









CC3200





CC3200 SimpleLink™ Wi-Fi® and Internet-of-Things Solution, a Single-Chip Wireless MCU

1 Device Overview

1.1 Features

- CC3200 SimpleLink Wi-Fi—Consists of Applications Microcontroller, Wi-Fi Network Processor, and Power-Management Subsystems
- Applications Microcontroller Subsystem
 - ARM[®] Cortex[®]-M4 Core at 80 MHz
 - Embedded Memory
 - RAM (Up to 256KB)
 - External Serial Flash Bootloader, and Peripheral Drivers in ROM
 - 32-Channel Direct Memory Access (µDMA)
 - Hardware Crypto Engine for Advanced Fast Security, Including
 - AES, DES, and 3DES
 - SHA2 and MD5
 - CRC and Checksum
 - 8-Bit Parallel Camera Interface
 - 1 Multichannel Audio Serial Port (McASP)
 Interface with Support for Two I2S Channels
 - 1 SD/MMC Interface
 - 2 Universal Asynchronous Receivers and Transmitters (UARTs)
 - 1 Serial Peripheral Interface (SPI)
 - 1 Inter-Integrated Circuit (I²C)
 - 4 General-Purpose Timers with 16-Bit Pulse-Width Modulation (PWM) Mode
 - 1 Watchdog Timer
 - 4-Channel 12-Bit Analog-to-Digital Converters (ADCs)
 - Up to 27 Individually Programmable, Multiplexed GPIO Pins
- Wi-Fi Network Processor Subsystem
 - Featuring Wi-Fi Internet-On-a-Chip™
 - Dedicated ARM MCU
 Completely Offloads Wi-Fi and Internet
 Protocols from the Application Microcontroller
 - Wi-Fi and Internet Protocols in ROM
 - 802.11 b/g/n Radio, Baseband, Medium Access Control (MAC), Wi-Fi Driver, and Supplicant
 - TCP/IP Stack

- Industry-Standard BSD Socket Application Programming Interfaces (APIs)
- 8 Simultaneous TCP or UDP Sockets
- 2 Simultaneous TLS and SSL Sockets
- Powerful Crypto Engine for Fast, Secure Wi-Fi and Internet Connections with 256-Bit AES Encryption for TLS and SSL Connections
- Station, AP, and Wi-Fi Direct[®] Modes
- WPA2 Personal and Enterprise Security
- SimpleLink Connection Manager for Autonomous and Fast Wi-Fi Connections
- SmartConfig[™] Technology, AP Mode, and WPS2 for Easy and Flexible Wi-Fi Provisioning
- TX Power
 - 18.0 dBm @ 1 DSSS
 - 14.5 dBm @ 54 OFDM
- RX Sensitivity
 - –95.7 dBm @ 1 DSSS
 - –74.0 dBm @ 54 OFDM
- Power-Management Subsystem
 - Integrated DC-DC Supports a Wide Range of Supply Voltage:
 - V_{BAT} Wide-Voltage Mode: 2.1 to 3.6 V
 - Preregulated 1.85-V Mode
 - Advanced Low-Power Modes
 - Hibernate: 4 µA
 - Low-Power Deep Sleep (LPDS): 120 μA
 - RX Traffic (MCU Active): 59 mA @ 54 OFDM
 - TX Traffic (MCU Active): 229 mA @ 54 OFDM, Maximum Power
 - Idle Connected (MCU in LPDS): 695 μA @ DTIM = 1
- Clock Source
 - 40.0-MHz Crystal with Internal Oscillator
 - 32.768-kHz Crystal or External RTC Clock
- Package and Operating Temperature
 - 0.5-mm Pitch, 64-Pin, 9-mm × 9-mm QFN
 - Ambient Temperature Range: –40°C to 85°C



1.2 Applications

- For Internet-of-Things applications, such as:
 - Cloud Connectivity
 - Home Automation
 - Home Appliances
 - Access Control
 - Security Systems
 - Smart Energy

- Internet Gateway
- Industrial Control
- Smart Plug and Metering
- Wireless Audio
- IP Network Sensor Nodes

1.3 Description

Start your design with the industry's first single-chip microcontroller unit (MCU) with built-in Wi-Fi connectivity. Created for the Internet of Things (IoT), the SimpleLink CC3200 device is a wireless MCU that integrates a high-performance ARM Cortex-M4 MCU, allowing customers to develop an entire application with a single IC. With on-chip Wi-Fi, Internet, and robust security protocols, no prior Wi-Fi experience is required for faster development. The CC3200 device is a complete platform solution including software, sample applications, tools, user and programming guides, reference designs, and the TI E2ETM support community. The device is available in a QFN package that is easy to layout.

The applications MCU subsystem contains an industry-standard ARM Cortex-M4 core running at 80 MHz. The device includes a wide variety of peripherals, including a fast parallel camera interface, I2S, SD/MMC, UART, SPI, I²C, and four-channel ADC. The CC3200 family includes flexible embedded RAM for code and data and ROM with external serial flash bootloader and peripheral drivers.

The Wi-Fi network processor subsystem features a Wi-Fi Internet-on-a-Chip and contains an additional dedicated ARM MCU that completely offloads the applications MCU. This subsystem includes an 802.11 b/g/n radio, baseband, and MAC with a powerful crypto engine for fast, secure Internet connections with 256-bit encryption. The CC3200 device supports Station, Access Point, and Wi-Fi Direct modes. The device also supports WPA2 personal and enterprise security and WPS 2.0. The Wi-Fi Internet-on-a-chip includes embedded TCP/IP and TLS/SSL stacks, HTTP server, and multiple Internet protocols.

The power-management subsystem includes integrated DC-DC converters supporting a wide range of supply voltages. This subsystem enables low-power consumption modes, such as the hibernate with RTC mode requiring less than $4 \mu A$ of current.

Device Information (1)

PART NUMBER	PACKAGE	BODY SIZE
CC3200	QFN (64)	9.0 mm x 9.0 mm

(1) For all available packages, see the orderable addendum at the end of the datasheet.



1.4 Functional Block Diagram

Figure 1-1 shows the CC3200 hardware overview.

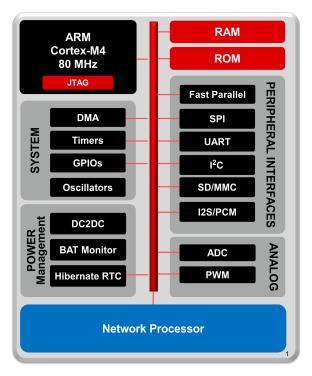


Figure 1-1. CC3200 Hardware Overview

Figure 1-2 shows an overview of the CC3200 embedded software.

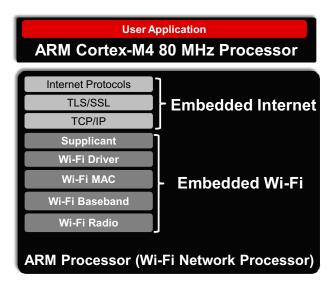


Figure 1-2. CC3200 Embedded Software Overview

Figure 1-3 shows a block diagram of the CC3200 device.

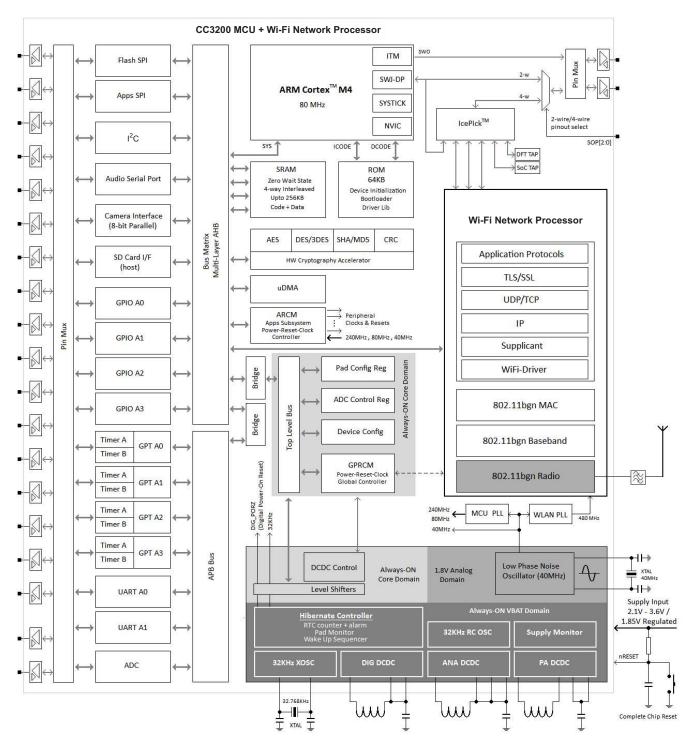


Figure 1-3. CC3200 Functional Block Diagram



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2 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

3 Terminal Configuration and Functions

Figure 3-1 shows pin assignments for the 64-pin QFN package.

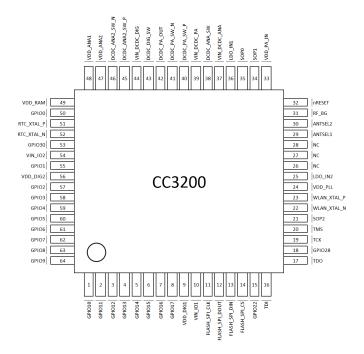
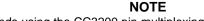


Figure 3-1. QFN 64-Pin Assignments

3.1 Pin Attributes and Pin Multiplexing

The device makes extensive use of pin multiplexing to accommodate the large number of peripheral functions in the smallest possible package. To achieve this configuration, pin multiplexing is controlled using a combination of hardware configuration (at device reset) and register control.



TI highly recommends using the CC3200 pin multiplexing utility to obtain the desired pinout.

The board and software designers are responsible for the proper pin multiplexing configuration. Hardware does not ensure that the proper pin multiplexing options are selected for the peripherals or interface mode used.

Table 3-1 describes the general pin attributes and presents an overview of pin multiplexing. All pin multiplexing options are configurable using the pin mux registers.

The following special considerations apply:

- All I/Os support drive strengths of 2, 4, and 6 mA. Drive strength is configurable individually for each pin.
- All I/Os support 10-μA pullups and pulldowns.
- These pulls are not active and all of the I/Os remain floating while the device is in Hibernate state.
- The VIO and V_{BAT} supply must be tied together at all times.
- All digital I/Os are nonfail-safe.



NOTE

If an external device drives a positive voltage to the signal pads and the CC3200 device is not powered, DC current is drawn from the other device. If the drive strength of the external device is adequate, an unintentional wakeup and boot of the CC3200 device can occur. To prevent current draw, TI recommends any one of the following:

- All devices interfaced to the CC3200 device must be powered from the same power rail as the chip.
- Use level-shifters between the device and any external devices fed from other independent rails.
- The nRESET pin of the CC3200 device must be held low until the VBAT supply to the
 device is driven and stable.

Table 3-1. Pin Multiplexing

	Ger	neral Pin	Attributes					Function				Pad Sta	tes
Pkg Pin	Pin Alias	Use	Select as Wakeup Source	Config Addl Analog Mux	Muxed with JTAG	Dig. Pin Mux Config Reg	Dig. Pin Mux Config Mode Value	Signal Name	Signal Description	Signal Direction	LPDS ⁽¹⁾	Hib ⁽²⁾	nRESET = 0
							0	GPIO10	General-Purpose I/O	I/O	Hi-Z		
						CDIO DAD CONEIC	1	I2C_SCL	I2C Clock	O (Open Drain)	Hi-Z		
1	GPIO10	I/O	No	No	No	GPIO_PAD_CONFIG_ 10 (0x4402 E0C8)	3	GT_PWM06	Pulse-Width Modulated O/P	0	Hi-Z	Hi-Z	Hi-Z
						,	7	UART1_TX	UART TX Data	0	1	·	
							6	SDCARD_CLK	SD Card Clock	0	0		
							12	GT_CCP01	Timer Capture Port	I	Hi-Z		
							0	GPIO11	General-Purpose I/O	I/O	Hi-Z		
							1	I2C_SDA	I2C Data	I/O (Open Drain)	Hi-Z		
							3	GT_PWM07	Pulse-Width Modulated O/P	0	Hi-Z		
2	GPIO11	I/O	Yes	No	No	GPIO_PAD_CONFIG_ 11	4	pXCLK (XVCLK)	Free Clock To Parallel Camera	0	0	Hi-Z	Hi-Z
						(0x4402 E0CC)	6	SDCARD_CM D	SD Card Command Line	I/O	Hi-Z		
							7	UART1_RX	UART RX Data	I	Hi-Z	•	
							12	GT_CCP02	Timer Capture Port	I	Hi-Z		
							13	McAFSX	I2S Audio Port Frame Sync	0	Hi-Z		



	Ger	neral Pin	Attributes					Function				Pad Sta	tes
Pkg Pin	Pin Alias	Use	Select as Wakeup Source	Config Addl Analog Mux	Muxed with JTAG	Dig. Pin Mux Config Reg	Dig. Pin Mux Config Mode Value	Signal Name	Signal Description	Signal Direction	LPDS ⁽¹⁾	Hib ⁽²⁾	nRESET = 0
							0	GPIO12	General Purpose I/O	I/O	Hi-Z		
							3	McACLK	I2S Audio Port Clock O	0	Hi-Z		
3	GPIO12	I/O	No	No	No	GPIO_PAD_CONFIG_	4	pVS (VSYNC)	Parallel Camera Vertical Sync	I	Hi-Z	Hi-Z	Hi-Z
3	GPIO12	1/0	NO	NO	INO	12 (0x4402 E0D0)	5	I2C_SCL	I2C Clock	I/O (Open Drain)	Hi-Z	ni-Z	⊓I-∠
							7	UART0_TX	UART0 TX Data	0	1		
							12	GT_CCP03	Timer Capture Port	I	Hi-Z		
							0	GPIO13	General-Purpose I/O	I/O			
						GPIO_PAD_CONFIG_	5	I2C_SDA	I2C Data	I/O (Open Drain)			
4	GPIO13	I/O	Yes	No	No	13 (0x4402 E0D4)	4	pHS (HSYNC)	Parallel Camera Horizontal Sync	1	Hi-Z	Hi-Z	Hi-Z
							7	UART0_RX	UART0 RX Data	I			
							12	GT_CCP04	Timer Capture Port	I			
							0	GPIO14	General-Purpose I/O	I/O			
						GPIO_PAD_CONFIG_	5	I2C_SCL	I2C Clock	I/O (Open Drain)			
5	GPIO14	I/O		No	No	14 (0x4402 E0D8)	7	GSPI_CLK	General SPI Clock	I/O	Hi-Z	Hi-Z	Hi-Z
							4	pDATA8 (CAM_D4)	Parallel Camera Data Bit 4	I			
							12	GT_CCP05	Timer Capture Port	I			

	Gen	eral Pin	Attributes					Function				Pad Sta	tes
Pkg Pin	Pin Alias	Use	Select as Wakeup Source	Config Addl Analog Mux	Muxed with JTAG	Dig. Pin Mux Config Reg	Dig. Pin Mux Config Mode Value	Signal Name	Signal Description	Signal Direction	LPDS ⁽¹⁾	Hib ⁽²⁾	nRESET = 0
							0	GPIO15	General-Purpose I/O	I/O			
						GPIO_PAD_CONFIG_	5	I2C_SDA	I2C Data	I/O (Open Drain)			
6	GPIO15	I/O		No	No	15 (0x4402 E0DC)	7	GSPI_MISO	General SPI MISO	I/O	Hi-Z	Hi-Z	Hi-Z
							4	pDATA9 (CAM_D5)	Parallel Camera Data Bit 5	I			
							13	GT_CCP06	Timer Capture Port	I			
											Hi-Z		
							0	GPIO16	General-Purpose I/O	I/O	Hi-Z		
											Hi-Z		
7	GPIO16	I/O		No	No	GPIO_PAD_CONFIG_ 16	7	GSPI_MOSI	General SPI MOSI	I/O	Hi-Z	Hi-Z	Hi-Z
,	0.1010	.,, C		110		(0x4402 E0E0)	4	pDATA10 (CAM_D6)	Parallel Camera Data Bit 6	ı	Hi-Z		
							5	UART1_TX	UART1 TX Data	0	1		
							13	GT_CCP07	Timer Capture Port	1	Hi-Z		
							0	GPIO17	General-Purpose I/O	I/O			
			Wake-Up			GPIO_PAD_CONFIG_	5	UART1_RX	UART1 RX Data	I			
8	GPIO17	I/O	Source	No	No	17 (0x4402 E0E4)	7	GSPI_CS	General SPI Chip Select	I/O	Hi-Z	Hi-Z	Hi-Z
							4	pDATA11 (CAM_D7)	Parallel Camera Data Bit 7	I			
9	VDD_DIG1	Int pwr	N/A	N/A	N/A	N/A	N/A	VDD_DIG1	Internal Digital Core Voltage				
10	VIN_IO1	Sup. input	N/A	N/A	N/A	N/A	N/A	VIN_IO1	Chip Supply Voltage (VBAT)				
11	FLASH_SPI_ CLK	0	N/A	N/A	N/A	N/A	N/A	FLASH_SPI_ CLK	Clock To SPI Serial Flash (Fixed Default)	0	Hi-Z ⁽³⁾	Hi-Z	Hi-Z



