-Address Need to be 0 to Access Registers**

| SUB-ADDRESS<br>A7A6A5A4A3A2A1A0 | OPERATION  | ACTION  | BYTE FORMAT D7D6D5D4D3D2D1D0   | DEFAULT<br>D7D6D5D4D3D2D1D0 | COMMENTS  |
|---------------------------------|------------|---|--|-----------------------------|---|
| 0000 0000 (00h)                 | Read/Write | Global Logic                                    | RESET_ALL, DT[1], DT[0], IGNORE_EN,<br>1KPD, SLOW, RD_TEMP, Unused                   | 0000 0000                   | Bits either act at top level or on all buck switching regulators at once  |
| 0000 0001 (01h)                 | Read/Write | Buck1 Register                                  | ENABLE, MODE, PHASE[1], PHASE[0],<br>DAC[3], DAC[2]. DAC[1], DAC[0]                  | 0000 1100                   |   |
| 0000 0010 (02h)                 | Read/Write | Buck2 Register                                  | ENABLE, MODE, PHASE[1], PHASE[0],<br>DAC[3], DAC[2]. DAC[1], DAC[0]                  | 0000 1100                   |   |
| 0000 0011 (03h)                 | Read/Write | Buck3 Register                                  | ENABLE, MODE, PHASE[1], PHASE[0],<br>DAC[3], DAC[2]. DAC[1], DAC[0]                  | 0001 1100                   |   |
| 0000 0100 (04h)                 | Read/Write | Buck4 Register                                  | ENABLE, MODE, PHASE[1], PHASE[0],<br>DAC[3], DAC[2]. DAC[1], DAC[0]                  | 0001 1100                   |   |
| 0000 0101 (05h)                 | Read/Write | Buck5 Register                                  | ENABLE, MODE, PHASE[1], PHASE[0],<br>DAC[3], DAC[2]. DAC[1], DAC[0]                  | 0010 1100                   |   |
| 0000 0110 (06h)                 | Read/Write | Buck6 Register                                  | ENABLE, MODE, PHASE[1], PHASE[0],<br>DAC[3], DAC[2]. DAC[1], DAC[0]                  | 0010 1100                   |   |
| 0000 0111 (07h)                 | Read/Write | Buck7 Register                                  | ENABLE, MODE, PHASE[1], PHASE[0],<br>DAC[3], DAC[2]. DAC[1], DAC[0]                  | 0011 1100                   |   |
| 0000 1000 (08h)                 | Read/Write | Buck8 Register                                  | ENABLE, MODE, PHASE[1], PHASE[0],<br>DAC[3], DAC[2]. DAC[1], DAC[0]                  | 0011 1100                   |   |
| 0000 1001 (09h)                 | Read/Write | RST Mask  | PGOOD[8], PGOOD[7], PGOOD[6],<br>PGOOD[5], PGOOD[4], PGOOD[3],<br>PGOOD[2], PGOOD[1] | 1111 1111                   | Fault will pull RST low if the corresponding bit is '1'   |
| 0000 1010 (0Ah)                 | Read/Write | IRQ PGOOD Mask                                  | PGOOD[8], PGOOD[7], PGOOD[6],<br>PGOOD[5], PGOOD[4], PGOOD[3],<br>PGOOD[2], PGOOD[1] | 0000 0000                   | Fault will pull IRQ low if the corresponding bit is '1'   |
| 0000 1011 (0Bh)                 | Read/Write | IRQ UVLO Mask                                   | UVLO[8], UVLO[7], UVLO[6], UVLO[5],<br>UVLO[4], UVLO[3], UVLO[2], UVLO[1]            | 0000 0000                   | Fault will pull IRQ low if the corresponding bit is '1'   |
| 0000 1100 (0Ch)                 | Read       | PGOOD Status Register<br>(Latched at IRQ fault) | PGOOD[8], PGOOD[7], PGOOD[6],<br>PGOOD[5], PGOOD[4], PGOOD[3],<br>PGOOD[2], PGOOD[1] |                             | Read back of PGOOD based faults. If the corresponding mask bit is '0', then bit can be used to read back real time data |
| 0000 1101 (0Dh)                 | Read       | UVLO Status Register<br>(Latched at IRQ fault)  | UVLO[8], UVLO[7], UVLO[6], UVLO[5],<br>UVLO[4], UVLO[3], UVLO[2], UVLO[1]            |                             | Read back of UVLO based faults. If the corresponding mask bit is '0', then bit can be used to read back real time data  |
| 0000 1110 (0Eh)                 | Read       | Temp Monitor                                    | DT_WARN, TEMP[6], TEMP[5],<br>TEMP[4], TEMP[3], TEMP[2], TEMP[1],<br>TEMP[0]         |                             | TEMP bits read back the TEMP digital code. DT_WARN bit latches high if an IRQ fault has been caused due to a DT Warning |
| 0000 1111 (0Fh)                 | Write      | Clear Interrupt                                 |  | NA                          | Clears the Interrupt Bit, Status Latches are Unlatched  |

When the LTC3375 is read from, it releases the SDA line so that the master may acknowledge receipt of the data. Since the LTC3375 only transmits one byte of data during a read cycle, a master not acknowledging the data sent by the LTC3375 has no I<sup>2</sup>C specific consequence on the operation of the I<sup>2</sup>C port.

### I<sup>2</sup>C Slave Address

The LTC3375 responds to a 7-bit address which has been factory programmed to b'0110100[R/WB]'. The LSB of the address byte, known as the read/write bit, should be 0 when writing to the LTC3375 and 1 when reading data from it. Considering the address as an 8-bit word,

## OPERATION

the write address is 68h and the read address is 69h. The LTC3375 will acknowledge both its read and write address.

### I<sup>2</sup>C Sub-Addressed Writing

The LTC3375 has 13 command registers for control input. They are accessed by the I<sup>2</sup>C port via a sub-addressed writing system.

A single write cycle of the LTC3375 consists of exactly three bytes except when a clear interrupt command is written. The first byte is always the LTC3375's write address. The second byte represents the LTC3375's sub-address. The sub-address is a pointer which directs the subsequent data byte within the LTC3375. The third byte consists of the data to be written to the location pointed to by the sub-address. The LTC3375 contains 12 control registers which can be written to.

### I<sup>2</sup>C Bus Write Operation

The master initiates communication with the LTC3375 with a START condition and the LTC3375's write address. If the address matches that of the LTC3375, the LTC3375 returns an acknowledge. The master should then deliver the sub-address. Again the LTC3375 acknowledges and the cycle is repeated for the data byte. The data byte is transferred to an internal holding latch upon the return of its acknowledge by the LTC3375. This procedure must be repeated for each sub-address that requires new data. After one or more cycles of [ADDRESS][SUB-ADDRESS][DATA], the master may terminate the communication with a STOP condition. Multiple sub-addresses may be written to with a single address command using a [ADDRESS][SUB-ADDRESS][DATA][SUB-ADDRESS][DATA] sequence. Alternatively, a REPEAT-START condition can be initiated by the master and another chip on the I<sup>2</sup>C bus can be addressed. This cycle can continue indefinitely and the LTC3375 will remember the last input valid data that it received. Once all chips on the bus have been addressed and sent valid data, a global STOP can be sent and the LTC3375 will update its command latches with the data that it had received.

It is important to understand that until a STOP signal is transmitted, data written to the LTC3375 command registers is not acted on by the LTC3375. Only once a STOP

signal is issued is the data transferred to the command latch and acted on.

### I<sup>2</sup>C Bus Read Operation

The LTC3375 has 13 command registers and three status registers. The contents of any of these registers, except for the Clear Interrupt (0Fh) register, may be read back via I<sup>2</sup>C.

To read the data of a register, that register's sub-address must be provided to the LTC3375. The bus master reads the status of the LTC3375 with a START condition followed by the LTC3375 write address followed by the first data byte (the sub-address of the register whose data needs to be read) which is acknowledged by the LTC3375. After receiving the acknowledge signal from the LTC3375 the bus master initiates a new START condition followed by the LTC3375 read address. The LTC3375 acknowledges the read address and then returns a byte of read back data from the selected register. A STOP command is not required for the bus read operation.

