HYDRAULIC ROB©TARM



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HYDRAULICROBØTARM

Product Introduction

This Robot Arm has made a little more interesting and hydro-mechanically fun.

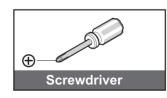
With Hydraulic Arm Edge, command six axes of varied movements: the gripper to open and close up to 1.89 inches, wrist rotation of 180 degrees, wrist mobility of 98 degrees, elbow range of 44 degrees, base rotation of 270 degrees, and shoulder motion of 45 degrees. With a vertical reach of 16.35 inches, horizontal reach of 12.42 inches, and lifting capacity of 50g, your robotic friend is ready for your genius to erupt. With the removal of the gripper, you can activate the suction apparatus. This feature enables the user to elevate objects with a larger surface area (like a small mobile phone). Another prodigious attribution is a braking system that is integrated in the lever controllers to execute all commands accurately. WOW!

How does Hydraulic Robot Arm equate to fun? Children will have total command and visual manipulation using the science principles of a Hydraulic system and its application. Easy to follow instructions with detailed graphic illustrations pave the way for successful and satisfying kit building of 229 pieces. Compliment your engineering, math, science, and technology learning strategy. No battery or motor required. It is powered by water; thus, the "Hydraulic" significance and how it manipulates axes movement via lever controllers. Hydraulic Robot Arm is recommended for ages 10 and up, but with its 229 assembly parts, it will challenge the beginner engineering enthusiasts.

Tools You May Need













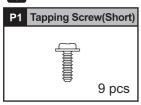


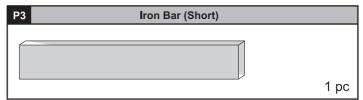
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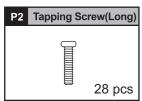
Tape Measure or Ruler

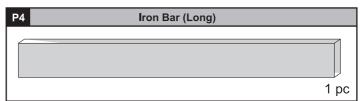
Mechanical Parts List

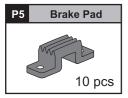
Product contains functional edges and sharp points.

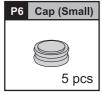


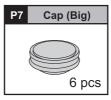


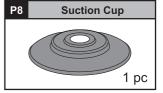


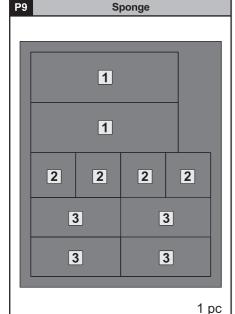


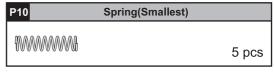


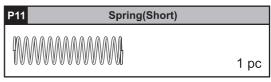


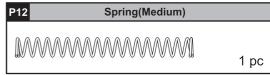


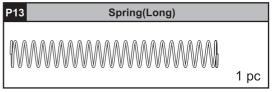


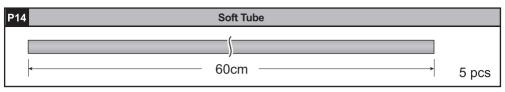


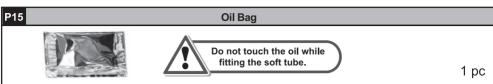


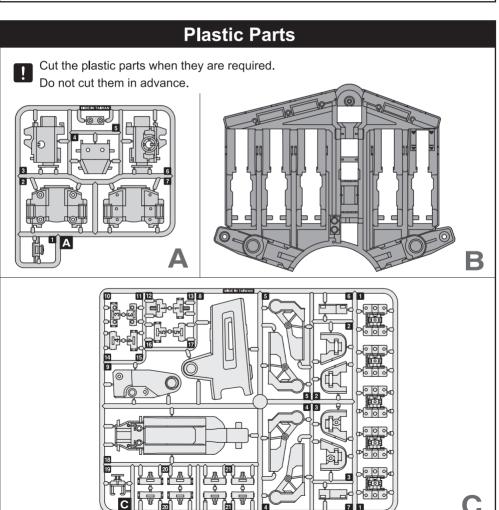


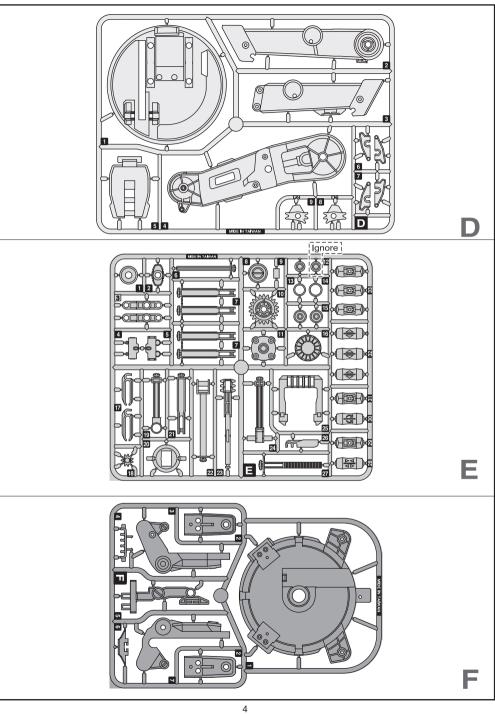


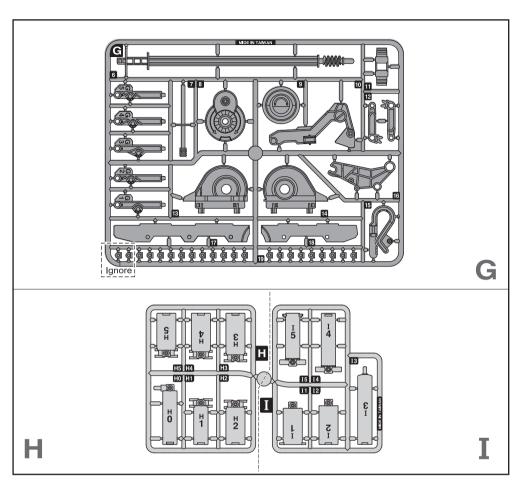


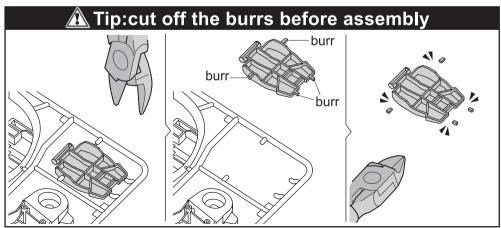




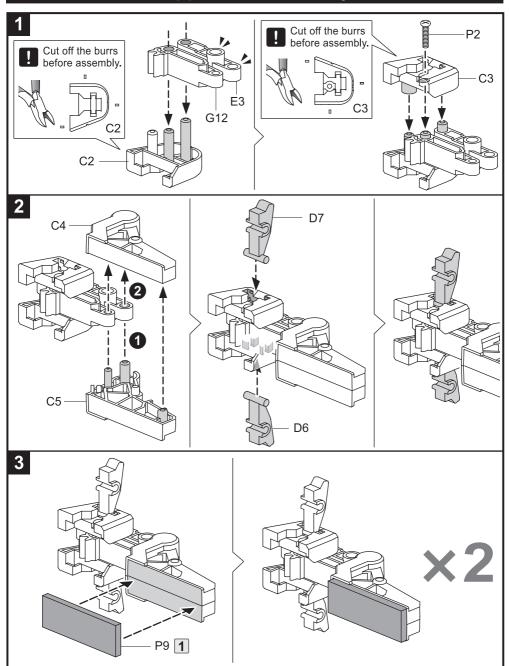




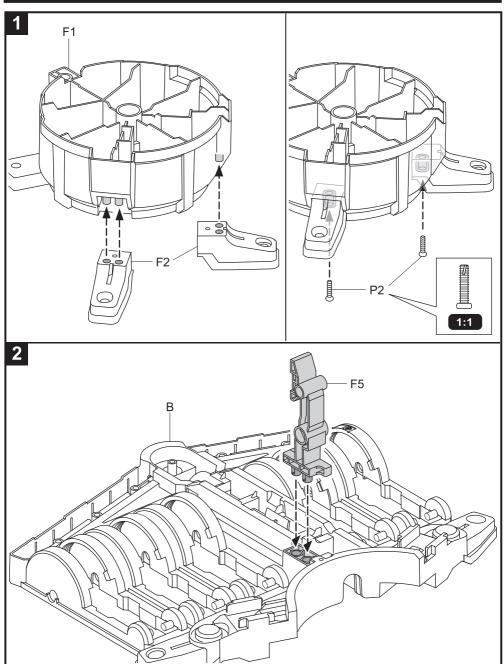


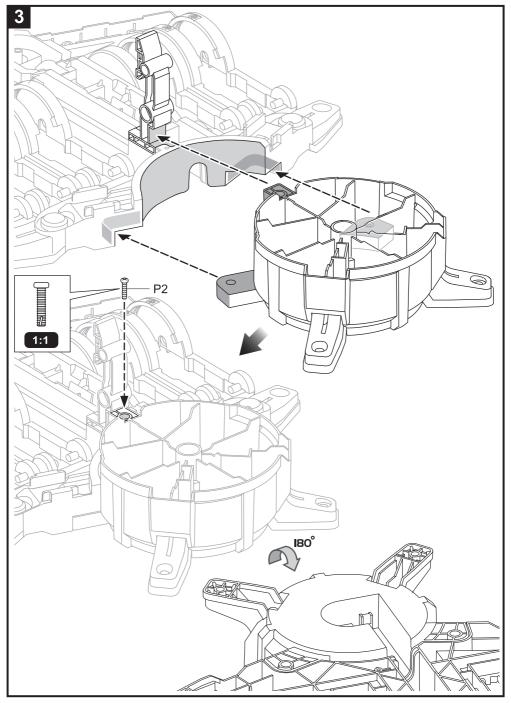


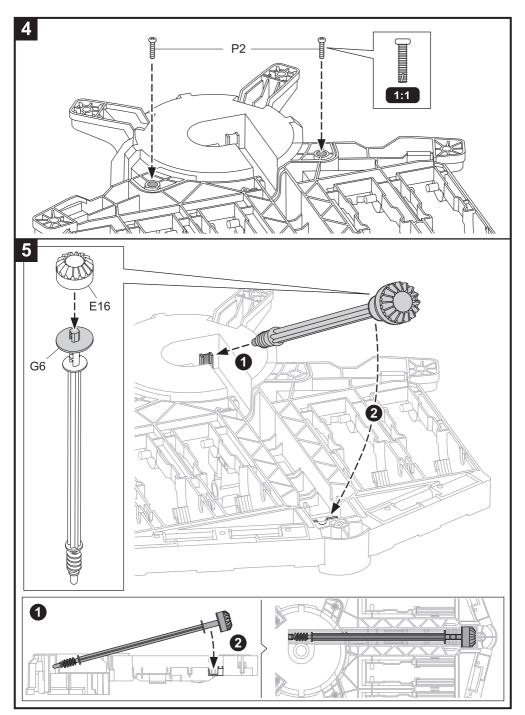
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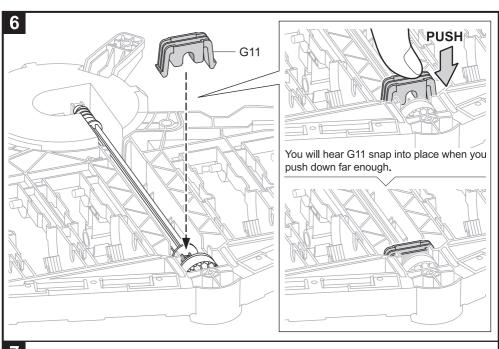


