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The address range is $A 20: A-1$ in byte mode (BYTE\#= $V_{I D}$ ) or A20:AO in word mode (BYTE\#= $V_{I H}$ ).

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The address range is A20:A-1 in byte mode (BYTE\#= $V_{I D}$ ) or A20:AO in word mode (BYTE\#= $V_{I H}$ ).

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$L=$ Logic Low $=V_{I L}, H=$ Logic High $=V_{I H}, S A=$ Sector Address, $X=$ Don't care .

The autoselect codes may also be accessed in-system via command sequences. See Table 11.2 on page 38.

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Not 100\% tested.





Refer to the Erase/Program Operations table for $t_{A S}$ and $t_{A H}$ specifications.

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1. Not $100 \%$ tested.
2. See Erase and Programming Performance on page 60 for more information.

3. $P A=$ program address, $P D=$ program data, $D_{\text {OUT }}$ is the true data at the program address.
4. Illustration shows device in word mode.

5. $S A=$ sector address (for Sector Erase), VA = Valid Address for reading status data (see Write Operation Status on page 40).
6. Illustration shows device in word mode.
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VA = Valid address. Illustration shows first status cycle after command sequence, last status read cycle, and array data read cycle.


VA = Valid address; not required for DQ6. Illustration shows first two status cycle after command sequence, last status read cycle, and array data read cycle.
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Not 100\% tested.



For sector protect, $A 6=0, A 1=1, A 0=0$. For sector unprotect, $A 6=1, A 1=1, A 0=0$.

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1. Not $100 \%$ tested.
2. See the Erase and Programming Performance on page 60 section for more information.

3. $P A=$ program address, $P D=$ program data, $D Q 7 \#=$ complement of the data written to the device,$D_{O U T}=$ data written to the device.
4. Figure indicates the last two bus cycles of the command sequence.
5. Word mode address used as an example.
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1. Typical program and erase times assume the following conditions: $25^{\circ} \mathrm{C}, V_{C C}=3.0 \mathrm{~V}, 100,000$ cycles, checkerboard data pattern.
2. Under worst case conditions of $90^{\circ} \mathrm{C}, V_{C C}=2.7 \mathrm{~V}, 1,000,000$ cycles.
3. The typical chip programming time is considerably less than the maximum chip programming time listed, since most bytes program faster than the maximum program times listed.
4. In the pre-programming step of the Embedded Erase algorithm, all bytes are programmed to 00h before erasure.
5. System-level overhead is the time required to execute the two- or four-bus-cycle sequence for the program command. See Table 11.2 for further information on command definitions.
6. The device has a minimum erase and program cycle endurance of 100,000 cycles per sector.
7. At extended temperature range $\left(>+85^{\circ} \mathrm{C}\right)$, typical erase time is 1.75 s and maximum erase time is 25 s .
8. At extended temperature range $\left(>+85^{\circ} \mathrm{C}\right)$, typical erase time is 112 s .

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Sampled, not $100 \%$ tested.
Test conditions $T_{A}=25^{\circ} \mathrm{C}, f=1.0 \mathrm{MHz}$.



* For reference only. BSC is an ANSI standard for Basic Space Centering.