Immediately after writing data to a register, the contents of that register may be read back if the bus master issues a START condition followed by the LTC3375 read address.

### Error Condition Reporting Via $\overline{RST}$ and $\overline{IRQ}$ Pins

Error conditions are reported back via the  $\overline{IRQ}$  and  $\overline{RST}$  pins. After an error condition is detected, status data can be read back to a microprocessor via I<sup>2</sup>C to determine the exact nature of the error condition.

Figure 4 is a simplified schematic showing the signal path for reporting errors via the  $\overline{RST}$  and  $\overline{IRQ}$  pins.

All buck switching regulators have an internal power good (PGOOD) signal. When the regulated output voltage of an enabled switcher rises above 93.5% of its programmed value, the PGOOD signal will transition high. When the regulated output voltage falls below 92.5% of its programmed value, the PGOOD signal is pulled low. If any internal PGOOD signal is not masked and stays low for greater than 50 $\mu$ s, then the  $\overline{RST}$  and  $\overline{IRQ}$  pins are pulled low, indicating to a microprocessor that an error condition has occurred. The 50 $\mu$ s filter time prevents the pins from being pulled low due to a transient.

## OPERATION

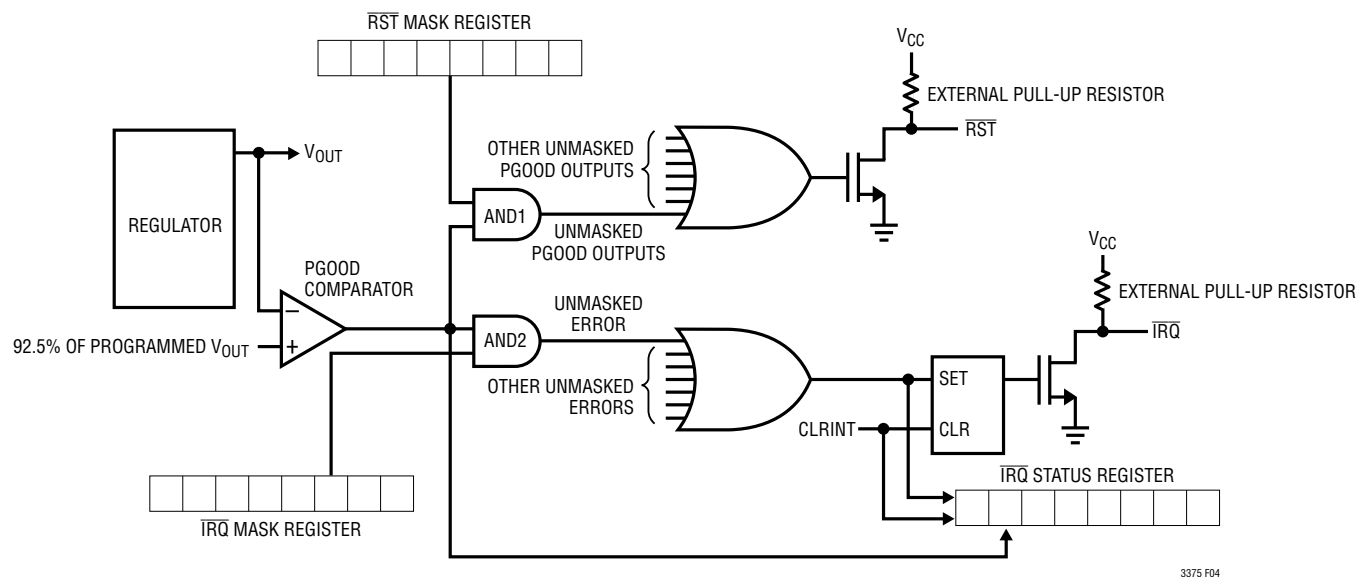


Figure 4. Simplified Schematic  $\overline{RST}$  and  $\overline{IRQ}$  Signal Path

An error condition that pulls the  $\overline{RST}$  pin low is not latched. When the error condition goes away, the  $\overline{RST}$  pin is released and is pulled high if no other error condition exists.

In addition to the PGOOD signals of the regulators the  $\overline{IRQ}$  pin also indicates the status of the pushbutton, die temperature, and undervoltage flags. Pushbutton faults cannot be masked. A fault that causes the  $\overline{IRQ}$  pin to be pulled low is latched with the exception of a pushbutton press that is less than 10 seconds ( $C_T = 0.01\mu\text{F}$ ) while ON is HIGH. In the case of a transient pushbutton press  $\overline{IRQ}$  will be held LOW for the duration of the button press latching after the 10 second power-down time has elapsed. In all other cases when the fault condition is cleared, the  $\overline{IRQ}$  pin is still maintained in its low state. The user needs to clear the interrupt by using a CLRINT command.

On start-up, all PGOOD status outputs are unmasked with respect to  $\overline{RST}$ . While all PGOOD and UVLO status outputs are masked with respect to  $\overline{IRQ}$ . A power-on reset will cause  $\overline{RST}$  to be pulled low. Once all enabled regulators have their output PGOOD for 230ms typical ( $C_T = 0.01\mu\text{F}$ ) the  $\overline{RST}$  output goes Hi-Z.

By masking a PGOOD signal, the  $\overline{RST}$  or  $\overline{IRQ}$  pin will remain Hi-Z even though the output voltage of a regulator may be below its PGOOD threshold. By masking a UVLO signal, the  $\overline{IRQ}$  pin will remain Hi-Z even though its associated input voltage may be below its UVLO threshold. However, when the status registers are read back, the true conditions of PGOOD and UVLO are reported. If a UVLO  $\overline{IRQ}$  is masked but the associated PGOOD signal is unmasked, then the  $\overline{IRQ}$  pin may still be pulled low due to a PGOOD LOW signal that resulted from an input UVLO.

### Temperature Monitoring and Overtemperature Protection

To prevent thermal damage to the LTC3375 and its surrounding components, the LTC3375 incorporates an overtemperature (OT) function. When the LTC3375 die temperature reaches 165°C (typical) all enabled buck switching regulators are shut down and remain in shut-down until the die temperature falls to 155°C (typical). The LTC3375 also has a die temperature warning function which warns a user that the die temperature has reached its programmed alarm threshold which allows the user to take any corrective action. The die temperature warning threshold is user programmable as shown in Table 2.

## OPERATION

**Table 2. Die Temperature Warning Thresholds**

| DT[1], DT[0] | DIE TEMPERATURE WARNING THRESHOLD |
|--------------|-----------------------------------|
| 00 (Default) | Inactive                          |
| 01           | 140°C                             |
| 10           | 125°C                             |
| 11           | 110°C                             |

A die temperature warning is reported to the user by pulling the  $\overline{\text{IRQ}}$  pin low. This warning can be read back on the LSB of the Temp\_Monitor register. The die temperature warning flag is disabled when the DT bits are set to 00 (default).

The temperature may be read back by the user either digitally through the I<sup>2</sup>C Temp\_Monitor Register or by sampling the TEMP pin analog voltage. The temperature, T, indicated by the TEMP pin voltage is given by:

$$T = \frac{V_{\text{TEMP}} + 19\text{mV}}{6.75\text{mV}} \cdot 1^\circ\text{C} \quad (1)$$

The analog voltage can be digitally polled using an internal A/D converter. In order to digitally read the temperature voltage the user should first issue a RD\_TEMP I<sup>2</sup>C command to tell the A/D converter to poll the TEMP voltage. At least 2ms after this command has been written the user may then poll the TEMP bits in the Temp\_Monitor register. The TEMP bits are related to the TEMP voltage as follows:

$$V_{\text{TEMP}} = 1.3\text{V} \cdot (0.08333 + 0.007161 \cdot D) \quad (2)$$

where D corresponds to the bit weight of the digital code. Combining Equation 1 and Equation 2 yields:

$$T = 18.86^\circ\text{C} + 1.379^\circ\text{C} \cdot D \quad (3)$$

If die temperature warning and temperature read back functionality are not desired, then the user may shut down the temperature monitor in order to lower quiescent current (15 $\mu$ A typical) by tying TEMP to V<sub>CC</sub>. In this case all enabled buck switching regulators are still shut down when the die temperature reaches 165°C (typical) and remain in shutdown until the die temperature falls to 155°C (typical). If none of the buck switching regulators are enabled, then the temperature monitor is also shut down to further reduce quiescent current.

