

Serial Bus Options for InfiniiVision X-Series Oscilloscopes

Data Sheet



Supported protocols and features

- 1²C
- SPI
- RS232/UART
- CAN
- CAN-dbc symbolic decode and trigger (4000 and 6000 X-Series only)
- LIN
- USB 2.0 low- and full-speed (4000 and 6000 X-Series only)
- USB 2.0 hi-speed (4000 and 6000 X-Series only)
- USB 2.0 signal quality (4000 and 6000 X-Series only)
- I²S (3000, 4000, and 6000 X-Series only)
- FlexRay (3000, 4000, and 6000 X-Series only)
- MIL-STD 1553 (3000, 4000, and 6000 X-Series only)
- ARINC 429 (3000, 4000, and 6000 X-Series only)
- · Hardware-based decoding
- Multi-bus analysis (3000, 4000, and 6000 X-Series only)
- · Automatic search and navigation
- · Compatibility with segmented memory acquisition
- Eye-diagram mask files available for CAN, FlexRay, MIL-STD 1553, and ARINC 429 (requires DSOX2MASK/DSOX3MASK/DSOX4MASK / DSOX6MASK mask test option)
- FlexRay physical layer conformance test software (3000, 4000, and 6000 X-Series only)

Introduction

Serial buses are pervasive in today's digital designs and are used for a variety of purposes including on-board chip-to-chip communication, CPU to peripheral control, as well as for remote sensor data transfer and control. Without intelligent oscilloscope serial bus triggering and protocol decode, it can be difficult to debug these buses and correlate data transfers with other mixed signal interactions in your system. Agilent's InfiniiVision X-Series oscilloscopes (DSOs) and mixed-signal oscilloscopes (MSOs) offer optional integrated serial bus triggering and hardware-based protocol decoding solutions that give you the tools you need to accelerate debug of your designs that include serial bus communication.



Agilent Technologies

Hardware-based decoding

Automatic search and navigation



Figure 1: Hardware-based decoding quickly reveals serial communication errors.

Agilent's InfiniiVision Series oscilloscopes are the industry's only scopes to use hardware-based decoding. Most other vendor's scopes with serial bus triggering and protocol decode, use software post-processing techniques to decode serial packets/frames. With these software techniques, waveform- and decode-update rates tend to be slow (sometimes seconds per update.) That's especially true when using deep memory, which is often required to capture multiple packetized serial bus signals. And when analyzing multiple serial buses simultaneously, software techniques can make decode update rates even slower.

Faster decoding with hardware-based technology enhances scope usability, and more importantly, the probability of capturing infrequent serial communication errors. Figure 1 shows an example of an Agilent InfiniiVision X-Series scope capturing a random and infrequent CAN error frame. The upper half of the scope's display shows the decoded data in a "Lister" format, along with a time-correlated decode trace shown below the waveform.

Symbolic trigger and decode

With the DSOX4AUTO or DSOX6AUTO option licensed on a 4000 or 6000 X-Series oscilloscope, you can import a .dbc file that defines your multi-node CAN network. The oscilloscope can then trigger on and decode the CAN bus symbolically as shown in Figure 2.

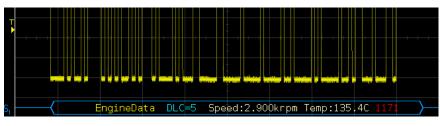
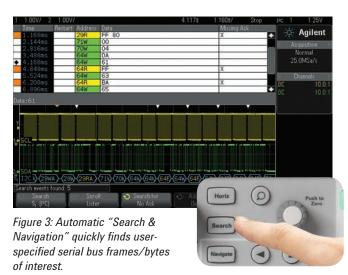


Figure 2: Symbolically decoding the CAN bus.



After capturing a long record of serial bus communication using the InfiniiVision scope's *MegaZoom* deep memory, you can easily perform a search operation based on specific criteria that you enter. Then, you can quickly navigate to bytes/frames of serial data that satisfy the entered search criteria. Figure 3 shows an example of searching on captured I²C data to find all occurrences of Read or Write operations with "No Ack." In this case, the scope found five occurrences of data transfers with "No Ack," and marked each occurrence with a white triangle to show where in time they happened relative to the captured waveform. Navigating and zooming-in on each marked byte/frame is quick and easy using the scope's front panel navigation keys.

Multi-bus analysis

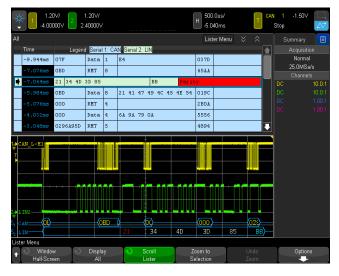


Figure 4: An interleaved "Lister" makes it easier to time-correlate activity between two decoded serial buses.

Many of today's designs include multiple serial buses. Sometimes it may be necessary to correlate data from one serial bus to another. Agilent's InfiniiVision 3000, 4000, and 6000 X-Series oscilloscopes can decode two serial buses simultaneously using hardware-based decoding. Plus they are the only scopes on the market that can also display the captured data in a time-interleaved "Lister" display, as shown in Figure 4. In this particular example, the scope has simultaneously decoded and interleaved a CAN and LIN bus in an automotive system.

Using segmented memory to capture multiple serial bus packets



Figure 5: Segmented memory acquisition selectively captures more packets/bytes of serial bus activity.

The segmented memory option for Agilent's InfiniiVision X-Series oscilloscopes (standard in 4000 and 6000 X-Series) can optimize your scope's memory, letting you capture more packets/frames of serial bus activity. Segmented memory acquisition optimizes the number of packetized serial communication frames that can be captured consecutively. Segmented memory does this by capturing just the selective frames/bytes of interest while ignoring (not digitizing) idle time and other unimportant frames/bytes. Figure 5 shows an example of the oscilloscope capturing 500 consecutive hi-speed USB split packets for a total acquisition time of approximately 200 ms. Capturing this much data using conventional oscilloscope acquisition memory would require 1G bytes of memory.

Agilent's InfiniiVision X-Series oscilloscopes are the only scopes on the market today that can acquire segments on up to four analog channels of acquisition, and time-correlated segments on digital channels (using an MSO model), along with automatic hardware-based serial bus decoding for each segment. In addition, you can use the scope's Search & Navigation capability after a segmented memory acquisition has been performed.

