

# **RF Agile Transceiver**

Data Sheet AD9361

### **FEATURES**

RF  $2 \times 2$  transceiver with integrated 12-bit DACs and ADCs

Band: 70 MHz to 6.0 GHz

**Supports TDD and FDD operation** 

Tunable channel bandwidth: <200 kHz to 56 MHz

Dual receivers: 6 differential or 12 single-ended inputs

Superior receiver sensitivity with a noise figure of 2 dB at

800 MHz local oscillator (LO)

RX gain control

Real-time monitor and control signals for manual gain

Independent automatic gain control Dual transmitters: 4 differential outputs Highly linear broadband transmitter

TX EVM: ≤-40 dB

TX noise: ≤-157 dBm/Hz noise floor

TX monitor: ≥66 dB dynamic range with 1 dB accuracy

Integrated fractional-N synthesizers 2.4 Hz maximum LO step size Multichip synchronization CMOS/LVDS digital interface

#### **APPLICATIONS**

Point to point communication systems Femtocell/picocell/microcell base stations General-purpose radio systems

### **GENERAL DESCRIPTION**

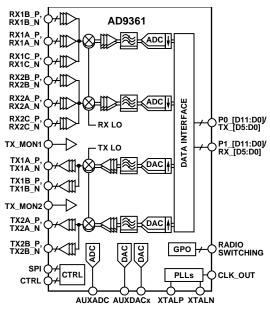
The AD9361 is a high performance, highly integrated radio frequency (RF) Agile Transceiver™ designed for use in 3G and 4G base station applications. Its programmability and wideband capability make it ideal for a broad range of transceiver applications. The device combines a RF front end with a flexible mixed-signal baseband section and integrated frequency synthesizers, simplifying design-in by providing a configurable digital interface to a processor. The AD9361 operates in the 70 MHz to 6.0 GHz range, covering most licensed and unlicensed bands. Channel bandwidths from less than 200 kHz to 56 MHz are supported.

The two independent direct conversion receivers have state-of-theart noise figure and linearity. Each receive (RX) subsystem includes independent automatic gain control (AGC), dc offset correction, quadrature correction, and digital filtering, thereby eliminating the need for these functions in the digital baseband. The AD9361 also has flexible manual gain modes that can be externally controlled. Two high dynamic range ADCs per channel digitize the received I and Q signals and pass them through configurable decimation filters and 128-tap finite impulse response (FIR) filters to produce a 12-bit output signal at the appropriate sample rate.

Rev. E

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### **FUNCTIONAL BLOCK DIAGRAM**



NOTES
1. SPI, CTRL, P0\_[D11:D0]/TX\_[D5:D0], P1\_[D11:D0]/RX\_[D5:D0],
AND RADIO SWITCHING CONTAIN MULTIPLE PINS.

Fiaure 1.

The transmitters use a direct conversion architecture that achieves high modulation accuracy with ultralow noise. This transmitter design produces a best in class TX EVM of <-40 dB, allowing significant system margin for the external PA selection. The on-board transmit (TX) power monitor can be used as a power detector, enabling highly accurate TX power measurements.

The fully integrated phase-locked loops (PLLs) provide low power fractional-N frequency synthesis for all receive and transmit channels. Channel isolation, demanded by frequency division duplex (FDD) systems, is integrated into the design. All VCO and loop filter components are integrated.

The core of the AD9361 can be powered directly from a 1.3 V regulator. The IC is controlled via a standard 4-wire serial port and four real-time I/O control pins. Comprehensive power-down modes are included to minimize power consumption during normal use. The AD9361 is packaged in a  $10 \text{ mm} \times 10 \text{ mm}$ , 144-ball chip scale package ball grid array (CSP\_BGA).

## **AD9361\* Product Page Quick Links**

Last Content Update: 08/30/2016

### Comparable Parts

View a parametric search of comparable parts

### Evaluation Kits <a> □</a>

- AD9361 Software Defined Radio Board (2.4GHz Optimized)
- · AD9361 Wideband Software Defined Radio Board

### Documentation <a>□</a>

### **Data Sheet**

AD9361: RF Agile Transceiver Data Sheet

### **User Guides**

- AD-FMCOMMS3-EBZ Reference Design
- UG-570: AD9361 Reference Manual

### Software and Systems Requirements

• AD-FMCOMMS2-EBZ Reference Design

### Reference Materials

### **Analog Dialogue**

 Highest Power Density, Multirail Power Solution for Space-Constrained Applications

#### Informational

• RadioVerse: Simplify RF System Design.

#### Press

- Analog Devices' Integrated Transceiver and Support Ecosystem Drive Next-Generation Software-Defined Radio Designs
- Analog Devices' Software-defined Radio Transceiver Named a Winner of UBM Tech's Prestigious ACE Award in Wireless/RF Category
- Analog Devices' Software-defined Radio Transceiver Named a Winner of UBM Tech's Prestigious ACE Award in Wireless/RF Category
- First Synchronized RF Transceiver Rapid Prototyping Kit for SDR Launched
- New PLLs Deliver Widest Frequency Range Coverage and Lowest VCO Phase Noise in a Single Device

### **Product Selection Guide**

· RF Source Booklet

### **Solutions Bulletins & Brochures**

• Software-Defined Radio Solutions from Analog Devices

### **Technical Articles**

- A Simple Baseband Processor for RF Transceivers
- Expanding the Role of WiMAX CPE Transceivers into Base Station Applications
- Multiband Military Communications Challenges Overcome by Software-Defined Radio
- Smart Partitioning in WiMAX Radios
- Summarizing Advances in SDR Technology

### **White Papers**

• Smart Partitioning in WiMAX Radios White Paper

### Design Resources <a> □</a>

- AD9361 Material Declaration
- PCN-PDN Information
- · Quality And Reliability
- · Symbols and Footprints

### Discussions <a>□</a>

View all AD9361 EngineerZone Discussions

# Sample and Buy <a> □</a>

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# Technical Support -

Submit a technical question or find your regional support number

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## **SPECIFICATIONS**

 $Electrical\ characteristics\ at\ VDD\_GPO = 3.3\ V,\ VDD\_INTERFACE = 1.8\ V,\ and\ all\ other\ VDDx\ pins = 1.3\ V,\ T_A = 25^{\circ}C,\ unless\ otherwise\ noted.$ 

Table 1.

Parameter <sup>1</sup>	Symbol	Min	Тур	Max	Unit	Test Conditions/ Comments
RECEIVERS, GENERAL						
Center Frequency		70		6000	MHz	
Gain						
Minimum			0		dB	
Maximum			74.5		dB	At 800 MHz
			73.0		dB	At 2300 MHz (RX1A, RX2A)
			72.0		dB	At 2300 MHz (RX1B,
						RX1C, RX2B, RX2C)
			65.5		dB	At 5500 MHz (RX1A, RX2A)
Gain Step			1		dB	
Received Signal Strength Indicator	RSSI					
Range			100		dB	
Accuracy			±2		dB	
RECEIVERS, 800 MHz						
Noise Figure	NF		2		dB	Maximum RX gain
Third-Order Input Intermodulation Intercept Point	IIP3		-18		dBm	Maximum RX gain
Second-Order Input Intermodulation Intercept Point	IIP2		40		dBm	Maximum RX gain
Local Oscillator (LO) Leakage			-122		dBm	At RX front-end input
Quadrature						
Gain Error			0.2		%	
Phase Error			0.2		Degrees	
Modulation Accuracy (EVM)			-42		dB	19.2 MHz reference clock
Input S <sub>11</sub>			-10		dB	
RX1 to RX2 Isolation						
RX1A to RX2A, RX1C to RX2C			70		dB	
RX1B to RX2B			55		dB	
RX2 to RX1 Isolation						
RX2A to RX1A, RX2C to RX1C			70		dB	
RX2B to RX1B			55		dB	
RECEIVERS, 2.4 GHz						
Noise Figure	NF		3		dB	Maximum RX gain
Third-Order Input Intermodulation Intercept Point	IIP3		-14		dBm	Maximum RX gain
Second-Order Input Intermodulation Intercept Point	IIP2		45		dBm	Maximum RX gain
Local Oscillator (LO) Leakage			-110		dBm	At receiver front-end input
Quadrature						
Gain Error			0.2		%	
Phase Error			0.2		Degrees	
Modulation Accuracy (EVM)			-42		dB	40 MHz reference clock
Input S <sub>11</sub>			-10		dB	TO THE LEGICITIES COOK
RX1 to RX2 Isolation			10			
RX1A to RX2A, RX1C to RX2C			65		dB	
RX1B to RX2B			50		dB	
RX2 to RX1 Isolation			50		ub ub	
RX2A to RX1A, RX2C to RX1C			65		dB	
RX2B to RX1B			50		dB	
מאצט נט מא דט	1	İ	JU		ub	

Parameter <sup>1</sup>	Symbol	Min	Тур	Max	Unit	Test Conditions/ Comments
RECEIVERS, 5.5 GHz						
Noise Figure	NF		3.8		dB	Maximum RX gain
Third-Order Input Intermodulation Intercept Point	IIP3		-17		dBm	Maximum RX gain
Second-Order Input Intermodulation Intercept Point	IIP2		42		dBm	Maximum RX gain
Local Oscillator (LO) Leakage			<b>-95</b>		dBm	At RX front-end input
Ouadrature						
Gain Error			0.2		%	
Phase Error			0.2		Degrees	
Modulation Accuracy (EVM)			-37		dB	40 MHz reference clock
modulation / tecaracy (Evin)			3,			(doubled internally for RF synthesizer)
Input S <sub>11</sub>			-10		dB	
RX1A to RX2A Isolation			52		dB	
RX2A to RX1A Isolation			52		dB	
TRANSMITTERS—GENERAL	]					
Center Frequency		70		6000	MHz	
Power Control Range			90		dB	
Power Control Resolution			0.25		dB	
TRANSMITTERS, 800 MHz						
Output S <sub>22</sub>			-10		dB	
Maximum Output Power			8		dBm	1 MHz tone into 50 Ω load
Modulation Accuracy (EVM)			-40		dB	19.2 MHz reference clock
Third-Order Output	OIP3		23		dBm	
Intermodulation Intercept Point	00					
Carrier Leakage			−50 −32		dBc dBc	0 dB attenuation 40 dB attenuation
Noise Floor			-157		dBm/Hz	90 MHz offset
Isolation			137		dbiii/112	JO WINZ ONSEC
TX1 to TX2			50		dB	
TX2 to TX1			50		dB	
TRANSMITTERS, 2.4 GHz			30		GD .	
Output S <sub>22</sub>			-10		dB	
•			-10 7.5		dBm	1 MHz tone into 50 Ω load
Maximum Output Power					dB	
Modulation Accuracy (EVM) Third-Order Output Intermod- ulation Intercept Point	OIP3		-40 19		dBm	40 MHz reference clock
Carrier Leakage			-50		dBc	0 dB attenuation
carrier Leanage			-30 -32		dBc	40 dB attenuation
Noise Floor			-32 -156		dBc/Hz	90 MHz offset
Isolation			150		GDIII/11Z	JO IVII IZ OITSEL
TX1 to TX2			50		dB	
TX2 to TX1			50 50		dB	
TRANSMITTERS, 5.5 GHz	+		JU		ub	
			-10		dB	
Output S <sub>22</sub>			-10 6.5			7 MUz tono into 50 0 lees
Maximum Output Power Modulation Accuracy (EVM)			6.5 –36		dBm dB	7 MHz tone into 50 Ω load 40 MHz reference clock
Modulation Accuracy (EVM)			-30		αв	(doubled internally for RF synthesizer)
Third-Order Output Intermodulation Intercept Point	OIP3		17		dBm	
Carrier Leakage			-50		dBc	0 dB attenuation
			-30		dBc	40 dB attenuation
Noise Floor			-151.5		dBm/Hz	90 MHz offset
Isolation						
TX1 to TX2			50		dB	
	Ī	Ī	50		dB	İ

Parameter <sup>1</sup>	Symbol	Min	Тур	Max	Unit	Test Conditions/ Comments
TX MONITOR INPUTS (TX_MON1, TX_MON2)						
Maximum Input Level			4		dBm	
Dynamic Range			66		dB	
Accuracy			1		dB	
LO SYNTHESIZER			<u>'</u>		GD.	
LO Frequency Step			2.4		Hz	2.4 GHz, 40 MHz
Lo Frequency Step			2.4		112	reference clock
Integrated Phase Noise						
800 MHz			0.13		° rms	100 Hz to 100 MHz,
						30.72 MHz reference clock
						(doubled internally for RF
2.4.611-			0.27		0	synthesizer)
2.4 GHz			0.37		° rms	100 Hz to 100 MHz, 40 MHz reference clock
5.5 GHz			0.59		° rms	100 Hz to 100 MHz,
3.3 GHZ			0.55		11113	40 MHz reference clock
						(doubled internally for RF
						synthesizer)
REFERENCE CLOCK (REF_CLK)						REF_CLK is either the input
						to the XTALP/XTALN pins or a line directly to the
						XTALN pin
Input						7111211
Frequency Range		19		50	MHz	Crystal input
3,100		10		80	MHz	External oscillator
Signal Level			1.3		V p-p	AC-coupled external
. 3						oscillator
AUXILIARY CONVERTERS						
ADC						
Resolution			12		Bits	
Input Voltage						
Minimum			0.05		V	
Maximum			VDDA1P3_BB - 0.05		V	
DAC						
Resolution			10		Bits	
Output Voltage						
Minimum			0.5		V	
Maximum			VDD_GPO - 0.3		V	
Output Current			10		mA	
DIGITAL SPECIFICATIONS (CMOS)						
Logic Inputs						
Input Voltage						
High		VDD_INTERFACE × 0.8		VDD_INTERFACE	V	
Low		0		VDD_INTERFACE × 0.2	V	
Input Current						
High		-10		+10	μΑ	
Low		-10		+10	μΑ	
Logic Outputs						
Output Voltage		VDD INTEREACEO.O.			.,	
High		VDD_INTERFACE × 0.8		VDD INTEREACE V 0.2	V	
DIGITAL SPECIFICATIONS (LVDS)				VDD_INTERFACE × 0.2	V	
DIGITAL SPECIFICATIONS (LVDS)						
Logic Inputs		025		1575	m\/	Each differential input in
Input Voltage Range		825		1575	mV	Each differential input in the pair
Input Differential Voltage		-100		+100	mV	
Threshold				· <del></del>	•	
Receiver Differential Input			100		Ω	
Impedance						