### RESET\_ALL Functionality

The RESET\_ALL bit shuts down all enabled regulators (enabled either via its enable pin or I<sup>2</sup>C) for one second. The RESET\_ALL bit is self clearing, and all other I<sup>2</sup>C bits (besides the enable bits, which are set low) will remain in their previous states. The RESET\_ALL bit will also reset the pushbutton to the powered-down state.

### Programming the Operating Frequency

Selection of the operating frequency is a trade-off between efficiency and component size. High frequency operation allows the use of smaller inductor and capacitor values. Operation at lower frequencies improves efficiency by reducing internal gate charge losses but requires larger inductance values and/or capacitance to maintain low output voltage ripple.

The operating frequency for all of the LTC3375 regulators is determined by an external resistor that is connected between the RT pin and ground. The operating frequency can be calculated by using the following equation:

$$f_{\text{osc}} = \frac{8 \cdot 10^{11} \cdot \Omega\text{Hz}}{R_T} \quad (4)$$

While the LTC3375 is designed to function with operating frequencies between 1MHz and 3MHz, it has safety clamps that will prevent the oscillator from running faster than 4MHz (typical) or slower than 250kHz (typical). Tying the RT pin to V<sub>CC</sub> sets the oscillator to the default internal operating frequency of 2MHz (typical).

The LTC3375's internal oscillator can be synchronized, through an internal PLL circuit, to an external frequency by applying a square wave clock signal to the SYNC pin. During synchronization, the top MOSFET turn-on of any buck switching regulators operating at 0° phase are locked to the rising edge of the external frequency source. All other buck switching regulators are locked to the appropriate phase of the external frequency source (see Buck Switching Regulators). The synchronization frequency range is 1MHz to 3MHz.



## OPERATION

After detecting an external clock on the first rising edge of the SYNC pin, the PLL starts up at the current frequency being programmed by the RT pin. The internal PLL then requires a certain number of periods to gradually settle until the frequency at SW matches the frequency and phase of SYNC.

When the external clock is removed the LTC3375 needs approximately 5 $\mu$ s to detect the absence of the external clock. During this time, the PLL will continue to provide clock cycles before it recognizes the lack of a SYNC input. Once the external clock removal has been identified, the oscillator will gradually adjust its operating frequency to match the desired frequency programmed at the RT pin.

### V<sub>CC</sub> Shunt Regulator

The LTC3375 has the control circuitry to regulate the output of an N-type device. The circuit should be connected as shown in Figures 6a and 6b. The voltage at FBV<sub>CC</sub> will servo to 1.20V and V<sub>CC</sub> can be programmed between 2.7V and 5.5V. The N-type device can be used to regulate a lower voltage at V<sub>CC</sub> while being powered from a high voltage supply. The N-type device must be chosen so that it can handle the power dissipated in regulating V<sub>CC</sub>. The internal circuitry of the LTC3375 can only pull-down on the V<sub>SHNT</sub> node. A pull-up resistor is required for positive gate drive.

If V<sub>CC</sub> is incorrectly programmed or a current load at V<sub>CC</sub> causes V<sub>SHNT</sub> to go above 6.1V (typical), then V<sub>SHNT</sub> will be internally clamped and V<sub>CC</sub> may lose regulation.

If the use of the V<sub>CC</sub> regulator is not desired, then V<sub>CC</sub> should be tied to an external DC voltage source and a decoupling capacitor. FBV<sub>CC</sub> and V<sub>SHNT</sub> should be tied to ground.

### Watchdog Timer

The watchdog circuit monitors a microprocessor's activity. The microprocessor is required to change the logic state of the WDI pin at least once every 1.5 seconds (typical) in order to clear the watchdog timer and prevent the WDO pin from signaling a timeout.

The watchdog timer begins running immediately after a power-on reset. The watchdog timer will continue to run until a transition is detected on the WDI input. During this time WDO will be in a Hi-Z state. Once the watchdog timer times out, WDO will be pulled low and the reset timer is started. WDO being pulled low may be used to force a reset on the controlling microprocessor. If no WDI transition is received when the reset timer times out, after 200ms (typical), WDO will again become Hi-Z and the 1.5 seconds watchdog reset time will begin again. If a transition is received on the WDI input during the watchdog timeout period, then WDO will become Hi-Z immediately after the WDI transition and the 1.5 seconds watchdog reset time will begin at that point.

## APPLICATIONS INFORMATION

### Buck Switching Regulator Output Voltage and Feedback Network

The output voltage of the buck switching regulators is programmed by a resistor divider connected from the switching regulator’s output to its feedback pin and is given by  $V_{OUT} = V_{FB}(1 + R2/R1)$  as shown in Figure 5. Typical values for R1 range from 40k to 1M. The buck regulator transient response may improve with optional capacitor  $C_{FF}$  that helps cancel the pole created by the feedback resistors and the input capacitance of the FB pin. Experimentation with capacitor values between 2pF and 22pF may improve transient response.

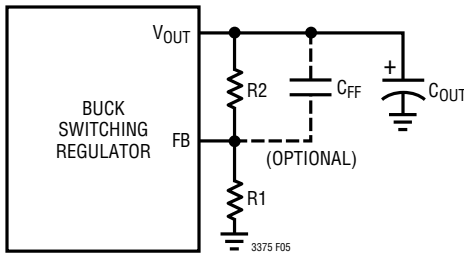


Figure 5. Feedback Components

### Buck Regulators

All eight buck regulators are designed to be used with inductors ranging from 1μH to 3.3μH depending on the lowest switching frequency that the buck regulator must operate at. To operate at 1MHz a 3.3μH inductor should be used, while to operate at 3MHz a 1μH inductor may be used. Table 3 shows some recommended inductors for the buck regulators.

Table 3. Recommended Inductors for 1A Buck Regulators

| PART NUMBER         | L (μH) | MAX I <sub>DC</sub> (A) | MAX DCR (mΩ) | SIZE IN mm (L × W × H) | MANUFACTURER |
|---------------------|--------|-------------------------|--------------|------------------------|--------------|
| IHLP1212ABER1R0M-11 | 1.0    | 3                       | 38           | 3 × 3.6 × 1.2          | Vishay       |
| 1239AS-H-1R0N       | 1      | 2.5                     | 65           | 2.5 × 2.0 × 1.2        | Toko         |
| XFL4020-222ME       | 2.2    | 3.5                     | 23.5         | 4 × 4 × 2.1            | CoilCraft    |
| 1277AS-H-2R2N       | 2.2    | 2.6                     | 84           | 3.2 × 2.5 × 1.2        | Toko         |
| IHLP1212BZER2R2M-11 | 2.2    | 3                       | 46           | 3 × 3.6 × 1.2          | Vishay       |
| XFL4020-332ME       | 3.3    | 2.8                     | 38.3         | 4 × 4 × 2.1            | CoilCraft    |
| IHLP1212BZER3R3M-11 | 3.3    | 2.7                     | 61           | 3 × 3.6 × 1.2          | Vishay       |

The input supply needs to be decoupled with a 10μF capacitor while the output needs to be decoupled with a 22μF capacitor. Refer to Capacitor Selection for details on selecting a proper capacitor.

Each buck regulator can be programmed via I<sup>2</sup>C. To program buck regulator 1 use sub-address 01h, buck regulator 2 sub-address 02h, buck regulator 3 sub-address 03h, buck regulator 4 sub address 04h, buck regulator 5 sub-address 05h, buck regulator 6 sub-address 06h, buck regulator 7 sub-address 07h, and buck regulator 8 sub-address 08h. The bit format is explained in Table 7.

### Combined Buck Regulators

A single 2A buck regulator is available by combining two adjacent 1A buck regulators together. Likewise a 3A or 4A buck regulator is available by combining any three or four adjacent buck regulators respectively. Tables 4, 5, and 6 show recommended inductors for these configurations.

The input supply needs to be decoupled with a 22μF capacitor while the output needs to be decoupled with a 47μF capacitor for a 2A combined buck regulator. Likewise for 3A and 4A configurations the input and output capacitance must be scaled up to account for the increased load. Refer to Capacitor Selection in the Applications Information section for details on selecting a proper capacitor.