Serial bus eye-diagram and pulse mask testing

With the addition of the DSOX2MASK, DSOX3MASK, DSOX4MASK, or DSOX6MASK mask test option, which can perform over 200,000 pass/fail tests (50,000 on 2000 X-Series) per second, you can perform eye-diagram and pulse mask testing on CAN signals on all InfiniiVision X-Series oscilloscopes. Eye-diagram mask testing on FlexRay, MIL-STD 1553, and ARINC 429 signals can be performed using an InfiniiVision 3000, 4000, or 6000 X-Series oscilloscope. Eye-diagram measurements provide a comprehensive signal quality test of the integrity of your transmitted and received signals. Agilent provides various mask files that you can download at no charge. The mask files are based on published industry mask standards and/or derived from physical layer/electrical specifications.

The following CAN mask files are available:

- 125 kbps 400 meters
- 250 kbps 200 meters
- 500 kbps 10 meters
- 500 kbps 80 meters
- 800 kbps 40 meters
- 1000 kbps 25 meters

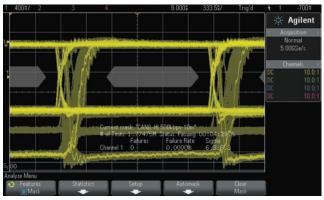


Figure 6: CAN 500 kbps mask test on 10 meter system.

The following FlexRay mask test files are available:

- TP1 standard voltage (10 Mbps only)
- TP1 increased voltage (10 Mbps only)
- TP11 standard voltage (10 Mbps only)
- TP11 increased voltage (10 Mbps only)
- TP4 10 Mbps
- TP4 5 Mbps
- TP4 2.5 Mbps

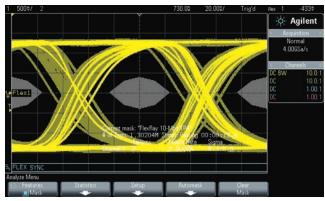


Figure 7: FlexRay TP4 eye-diagram mask test.

The following MIL-STD 1553 mask test files are available:

- · System xfmr-coupled Input
- · System direct-coupled Input
- BC xfmr-coupled Input
- BC direct-coupled Input
- RT xfmr-coupled Input
- · RT direct-coupled Input

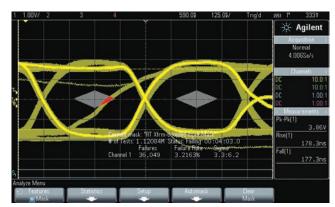


Figure 8: MIL-STD 1553 BC to RT xfrm-coupled input mask test reveals a shifted bit that violates the pass/fail mask.

Serial bus eye-diagram and pulse mask yesting

The following ARINC 429 mask/pulse test files are available:

- · 100 kbps Eye Test
- 100 kbps 1's Pulse Test
- 100 kbps 0's Pulse Test
- · 100 kbps Null Level Test
- 12.5 kbps Eye Test
- 12.5 kbps 1's Pulse Test
- 12.5 kbps 0's Pulse Test
- 12.5 kbps Null Level Test

For additional information about eye-diagram mask testing on CAN, FlexRay, MIL-STD 1553, and ARINC 429 signals, refer to the application notes listed at the end of this document.

Automated physical layer conformance testing

To perform USB 2.0 signal quality testing based on USB-IF compliance standards, Agilent offers the DSOX4USBSQ or DSOX6USBSQ options on InfiniiVision 4000 or 6000 X-Series oscilloscopes. Figure 10 shows an example of the USB 2.0 real-time eye test. Also included with this option is complete signal quality test report generation in HTML format. To see the complete list of supported tests, refer to the DSOX4USBSQ/DSOX6USBSQ signal quality test option data sheet listed at the ended of this document.

To perform physical layer conformance testing on the differential FlexRay bus, Agilent provides a PC-based software package that you can download from Agilent's website at no additional charge. If the InfiniiVision X-Series scope is licensed with the FlexRay, mask test, and segmented memory, you can perform automated physical layer tests at either receiver input or transmitter output test points. Figure 10 shows an example of the generated report from a signal integrity voting test on a 10-Mbs isolated "1" pulse. The test report includes comprehensive pass/fail and margin analysis based on published specifications.

Refer to the tables in the Specifications/Characteristics section of this document on page 15 to see the entire list of 33 available FlexRay tests that can be selected and performed using the FlexRay physical layer conformance test software package.

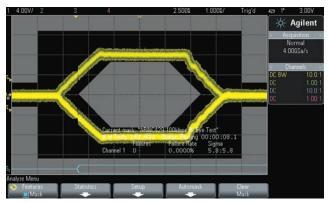


Figure 9: ARINC 429 100 kbps eye-diagram mask test.

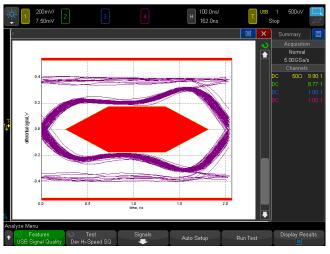


Figure 10: USB 2.0 signal quality eye test based on USB-IF physical layer compliance standards.

| Isolated | One | | | | Reference. |
|-------------------------------------|------------------------------------------------------------------------------------------------|---------------|------------------------------------------|-----------|------------|
| Test Summary: Pass | | solated "One" | Pass | | |
| Result Details Isolated One(Imag | (See image) | | | | |
| Trial 1 | (| | | | |
| Parameter | Description | Specification | Data Measurements | Pass/Fail | |
| dBitLong | Longest Single bit | - | 97.06 ns | Pass | |
| dBitShort | Shortest Single bit | 70.95 ns | 95.49 ns | Pass | |
| dBitLength Variation | Bit Asymmetry | 7 ns | 1.56 ns | Pass | |
| dEdge01 | Rising Edge Duration | 50 ns | 10.72 ns | Pass | |
| dEdge10 | Falling Edge Duration | 50 ns | 10.59 ns | Pass | |
| dEdgeMax | Slowest Edge | 50 ns | 10.72 ns | Pass | |
| dEdgeMax | Slowest Edge | 50 ns | 10.72 ns | Pass | |
| uData1Top | Required maximal LvI | 330 mV | 1.2973 V | Pass | |
| Sq1 | Voted Signal Quality | - | - | Pass | |
| Trial 1: Isolated One | (Image) | | | | |
| | 15 05 05 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 | 300 69 | 500 00 10 000 00 00 00 00 00 00 00 00 00 | w/o LPF | |

Figure 11: FlexRay signal integrity voting test performed on an isolated "1" bit.

Probing differential serial buses

Many of today's serial buses are based on differential signaling including USB, CAN, FlexRay, MIL-STD 1553, and ARINC 429. In addition, serial buses based on the RS232/UART protocol are often differential if implemented with RS422 or RS485 output drivers/ transceivers. Agilent offers a wide range of differential active probes compatible with the InfiniiVision X-Series oscilloscopes for various bandwidth and dynamic range applications. Table 1 shows the differential probes that Agilent recommends for each of the listed differential serial buses.