Parameter <sup>1</sup>	Symbol	Min	Тур	Max	Unit	Test Conditions/ Comments
Logic Outputs						
Output Voltage						
High				1375	mV	
Low		1025			mV	
Output Differential Voltage		150			mV	Programmable in 75 mV steps
Output Offset Voltage			1200		mV	
GENERAL-PURPOSE OUTPUTS						
Output Voltage						
High		VDD_GPO × 0.8			V	
Low				$VDD\_GPO \times 0.2$	V	
Output Current			10		mA	
SPI TIMING						VDD_INTERFACE = 1.8 V
SPI_CLK						
Period	t <sub>CP</sub>	20			ns	
Pulse Width	t <sub>MP</sub>	9			ns	
SPI_ENB Setup to First SPI_CLK Rising Edge	t <sub>sc</sub>	1			ns	
Last SPI_CLK Falling Edge to SPI_ENB Hold	t <sub>HC</sub>	0			ns	
SPI_DI						
Data Input Setup to SPI_CLK	ts	2			ns	
Data Input Hold to SPI_CLK	t <sub>H</sub>	1			ns	
SPI_CLK Rising Edge to Output  Data Delay						
4-Wire Mode	tco	3		8	ns	
3-Wire Mode	tco	3		8	ns	
Bus Turnaround Time, Read	t <sub>HZM</sub>	t <sub>H</sub>		tco (max)	ns	After BBP drives the last address bit
Bus Turnaround Time, Read	t <sub>HZS</sub>	0		$t_{\text{CO (max)}}$	ns	After AD9361 drives the last data bit
DIGITAL DATA TIMING (CMOS), VDD_INTERFACE = 1.8 V						
DATA_CLK Clock Period	t <sub>CP</sub>	16.276			ns	61.44 MHz
DATA_CLK and FB_CLK Pulse Width	t <sub>MP</sub>	45% of t <sub>CP</sub>		55% of $t_{CP}$	ns	
TX Data						TX_FRAME, P0_D, and P1_D
Setup to FB_CLK	t <sub>STX</sub>	1			ns	_
Hold to FB CLK	t <sub>HTX</sub>	0			ns	
DATA_CLK to Data Bus Output Delay	t <sub>DDRX</sub>	0		1.5	ns	
DATA_CLK to RX_FRAME Delay	t <sub>DDDV</sub>	0		1.0	ns	
Pulse Width						
ENABLE	t <sub>ENPW</sub>	t <sub>CP</sub>			ns	
TXNRX	t <sub>TXNRXPW</sub>	t <sub>CP</sub>			ns	FDD independent ENSM mode
TXNRX Setup to ENABLE Bus Turnaround Time	t <sub>TXNRXSU</sub>	0			ns	TDD ENSM mode
Bus Turnaround Time Before RX		2.4				TDD made
	t <sub>RPRE</sub>	2 × t <sub>CP</sub>			ns	TDD mode
After RX	<b>t</b> <sub>RPST</sub>	2 × t <sub>CP</sub>	2		ns F	TDD mode
Capacitive Load			3		pF	
Capacitive Input			3		pF	

TXNRX Setup to ENABLE   Bus Turnaround Time   Before RX   Terms   2 × tcr	Parameter <sup>1</sup>	Symbol	Min	Тур	Max	Unit	Test Conditions/ Comments
DATA_CLK Glock Period   Care   Car							
DATA_CLK and FB_CLK Pulse Width   TX Data   TX_FRAME_PO_D, and Pl_D		$t_{CP}$	16.276			ns	61.44 MHz
TX Data	DATA_CLK and FB_CLK Pulse	-			55% of t <sub>CP</sub>		
Setup to FB, CLK							1
Hold to FB_CLK   Light   Lig	Setup to FB CLK	†сту	1			ns	11_5
DATA_CLK to Data Bus Output Delay Pulse Wirth ENABLE   town Delay Pulse Wirth   town Delay Pulse Puls	• –	-					
DATA_CLK to RX_FRAME Delay Pulse Width ENABLE TXNRX         tovov         0         1.0         ns         FDD independent ENSI mode           TXNRX Setup to ENABLE Bus Turnaround Time Before RX After RX         time: 2 × try         ns         TDD ENSM mode           DGFGAL DATA FIRMS (IVDS) DATA_CLK Clock Period DATA_CLK Clock Period TX DATA_CLK Data Bus Output Delay DATA_CLK Data Bus Output Delay         tox         55% of try         ns         TX_FRAME and TX_D           DATA_CLK Tox RX_FRAME Delay Pulse Width         toxx         0         1.25         ns         TX_FRAME and TX_D           TXNRX Setup to ENABLE Bus Turnaround Time Before RX After RX Capacitive Load Capacitive Load TX DATA_CLK DATA Bus Output Delay         toxx         0.25         1.25         ns         TX_FRAME and TX_D           DATA_CLK Tox RX_FRAME Delay Pulse Width         toxx         0.25         1.25         ns         FDD independent ENSI mode           TXNRX Setup to ENABLE Bus Turnaround Time Before RX After RX tox         1xxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxx	DATA_CLK to Data Bus Output				1.2		
TXNRX	DATA_CLK to RX_FRAME Delay	t <sub>DDDV</sub>	0		1.0	ns	
TXNRX	ENABLE	<b>t</b> enpw	tcp			ns	
Bus Turnaround Time   Before RX   To Defend   Service							FDD independent ENSM mode
Before RX         times         2 x tor         ns         TDD mode           After RX         times         2 x tor         ns         TDD mode           Capacitive Load         3         pF         pF           DIGITAL DATA TIMING (LVDS)         tor         4.069         ns         245.76 MHz           DATA_CLK Clock Period         tor         4.069         ns         245.76 MHz           DATA_CLK And FB_CLK Pulse Width         tor         4.069         ns         ns           Setup to FB_CLK         time         0         ns         ns           DATA_CLK to Data Bus Output Delay         torex         0.25         1.25         ns           DATA_CLK to RX_FRAME Delay Pulse Width         torex         0.25         1.25         ns           ENABLE TXNRX         torex         torex         torex         ns         FDD independent ENS mode           TXNRX Setup to ENABLE Bus Tumaround Time         terex         2 x tor         ns         FDD ENSM mode           Bus Tumaround Time         Before RX         times         2 x tor         ns         ns           Capacitive Load         3         3         pF           Capacitive Input         3         y         y <td>-</td> <td>t<sub>TXNRXSU</sub></td> <td>0</td> <td></td> <td></td> <td>ns</td> <td>TDD ENSM mode</td>	-	t <sub>TXNRXSU</sub>	0			ns	TDD ENSM mode
After RX         t <sub>RST</sub> 2 × t <sub>O</sub> ns         DF         TDD mode           Capacitive Input         3         pF         pF         pF           DIGITAL DATA TIMINING (U/DS)         DATA_CLK Clock Period         t <sub>O</sub> 4.069         ns         245.76 MHz           DATA_CLK and FB_CLK Pulse Width         t <sub>UP</sub> 45% of t <sub>O</sub> 55% of t <sub>O</sub> ns         245.76 MHz           TX Data         Setup to FB_CLK         t <sub>TXT</sub> 1         ns         ns         ns         TX_FRAME and TX_D           Setup to FB_CLK         t <sub>TXT</sub> 1         ns         ns         ns         ns         TX_FRAME and TX_D         TX_FRAME and TX_D         ns		topes	2 × tcn			ns	TDD mode
Capacitive Load         3         pF         pD         pD         pD         pD         pD         pD         pD         pD         pD         ADATA_CLK Not Clock Period         to.000         to.000         TXL_FRAME and TX_D         TXL_FRAME			-				
Capacitive Input   3		URPS1	2 × t(p	2			1DD IIIode
DIGITAL DATA TIMING (LVDS)   DATA_CLK Clock Period   Tupe   45% of tcp   4.069	•						
DATA_CLK Clock Period         tcp         4.069         ns         245.76 MHz           DATA_CLK and FB_CLK Pulse Width         twe         45% of tcp         55% of tcp         ns         245.76 MHz           TX Data         Setup to FB_CLK         tstx         1         ns         ns         ns           Setup to FB_CLK         ttrx         0         ns         ns         ns         ns           DATA_CLK to Data Bus Output Delay         tcp         0.25         1.25         ns         ns         ns         FDD independent ENSI mode           TXNRX         tcp         tcp         ns         FDD independent ENSI mode         ns         FDD independent ENSI mode           TXNRX Setup to ENABLE         tcp         ns         FDD independent ENSI mode         ns         TDD ENSM mode           Bus Turnaround Time         Before RX         tcp         2 × tcp         ns         TDD ENSM mode           SUPPLY CHARACTERISTICS         3         pF         pF         pF           1.3 Walin Supply Voltage         1.267         1.3         1.33         V           VDD_INTERFACE Supply Nominal Settings         1.71         2.625         V           LVDS         1.71         2.625         V				3		pr	
DATA_CLK and FB_CLK Pulse							0.5 74.441
Width TX Data Setup to FB_CLK Hold to FB_CLK Hold to FB_CLK Umx DATA_CLK to Data Bus Output Delay DATA_CLK to Data Bus Output Delay DATA_CLK to RX_FRAME Delay Pulse Width ENABLE TXNRX Umx TXNRX  TXPRAME and TX_D  TX FRAME and TX_D  TXX_FRAME and TX_D  TX_FRAME and TX_D  TX_FX_TX_TX_TX_TX	<del>-</del>						245./6 MHz
Setup to FB_CLK	Width	t <sub>MP</sub>	45% of t <sub>CP</sub>		55% of t <sub>CP</sub>	ns	
Hold to FB_CLK DATA_CLK to Data Bus Output Delay DATA_CLK to RX_FRAME Dela							TX_FRAME and TX_D
DATA_CLK to Data Bus Output Delay Delay DATA_CLK to Data Bus Output Delay Use Width   ENABLE	. –	t <sub>STX</sub>	1			ns	
Delay DATA_CLK to RX_FRAME Delay Pulse Width ENABLE TXNRX txnmxxw tynmxxw txnmxxw txnmxxx txnmxx txn	Hold to FB_CLK	t <sub>HTX</sub>	0			ns	
Pulse Width ENABLE TXNRX  TXNRX  TXNRX by to ENABLE Bus Turnaround Time Before RX After RX Capacitive Load Capacitive Input  SUPPLY CHARACTERISTICS 1.3 V Main Supply Voltage VDD_INTERFACE Supply Nominal Settings VDD_GPO Supply Nominal Setting VDD_GPO Supply Nominal Setting VDD_GPO Tolerance Current Consumption VDDx, Sleep Mode  TXNRX btc tcp tcp tcp tcp tcp tcp tcp tcp tcp t		t <sub>DDRX</sub>	0.25		1.25	ns	
TXNRX	,	t <sub>DDDV</sub>	0.25		1.25	ns	
TXNRX Setup to ENABLE Bus Turnaround Time Before RX After RX Capacitive Load Capacitive Input  SUPPLY CHARACTERISTICS 1.3 V Main Supply Voltage VDD_INTERFACE Supply Nominal Settings CMOS LVDS VDD_INTERFACE Tolerance VDD_GPO Supply Nominal Setting VDD_GPO Supply Nominal Setting VDD_GPO Tolerance Current Consumption VDDx, Sleep Mode  TDD ENSM mode TDD ENSM mode TDD ENSM mode TDD ENSM mode TDD ENSM mode TDD ENSM mode TDD ENSM mode TDD ENSM mode TDD ENSM mode TDD ENSM mode TDD ENSM mode TDD ENSM mode TDD ENSM mode TDD ENSM mode TDD ENSM mode TDD ENSM mode TDD ENSM mode Tole ENSM mode TDD ENSM mode TDD ENSM mode TDD ENSM mode TDD ENSM mode TDD ENSM mode TDD ENSM mode TDD ENSM mode TDD ENSM mode TDD ENSM mode TDD ENSM mode TDD ENSM mode TDD ENSM mode TDD ENSM mode	ENABLE	tenpw	t <sub>CP</sub>			ns	
Bus Turnaround Time Before RX After RX Capacitive Load Capacitive Input SUPPLY CHARACTERISTICS 1.3 V Main Supply Voltage VDD_INTERFACE Supply Nominal Settings CMOS LVDS VDD_INTERFACE Tolerance VDD_GPO Supply Nominal Setting VDD_GPO Tolerance Current Consumption VDDx, Sleep Mode  Tapacitive Load Tapacitive Load Sample Setting Sample Setting Sample Setting Sample Setting Sample	TXNRX	t <sub>TXNRXPW</sub>	t <sub>CP</sub>			ns	FDD independent ENSM mode
Before RX After RX  Capacitive Load Capacitive Input  SUPPLY CHARACTERISTICS 1.3 V Main Supply Voltage VDD_INTERFACE Supply Nominal Settings CMOS LVDS  VDD_INTERFACE Tolerance VDD_GPO Supply Nominal Setting VDD_GPO Tolerance Current Consumption VDDx, Sleep Mode  TRPST  2 × tcp  1 2 × tcp  1 2 × tcp  1 3  3	TXNRX Setup to ENABLE	t <sub>TXNRXSU</sub>	0			ns	TDD ENSM mode
After RX Capacitive Load Capacitive Input  SUPPLY CHARACTERISTICS  1.3 V Main Supply Voltage VDD_INTERFACE Supply Nominal Settings CMOS LVDS VDD_INTERFACE Tolerance  VDD_GPO Supply Nominal Setting VDD_GPO Tolerance  Current Consumption VDDx, Sleep Mode  Tolerance is applicable to any voltage setting  LVDS  Tolerance is applicable to any voltage setting  LVD Tolerance is applicable to any voltage setting  LVD Tolerance is applicable to any voltage setting  LVD Tolerance is applicable to any voltage setting  LVD LVD Tolerance is applicable to any voltage setting  LVD LVD LVD LVD LVD LVD LVD LVD LVD LV							
After RX Capacitive Load Capacitive Input  SUPPLY CHARACTERISTICS  1.3 V Main Supply Voltage VDD_INTERFACE Supply Nominal Settings CMOS LVDS VDD_INTERFACE Tolerance  VDD_GPO Supply Nominal Setting VDD_GPO Tolerance  Current Consumption VDDx, Sleep Mode  Agents	Before RX	t <sub>RPRE</sub>	$2 \times t_{CP}$			ns	
Capacitive Load Capacitive Input  SUPPLY CHARACTERISTICS  1.3 V Main Supply Voltage VDD_INTERFACE Supply Nominal Settings CMOS LVDS VDD_INTERFACE Tolerance  VDD_GPO Supply Nominal Setting VDD_GPO Tolerance  Current Consumption VDDx, Sleep Mode  1.267  1.3  1.3  1.33  V  V  V  V  V  V  V  V  V  V  V  V	After RX					ns	
Capacitive Input     3     pF       SUPPLY CHARACTERISTICS     1.3 V Main Supply Voltage     1.267     1.3     1.33     V       VDD_INTERFACE Supply Nominal Settings     1.14     2.625     V       LVDS     1.71     2.625     V       VDD_INTERFACE Tolerance     -5     +5     %     Tolerance is applicable to any voltage setting       VDD_GPO Supply Nominal Setting     1.3     3.3     V     When unused, must be set to 1.3 V       VDD_GPO Tolerance     -5     +5     %     Tolerance is applicable to any voltage setting       Current Consumption VDDx, Sleep Mode     180     μA     Sum of all input current				3			
SUPPLY CHARACTERISTICS  1.3 V Main Supply Voltage VDD_INTERFACE Supply Nominal Settings CMOS LVDS 1.14 2.625 V VDD_INTERFACE Tolerance VDD_INTERFACE Tolerance  -5 +5 % Tolerance is applicable to any voltage setting VDD_GPO Supply Nominal Setting VDD_GPO Tolerance -5 +5 % Tolerance is applicable to any voltage setting VDD_GPO Tolerance -5 +5 % Tolerance is applicable to any voltage setting VDD_GPO Tolerance -5 +5 % Tolerance is applicable to any voltage setting VDD_GPO Tolerance -5 +5 % Tolerance is applicable to any voltage setting VDD_GPO Tolerance -5 +5 % Tolerance is applicable to any voltage setting							
1.3 V Main Supply Voltage  VDD_INTERFACE Supply Nominal Settings  CMOS LVDS  1.14  2.625  V  VDD_INTERFACE Tolerance  -5  +5  V  When unused, must be set to 1.3 V  VDD_GPO Tolerance  Current Consumption VDDx, Sleep Mode  1.267  1.3  1.3  1.3  1.3  V  V  VDD_GPO Supply Nominal Setting  V  VDD_GPO Tolerance  1.3  1.3  1.3  1.3  1.3  1.3  1.3  1.		1		-		,	
Nominal Settings CMOS LVDS 1.14 2.625 V  VDD_INTERFACE Tolerance -5 +5 Wob_GPO Supply Nominal Setting VDD_GPO Tolerance -5 +5 Wob_GPO Tolerance -5 +5 Wob_GPO Tolerance -5 +5 Wob_GPO Tolerance -5 +5 Wob_GPO Tolerance -5	1.3 V Main Supply Voltage		1.267	1.3	1.33	V	
CMOS1.142.625VLVDS1.712.625VVDD_INTERFACE Tolerance-5+5%Tolerance is applicable to any voltage settingVDD_GPO Supply Nominal Setting1.33.3VWhen unused, must be set to 1.3 VVDD_GPO Tolerance-5+5%Tolerance is applicable to any voltage settingCurrent Consumption VDDx, Sleep Mode180μASum of all input current							
LVDS  1.71  2.625  V  VDD_INTERFACE Tolerance  -5  +5  %  Tolerance is applicable to any voltage setting  VDD_GPO Supply Nominal Setting  VDD_GPO Tolerance  -5  +5  When unused, must be set to 1.3 V  VDD_GPO Tolerance  -5  +5  %  Tolerance is applicable to any voltage setting  VDD_GPO Tolerance  -5  +5  %  Tolerance is applicable to any voltage setting  VDD_GPO Tolerance  Lumber Tolerance is applicable to any voltage setting  VDD_GPO Tolerance  -5  -5  -5  -5  -5  -5  -5  -5  -5  -	<del>-</del>		1.14		2.625	V	
VDD_INTERFACE Tolerance-5+5%Tolerance is applicable to any voltage settingVDD_GPO Supply Nominal Setting1.33.3VWhen unused, must be set to 1.3 VVDD_GPO Tolerance-5+5%Tolerance is applicable to any voltage settingCurrent Consumption 							
VDD_GPO Supply Nominal Setting       1.3       3.3       V       When unused, must be set to 1.3 V         VDD_GPO Tolerance       -5       +5       %       Tolerance is applicable to any voltage setting         Current Consumption VDDx, Sleep Mode       180       μA       Sum of all input current							Tolerance is applicable to any voltage setting
VDD_GPO Tolerance			1.3		3.3	V	When unused, must be
Current Consumption VDDx, Sleep Mode 180 μA Sum of all input current	3		-5		+5	%	Tolerance is applicable
				180		μА	
NULL 13EL 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	VDD_GPO			50		μΑ	No load