In many cases, any extra unused buck converters may be used to increase the efficiency of the active regulators. In general the efficiency will improve for any regulators running close to their rated load currents. If there are unused regulators, the user should look at their specific applications and current requirements to decide whether to add extra stages.

## APPLICATIONS INFORMATION

**Table 4. Recommended Inductors for 2A Buck Regulators**

| PART NUMBER         | L ( $\mu$ H) | MAX I <sub>DC</sub> (A) | MAX DCR (m $\Omega$ ) | SIZE IN mm (L $\times$ W $\times$ H) | MANUFACTURER     |
|---------------------|--------------|-------------------------|-----------------------|--------------------------------------|------------------|
| XFL4020-102ME       | 1.0          | 5.1                     | 11.9                  | 4 $\times$ 4 $\times$ 2.1            | CoilCraft        |
| 74437324010         | 1            | 9                       | 27                    | 4.45 $\times$ 4.06 $\times$ 1.8      | Würth Elektronik |
| XAL4020-222ME       | 2.2          | 5.6                     | 38.7                  | 4 $\times$ 4 $\times$ 2.1            | CoilCraft        |
| FDV0530-2R2M        | 2.2          | 5.3                     | 15.5                  | 6.2 $\times$ 5.8 $\times$ 3          | Toko             |
| IHLP2020BZER2R2M-11 | 2.2          | 5                       | 37.7                  | 5.49 $\times$ 5.18 $\times$ 2        | Vishay           |
| XAL4030-332ME       | 3.3          | 5.5                     | 28.6                  | 4 $\times$ 4 $\times$ 3.1            | CoilCraft        |
| FDV0530-3R3M        | 3.3          | 4.1                     | 34.1                  | 6.2 $\times$ 5.8 $\times$ 3          | Toko             |

**Table 5. Recommended Inductors for 3A Buck Regulators**

| PART NUMBER         | L ( $\mu$ H) | MAX I <sub>DC</sub> (A) | MAX DCR (m $\Omega$ ) | SIZE IN mm (L $\times$ W $\times$ H) | MANUFACTURER     |
|---------------------|--------------|-------------------------|-----------------------|--------------------------------------|------------------|
| XAL4020-102ME       | 1.0          | 8.7                     | 14.6                  | 4 $\times$ 4 $\times$ 2.1            | CoilCraft        |
| FDV0530-1R0M        | 1            | 8.4                     | 11.2                  | 6.2 $\times$ 5.8 $\times$ 3          | Toko             |
| XAL5030-222ME       | 2.2          | 9.2                     | 14.5                  | 5.28 $\times$ 5.48 $\times$ 3.1      | CoilCraft        |
| IHLP2525CZER2R2M-01 | 2.2          | 8                       | 20                    | 6.86 $\times$ 6.47 $\times$ 3        | Vishay           |
| 74437346022         | 2.2          | 6.5                     | 20                    | 7.3 $\times$ 6.6 $\times$ 2.8        | Würth Elektronik |
| XAL5030-332ME       | 3.3          | 8.7                     | 23.3                  | 5.28 $\times$ 5.48 $\times$ 3.1      | CoilCraft        |
| SPM6530T-3R3M       | 3            | 7.3                     | 27                    | 7.1 $\times$ 6.5 $\times$ 3          | TDK              |

**Table 6. Recommended Inductors for 4A Buck Regulators**

| PART NUMBER         | L ( $\mu$ H) | MAX I <sub>DC</sub> (A) | MAX DCR (m $\Omega$ ) | SIZE IN mm (L $\times$ W $\times$ H) | MANUFACTURER |
|---------------------|--------------|-------------------------|-----------------------|--------------------------------------|--------------|
| XAL5030-122ME       | 1.2          | 12.5                    | 9.4                   | 5.28 $\times$ 5.48 $\times$ 3.1      | CoilCraft    |
| SPM6530T-1R0M120    | 1            | 14.1                    | 7.81                  | 7.1 $\times$ 6.5 $\times$ 3          | TDK          |
| XAL5030-222ME       | 2.2          | 9.2                     | 14.5                  | 5.28 $\times$ 5.48 $\times$ 3.1      | CoilCraft    |
| SPM6530T-2R2M       | 2.2          | 8.4                     | 19                    | 7.1 $\times$ 6.5 $\times$ 3          | TDK          |
| IHLP2525EZER2R2M-01 | 2.2          | 13.6                    | 20.9                  | 6.86 $\times$ 6.47 $\times$ 5        | Vishay       |
| XAL6030-332ME       | 3.3          | 8                       | 20.81                 | 6.36 $\times$ 6.56 $\times$ 3.1      | CoilCraft    |
| FDVE1040-3R3M       | 3.3          | 9.8                     | 10.1                  | 11.2 $\times$ 10 $\times$ 4          | Toko         |

**Table 7. Global Buck Regulator Program Register Bit Format**

|  |               |  |
|--|---------------|--|
| Bit7   | ENABLE        | Default is '0' which disables the part. A buck regulator can also be enabled via its enable pin. When enabled via pin, the contents of the I <sup>2</sup> C register program its functionality.  |
| Bit6   | MODE          | Default is '0' which is Burst Mode operation. A '1' programs the regulator to operate in forced continuous mode.   |
| Bit5(PHASE1)<br>Bit4(PHASE0)                         | Phase Control | Default varies per converter. '00' programs a SW HIGH transition to coincide with the internal clock rising edge. '01' programs a 90° offset, '10' programs a 180° offset, and '11' programs a 270° offset.  |
| Bit3(DAC3)<br>Bit2(DAC2)<br>Bit1(DAC1)<br>Bit0(DAC0) | DAC Control   | These bits are used to program the feedback regulation voltage. Default is '1100' which programs a voltage of 725mV. Bits '0000' program the lowest feedback regulation of 425mV, and '1111' programs a full-scale voltage of 800mV. An LSB (DAC0) has a bit weight of 25mV. |

## APPLICATIONS INFORMATION

### V<sub>CC</sub> Shunt Regulator

If load steps seen on V<sub>CC</sub> are of great concern, then the compensation capacitor should be tied from V<sub>CC</sub> to ground as shown in Figure 6a. If load steps are not of a concern, but instead smaller compensation components are desired then the compensation capacitor should be tied from V<sub>SHNT</sub> to ground as shown in Figure 6b.

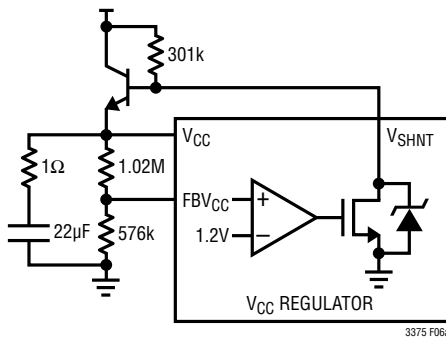


Figure 6a. V<sub>CC</sub> Regulator Compensated from the V<sub>CC</sub> Pin

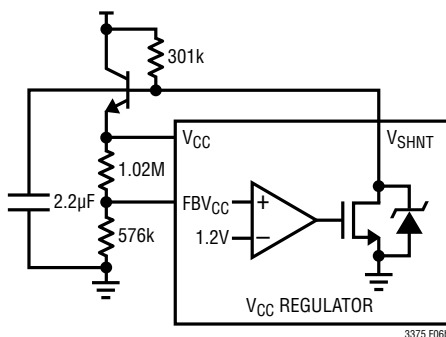


Figure 6b. V<sub>CC</sub> Regulator Compensated from the V<sub>SHNT</sub> Pin

The exact components used in the V<sub>CC</sub> shunt regulator are dependent on the specific conditions used in the application. Care should be taken to make sure that the power dissipation limits of the specific N-type device used are not exceeded, because damage to the external device can lead to damage to the LTC3375.

For an NPN device the pullup resistor between V<sub>SHNT</sub> and the supply voltage should be sized such that:

$$R_{PULLUP} < \frac{V_{SUPPLY(MINIMUM)} - (V_{CC} + V_{BE})}{I_{VCC(MAX)}} \cdot \beta$$

Where V<sub>SUPPLY(MINIMUM)</sub> is the lowest possible collector voltage, V<sub>BE</sub> and β are specific to the NPN in the application, and I<sub>VCC(MAX)</sub> is the maximum desired load current from V<sub>CC</sub>.