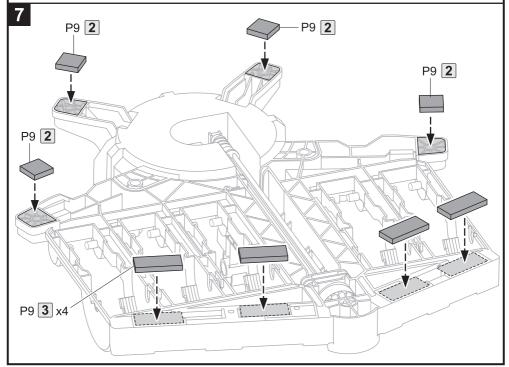
Stand & Control Base Assembly

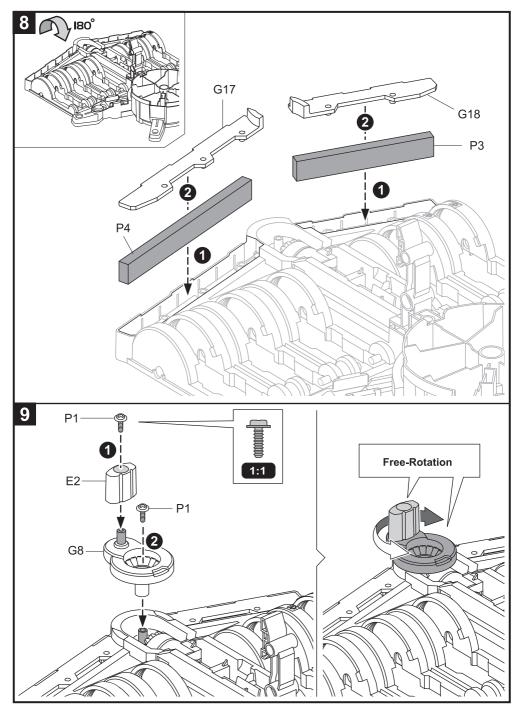


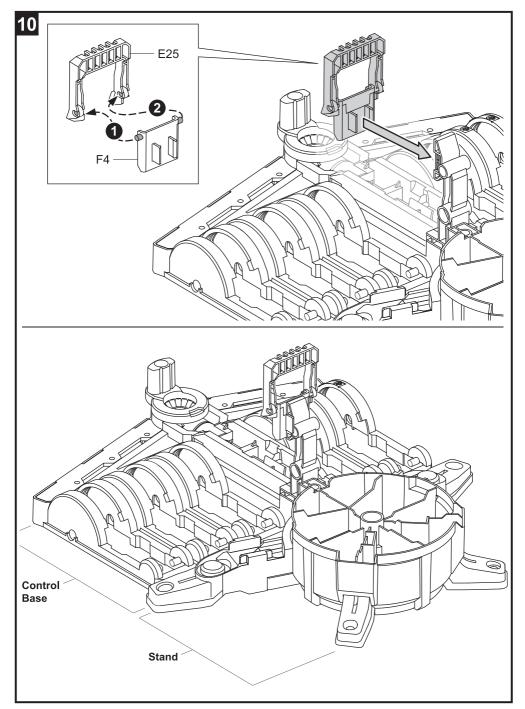




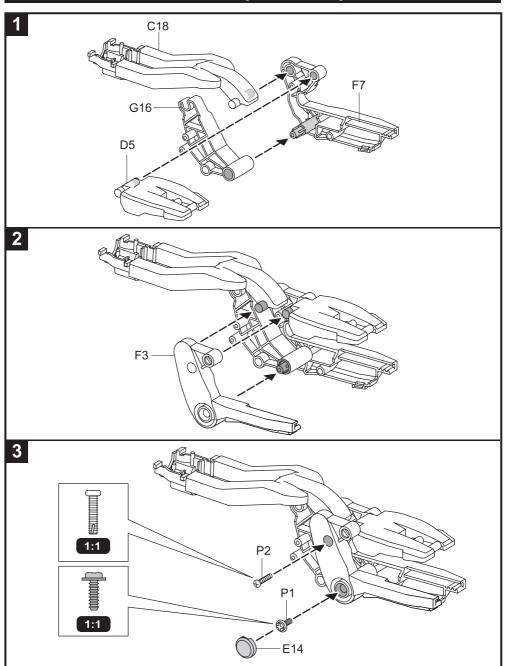


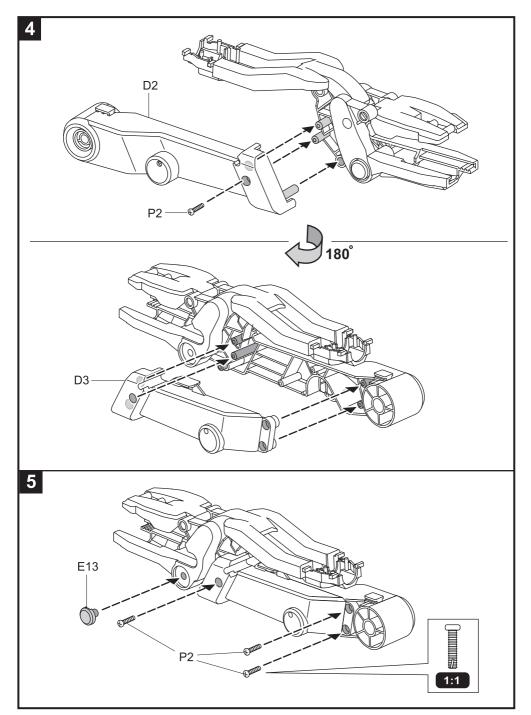


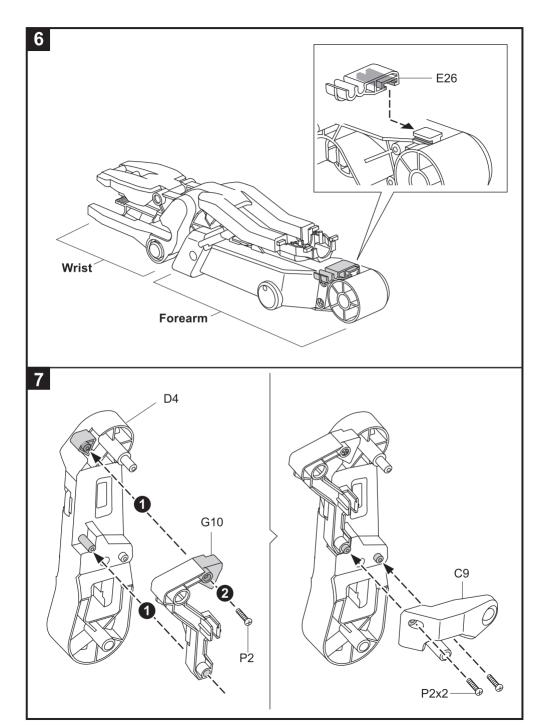


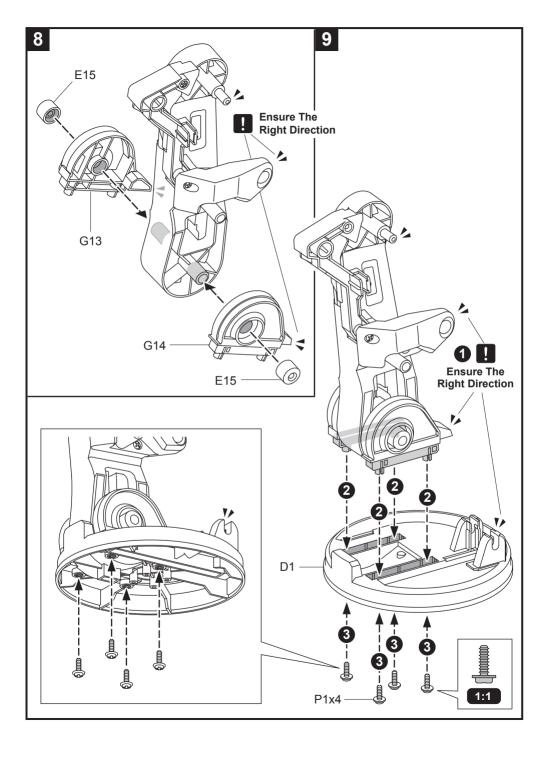


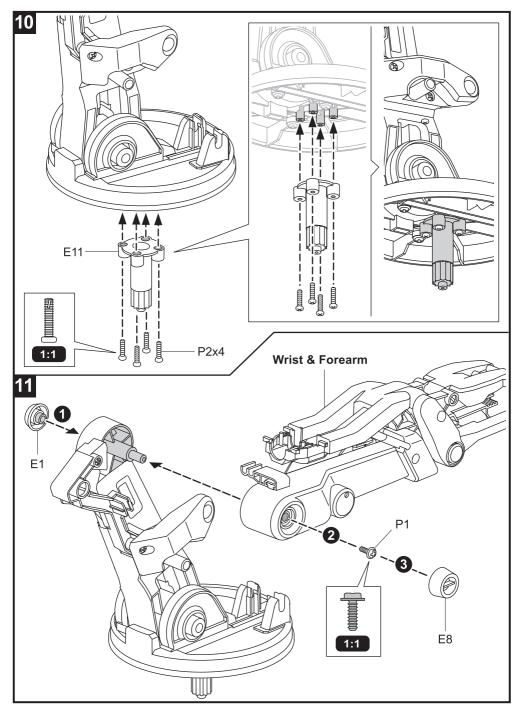
Main Body Assembly

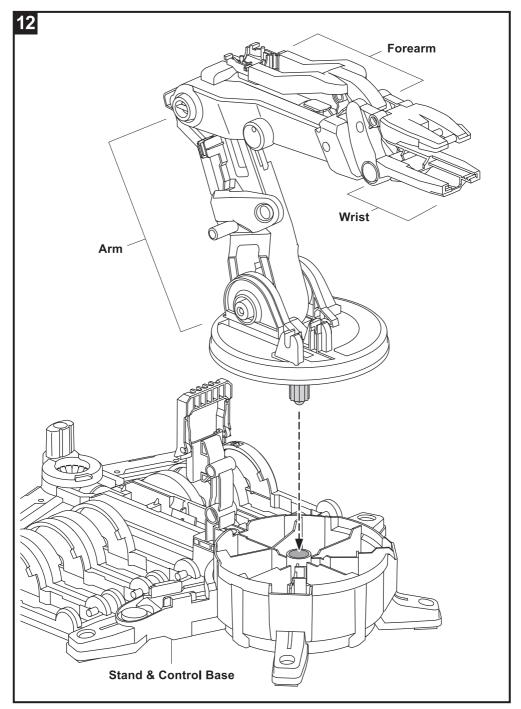


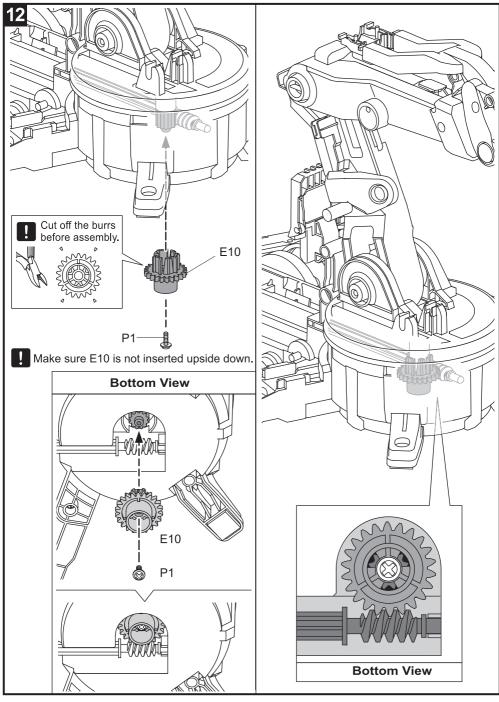




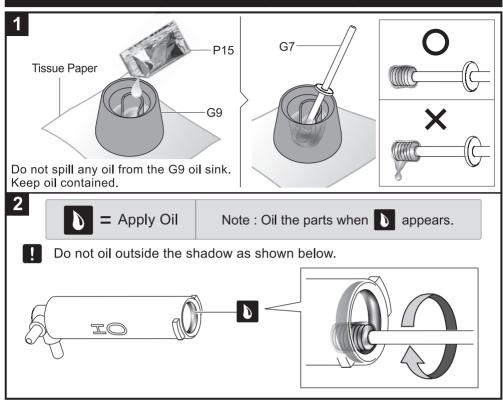




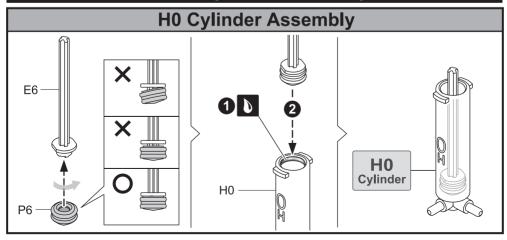


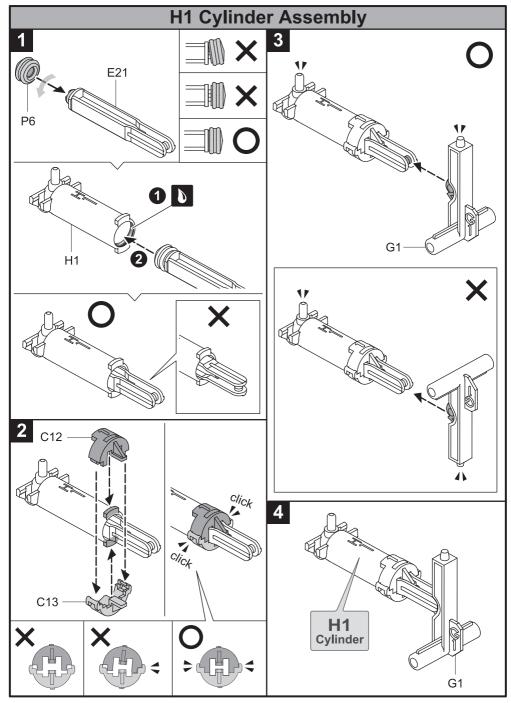


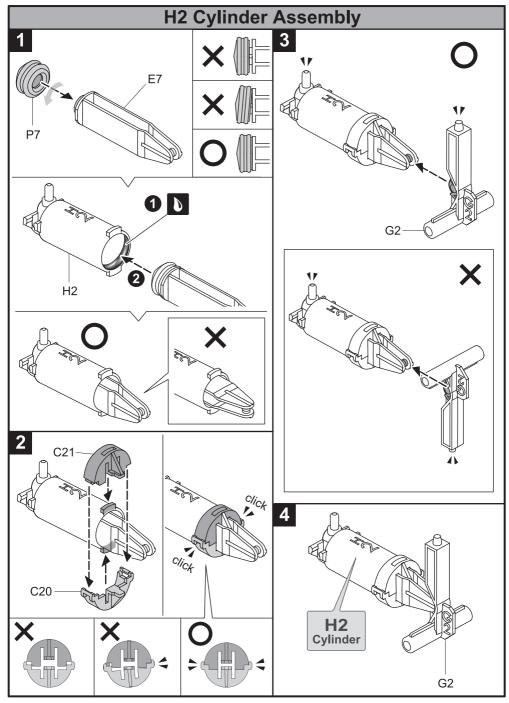
How To Oil The Parts

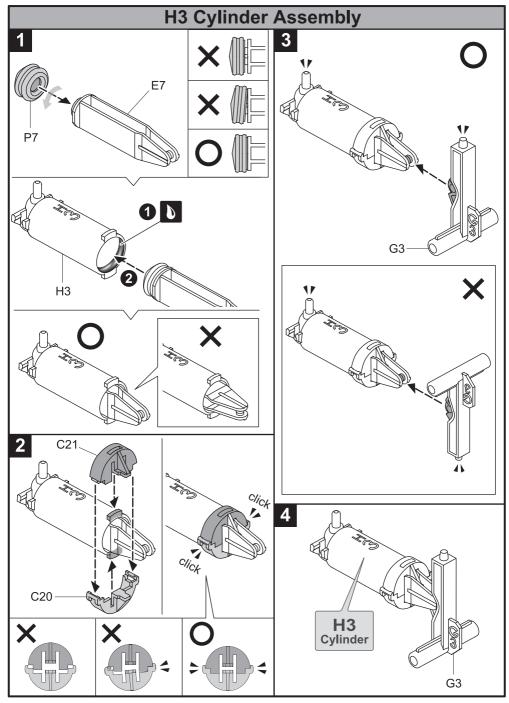


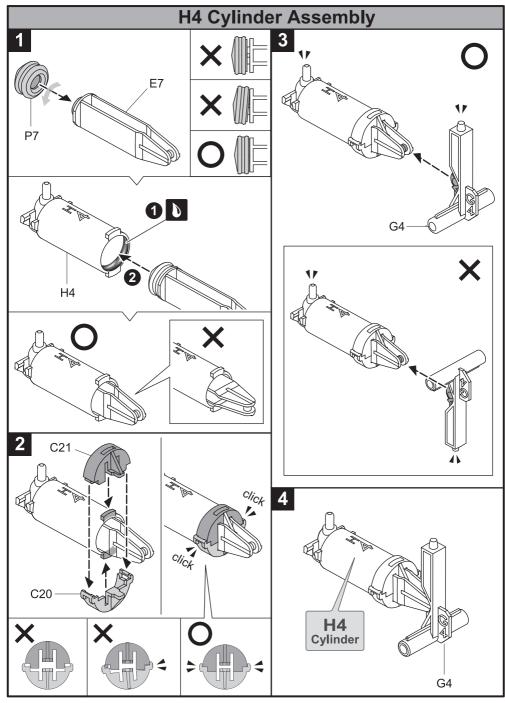
H0~H5 Cylinder Assembly

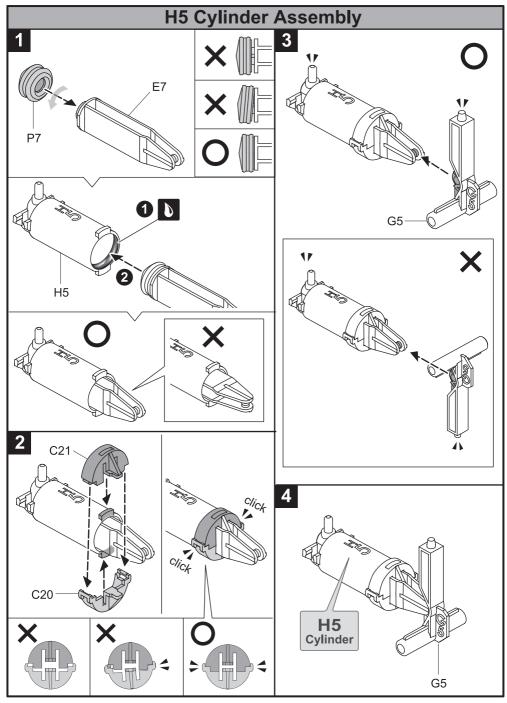




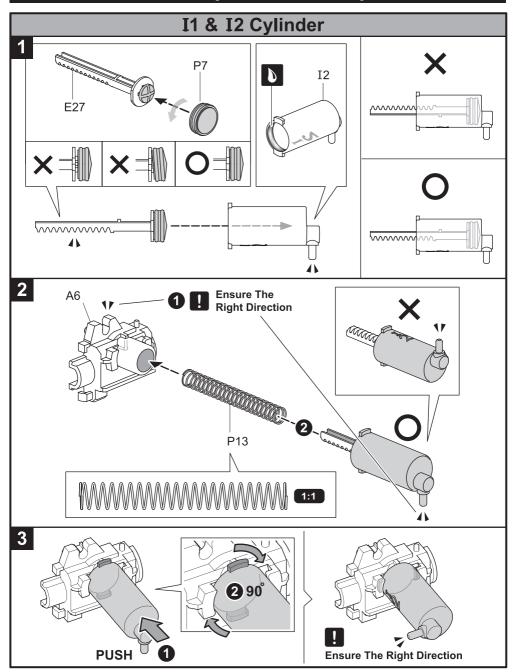


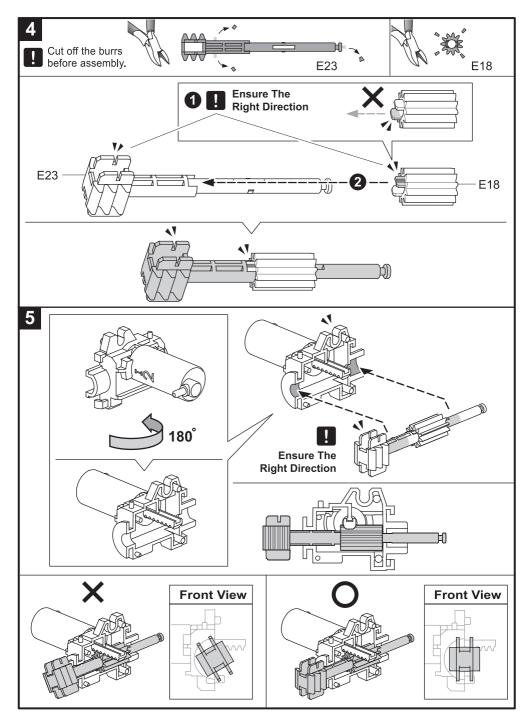