N2818A¹ **Differential bus** N2791A N2750A (200-MHz bandwidth) (max bit rate) (25-MHz bandwidth) (1.5-GHz bandwidth) $\sqrt{}$ $\sqrt{}$ CAN (1 Mbps) $\sqrt{}$ FlexRay (10 Mbps) $\sqrt{}$ $\sqrt{}$ MIL-STD 1553 (1 Mbps) $\sqrt{}$ $\sqrt{}$ ARINC 429 (100 kbps) $\sqrt{}$ $\sqrt{}$ RS422/RS485 (10 Mbps) Hi-speed USB (480 Mbps) $\sqrt{}$

Table 1: Recommended Probes for Differential Buses

Note 1: The N2818A differential probe is not compatible with Agilent's InfiniiVision 2000 X-Series oscilloscopes.

If you need to connect to DB9-SubD connectors on your differential CAN and/or FlexRay bus, Agilent also offers the CAN/ FlexRay DB9 probe head (part number 0960-2926). This differential probe head, which is shown in the inset picture of Figure 12, is compatible with both the N2791A and N2818A differential active probes and allows you to easily connect to your CAN and/or FlexRay differential bus.

The N2750A differential active probe shown in Figure 13, which is recommended for hi-speed USB 2.0 measurement applications, is based on Agilent's InfiniiMode technology. With the press of a button, you can quickly toggle between viewing the differential signal, high-side signal, low-side signal, or the common mode signal on the USB 2.0 hi-speed bus without moving probe connections. Note that this probe also comes with a built-in headlight.

For more information about Agilent's probing solutions, refer to the InfiniiVision Series Oscilloscope Probes & Accessories data sheet (publication number 5968-8153EN) listed at the end of this document.



Figure 12: Agilent's N2818A 200-MHz differential active probe.



Figure 13: Agilent's N2750A 1.5-GHz InfiniiMode differential active probe.

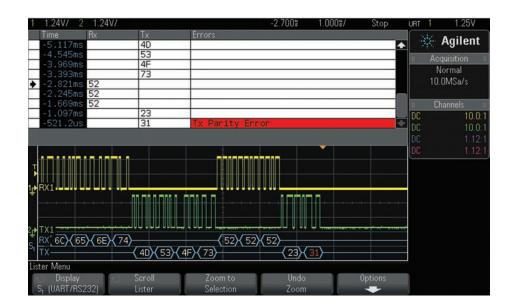
| I ² C specifications | I ² C specifications/characteristics (DSOX2EMBD, DSOX3EMBD, DSOX4EMBD, and DSOX6EMBD) | | |
|---------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--|--|
| Clock and data input source | Analog channels 1, 2, 3, or 4 Digital channels D0 to D15 (3000, 4000, and 6000 X-Series only) | | |
| Max clock/data rate | Up to 3.4 Mbps | | |
| Triggering | Start condition Stop condition Missing acknowledge Address with no acknowledge Restart EEPROM data read Frame (Start:Addr7:Read:Ack:Data) Frame (Start:Addr7:Write:Ack:Data) Frame (Start:Addr7:Read:Ack:Data:Ack:Data2) Frame (Start:Addr7:Write:Ack:Data:Ack:Data2) 10-bit write | | |
| Hardware-based decode | Data (HEX digits in white) Address decode size: 7 bits (excludes R/W bit) or 8 bits (includes R/W bit) Read address (HEX digits followed by "R" in yellow) Write address (HEX digits followed by "W" in light-blue) Restart addresses ("S" in green, followed by HEX digits, followed by "R" or "W") Acknowledges (suffixes "A" or "~A" in the same color as the data or address preceding it) Idle bus (mid-level bus trace in dark blue) Active bus (bi-level bus trace in dark blue) Unknown/error bus (bi-level bus trace in red) | | |
| Multi-bus analysis | l ² C plus one other serial bus, including another l ² C bus. (3000, 4000, and 6000 X-Series only) | | |

| 1 1.00V/ | 2 1.00V | / | | | 1.650 | £ 200.0 | 0%/ | Stop | I2C 1 | 1.25V |
|----------------------------------|---------|---------|-------|-----------|-------|------------|------------|----------------------|----------|----------------|
| Time | Restart | Address | Data | | | M | issing Ack | | 100 | Amilant |
| -1.508m | | 71W | 10 | | | | 100 ANAI | * | * | Agilent |
| -836.1u | | 29₩ | 01 60 | | | | | | :: år | quisition = |
| 203.9us | | 29W | 04 | | | | | | | Vormal |
| 883.9us | | 29R | FF 80 | | | X | | | | |
| 1.864ms | | 71W | 00 | | | | | | 51 | I.OMSa/s |
| 2.536ms | | 70W | 04 | | | | | | | |
| 3.208ms | | 64W | DA | | | | | | # C | hannels : |
| 3.888ms | | 64W | 61 | | | | | | DC | 10.0:1 |
| 4.568ms | | 64R | FF | | | X | | * | DC | 10.0:1 |
| | | | | | | | | | | |
| Data:FF 80 | | | | | | | | | DC DC | 1.12: 1.12: |
| | | | | | | | | | | |
| 21 SDA1 | < 2 | 9RA | FFA | 80~A | | '1WA | 00A | $\rightarrow \frown$ | | |
| Lister Menu | | | | | | | | | 3 | |
| Display | | 🗇 Scro | | Zoom to | | ndo Iom | | tions | | |
| S ₁ (I ² C | | Liste | A | Selection | | | | - | | |

| SPI specifications/c | SPI specifications/characteristics (DSOX2EMBD, DSOX3EMBD, DSOX4EMBD, and DSOX6EMBD) | | |
|----------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--|--|
| MOSI, MISO, Clock, and CS input source | Analog channels 1, 2, 3, or 4 Digital channels D0 to D15 (3000, 4000, and 6000 X-Series only) | | |
| Max clock/data rate | Up to 25 Mb/s | | |
| Triggering | 4- to 64-bit data pattern during a user-specified framing period Framing period can be a positive or negative chip select (CS or ~CS) or clock idle time (timeout) | | |
| Hardware-based decode | Number of decode traces: 2 independent traces (MISO and MOSI) Data (hex digits in white) Unknown/error bus (bi-level bus trace in red) Number of clocks/packet ("XX CLKS" in light-blue above data packet) Idle bus (mid-level bus trace in dark blue) Active bus (bi-level bus trace in dark blue) | | |
| Multi-bus analysis | SPI plus one other serial bus, excluding another SPI bus. (3000, 4000, and 6000 X-Series only) | | |