	Ger	eral Pin	Attributes					Function				Pad Stat	tes
Pkg Pin	Pin Alias	Use	Select as Wakeup Source	Config Addl Analog Mux	Muxed with JTAG	Dig. Pin Mux Config Reg	Dig. Pin Mux Config Mode Value	Signal Name	Signal Description	Signal Direction	LPDS ⁽¹⁾	Hib ⁽²⁾	nRESET = 0
12	FLASH_SPI_ DOUT	0	N/A	N/A	N/A	N/A	N/A	FLASH_SPI_ DOUT	Data To SPI Serial Flash (Fixed Default)	0	Hi-Z ⁽³⁾	Hi-Z	Hi-Z
13	FLASH_SPI_ DIN	I	N/A	N/A	N/A	N/A	N/A	FLASH_SPI_ DIN	Data From SPI Serial Flash (Fixed Default)	I			
14	FLASH_SPI_ CS	0	N/A	N/A	N/A	N/A	N/A	FLASH_SPI_ CS	Chip Select To SPI Serial Flash (Fixed Default)	0	1	Hi-Z	Hi-Z
							0	GPIO22	General-Purpose I/O	I/O	Hi-Z		
15	GPIO22	I/O	No	No	No	GPIO_PAD_CONFIG_ 22 (0x4402 E0F8)	7	McAFSX	I2S Audio Port Frame Sync	0	Hi-Z	Hi-Z	Hi-Z
						(0.1.102 201 0)	5	GT_CCP04	Timer Capture Port	I			
							1	TDI	JTAG TDI. Reset Default Pinout.	ı	Hi-Z		
16	TDI	I/O	No	No	MUXed with	GPIO_PAD_CONFIG_	0	GPIO23	General-Purpose I/O	I/O	HI-Z	Hi-Z	Hi-Z
10	וטו	1/0	INO	NO	JTAG TDI	23 (0x4402 E0FC)	2	UART1_TX	UART1 TX Data	0	1	ПІ-Д	⊓I-Z
					וטו	,	9	I2C_SCL	I2C Clock	I/O (Open Drain)	Hi-Z		

	Ger	eral Pin	Attributes					Function				Pad Sta	tes
Pkg Pin	Pin Alias	Use	Select as Wakeup Source	Config Addl Analog Mux	Muxed with JTAG	Dig. Pin Mux Config Reg	Dig. Pin Mux Config Mode Value	Signal Name	Signal Description	Signal Direction	LPDS ⁽¹⁾	Hib ⁽²⁾	nRESET = 0
							1	TDO	JTAG TDO. Reset Default Pinout.	0			
							0	GPIO24	General-Purpose I/O	I/O			
					MUXed	GPIO_PAD_CONFIG_	5	PWM0	Pulse Width Modulated O/P	0			
17	TDO	I/O	Wake-Up Source	No	with JTAG	24	2	UART1_RX	UART1 RX Data	I	Hi-Z	Hi-Z	Hi-Z
			Course		TDO	(0x4402 E100)	9	I2C_SDA	I2C Data	I/O (Open Drain)			
							4	GT_CCP06	Timer Capture Port	I			
							6	McAFSX	I2S Audio Port Frame Sync	0			
18	GPIO28	I/O		No		GPIO_PAD_CONFIG_ 28 (0x4402 E110)	0	GPIO28	General-Purpose I/O	I/O	Hi-Z	Hi-Z	Hi-Z
19	TCK	I/O	No	No	MUXed with JTAG/S		1	TCK	JTAG/SWD TCK Reset Default Pinout	I	Hi-Z	Hi-Z	Hi-Z
					WD- TCK		8	GT_PWM03	Pulse Width Modulated O/P	0			
20	TMS	I/O	No	No	MUXed with JTAG/S	GPIO_PAD_CONFIG_ 29	1	TMS	JATG/SWD TMS Reset Default Pinout	I/O	Hi-Z	Hi-Z	Hi-Z
					WD- TMSC	(0x4402 E114)	0	GPIO29	General-Purpose I/O				



	Ger	eral Pin	Attributes					Function				Pad Sta	tes
Pkg Pin	Pin Alias	Use	Select as Wakeup Source	Config Addl Analog Mux	Muxed with JTAG	Dig. Pin Mux Config Reg	Dig. Pin Mux Config Mode Value	Signal Name	Signal Description	Signal Direction	LPDS ⁽¹⁾	Hib ⁽²⁾	nRESET = 0
							0	GPIO25	General-Purpose I/O	0	Hi-Z		
							9	GT_PWM02	Pulse Width Modulated O/P	0	Hi-Z		
21 ⁽⁴⁾⁽⁵⁾	SOP2	O Only	No	No	No	GPIO_PAD_CONFIG_ 25	2	McAFSX	I2S Audio Port Frame Sync	0	Hi-Z	Hi-Z	Hi-Z
						(0x4402 E104)	See (6)	TCXO_EN	Enable to Optional External 40-MHz TCXO	0	0		
							See (7)	SOP2	Sense-On-Power 2	I			
22	WLAN_XTAL _N	WLAN Ana.	N/A	N/A	N/A	N/A	See (6)	WLAN_XTAL_ N	40-MHz XTAL Pulldown if ext TCXO is used.				
23	WLAN_XTAL _P	WLAN Ana.	N/A	N/A	N/A	N/A		WLAN_XTAL_ P	40-MHz XTAL or TCXO clock input				
24	VDD_PLL	Int. Pwr	N/A	N/A	N/A	N/A		VDD_PLL	Internal analog voltage				
25	LDO_IN2	Int. Pwr	N/A	N/A	N/A	N/A		LDO_IN2	Analog RF supply from ANA DC-DC output				
26	NC	WLAN Ana.	N/A	N/A	N/A	N/A		NC	Reserved				
27	NC	WLAN Ana.	N/A	N/A	N/A	N/A		NC	Reserved				
28	NC	WLAN Ana.	N/A	N/A	N/A	N/A		NC	Reserved				
29 ⁽⁸⁾	ANTSEL1	O Only	No	User config not required	No	GPIO_PAD_CONFIG_ 26 (0x4402 E108)	0	ANTSEL1 ⁽³⁾	Antenna Selection Control	0	Hi-Z	Hi-Z	Hi-Z
30 ⁽⁸⁾	ANTSEL2	O Only	No	User config not required	No	GPIO_PAD_CONFIG_ 27 (0x4402 E10C)	0	ANTSEL2 ⁽³⁾	Antenna Selection Control	0	Hi-Z	Hi-Z	Hi-Z
31	RF_BG	WLAN Ana.	N/A	N/A	N/A	N/A		RF_BG	RF BG band				

	Ger	eral Pin	Attributes					Function				Pad Stat	tes
Pkg Pin	Pin Alias	Use	Select as Wakeup Source	Config Addl Analog Mux	Muxed with JTAG	Dig. Pin Mux Config Reg	Dig. Pin Mux Config Mode Value	Signal Name	Signal Description	Signal Direction	LPDS ⁽¹⁾	Hib ⁽²⁾	nRESET = 0
32	nRESET	Glob. Rst	N/A	N/A	N/A	N/A		nRESET	Master chip reset. Active low.				
33	VDD_PA_IN	Int. Pwr	N/A	N/A	N/A	N/A		VDD_PA_IN	PA supply voltage from PA DC-DC output.				
34 ⁽⁵⁾	SOP1	Config Sense	N/A	N/A	N/A	N/A		SOP1	Sense On Power 1				
35 ⁽⁵⁾	SOP0	Config Sense	N/A	N/A	N/A	N/A		SOP0	Sense On Power 0				
36	LDO_IN1	Internal Power	N/A	N/A	N/A	N/A		LDO_IN1	Analog RF supply from ana DC-DC output				
37	VIN_DCDC_ ANA	Supply Input	N/A	N/A	N/A	N/A		VIN_DCDC_A NA	Analog DC-DC input (connected to chip input supply [VBAT])				
38	DCDC_ANA_ SW	Internal Power	N/A	N/A	N/A	N/A		DCDC_ANA_S W	Analog DC-DC switching node.				
39	VIN_DCDC_ PA	Supply Input	N/A	N/A	N/A	N/A		VIN_DCDC_PA	PA DC-DC input (connected to chip input supply [VBAT])				
40	DCDC_PA_S W_P	Internal Power	N/A	N/A	N/A	N/A		DCDC_PA_SW _P	PA DCDC switching node				
41	DCDC_PA_S W_N	Internal Power	N/A	N/A	N/A	N/A		DCDC_PA_SW _N	PA DCDC switching node				
42	DCDC_PA_O UT	Internal Power	N/A	N/A	N/A	N/A		DCDC_PA_OU T	PA buck converter output				
43	DCDC_DIG_ SW	Internal Power	N/A	N/A	N/A	N/A		DCDC_DIG_S W	DIG DC-DC switching node				
44	VIN_DCDC_ DIG	Supply Input	N/A	N/A	N/A	N/A		VIN_DCDC_DI G	DIG DC-DC input (connected to chip input supply [VBAT])				



	Gen	eral Pin	Attributes					Function				Pad Stat	tes
Pkg Pin	Pin Alias	Use	Select as Wakeup Source	Config Addl Analog Mux	Muxed with JTAG	Dig. Pin Mux Config Reg	Dig. Pin Mux Config Mode Value	Signal Name	Signal Description	Signal Direction	LPDS ⁽¹⁾	Hib ⁽²⁾	nRESET = 0
							0	GPIO31	General-Purpose I/O	I/O			
							9	UART0_RX	UART0 RX Data	I			
							12	McAFSX	I2S Audio Port Frame Sync	0	Hi-Z	Hi-Z	Hi-Z
(40)	DCDC ANA2			User config not		GPIO_PAD_CONFIG_	2	UART1_RX	UART1 RX Data	I	HI-Z	HI-Z	HI-Z
45 ⁽¹⁰⁾	_SW_P	I/O	No	required (9)(11)	No	31 (0x4402 E11C)	6	McAXR0	I2S Audio Port Data 0 (RX/TX)	I/O			
							7	GSPI_CLK	General SPI Clock	I/O			
							See (6)	DCDC_ANA2_ SW_P	ANA2 DCDC Converter +ve Switching Node.				
46	DCDC_ANA2 _SW_N	Internal Power	N/A	N/A	N/A	N/A	N/A	DCDC_ANA2_ SW_N	ANA2 DCDC Converter -ve Switching Node.				
47	VDD_ANA2	Internal Power	N/A	N/A	N/A	N/A	N/A	VDD_ANA2	ANA2 DCDC O				
48	VDD_ANA1	Internal Power	N/A	N/A	N/A	N/A	N/A	VDD_ANA1	Analog supply fed by ANA2 DCDC output				
49	VDD_RAM	Internal Power	N/A	N/A	N/A	N/A	N/A	VDD_RAM	SRAM LDO output				

	Gen	eral Pin	Attributes					Function				Pad Stat	tes
Pkg Pin	Pin Alias	Use	Select as Wakeup Source	Config Addl Analog Mux	Muxed with JTAG	Dig. Pin Mux Config Reg	Dig. Pin Mux Config Mode Value	Signal Name	Signal Description	Signal Direction	LPDS ⁽¹⁾	Hib ⁽²⁾	nRESET = 0
							0	GPIO0	General-Purpose I/O	I/O	Hi-Z	Hi-Z	Hi-Z
							12	UART0_CTS	UART0 Clear To Send Input (Active Low)	I	Hi-Z	Hi-Z	Hi-Z
							6	McAXR1	I2S Audio Port Data 1 (RX/TX)	I/O	Hi-Z		
				User		GPIO_PAD_CONFIG_	7	GT_CCP00	Timer Capture Port	I	Hi-Z		
50	GPIO0	I/O	No	config not required	No	0 (0x4402 E0A0)	9	GSPI_CS	General SPI Chip Select	I/O	Hi-Z		
							10	UART1_RTS	UART1 Request To Send O (Active Low)	0	1		
							3	UART0_RTS	UART0 Request To Send O (Active Low)	0	1		
							4	McAXR0	I2S Audio Port Data 0 (RX/TX)	I/O	Hi-Z		
51	RTC_XTAL_ P	RTC Clock	N/A	N/A	N/A	N/A		RTC_XTAL_P	Connect 32.768- kHz XTAL or Froce external CMOS level clock				



	Ger	eral Pin	Attributes					Function				Pad Sta	tes
Pkg Pin	Pin Alias	Use	Select as Wakeup Source	Config Addl Analog Mux	Muxed with JTAG	Dig. Pin Mux Config Reg	Dig. Pin Mux Config Mode Value	Signal Name	Signal Description	Signal Direction	LPDS ⁽¹⁾	Hib ⁽²⁾	nRESET = 0
								RTC_XTAL_N	Connect 32.768- kHz XTAL or connect a 100 k Ω to V _{supply} .				
							0	GPIO32	General-Purpose I/O	I/O	Hi-Z		
	570 V74			User		GPIO_PAD_CONFIG_	2	McACLK	I2S Audio Port Clock O	0	Hi-Z		
52 ⁽¹⁰⁾	RTC_XTAL_ N	O Only		config not required (9)(12)	No	32 (0x4402 E120)	4	McAXR0	I2S Audio Port Data (Only O Mode Supported On Pin 52)	0	Hi-Z	Hi-Z	Hi-Z
							6	UART0_RTS	UARTO Request To Send O (Active Low)	0	1		
							8	GSPI_MOSI	General SPI MOSI	I/O	Hi-Z		
							0	GPIO30	General-Purpose I/O	I/O	Hi-Z	Hi-Z	Hi-Z
							9	UART0_TX	UART0 TX Data	0	1		
				User		GPIO_PAD_CONFIG_	2	McACLK	I2S Audio Port Clock O	0	Hi-Z		
53	GPIO30	I/O	No	config not required	No	30 (0x4402 E118)	3	McAFSX	I2S Audio Port Frame Sync	0	Hi-Z		
							4	GT_CCP05	Timer Capture Port	I	Hi-Z		
							7	GSPI_MISO	General SPI MISO	I/O	Hi-Z		
54	VIN_IO2	Supply Input	N/A	N/A	N/A	N/A		VIN_IO2	Chip Supply Voltage (VBAT)				

	Ger	neral Pin	Attributes					Function			Pad States			
Pkg Pin	Pin Alias	Use	Select as Wakeup Source	Config Addl Analog Mux	Muxed with JTAG	Dig. Pin Mux Config Reg	Dig. Pin Mux Config Mode Value	Signal Name	Signal Description	Signal Direction	LPDS ⁽¹⁾	Hib ⁽²⁾	nRESET = 0	
							0	GPIO1	General-Purpose I/O	I/O	Hi-Z	Hi-Z	Hi-Z	
							3	UART0_TX	UART0 TX Data	0	1			
55	GPIO1	I/O	No	No	No	GPIO_PAD_CONFIG_ 1 (0x4402 E0A4)	4	pCLK (PIXCLK)	Pixel Clock From Parallel Camera Sensor	I	Hi-Z			
					6 UART1_TX	UART1_TX	UART1 TX Data	0	1					
							7	GT_CCP01	Timer Capture Port	I	Hi-Z			
56	VDD_DIG2	Internal Power	N/A	N/A	N/A	N/A		VDD_DIG2	Internal Digital Core Voltage					
							See (6)	ADC_CH0	ADC Channel 0 Input (1.5V max)	I				
(40)		Analog Input (up to	Wake-Up	See		GPIO_PAD_CONFIG_	0	GPIO2	General-Purpose I/O	I/O	Hi-Z		11: 7	
57 ⁽¹³⁾	GPIO2	1.5 V)/	Source	See (10)(14)	No	2 (0x4402 E0A8)	3	UART0_RX	UART0 RX Data	I	Hi-Z	Hi-Z	Hi-Z	
		Digital I/O				(0,4402 2040)	6	UART1_RX	UART1 RXt Data	I	Hi-Z			
		"."					7	GT_CCP02	Timer Capture Port	I	Hi-Z		Hi-Z Hi-Z	
		Analog					See (6)	ADC_CH1	ADC Channel 1 Input (1.5V max)	I				
58 ⁽¹³⁾	GPIO3	Input (up to	No	See (10)(14)	No	GPIO_PAD_CONFIG_ 3	0	GPIO3	General-Purpose I/O	I/O	Hi-Z	Hi-Z	Hi-Z	
		1.5V)/D igital		(10)(14)		(0x4402 E0AC)	6	UART1_TX	UART1 TX Data	0	1			
		Ĭ/O.					4	pDATA7 (CAM_D3)	Parallel Camera Data Bit 3	I	Hi-Z			
		Analog					See (6)	ADC_CH2	ADC Channel 2 Input (1.5V max)	I				
59 ⁽¹³⁾	GPIO4	Input (up to	Wake-up	See	No	GPIO_PAD_CONFIG_	0	GPIO4	General-Purpose I/O		Hi-Z	Hi-Z		
	0.101	1.5V)/D Source (10)(14) 100 (0x4402 E0B0) 6 UART1_RX UART1_RX Data I Hi	Hi-Z	† · · · <u>-</u>										
			igital	234100				4			I	Hi-Z		



Table 3-1. Pin Multiplexing (continued)

