E6A2-C

CSM_F6A2-C_DS_F_4

Compact Encoder with External Diameter of 25 mm

- Incremental model
- External diameter of 25 mm.
- Resolution of up to 500 ppr.





Be sure to read *Safety Precautions* on page 3.

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Ordering Information

Encoders [Refer to Dimensions on page 4.]

Output phases	Power supply voltage	Output configuration	Resolution (pulses/rotation)	Model	
Phase A	5 to 12 VDC	Voltage output	10, 20, 60, 100, 200, 300, 360	E6A2-CS3E (resolution) 0.5M	
		Voltage output	500	Example: E6A2-CS3E 10P/R 0.5M	
		Open-collector output (NPN output)	10, 20, 60, 100, 200, 300, 360	E6A2-CS3C (resolution) 0.5M	
			500	Example: E6A2-CS3C 10P/R 0.5M	
	12 to 24 VDC		10, 20, 60, 100, 200, 300, 360	E6A2-CS5C (resolution) 0.5M	
			500	Example: E6A2-CS5C 10P/R 0.5M	
Phases A and B	5 to 12 VDC	Voltage output	100, 200, 360	E6A2-CW3E (resolution) 0.5M	
			500	Example: E6A2-CW3E 100P/R 0.5M	
		Open-collector output (NPN output)	100, 200, 360	E6A2-CW3C (resolution) 0.5M	
			500	Example: E6A2-CW3C 100P/R 0.5M	
	12 to 24 VDC		100, 200, 360	E6A2-CW5C (resolution) 0.5M	
			500	Example: E6A2-CW5C 100P/R 0.5M	
Phases A, B, and Z	5 to 12 VDC	Voltage output	100, 200, 360	E6A2-CWZ3E (resolution) 0.5M	
			500	Example: E6A2-CWZ3E 100P/R 0.5M	
		Open-collector output (NPN output)	100, 200, 360	E6A2-CWZ3C (resolution) 0.5M	
			500	Example: E6A2-CWZ3C 100P/R 0.5M	
	12 to 24 VDC		100, 200, 360	E6A2-CWZ5C (resolution) 0.5M	
			500	Example: E6A2-CWZ5C 100P/R 0.5M	

Accessories (Order Separately) [Refer to Dimensions on Rotary Encoder Accessories.]

Name	Model	Remarks					
Coupling	E69-C04B	Provided with the product.					
Servo Mounting Bracket	E69-1	Provided with the E6A2-CWZ□.					

Refer to Accessories for details.