| 1 2 6.980s 500.0s/ Stop | spi D _e TTL |
|----------------------------------------------------------------|------------------------|
| Time MOSI MISO | Agilont |
| -8.628ms 02 08 49 4C 45 4E 54 FF FF FF FF FF FF FF FF | 🖌 🔆 Agilent |
| -3.924ms 03 06 00 00 00 00 00 00 00 FF FF 41 67 49 4C 45 4E 54 | Acquisition |
| -640.1us 06 FF | Normal |
| 99.92us 05 FF FF 02 | 25.0MSa/s |
| 1.384ms 02 10 4D 53 4F FF FF FF FF FF | 20.01413073 |
| 5.000ms 03 10 00 00 00 FF FF 6F 73 4F ◆ 6.980ms 06 FF | 01 1 |
| 7.720ms 05 FF FF 02 | : Channels : |
| 8.896ms 02 20 FF FF | DC 10.0:1 |
| | 10.0:1 |
| M0SI:06 | DC 1.12:1 |
| D _g MOSI1 | DC 1.12:1 |
| D _g MISO1 | |
| D_ CLK1 | 10 |
| | 0 |
| D ₈ ~CS1 | - |
| | |
| 40 CLKS 8 CLKS 16 CLKS | |
| S, MOSI (03 10 00 00 00 (06) 05 FF) 02 | |
| MISO FF FF 6F 73 4F FF FF 02 FF 02 FF | |
| Lister Menu | |
| Display Scroll Zoom to Undo Options | |
| S, (SPI) Lister Selection Zoom 🔫 | |

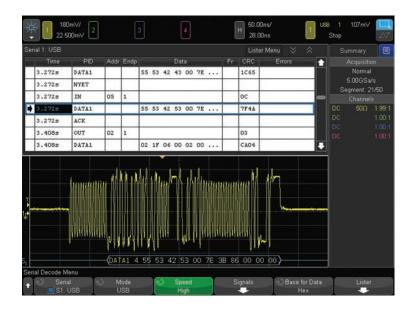
| RS232/UART specifica | tions/characteristics (DSOX2COMP, DSOX3COMP, DSOX4COMP, and DSOX6COMP) |
|---------------------------|----------------------------------------------------------------------------|
| Tx and Rx input source | Analog channels 1, 2, 3, or 4 |
| | Digital channels D0 to D15 (3000, 4000, and 6000 X-Series only) |
| Bus configuration | |
| Baud rates | 100 b/s up to 8 Mb/s |
| Number of bits | 5 to 9 |
| Parity | None, odd, or even |
| Polarity | ldle low or idle high |
| Bit order | LSB out first or MSB out first |
| Triggering | Rx start bit |
| | Rx stop bit |
| | Rx data |
| | Rx 1:data (9-bit format) |
| | Rx 0:data (9-bit format) |
| | Rx X:data (9-bit format) |
| | Rx or Tx parity error |
| | Tx start bit |
| | Tx stop bit |
| | Tx data |
| | Tx 1:data (9-bit format) |
| | Tx 0:data (9-bit format) |
| | Tx X:data (9-bit format) |
| | Burst (nth frame within burst defined by timeout) |
| Hardware-based decode | |
| Number of decode traces | 2 independent traces (Tx and Rx) |
| Data format | Binary, hex, or ASCII-code characters |
| Data byte display | White characters if no parity error, red characters if parity or bus error |
| Idle bus trace | Mid-level bus trace in blue |
| Active bus trace | Bi-level trace in blue |
| Multi-bus analysis | RS232/UART plus one other serial bus, including another RS232/UART bus. |
| - | (3000, 4000, and 6000 X-Series only) |
| Totalize/counter function | Total received frames |
| | Total transmitted frames |
| | Total parity error frames (with percentage) |



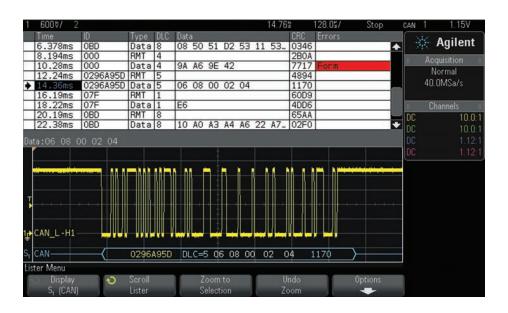
| USB 2.0 low- and full-spe | eed specifications/characteristics (DSOX4USBFL and DSOX6USBFL) |
|----------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| USB input source (D+ & D-) | Analog channels 1, 2, 3, 4 Digital channels D0-D15 |
| Speed | Low (1.5 Mb/s) and Full (12 Mb/s) |
| Triggering | Start of packet (SOP) End of packet (EOP) Suspend – when bus is idle for > 3 ms Resume – when exiting an idle state > 10 ms Reset – when SE0 is > 10 ms Token packet with specified content Data packet with specified content Handshake packet with specified content Special packet with specified content All errors – any of the below error conditions PID error – if packet type field does not match check field CRC5 error – if 5 bit CRC error is detected CRC16 error – if 16 bit CRC error is detected Glitch error – if >6 consecutive "ones" are detected SE1 error – if SE1 > 1 bit time |
| Hardware-based decode | |
| Base format | Hex, Binary, ASCII, or Decimal data decode |
| Token packets (excluding SOF, 3 bytes) | PID (yellow, "OUT", "IN", "SETUP", "PING") PID Check (yellow when valid, red when error detected) – numeric value Address (blue, 7 bits) Endpoint (green, 4 bits) CRC (blue when valid, red when error detected, 5 bits) |
| Token packets (SOF, 3 bytes) | PID (yellow, "SOF") PID Check (yellow when valid, red when error detected, 5 bits) Frame (green, 11-bits) – the frame number CRC (blue when valid, red when error detected, 5 bits) |
| Data packets (3 to 1027 bytes) | PID (yellow, "DATA0", "DATA1", DATA2", "MDATA") PID Check (yellow when valid, red when error detected, 16 bits) |
| Handshake packets (1 byte) | PID (yellow, "ACK", "NAK", "STALL", "NYET", "PRE", "ERR") PID Check (yellow when valid, read when error detected) – numeric value Hub Addr (green, 7 bits) SC (blue, 1 bit) Port (green, 7 bits) S & E U (blue, 2 bits) ET (green, 2 bits) CRC (blue when valid, red when error detected, 5 bits |
| | |