	Ger	neral Pin	Attributes					Function			Pad States		
Pkg Pin	Pin Alias	Use	Select as Wakeup Source	Config Addl Analog Mux	Muxed with JTAG	Dig. Pin Mux Config Reg	Dig. Pin Mux Config Mode Value	Signal Name	Signal Description	Signal Direction	LPDS ⁽¹⁾	Hib ⁽²⁾	nRESET = 0
							See (6)	ADC_CH3	ADC Channel 3 Input (1.5V max)	I			
		Analog Input					0	GPIO5	General-Purpose I/O	I/O	Hi-Z		
60 ⁽¹³⁾	GPIO5	(up to 1.5V)/D	No	See (10)(14)	No	GPIO_PAD_CONFIG_ 5 (0x4402 E0B4)	4	pDATA5 (CAM_D1)	Parallel Camera Data Bit 1	I	Hi-Z	Hi-Z	Z Hi-Z
		igital I/O.				(0,4402 2004)	6	McAXR1	I2S Audio Port Data 1 (RX/TX)	I/O	Hi-Z		
							7	GT_CCP05	Timer Capture Port	I	Hi-Z		
							0	GPIO6	General-Purpose I/O	I/O	Hi-Z		
							5	UARTO_RTS	UARTO Request To Send O (Active Low)	0	1		
						GPIO_PAD_CONFIG_	4	pDATA4 (CAM_D0)	Parallel Camera Data Bit 0	I	Hi-Z		
61	GPIO6	No	No	No	No	6 (0x4402 E0B8)	3	UART1_CTS	UART1 Clear To Send Input (Active Low)	I	Hi-Z	Hi-Z	
							6	UARTO_CTS	UART0 Clear To Send Input (Active Low)	I	Hi-Z		
							7	GT_CCP06	Timer Capture Port	I	Hi-Z		
							0	GPIO7	General-Purpose I/O	I/O	Hi-Z		
							13	McACLKX	I2S Audio Port Clock O	0	Hi-Z		
62	GPIO7	I/O	No	No	No	GPIO_PAD_CONFIG_ 7 (0x4402 E0BC)	3	UART1_RTS	UART1 Request To Send O (Active Low)	0	1	Hi-Z	Hi-Z
						10 UARTO_RTS UARTO Request O 1 To Send O (Active Low)	st O 1	O 1	1				
							11	UART0_TX	UART0 TX Data	0	1		

	Ger	eral Pin	Attributes					Function			Pad States			
Pkg Pin	Pin Alias	Use	Select as Wakeup Source	Config Addl Analog Mux	Muxed with JTAG	Dig. Pin Mux Config Reg	Dig. Pin Mux Config Mode Value	Signal Name	Signal Description	Signal Direction	LPDS ⁽¹⁾	Hib ⁽²⁾	nRESET = 0	
							0	GPIO8	General-Purpose I/O	I/O				
63	GPIO8	I/O	No	No	No	GPIO_PAD_CONFIG_ 8 (0x4402 E0C0)	6	SDCARD_IRQ	Interrupt from SD Card (Future support)	I	Hi-Z	Hi-Z	Hi-Z	
						(0x4402 E0C0)	7	McAFSX	I2S Audio Port Frame Sync	0			Hi-Z	
							12	GT_CCP06	Timer Capture Port	I				
							0	GPIO9	General-Purpose I/O	I/O				
						GPIO_PAD_CONFIG_ 9	9	3	GT_PWM05	Pulse Width Modulated O/P	0			
64	GPIO9	I/O	No	No	No			9 (0x4402 E0C4)	6	SDCARD_DAT A	SD Cad Data	I/O	Hi-Z	Hi-Z
						(0,4402 2004)	7	McAXR0	I2S Audio Port Data (Rx/Tx)	I/O				
				12	GT_CCP00	Timer Capture Port	I							
65	GND_TAB								Thermal pad and electrical ground					

- (1) LPDS mode: The state of unused GPIOs in LPDS is input with 500 kΩ pulldown. For all used GPIOs , the user can enable internal pulls, which would hold them in a valid state.
- (2) Hibernate mode: The CC3200 device leaves the digital pins in a Hi-Z state without any internal pulls when the device enters hibernate state. This can cause glitches on output lines unless held at valid levels by external resistors.
- (3) To minimize leakage in some serial flash vendors during LPDS, TI recommends the user application always enable internal weak pulldowns on FLASH_SPI_DATA and FLASH_SPI_CLK pins.
- (4) This pin has dual functions: as a SOP[2] (device operation mode), and as an external TCXO enable. As a TXCO enable, the pin is an output on power up and driven logic high. During hibernate low-power mode, the pin is in a high impedance state but pulled down for SOP mode to disable TCXO. Because of SOP functionality, the pin must be used as output only.
- (5) Higher leakage current from the onboard serial flash can occur due to floating inputs when the device enters Hibernate mode. See reference schematics for recommended pull-up and pull-down resistors.
- (6) For details on proper use, see Section 3.2, Drive Strength and Reset States for Analog-Digital Multiplexed Pins.
- (7) This pin is one of three that must have a passive pullup or pulldown resistor on board to configure the chip hardware power-up mode. Because of this reason, if this pin is used for digital functions, it must be output only.
- (8) This pin is reserved for WLAN antenna selection, controlling an external RF switch that multiplexes the RF pin of the CC3200 device between two antennas. These pins should not be used for other functionalities in general.

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(9) Device firmware automatically enables the digital path during ROM boot.

- (10) Pin 45 is used by an internal DC-DC (ANA2_DCDC) and pin 52 is used by the RTC XTAL oscillator. These modules use automatic configuration sensing. Therefore, some board-level configuration is required to use pin 45 and pin 52 as digital pads (see Figure 3-2). Because the CC3200R device does not require ANA2_DCDC, the pin can always be used for digital functions. However, pin 47 must be shorted to the supply input. Typically, pin 52 is used for RTC XTAL in most applications. However, in some applications a 32.768-kHz square-wave clock might always be available onboard. In such cases, the XTAL can be removed to free up pin 52 for digital functions. The external clock must then be applied at pin 51. For the chip to automatically detect this configuration, a 100K pull-up resistor must be connected between pin 52 and the supply line. To prevent false detection, TI recommends using pin 52 for output-only functions.
- (11) VDD_FLASH must be shorted to V_{supply}.
- (12) To use the digital functions, RTC_XTAL_N must be pulled high to V_{supply} using 100-K Ω resistor.
- (13) This pin is shared by the ADC inputs and digital I/O pad cells. Important: The ADC inputs are tolerant up to 1.8 V. On the other hand, the digital pads can tolerate up to 3.6 V. Hence, care must be taken to prevent accidental damage to the ADC inputs. TI recommends that the output buffer(s) of the digital I/Os corresponding to the desired ADC channel be disabled first (that is, converted to high-impedance state), and thereafter the respective pass switches (S7, S8, S9, S10) should be enabled (see Section 3.2, Drive Strength and Reset States for Analog-Digital Multiplexed Pins).
- (14) Requires user configuration to enable the ADC channel analog switch. (The switch is off by default.) The digital I/O is always connected and must be made Hi-Z before enabling the ADC switch.

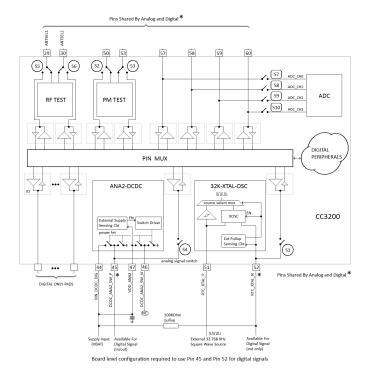


Figure 3-2. Board Configuration to Use Pins 45 and 52 as Digital Signals



3.1.1 Connections for Unused Pins

All unused pins must be left as no connect (NC) pins. For a list of NC pins, see Table 3-2.

Table 3-2. Connections for Unused Pins

FUNCTION	SIGNAL NAME	PIN NUMBER
WLAN Analog	NC	26
WLAN Analog	NC	27
WLAN Analog	NC	28



3.1.2 Recommended Pin Multiplexing Configurations

Table 3-3 lists the recommended pin multiplexing configurations.

Table 3-3. Recommended Pin Multiplexing Configurations

				CC3200 Recon	nmended Pinou	it Grouping Use	e – Examples ⁽¹⁾				
	Home Security High- end Toys	Wifi Audio ++ Industrial	Sensor-Tag	Home Security Toys	Wifi Audio ++ Industrial	WiFi Remote w/ 7x7 keypad and audio	Sensor Door- Lock Fire- Alarm Toys w/o Cam	Industrial Home Appliances	Industrial Home Appliances Smart-Plug	Industrial Home Appliances"	GPIOs
	External 32 kHz ⁽²⁾	External 32 kHz ⁽²⁾								External TCXO 40 MHZ (-40 to +85°C)	
	Cam + I2S (Tx or Rx) + I2C + SPI + SWD + UART-Tx + (App Logger) 2 GPIO + 1PWM + *4 overlaid wakeup from Hib	I2S (Tx & Rx) + 1 Ch ADC + 1x 4wire UART + 1x 2wire UART + 1bit SD Card + SPI + I2C + SWD + 3 GPIO + 1 PWM + 1 GPIO with Wake-From- Hib	I2S (Tx & Rx) + 2 Ch ADC + 2wire UART + SPI + I2C + SWD + 2 PMW + 6 GPIO + 3 GPIO with Wake-From- Hib	Cam + I2S (Tx or Rx) + I2C + SWD + UART-Tx + (App Logger) 4 GPIO + 1PWM + *4 overlaid wakeup from HIB	I2S (Tx & Rx) + 1 Ch ADC + 2x 2wire UART + 1bit SD Card + SPI + I2C + SWD + 4 GPIO + 1 PWM + 1 GPIO with Wake-From- Hib	I2S (Tx & Rx) + 1 Ch ADC + UART (Tx Only) I2C + SWD + 15 GPIO + 1 PWM + 1 GPIO with Wake-From- Hib	I2S (Tx or Rx) + 2 Ch ADC + 2 wire UART + SPI + I2C + 3 PMW + 3 GPIO with Wake-From- Hib + 5 GPIO SWD +	4 Ch ADC + 1x 4wire UART + 1x 2wire UART + SPI + I2C + SWD + 1 PWM + 6 GPIO + 1 GPIO with Wake-From- Hib Enable for Ext 40 MHz TCXO	3 Ch ADC + 2wire UART + SPI + I2C + SWD + 3 PWM + 9 GPIO + 2 GPIO with Wake-From- Hib	2 Ch ADC + 2wire UART + I2C + SWD + 3 PWM + 11 GPIO + 5 GPIO with Wake-From- Hib	
Pin Number	Pinout #11	Pinout #10	Pinout #9	Pinout #8	Pinout #7	Pinout #6	Pinout #5	Pinout #4	Pinout #3	Pinout #2	Pinout #1
52	GSPI-MOSI	McASP-D0 (Tx)									GPIO_32 output only
53	GSPI-MISO	MCASP- ACLKX	MCASP- ACLKX	GPIO_30	GPIO_30	GPIO_30	GPIO_30	UART0-TX	GPIO_30	UART0-TX	GPIO_30
45	GSPI-CLK	McASP-AFSX	McASP-D0	GPIO_31	McASP-AFSX	McASP-AFSX	McASP-AFSX	UART0-RX	GPIO_31	UART0-RX	GPIO_31
50	GSPI-CS	McASP-D1 (Rx)	McASP-D1	McASP-D1	McASP-D1	McASP-D1	McASP-D1	UARTO-CTS	GPIO_0	GPIO_0	GPIO_0
55	pCLK (PIXCLK)	UART0-TX	UART0-TX	PIXCLK	UART0-TX	UART0-TX	UART0-TX	GPIO-1	UART0-TX	GPIO_1	GPIO_1
57	(wake) GPIO2	UART0-RX	UART0-RX	(wake) GPIO2	UART0-RX	GPIO_2	UART0-RX	ADC-0	UART0-RX	(wake) GPIO_2	(wake) GPIO_2
58	pDATA7 (D3)	UART1-TX	ADC-CH1	pDATA7 (D3)	UART1-TX	GPIO_3	ADC-1	ADC-1	ADC-1	ADC-1	GPIO_3

⁽¹⁾ Pins marked "wake" can be configured to wake up the chip from HIBERNATE or LPDS state. In the current silicon revision, any wake pin can trigger wake up from HIBERNATE. The wakeup monitor in the hibernate control module logically ORs these pins applying a selection mask. However, wakeup from LPDS state can be triggered only by one of the wakeup pins that can be configured before entering LPDS. The core digital wakeup monitor use a mux to select one of these pins to monitor.

⁽²⁾ The device supports the feeding of an external 32.768-kHz clock. This configuration frees one pin (32K_XTAL_N) to use in output-only mode with a 100K pullup.

Table 3-3. Recommended Pin Multiplexing Configurations (continued)

				CC3200 Recon	nmended Pinou	ıt Grouping Us	e – Examples ⁽¹)			
59	pDATA6 (D2)	UART1-RX	(wake) GPIO_4	pDATA6 (D2)	UART1-RX	GPIO_4	(wake) GPIO_4	ADC-2	ADC-2	(wake) GPIO_4	(wake) GPIO_4
60	pDATA5 (D1)	ADC-3	ADC-3	pDATA5 (D1)	ADC-3	ADC-3	ADC-3	ADC-3	ADC-3	ADC-3	GPIO_5
61	pDATA4 (D0)	UART1-CTS	GPIO_6	pDATA4 (D0)	GPIO_6	GPIO_6	GPIO_6	UART0-RTS	GPIO_6	GPIO_6	GPIO_6
62	McASP- ACLKX	UART1-RTS	GPIO_7	McASP- ACLKX	McASP- ACLKX	McASP- ACLKX	McASP- ACLKX	GPIO_7	GPIO_7	GPIO_7	GPIO_7
63	McASP-AFSX	SDCARD-IRQ	McASP-AFSX	McASP-AFSX	SDCARD-IRQ	GPIO_8	GPIO_8	GPIO_8	GPIO_8	GPIO_8	GPIO_8
64	McASP-D0	SDCARD- DATA	GT_PWM5	McASP-D0	SDCARD- DATA	GPIO_9	GT_PWM5	GT_PWM5	GT_PWM5	GT_PWM5	GPIO_9
1	UART1-TX	SDCARD- CLK	GPIO_10	UART1-TX	SDCARD- CLK	GPIO_10	GT_PWM6	UART1-TX	GT_PWM6	GPIO_10	GPIO_10
2	(wake) pXCLK (XVCLK)	SDCARD- CMD	(wake) GPIO_11	(wake) pXCLK (XVCLK)	SDCARD- CMD	GPIO_11	(wake) GPIO_11	UART1-RX	(wake) GPIO_11	(wake) GPIO_11	(wake) GPIO_11
3	pVS (VSYNC)	I2C-SCL	I2C-SCL	pVS (VSYNC)	I2C-SCL	GPIO_12	I2C-SCL	I2C-SCL	I2C-SCL	GPIO_12	GPIO_12
4	(wake) pHS (HSYNC)	I2C-SDA	I2C-SDA	(wake) pHS (HSYNC)	I2C-SDA	GPIO_13	I2C-SDA	I2C-SDA	I2C-SDA	(wake) GPIO_13	(wake) GPIO_13
5	pDATA8 (D4)	GSPI-CLK	GSPI-CLK	pDATA8 (D4)	GSPI-CLK	I2C-SCL	GSPI-CLK	GSPI-CLK	GSPI-CLK	I2C-SCL	GPIO_14
6	pDATA9 (D5)	GSPI-MISO	GSPI-MISO	pDATA9 (D5)	GSPI-MISO	I2C-SDA	GSPI-MISO	GSPI-MISO	GSPI-MISO	I2C-SDA	GPIO_15
7	pDATA10 (D6)	GSPI-MOSI	GSPI-MOSI	pDATA10 (D6)	GSPI-MOSI	GPIO_16	GSPI-MOSI	GSPI-MOSI	GSPI-MOSI	GPIO_16	GPIO_16
8	(wake) pDATA11 (D7)	GSPI-CS	GSPI-CS	(wake) pDATA11 (D7)	GSPI-CS	GPIO_17	GSPI-CS	GSPI-CS	GSPI-CS	(wake) GPIO_17	(wake) GPIO_17
11	SPI- FLASH_CLK	SPI- FLASH_CLK	SPI- FLASH_CLK	SPI- FLASH_CLK	SPI- FLASH_CLK	SPI- FLASH_CLK	SPI- FLASH_CLK	SPI- FLASH_CLK	SPI- FLASH_CLK	SPI- FLASH_CLK	SPI- FLASH_CLK
12	SPI-FLASH- DOUT	SPI-FLASH- DOUT	SPI-FLASH- DOUT	SPI-FLASH- DOUT	SPI-FLASH- DOUT	SPI-FLASH- DOUT	SPI-FLASH- DOUT	SPI-FLASH- DOUT	SPI-FLASH- DOUT	SPI-FLASH- DOUT	SPI-FLASH- DOUT
13	SPI-FLASH- DIN	SPI-FLASH- DIN	SPI-FLASH- DIN	SPI-FLASH- DIN	SPI-FLASH- DIN	SPI-FLASH- DIN	SPI-FLASH- DIN	SPI-FLASH- DIN	SPI-FLASH- DIN	SPI-FLASH- DIN	SPI-FLASH- DIN
14	SPI-FLASH- CS	SPI-FLASH- CS	SPI-FLASH- CS	SPI-FLASH- CS	SPI-FLASH- CS	SPI-FLASH- CS	SPI-FLASH- CS	SPI-FLASH- CS	SPI-FLASH- CS	SPI-FLASH- CS	SPI-FLASH- CS
15	GPIO_22	GPIO_22	GPIO_22	GPIO_22	GPIO_22	GPIO_22	GPIO_22	GPIO_22	GPIO_22	GPIO_22	GPIO_22
16	I2C-SCL	GPIO_23	GPIO_23	I2C-SCL	GPIO_23	GPIO_23	GPIO_23	GPIO_23	GPIO_23	GPIO_23	GPIO_23
17	I2C-SDA	(wake) GPIO_24	(wake) GPIO_24	I2C-SDA	(wake) GPIO_24	(wake) GPIO_24	(wake) GPIO_24	(wake) GPIO_24	(wake) GPIO_24	GT-PWM0	(wake) GPIO_24
19	SWD-TCK	SWD-TCK	SWD-TCK	SWD-TCK	SWD-TCK	SWD-TCK	SWD-TCK	SWD-TCK	SWD-TCK	SWD-TCK	SWD-TCK
20	SWD-TMS	SWD-TMS	SWD-TMS	SWD-TMS	SWD-TMS	SWD-TMS	SWD-TMS	SWD-TMS	SWD-TMS	SWD-TMS	SWD-TMS

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Table 3-3. Recommended Pin Multiplexing Configurations (continued)

	CC3200 Recommended Pinout Grouping Use – Examples ⁽¹⁾											
18	18 GPIO_28											
21	GT_PWM2	GT_PWM2	GT_PWM2	GT_PWM2	GT_PWM2	GT_PWM2	GT_PWM2	TCXO_EN	GT_PWM2	GT_PWM2	GPIO_25 out only	



3.2 Drive Strength and Reset States for Analog-Digital Multiplexed Pins

Table 3-4 describes the use, drive strength, and default state of these pins at first-time power up and reset (nRESET pulled low).