Likewise R<sub>PULLUP</sub> may be sized such to current limit I<sub>VCC</sub> from an NPN device to prevent damage to the circuit from a short on the V<sub>CC</sub> pin, and to prevent the NPN from exceeding its safe operating current:

$$R_{PULLUP} > \frac{V_{SUPPLY(MAXIMUM)} - (V_{CC} + V_{BE})}{I_{VCC(LIMIT)}} \cdot \beta$$

Where V<sub>CC</sub> = 0V in the case of a grounded output.

Alternatively, the current may be limited by adding a resistor between V<sub>CC</sub> and the emitter of the NPN such that:

$$R_{LIM} = \frac{6.1V - (V_{CC} + V_{BE})}{I_{VCC(LIMIT)}}$$

In this case when I<sub>VCC</sub> exceeds I<sub>VCC(LIMIT)</sub> V<sub>CC</sub> will start to collapse. The NPN should be sized to be able to survive at least:

$$I_{VCC(MAX)} = \frac{6.1V - V_{BE}}{R_{LIM}}$$

for the given supply voltage, where 6.1V is the maximum V<sub>SHNT</sub> voltage (typical).

The user should verify that the circuit is stable over the specific conditions of the desired application. In general increasing the value of the compensation capacitor used or increasing R<sub>PULLUP</sub> can improve stability. The user should keep in mind that increasing R<sub>PULLUP</sub> also decreases I<sub>VCC(MAX)</sub>. In general the highest V<sub>SUPPLY</sub> at I<sub>VCC(MAX)</sub> yields the worst stability for the circuit in Figure 6a, while the highest V<sub>SUPPLY</sub> at no load on V<sub>CC</sub> yields the worst stability for the circuit in Figure 6b.

## APPLICATIONS INFORMATION

In general the circuit in 6a is recommended if the application needs to drive any external circuitry with  $V_{CC}$  or if the larger compensation capacitor is tolerable. If  $V_{CC}$  is only needed to drive the LTC3375 and smaller component sizes are critical, then the circuit in Figure 6b may be used.

### Input and Output Decoupling Capacitor Selection

The LTC3375 has individual input supply pins for each buck switching regulator. Each of these pins must be decoupled with low ESR capacitors to GND. These capacitors must be placed as close to the pins as possible. Ceramic dielectric capacitors are a good compromise between high dielectric constant and stability versus temperature and DC bias. Note that the capacitance of a capacitor deteriorates at higher DC bias. It is important to consult manufacturer data sheets and obtain the true capacitance of a capacitor at the DC bias voltage it will be operated at. For this reason, avoid the use of Y5V dielectric capacitors. The X5R/X7R dielectric capacitors offer good overall performance.

The input supply voltage Pins 2, 5, 8, 11, 26, 29, 32 and 35 all need to be decoupled with at least 10 $\mu$ F capacitors.

### Choosing the $C_T$ Capacitor

The  $C_T$  capacitor may be used to program the timing parameters associated with the pushbutton. For a given  $C_T$  capacitor the timing parameters may be calculated as below.  $C_T$  is in units of  $\mu$ F.

$$t_{PB\_LO} = 5000 \cdot C_T \text{ ms}$$

$$t_{PB\_ON} = 20000 \cdot C_T \text{ ms}$$

$$t_{PB\_OFF} = 1000 \cdot C_T \text{ seconds}$$

$$t_{HR} = 100 \cdot C_T \text{ seconds}$$

$$t_{IRQ\_PW} = 5000 \cdot C_T \text{ ms}$$

$$t_{KILLH} = 1000 \cdot C_T \text{ seconds}$$

$$t_{KILLL} = 5000 \cdot C_T \text{ ms}$$

$$t_{RST} = 23000 \cdot C_T \text{ ms}$$

### Programming the Global Register

The Global Register contains functions that either act on the LTC3375 top level or act on all buck switching regulators at once. These functions are described in Table 8. The default structure is '0000 0000b'.

### Programming the $\overline{RST}$ and $\overline{IRQ}$ Mask Registers

The  $\overline{RST}$  mask register can be programmed by the user at sub-address 09h and its format is shown in Table 9.

If a bit is set to '1', then the corresponding regulator's PGOOD will pull  $\overline{RST}$  low if a PGOOD fault were to occur. The default for this register is FFh.

The  $\overline{IRQ}$  mask registers have the same bit format as the  $\overline{RST}$  mask register. The  $\overline{IRQ}$  mask registers are located at sub-addresses 0Ah and 0Bh and their default contents are 00h.

### Status Byte Read Back

When either the  $\overline{RST}$  or  $\overline{IRQ}$  pin is pulled low, it indicates to the user that a fault condition has occurred. To find out the exact nature of the fault, the user can read the status registers. There are three registers that contain status information. The register at sub-address 0Ch provides PGOOD fault condition reporting, while the register at sub-address 0Dh provides UVLO fault condition reporting. These bits are all latched at interrupt. If any of the bits are disabled via masking, then their real time, unlatched status information is still available. Bit7 of the register at sub-address 0Eh provides latched information on the status of the DT Warning. Figure 4 shows the operation of the status registers. The contents of the  $\overline{IRQ}$  status register are cleared when a CLRINT signal is issued. A PGOOD bit is a '0' if the regulator's output voltage is more than 7.5% below its programmed value. A UVLO bit is a '0' if the associated  $V_{IN}$  is above its input UVLO threshold. The format for the status registers is shown in Table 10.

A write operation cannot be performed to any of these status registers.

## APPLICATIONS INFORMATION

**Table 8. Global Control Program Register Bit Format**

|                        |                    |   |
|------------------------|--------------------|---|
| Bit7                   | RESET_ALL          | Default is '0'. When asserted all buck converters will power down for 1 second after which the bit will clear itself.   |
| Bit6(DT1)<br>Bit5(DT0) | DT WARNING CONTROL | Default is '00' which deactivates the DT warning. '01' programs -140°, '10' programs -125°, and '11' programs -110°.  |
| Bit4                   | IGNORE_EN          | Default is '0' which allows the EN pins to power on the buck converters. When written to '1' the enable pins will be ignored. This allows power-down sequencing via I <sup>2</sup> C even if the EN pins are tied to a logic HIGH voltage source. |
| Bit3                   | 1KPD               | Default is '0' in which the SW node remains in a high impedance state when the regulator is in shutdown. A '1' pulls the SW node to GND through a 1k resistor. This bit acts on all buck converters at once.                                      |
| Bit2                   | SLOW EDGE          | This bit controls the slew rate of the switch node. Default is '0' which enables the switch node to slew at a faster rate, than if the bit were programmed a '1'. This bit acts on all buck converters at once.                                   |
| Bit1                   | RD_TEMP            | Default is '0'. This bit commands the temperature A/D to sample the voltage present at the TEMP pin. After a read is complete this bit will clear itself.   |
| Bit0                   | Unused             | This bit is unused and must be written to "0"   |

**Table 9**

| BIT7     | BIT6     | BIT5     | BIT4     | BIT3     | BIT2     | BIT1     | BIT0     |
|----------|----------|----------|----------|----------|----------|----------|----------|
| PGOOD[8] | PGOOD[7] | PGOOD[6] | PGOOD[5] | PGOOD[4] | PGOOD[3] | PGOOD[2] | PGOOD[1] |

**Table 10**

| Sub-Address | BIT7     | BIT6     | BIT5     | BIT4     | BIT3     | BIT2     | BIT1     | BIT0     |
|-------------|----------|----------|----------|----------|----------|----------|----------|----------|
| 0Ch         | PGOOD[8] | PGOOD[7] | PGOOD[6] | PGOOD[5] | PGOOD[4] | PGOOD[3] | PGOOD[2] | PGOOD[1] |
| 0Dh         | UVLO[8]  | UVLO[7]  | UVLO[6]  | UVLO[5]  | UVLO[4]  | UVLO[3]  | UVLO[2]  | UVLO[1]  |
| 0Eh         | DT_WARN  | TEMP[6]  | TEMP[5]  | TEMP[4]  | TEMP[3]  | TEMP[2]  | TEMP[1]  | TEMP[0]  |