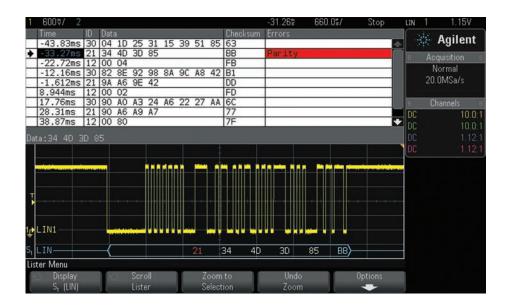
| USB 2.0 high-speed specifications/characteristics (DSOX4USBH and DSOX6USBH) | | | | |
|-----------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--|--|--|
| USB differential input source | Analog channels 1, 2, 3, 4 (using a differential active probe) | | | |
| Speed | High (480 Mb/s) | | | |
| Triggering | Token packet with specified content Data packet with specified content Handshake packet with specified content Special packet with specified content All errors – any of the below error conditions PID error – if packet type field does not match check field CRC5 error – if 5 bit CRC error is detected CRC16 error – if 16 bit CRC error is detected Glitch error – if two transitions occur in half a bit time | | | |
| Hardware-based decode | | | | |
| Base format | Hex, Binary, ASCII, or Decimal data decode | | | |
| Token packets (excluding SOF, 3 bytes) | PID (yellow, "OUT", "IN", "SETUP", "PING") PID check (yellow when valid, red when error detected) – numeric value Address (blue, 7 bits) Endpoint (green, 4 bits) CRC (blue when valid, red when error detected, 5 bits) | | | |
| Token packets (SOF, 3 bytes) | PID (yellow, "SOF") PID check (yellow when valid, red when error detected, 5 bits) Frame (green, 11-bits) – the frame number CRC (blue when valid, red when error detected, 5 bits) | | | |
| Data packets (3 to 1027 bytes) | PID (yellow, "DATA0", "DATA1", DATA2", "MDATA") PID check (yellow when valid, red when error detected, 16 bits) | | | |
| Handshake packets (1 byte) | PID (yellow, "ACK", "NAK", "STALL", "NYET", "PRE", "ERR") PID check (yellow when valid, read when error detected) – numeric value Hub Addr (green, 7 bits) SC (blue, 1 bit) Port (green, 7 bits) S & E U (blue, 2 bits) ET (green, 2 bits) CRC (blue when valid, red when error detected, 5 bits | | | |
| Multi-bus analysis | N/A | | | |
| | | | | |



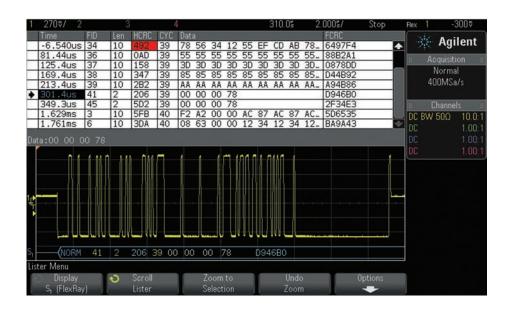
| CAN specifications/cl | naracteristics (DSOX2AUTO, DSOX3AUTO, DSOX4AUTO, and DSOX6AUTO) |
|---------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| CAN input source | Analog channels 1, 2, 3, or 4 Digital channels D0 to D15 non-differential. (3000, 4000, and 6000 X-Series only) |
| Signal types | Rx, Tx, CAN_L, CAN_H, Diff (L-H), Diff (H-L) |
| Baud rates | 10 kb/s up to 5 Mb/s |
| Triggering | Start-of-frame (SOF) Remote frame ID (RMT) Data frame ID (~RMT) Remote or data frame ID Data frame ID and data Error frame All errors (includes protocol "form" errors that may not generate flagged error frames) Acknowledge errors Overload frames ID length: 11 bits or 29 bits (extended) |
| Symbolic triggering (DSOX4AUTO only) | Message names Message and signal values/encoded states |
| Hardware-based decode | Frame ID (hex digits in yellow) Remote frame (RMT in green) Data length code (DLC in blue) Data bytes (hex digits in white) CRC (hex digits in blue = valid, hex digits in red = error) Error frame (bi-level bus trace and ERR message in red) Form error (bi-level bus trace and "?" in red) Overload frame ("OVRLD" in blue) Idle bus (mid-level bus trace in dark blue) Active bus (bi-level bus trace in dark blue) |
| Symbolic decode (DSOX4AUTO only) | Message names (alpha-numeric characters in yellow) Signal names, value/encoded state, and units (alpha-numeric characters in white) |
| Multi-bus analysis | CAN plus one other serial bus, including another CAN bus. (3000, 4000, and 6000 X-Series only) |
| Totalize function | Total frames, total overload frames, total error frames, bus utilization (bus load) |
| Eye-diagram mask testing (requires DSOX3MASK /DSOX4MASK /DSOX6MASK) | Various downloadable mask files available based on differential probing polarity, baud rate, and network length |



| LIN input source | Analog channels 1, 2, 3, or 4 Digital channels D0 to D15 (3000, 4000, and 6000 X-Series only) |
|-----------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| LIN standards | LIN 1.3 or LIN 2.X |
| Baud rates | 2400 b/s to 625 kb/s |
| Triggering | Sync break Frame ID (0X00 _{HEX} to 0X3F _{HEX}) Frame ID and data Parity error Checksum error |
| Hardware-based decode | Frame ID (6-bit hex digits in yellow) Frame ID and optional parity bits (8-bit hex digits in yellow if valid, red if parity bit error) Data bytes (hex digits in white) Check sum (hex digits in blue = valid, hex digits in red = error) Sync error ("SYNC" in red) THeader-max ("THM" in red) TFrame-max ("TFM" in red) Parity error ("PAR" in red) LIN 1.3 wake-up error ("WUP" in red) Idle bus (mid-level bus trace in dark blue) Active bus (bi-level bus trace in dark blue) |
| Multi-bus analysis | LIN plus one other serial bus, including another LIN bus. (3000, 4000, and 6000 X-Series only) |