Table 3-4. Drive Strength and Reset States for Analog-Digital Multiplexed Pins

Pin	Board Level Configuration and Use	Default State at First Power Up or Forced Reset	State after Configuration of Analog Switches (ACTIVE, LPDS, and HIB Power Modes)	Maximum Effective Drive Strength (mA)
29	Connected to the enable pin of the RF switch (ANTSEL1). Other use not recommended.	Analog is isolated. The digital I/O cell is also isolated.	Determined by the I/O state, as are other digital I/Os.	4
30	Connected to the enable pin of the RF switch (ANTSEL2). Other use not recommended.	Analog is isolated. The digital I/O cell is also isolated.	Determined by the I/O state, as are other digital I/Os.	4
45	VDD_ANA2 (pin 47) must be shorted to the input supply rail. Otherwise, the pin is driven by the ANA2 DC-DC.	Analog is isolated. The digital I/O cell is also isolated.	Determined by the I/O state, as are other digital I/Os.	4
50	Generic I/O	Analog is isolated. The digital I/O cell is also isolated.	Determined by the I/O state, as are other digital I/Os.	4
52	The pin must have an external pullup of 100 K to the supply rail and must be used in output signals only.	Analog is isolated. The digital I/O cell is also isolated.	Determined by the I/O state, as are other digital I/Os.	4
53	Generic I/O	Analog is isolated. The digital I/O cell is also isolated.	Determined by the I/O state, as are other digital I/Os.	4
57	Analog signal (1.8 V absolute, 1.46 V full scale)	ADC is isolated. The digital I/O cell is also isolated.	Determined by the I/O state, as are other digital I/Os.	4
58	Analog signal (1.8 V absolute, 1.46 V full scale)	ADC is isolated. The digital I/O cell is also isolated.	Determined by the I/O state, as are other digital I/Os.	4
59	Analog signal (1.8 V absolute, 1.46 V full scale)	ADC is isolated. The digital I/O cell is also isolated.	Determined by the I/O state, as are other digital I/Os.	4
60	Analog signal (1.8 V absolute, 1.46 V full scale)	ADC is isolated. The digital I/O cell is also isolated.	Determined by the I/O state, as are other digital I/Os.	4

3.3 Pad State After Application of Power To Chip But Prior To Reset Release

When a stable power is applied to the CC3200 chip for the first time or when supply voltage is restored to the proper value following a prior period with supply voltage below 1.5 V, the level of the digital pads are undefined in the period starting from the release of nRESET and until DIG_DCDC powers up. This period is less than approximately 10 ms. During this period, pads can be internally pulled weakly in either direction. If a certain set of pins are required to have a definite value during this pre-reset period, an appropriate pullup or pulldown must be used at the board level. The recommended value of this external pull is 2.7 K Ω .



4 Specifications

All measurements are referenced at the device pins, unless otherwise indicated. All specifications are over process and voltage, unless otherwise indicated.

4.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)

PARAMETERS	PINS	MIN	MAX	UNIT
V _{BAT} and V _{IO}	37, 39, 44	-0.5	3.8	V
V _{IO} -V _{BAT} (differential)	10, 54		0.0	V
Digital inputs		-0.5	V _{IO} + 0.5	V
RF pins		-0.5	2.1	V
Analog pins (XTAL)		-0.5	2.1	V
Operating temperature range (T _A)		-40	+85	°C

4.2 Handling Ratings

			MIN	MAX	UNIT
T _{stg}	Storage temperature range	}	– 55	+125	°C
V	Floatroatatio diochorgo	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins ⁽¹⁾	-2000	+2000	V
V _{ESD}	Electrostatic discharge	Charged device model (CDM), per JEDEC specification JESD22-C101, all pins ⁽²⁾	-500	+500	V

⁽¹⁾ JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

4.3 Power-On Hours

CONDITIONS	POH
T _{Ambient} up to 85°C, assuming 20% active mode and 80% sleep mode	17,500 ⁽¹⁾

⁽¹⁾ The CC3200 device can be operated reliably for 10 years.

4.4 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted) (1)

PARAMETERS	PINS	CONDITIONS ^{(2) (3)}	MIN	TYP	MAX	UNIT
V_{BAT} , V_{IO} (shorted to V_{BAT})	10, 37, 39, 44, 54	Direct battery connection	2.1	3.3	3.6	V
V_{BAT} , V_{IO} (shorted to V_{BAT})	10, 37, 39, 44, 54	Preregulated 1.85 V	1.76	1.85	1.9	V
Ambient thermal slew			-20		20	°C/minute

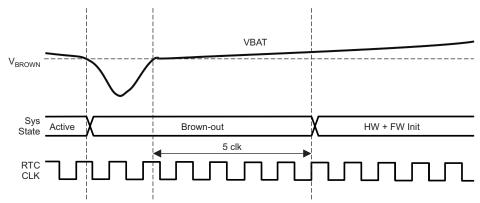
⁽¹⁾ Operating temperature is limited by crystal frequency variation.

The device enters a brown-out condition whenever the input voltage dips below V_{BROWN} (see Figure 4-1). This condition must be considered during design of the power supply routing, especially if operating from a battery. High-current operations (such as a TX packet) cause a dip in the supply voltage, potentially triggering a brown-out. The resistance includes the internal resistance of the battery, contact resistance of the battery holder (4 contacts for a 2 x AA battery) and the wiring and PCB routing resistance.

⁽²⁾ JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

⁽²⁾ To ensure WLAN performance, ripple on the 2.1- to 3.3-V supply must be less than ±300 mV.

⁽³⁾ To ensure WLAN performance, ripple on the 1.85-V supply must be less than 2% (±40 mV).



Note: For V_{BAT} wide-voltage mode, $V_{BROWN} = 2.1 \text{ V}$. For preregulated 1.85-V mode, $V_{BROWN} = 1.76 \text{ V}$.

Figure 4-1. Brown-Out Timing Diagram

For example, the device draws about 400 mA from the supply @ 2.3 V for a 1 DSSS packet at maximum power. This condition can cause a drop of 200 mV across a $0.5-\Omega$ routing resistance.

In the brown-out condition, the device is in RESET state except for the Hibernate module (including the 32-kHz RTC clock), which is kept on. The current in this state can reach approximately $400 \, \mu A$.

4.5 Electrical Characteristics

3.3 V, 25°C

GPIO Pins Except 29, 30, 45, 50, 52, and 53 (25°C) ⁽¹⁾									
	PARAMET	ER	TEST CONDITIONS	MIN	NOM	MAX	UNIT		
C _{IN}	Pin capacitance				4		pF		
V _{IH}	High-level input	voltage		0.65 × VDD		VDD + 0.5 V	V		
V _{IL}	Low-level input v	roltage		-0.5		0.35 × VDD	V		
I _{IH}	High-level input	current			5		nA		
I _{IL}	Low-level input of	current			5		nA		
V _{OH}	High-level output 3.0 V)	t voltage (VDD =		2.4			V		
V _{OL}	Low-level output 3.0 V)	voltage (VDD =				0.4	V		
I _{OH}	High-level	2-mA Drive		2			mA		
	source current, VOH = 2.4	4-mA Drive		4			mA		
	VOIT = 2.4	6-mA Drive		6			mA		
I _{OL}	Low-level sink current, VOH = 0.4	2-mA Drive		2			mA		
		4-mA Drive		4			mA		
	VOIT = 0.4	6-mA Drive		6			mA		

⁽¹⁾ TI recommends using the lowest possible drive strength that is adequate for the applications. This recommendation minimizes the risk of interference to the WLAN radio and mitigates any potential degradation of RF sensitivity and performance. The default drive strength setting is 6 mA.



3.3 V, 25°C

GPIO Pins 29, 30, 45, 50, 52, and 53 (25°C) ⁽¹⁾									
	PARAMET	ER	TEST CONDITIONS	MIN	NOM	MAX	UNIT		
C _{IN}	Pin capacitance				7		pF		
V _{IH}	High-level input	voltage		0.65 × VDD		VDD + 0.5V	V		
V _{IL}	Low-level input v	roltage		-0.5		0.35 × VDD	V		
I _{IH}	High-level input of	current			50		nA		
I _{IL}	Low-level input of	Low-level input current			50		nA		
V _{OH}	High-level output (VDD= 3.0 V)	High-level output voltage (VDD= 3.0 V)		2.4			V		
V _{OL}	Low-level output (VDD= 3.0 V)	voltage				0.4	V		
I _{OH}	High-level	2-mA Drive		1.5			mA		
	source current, V _{OH} = 2.4	4-mA Drive		2.5			mA		
	VOH - 2.4	6-mA Drive		3.5			mA		
I _{OL}	Low-level sink	2-mA Drive		1.5			mA		
	current, V _{OH} = 0.4	4-mA Drive		2.5			mA		
	0.4	6-mA Drive		3.5			mA		

⁽¹⁾ TI recommends using the lowest possible drive strength that is adequate for the applications. This recommendation minimizes the risk of interference to the WLAN radio and mitigates any potential degradation of RF sensitivity and performance. The default drive strength setting is 6 mA.

3.3 V, 25°C

Pin Int	Pin Internal Pullup and Pulldown (25°C) ⁽¹⁾								
	PARAMETER	TEST CONDITIONS	MIN	NOM	MAX	UNIT			
I _{OH}	Pull-Up current, $V_{OH} = 2.4$ (VDD = 3.0 V)		5		10	μА			
I _{OL}	Pull-Down current, V _{OL} = 0.4 (VDD = 3.0 V)		5			μА			

⁽¹⁾ TI recommends using the lowest possible drive strength that is adequate for the applications. This recommendation minimizes the risk of interference to WLAN radio and mitigates any potential degradation of RF sensitivity and performance. The default drive-strength setting is 6 mA.

4.6 WLAN Receiver Characteristics

 $T_A = +25$ °C, $V_{BAT} = 2.1$ to 3.6 V. Parameters measured at SoC pin on channel 7 (2442 MHz)

Parameter	Condition (Mbps)	Min	Тур	Max	Units
	1 DSSS		-95.7		
	2 DSSS		-93.6		
	11 CCK		-88.0		
	6 OFDM		-90.0		
Sensitivity	9 OFDM		-89.0		
(8% PER for 11b rates, 10% PER for 11g/11n rates)(10% PER) ⁽¹⁾	18 OFDM		-86.0		dBm
	36 OFDM		-80.5		авш
	54 OFDM		-74.0		
	MCS0 (GF) ⁽²⁾		-89.0		
	MCS7 (GF) ⁽²⁾		-71.0		
Maximum input level	802.11b		-4.0		
(10% PER)	802.11g		-10.0		

⁽¹⁾ Sensitivity is 1-dB worse on channel 13 (2472 MHz).

⁽²⁾ Sensitivity for mixed mode is 1-dB worse.



WLAN Transmitter Characteristics

 $T_A = +25$ °C, $V_{BAT} = 2.1$ to 3.6 V. Parameters measured at SoC pin on channel 7 (2442 MHz). (1)

Parameter	Condition ⁽²⁾	Min	Тур	Max	Units	
	1 DSSS		18.0			
	2 DSSS		18.0			
	11 CCK		18.3			
	6 OFDM		17.3			
Maximum RMS output power measured at 1 dB from IEEE spectral mask or EVM	9 OFDM		17.3		dBm	
T ab nom tele oposital mask of evin	18 OFDM		17.0			
	36 OFDM		16.0			
	54 OFDM		14.5			
	MCS7 (MM)		13.0		1	
Transmit center frequency accuracy		-25		25	ppm	

Channel-to-channel variation is up to 2 dB. The edge channels (2412 and 2472 MHz) have reduced TX power to meet FCC emission (1)

Current Consumption

 $T_{\Delta} = +25^{\circ}C, V_{B\Delta T} = 3.6 \text{ V}$

PAR	RAMETER		TEST CONDITIONS(1)	(2)	MIN	TYP	MAX	UNIT
			4 D000	TX power level = 0		278		
			1 DSSS	TX power level = 4		194		
		TV	COEDM	TX power level = 0		254		
	NIME ACTIVE	TX	6 OFDM	TX power level = 4		185		
MCU ACTIVE	NWP ACTIVE		54 OFDM	TX power level = 0		229		mA
			54 OFDM	TX power level = 4		166		
		DV	1 DSSS 54 OFDM			59		
		RX				59		
	NWP idle connect	ed ⁽³⁾	1(3)					
			4 0000	TX power level = 0		275		
			1 DSSS	TX power level = 4		191		
		TV	COEDM	TX power level = 0		251		
	NIME ACTIVE	TX	6 OFDM	TX power level = 4		182		
MCU SLEEP	NWP ACTIVE		54 OFDM	TX power level = 0		226		mA
			54 OFDM	TX power level = 4		163		
		DV	1 DSSS			56		
		RX	54 OFDM			56		
NWP idle connec		ed ⁽³⁾				12.2		

In preregulated 1.85-V mode, maximum TX power is 0.25 to 0.75 dB lower for modulations higher than 18 OFDM.

⁽¹⁾ TX power level = 0 implies maximum power (see Figure 4-2 through Figure 4-4). TX power level = 4 implies output power backed off approximately 4 dB.

The CC3200 system is a constant power-source system. The active current numbers scale based on the V_{BAT} voltage supplied.

DTIM = 1(3)



Current Consumption (continued)

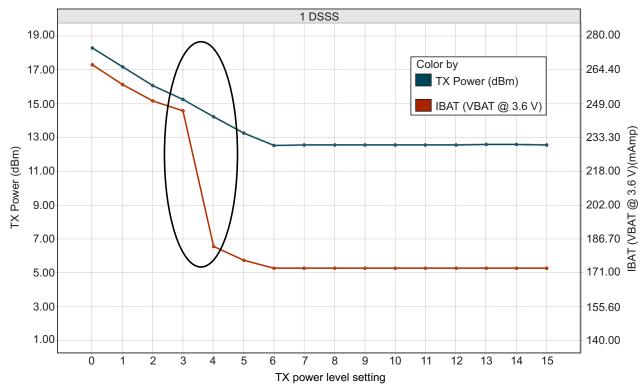
 $T_A = +25$ °C, $V_{BAT} = 3.6 \text{ V}$

PAR	AMETER	T	EST CONDITIONS(1)	(2)	MIN	TYP	MAX	UNIT
			1 DSSS	TX power level = 0		272		
			1 0555	TX power level = 4		188		
		TV	C OFDM	TX power level = 0		248		
	NIVA/D a ativis	TX	6 OFDM	TX power level = 4		179		mA
MOLLLDDG	NWP active		54 OFDM	TX power level = 0		223		
MCU LPDS			54 OFDM	TX power level = 4		160		
		DV	1 DSSS	DSSS		53		
		RX	54 OFDM			53		
	NWP LPDS ⁽⁴⁾					0.12		
	NWP idle connec	cted ⁽³⁾				0.695		
MCU hibernate	NWP hibernate (5	5)				4		μA
		V _{BAT} = 3.3 V				450		
Peak calibration co	urrent ⁽⁶⁾	V _{BAT} = 2.1 V				670		mA
		V _{BAT} = 1.85 V				700		

⁽⁴⁾ LPDS current does not include the external serial flash. The LPDS number reported is with retention of 64KB MCU SRAM. The CC3200 device can be configured to retain 0KB, 64KB, 128KB, 192KB or 256KB SRAM in LPDS. Each 64KB retained increases LPDS current by 4 μA.