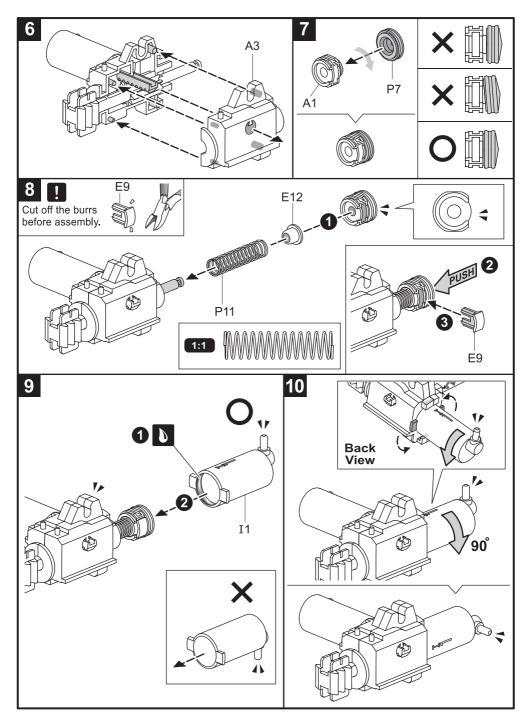




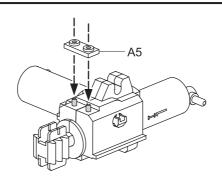
I1 ~ I5 Cylinder Assembly

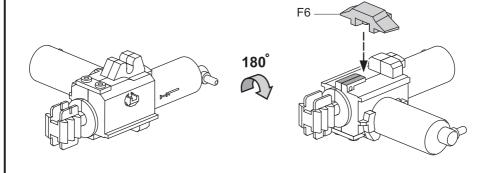


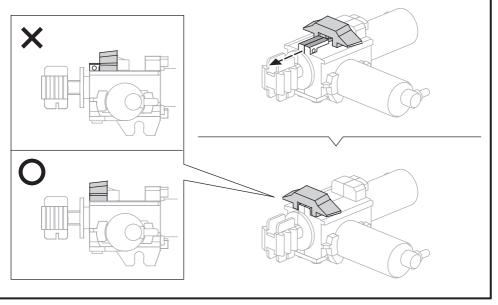


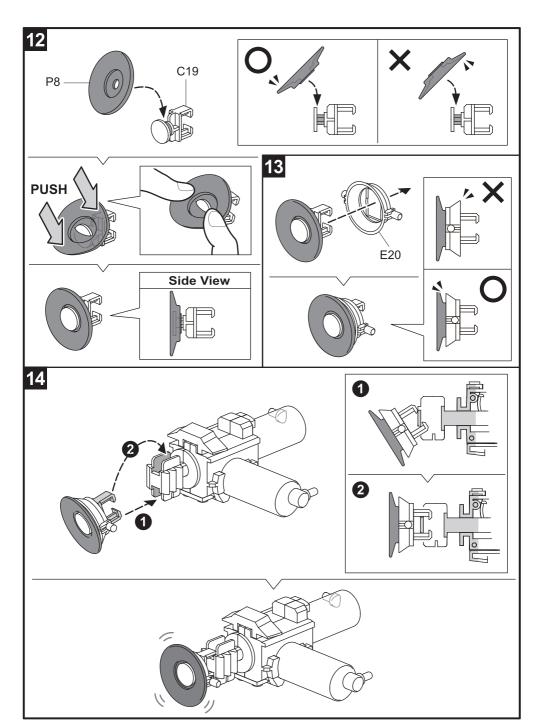


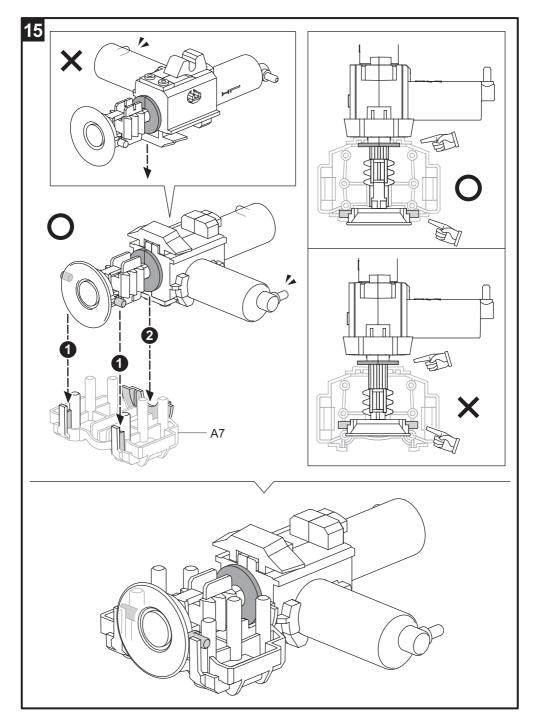


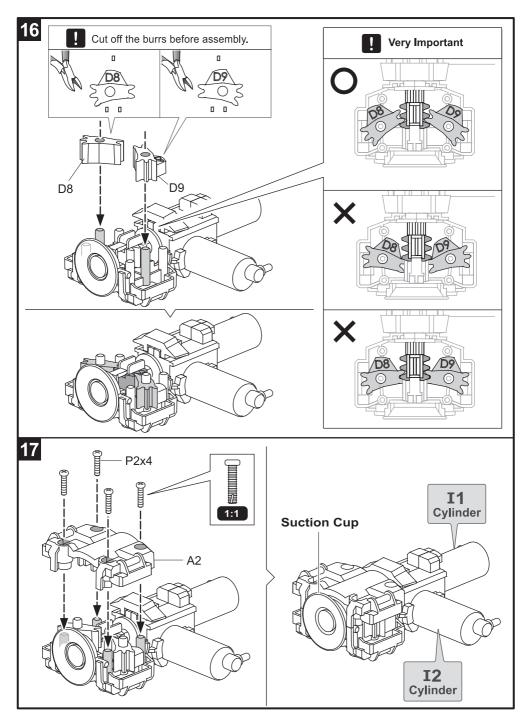


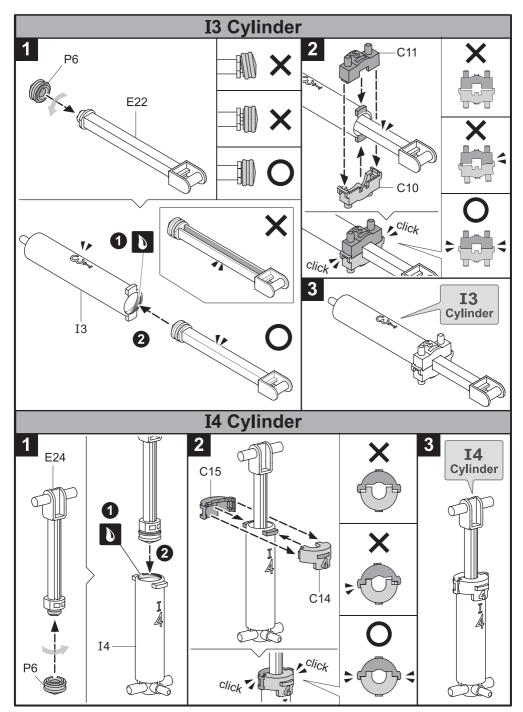


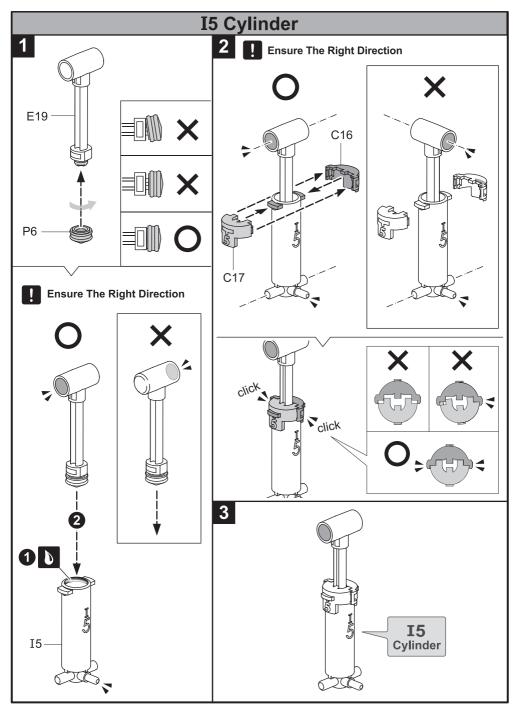




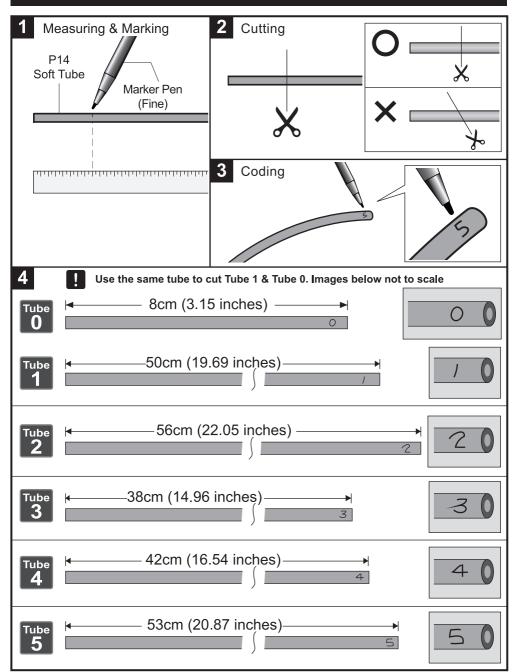




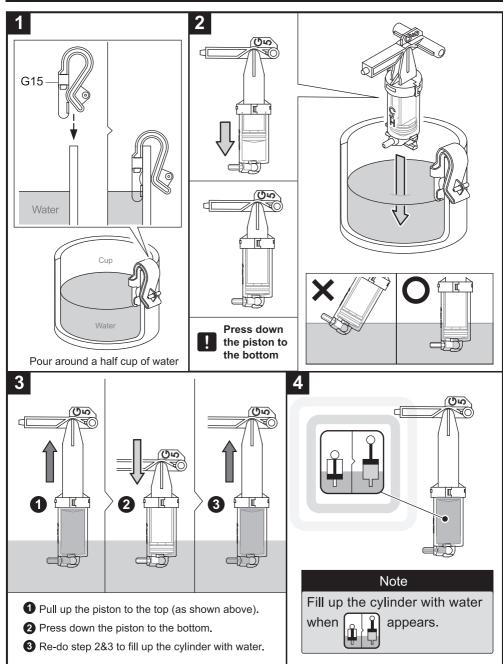


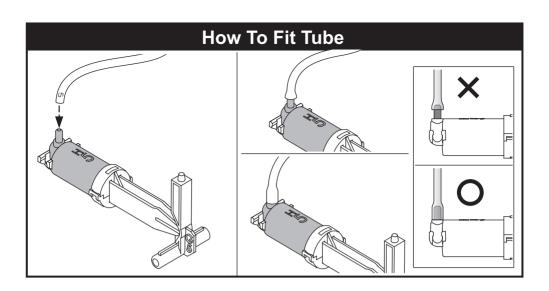


How To Cut The Tube

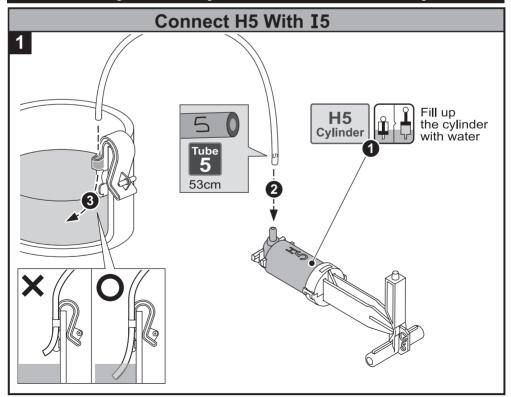


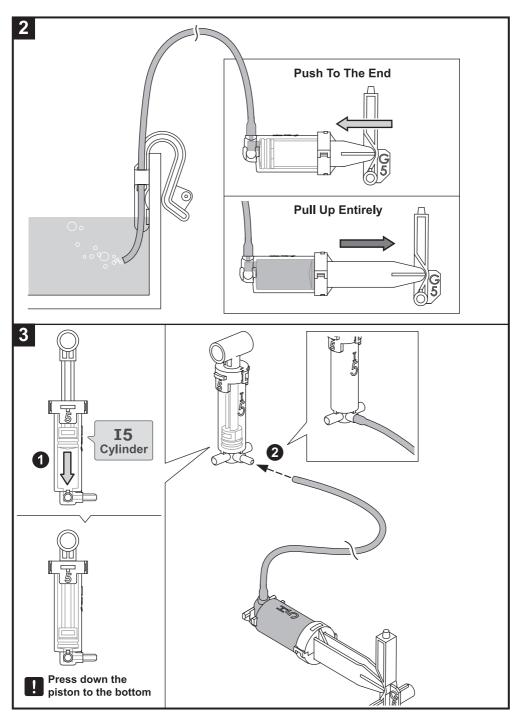
How To Fill Up The Cylinder With Water

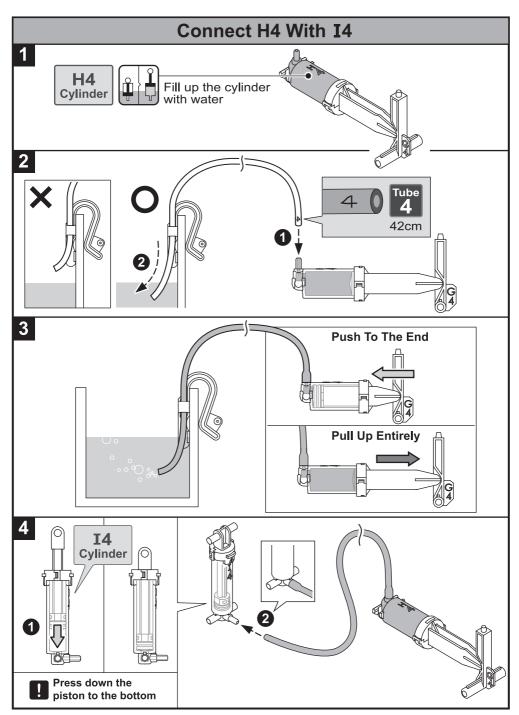


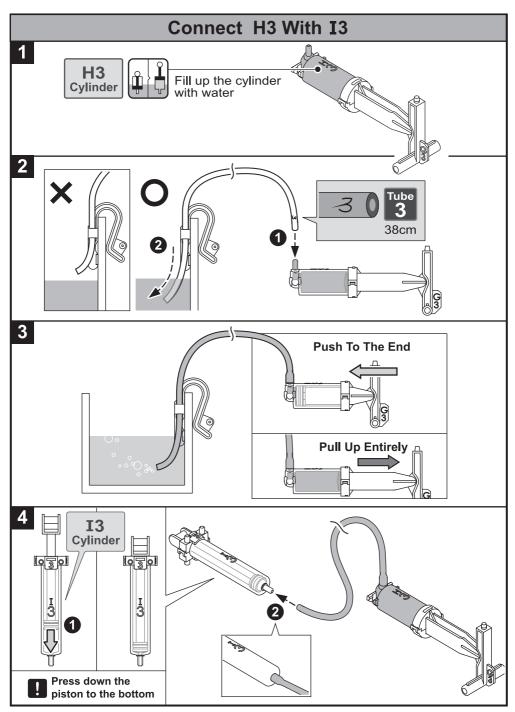


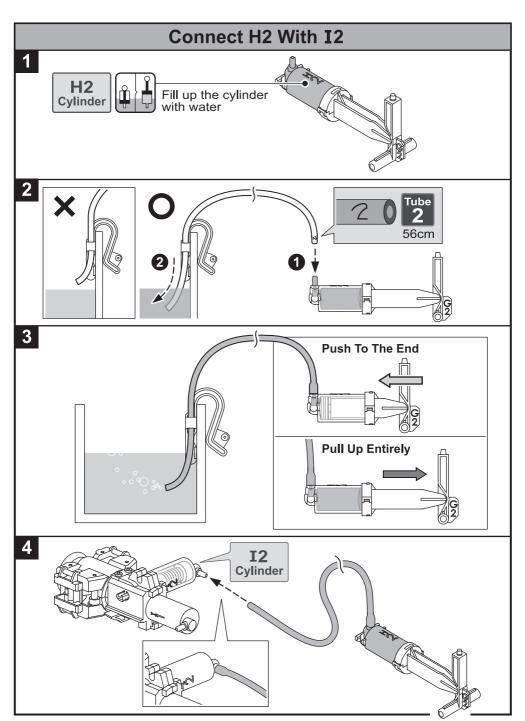
Hydraulic Cylinder Moduel Assembly

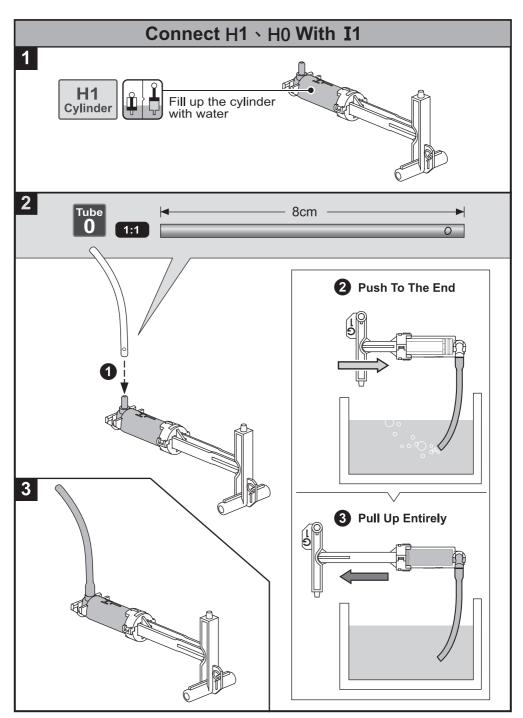