| FlexRay channels A or B Baud rates 2.5 Mbps, 5.0 Mbps, and 10 Mbps Frame triggering • Frame type: startup (SUP), not startup (~SUP), sync (SYNC), not sync (~SYNC), not (NULL), not null (~NULL), normal (NORM), and All • Frame ID: 1 to 2047 (decimal format), and All • Base: 0 to 63 (decimal format), and All • Base: 0 to 63 (decimal format), and All • Base: 0 to 63 (decimal format), and All • Repetition: 1, 2, 4, 8, 16, 32, 64 (decimal format), and All • Repetition: 1, 2, 4, 8, 16, 32, 64 (decimal format), and All Error triggering • All errors • Header CRC error • Frame CRC error • Frame CRC error • TSS (transmission start sequence) • BSS (byte start sequence) • BSS (byte start sequence) • FES/DTS (frame end or dynamic trailing sequence) • Frame ID (decimal digits in yellow) • Payload-length (decimal number of words in green) • Header CRC (hex digits in blue if valid, or red digits if invalid) • Cycle number (decimal digits in yellow) • Data bytes (HEX digits in white) • Frame CRC (hex digits in blue if valid, or red digits • Total frames • Total frames • Total frames • Total frames • Total frames • Total null frames • Total null frames • Total null frames | FlexRay specific | cations/characteristics (DSOX3FLEX, DSOX4FLEX, and DSOX6FLEX) |
|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Baud rates 2.5 Mbps, 5.0 Mbps, and 10 Mbps Frame triggering • Frame type: startup (SUP), not startup (~SUP), sync (SYNC), not sync (~SYNC), not (NULL), normal (NORM), and All • Frame ID: 1 to 2047 (decimal format), and All • Base: 0 to 63 (decimal format), and All • Repetition: 1, 2, 4, 8, 16, 32, 64 (decimal format), and All • Repetition: 1, 2, 4, 8, 16, 32, 64 (decimal format), and All Error triggering • All errors • Header CRC error • Frame CRC error • Frame CRC error • FSS (byte start sequence) • SS (byte start sequence) • FES/DTS (frame end or dynamic trailing sequence) • Frame ID (decimal digits in yellow) • Payload-length (decimal number of words in green) • Header CRC (hex digits in blue if valid, or red digits if invalid) • Cycle number (decimal digits in yellow) • Data bytes (HEX digits in white) • Frame CRC (hex digits in blue if valid, or red digits • Total grames • Total frames • Total frames • Total null frames • Total null frames | FlexRay input source | Channel 1, 2, 3, or 4 (using differential probe) |
| Frame triggering • Frame type: startup (SUP), not startup (~SUP), sync (SYNC), not sync (~SYNC), not (NULL), not null (~NULL), normal (NORM), and All • Frame ID: 1 to 2047 (decimal format), and All • Frame ID: 1 to 2047 (decimal format), and All • Base: 0 to 63 (decimal format), and All • Base: 0 to 63 (decimal format), and All • Repetition: 1, 2, 4, 8, 16, 32, 64 (decimal format), and All • Repetition: 1, 2, 4, 8, 16, 32, 64 (decimal format), and All Error triggering • All errors • Header CRC error • Frame CRC error • SS (transmission start sequence) • BSS (byte start sequence) • FES/DTS (frame end or dynamic trailing sequence) • Frame ID (decimal digits in yellow) • Payload-length (decimal number of words in green) • Header CRC (hex digits in blue if valid, or red digits if invalid) • Cycle number (decimal digits in yellow) • Data bytes (HEX digits in white) • Frame CRC (hex digits in blue if valid, or red digits • Total frames Total synchronization frames • Total frames • Total null frames • Total null frames | FlexRay channels | A or B |
| (NULL), not null (~NULL), normal (NORM), and All• Frame ID: 1 to 2047 (decimal format), and All• Cycle - • Base: 0 to 63 (decimal format), and All • Repetition: 1, 2, 4, 8, 16, 32, 64 (decimal format), and AllError triggering• All errors • Header CRC error • Frame CRC errorEvent triggering• Wake-up • TSS (transmission start sequence) • BSS (byte start sequence) • FES/DTS (frame end or dynamic trailing sequence)Frame decoding• Frame trype (NORM, SYNC, SUP, NULL in blue) • Frame ID (decimal digits in yellow) • Payload-length (decimal number of words in green) • Header CRC (hex digits in blue if valid, or red digits if invalid) • Cycle number (decimal digits in yellow) • Data bytes (HEX digits in white) • Frame CRC (hex digits in blue if valid, or red digits • Total frames • Total frames • Total synchronization frames • Total null frames | Baud rates | 2.5 Mbps, 5.0 Mbps, and 10 Mbps |
| Header CRC error Frame CRC error Wake-up TSS (transmission start sequence) BSS (byte start sequence) FES/DTS (frame end or dynamic trailing sequence) Frame decoding Frame type (NORM, SYNC, SUP, NULL in blue) Frame ID (decimal digits in yellow) Payload-length (decimal number of words in green) Header CRC (hex digits in blue if valid, or red digits if invalid) Cycle number (decimal digits in yellow) Data bytes (HEX digits in white) Frame CRC (hex digits in blue if valid, or red digits Totalize function Total frames Total synchronization frames Total null frames Total null frames Total null frames | Frame triggering | Frame ID: 1 to 2047 (decimal format), and All Cycle - Base: 0 to 63 (decimal format), and All |
| TSS (transmission start sequence) BSS (byte start sequence) FES/DTS (frame end or dynamic trailing sequence) Frame decoding Frame type (NORM, SYNC, SUP, NULL in blue) Frame ID (decimal digits in yellow) Payload-length (decimal number of words in green) Header CRC (hex digits in blue if valid, or red digits if invalid) Cycle number (decimal digits in yellow) Data bytes (HEX digits in blue if valid, or red digits Frame CRC (hex digits in blue if valid, or red digits | Error triggering | Header CRC error |
| Frame ID (decimal digits in yellow) Payload-length (decimal number of words in green) Header CRC (hex digits in blue if valid, or red digits if invalid) Cycle number (decimal digits in yellow) Data bytes (HEX digits in white) Frame CRC (hex digits in blue if valid, or red digits | Event triggering | TSS (transmission start sequence) BSS (byte start sequence) |
| • Total synchronization frames • Total null frames Eye-diagram mask testing (requires TP1 standard voltage (10 Mbps only) | Frame decoding | Frame ID (decimal digits in yellow) Payload-length (decimal number of words in green) Header CRC (hex digits in blue if valid, or red digits if invalid) Cycle number (decimal digits in yellow) Data bytes (HEX digits in white) |
| | Totalize function | Total synchronization frames |
| DSOX6MASK mask test option plus TP11 standard voltage (10 Mbps only) | Eye-diagram mask testing (requires DSOX3MASK/DSOX4MASK/ DSOX6MASK mask test option plus downloadable mask files) | TP1 increased voltage (10 Mbps only) TP11 standard voltage (10 Mbps only) TP11 increased voltage (10 Mbps only) |
| Multi-bus analysis FlexRay plus one other serial bus (including another FlexRay bus) | Multi-bus analysis | FlexRay plus one other serial bus (including another FlexRay bus) |

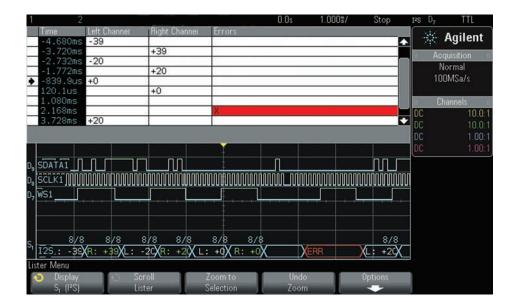


FlexRay physical layer conformance test software Requires FlexRay option (DSOX3FLEX/DSOX4FLEX/DSOX6FLEX) Mask test option (DSOX3MASK/DSOX4MASK/DSOX6MASK) Segmented memory option (DSOX3SGM or standard on 4000 and 6000 X-Series)