(5) Serial flash current consumption in power-down mode during hibernate is not included.

⁽⁶⁾ The complete calibration can take up to 17 mJ of energy from the battery over a time of 24 ms. Calibration is performed sparingly, typically when coming out of Hibernate and only if temperature has changed by more than 20°C or the time elapsed from prior calibration is greater than 24 hours.



Note: The area enclosed in the circle represents a significant reduction in current when transitioning from TX power level 3 to 4. In the case of lower range requirements (14 dbm output power), TI recommends using TX power level 4 to reduce the current.

Figure 4-2. TX Power and IBAT vs TX Power Level Settings (1 DSSS)

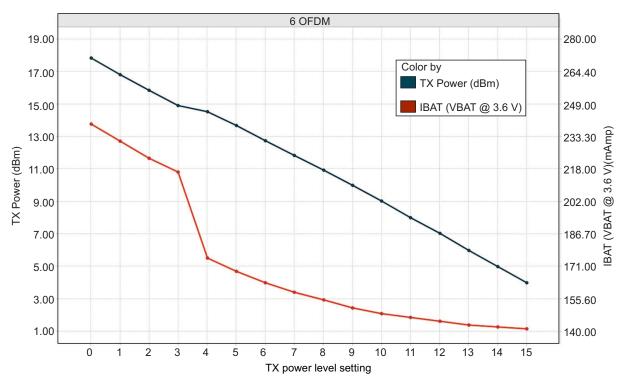


Figure 4-3. TX Power and IBAT vs TX Power Level Settings (6 OFDM)

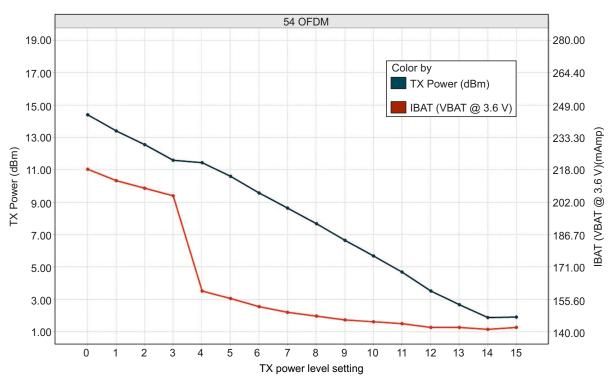


Figure 4-4. TX Power and IBAT vs TX Power Level Settings (54 OFDM)



4.9 Thermal Characteristics for RGC Package

	AIR FLOW								
PARAMETER	0 lfm (C/W)	150 lfm (C/W)	250 lfm (C/W)	500 lfm (C/W)					
θ_{ja}	23	14.6	12.4	10.8					
Ψ_{jt}	0.2	0.2	0.3	0.1					
Ψ_{jb}	2.3	2.3	2.2	2.4					
$\theta_{ m jc}$	6.3								
θ_{jb}	2.4								

4.10 Timing and Switching Characteristics

4.10.1 Power Supply Sequencing

For proper operation of the CC3200 device, perform the recommended power-up sequencing as follows:

- 1. Tie V_{BAT} (pins 37, 39, 44) and V_{IO} (pins 54 and 10) together on the board.
- 2. Hold the RESET pin low while the supplies are ramping up. TI recommends using a simple RC circuit (100K \parallel 0.1 μ F, RC = 10 ms).
- 3. For an external RTC clock, ensure that the clock is stable before RESET is deasserted (high).

For timing diagrams, see Section 4.10.2, Reset Timing.

4.10.2 Reset Timing

4.10.2.1 nRESET (32K XTAL)

Figure 4-5 shows the reset timing diagram for the 32K XTAL first-time power-up and reset removal.

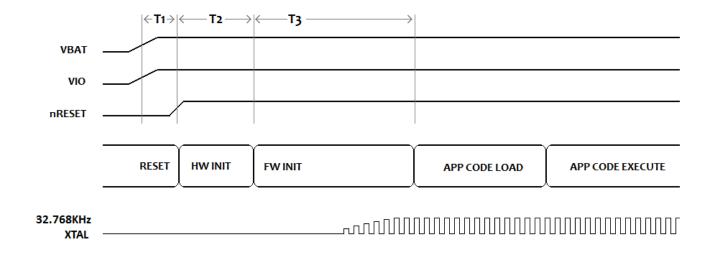


Figure 4-5. First-Time Power-Up and Reset Removal Timing Diagram (32K XTAL)



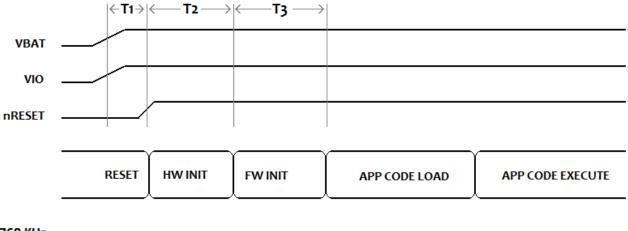
Table 4-1 describes the timing requirements for the 32K XTAL first-time power-up and reset removal.

Table 4-1. First-Time Power-Up and Reset Removal Timing Requirements (32K XTAL)

Item	Name	Description	Min	Тур	Max
T1	Supply settling time	Depends on application board power supply, decap, and so on		3 ms	
T2	Hardware wakeup time			25 ms	
Т3	Time taken by ROM firmware to initialize hardware	Includes 32.768 -kHz XOSC settling time		1.1 s	

4.10.2.2 nRESET (External 32K)

Figure 4-6 shows the reset timing diagram for the external 32K first-time power-up and reset removal.



32.768 KHz External Clock

Figure 4-6. First-Time Power-Up and Reset Removal Timing Diagram (External 32K)

Table 4-2 describes the timing requirements for the external 32K first-time power-up and reset removal.

Table 4-2. First-Time Power-Up and Reset Removal Timing Requirements (External 32K)

Item	Name	Description	Min	Тур	Max
T1	Supply settling time	Depends on application board power supply, decap, and so on		3 ms	
T2	Hardware wakeup time			25 ms	
Т3	Time taken by ROM firmware to initialize hardware	Time taken by ROM firmware		3 ms	



4.10.2.3 Wakeup from Hibernate

Figure 4-7 shows the timing diagram for wakeup from the hibernate state.

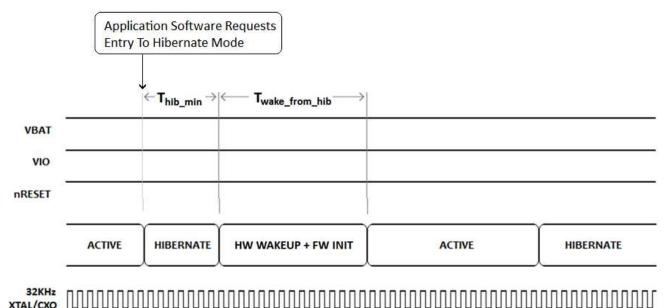


Figure 4-7. nHIB Timing Diagram

NOTE

The 32.768-kHz XTAL is kept enabled by default when the chip goes to hibernate.

Table 4-3 describes the timing requirements for nHIB.

Table 4-3. Software Hibernate Timing Requirements

Item	Name	Description	Min	Тур	Max
T _{hib_min}	Minimum hibernate time		10 ms		
T _{wake_from_hib} ⁽¹⁾	Hardware wakeup time plus firmware initialization time			50 ms	

⁽¹⁾ Twake_from_hib can be 200 ms on rare occasions when calibration is performed. Calibration is performed sparingly, typically when exiting Hibernate and only if temperature has changed by more than 20°C or more than 24 hours have elapsed since a prior calibration.

4.10.3 Clock Specifications

The CC3200 device requires two separate clocks for its operation:

- A slow clock running at 32.768 kHz is used for the RTC.
- A fast clock running at 40 MHz is used by the device for the internal processor and the WLAN subsystem.

The device features internal oscillators that enable the use of cheaper crystals rather than dedicated TCXOs for these clocks. The RTC can also be fed externally to provide reuse of an existing clock on the system and reduce overall cost.

4.10.3.1 Slow Clock Using Internal Oscillator

The RTC crystal connected on the device supplies the free-running slow clock. The accuracy of the slow clock frequency must be 32.768 kHz ±150 ppm. In this mode of operation, the crystal is tied between RTC_XTAL_P (pin 51) and RTC_XTAL_N (pin 52) with a suitable load capacitance.

Figure 4-8 shows the crystal connections for the slow clock.

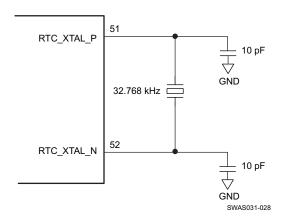


Figure 4-8. RTC Crystal Connections

4.10.3.2 Slow Clock Using an External Clock

When an RTC clock oscillator is present in the system, the CC3200 device can accept this clock directly as an input. The clock is fed on the RTC_XTAL_P line and the RTC_XTAL_N line is held to VIO. The clock must be a CMOS-level clock compatible with VIO fed to the device.

Figure 4-9 shows the external RTC clock input connection.

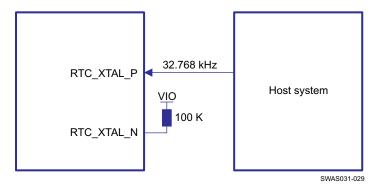


Figure 4-9. External RTC Clock Input

4.10.3.3 Fast Clock (F_{ref}) Using an External Crystal

The CC3200 device also incorporates an internal crystal oscillator to support a crystal-based fast clock. The XTAL is fed directly between WLAN_XTAL_P (pin 23) and WLAN_XTAL_N (pin 22) with suitable loading capacitors.

Figure 4-10 shows the crystal connections for the fast clock.

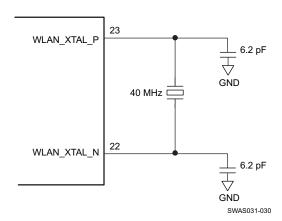


Figure 4-10. Fast Clock Crystal Connections

4.10.3.4 Fast Clock (F_{ref}) Using an External Oscillator

The CC3200 device can accept an external TCXO/XO for the 40-MHz clock. In this mode of operation, the clock is connected to WLAN_XTAL_P (pin 23). WLAN_XTAL_N (pin 22) is connected to GND. The external TCXO/XO can be enabled by TCXO_EN (pin 21) from the device to optimize the power consumption of the system.

If the TCXO does not have an enable input, an external LDO with an enable function can be used. Using the LDO improves noise on the TCXO power supply.

Figure 4-11 shows the connection.

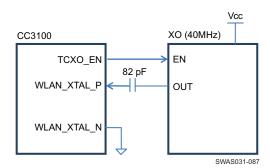


Figure 4-11. External TCXO Input

Table 4-4 lists the external F_{ref} clock requirements.

Table 4-4. External F_{ref} Clock Requirements (-40°C to +85°C)

Chara	cteristics	Condition	Sym	Min	Тур	Max	Unit
Frequency					40.00		MHz
Frequency accuracy (Initial + temp + aging)						±20	ppm
Frequency input duty cycle				45	50	55	%
Clock voltage limits		Sine or clipped sine wave, AC coupled	Vpp	0.7		1.2	Vpp
Phase noise @ 40 MHz		@ 1 kHz				-125	dBc/Hz
		@ 10 kHz				-138.5	dBc/Hz
		@ 100 kHz				-143	dBc/Hz
Input impedance	Resistance			12			ΚΩ
	Capacitance					7	pF



4.10.3.5 Input Clocks/Oscillators

Table 4-5 lists the RTC crystal requirements.

Table 4-5. RTC Crystal Requirements

CHARACTERISTICS	CONDITION	SYM	MIN	TYP	MAX	UNIT
Frequency				32.768		kHz
Frequency accuracy	Initial + temp + aging				±150	ppm
Crystal ESR	32.768 kHz, C1 = C2 = 10 pF				70	kΩ

Table 4-6 lists the external RTC digital clock requirements.

Table 4-6. External RTC Digital Clock Requirements

CHARACTERISTICS	CONDITION	SYM	MIN	TYP	MAX	UNIT
Frequency				32768		Hz
Frequency accuracy					±150	ppm
(Initial + temp + aging)						
Input transition time t _r /t _f (10% to 90%)		t _r /t _f			100	ns
Frequency input duty cycle			20	50	80	%
Slow clock input voltage limits	Square wave, DC coupled	V _{ih}	0.65 × V _{IO}		V _{IO}	V
		V_{il}	0		0.35 × V _{IO}	V peak
Input impedance			1			ΜΩ
					5	pF

Table 4-7 lists the WLAN fast-clock crystal requirements.

Table 4-7. WLAN Fast-Clock Crystal Requirements

CHARACTERISTICS	CONDITION	SYM	MIN	TYP	MAX	UNIT
Frequency				40		MHz
Frequency accuracy	Initial + temp + aging				±20	ppm
Crystal ESR	40 MHz, C1 = C2 = 6.2 pF		40	50	60	Ohm

4.10.4 Peripherals

This section describes the peripherals that are supported by the CC3200 device:

- SPI
- McASP
- GPIO
- I²C
- IEEE 1149.1 JTAG
- ADC
- Camera parallel port
- UART

4.10.4.1 SPI

4.10.4.1.1 SPI Master

The CC3200 microcontroller includes one SPI module, which can be configured as a master or slave device. The SPI includes a serial clock with programmable frequency, polarity, and phase, a programmable timing control between chip select and external clock generation, and a programmable delay before the first SPI word is transmitted. Slave mode does not include a dead cycle between two successive words.



Figure 4-12 shows the timing diagram for the SPI master.

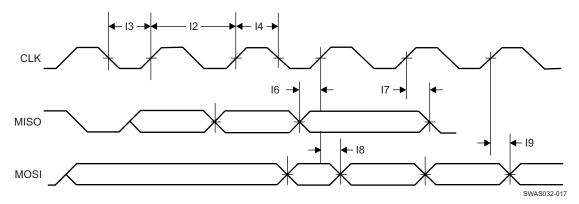


Figure 4-12. SPI Master Timing Diagram

Table 4-8 lists the timing parameters for the SPI master.

Table 4-8. SPI Master Timing Parameters

Parameter Number	Parameter ⁽¹⁾	Parameter Name	Min	Max	Unit
I1	F	Clock frequency		20	MHz
12	T _{clk}	Clock period	50		ns
13	t _{LP}	Clock low period	Clock low period		ns
14	t _{HT}	Clock high period	Clock high period		ns
15	D	Duty cycle	45	55	%
16	t _{IS}	RX data setup time	1		ns
17	t _{IH}	RX data hold time	2		ns
18	t _{OD}	TX data output delay		8.5	ns
19	t _{OH}	TX data hold time		8	ns

⁽¹⁾ Timing parameter assumes a maximum load of 20 pF.

4.10.4.1.2 SPI Slave

Figure 4-13 shows the timing diagram for the SPI slave.

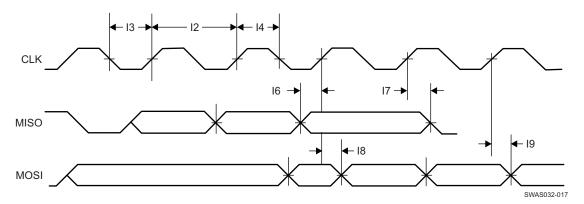


Figure 4-13. SPI Slave Timing Diagram

Table 4-9 lists the timing parameters for the SPI slave.

Table 4-9	. SPI	Slave	Timing	Parameters
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Parameter Number	Parameter ⁽¹⁾	Parameter Name	Min	Max	Unit
I1	F	Clock frequency @ VBAT = 3.3 V		20	MHz
		Clock frequency @ VBAT ≤ 2.1 V		12	
12	Tclk	Clock period	Clock period 50		ns
13	tLP	Clock low period		25	ns
14	tHT	Clock high period		25	ns
15	D	Duty cycle	45	55	%
16	tIS	RX data setup time	4		ns
17	tlH	RX data hold time	4		ns
18	tOD	TX data output delay		20	
19	tOH	TX data hold time	TX data hold time		ns

⁽¹⁾ Timing parameter assumes a maximum load of 20 pF at 3.3 V.

4.10.4.2 McASP

The McASP interface functions as a general-purpose audio serial port optimized for multichannel audio applications and supports transfer of two stereo channels over two data pins. The McASP consists of transmit and receive sections that operate synchronously and have programmable clock and frame-sync polarity. A fractional divider is available for bit-clock generation.

4.10.4.2.1 I2S Transmit Mode

Figure 4-14 shows the timing diagram for the I2S transmit mode.

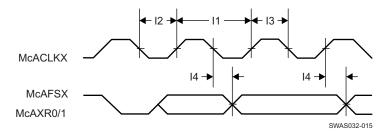


Figure 4-14. I2S Transmit Mode Timing Diagram

Table 4-10 lists the timing parameters for the I2S transmit mode.