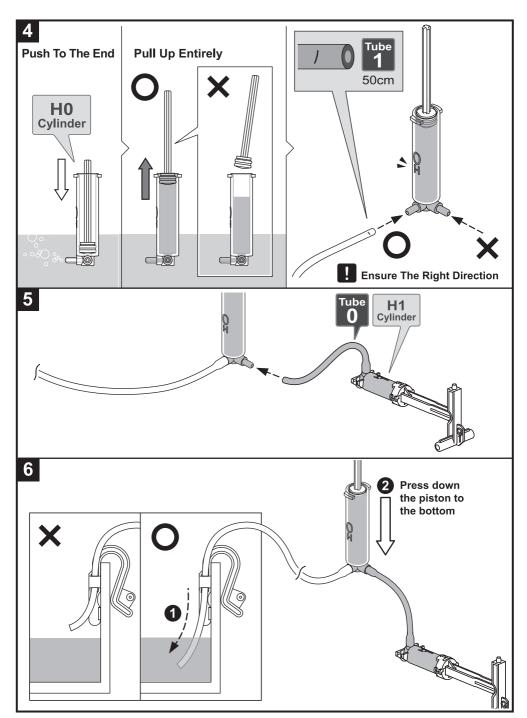


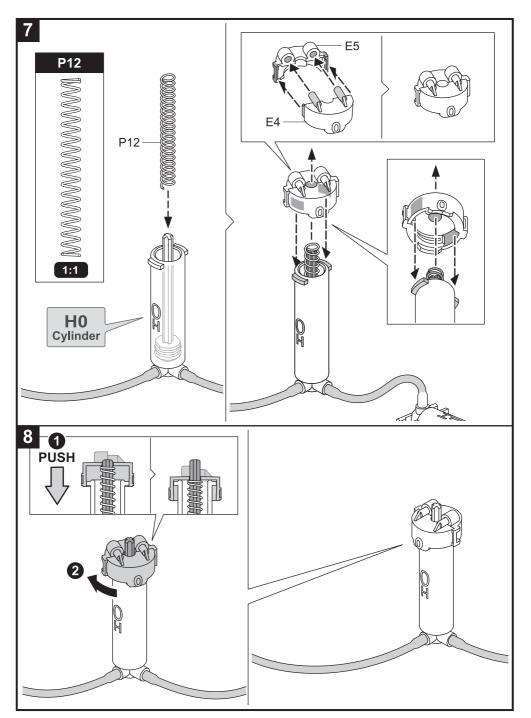


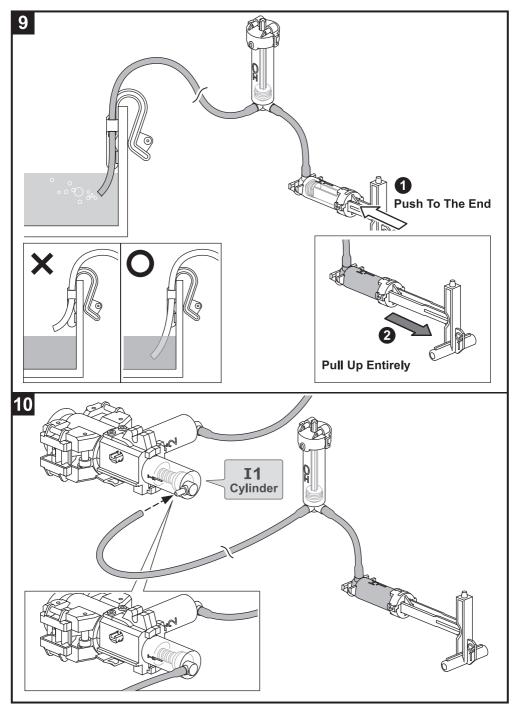


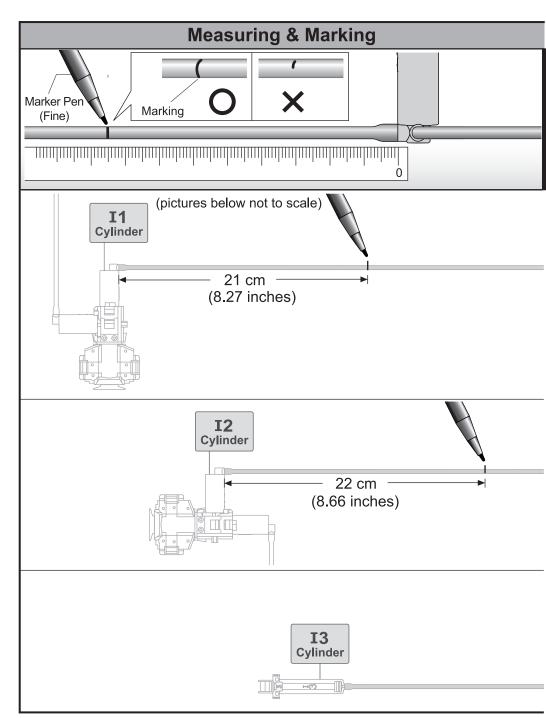


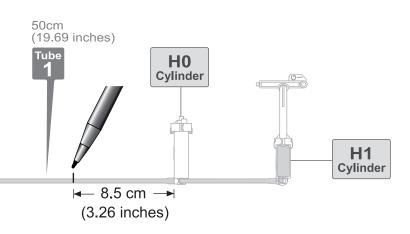


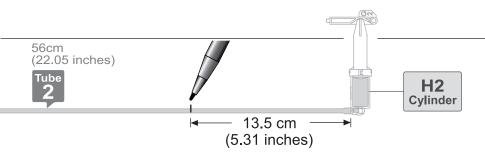


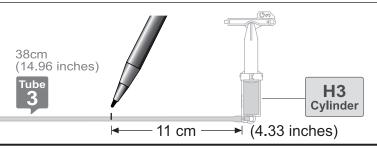


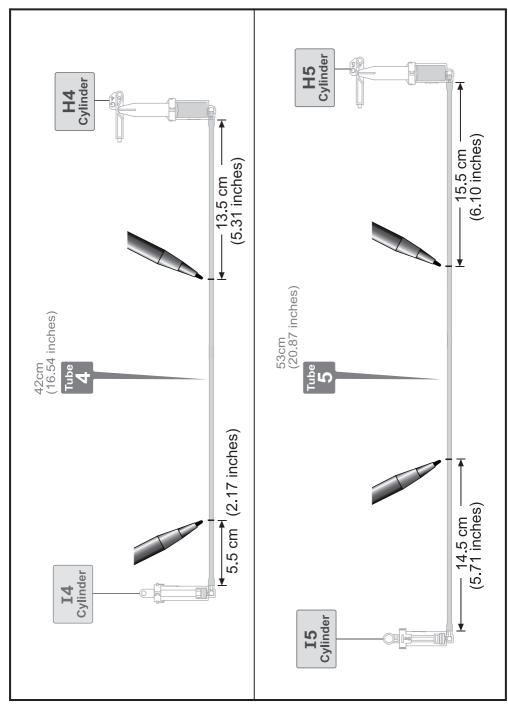




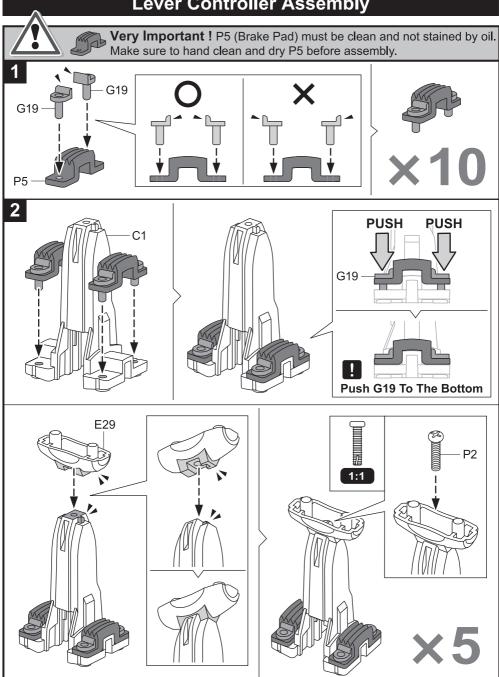


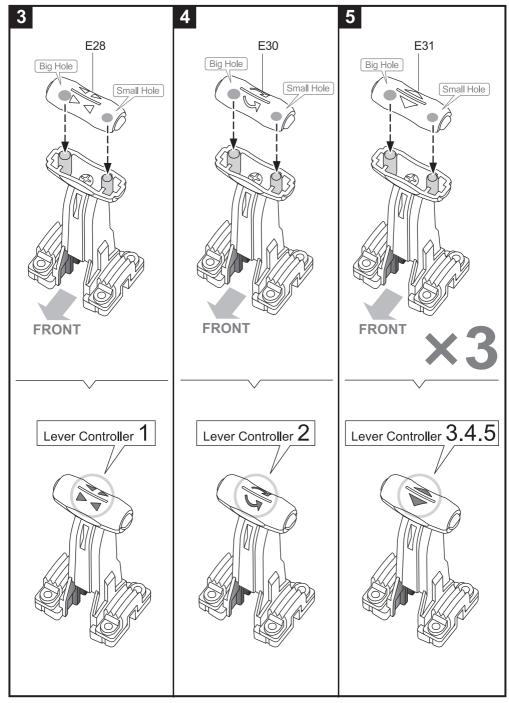




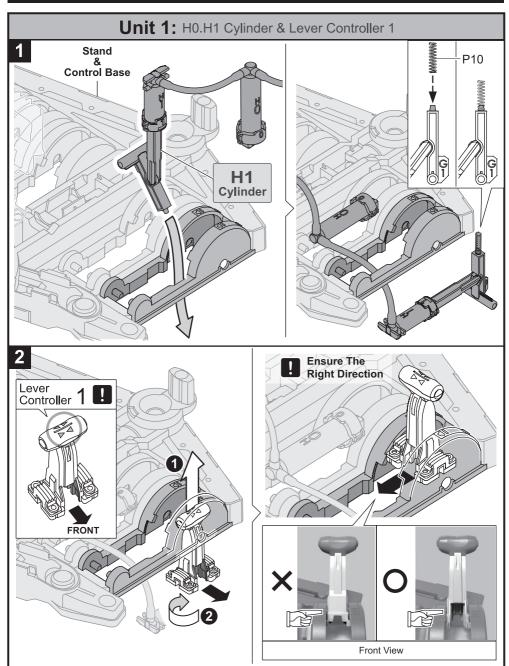


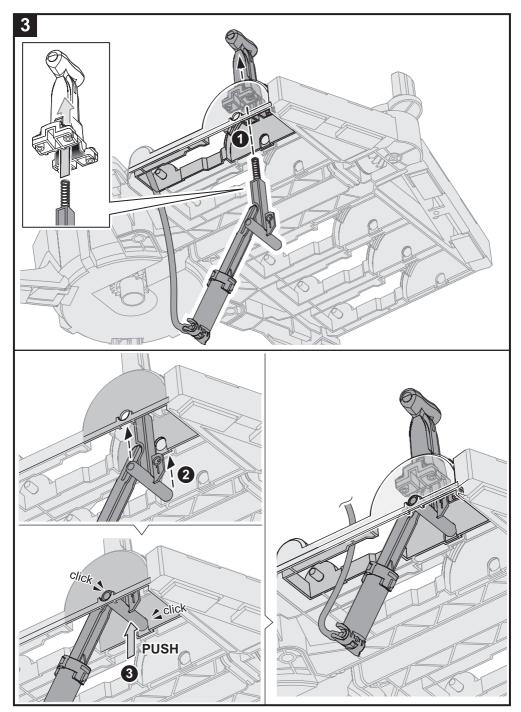
Lever Controller Assembly

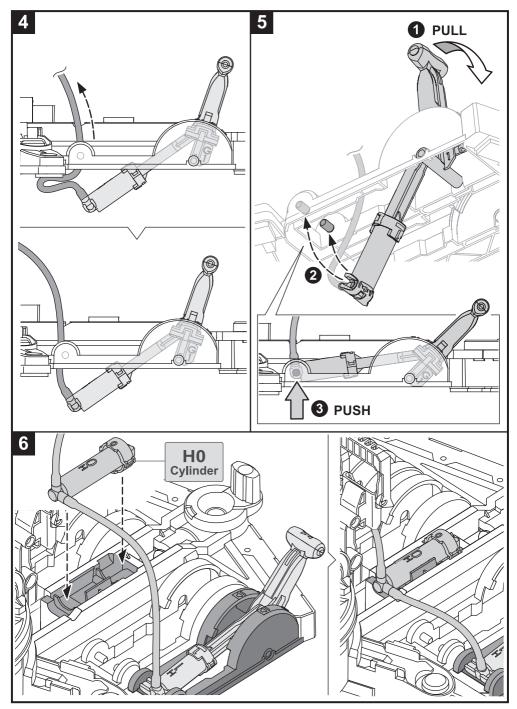


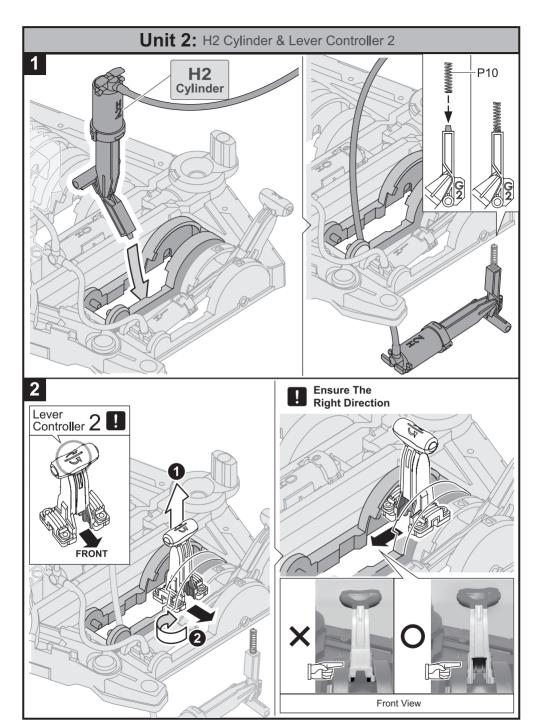


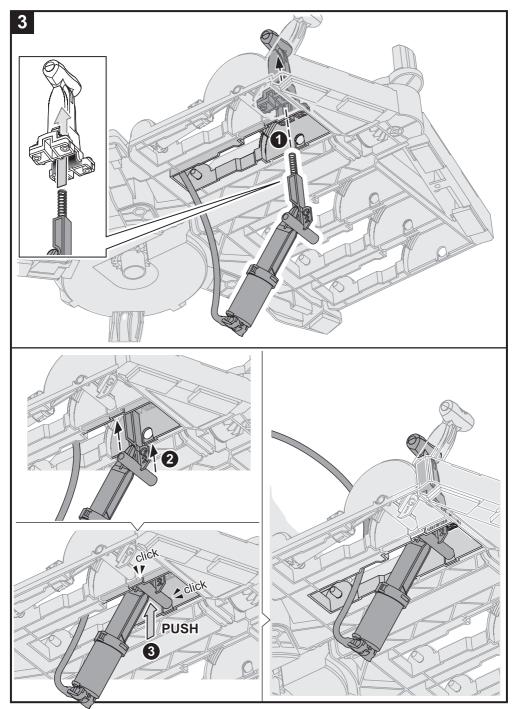
Control Moduel Assembly

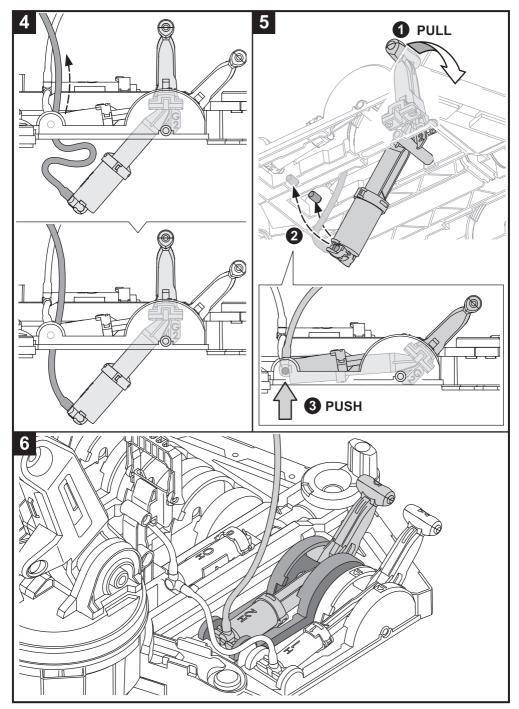


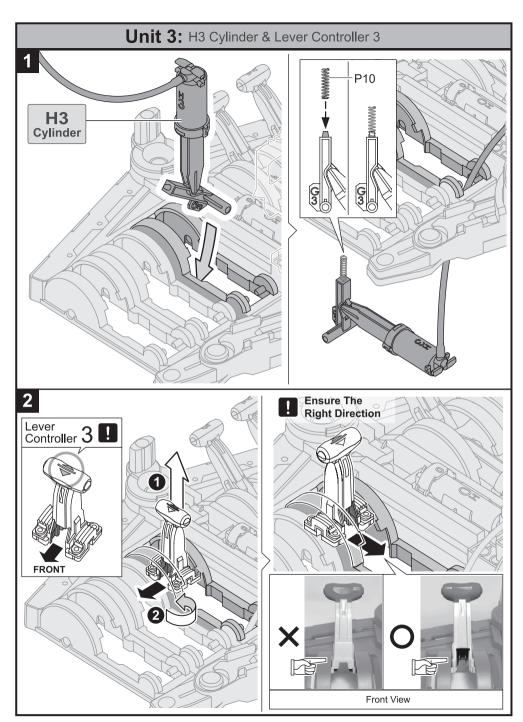


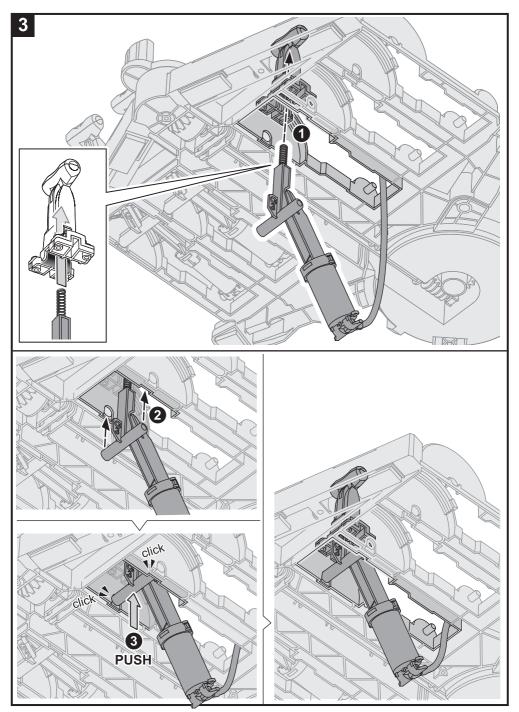


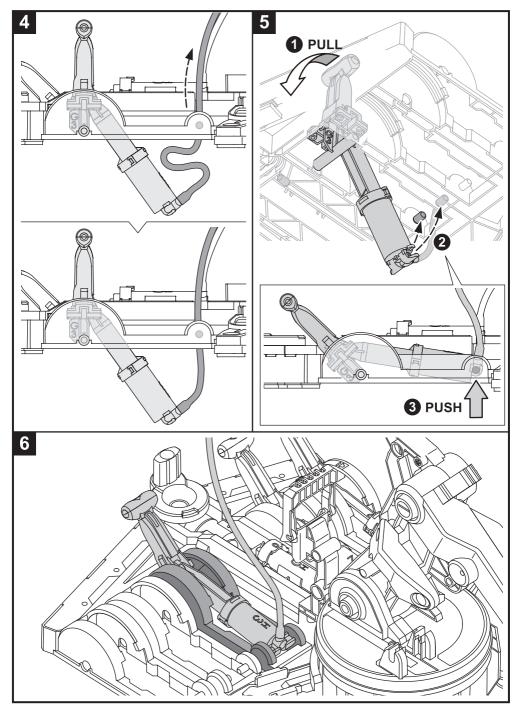


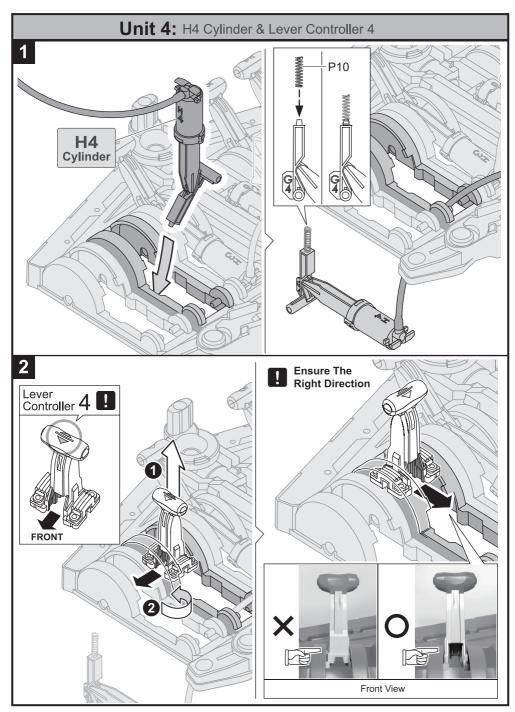