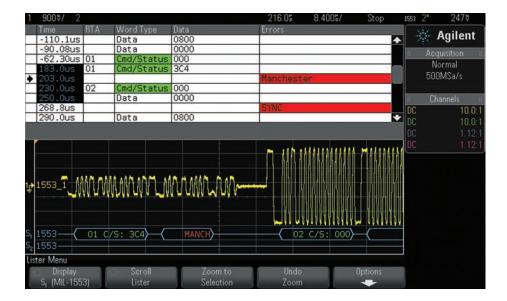
| | Table 1: Receiver input tests |
|---------------------|-------------------------------------------------------------------------|
| Parameter tested | Test description |
| | Eye-diagram mask tests: |
| TP4 – All | Receiver mask test on all frames |
| TP4 – ID | Receiver mask test on specified frame |
| : | Signal integrity voting tests on 13 MHz low-pass filtered Isolated "1": |
| uData1Top | Required maximal level |
| dBitShort | Shortest single bit |
| dBitLengthVariation | Bit asymmetry |
| dEdge01 | Rising edge duration (-300 mV to +300 mV) |
| dEdge10 | Falling edge duration (+300 mV to -300 mV) |
| dEdgeMax | Slowest edge |
| Sq1 | Isolated "1" voted signal quality |
| : | Signal integrity voting tests on 13 MHz low-pass filtered Isolated "0": |
| uData0Top | Required minimal level |
| dBitShort | Shortest single bit |
| dBitLengthVariation | Bit asymmetry |
| dEdge01 | Rising edge duration (-300 mV to +300 mV) |
| dEdge10 | Falling edge duration (+300 mV to -300 mV) |
| dEdgeMax | Slowest edge |
| SqO | Isolated "0" voted signal quality |
| | Advanced diagnostic tests: |
| gdTSSTransmitter | Transmitted TSS width @ receiver |
| МСТ | Mean corrected cycle time |
| uBusRx-Data | Data 1 amplitude |
| -uBusRx-Data | Data 0 amplitude |
| uRx-Idle | Mean idle level |
| dBusRx01 | Rise time Data0 to Data1 (-300 mV to +300 mV) |
| dBusRx10 | Fall time Data1 to Data0 (+300 mV to -300 mV) |

| Table 2: Transmitter output tests | | |
|---------------------------------------|---------------------------------------------------|--|
| Parameter tested | Test description | |
| Eye-diagram mask tests (10 Mbs only): | | |
| TP1 – Std V | Mask test on standard voltage bus driver output | |
| TP1 – Incr V | Mask test on increased voltage bus driver output | |
| TP11 – Std V | Mask test on standard voltage active star output | |
| P11 – Incr V | Mask test on increased voltage active star output | |
| Advanced diagnostic tests: | | |
| gdTSSTransmitter | Transmitted TSS width | |
| uBusTx-Data | Data 1 amplitude | |
| -uBusTx-Data | Data 0 amplitude | |
| uRx-Idle | Mean idle level | |
| dBusTx01 | Rise time Data0 to Data1 (20% to 80%) | |
| dBusTx10 | Fall time Data1 to Data0 (80% to 20%) | |
| | | |

| I ² S specifications/characteristics (DSOX3AUDIO, DSOX4AUDIO, and DSOX6AUDIO) | | |
|------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------|--|
| SCLK, WS, and SDATA input source | Analog channels 1, 2, 3, or 4 | |
| | Digital channels D0 to D15 | |
| Bus configuration: | | |
| Transmitted word size | 4 to 32 bits (user selectable) | |
| Decoded/receiver word size | 4 to 32 bits (user selectable) | |
| Alignment | Standard, left-justified, or right-justified | |
| Word select - low | Left-channel or right-channel | |
| SCLK slope | Rising edge or falling edge | |
| Decoded base | Hex (2's complement) or signed decimal | |
| Baud rates | 2400 b/s to 625 kb/s | |
| Triggering: | | |
| Audio channel | Audio left, audio right, or either | |
| Trigger modes | = (Equal to entered data value) | |
| | ≠ (Not equal to entered data value) | |
| | < (Less than entered data value) | |
| | > (Greater than entered data value) | |
| | >< (Within range of entered data values) | |
| | <> (Out of range of entered data values) | |
| | Increasing value that crosses armed (\leq) and trigger (>=) entered data values | |
| | Decreasing value that crosses armed (\geq =) and trigger (<=) entered data values | |
| Hardware-based decode: | | |
| Left channel | L: "decoded value" in white | |
| Right channel | R: "decoded value" in green | |
| Error | ERR in red (mismatch between transmitted and received word size, or invalid input signaling) | |
| Word size indicator | "# of TX / # of RX" CLKS in blue displayed above each decoded work | |
| Multi-bus analysis | l ² S plus one other serial bus (<u>excluding</u> another l ² S bus) | |



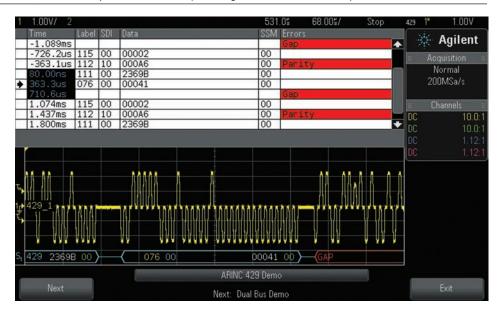
| MIL-STD 1553 specif | ications/characteristics (DSOX3AERO, DSOX4AERO, and DSOX6AERO) |
|----------------------------------------------------------|------------------------------------------------------------------------------|
| MIL-Std 1553 Input Source | Analog channels 1, 2, 3, or 4 (using a differential active probe) |
| Triggering | Data word start |
| | Data word stop |
| | Command/status word start |
| | Command/status word stop |
| | Remote terminal address (hex) |
| | Remote terminal address (hex) + 11 bits (binary) |
| | Parity error |
| | Sync error |
| | Manchester error |
| Color-coded, hardware-accelerated • Base: HEX or binary | |
| decode | Command or status word ("C/S" in green) |
| | Remote terminal address (hex or binary digits in green) |
| | 11 Bits following RTA (hex or binary digits in green) |
| | Data word ("D" in white) |
| | Data word bits (hex or binary digits in white) |
| | Parity error (all decoded text in red) |
| | Synchronization error ("Sync" in red) |
| | Manchester error ("Manch" in red) |
| Eye-diagram mask testing (requires | System xfmr-coupled Input |
| DSOX3MASK mask test option plus | System direct-coupled Input |
| downloadable mask files) | BC xfmr-coupled Input |
| | BC direct-coupled Input |
| | RT xfmr-coupled Input |
| | RT xfmr-coupled Input |
| Multi-bus analysis | MIL-STD 1553 plus one other serial bus, (including another MIL-STD 1553 bus) |