### PCB Considerations

When laying out the printed circuit board, the following list should be followed to ensure proper operation of the LTC3375:

1. The exposed pad of the package (Pin 49) should connect directly to a large ground plane to minimize thermal and electrical impedance.
2. All the input supply pins should each have a decoupling capacitor.
3. The connections to the switching regulator input supply pins and their respective decoupling capacitors should be kept as short as possible. The GND side of these capacitors should connect directly to the ground plane of the part. These capacitors provide the AC current to the internal power MOSFETs and their drivers. It is important to minimize inductance from these capacitors to the  $V_{IN}$  pins of the LTC3375.
4. The switching power traces connecting SW1, SW2, SW3, SW4, SW5, SW6, SW7 and SW8 to their respective inductors should be minimized to reduce radiated EMI and parasitic coupling. Due to the large voltage swing of the switching nodes, high input impedance sensitive nodes, such as the feedback nodes, should be kept far away or shielded from the switching nodes or poor performance could result.
5. The GND side of the switching regulator output capacitors should connect directly to the thermal ground plane of the part. Minimize the trace length from the output capacitor to the inductor(s)/pin(s).
6. In a combined buck regulator application the trace length of switch nodes to the inductor must be kept equal to ensure proper operation.

# TYPICAL APPLICATIONS

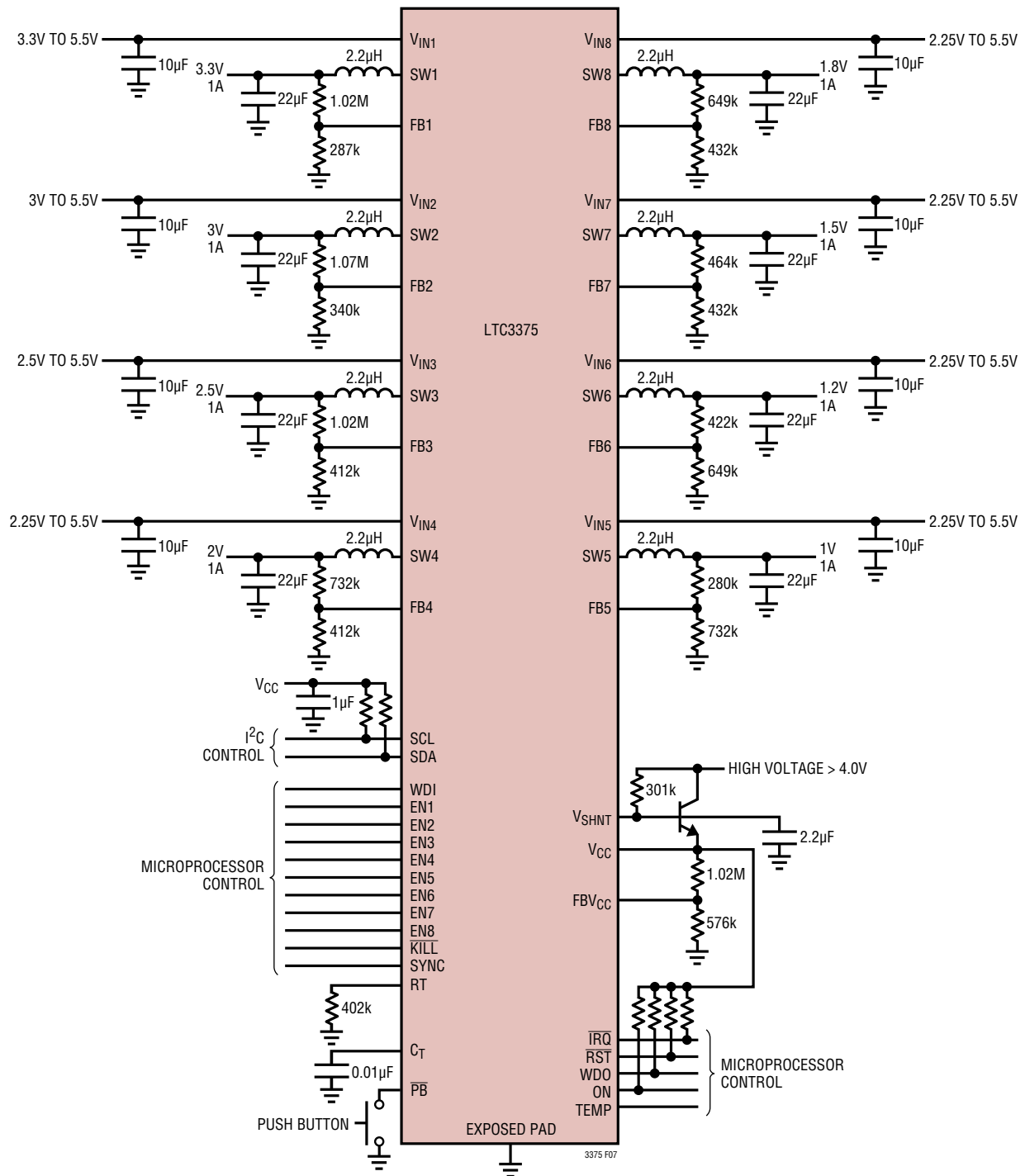


Figure 7. Detailed Front Page Application Circuit

TYPICAL APPLICATIONS

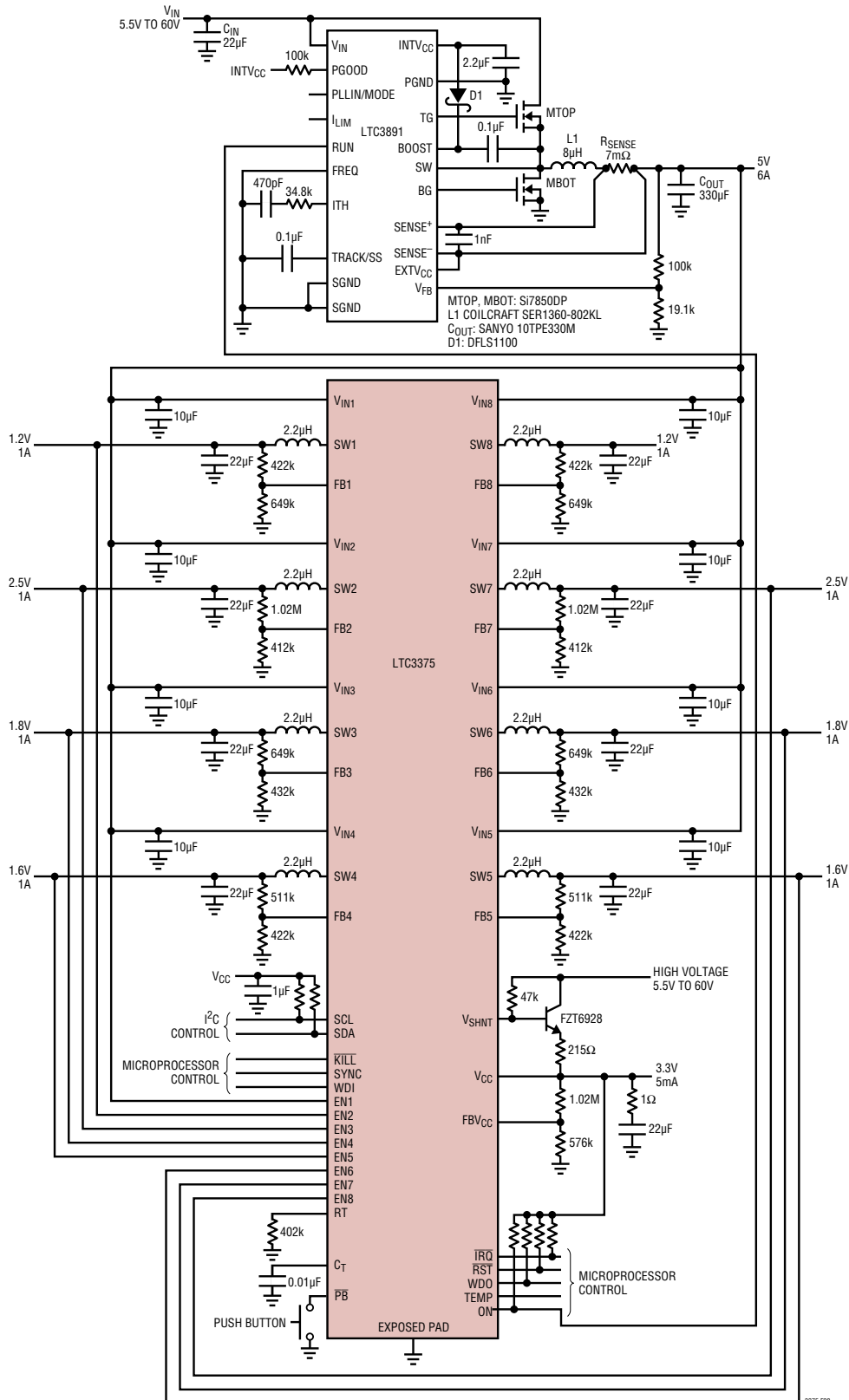


Figure 8. Buck Regulators with Sequenced Start-Up Driven from a High Voltage Upstream Buck Converter