<sup>&</sup>lt;sup>1</sup> When referencing a single function of a multifunction pin in the parameters, only the portion of the pin name that is relevant to the specification is listed. For full pin names of multifunction pins, refer to the Pin Configuration and Function Descriptions section.

### CURRENT CONSUMPTION—VDD\_INTERFACE

Table 2. VDD\_INTERFACE = 1.2 V

Parameter	Min Typ Max	Unit	Test Conditions/Comments
SLEEP MODE	45	μΑ	Power applied, device disabled
1RX, 1TX, DDR			
LTE10			
Single Port	2.9	mA	30.72 MHz data clock, CMOS
Dual Port	2.7	mA	15.36 MHz data clock, CMOS
LTE20			
Dual Port	5.2	mA	30.72 MHz data clock, CMOS
2RX, 2TX, DDR			
LTE3			
Dual Port	1.3	mA	7.68 MHz data clock, CMOS
LTE10			
Single Port	4.6	mA	61.44 MHz data clock, CMOS
Dual Port	5.0	mA	30.72 MHz data clock, CMOS
LTE20			
Dual Port	8.2	mA	61.44 MHz data clock, CMOS
GSM			
Dual Port	0.2	mA	1.08 MHz data clock, CMOS
WiMAX 8.75			
Dual Port	3.3	mA	20 MHz data clock, CMOS
WiMAX 10			
Single Port			
TDD RX	0.5	mA	22.4 MHz data clock, CMOS
TDD TX	3.6	mA	22.4 MHz data clock, CMOS
FDD	3.8	mA	44.8 MHz data clock, CMOS
WiMAX 20			
Dual Port			
FDD	6.7	mA	44.8 MHz data clock, CMOS

Table 3. VDD\_INTERFACE = 1.8 V

Parameter	Min Typ	Max Unit	Test Conditions/Comments
SLEEP MODE	84	μΑ	Power applied, device disabled
1RX, 1TX, DDR			
LTE10			
Single Port	4.5	mA	30.72 MHz data clock, CMOS
Dual Port	4.1	mA	15.36 MHz data clock, CMOS
LTE20			
Dual Port	8.0	mA	30.72 MHz data clock, CMOS
2RX, 2TX, DDR			
LTE3			
Dual Port	2.0	mA	7.68 MHz data clock, CMOS
LTE10			
Single Port	8.0	mA	61.44 MHz data clock, CMOS
Dual Port	7.5	mA	30.72 MHz data clock, CMOS
LTE20			
Dual Port	14.0	mA	61.44 MHz data clock, CMOS
GSM			
Dual Port	0.3	mA	1.08 MHz data clock, CMOS
WiMAX 8.75			
Dual Port	5.0	mA	20 MHz data clock, CMOS

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Parameter	Min	Тур	Max	Unit	Test Conditions/Comments
WiMAX 10					
Single Port					
TDD RX		0.7		mA	22.4 MHz data clock, CMOS
TDD TX		5.6		mA	22.4 MHz data clock, CMOS
FDD		6.0		mA	44.8 MHz data clock, CMOS
WiMAX 20					
Dual Port					
FDD		10.7		mA	44.8 MHz data clock, CMOS
P-P56					
75 mV Differential Output		14.0		mA	240 MHz data clock, LVDS
300 mV Differential Output		35.0		mA	240 MHz data clock, LVDS
450 mV Differential Output		47.0		mA	240 MHz data clock, LVDS

Table 4. VDD\_INTERFACE = 2.5 V

Parameter	Min	Тур	Max	Unit	Test Conditions/Comments
SLEEP MODE		150		μΑ	Power applied, device disabled
1RX, 1TX, DDR					
LTE10					
Single Port		6.5		mA	30.72 MHz data clock, CMOS
Dual Port		6.0		mA	15.36 MHz data clock, CMOS
LTE20					
Dual Port		11.5		mA	30.72 MHz data clock, CMOS
2RX, 2TX, DDR					
LTE3					
Dual Port		3.0		mA	7.68 MHz data clock, CMOS
LTE10					
Single Port		11.5		mA	61.44 MHz data clock, CMOS
Dual Port		10.0		mA	30.72 MHz data clock, CMOS
LTE20					
Dual Port		20.0		mA	61.44 MHz data clock, CMOS
GSM					
Dual Port		0.5		mA	1.08 MHz data clock, CMOS
WiMAX 8.75					
Dual Port		7.3		mA	20 MHz data clock, CMOS
WiMAX 10					
Single Port					
TDD RX		1.3		mA	22.4 MHz data clock, CMOS
TDD TX		8.0		mA	22.4 MHz data clock, CMOS
FDD		8.7		mA	44.8 MHz data clock, CMOS
WiMAX 20					
Dual Port					
FDD		15.3		mA	44.8 MHz data clock, CMOS
P-P56					
75 mV Differential Output		26.0		mA	240 MHz data clock, LVDS
300 mV Differential Output		45.0		mA	240 MHz data clock, LVDS
450 mV Differential Output		58.0		mA	240 MHz data clock, LVDS

### CURRENT CONSUMPTION—VDDD1P3\_DIG AND VDDAx (COMBINATION OF ALL 1.3 V SUPPLIES)

Table 5. 800 MHz, TDD Mode

Parameter	Min Typ	Max Unit	Test Conditions/Comments
1RX			
5 MHz Bandwidth	180	mA	Continuous RX
10 MHz Bandwidth	210	mA	Continuous RX
20 MHz Bandwidth	260	mA	Continuous RX
2RX			
5 MHz Bandwidth	265	mA	Continuous RX
10 MHz Bandwidth	315	mA	Continuous RX
20 MHz Bandwidth	405	mA	Continuous RX
1TX			
5 MHz Bandwidth			
7 dBm	340	mA	Continuous TX
–27 dBm	190	mA	Continuous TX
10 MHz Bandwidth			
7 dBm	360	mA	Continuous TX
–27 dBm	220	mA	Continuous TX
20 MHz Bandwidth			
7 dBm	400	mA	Continuous TX
–27 dBm	250	mA	Continuous TX
2TX			
5 MHz Bandwidth			
7 dBm	550	mA	Continuous TX
–27 dBm	260	mA	Continuous TX
10 MHz Bandwidth			
7 dBm	600	mA	Continuous TX
–27 dBm	310	mA	Continuous TX
20 MHz Bandwidth			
7 dBm	660	mA	Continuous TX
–27 dBm	370	mA	Continuous TX

Table 6. TDD Mode, 2.4 GHz

Parameter	Min T	ур Мах	Unit	Test Conditions/Comments
1RX				
5 MHz Bandwidth	1	75	mA	Continuous RX
10 MHz Bandwidth	2	00	mA	Continuous RX
20 MHz Bandwidth	2	40	mA	Continuous RX
2RX				
5 MHz Bandwidth	2	60	mA	Continuous RX
10 MHz Bandwidth	3	05	mA	Continuous RX
20 MHz Bandwidth	3	90	mA	Continuous RX
1TX				
5 MHz Bandwidth				
7 dBm	3	50	mA	Continuous TX
–27 dBm	1	60	mA	Continuous TX
10 MHz Bandwidth				
7 dBm	3	80	mA	Continuous TX
–27 dBm	2	20	mA	Continuous TX
20 MHz Bandwidth				
7 dBm	4	10	mA	Continuous TX
–27 dBm	2	60	mA	Continuous TX
2TX				
5 MHz Bandwidth				
7 dBm	5	80	mA	Continuous TX
–27 dBm	2	80	mA	Continuous TX
10 MHz Bandwidth				
7 dBm	6	35	mA	Continuous TX
–27 dBm	3	330		Continuous TX
20 MHz Bandwidth				
7 dBm	6	90	mA	Continuous TX
–27 dBm	3	90	mA	Continuous TX