Table 4-10. I2S Transmit Mode Timing Parameters

Parameter Number	Parameter ⁽¹⁾	Parameter Name	Min	Max	Unit
I1	fclk	Clock frequency		9.216	MHz
12	tLP	Clock low period		1/2 fclk	ns
13	tHT	Clock high period		1/2 fclk	ns
14	tOH	TX data hold time		22	ns

(1) Timing parameter assumes a maximum load of 20 pF.



4.10.4.2.2 I2S Receive Mode

Figure 4-15 shows the timing diagram for the I2S receive mode.

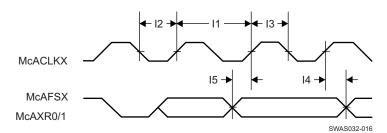


Figure 4-15. I2S Receive Mode Timing Diagram

Table 4-11 lists the timing parameters for the I2S receive mode.

Table 4-11. I2S Receive Mode Timing Parameters

Parameter Number	Parameter ⁽¹⁾	Parameter Name	Min	Max	Unit
I1	fclk	Clock frequency		9.216	MHz
12	tLP	Clock low period		1/2 fclk	ns
13	tHT	Clock high period		1/2 fclk	ns
14	tOH	RX data hold time		0	ns
15	tOS	RX data setup time		15	ns

⁽¹⁾ Timing parameter assumes a maximum load of 20 pF.

4.10.4.3 GPIO

All digital pins of the device can be used as general-purpose input/output (GPIO) pins. The GPIO module consists of four GPIO blocks, each of which provides eight GPIOs. The GPIO module supports 24 programmable GPIO pins, depending on the peripheral used. Each GPIO has configurable pullup and pulldown strength (weak 10 μ A), configurable drive strength (2, 4, and 6 mA), and open-drain enable.

Figure 4-16 shows the GPIO timing diagram.

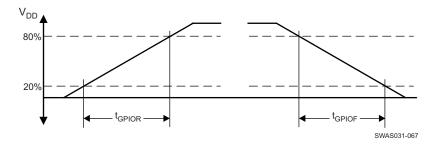


Figure 4-16. GPIO Timing

4.10.4.3.1 GPIO Output Transition Time Parameters (V_{supply} = 3.3 V)

Table 4-12 lists the GPIO output transition times for $V_{supply} = 3.3 \text{ V}$.

Table 4-12. GPIO Output Transition Times $(V_{supply} = 3.3 \text{ V})^{(1)(2)}$

Drive			T _r (ns)		T _f (ns)		
Strength (mA)	Drive Strength Control Bits	Min	Nom	Max	Min	Nom	Max
	2MA_EN=1						
2	4MA_EN=0	8.0	9.3	10.7	8.2	9.5	11.0
	8MA_EN=0						
	2MA_EN=0						
4	4MA_EN=1	6.6	7.1	7.6	4.7	5.2	5.8
	8MA_EN=0						
	2MA_EN=0						
8	4MA_EN=0	3.2	3.5	3.7	2.3	2.6	2.9
	8MA_EN=1						
	2MA_EN=1						
14	4MA_EN=1	1.7	1.9	2.0	1.3	1.5	1.6
	8MA_EN=1						

4.10.4.3.2 GPIO Output Transition Time Parameters (Vsupply = 1.8 V)

Table 4-13 lists the GPIO output transition times for $V_{supply} = 1.8 \text{ V}$.

Table 4-13. GPIO Output Transition Times $(V_{supply} = 1.8 \text{ V})^{(1)(2)}$

Drive			T _r (ns)		T _f (ns)		
Strength (mA)	Drive Strength Control Bits	Min	Nom	Max	Min	Nom	Max
	2MA_EN=1						
2	4MA_EN=0	11.7	13.9	16.3	11.5	13.9	16.7
	8MA_EN=0						
	2MA_EN=0						
4	4MA_EN=1	13.7	15.6	18.0	9.9	11.6	13.6
	8MA_EN=0						
	2MA_EN=0						
8	4MA_EN=0	5.5	6.4	7.4	3.8	4.7	5.8
	8MA_EN=1						
	2MA_EN=1						
14	4MA_EN=1	2.9	3.4	4.0	2.2	2.7	3.3
	8MA_EN=1						

 $V_{supply} = 1.8 \text{ V}, T = 25^{\circ}\text{C}, \text{ total pin load} = 30 \text{ pF}$

4.10.4.3.3 GPIO Input Transition Time Parameters

Table 4-14 lists the input transition time parameters.

Table 4-14. GPIO Input Transition Time Parameters

Parameter	Condition	Symbol	Min	Max	Unit
Input transition time		t _r	1	3	20
(t_r,t_f) , 10% to 90%		t _f	1	3	ns

 $V_{supply} = 3.3 \text{ V}, T = 25^{\circ}\text{C}, \text{ total pin load} = 30 \text{ pF}$ The transition data applies to the pins other than the multiplexed analog-digital pins 29, 30, 45, 50, 52, and 53.

The transition data applies to the pins other than the multiplexed analog-digital pins 29, 30, 45, 50, 52, and 53.



4.10.4.4 I²C

The CC3200 microcontroller includes one I²C module operating with standard (100 Kbps) or fast (400 Kbps) transmission speeds.

Figure 4-17 shows the I²C timing diagram.

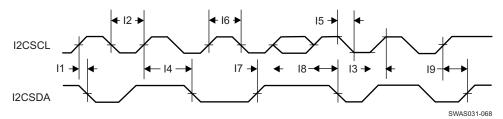


Figure 4-17. I²C Timing

Table 4-15 lists the I²C timing parameters.

Table 4-15. I²C Timing Parameters⁽¹⁾

Parameter Number	Parameter	Parameter Name	Min	Max	Unit
I2	t _{LP}	Clock low period	See (2).	-	System clock
13	t _{SRT}	SCL/SDA rise time	_	See (3).	ns
14	t _{DH}	Data hold time	NA	-	
15	t _{SFT}	SCL/SDA fall time	_	3	ns
16	t _{HT}	Clock high time	See (2).	-	System clock
17	t _{DS}	Data setup time	tLP/2		System clock
18	t _{SCSR}	Start condition setup time	36	-	System clock
19	t _{SCS}	Stop condition setup time	24	-	System clock

⁽¹⁾ All timing is with 6-mA drive and 20-pF load.

4.10.4.5 IEEE 1149.1 JTAG

The Joint Test Action Group (JTAG) port is an IEEE standard that defines a test access port (TAP) and boundary scan architecture for digital integrated circuits and provides a standardized serial interface to control the associated test logic. For detailed information on the operation of the JTAG port and TAP controller, see the IEEE Standard 1149.1, Test Access Port and Boundary- Scan Architecture.

Figure 4-18 shows the JTAG timing diagram.

⁽²⁾ This value depends on the value programmed in the clock period register of I²C. Maximum output frequency is the result of the minimal value programmed in this register.

⁽³⁾ Because ¹²C is an open-drain interface, the controller can drive logic 0 only. Logic is the result of external pullup. Rise time depends on the external signal capacitance and external pullup register value.

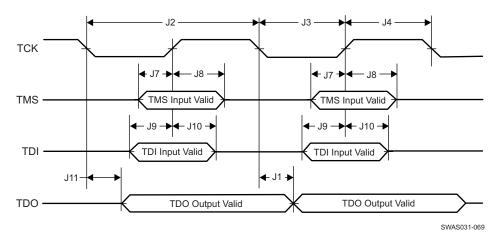


Figure 4-18. JTAG Timing

Table 4-16 lists the JTAG timing parameters.

Table 4-16. JTAG Timing Parameters

Parameter Number	Parameter	Parameter Name	Min	Max	Unit
J1	fTCK	Clock frequency		15	MHz
J2	tTCK	Clock period		1/fTCK	ns
J3	tCL	Clock low period		tTCK/2	ns
J4	tCH	Clock high period		tTCK/2	ns
J7	tTMS_SU	TMS setup time	1		
J8	tTMS_HO	TMS hold time	16		
J9	tTDI_SU	TDI setup time	1		
J10	tTDI_HO	TDI hold time	16		
J11	tTDO_HO	TDO hold time		15	

4.10.4.6 ADC

Table 4-17 lists the ADC electrical specifications.

Table 4-17. ADC Electrical Specifications

Parameter	Description	Condition and Assumptions	Min	Тур	Max	Unit
Nbits	Number of bits			12		Bits
INL	Integral nonlinearity	Worst-case deviation from histogram method over full scale (not including first and last three LSB levels)	-2.5		2.5	LSB
DNL	Differential nonlinearity	Worst-case deviation of any step from ideal	-1		4	LSB
Input range			0		1.4	V
Driving source impedance					100	Ω
FCLK	Clock rate	Successive approximation input clock rate		10		MHz
Input capacitance				3.2		pF
Number of channels				4		
F _{sample}	Sampling rate of each ADC			62.5		KSPS
F_input_max	Maximum input signal frequency				31	kHz
SINAD	Signal-to-noise and distortion	Input frequency dc to 300 Hz and 1.4 V _{pp} sine wave input	55	60		dB



Parameter	Description	Condition and Assumptions	Min	Тур	Max	Unit
I_active	Active supply current	Average for analog-to-digital during conversion without reference current		1.5		mA
I_PD	Power-down supply current for core supply	Total for analog-to-digital when not active (this must be the SoC level test)		1		μΑ
Absolute offset error		FCLK = 10 MHz		±2		mV
Gain error				±2		%

Figure 4-19 shows the ADC clock timing diagram.

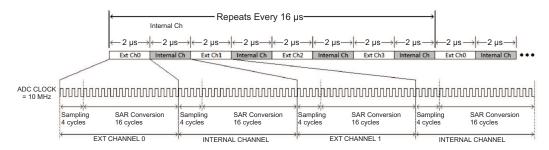


Figure 4-19. ADC Clock Timing

4.10.4.7 Camera Parallel Port

The fast camera parallel port interfaces with a variety of external image sensors, stores the image data in a FIFO, and generates DMA requests. The camera parallel port supports 8 bits.

Figure 4-20 shows the timing diagram for the camera parallel port.

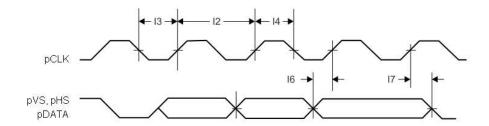


Figure 4-20. Camera Parallel Port Timing Diagram

Table 4-18 lists the timing parameters for the camera parallel port.

Table 4-18. Camera Parallel Port Timing Parameters

Parameter Number	Parameter	Parameter Name	Min	Max	Unit
	pCLK	Clock frequency		2	MHz
12	T _{clk}	Clock period		1/pCLK	ns
13	t _{LP}	Clock low period		T _{clk} /2	ns
14	t _{HT}	Clock high period		T _{clk} /2	ns
17	D	Duty cycle		45 to 55	%
18	t _{IS}	RX data setup time		2	ns
19	t _{IH}	RX data hold time		2	ns

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4.10.4.8 UART

The CC3200 device includes two UARTs with the following features:

- Programmable baud-rate generator allowing speeds up to 3 Mbps
- Separate 16 x 8 TX and RX FIFOs to reduce CPU interrupt service loading
- Programmable FIFO length, including 1-byte deep operation providing conventional double-buffered interface
- FIFO trigger levels of 1/8, 1/4, 1/2, 3/4, and 7/8
- Standard asynchronous communication bits for start, stop, and parity
- Line-break generation and detection
- Fully programmable serial interface characteristics
 - 5, 6, 7, or 8 data bits
 - Even, odd, stick, or no-parity bit generation and detection
 - 1 or 2 stop-bit generation
- RTS and CTS hardware flow support
- Standard FIFO-level and End-of-Transmission interrupts
- Efficient transfers using µDMA
 - Separate channels for transmit and receive
 - Receive single request asserted when data is in the FIFO; burst request asserted at programmed FIFO
 - Transmit single request asserted when there is space in the FIFO; burst request asserted at programmed FIFO level
- System clock is used to generate the baud clock.

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5 Detailed Description

5.1 Overview

The CC3200 device has a rich set of peripherals for diverse application requirements. The device optimizes bus matrix and memory management to give the application developer the needed advantage. This section briefly highlights the internal details of the CC3200 device and offers suggestions for application configurations.

5.1.1 Device Features

5.2 Functional Block Diagram

Figure 5-1 shows the functional block diagram of the CC3200 SimpleLink Wi-Fi solution.

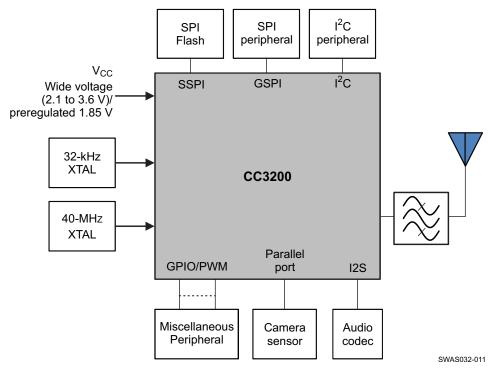


Figure 5-1. Functional Block Diagram

5.3 ARM Cortex-M4 Processor Core Subsystem

The high-performance ARM Cortex-M4 processor provides a low-cost platform that meets the needs of minimal memory implementation, reduced pin count, and low power consumption, while delivering outstanding computational performance and exceptional system response to interrupts.

- The ARM Cortex-M4 core has low-latency interrupt processing with the following features:
 - A 32-bit ARM Cortex Thumb® instruction set optimized for embedded applications
 - Handler and thread modes
 - Low-latency interrupt handling by automatic processor state saving and restoration during entry and exit
 - Support for ARMv6 unaligned accesses



- Nested vectored interrupt controller (NVIC) closely integrated with the processor core to achieve low latency interrupt processing. Features include:
 - Bits of priority configurable from 3 to 8
 - Dynamic reprioritization of interrupts
 - Priority grouping that enables selection of preempting interrupt levels and nonpreempting interrupt levels
 - Support for tail-chaining and late arrival of interrupts, which enables back-to-back interrupt
 processing without the overhead of state saving and restoration between interrupts
 - Processor state automatically saved on interrupt entry and restored on interrupt exit with no instruction overhead
 - Wake-up interrupt controller (WIC) providing ultra-low power sleep mode support
- Bus interfaces:
 - Three advanced high-performance bus (AHB-Lite) interfaces: ICode, DCode, and system bus interfaces
 - Bit-band support for memory and select peripheral that includes atomic bit-band write and read operations
- Low-cost debug solution featuring:
 - Debug access to all memory and registers in the system, including access to memory-mapped devices, access to internal core registers when the core is halted, and access to debug control registers even while SYSRESETn is asserted
 - Serial wire debug port (SW-DP) or serial wire JTAG debug port (SWJ-DP) debug access
 - Flash patch and breakpoint (FPB) unit to implement breakpoints and code patches

5.4 CC3200 Device Encryption

Figure 5-2 shows a standard MCU for the CC3200 device. Application image and user data files are not encrypted. Network certificates are encrypted using a device-specific key.

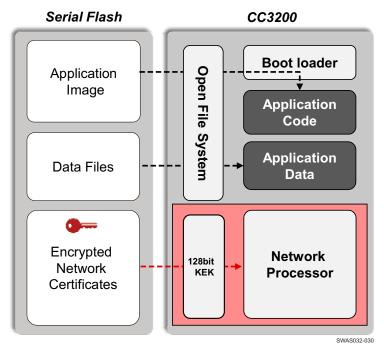


Figure 5-2. CC3200 Standard MCU



5.5 Wi-Fi Network Processor Subsystem

The Wi-Fi network processor subsystem includes a dedicated ARM MCU to completely offload the host MCU along with an 802.11 b/g/n radio, baseband, and MAC with a powerful crypto engine for a fast, secure WLAN and Internet connections with 256-bit encryption. The CC3200 device supports station, AP, and Wi-Fi Direct modes. The device also supports WPA2 personal and enterprise security and WPS 2.0. The Wi-Fi network processor includes an embedded IPv4 TCP/IP stack.

Table 5-1 summarizes the NWP features.