# TYPICAL APPLICATIONS

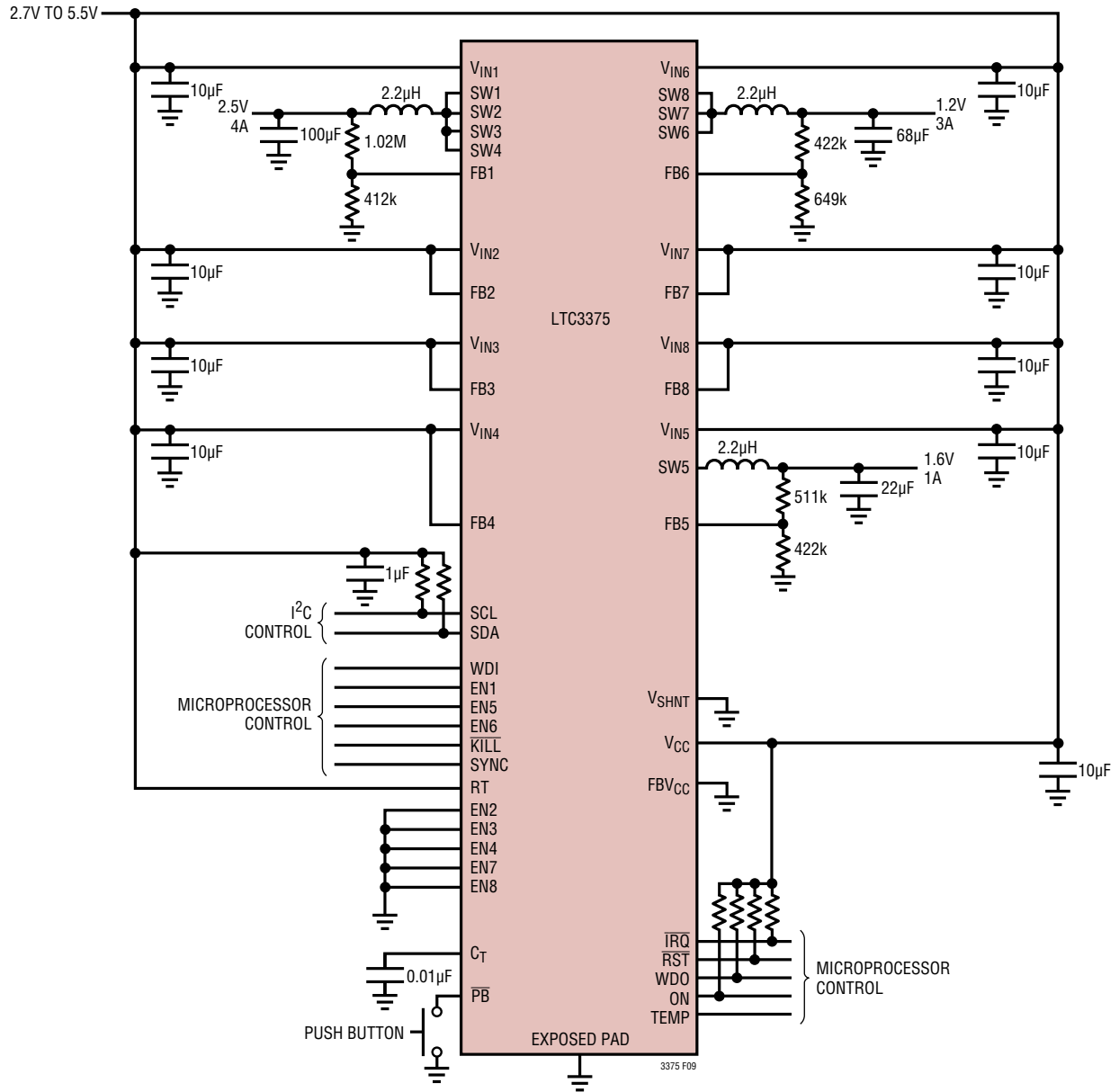
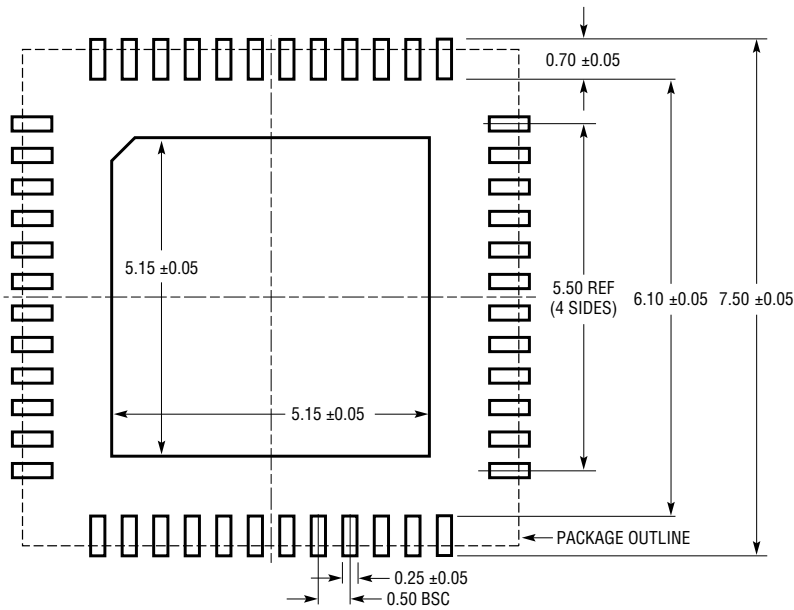