Table 7. TDD Mode, 5.5 GHz

Parameter	Min	Тур	Max	Unit	Test Conditions/Comments
1RX					
5 MHz Bandwidth		175		mA	Continuous RX
40 MHz Bandwidth		275		mA	Continuous RX
2RX					
5 MHz Bandwidth		270		mA	Continuous RX
40 MHz Bandwidth		445		mA	Continuous RX
1TX					
5 MHz Bandwidth					
7 dBm		400		mA	Continuous TX
–27 dBm		240		mA	Continuous TX
40 MHz Bandwidth					
7 dBm		490		mA	Continuous TX
–27 dBm		385		mA	Continuous TX
2TX					
5 MHz Bandwidth					
7 dBm		650		mA	Continuous TX
–27 dBm		335		mA	Continuous TX
40 MHz Bandwidth					
7 dBm		820		mA	Continuous TX
–27 dBm		500		mA	Continuous TX

Table 8. FDD Mode, 800 MHz

Parameter	Min Typ	Max	Unit	Test Conditions/Comments
1RX, 1TX				
5 MHz Bandwidth				
7 dBm	490		mA	
−27 dBm	345		mA	
10 MHz Bandwidth				
7 dBm	540		mA	
–27 dBm	395		mA	
20 MHz Bandwidth				
7 dBm	615		mA	
–27 dBm	470		mA	
2RX, 1TX				
5 MHz Bandwidth				
7 dBm	555		mA	
–27 dBm	410		mA	
10 MHz Bandwidth				
7 dBm	625		mA	
–27 dBm	480		mA	
20 MHz Bandwidth				
7 dBm	740		mA	
–27 dBm	600		mA	
1RX, 2TX				
5 MHz Bandwidth				
7 dBm	685		mA	
–27 dBm	395		mA	
10 MHz Bandwidth				
7 dBm	755		mA	
–27 dBm	465		mA	
20 MHz Bandwidth				
7 dBm	850		mA	
–27 dBm	570		mA	
2RX, 2TX				
5 MHz Bandwidth				
7 dBm	790		mA	
–27 dBm	495		mA	
10 MHz Bandwidth				
7 dBm	885		mA	
–27 dBm	590		mA	
20 MHz Bandwidth				
7 dBm	1020		mA	
–27 dBm	730		mA	

Table 9. FDD Mode, 2.4 GHz

Parameter	Min Typ	Max Unit	Test Conditions/Comments
1RX, 1TX			
5 MHz Bandwidth			
7 dBm	500	mA	
–27 dBm	350	mA	
10 MHz Bandwidth			
7 dBm	540	mA	
–27 dBm	390	mA	
20 MHz Bandwidth			
7 dBm	620	mA	
–27 dBm	475	mA	
2RX, 1TX			
5 MHz Bandwidth			
7 dBm	590	mA	
–27 dBm	435	mA	
10 MHz Bandwidth			
7 dBm	660		
–27 dBm	510	mA	
20 MHz Bandwidth			
7 dBm	770	mA	
–27 dBm	620	mA	
1RX, 2TX		mA	
5 MHz Bandwidth			
7 dBm	730	mA	
–27 dBm	425	mA	
10 MHz Bandwidth			
7 dBm	800	mA	
–27dBm	500	mA	
20 MHz Bandwidth			
7 dBm	900	mA	
–27 dBm	600	mA	
2RX, 2TX		mA	
5 MHz Bandwidth			
7 dBm	820		
–27 dBm	515	mA	
10 MHz Bandwidth	3.3		
7 dBm	900	mA	
–27 dBm	595	mA	
20 MHz Bandwidth	3,3		
7 dBm	1050	mA	
–27 dBm	740	mA	

### Table 10. FDD Mode, 5.5 GHz

Parameter	Min	Тур	Max	Unit	Test Conditions/Comments
1RX, 1TX					
5 MHz Bandwidth					
7 dBm		550		mA	
–27 dBm		385		mA	
2RX, 1TX					
5 MHz Bandwidth					
7 dBm		645		mA	
–27 dBm		480		mA	
1RX, 2TX					
5 MHz Bandwidth					
7 dBm		805		mA	
–27 dBm		480		mA	
2RX, 2TX					
5 MHz Bandwidth					
7 dBm		895		mA	
–27 dBm		575		mA	

### **ABSOLUTE MAXIMUM RATINGS**

Table 11.

Tubic II.	
Parameter	Rating
VDDx to VSSx	-0.3 V to +1.4 V
VDD_INTERFACE to VSSx	-0.3 V to +3.0 V
VDD_GPO to VSSx	−0.3 V to +3.9 V
Logic Inputs and Outputs to VSSx	-0.3 V to VDD_INTERFACE + 0.3 V
Input Current to Any Pin Except Supplies	±10 mA
RF Inputs (Peak Power)	2.5 dBm
TX Monitor Input Power (Peak Power)	9 dBm
Package Power Dissipation	$(T_{JMAX} - T_{A})/\theta_{JA}$
Maximum Junction Temperature (T <sub>JMAX</sub> )	110°C
Operating Temperature Range	–40°C to +85°C
Storage Temperature Range	−65°C to +150°C

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

### **REFLOW PROFILE**

The AD9361 reflow profile is in accordance with the JEDEC JESD20 criteria for Pb-free devices. The maximum reflow temperature is 260°C.

### THERMAL RESISTANCE

 $\theta_{JA}$  is specified for the worst-case conditions, that is, a device soldered in a circuit board for surface-mount packages.

**Table 12. Thermal Resistance** 

Package Type	Airflow Velocity (m/sec)	<b>θ</b> <sub>JA</sub> <sup>1, 2</sup>	<b>θ</b> <sub>JC</sub> <sup>1,3</sup>	<b>θ</b> <sub>JB</sub> <sup>1, 4</sup>	Ψ <sub>л</sub> <sup>1,2</sup>	Unit
144-Ball	0	32.3	9.6	20.2	0.27	°C/W
CSP_BGA	1.0	29.6			0.43	°C/W
	2.5	27.8			0.57	°C/W

<sup>&</sup>lt;sup>1</sup> Per JEDEC JESD51-7, plus JEDEC JESD51-5 2S2P test board.

### **ESD CAUTION**



**ESD** (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

 $<sup>^{\</sup>rm 2}$  Per JEDEC JESD51-2 (still air) or JEDEC JESD51-6 (moving air).

 $<sup>^{\</sup>rm 3}$  Per MIL-STD 883, Method 1012.1.

<sup>&</sup>lt;sup>4</sup> Per JEDEC JESD51-8 (still air).

## PIN CONFIGURATION AND FUNCTION DESCRIPTIONS

	1	2	3	4	5	6	7	8	9	10	11	12
Α	RX2A_N	RX2A_P	NC	VSSA	TX_MON2	VSSA	TX2A_N	TX2A_P	TX2B_N	TX2B_P	VDDA1P1_ TX_VCO	TX_EXT_ LO_IN
В	VSSA	VSSA	AUXDAC1	GPO_3	GPO_2	GPO_1	GPO_0	VDD_GPO	VDDA1P3_ TX_LO	VDDA1P3_ TX_VCO_ LDO	TX_VCO_ LDO_OUT	VSSA
С	RX2C_P	VSSA	AUXDAC2	TEST/ ENABLE	CTRL_IN0	CTRL_IN1	VSSA	VSSA	VSSA	VSSA	VSSA	VSSA
D	RX2C_N	VDDA1P3_ RX_RF	VDDA1P3_ RX_TX	CTRL_OUT0	CTRL_IN3	CTRL_IN2	P0_D9/ TX_D4_P	P0_D7/ TX_D3_P	P0_D5/ TX_D2_P	P0_D3/ TX_D1_P	P0_D1/ TX_D0_P	VSSD
E	RX2B_P	VDDA1P3_ RX_LO	VDDA1P3_ TX_LO_ BUFFER	CTRL_OUT1	CTRL_OUT2	CTRL_OUT3	P0_D11/ TX_D5_P	P0_D8/ TX_D4_N	P0_D6/ TX_D3_N	P0_D4/ TX_D2_N	P0_D2/ TX_D1_N	P0_D0/ TX_D0_N
F	RX2B_N	VDDA1P3_ RX_VCO_ LDO	VSSA	CTRL_OUT6	CTRL_OUT5	CTRL_OUT4	VSSD	P0_D10/ TX_D5_N	VSSD	FB_CLK_P	VSSD	VDDD1P3_ DIG
G	RX_EXT_ LO_IN	RX_VCO_ LDO_OUT	VDDA1P1_ RX_VCO	CTRL_OUT7	EN_AGC	ENABLE	RX_ FRAME_N	RX_ FRAME_P	TX_ FRAME_P	FB_CLK_N	DATA_ CLK_P	VSSD
Н	RX1B_P	VSSA	VSSA	TXNRX	SYNC_IN	VSSA	VSSD	P1_D11/ RX_D5_P	TX_ FRAME_N	VSSD	DATA_ CLK_N	VDD_ INTERFACE
J	RX1B_N	VSSA	VDDA1P3_ RX_SYNTH	SPI_DI	SPI_CLK	CLK_OUT	P1_D10/ RX_D5_N	P1_D9/ RX_D4_P	P1_D7/ RX_D3_P	P1_D5/ RX_D2_P	P1_D3/ RX_D1_P	P1_D1/ RX_D0_P
κ	RX1C_P	VSSA	VDDA1P3_ TX_SYNTH	VDDA1P3_ BB	RESETB	SPI_ENB	P1_D8/ RX_D4_N	P1_D6/ RX_D3_N	P1_D4/ RX_D2_N	P1_D2/ RX_D1_N	P1_D0/ RX_D0_N	VSSD
L	RX1C_N	VSSA	VSSA	RBIAS	AUXADC	SPI_DO	VSSA	VSSA	VSSA	VSSA	VSSA	VSSA
М	RX1A_P	RX1A_N	NC	VSSA	TX_MON1	VSSA	TX1A_P	TX1A_N	TX1B_P	TX1B_N	XTALP	XTALN

ANALOG I/O DC POWER DIGITAL I/O GROUND NO CONNECT

Figure 2. Pin Configuration, Top View

**Table 13. Pin Function Descriptions** 

Pin No.	Type <sup>1</sup>	Mnemonic	Description
A1, A2	I	RX2A_N, RX2A_P	Receive Channel 2 Differential Input A. Alternatively, each pin can be used as a single-ended input or combined to make a differential pair. Tie unused pins to ground.
A3, M3	NC	NC	No Connect. Do not connect to these pins.
A4, A6, B1, B2, B12, C2, C7 to C12, F3, H2, H3, H6, J2, K2, L2, L3, L7 to L12, M4, M6	I	VSSA	Analog Ground. Tie these pins directly to the VSSD digital ground on the printed circuit board (one ground plane).
A5	1	TX_MON2	Transmit Channel 2 Power Monitor Input. If this pin is unused, tie it to ground.
A7, A8	0	TX2A_N, TX2A_P	Transmit Channel 2 Differential Output A. Tie unused pins to 1.3 V.
A9, A10	0	TX2B_N, TX2B_P	Transmit Channel 2 Differential Output B. Tie unused pins to 1.3 V.
A11	1	VDDA1P1_TX_VCO	Transmit VCO Supply Input. Connect to B11.
A12	1	TX_EXT_LO_IN	External Transmit LO Input. If this pin is unused, tie it to ground.
B3	0	AUXDAC1	Auxiliary DAC 1 Output.
B4 to B7	0	GPO_3 to GPO_0	3.3 V Capable General-Purpose Outputs.
B8	I	VDD_GPO	2.5 V to 3.3 V Supply for the AUXDAC and General-Purpose Output Pins. When the VDD_GPO supply is not used, this supply must be set to 1.3 V.
B9	1	VDDA1P3_TX_LO	Transmit LO 1.3 V Supply Input.
B10	1	VDDA1P3_TX_VCO_LDO	Transmit VCO LDO 1.3 V Supply Input. Connect to B9.
B11	0	TX_VCO_LDO_OUT	Transmit VCO LDO Output. Connect to A11 and a 1 $\mu F$ bypass capacitor in series with a 1 $\Omega$ resistor to ground.
C1, D1	I	RX2C_P, RX2C_N	Receive Channel 2 Differential Input C. Each pin can be used as a single-ended input or combined to make a differential pair. These inputs experience degraded performance above 3 GHz. Tie unused pins to ground.