Table 5-1. Summary of Features Supported by the NWP Subsystem

Item	Domain	Category	Feature	Details
1	TCP/IP	Network Stack	IPv4	Baseline IPv4 stack
2	TCP/IP	Network Stack	TCP/UDP	Base protocols
3	TCP/IP	Protocols	DHCP	Client and server mode
4	TCP/IP	Protocols	ARP	Support ARP protocol
5	TCP/IP	Protocols	DNS/mDNS	DNS Address resolution and local server
6	TCP/IP	Protocols	IGMP	Up to IGMPv3 for multicast management
7	TCP/IP	Applications	mDNS	Support multicast DNS for service publishing over IP
8	TCP/IP	Applications	mDNS-SD	Service discovery protocol over IP in local network
9	TCP/IP	Applications	Web Sever/HTTP Server	URL static and dynamic response with template.
10	TCP/IP	Security	TLS/SSL	TLS v1.2 (client/server)/SSL v3.0
11	TCP/IP	Security	TLS/SSL	For the supported Cipher Suite, go to SimpleLink Wi-Fi CC3200 SDK.
12	TCP/IP	Sockets	RAW Sockets	User-defined encapsulation at WLAN MAC/PHY or IP layers
13	WLAN	Connection	Policies	Allows management of connection and reconnection policy
14	WLAN	MAC	Promiscuous mode	Filter-based Promiscuous mode frame receiver
15	WLAN	Performance	Initialization time	From enable to first connection to open AP less than 50 ms
16	WLAN	Performance	Throughput	UDP = 16 Mbps
17	WLAN	Performance	Throughput	TCP = 12 Mbps
18	WLAN	Provisioning	WPS2	Enrollee using push button or PIN method.
19	WLAN	Provisioning	AP Config	AP mode for initial product configuration (with configurable Web page and beacon Info element)
20	WLAN	Provisioning	SmartConfig	Alternate method for initial product configuration
21	WLAN	Role	Station	802.11bgn Station with legacy 802.11 power save
22	WLAN	Role	Soft AP	802.11 bg single station with legacy 802.11 power save
23	WLAN	Role	P2P	P2P operation as GO
24	WLAN	Role	P2P	P2P operation as CLIENT
25	WLAN	Security	STA-Personal	WPA2 personal security
26	WLAN	Security	STA-Enterprise	WPA2 enterprise security
27	WLAN	Security	STA-Enterprise	EAP-TLS
28	WLAN	Security	STA-Enterprise	EAP-PEAPv0/TLS
29	WLAN	Security	STA-Enterprise	EAP-PEAPv1/TLS
30	WLAN	Security	STA-Enterprise	EAP-PEAPv0/MSCHAPv2
31	WLAN	Security	STA-Enterprise	EAP-PEAPv1/MSCHAPv2
32	WLAN	Security	STA-Enterprise	EAP-TTLS/EAP-TLS
33	WLAN	Security	STA-Enterprise	EAP-TTLS/MSCHAPv2
34	WLAN	Security	AP-Personal	WPA2 personal security



5.6 Power-Management Subsystem

The CC3200 power-management subsystem contains DC-DC converters to accommodate the differing voltage or current requirements of the system.

- Digital DC-DC
 - Input: VBAT wide voltage (2.1 to 3.6 V) or preregulated 1.85 V
- ANA1 DC-DC
 - Input: VBAT wide voltage (2.1 to 3.6 V)
 - In preregulated 1.85-V mode, the ANA1 DC-DC converter is bypassed.
- PA DC-DC
 - Input: VBAT wide voltage (2.1 to 3.6 V)
 - In preregulated 1.85-V mode, the PA DC-DC converter is bypassed.

In preregulated 1.85-V mode, the ANA1 DC-DC and PA DC-DC converters are bypassed. The CC3200 device is a single-chip WLAN radio solution used on an embedded system with a wide-voltage supply range. The internal power management, including DC-DC converters and LDOs, generates all of the voltages required for the device to operate from a wide variety of input sources. For maximum flexibility, the device can operate in the modes described in the following sections.

5.6.1 VBAT Wide-Voltage Connection

In the wide-voltage battery connection, the device is powered directly by the battery or preregulated 3.3-V supply. All other voltages required to operate the device are generated internally by the DC-DC converters. This scheme is the most common mode for the device as it supports wide-voltage operation from 2.1 to 3.6 V (for electrical connections, see Section 6.1.1, *Typical Application – CC3200 Wide-Voltage Mode*).

5.6.2 Preregulated 1.85 V

The preregulated 1.85-V mode of operation applies an external regulated 1.85 V directly at the pins 10, 25, 33, 36, 37, 39, 44, 48, and 54 of the device. The VBAT and the VIO are also connected to the 1.85-V supply. This mode provides the lowest BOM count version in which inductors used for PA DC-DC and ANA1 DC-DC (2.2 and 1 μ H) and a capacitor (22 μ F) can be avoided. For electrical connections, see Section 6.1.2, Typical Application – CC3200 Preregulated 1.85-V Mode.

In the preregulated 1.85-V mode, the regulator providing the 1.85 V must have the following characteristics:

- Load current capacity ≥900 mA.
- Line and load regulation with <2% ripple with 500 mA step current and settling time of <4 µs with the load step.
- The regulator must be placed very close to the CC3200 device so that the IR drop to the device is very low.

5.7 Low-Power Operating Mode

From a power-management perspective, the CC3200 device comprises the following two independent subsystems:

- Cortex-M4 application processor subsystem
- Networking subsystem

Each subsystem operates in one of several power states.

The Cortex-M4 application processor runs the user application loaded from an external serial flash. The networking subsystem runs preprogrammed TCP/IP and Wi-Fi data link layer functions.

The user program controls the power state of the application processor subsystem and can be in one of the five modes described in Table 5-2.



NOTE

Table 5-2 lists the modes by power consumption, with highest power modes listed first.

Table 5-2. User Program Modes

Application Processor (MCU) Mode	Description
MCU active mode	MCU executing code at 80-MHz state rate
MCU sleep mode	The MCU clocks are gated off in sleep mode and the entire state of the device is retained. Sleep mode offers instant wakeup. The MCU can be configured to wake up by an internal fast timer or by activity from any GPIO line or peripheral.
MCU LPDS mode	State information is lost and only certain MCU-specific register configurations are retained. The MCU can wake up from external events or by using an internal timer. (The wake-up time is less than 3 ms.) Certain parts of memory can be retained while the MCU is in LPDS mode. The amount of memory retained is configurable. Users can choose to preserve code and the MCU-specific setting. The MCU can be configured to wake up using the RTC timer or by an external event on a GPIO (GPIO0–GPIO6).
MCU hibernate mode	The lowest power mode in which all digital logic is power-gated. Only a small section of the logic directly powered by the input supply is retained. The real-time clock (RTC) clock keeps running and the MCU supports wakeup from an external event or from an RTC timer expiry. Wake-up time is longer than LPDS mode at about 15 ms plus the time to load the application from serial flash, which varies according to code size. In this mode, the MCU can be configured to wake up using the RTC timer or external event on a GPIO (GPIO0–GPIO6).

The NWP can be active or in LPDS mode and takes care of its own mode transitions. When there is no network activity, the NWP sleeps most of the time and wakes up only for beacon reception.

Table 5-3. Networking Subsystem Modes

Network Processor Mode	Description
Network active mode processing layer 3, 2, and 1	Transmitting or receiving IP protocol packets
Network active mode (processing layer 2 and 1)	Transmitting or receiving MAC management frames; IP processing not required.
Network active listen mode	Special power optimized active mode for receiving beacon frames (no other frames supported)
Network connected Idle	A composite mode that implements 802.11 infrastructure power save operation. The CC3200R network processor automatically goes into LPDS mode between beacons and then wakes to active listen mode to receive a beacon and determine if there is pending traffic at the access point. If not, the network processor returns to LPDS mode and the cycle repeats.
Network LPDS mode	Low-power state between beacons in which the state is retained by the network processor, allowing for a rapid wake up.
Network disabled	

The operation of the application and network processor ensures that the device remains in the lowest power mode most of the time to preserve battery life. Table 5-4 summarizes the important CC3200 chip-level power modes.

Table 5-4. Important Chip-Level Power Modes

Power States for Applications MCU and Network Processor	Network Processor Active Mode (Transmit, Receive, or Listen)	Network Processor LPDS Mode	Network Processor Disabled
MCU active mode	Chip = active (C)	Chip = active	Chip = active
MCU LPDS mode	Chip = active (A)	Chip = LPDS (B)	Chip = LPDS
MCU hibernate mode	Not supported because chip is hibernated by MCU; thus, network processor cannot be in active mode	Not supported because chip is hibernated by MCU; thus, network processor cannot be in LPDS mode	Chip = hibernate (D)



The following examples show the use of the power modes in applications:

- A product that is continuously connected to the network in the 802.11 infrastructure power-save mode but sends and receives little data spends most of the time in connected idle, which is a composite of modes A (receiving a beacon frame) and B (waiting for the next beacon).
- A product that is not continuously connected to the network but instead wakes up periodically (for example, every 10 minutes) to send data spends most of the time in mode D (hibernate), jumping briefly to mode C (active) to transmit data.

5.8 Memory

5.8.1 External Memory Requirements

The CC3200 device maintains a proprietary file system on the SFLASH. The CC3200 file system stores the service pack file, system files, configuration files, certificate files, web page files, and user files. By using a format command through the API, users can provide the total size allocated for the file system. The starting address of the file system cannot be set and is always located at the beginning of the SFLASH. The applications microcontroller must access the SFLASH memory area allocated to the file system directly through the CC3200 file system. The applications microcontroller must not access the SFLASH memory area directly.

The file system manages the allocation of SFLASH blocks for stored files according to download order, which means that the location of a specific file is not fixed in all systems. Files are stored on SFLASH using human-readable file names rather than file IDs. The file system API works using plain text, and file encryption and decryption is invisible to the user. Encrypted files can be accessed only through the file system (see Figure 5-2).

All file types can have a maximum of 128 supported files in the file system. All files are stored in blocks of 4KB and thus use a minimum of 4KB of flash space. Encrypted files with fail-safe support and optional security are twice the original size and use a minimum of 8KB. Encrypted files are counted as fail safe in terms of space. The maximum file size is 16MB.

Table 5-5 lists the SFLASH size recommendations.

Table 5-5. CC3200 SFLASH Size Recommendations

Item	Typical Fail-Safe	Typical NonFail-Safe
File system	20KB	20KB
Service pack	224KB	112KB
System and configuration files	216KB	108KB
MCU code	512KB	256KB
Total	4Mb	2Mb
Recommended	16Mb	8Mb

The CC3200 device supports JEDEC specification SFDP (serial flash device parameters). The following SFLASH devices are verified for functionality with the CC3200 device in addition to the ones in the reference design:

Micron (N25Q128-A13BSE40): 128Mb

Spansion (S25FL208K): 8Mb
 Winbond (W25Q16V): 16Mb
 Adesto (AT25DF081A): 8Mb

Macronix (MX25L12835F-M2): 128Mb

For compatibility with the CC3200 device, the SFLASH device must support the following commands:

- Command 0x9F (read the device ID [JEDEC]). Procedure: SEND 0x9F, READ 3 bytes.
- Command 0x05 (read the status of the SFLASH). Procedure: SEND 0x05, READ 1 byte. Assume bit 0 is busy and bit 1 is write enable.



- Command 0x06 (set write enable). Procedure: SEND 0x06, read status until write-enable bit is set.
- Command 0xC7 (chip erase). Procedure: SEND 0xC7, read status until busy bit is cleared.
- Command 0x03 (read data). Procedure: SEND 0x03, SEND 24-bit address, read *n* bytes.
- Command 0x02 (write page). Procedure: SEND 0x02, SEND 24-bit address, write n bytes (0<n<256).
- Command 0x20 (sector erase). Procedure: SEND 0x20, SEND 24-bit address, read status until busy bit is cleared. Sector size is assumed to be always 4K.

5.8.2 Internal Memory

The CC3200 device includes on-chip SRAM to which application programs are downloaded and executed. The application developer must share the SRAM for code and data. To select the appropriate SRAM configuration, see the device variants listed in the orderable addendum at the end of this datasheet. The micro direct memory access (µDMA) controller can transfer data to and from SRAM and various peripherals. The CC3200 ROM holds the rich set of peripheral drivers, which saves SRAM space. For more information on drivers, see the CC3200 API list.

5.8.2.1 SRAM

The CC3200 family provides up to 256KB of zero-wait-state, on-chip SRAM. Internal RAM is capable of selective retention during LPDS mode. This internal SRAM is located at offset 0x2000 0000 of the device memory map.

Use the µDMA controller to transfer data to and from the SRAM.

When the device enters low-power mode, the application developer can choose to retain a section of memory based on need. Retaining the memory during low-power mode provides a faster wakeup. The application developer can choose the amount of memory to retain in multiples of 64KB. For more information, see the API guide.

5.8.2.2 ROM

The internal zero-wait-state ROM of the CC3200 device is at address 0x0000 0000 of the device memory and programmed with the following components:

- Bootloader
- · Peripheral driver library (DriverLib) release for product-specific peripherals and interfaces

The bootloader is used as an initial program loader (when the serial flash memory is empty). The CC3200 DriverLib software library controls on-chip peripherals with a bootloader capability. The library performs peripheral initialization and control functions, with a choice of polled or interrupt-driven peripheral support. The DriverLib APIs in ROM can be called by applications to reduce flash memory requirements and free the flash memory to be used for other purposes.

5.8.2.3 Memory Map

Table 5-6 describes the various MCU peripherals and how they are mapped to the processor memory. For more information on peripherals, see the API document.

Table 5-6. Memory Map

Start Address	End Address	Description	Comment
0x0000 0000	0x0007 FFFF	On-chip ROM (Bootloader + DriverLib)	
0x2000 0000	0x2003 FFFF	Bit-banded on-chip SRAM	
0x2200 0000	0x23FF FFFF	Bit-band alias of 0x2000 0000 through 0x200F FFFF	
0x4000 0000	0x4000 0FFF	Watchdog timer A0	
0x4000 4000	0x4000 4FFF	GPIO port A0	
0x4000 5000	0x4000 5FFF	GPIO port A1	
0x4000 6000	0x4000 6FFF	GPIO port A2	



Table 5-6. Memory Map (continued)

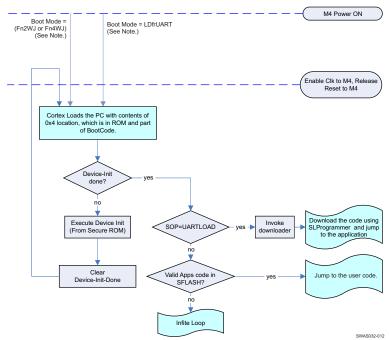
Start Address	End Address	Description	Comment
0x4000 7000	0x4000 7FFF	GPIO port A3	
0x4000 C000	0x4000 CFFF	UART A0	
0x4000 D000	0x4000 DFFF	UART A1	
0x4002 0000	0x400 07FF	I ² C A0 (Master)	
0x4002 0800	0x4002 0FFF	I ² C A0 (Slave)	
0x4003 0000	0x4003 0FFF	General-purpose timer A0	
0x4003 1000	0x4003 1FFF	General-purpose timer A1	
0x4003 2000	0x4003 2FFF	General-purpose timer A2	
0x4003 3000	0x4003 3FFF	General-purpose timer A3	
0x400F 7000	0x400F 7FFF	Configuration registers	
0x400F E000	0x400F EFFF	System control	
0x400F F000	0x400F FFFF	μDMA	
0x4200 0000	0x43FF FFFF	Bit band alias of 0x4000.0000 through 0x400F.FFFF	
0x4401 C000	0x4401 EFFF	McASP	
0x4402 0000	0x4402 0FFF	SSPI	Used for external serial flash
0x4402 1000	0x4402 2FFF	GSPI	Used by application processor
0x4402 5000	0x4402 5FFF	MCU reset clock manager	
0x4402 6000	0x4402 6FFF	MCU configuration space	
0x4402 D000	0x4402 DFFF	Global power, reset, and clock manager (GPRCM)	
0x4402 E000	0x4402 EFFF	MCU shared configuration	
0x4402 F000	0x4402 FFFF	Hibernate configuration	
0x4403 0000	0x4403 FFFF	Crypto range (includes apertures for all crypto-related blocks as follows)	
0x4403 0000	0x4403 0FFF	DTHE registers and TCP checksum	
0x4403 5000	0x4403 5FFF	MD5/SHA	
0x4403 7000	0x4403 7FFF	AES	
0x4403 9000	0x4403 9FFF	DES	
0xE000 0000	0xE000 0FFF	Instrumentation trace Macrocell™	
0xE000 1000	0xE000 1FFF	Data watchpoint and trace (DWT)	
0xE000 2000	0xE000 2FFF	Flash patch and breakpoint (FPB)	
0xE000 E000	0xE000 EFFF	Nested vectored interrupt controller (NVIC)	
0xE004 0000	0xE004 0FFF	Trace port interface unit (TPIU)	
0xE004 1000	0xE004 1FFF	Reserved for embedded trace macrocell (ETM)	
0xE004 2000	0xE00F FFFF	Reserved	

5.9 Boot Modes

5.9.1 Overview

The boot process of the application processor includes two phases. The first phase consists of unrestricted access to all register space and configuration of the specific device setting. In the second phase, the application processor executes user-specific code.

Figure 5-3 shows the bootloader flow chart.



Note: For definitions of the SoP mode functional configurations, see Table 5-7.

Figure 5-3. Bootloader Flow Chart

5.9.2 Invocation Sequence/Boot Mode Selection

The following sequence of events occur during the Cortex processor boot:

- 1. After power-on-reset (POR), the processor starts execution.
- 2. The processor jumps to the first few lines (FFL) of code in the ROM to determine if the current boot is the first device-init boot or the second MCU boot. The determination is based on the Device-Init flag in a secure register. The Device-Init flag is set out of POR. The registers in the secure region are accessible only in the device-init mode.
- 3. If the current boot is the first boot, the processor executes the device-init code from ROM.
- 4. At the end of the boot, the processor clears the Device-Init flag and changes the master ID of the processor and the DMA. These registers are part of the secure region.
- 5. The processor resets itself, initiating a second boot.
- 6. During the second boot, the processor rereads the Device-Init flag, the bit is cleared, and the processor obtains a different master ID.
- 7. After executing FFL and the unsecure boot code, the processor jumps to the developer code (application).
- 8. For the rest of the operation (until the next power cycle), the Cortex mode is designated the MCU. During this phase, access to the secure region is restricted.