Figure 9. Combined Buck Regulators with Common Input Supply

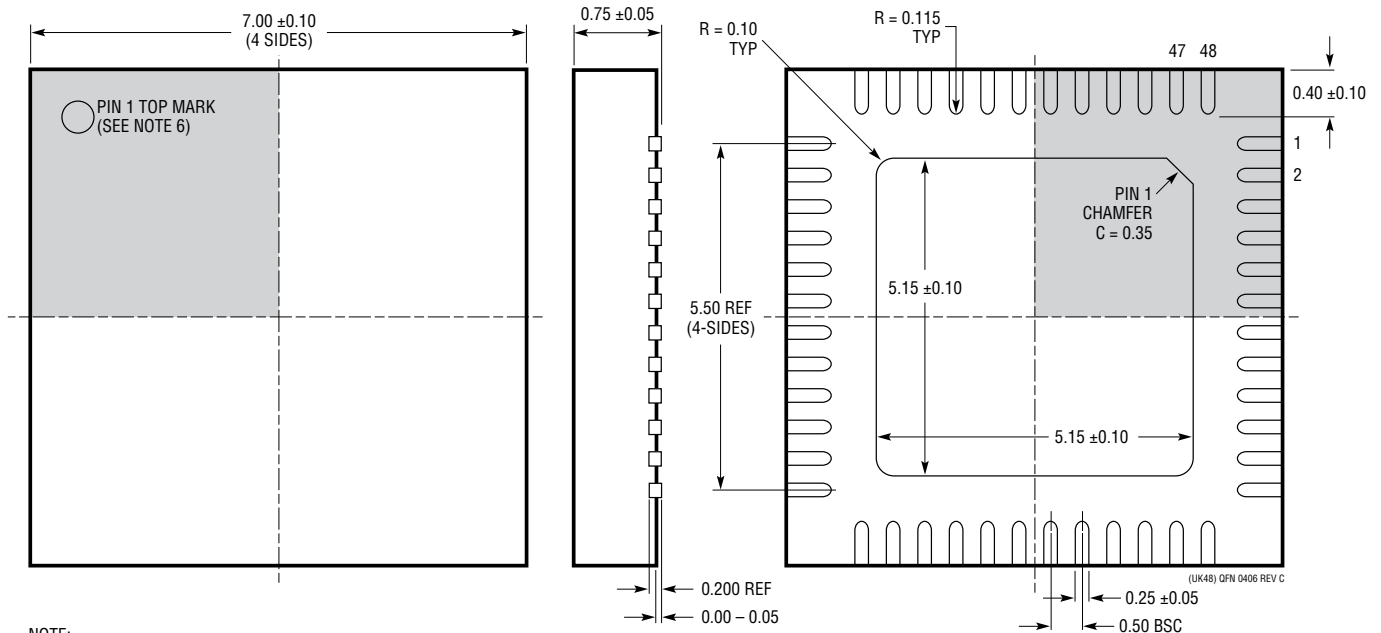
# PACKAGE DESCRIPTION

Please refer to <http://www.linear.com/designtools/packaging/> for the most recent package drawings.

**UK Package**  
**48-Lead Plastic QFN (7mm × 7mm)**  
 (Reference LTC DWG # 05-08-1704 Rev C)



RECOMMENDED SOLDER PAD PITCH AND DIMENSIONS  
 APPLY SOLDER MASK TO AREAS THAT ARE NOT SOLDERED



- NOTE:
1. DRAWING CONFORMS TO JEDEC PACKAGE OUTLINE MO-220 VARIATION (WKKD-2)
  2. DRAWING NOT TO SCALE
  3. ALL DIMENSIONS ARE IN MILLIMETERS
  4. DIMENSIONS OF EXPOSED PAD ON BOTTOM OF PACKAGE DO NOT INCLUDE MOLD FLASH. MOLD FLASH, IF PRESENT, SHALL NOT EXCEED 0.20mm ON ANY SIDE, IF PRESENT
  5. EXPOSED PAD SHALL BE SOLDER PLATED
  6. SHADED AREA IS ONLY A REFERENCE FOR PIN 1 LOCATION ON THE TOP AND BOTTOM OF PACKAGE

BOTTOM VIEW—EXPOSED PAD

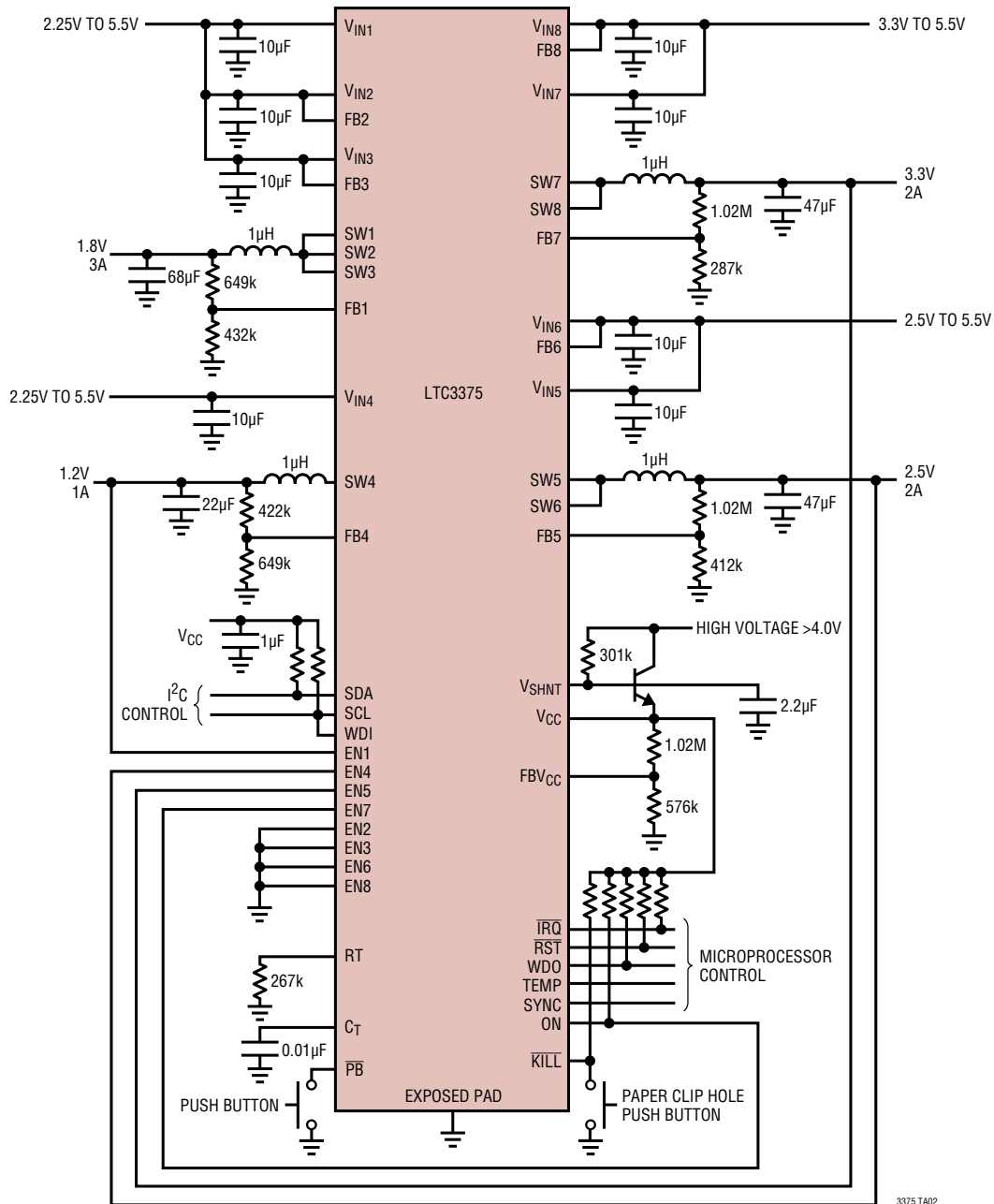
(UK48) QFN 0406 REV C

## REVISION HISTORY

| REV | DATE  | DESCRIPTION   | PAGE NUMBER |
|-----|-------|---|-------------|
| A   | 03/13 | Clarified $V_{CC}$ input supply current specification                         | 4           |
|     |       | Clarified RST pin functionality   | 12          |
|     |       | Clarified Buck Regulators with Combined Power Stages                          | 16, 17      |
|     |       | Clarified Table 6 Recommended Inductor Ratings                                | 27          |
| B   | 07/13 | Modified SYNC pin description   | 12          |
| C   | 10/13 | Changed units on $V_{IL}$ specification                                       | 5           |
|     |       | Modified Bit 3 conditions in Global Control Program Register Bit Format Table | 30          |

## TYPICAL APPLICATION

Combined Bucks with 3MHz Switch Frequency, Sequenced Power Up, and KILL Based Hardware Override Shut Down



3375 TA02

## RELATED PARTS

| PART NUMBER                       | DESCRIPTION   | COMMENTS  |
|-----------------------------------|---|---|
| <a href="#">LTC3675</a>           | 7-Channel Configurable High Power PMIC                  | Four Parallelable Buck DC/DCs (1A, 1A, 500mA, 500mA), 1A Boost, 1A Buck-Boost, 25mA LDO, Dual String LED Driver, Pushbutton, I <sup>2</sup> C Control |
| <a href="#">LTC3589/LTC3589-1</a> | 8-Output Regulator with Sequencing and I <sup>2</sup> C | Three Buck DC/DCs, Three 250mA LDOs, 25mA LDO, 1.2A Buck-Boost, Pushbutton, I <sup>2</sup> C Control  |

3375fc