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Pin No.	Type <sup>1</sup>	Mnemonic	Description
C3	0	AUXDAC2	Auxiliary DAC 2 Output.
C4	1	TEST/ENABLE	Test Input. Ground this pin for normal operation.
C5, C6, D6, D5	1	CTRL_IN0 to CTRL_IN3	Control Inputs. Used for manual RX gain and TX attenuation control.
D2	1	VDDA1P3_RX_RF	Receiver 1.3 V Supply Input. Connect to D3.
D3	1	VDDA1P3_RX_TX	1.3 V Supply Input.
D4, E4 to E6, F4 to F6, G4	0	CTRL_OUT0, CTRL_OUT1 to CTRL_OUT3, CTRL_OUT6 to CTRL_OUT4, CTRL_OUT7	Control Outputs. These pins are multipurpose outputs that have programmable functionality.
D7	I/O	P0_D9/TX_D4_P	Digital Data Port PO/Transmit Differential Input Bus. This is a dual function pin. As PO_D9, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 0. Alternatively, this pin (TX_D4_P) can function as part of the LVDS 6-bit TX differential input bus with internal LVDS termination.
D8	I/O	P0_D7/TX_D3_P	Digital Data Port PO/Transmit Differential Input Bus. This is a dual function pin. As PO_D7, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 0. Alternatively, this pin (TX_D3_P) can function as part of the LVDS 6-bit TX differential input bus with internal LVDS termination.
D9	I/O	P0_D5/TX_D2_P	Digital Data Port PO/Transmit Differential Input Bus. This is a dual function pin. As PO_D5, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 0. Alternatively, this pin (TX_D2_P) can function as part of the LVDS 6-bit TX differential input bus with internal LVDS termination.
D10	I/O	P0_D3/TX_D1_P	Digital Data Port PO/Transmit Differential Input Bus. This is a dual function pin. As PO_D3, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 0. Alternatively, this pin (TX_D1_P) can function as part of the LVDS 6-bit TX differential input bus with internal LVDS termination.
D11	I/O	P0_D1/TX_D0_P	Digital Data Port PO/Transmit Differential Input Bus. This is a dual function pin. As PO_D1, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 0. Alternatively, this pin (TX_D0_P) can function as part of the LVDS 6-bit TX differential input bus with internal LVDS termination.
D12, F7, F9, F11, G12, H7, H10, K12	I	VSSD	Digital Ground. Tie these pins directly to the VSSA analog ground on the printed circuit board (one ground plane).
E1, F1	I	RX2B_P, RX2B_N	Receive Channel 2 Differential Input B. Each pin can be used as a single-ended input or combined to make a differential pair. These inputs experience degraded performance above 3 GHz. Tie unused pins to ground.
E2	1	VDDA1P3_RX_LO	Receive LO 1.3 V Supply Input.
E3	1	VDDA1P3_TX_LO_BUFFER	1.3 V Supply Input.
E7	I/O	P0_D11/TX_D5_P	Digital Data Port PO/Transmit Differential Input Bus. This is a dual function pin. As PO_D11, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 0. Alternatively, this pin (TX_D5_P) can function as part of the LVDS 6-bit TX differential input bus with internal LVDS termination.
E8	I/O	P0_D8/TX_D4_N	Digital Data Port Po/Transmit Differential Input Bus. This is a dual function pin. As PO_D8, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 0. Alternatively, this pin (TX_D4_N) can function as part of the LVDS 6-bit TX differential input bus with internal LVDS termination.
E9	I/O	P0_D6/TX_D3_N	Digital Data Port PO/Transmit Differential Input Bus. This is a dual function pin. As PO_D6, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 0. Alternatively, this pin (TX_D3_N) can function as part of the LVDS 6-bit TX differential input bus with internal LVDS termination.
E10	I/O	P0_D4/TX_D2_N	Digital Data Port PO/Transmit Differential Input Bus. This is a dual function pin. As PO_D4, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 0. Alternatively, this pin (TX_D2_N) can function as part of the LVDS 6-bit TX differential input bus with internal LVDS termination.
E11	I/O	P0_D2/TX_D1_N	Digital Data Port PO/Transmit Differential Input Bus. This is a dual function pin. As PO_D2, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 0. Alternatively, this pin (TX_D1_N) can function as part of the LVDS 6-bit TX differential input bus with internal LVDS termination.
E12	I/O	P0_D0/TX_D0_N	Digital Data Port PO/Transmit Differential Input Bus. This is a dual function pin. As PO_DO, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 0. Alternatively, this pin (TX_DO_N) can function as part of the LVDS 6-bit TX differential input bus with internal LVDS termination.

Pin No.	Type <sup>1</sup>	Mnemonic	Description
F2	I	VDDA1P3_RX_VCO_LDO	Receive VCO LDO 1.3 V Supply Input. Connect to E2.
F8	I/O	P0_D10/TX_D5_N	Digital Data Port P0/Transmit Differential Input Bus. This is a dual function pin. As P0_D10, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 0. Alternatively, this pin (TX_D5_N) can function as part of the LVDS 6-bit TX differential input bus with internal LVDS termination.
F10, G10	1	FB_CLK_P, FB_CLK_N	Feedback Clock. These pins receive the FB_CLK signal that clocks in TX data. In CMOS mode, use FB_CLK_P as the input and tie FB_CLK_N to ground.
F12	1	VDDD1P3_DIG	1.3 V Digital Supply Input.
G1	1	RX_EXT_LO_IN	External Receive LO Input. If this pin is unused, tie it to ground.
G2	0	RX_VCO_LDO_OUT	Receive VCO LDO Output. Connect this pin directly to G3 and a 1 $\mu$ F bypass capacitor in series with a 1 $\Omega$ resistor to ground.
G3	1	VDDA1P1_RX_VCO	Receive VCO Supply Input. Connect this pin directly to G2 only.
G5	1	EN_AGC	Manual Control Input for Automatic Gain Control (AGC).
G6	1	ENABLE	Control Input. This pin moves the device through various operational states.
G7, G8	0	RX_FRAME_N, RX_FRAME_P	Receive Digital Data Framing Output Signal. These pins transmit the RX_FRAME signal that indicates whether the RX output data is valid. In CMOS mode, use RX_FRAME_P as the output and leave RX_FRAME_N unconnected.
G9, H9	I	TX_FRAME_P, TX_FRAME_N	Transmit Digital Data Framing Input Signal. These pins receive the TX_FRAME signal that indicates when TX data is valid. In CMOS mode, use TX_FRAME_P as the input and tie TX_FRAME_N to ground.
G11, H11	0	DATA_CLK_P, DATA_CLK_N	Receive Data Clock Output. These pins transmit the DATA_CLK signal that is used by the BBP to clock RX data. In CMOS mode, use DATA_CLK_P as the output and leave DATA_CLK_N unconnected.
H1, J1	I	RX1B_P, RX1B_N	Receive Channel 1 Differential Input B. Alternatively, each pin can be used as a single-ended input. These inputs experience degraded performance above 3 GHz. Tie unused pins to ground.
H4	1	TXNRX	Enable State Machine Control Signal. This pin controls the data port bus direction. Logic low selects the RX direction, and logic high selects the TX direction.
H5	1	SYNC_IN	Input to Synchronize Digital Clocks Between Multiple AD9361 Devices. If this pin is unused, tied it to ground.
H8	I/O	P1_D11/RX_D5_P	Digital Data Port P1/Receive Differential Output Bus. This is a dual function pin. As P1_D11, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 1. Alternatively, this pin (RX_D5_P) can function as part of the LVDS 6-bit RX differential output bus with internal LVDS termination.
H12	1	VDD_INTERFACE	1.2 V to 2.5 V Supply for Digital I/O Pins (1.8 V to 2.5 V in LVDS Mode).
J3	1	VDDA1P3_RX_SYNTH	1.3 V Supply Input.
J4	1	SPI_DI	SPI Serial Data Input.
J5	1	SPI_CLK	SPI Clock Input.
J6	0	CLK_OUT	Output Clock. This pin can be configured to output either a buffered version of the external input clock, the DCXO, or a divided-down version of the internal ADC_CLK.
J7	I/O	P1_D10/RX_D5_N	Digital Data Port P1/Receive Differential Output Bus. This is a dual function pin. As P1_D10, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 1. Alternatively, this pin (RX_D5_N) can function as part of the LVDS 6-bit RX differential output bus with internal LVDS termination.
J8	I/O	P1_D9/RX_D4_P	Digital Data Port P1/Receive Differential Output Bus. This is a dual function pin. As P1_D9, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 1. Alternatively, this pin (RX_D4_P) can function as part of the LVDS 6-bit RX differential output bus with internal LVDS termination.
J9	I/O	P1_D7/RX_D3_P	Digital Data Port P1/Receive Differential Output Bus. This is a dual function pin. As P1_D7, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 1. Alternatively, this pin (RX_D3_P) can function as part of the LVDS 6-bit RX differential output bus with internal LVDS termination.
J10	I/O	P1_D5/RX_D2_P	Digital Data Port P1/Receive Differential Output Bus. This is a dual function pin. As P1_D5, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 1. Alternatively, this pin (RX_D2_P) can function as part of the LVDS 6-bit RX differential output bus with internal LVDS termination.

Pin No.	Type <sup>1</sup>	Mnemonic	Description
J11	I/O	P1_D3/RX_D1_P	Digital Data Port P1/Receive Differential Output Bus. This is a dual function pin. As P1_D3, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 1. Alternatively, this pin (RX_D1_P) can function as part of the LVDS 6-bit RX differential output bus with internal LVDS termination.
J12	I/O	P1_D1/RX_D0_P	Digital Data Port P1/Receive Differential Output Bus. This is a dual function pin. As P1_D1, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 1. Alternatively, this pin (RX_D0_P) can function as part of the LVDS 6-bit RX differential output bus with internal LVDS termination.
K1, L1	I	RX1C_P, RX1C_N	Receive Channel 1 Differential Input C. Alternatively, each pin can be used as a single-ended input. These inputs experience degraded performance above 3 GHz. Tie unused pins to ground.
K3	1	VDDA1P3_TX_SYNTH	1.3 V Supply Input.
K4	1	VDDA1P3_BB	1.3 V Supply Input.
K5	1	RESETB	Asynchronous Reset. Logic low resets the device.
K6	1	SPI_ENB	SPI Enable Input. Set this pin to logic low to enable the SPI bus.
K7	I/O	P1_D8/RX_D4_N	Digital Data Port P1/Receive Differential Output Bus. This is a dual function pin. As P1_D8, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 1. Alternatively, this pin (RX_D4_N) can function as part of the LVDS 6-bit RX differential output bus with internal LVDS termination.
K8	I/O	P1_D6/RX_D3_N	Digital Data Port P1/Receive Differential Output Bus. This is a dual function pin. As P1_D6, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 1. Alternatively, this pin (RX_D3_N) can function as part of the LVDS 6-bit RX differential output bus with internal LVDS termination.
K9	I/O	P1_D4/RX_D2_N	Digital Data Port P1/Receive Differential Output Bus. This is a dual function pin. As P1_D4, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 1. Alternatively, this pin (RX_D2_N) can function as part of the LVDS 6-bit RX differential output bus with internal LVDS termination.
K10	I/O	P1_D2/RX_D1_N	Digital Data Port P1/Receive Differential Output Bus. This is a dual function pin. As P1_D2, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 1. Alternatively, this pin (RX_D1_N) can function as part of the LVDS 6-bit RX differential output bus with internal LVDS termination.
K11	I/O	P1_D0/RX_D0_N	Digital Data Port P1/Receive Differential Output Bus. This is a dual function pin. As P1_D0, it functions as part of the 12-bit bidirectional parallel CMOS level Data Port 1. Alternatively, this pin (RX_D0_N) can function as part of the LVDS 6-bit RX differential output bus with internal LVDS termination.
L4	1	RBIAS	Bias Input Reference. Connect this pin through a 14.3 k $\Omega$ (1% tolerance) resistor to ground.
L5	1	AUXADC	Auxiliary ADC Input. If this pin is unused, tie it to ground.
L6	О	SPI_DO	SPI Serial Data Output in 4-Wire Mode, or High-Z in 3-Wire Mode.
M1, M2	1	RX1A_P, RX1A_N	Receive Channel 1 Differential Input A. Alternatively, each pin can be used as a single-ended input. Tie unused pins to ground.
M5	1	TX_MON1	Transmit Channel 1 Power Monitor Input. When this pin is unused, tie it to ground.
M7, M8	0	TX1A_P,TX1A_N	Transmit Channel 1 Differential Output A. Tie unused pins to 1.3 V.
M9, M10	0	TX1B_P, TX1B_N	Transmit Channel 1 Differential Output B. Tie unused pins to 1.3 V.
M11, M12	I	XTALP, XTALN	Reference Frequency Crystal Connections. When a crystal is used, connect it between these two pins. When an external clock source is used, connect it to XTALN and leave XTALP unconnected.

 $<sup>^{\</sup>rm 1}\,\rm I$  is input, O is output, I/O is input/output, or NC is not connected.