5.9.3 Boot Mode List

The CC3200 device implements a sense-on-power (SoP) scheme to determine the device operation mode. The device can be configured to power up in one of the three following modes:

- Fn4WJ: Functional mode with a 4-wire JTAG mapped to fixed pins.
- Fn2WJ: Functional mode with a 2-wire SWD mapped to fixed pins.
- LDfrUART: UART load mode to flash the system during development and in OEM assembly line (for example, serial flash connected to the CC3200R device).



SoP values are sensed from the device pin during power up. This encoding determines the boot flow. Before the device is taken out of reset, the SoP values are copied to a register and then determine the device opeartion mode while powering up. These values determine the boot flow as well as the default mapping for some of the pins (JTAG, SWD, UARTO) Table 5-7 show the pull configurations.

Table 5-7. CC32x0 Functional Configurations

Name	SoP[2]	SoP[1]	SoP[0]	SoP Mode	Comment
UARTLOAD	Pullup	Pulldown	Pulldown	LDfrUART	Factory/Lab Flash/SRAM load through UART. Device waits indefinitely for UART to load code. The SOP bits then must be toggled to configure the device in functional mode. Also puts JTAG in 4-wire mode.
FUNCTIONAL_ 2WJ	Pulldown	Pulldown	Pullup	Fn2WJ	Functional development mode. In this mode, two- pin SWD is available to the developer. TMS and TCK are available for debugger connection.
FUNCTIONAL_ 4WJ	Pulldown	Pulldown	Pulldown	Fn4WJ	Functional development mode. In this mode, four- pin JTAG is available to the developer. TDI, TMS, TCK, and TDO are available for debugger connection.

The recommended value of pull resistors for SOP0 and SOP1 is 100 k Ω and 2.7 k Ω for SOP2. SOP2 can be used by the application for other functions after chip power-up is complete. However, to avoid spurious SOP values from being sensed at power-up, TI strongly recommends that the SOP2 pin be used only for output signals. On the other hand, the SOP0 and SOP1 pins are multiplexed with WLAN analog test pins and are not available for other functions.



6 Applications and Implementation

6.1 Application Information

6.1.1 Typical Application – CC3200 Wide-Voltage Mode

Figure 6-1 shows the schematics for an application using the CC3200 wide-voltage mode.

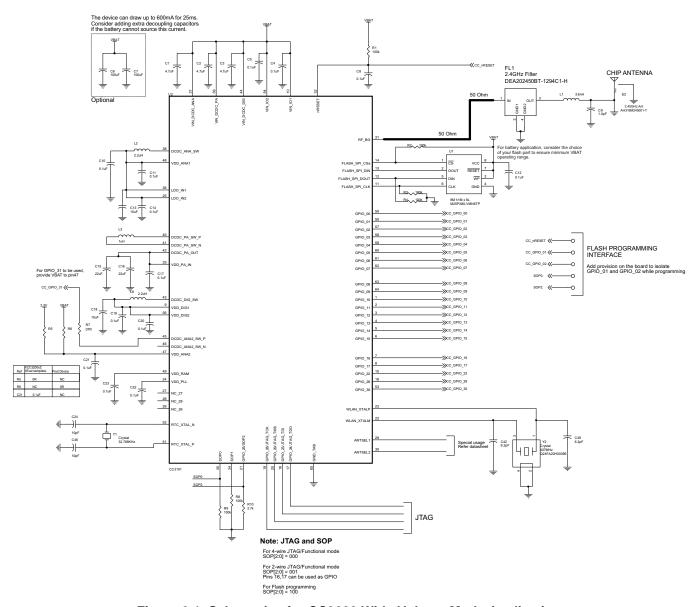


Figure 6-1. Schematics for CC3200 Wide-Voltage Mode Application



Table 6-1 lists the bill of materials for an application using the CC3200 wide-voltage mode.

Table 6-1. Bill of Materials for CC3200 Wide-Voltage Mode Application

Item	Qty	Part Reference	Value	Manufacturer	Part Number	Description
1	3	C1 C2 C3	4.7 µF	Samsung Electro- Mechanics America, Inc	CL05A475MQ5NRNC	Capacitor, Ceramic: 4.7 µF 6.3 V 20% X5R 0402
2	13	C4 C5 C8 C11 C12 C13 C14 C17 C19 C20 C21 C22 C23	0.1 μF	Taiyo Yuden	LMK105BJ104KV-F	Capacitor, Ceramic: 0.1 μF 10 V 10% X5R 0402
3	1	C9	1.0 pF	Murata Electronics North America	GJM1555C1H1R0BB01D	Capacitor, Ceramic: 1 pF 50 V NP0 0402
4	2	C10 C18	10 μF	Murata Electronics North America	GRM188R60J106ME47D	Capacitor, Ceramic: 10 µF 6.3 V 20% X5R 0603
5	2	C15 C16	22 μF	Taiyo Yuden	AMK107BBJ226MAHT	Capacitor, Ceramic: 22 µF 4 V 20% X5R 0603
6	2	C24 C46	10 pF	Murata Electronics North America	GRM1555C1H100FA01D	Capacitor, Ceramic: 10 pF 50 V 1% NP0 0402
7	2	C42 C49	6.2 pF	Murata Electronics North America	GRM1555C1H6R2BA01D	Capacitor, Ceramic: 6.2 pF 50 V NP0 0402
8	1	E2	2.4- GHz Ant	Taiyo Yuden	AH316M245001-T	Chip Antenna: 50 Ω Bluetooth WLAN ZigBee [®] WIMAX
9	1	FL1	2.4- GHz Filter	TDK-Epcos	DEA202450BT-1294C1-H	Filter, Bandpass: 2.4 GHz WLAN SMD
10	1	L1	3.6 nH	Murata Electronics North America	LQP15MN3N6B02D	Inductor: 3.6 nH 0.1 nH 0402
11	2	L2 L8	2.2 µH	Murata Electronics North America	LQM2HPN2R2MG0L	Inductor: 2.2 µH 20% 1300 mA 1008
12	1	L3	1 µH	Murata	LQM2HPN1R0MJ0L	Inductor, Power: 1.0 μH 1500 mA 1007
16	1	U1	8M (1M x 8)	Micron Technology Inc	M25PX80-VMN6TP	IC Flash: 8Mb 75 MHz 8SO
17	1	U2	CC3200	Texas Instruments	CC3200R1-M2RTDR	ARM M4 MCU with 802.11bgn WI-FI
18	1	Y1	Crystal	Abracon Corporation	ABS07-32.768KHZ-T	Crystal: 32.768 kHz 12.5 pF SMD
19	1	Y2	Crystal	Epson	Q24FA20H00396	Crystal: 40 MHz 8 pF SMD

Typical Application - CC3200 Preregulated 1.85-V Mode

Figure 6-2 shows the schematics for an application using the CC3200 preregulated 1.85-V mode.

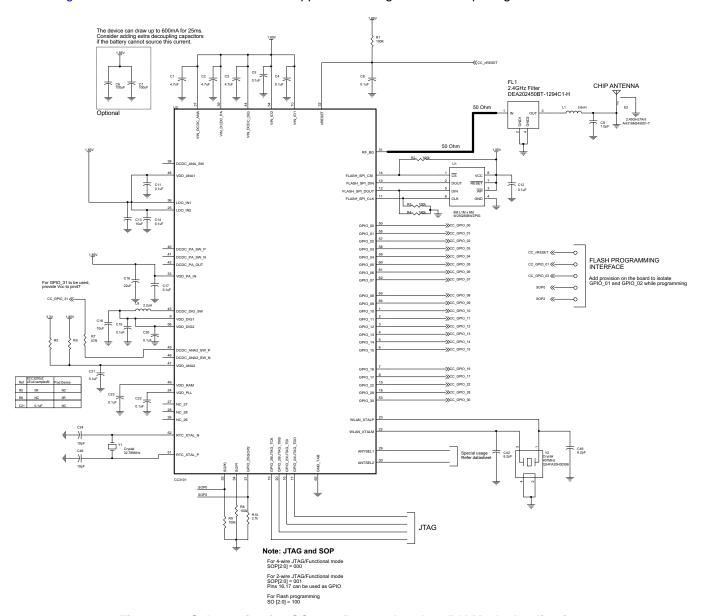


Figure 6-2. Schematics for CC3200 Preregulated 1.85-V Mode Application



Table 6-1 lists the bill of materials for an application using the CC3200 preregulated 1.85-V mode.

Table 6-2. Bill of Materials for CC3200 Preregulated 1.85-V Mode Application

Item	Qty	Part Reference	Value	Manufacturer	Part Number	Description
1	3	C1 C2 C3	4.7 µF	Samsung Electro- Mechanics America, Inc	CL05A475MQ5NRNC	Capacitor, Ceramic: 4.7 µF 6.3 V 20% X5R 0402
2	12	C4 C5 C8 C11 C12 C14 C17 C19 C20 C21 C22 C23	0.1 μF	Taiyo Yuden	LMK105BJ104KV-F	Capacitor, Ceramic: 0.1 µF 10 V 10% X5R 0402
3	1	C9	1.0 pF	Murata Electronics North America	GJM1555C1H1R0BB01D	Capacitor, Ceramic: 1 pF 50 V NP0 0402
4	1	C16	22 µF	Taiyo Yuden	AMK107BBJ226MAHT	Capacitor, Ceramic: µF 4 V 20% X5R 0603
5	2	C13 C18	10 μF	Murata Electronics North America	GRM188R60J106ME47D	Capacitor, Ceramic: 10 µF 6.3 V 20% X5R 0603
6	2	C24 C46	10 pF	Murata Electronics North America	GRM1555C1H100FA01D	Capacitor, Ceramic: 10 pF 50 V 1% NP0 0402
7	2	C42 C49	6.2 pF	Murata Electronics North America	GRM1555C1H6R2BA01D	Capacitor, Ceramic: 6.2 pF 50 V NP0 0402
8	1	E2	2.4- GHz Ant	Taiyo Yuden	AH316M245001-T	Antenna, Chip: 50 Ω Bluetooth WLAN ZigBee WIMAX
9	1	FL1	2.4- GHz Filter	TDK-Epcos	DEA202450BT-1294C1-H	Filter, Bandpass: 2.4 GHz WLAN SMD
10	1	L1	3.6 nH	Murata Electronics North America	LQP15MN3N6B02D	Inductor: 3.6 nH 0.1 nH 0402
11	1	L8	2.2 µH	Murata Electronics North America	LQM2HPN2R2MG0L	Inductor: 2.2 µH 20% 1300 mA 1008
15	1	U1	8M (1M x 8)	Winbond	W25Q80BWZPIG	IC FLASH 8Mb 75 MHz 8WSON
16	1	U2	CC3200	Texas Instruments	CC3200R1-M2RTDR	ARM M4 MCU with 802.11bgn WIFI
17	1	Y1	Crystal	Abracon Corporation	ABS07-32.768KHZ-T	Crystal: 32.768 kHz 12.5 pF SMD
18	1	Y2	Crystal	Epson	Q24FA20H00396	Crystal: 40 MHz 8 pF SMD



7 Device and Documentation Support

7.1 Device Support

7.1.1 Development Support

The CC3200 evaluation board includes a set of tools and documentation to help the user during the development phase.

7.1.1.1 PinMux Tool

The CC3200 device uses pin multiplexing extensively to accommodate the large number of peripheral functions in the smallest possible package. The PinMux tool is a utility used to select the appropriate pin multiplexing configuration that meets the end application requirements. The PinMux tool makes it easy to understand the various pin multiplexing options and enables the best configuration to be chosen without error.

7.1.1.2 Radio Tool

The SimpleLink radio tool is a utility for operating and testing the CC3200 chipset designs during development of the application board. The CC3200 device has an auto-calibrated radio that enables easy connection to the antenna without requiring expertise in radio circuit design.

7.1.1.3 Uniflash Flash Programmer

The Uniflash flash programmer utility allows end users to communicate with the SimpleLink device to update the serial flash. The easy GUI interface enables flashing of files (including read-back verification option), storage format (secured and nonsecured formatting), version reading for boot loader and chip ID, and so on.

7.1.2 Device Nomenclature

To designate the stages in the product development cycle, TI assigns prefixes to the part numbers of the CC3200 device and support tools (see Figure 7-1).

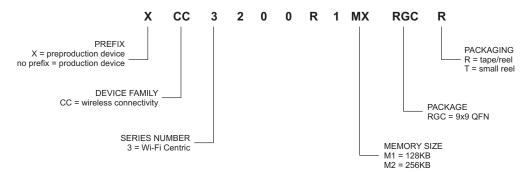


Figure 7-1. CC3200 Device Nomenclature



7.2 Documentation Support

The following documents provide support for the CC3200 device.

SWRU372	CC3200 SimpleLink Wi-Fi and IoT Solution With MCU Launch Pad Getting Started Guide
SWRU367	CC3200 SimpleLink Wi-Fi and IoT Solution With MCU Technical Reference Manual
SWRU369	CC3200 SimpleLink Wi-Fi and IoT Solution With MCU Programmer's Guide
SWRU370	CC3100 and CC3200 SimpleLink Wi-Fi and IoT Solution Layout Guidelines
SWRU372	CC3200 SimpleLink Wi-Fi and IoT Solution With MCU LaunchPad Hardware User Guide
SWRC289	CC3200 SimpleLink Wi-Fi and IoT Solution With MCU Launch Pad Board Design Files

7.3 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's <u>Terms of Use</u>.

TI E2E™ Online Community TI's Engineer-to-Engineer (E2E) Community. Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

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7.5 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

7.6 Glossary

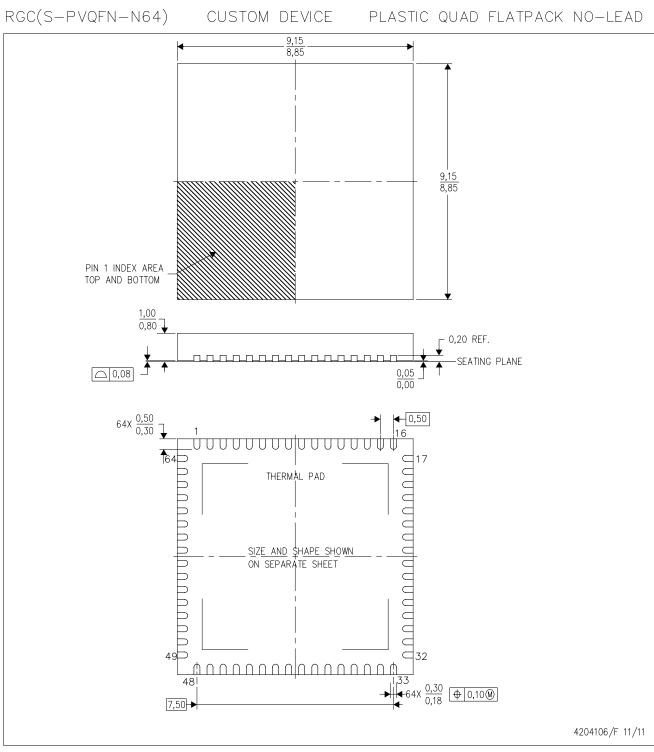
SLYZ022 — TI Glossary.

This glossary lists and explains terms, acronyms, and definitions.

www.ti.com

8 Mechanical Packaging and Orderable Information

The following pages include mechanical packaging and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



- NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5—1994.
 - B. This drawing is subject to change without notice.
 - C. Quad Flatpack, No-leads (QFN) package configuration.
 - D. The package thermal pad must be soldered to the board for thermal and mechanical performance.
 - E. See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.



RGC (S-PVQFN-N64)

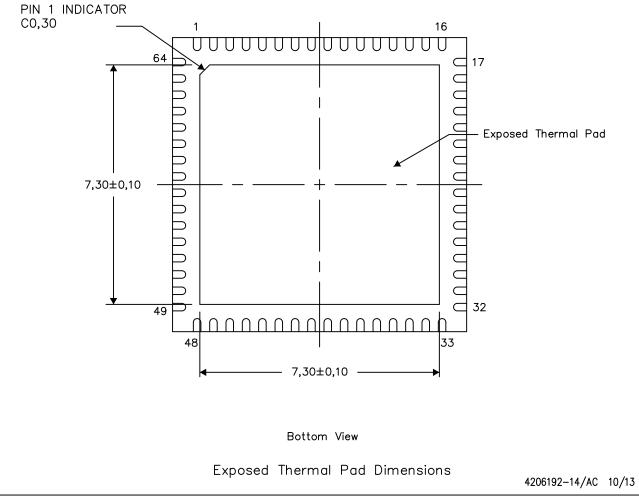
PLASTIC QUAD FLATPACK NO-LEAD

THERMAL INFORMATION

This package incorporates an exposed thermal pad that is designed to be attached directly to an external heatsink. The thermal pad must be soldered directly to the printed circuit board (PCB). After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For information on the Quad Flatpack No—Lead (QFN) package and its advantages, refer to Application Report, QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271. This document is available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.



NOTE: A. All linear dimensions are in millimeters



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