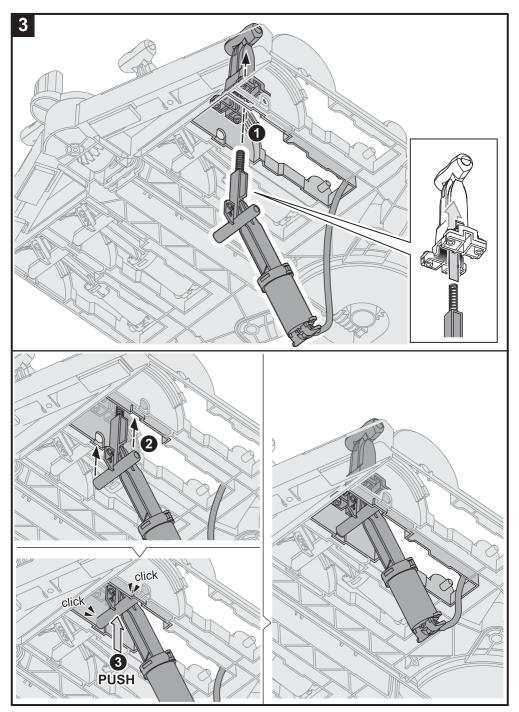


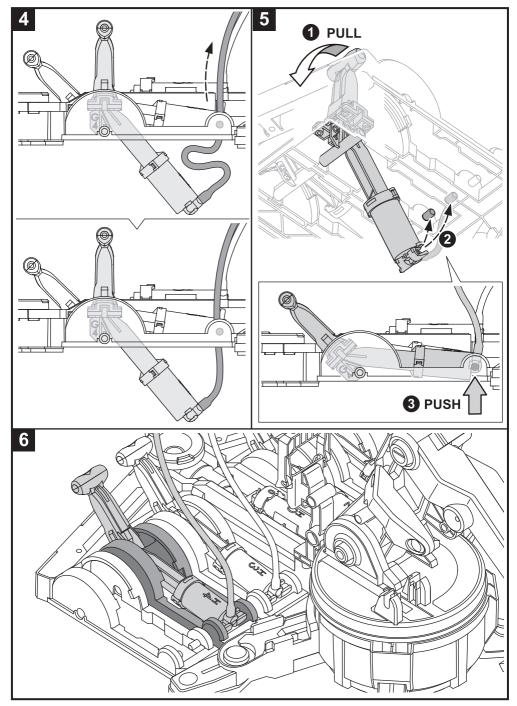


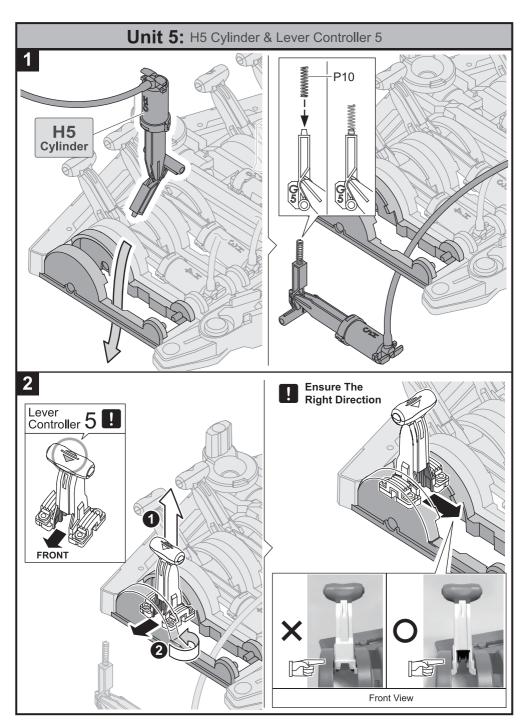


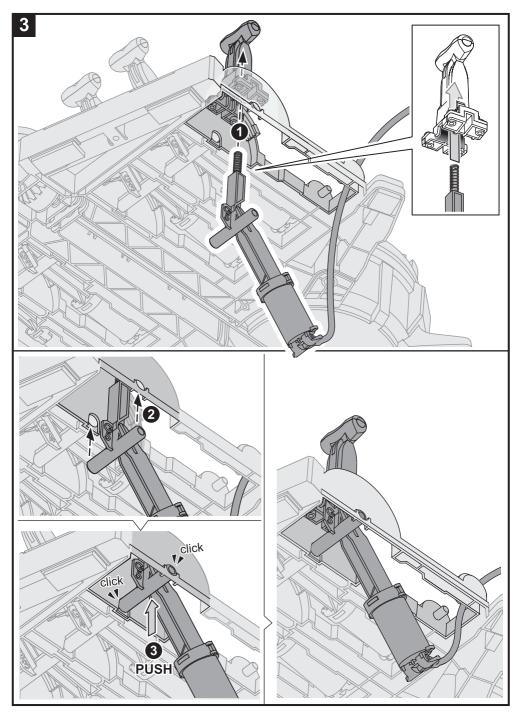


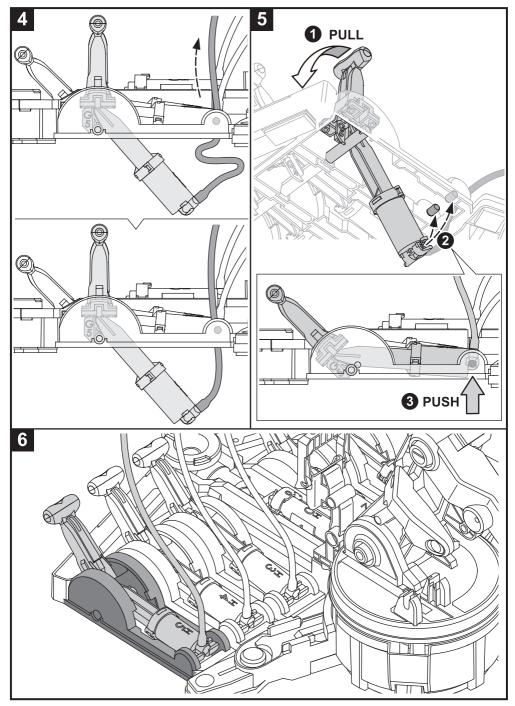




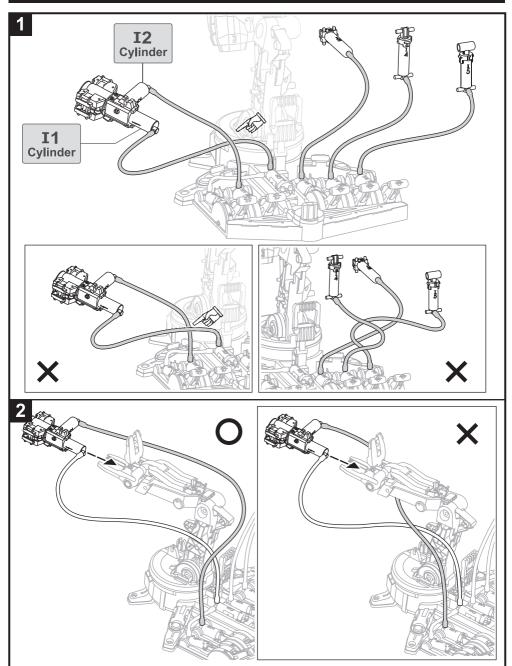


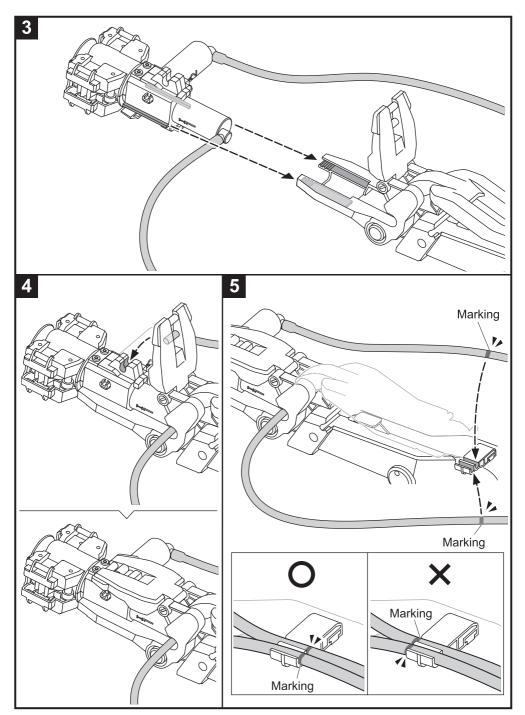


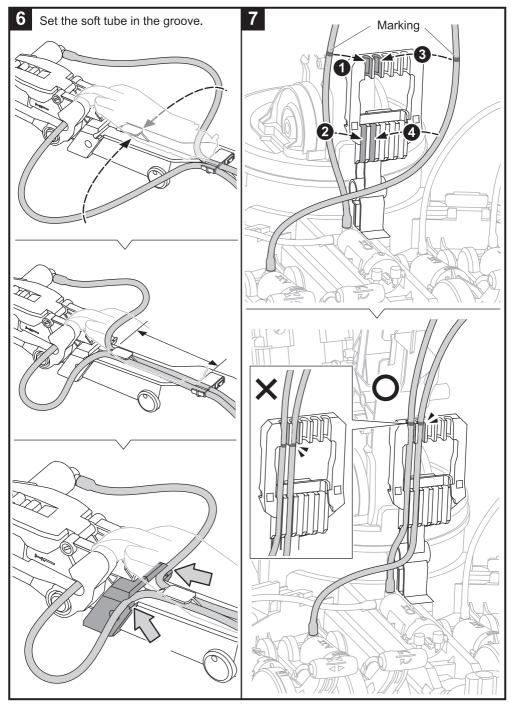


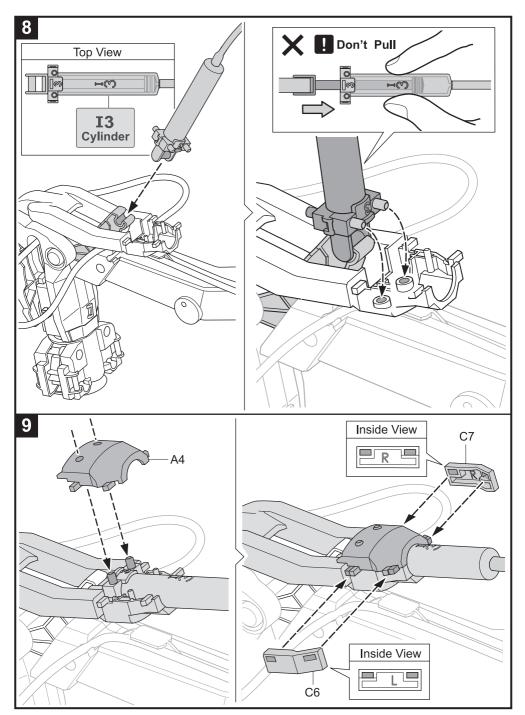


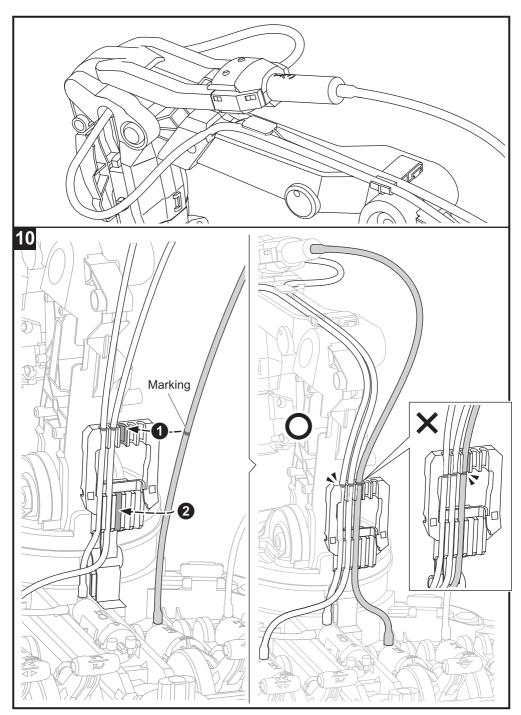
Robot Arm Module Assembly

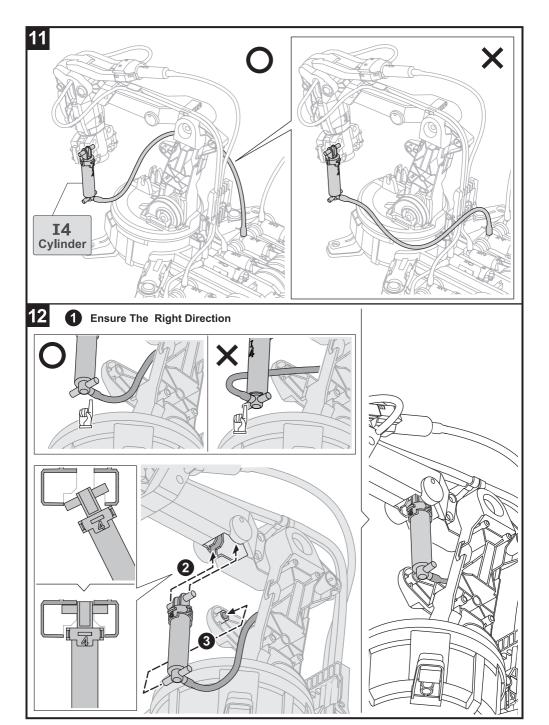


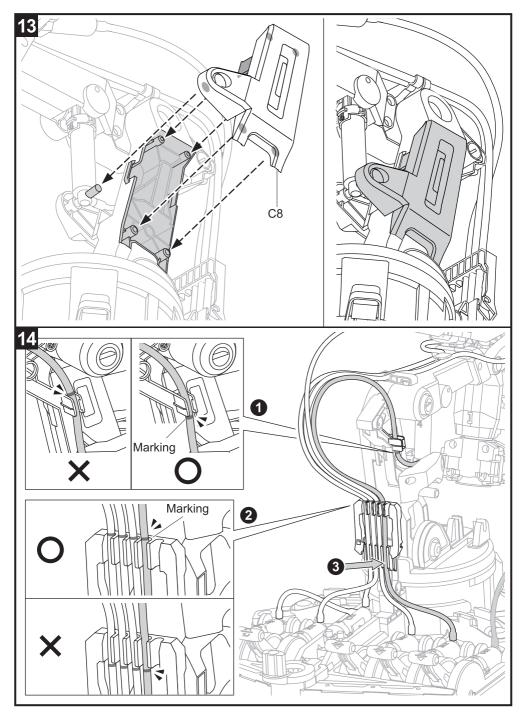


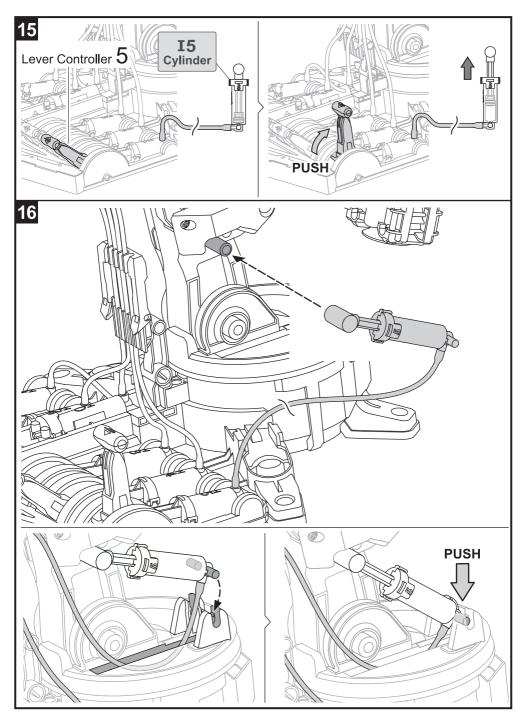


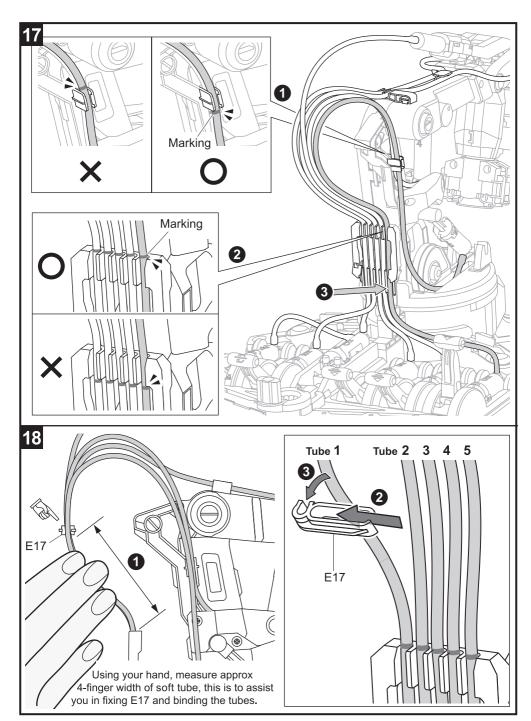


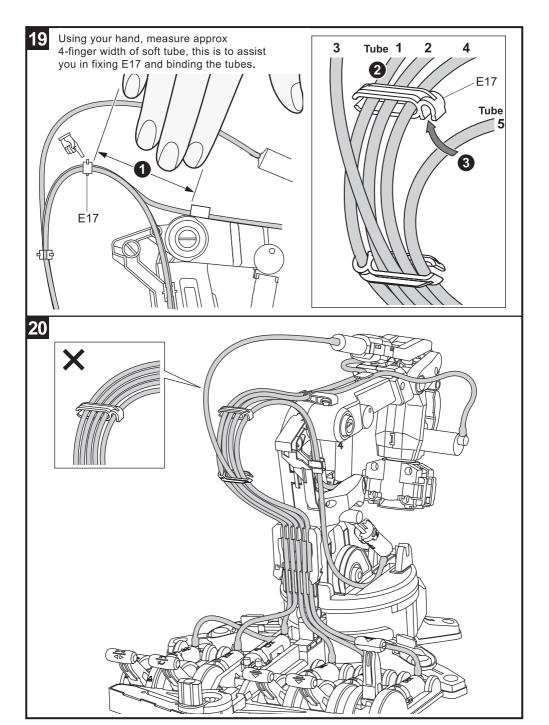




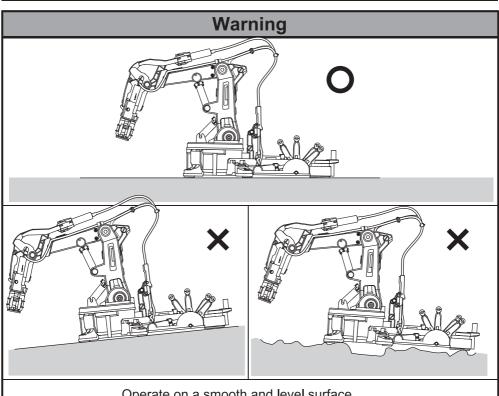


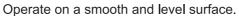


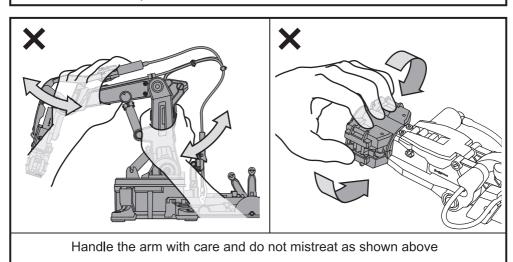


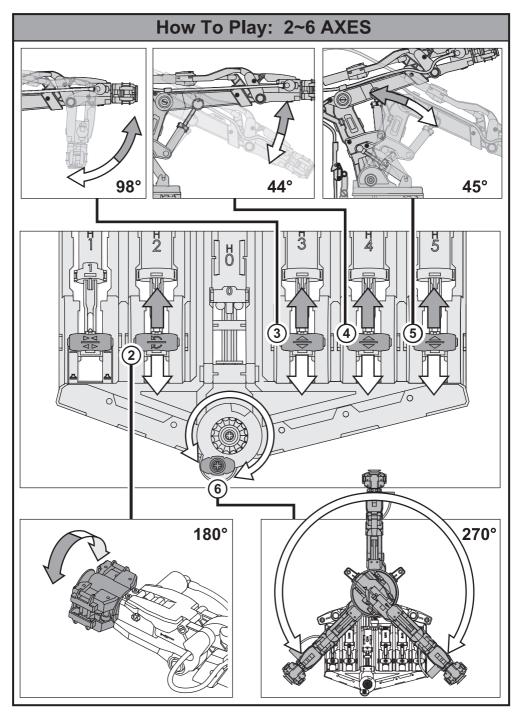


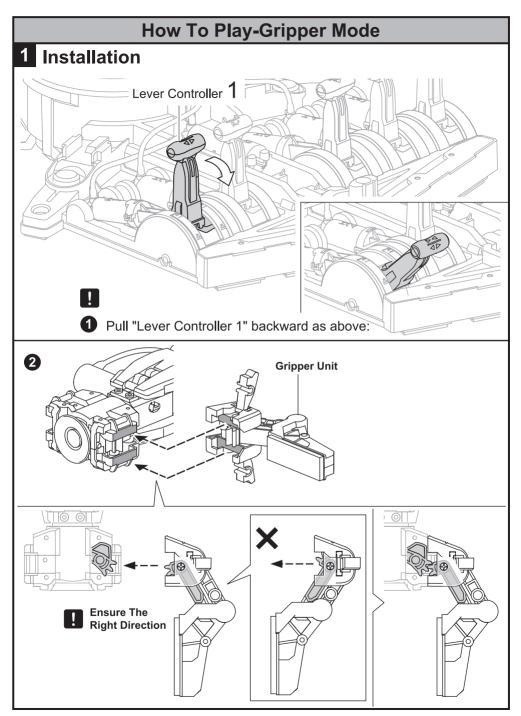
How To Play