### TYPICAL PERFORMANCE CHARACTERISTICS

### **800 MHz FREQUENCY BAND**

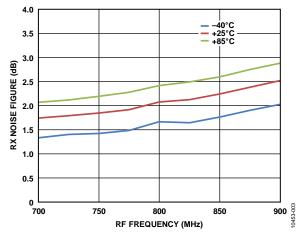


Figure 3. RX Noise Figure vs. RF Frequency

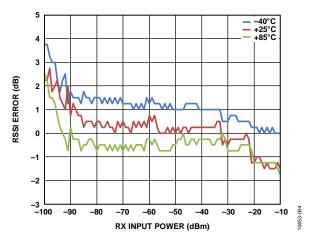


Figure 4. RSSI Error vs. RX Input Power, LTE 10 MHz Modulation (Referenced to -50 dBm Input Power at 800 MHz)

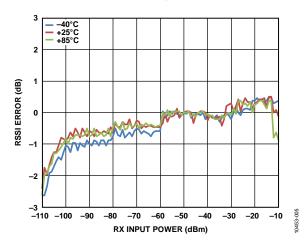


Figure 5. RSSI Error vs. RX Input Power, Edge Modulation (Referenced to -50 dBm Input Power at 800 MHz)

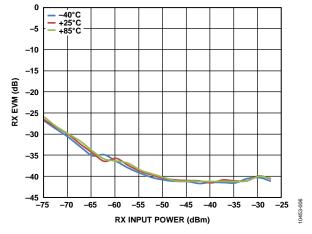


Figure 6. RX EVM vs. RX Input Power, 64 QAM LTE 10 MHz Mode, 19.2 MHz REF\_CLK

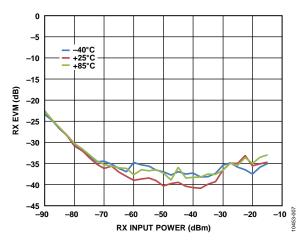


Figure 7. RX EVM vs. RX Input Power, GSM Mode, 30.72 MHz REF\_CLK (Doubled Internally for RF Synthesizer)

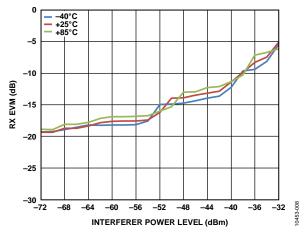


Figure 8. RX EVM vs. Interferer Power Level, LTE 10 MHz Signal of Interest with  $P_{\rm IN}=-82$  dBm, 5 MHz OFDM Blocker at 7.5 MHz Offset

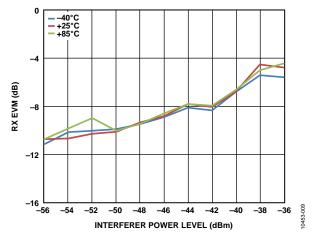


Figure 9. RX EVM vs. Interferer Power Level, LTE 10 MHz Signal of Interest with  $P_{\rm IN}$  = -90 dBm, 5 MHz OFDM Blocker at 17.5 MHz Offset

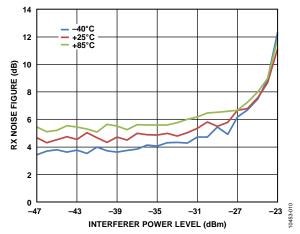


Figure 10. RX Noise Figure vs. Interferer Power Level, Edge Signal of Interest with  $P_{\rm IN} = -90$  dBm, CW Blocker at 3 MHz Offset, Gain Index = 64

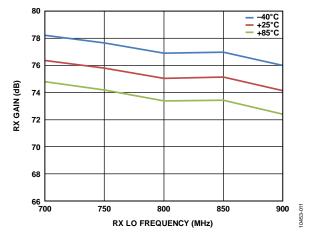


Figure 11. RX Gain vs. RX LO Frequency, Gain Index = 76 (Maximum Setting)

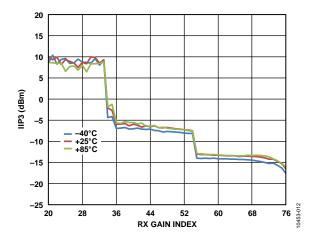


Figure 12. Third-Order Input Intercept Point (IIP3) vs. RX Gain Index, f1 = 1.45 MHz, f2 = 2.89 MHz, GSM Mode

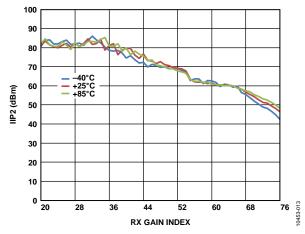


Figure 13. Second-Order Input Intercept Point (IIP2) vs. RX Gain Index, f1 = 2.00 MHz, f2 = 2.01 MHz, GSM Mode

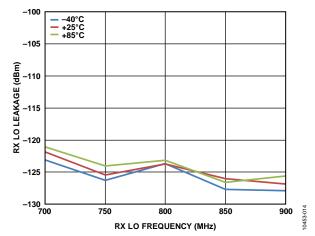


Figure 14. RX Local Oscillator (LO) Leakage vs. RX LO Frequency

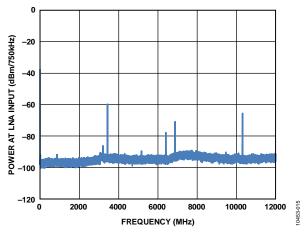


Figure 15. RX Emission at LNA Input, DC to 12 GHz,  $f_{LO\_RX}$  = 800 MHz, LTE 10 MHz,  $f_{LO\_TX}$  = 860 MHz

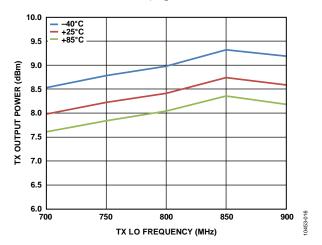


Figure 16. TX Output Power vs. TX LO Frequency, Attenuation Setting = 0 dB, Single Tone Output

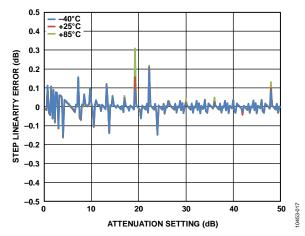


Figure 17. TX Power Control Linearity Error vs. Attenuation Setting

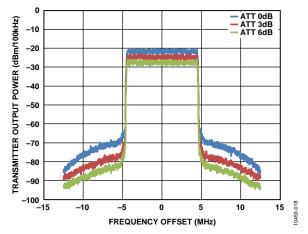


Figure 18. TX Spectrum vs. Frequency Offset from Carrier Frequency,  $f_{LO\_TX}$  = 800 MHz, LTE 10 MHz Downlink (Digital Attenuation Variations Shown)

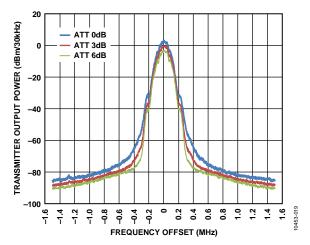


Figure 19. TX Spectrum vs. Frequency Offset from Carrier Frequency,  $f_{10\_TX}$  = 800 MHz, GSM Downlink (Digital Attenuation Variations Shown), 3 MHz Range

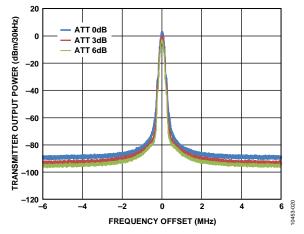


Figure 20. TX Spectrum vs. Frequency Offset from Carrier Frequency,  $f_{\text{LO},TX}$  = 800 MHz, GSM Downlink (Digital Attenuation Variations Shown), 12 MHz Range

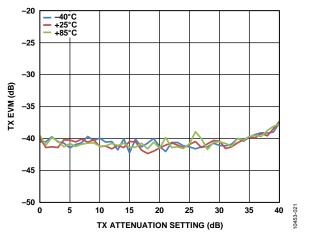


Figure 21. TX EVM vs. TX Attenuation Setting,  $f_{LQ_TX}$  = 800 MHz, LTE 10 MHz, 64 QAM Modulation, 19.2 MHz REF\_CLK

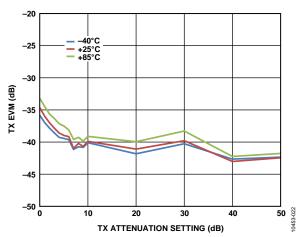


Figure 22. TX EVM vs. TX Attenuation Setting,  $f_{LO\_TX} = 800$  MHz, GSM Modulation, 30.72 MHz REF\_CLK (Doubled Internally for RF Synthesizer)

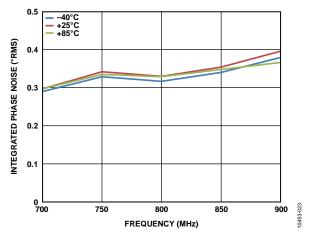


Figure 23. Integrated TX LO Phase Noise vs. Frequency, 19.2 MHz REF\_CLK

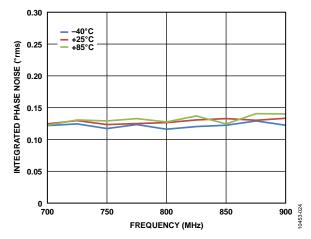


Figure 24. Integrated TX LO Phase Noise vs. Frequency, 30.72 MHz REF\_CLK (Doubled Internally for RF Synthesizer)

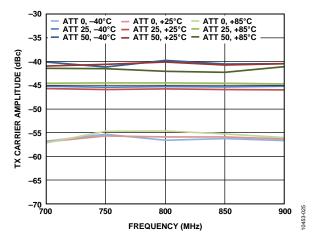


Figure 25. TX Carrier Rejection vs. Frequency

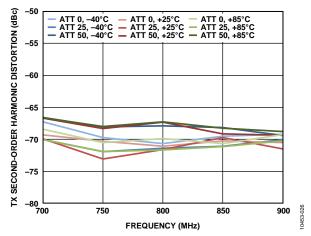


Figure 26. TX Second-Order Harmonic Distortion (HD2) vs. Frequency

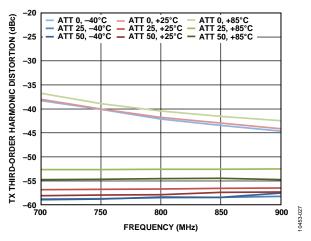


Figure 27. TX Third-Order Harmonic Distortion (HD3) vs. Frequency

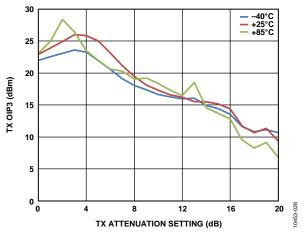


Figure 28. TX Third-Order Output Intercept Point (OIP3) vs. TX Attenuation Setting

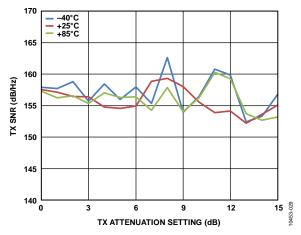


Figure 29. TX Signal-to-Noise Ratio (SNR) vs. TX Attenuation Setting, LTE 10 MHz Signal of Interest with Noise Measured at 90 MHz Offset

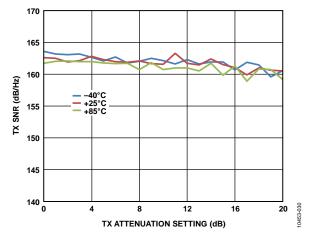


Figure 30. TX Signal-to-Noise Ratio (SNR) vs. TX Attenuation Setting, GSM Signal of Interest with Noise Measured at 20 MHz Offset

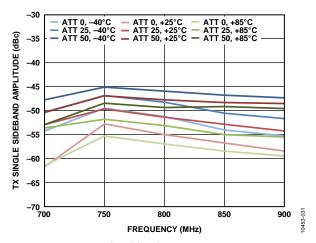


Figure 31. TX Single Sideband (SSB) Rejection vs. Frequency, 1.5375 MHz Offset

### 2.4 GHz FREQUENCY BAND

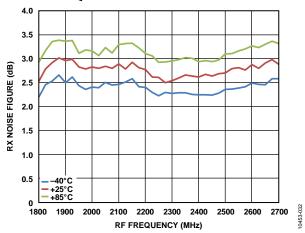


Figure 32. RX Noise Figure vs. RF Frequency

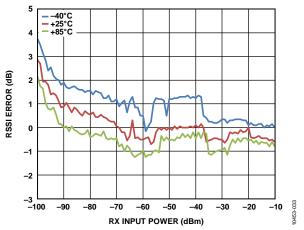


Figure 33. RSSI Error vs. RX Input Power, Referenced to -50 dBm Input Power at 2.4 GHz

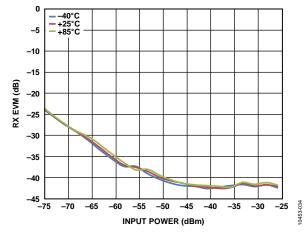


Figure 34. RX EVM vs. Input Power, 64 QAM LTE 20 MHz Mode, 40 MHz REF\_CLK

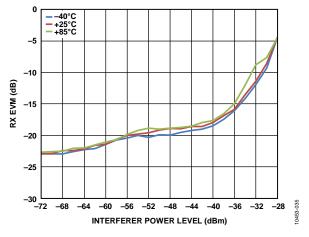


Figure 35. RX EVM vs. Interferer Power Level, LTE 20 MHz Signal of Interest with  $P_{\rm IN} = -75$  dBm, LTE 20 MHz Blocker at 20 MHz Offset

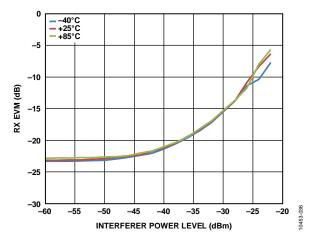


Figure 36. RX EVM vs. Interferer Power Level, LTE 20 MHz Signal of Interest with  $P_{\rm IN} = -75$  dBm, LTE 20 MHz Blocker at 40 MHz Offset

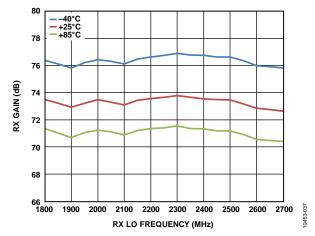


Figure 37. RX Gain vs. RX LO Frequency, Gain Index = 76 (Maximum Setting)

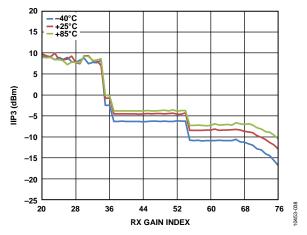


Figure 38. Third-Order Input Intercept Point (IIP3) vs. RX Gain Index, f1 = 30 MHz, f2 = 61 MHz

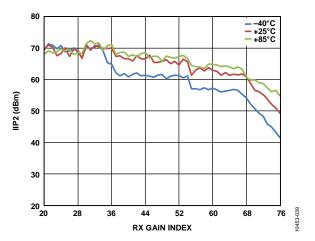


Figure 39. Second-Order Input Intercept Point (IIP2) vs. RX Gain Index, f1=60 MHz, f2=61 MHz

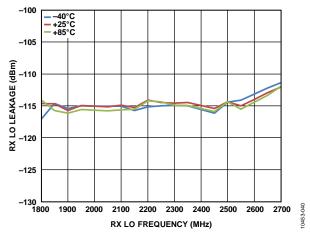


Figure 40. RX Local Oscillator (LO) Leakage vs. RX LO Frequency

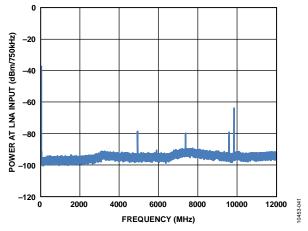


Figure 41. RX Emission at LNA Input, DC to 12 GHz,  $f_{LO\_RX}$  = 2.4 GHz, LTE 20 MHz,  $f_{LO\_TX}$  = 2.46 GHz