| ARINC 429 specifications/characteristics (DSOX3AERO, DSOX4AERO, and DSOX6AERO) | | |
|--------------------------------------------------------------------------------|-------------------------------------------------------------------|--|
| ARINC 429 input source | Analog channels 1, 2, 3, or 4 (using a differential active probe) | |
| Baud rates | High (100 kbps) | |
| | Low (12.5 kbps) | |
| Triggering | Word start | |
| | Word stop | |
| | Label (octal) | |
| | Label (octal) + bits (binary) | |
| | Label range (octal) | |
| | Parity error | |
| | Word error | |
| | Gap error | |
| | Word or gap error | |
| | All errors | |
| | All bits (useful for eye-diagram testing)) | |
| | All 0 bits | |
| | All 1 bits | |
| Color-coded, hardware-accelerated | Word format: label/SDI/data/SSM or label/data/SSM or label/data | |
| decode | Label (octal digits in yellow) | |
| | SDI (binary digits in blue) | |
| | Data (hex or binary digits in white) | |
| | SSM (binary digits in green) | |
| | Errors (text in red) | |
| Totalize function | Total words | |
| | Total errors | |
| Eye-diagram and pulse mask | 100 kbps eye test | |
| testing (requires DSOX3MASK plus | 100 kbps 1's test | |
| downloadable mask files) | 100 kbps 0's test | |
| | 100 kbps null test | |
| | 12.5 kbps eye test | |
| | 12.5 kbps 1's test | |
| | 12.5 kbps 0's test | |
| | 12.5 kbps null test | |
| Multi hua analysia | ADING 420 plus and other hus /including another ADING 420 hus) | |

Multi-bus analysis

ARINC 429 plus one other bus (including another ARINC 429 bus)



Ordering information

The various serial bus options are compatible on most models of the Agilent InfiniiVision 3000, 4000, and 6000 X-Series oscilloscopes. The entry-level 2000 X-Series oscilloscopes support only the I²C/SPI, RS232/UART, and CAN/LIN options. Existing InfiniiVision X-Series oscilloscopes can also be upgraded with these options.

For most model numbers, the number after DSOX tells you to which series of oscilloscope it applies. For example, DSOX2EMBD applies to the 2000 X-Series and DSOX3EMBD applies to the 3000 X-Series.

| Model number | Description | | |
|-----------------------------------------------|-------------------------------------------------------------------------------------------------------|--|--|
| DS0X2EMBD, DS0X3EMBD, DS0X4EMBD, or DS0X6EMBD | I ² C and SPI trigger and decode | | |
| DSOX2COMP, DSOX3COMP, DSOX4COMP, or DSOX6COMP | RS232/UART trigger and decode | | |
| DSOX2AUTO, DSOX3AUTO, DSOX4AUTO, or DSOX6AUTO | CAN and LIN trigger and decode (CANdbc Symbolic on 4000 and 6000 X-Series models) | | |
| DSOX3FLEX, DSOX4FLEX, or DSOX6FLEX | FlexRay trigger and decode | | |
| DSOX3AERO, DSOX4AERO, or DSOX6AERO | MIL-STD 1553 and ARINC 429 trigger and decode | | |
| DSOX3AUDIO, DSOX4AUDIO, or DSOX6AUDIO | l ² S trigger and decode | | |
| DSOX4USBFL or DSOX6USBFL | USB 2.0 low- and full-speed trigger and decode | | |
| DSOX4USBH or DSOX6USBH | USB 2.0 hi-speed trigger and decode (1 GHz minimum bandwidth models of 4000 or 6000 X-Series only) | | |
| DSOX4USBSQ or DSOX6USBSQ | USB 2.0 signal quality test (hi-speed tests require 1.5 GHz bandwidth models) | | |
| DSOX2SGM and DSOX3SGM | Segmented memory (standard on 4000 and 6000 X-Series models) | | |
| DSOX2MASK, DSOX3MASK, DSOX4MASK, or DSOX6MASK | Mask test option | | |
| N2791A | 25-MHz differential active probe | | |
| N2818A | 200-MHz differential active probe | | |
| N2750A | 1.5 GHz differential active probe (recommended for USB 2.0 hi-speed applications) | | |
| 0960-2926 | DB9 probe head adapter for N2791A and N2818A | | |

Additional options and accessories are available for Agilent's InfiniiVision oscilloscopes. Refer to the first four documents in the list below for ordering information about these additional options and accessories.

Related Agilent literature

| Publication title | Publication type | Publication number |
|--------------------------------------------------------------------------|------------------|--------------------|
| InfiniiVision 2000 X-Series Oscilloscope | Data sheet | 5990-6618EN |
| InfiniiVision 3000 X-Series Oscilloscope | Data sheet | 5990-6619EN |
| InfiniiVision 4000 X-Series Oscilloscope | Data sheet | 5991-1103EN |
| InfiniiVision 6000 X-Series Oscilloscope | Data sheet | 5991-4087EN |
| InfiniiVision Series Oscilloscope Probes and Accessories | Selection guide | 5968-8153EN |
| N2818A/N2819A 200/800 MHz Differential Active Probes | Data sheet | 5990-4753EN |
| N2750A/51A/52A InfiniiMode Differential Active Probes | Data sheet | 5991-0560EN |
| DSOX4USBSQ USB 2.0 Signal Quality Test Option | Data sheet | 5991-1762EN |
| Using Oscilloscope Segmented Memory for Serial Bus Applications | Application note | 5990-5817EN |
| Characterizing Hi-speed USB 2.0 Serial Buses in Embedded Designs | Application note | 5991-1148EN |
| Debug Automotive Designs Faster with CAN-dbc Symbolic Trigger and Decode | Application note | 5991-2847EN |
| CAN Eye-diagram Mask Testing | Application note | 5991-0484EN |
| FlexRay Eye-diagram Mask Testing | Application note | 5990-4923EN |
| MIL-STD 1553 Eye-diagram Mask Testing | Application note | 5990-9324EN |
| ARINC 429 Eye-diagram Mask Testing | Application note | 5990-9325EN |

To download these documents, insert the publication number in the URL: http://cp.literature.agilent.com/litweb/pdf/xxxx-xxxxEN.pdf

Product web site

For the most up-to-date and complete application and product information, please visit our product Web sites at:

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