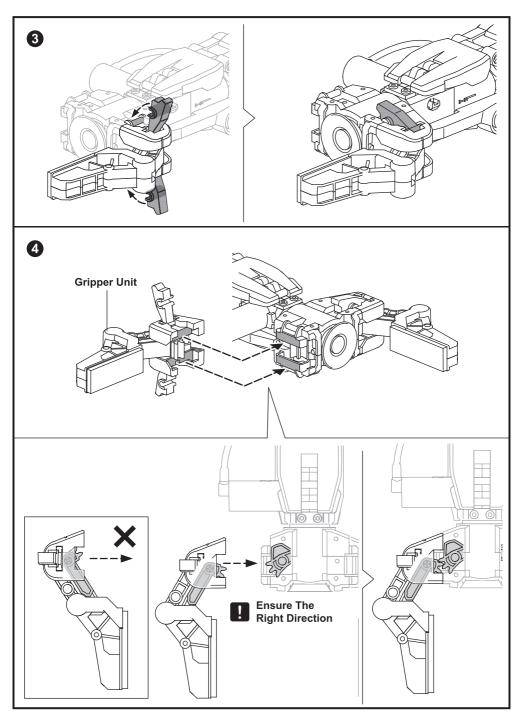


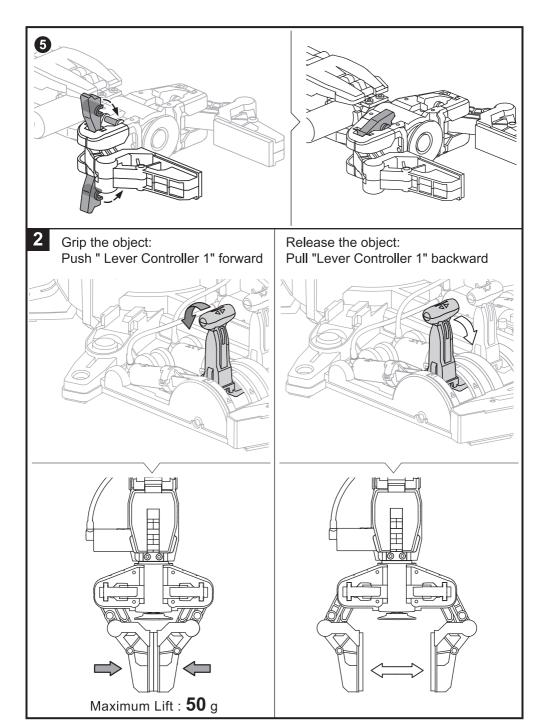






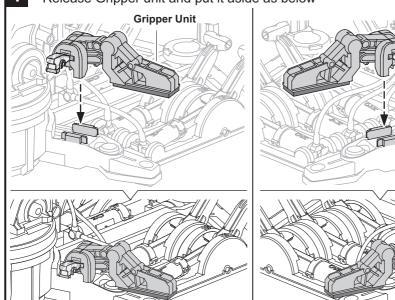




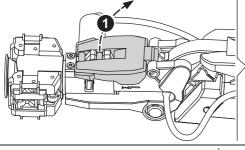


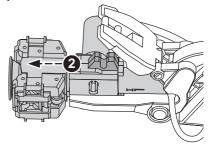
How To Play- Suction Mode

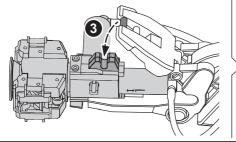
Release Gripper unit and put it aside as below

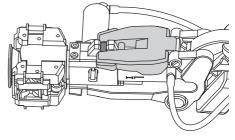


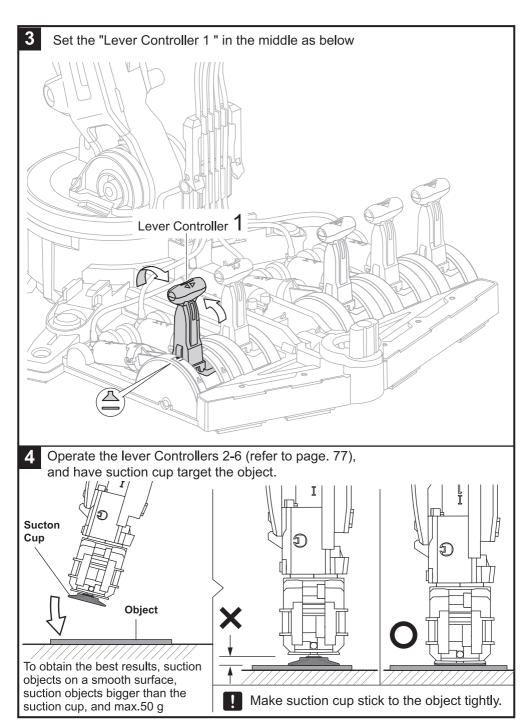
Wery Important !! Step 2 must be completely fulfilled under Suction Mode.

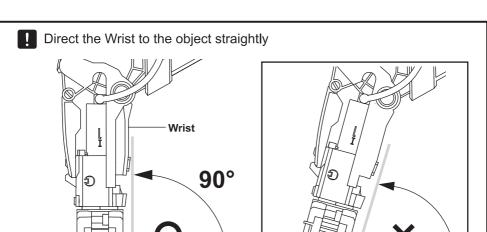


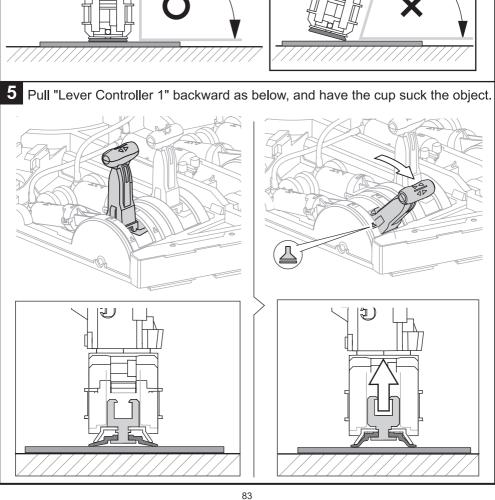


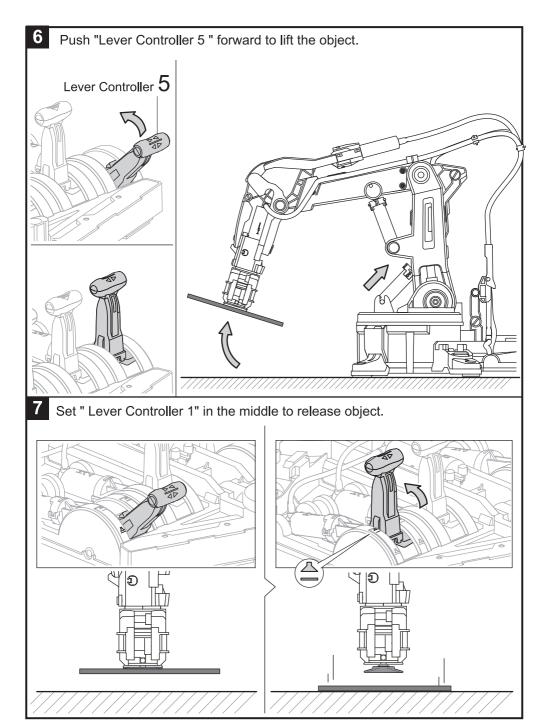


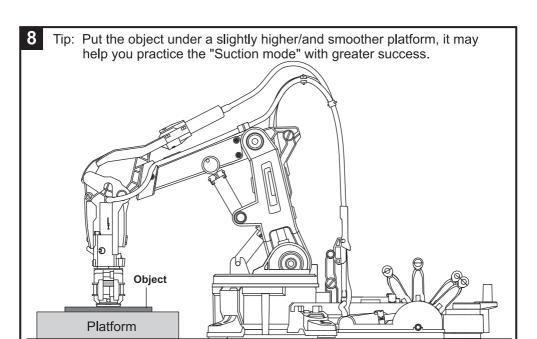






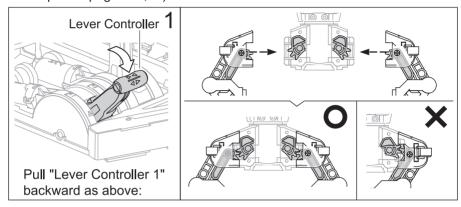




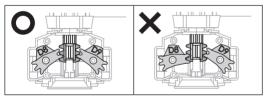


Trouble Shooting

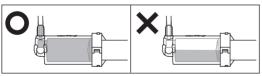
- If gripper unit does not work (open or close) functionally, please check following steps.