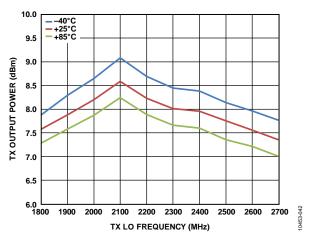


Figure 42. TX Output Power vs. TX LO Frequency, Attenuation Setting = 0 dB, Single Tone Output

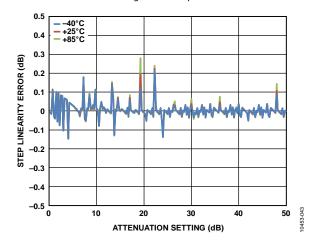


Figure 43. TX Power Control Linearity Error vs. Attenuation Setting

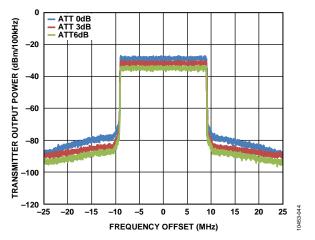


Figure 44. TX Spectrum vs. Frequency Offset from Carrier Frequency,  $f_{LO\_TX} = 2.3$  GHz, LTE 20 MHz Downlink (Digital Attenuation Variations Shown)

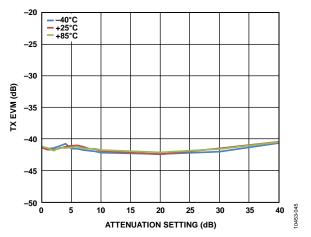


Figure 45. TX EVM vs. Transmitter Attenuation Setting, 40 MHz REF\_CLK, LTE 20 MHz, 64 QAM Modulation

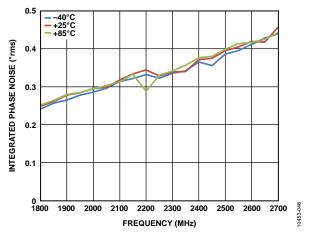


Figure 46. Integrated TX LO Phase Noise vs. Frequency, 40 MHz REF\_CLK

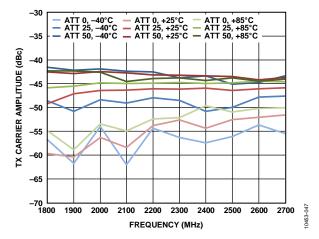


Figure 47. TX Carrier Rejection vs. Frequency

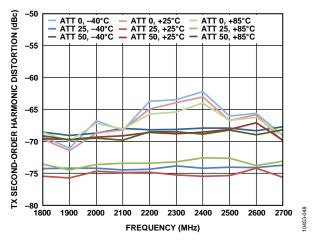


Figure 48. TX Second-Order Harmonic Distortion (HD2) vs. Frequency

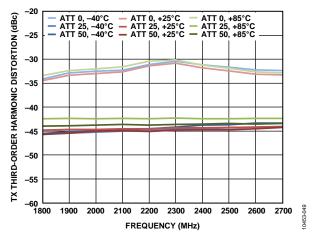


Figure 49. TX Third-Order Harmonic Distortion (HD3) vs. Frequency

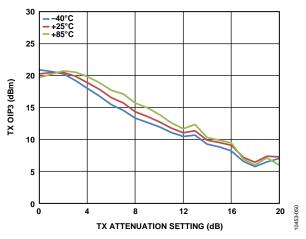


Figure 50. TX Third-Order Output Intercept Point (OIP3) vs. TX Attenuation Setting

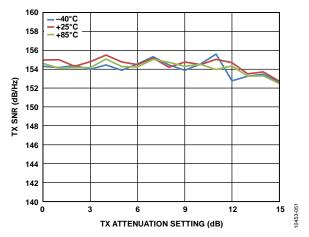


Figure 51. TX Signal-to-Noise Ratio (SNR) vs. TX Attenuation Setting, LTE 20 MHz Signal of Interest with Noise Measured at 90 MHz Offset

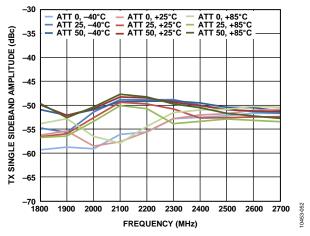


Figure 52. TX Single Sideband (SSB) Rejection vs. Frequency, 3.075 MHz Offset

### **5.5 GHz FREQUENCY BAND**

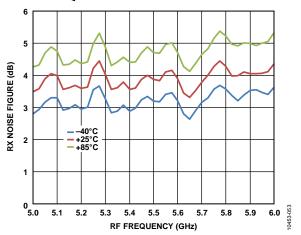


Figure 53. RX Noise Figure vs. RF Frequency

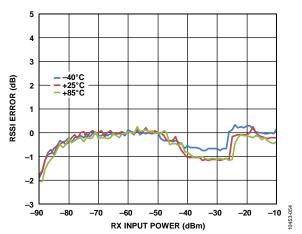


Figure 54. RSSI Error vs. RX Input Power, Referenced to -50 dBm Input Power at 5.8 GHz

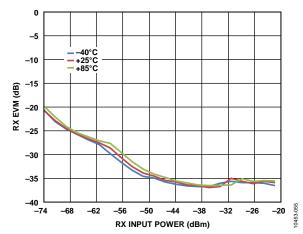


Figure 55. RX EVM vs. RX Input Power, 64 QAM WiMAX 40 MHz Mode, 40 MHz REF\_CLK (Doubled Internally for RF Synthesizer)

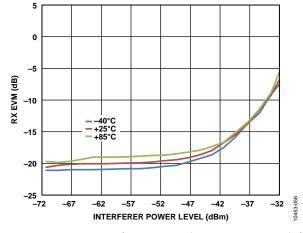


Figure 56. RX EVM vs. Interferer Power Level, WiMAX 40 MHz Signal of Interest with  $P_{\rm IN} = -74$  dBm, WiMAX 40 MHz Blocker at 40 MHz Offset

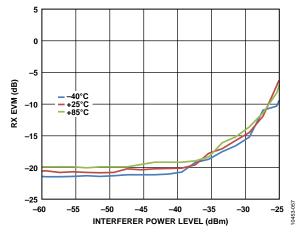


Figure 57. RX EVM vs. Interferer Power Level, WiMAX 40 MHz Signal of Interest with  $P_{\rm IN} = -74$  dBm, WiMAX 40 MHz Blocker at 80 MHz Offset

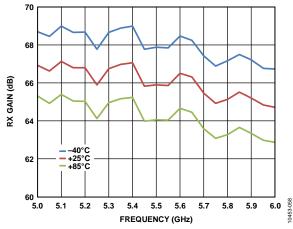


Figure 58. RX Gain vs. Frequency, Gain Index = 76 (Maximum Setting)

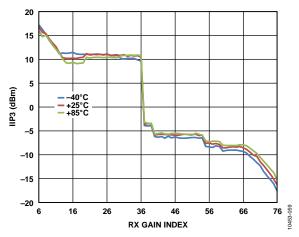


Figure 59. Third-Order Input Intercept Point (IIP3) vs. RX Gain Index, f1 = 50 MHz, f2 = 101 MHz

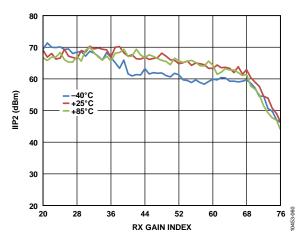


Figure 60. Second-Order Input Intercept Point (IIP2) vs. RX Gain Index, f1 = 70 MHz, f2 = 71 MHz

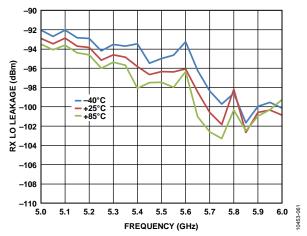


Figure 61. RX Local Oscillator (LO) Leakage vs. Frequency

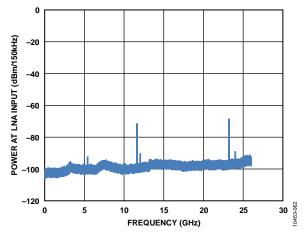


Figure 62. RX Emission at LNA Input, DC to 26 GHz,  $f_{LO\_RX}$  = 5.8 GHz, WiMAX 40 MHz

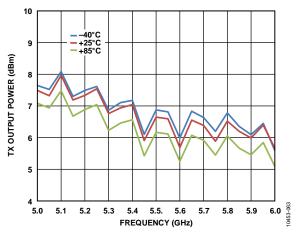


Figure 63. TX Output Power vs. Frequency, Attenuation Setting = 0 dB, Single Tone

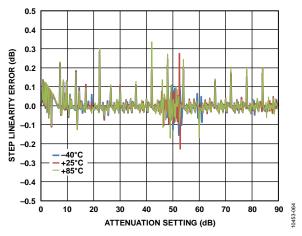


Figure 64. TX Power Control Linearity Error vs. Attenuation Setting

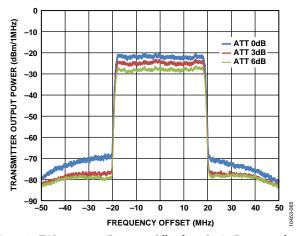


Figure 65. TX Spectrum vs. Frequency Offset from Carrier Frequency,  $f_{LO\_TX} = 5.8$  GHz, WiMAX 40 MHz Downlink (Digital Attenuation Variations Shown)

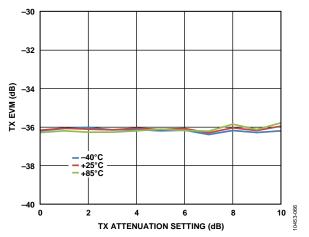


Figure 66. TX EVM vs. TX Attenuation Setting, WiMAX 40 MHz, 64 QAM Modulation,  $f_{\text{LO\_TX}} = 5.495$  GHz, 40 MHz REF\_CLK (Doubled Internally for RF Synthesizer)

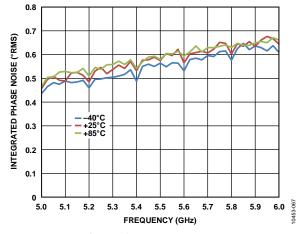


Figure 67. Integrated TX LO Phase Noise vs. Frequency, 40 MHz REF\_CLK (Doubled Internally for RF Synthesizer)

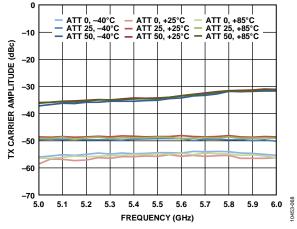


Figure 68. TX Carrier Rejection vs. Frequency

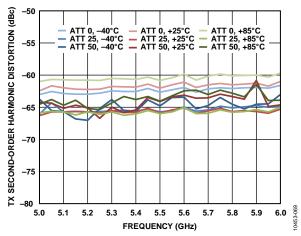


Figure 69. TX Second-Order Harmonic Distortion (HD2) vs. Frequency

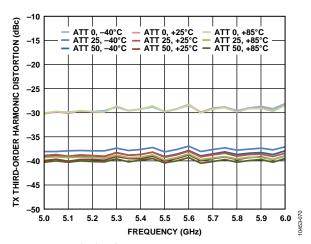


Figure 70. TX Third-Order Harmonic Distortion (HD3) vs. Frequency

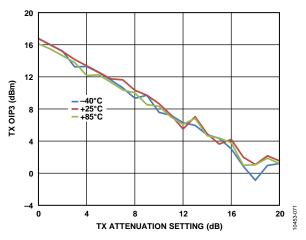


Figure 71. TX Third-Order Output Intercept Point (OIP3) vs. TX Attenuation Setting,  $f_{LO_TX} = 5.8 \text{ GHz}$ 

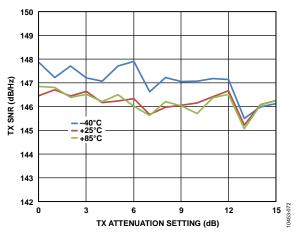


Figure 72. TX Signal-to-Noise Ratio (SNR) vs. TX Attenuation Setting, WiMAX 40 MHz Signal of Interest with Noise Measured at 90 MHz Offset,  $f_{\text{LO}\_\text{TX}} = 5.745 \text{ GHz}$ 

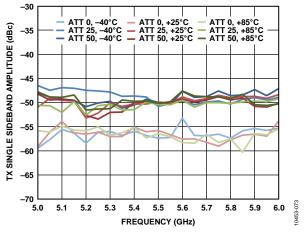


Figure 73. TX Single Sideband (SSB) Rejection vs. Frequency, 7 MHz Offset

### THEORY OF OPERATION

### **GENERAL**

The AD9361 is a highly integrated radio frequency (RF) transceiver capable of being configured for a wide range of applications. The device integrates all RF, mixed signal, and digital blocks necessary to provide all transceiver functions in a single device. Programmability allows this broadband transceiver to be adapted for use with multiple communication standards, including frequency division duplex (FDD) and time division duplex (TDD) systems. This programmability also allows the device to be interfaced to various baseband processors (BBPs) using a single 12-bit parallel data port, dual 12-bit parallel data ports, or a 12-bit low voltage differential signaling (LVDS) interface.

The AD9361 also provides self-calibration and automatic gain control (AGC) systems to maintain a high performance level under varying temperatures and input signal conditions. In addition, the device includes several test modes that allow system designers to insert test tones and create internal loopback modes that can be used by designers to debug their designs during prototyping and optimize their radio configuration for a specific application.