 - **1.**Check if gripper unit is installed in the correct position and direction (as below pics in pages 78,79)



2. Back to page 32, and check step 16 is correct.

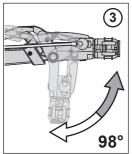


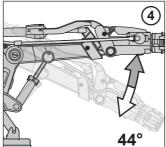
3. Check if there is excess air inside the Cylinder H1, I1 and Tube 1. In the case, back to pages 42-45 to re-assemble."

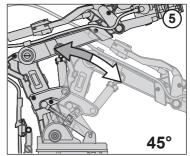


- If sunction cup cannot suck the objects under suction mode.
 - 1. Back to pages 81~84, and check if all steps 2~6 are installed correctly.
 - **2.** Check if there are excess air inside the Cylinder H1, I1 and Tube 1. In the case, back to pages 42-45 to re-assemble.

● If operation angle on the Axes 3/4/5 is unable to extend to the max.





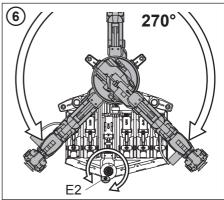


- **1.**Check if there is excess air inside the Cylinder H3/4/5, I3/4/5, and Tube 3/4/5, in that case, back to pages 37~40 to re-assemble.
- Check if all tubes are routing and not twisting during assembly. In the case of twisted tubes.
 - (a) back to pages 66~75 " Robot Arm Module Assembly " to check if all markings on the tubes are installed in the right position.
 - (b) back to Pages 46~48 " Measuring & Marking " to check if all lengths of tubes are cut and marked correctly.

■ Poor movement of the 6th Axe. 6

1.If 6th Axe doesnot move when rotating E2, back to Page 19, Step 13 and check if E10 is intalled in the right position.





- **2.** Check if all tubes are routing and not twisting during assembly. In the case of twisted tubes,
 - (a) back to pages 66~75 "Robot Arm Module Assembly" to check if all markings on the tubes are installed in the right position.
 - (b) back to Pages 46~48 " Measuring & Marking" to check if all lengths of tubes are cut and marked correctly.