### **RECEIVER**

The receiver section contains all blocks necessary to receive RF signals and convert them to digital data that is usable by a BBP. There are two independently controlled channels that can receive signals from different sources, allowing the device to be used in multiple input, multiple output (MIMO) systems while sharing a common frequency synthesizer.

Each channel has three inputs that can be multiplexed to the signal chain, making the AD9361 suitable for use in diversity systems with multiple antenna inputs. The receiver is a direct conversion system that contains a low noise amplifier (LNA), followed by matched in-phase (I) and quadrature (Q) amplifiers, mixers, and band shaping filters that down convert received signals to baseband for digitization. External LNAs can also be interfaced to the device, allowing designers the flexibility to customize the receiver front end for their specific application.

Gain control is achieved by following a preprogrammed gain index map that distributes gain among the blocks for optimal performance at each level. This can be achieved by enabling the internal AGC in either fast or slow mode or by using manual gain control, allowing the BBP to make the gain adjustments as needed. Additionally, each channel contains independent RSSI measurement capability, dc offset tracking, and all circuitry necessary for self-calibration.

The receivers include 12-bit, sigma-delta  $(\Sigma - \Delta)$  ADCs and adjustable sample rates that produce data streams from the received signals. The digitized signals can be conditioned further by a series of decimation filters and a fully programmable 128-tap FIR filter with additional decimation settings. The sample rate of each

digital filter block is adjustable by changing decimation factors to produce the desired output data rate.

### **TRANSMITTER**

The transmitter section consists of two identical and independently controlled channels that provide all digital processing, mixed signal, and RF blocks necessary to implement a direct conversion system while sharing a common frequency synthesizer. The digital data received from the BBP passes through a fully programmable 128-tap FIR filter with interpolation options. The FIR output is sent to a series of interpolation filters that provide additional filtering and data rate interpolation prior to reaching the DAC. Each 12-bit DAC has an adjustable sampling rate. Both the I and Q channels are fed to the RF block for upconversion.

When converted to baseband analog signals, the I and Q signals are filtered to remove sampling artifacts and fed to the upconversion mixers. At this point, the I and Q signals are recombined and modulated on the carrier frequency for transmission to the output stage. The combined signal also passes through analog filters that provide additional band shaping, and then the signal is transmitted to the output amplifier. Each transmit channel provides a wide attenuation adjustment range with fine granularity to help designers optimize signal-to-noise ratio (SNR).

Self-calibration circuitry is built into each transmit channel to provide automatic real-time adjustment. The transmitter block also provides a TX monitor block for each channel. This block monitors the transmitter output and routes it back through an unused receiver channel to the BBP for signal monitoring. The TX monitor blocks are available only in TDD mode operation while the receiver is idle.

### **CLOCK INPUT OPTIONS**

The AD9361 operates using a reference clock that can be provided by two different sources. The first option is to use a dedicated crystal with a frequency between 19 MHz and 50 MHz connected between the XTALP and XTALN pins. The second option is to connect an external oscillator or clock distribution device (such as the AD9548) to the XTALN pin (with the XTALP pin remaining unconnected). If an external oscillator is used, the frequency can vary between 10 MHz and 80 MHz. This reference clock is used to supply the synthesizer blocks that generate all data clocks, sample clocks, and local oscillators inside the device.

Errors in the crystal frequency can be removed by using the digitally programmable digitally controlled crystal oscillator (DCXO) function to adjust the on-chip variable capacitor. This capacitor can tune the crystal frequency variance out of the system, resulting in a more accurate reference clock from which all other frequency signals are generated. This function can also be used with on-chip temperature sensing to provide oscillator frequency temperature compensation during normal operation.

#### **SYNTHESIZERS**

#### **RF PLLs**

The AD9361 contains two identical synthesizers to generate the required LO signals for the RF signal paths:—one for the receiver and one for the transmitter. Phase-locked loop (PLL) synthesizers are fractional-N designs incorporating completely integrated voltage controlled oscillators (VCOs) and loop filters. In TDD operation, the synthesizers turn on and off as appropriate for the RX and TX frames. In FDD mode, the TX PLL and the RX PLL can be activated simultaneously. These PLLs require no external components.

### **BB PLL**

The AD9361 also contains a baseband PLL synthesizer that is used to generate all baseband related clock signals. These include the ADC and DAC sampling clocks, the DATA\_CLK signal (see the Digital Data Interface section), and all data framing signals. This PLL is programmed from 700 MHz to 1400 MHz based on the data rate and sample rate requirements of the system.

### **DIGITAL DATA INTERFACE**

The AD9361 data interface uses parallel data ports (P0 and P1) to transfer data between the device and the BBP. The data ports can be configured in either single-ended CMOS format or differential LVDS format. Both formats can be configured in multiple arrangements to match system requirements for data ordering and data port connections. These arrangements include single port data bus, dual port data bus, single data rate, double data rate, and various combinations of data ordering to transmit data from different channels across the bus at appropriate times.

Bus transfers are controlled using simple hardware handshake signaling. The two ports can be operated in either bidirectional (TDD) mode or in full duplex (FDD) mode where half the bits are used for transmitting data and half are used for receiving data. The interface can also be configured to use only one of the data ports for applications that do not require high data rates and prefer to use fewer interface pins.

### DATA\_CLK Signal

RX data supplies the DATA\_CLK signal that the BBP can use when receiving the data. The DATA\_CLK can be set to a rate that provides single data rate (SDR) timing where data is sampled on each rising clock edge, or it can be set to provide double data rate (DDR) timing where data is captured on both rising and falling edges. This timing applies to operation using either a single port or both ports.

#### FB CLK Signal

For transmit data, the interface uses the FB\_CLK signal as the timing reference. FB\_CLK allows source synchronous timing with rising edge capture for burst control signals and either rising edge (SDR mode) or both edge capture (DDR mode) for transmit signal bursts. The FB\_CLK signal must have the same frequency and duty cycle as DATA\_CLK.

### RX\_FRAME Signal

The device generates an RX\_FRAME output signal whenever the receiver outputs valid data. This signal has two modes: level mode (RX\_FRAME stays high as long as the data is valid) and pulse mode (RX\_FRAME pulses with a 50% duty cycle). Similarly, the BBP must provide a TX\_FRAME signal that indicates the beginning of a valid data transmission with a rising edge. Similar to the RX\_FRAME, the TX\_FRAME signal can remain high throughout the burst or it can be pulsed with a 50% duty cycle.

### **ENABLE STATE MACHINE**

The AD9361 transceiver includes an enable state machine (ENSM) that allows real-time control over the current state of the device. The device can be placed in several different states during normal operation, including

- Wait—power save, synthesizers disabled
- Sleep—wait with all clocks/BB PLL disabled
- TX—TX signal chain enabled
- RX—RX signal chain enabled
- FDD—TX and RX signal chains enabled
- Alert—synthesizers enabled

The ENSM has two possible control methods: SPI control and pin control.

#### **SPI Control Mode**

In SPI control mode, the ENSM is controlled asynchronously by writing SPI registers to advance the current state to the next state. SPI control is considered asynchronous to the DATA\_CLK because the SPI\_CLK can be derived from a different clock reference and can still function properly. The SPI control ENSM method is recommended when real-time control of the synthesizers is not necessary. SPI control can be used for real-time control as long as the BBIC has the ability to perform timed SPI writes accurately.

#### Pin Control Mode

In pin control mode, the enable function of the ENABLE pin and the TXNRX pin allow real-time control of the current state. The ENSM allows TDD or FDD operation depending on the configuration of the corresponding SPI register. The ENABLE and TXNRX pin control method is recommended if the BBIC has extra control outputs that can be controlled in real time, allowing a simple 2-wire interface to control the state of the device. To advance the current state of the ENSM to the next state, the enable function of the ENABLE pin can be driven by either a pulse (edge detected internally) or a level.

When a pulse is used, it must have a minimum pulse width of one FB\_CLK cycle. In level mode, the ENABLE and TXNRX pins are also edge detected by the AD9361 and must meet the same minimum pulse width requirement of one FB\_CLK cycle.

In FDD mode, the ENABLE and TXNRX pins can be remapped to serve as real-time RX and TX data transfer control signals. In this mode, the ENABLE pin enables or disables the receive signal path, and the TXNRX pin enables or disables the transmit signal path. In this mode, the ENSM is removed from the system for control of all data flow by these pins.

#### **SPI INTERFACE**

The AD9361 uses a serial peripheral interface (SPI) to communicate with the BBP. This interface can be configured as a 4-wire interface with dedicated receive and transmit ports, or it can be configured as a 3-wire interface with a bidirectional data communication port. This bus allows the BBP to set all device control parameters using a simple address data serial bus protocol.

Write commands follow a 24-bit format. The first six bits are used to set the bus direction and number of bytes to transfer. The next 10 bits set the address where data is to be written. The final eight bits are the data to be transferred to the specified register address (MSB to LSB). The AD9361 also supports an LSB-first format that allows the commands to be written in LSB to MSB format. In this mode, the register addresses are incremented for multibyte writes.

Read commands follow a similar format with the exception that the first 16 bits are transferred on the SPI\_DI pin and the final eight bits are read from the AD9361, either on the SPI\_DO pin in 4-wire mode or on the SPI\_DI pin in 3-wire mode.

#### **CONTROL PINS**

### Control Outputs (CTRL\_OUT[7:0])

The AD9361 provides eight simultaneous real-time output signals for use as interrupts to the BBP. These outputs can be configured to output a number of internal settings and measurements that the BBP can use when monitoring transceiver performance in different situations. The control output pointer register selects what information is output to these pins, and the control output enable register determines which signals are activated for monitoring by the BBP. Signals used for manual gain mode, calibration flags, state machine states, and the ADC output are among the outputs that can be monitored on these pins.

### Control Inputs (CTRL IN[3:0])

The AD9361 provides four edge detected control input pins. In manual gain mode, the BBP can use these pins to change the gain table index in real time. In transmit mode, the BBP can use two of the pins to change the transmit gain in real time.

### GPO PINS (GPO\_3 TO GPO\_0)

The AD9361 provides four, 3.3 V capable general-purpose logic output pins: GPO\_3, GPO\_2, GPO\_1, and GPO\_0. These pins can be used to control other peripheral devices such as regulators and switches via the AD9361 SPI bus, or they can function as slaves for the internal AD9361 state machine.

# AUXILIARY CONVERTERS AUXADC

The AD9361 contains an auxiliary ADC that can be used to monitor system functions such as temperature or power output. The converter is 12 bits wide and has an input range of 0 V to 1.25 V. When enabled, the ADC is free running. SPI reads provide the last value latched at the ADC output. A multiplexer in front of the ADC allows the user to select between the AUXADC input pin and a built-in temperature sensor.

#### **AUXDAC1** and **AUXDAC2**

The AD9361 contains two identical auxiliary DACs that can provide power amplifier (PA) bias or other system functionality. The auxiliary DACs are 10 bits wide, have an output voltage range of 0.5 V to VDD\_GPO -0.3 V, a current drive of 10 mA, and can be directly controlled by the internal enable state machine.

#### **POWERING THE AD9361**

The AD9361 must be powered by the following three supplies: the analog supply (VDDD1P3\_DIG/VDDAx = 1.3 V), the interface supply (VDD\_INTERFACE = 1.8 V), and the GPO supply (VDD\_GPO = 3.3 V).

For applications requiring optimal noise performance, it is recommended that the 1.3 V analog supply be split and sourced from low noise, low dropout (LDO) regulators. Figure 74 shows the recommended method.

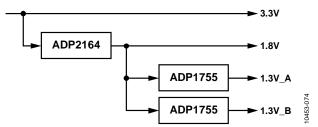


Figure 74. Low Noise Power Solution for the AD9361

For applications where board space is at a premium, and optimal noise performance is not an absolute requirement, the 1.3 V analog rail can be provided directly from a switcher, and a more integrated power management unit (PMU) approach can be adopted. Figure 75 shows this approach.

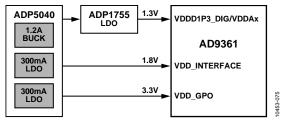


Figure 75. Space-Optimized Power Solution for the AD9361

### PACKAGING AND ORDERING INFORMATION

### **OUTLINE DIMENSIONS**

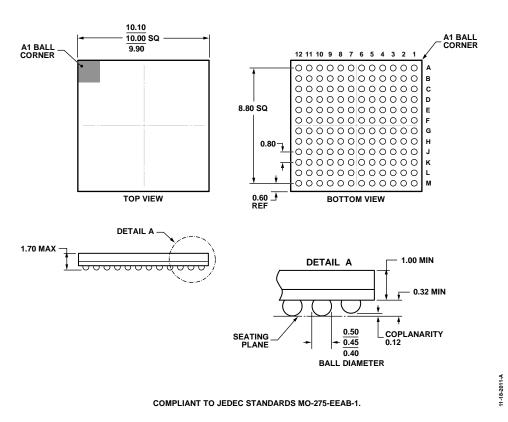


Figure 76. 144-Ball Chip Scale Package Ball Grid Array [CSP\_BGA] (BC-144-7) Dimensions shown in millimeters

### **ORDERING GUIDE**

Model <sup>1</sup>	Temperature Range	Package Description	Package Option
AD9361BBCZ	−40°C to +85°C	144-Ball Chip Scale Package Ball Grid Array [CSP_BGA]	BC-144-7
AD9361BBCZ-REEL	−40°C to +85°C	144-Ball Chip Scale Package Ball Grid Array [CSP_BGA]	BC-144-7

<sup>&</sup>lt;sup>1</sup> Z = RoHS Compliant Part.