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Ratings and Specifications

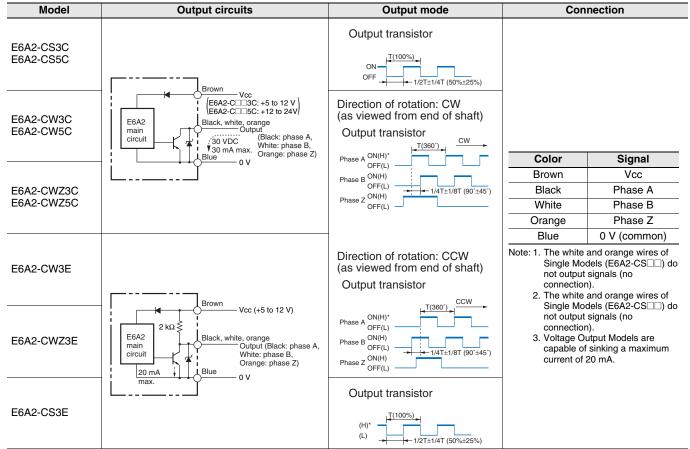
Item	Model	E6A2-CS3E	E6A2-CS3C	E6A2-CS5C	E6A2-CW3E	E6A2-CW3C	E6A2-CW5C	E6A2- CWZ3E	E6A2- CWZ3C	E6A2- CWZ5C
Power su voltage	wer supply 5 VDC –5% to 12 V +10%, ripple (p-p): 5% max. 12 VDC –10% to 24 VDC +15%, ripple (p-p): 5% max.		5 VDC –5% to 12 V +10%, ripple (p-p): 5% max. 12 VDC -10% to 24 VDC +15%, ripple (p-p): 5% max.		5 VDC –5% to 12 V +10% ripple (p-p): 5% max. 12 VDC -10% to 24 VDC +15%, ripp (p-p): 5% max.		-10% to 24 VDC +15%, ripple (p-p): 5%			
Current consump	otion*1	30 mA max. 20 mA max.		30 mA max.	20 mA max.		50 mA max.	30 mA max.		
Resolution)	on (pulses/	10, 20, 60, 100, 200, 300, 360, 500			100, 200, 360, 500					
Output pl	hases	Phase A			Phases A and B Phases A, B, and Z					
Output co	onfiguration	Voltage output NPN open-collector output		Voltage out- put	NPN open-collector output		Voltage out- put	NPN open-collector output		
Output capacity		Output resistance: $2 \text{ k}\Omega$ Output current: 20 mA max. Residual voltage: 0.4 V max. (Output current: 20 mA max.)	Applied voltage: 30 VDC max. Sink current: 30 mA max. Residual voltage: 0.4 V max. (at sink current of 30 mA)		Output resistance: $2 \text{ k}\Omega$ Output current: 20 mA max. Residual voltage: 0.4 V max. (Output current: 20 mA max.)	Applied voltage: 30 VDC max. Sink current: 30 mA max. Residual voltage: 0.4 V max. (at sink current of 30 mA)		Output resistance: 2 kΩ Output current: 20 mA max. Residual voltage: 0.4 V max. (Output current: 20 mA max.)	Applied voltage: 30 VDC max. Sink current: 30 mA max. Residual voltage: 0.4 V max. (at sink current of 30 mA)	
Maximum frequency	n response y*2	30 kHz								
Phase difference between outputs			Phase difference between phases A and B: 90°±45°							
Output di	uty factor	50±25%								
Rise and fall times of output		1.0 µs max. (Cable length: 500 mm, Sink current: 10 mA)	1.0 μs max. (Cable length: 500 mm, Control output voltage: 5 V, Load resistance: 1 $k\Omega$)		1.0 µs max. (Cable length: 500 mm, Sink current: 10 mA)	1.0 μs max. (Cable length: 500 mm, Control output voltage: 5 V, Load resistance: 1 $k\Omega$)		1.0 µs max. (Cable length: 500 mm, Sink current: 10 mA)	1.0 μ s max. (Cable length: 500 mm, Control output voltage: 5 V, Load resistance: 1 $k\Omega$)	
Starting torque 1 mN·m max										
Moment of	of inertia	1 × 10 ⁻⁷ kg⋅m ²	max.							
Shaft	Radial	10 N								
loading	Thrust	50 N								
Maximum permissil	n ble speed	5,000 r/min								
Ambient t range	temperature	Operating: -10 to 55°C (with no icing), Storage: -25 to 80°C (with no icing)								
Ambient l	humidity	Operating/storage: 35% to 85% (with no condensation)								
Insulation	n resistance	$20~\text{M}\Omega$ min. (at 500 VDC) between current-carrying parts and case								
Dielectric	strength	500 VAC, 50/60 Hz for 1 min between current-carrying parts and case								
Vibration	resistance	Destruction: 10 to 55 Hz, 1.5-mm double amplitude for 2 hours each in X, Y, and Z directions								
Shock res	sistance	Destruction: 50	00m/s² 3 times e	each in X, Y, an	d Z directions					
Degree of protection	f n*3	IEC 60529 IP50								
Connecti	on method	Pre-wired Models (Standard cable length: 500 mm)								
Material		Case: Aluminum alloy, Main unit: Aluminum, Shaft: SUS420J2, Mounting Bracket: Galvanized iron								
Weight (packed s	state)	Approx. 35 g								
Accessor	ries	Coupling, Serv	o Mounting Bra	cket (provided	with the E6A2-C	WZ□), Hexago	nal wrench, Inst	truction manual		

Maximum electrical response speed (rpm) = $\frac{\text{Maximum response frequency}}{\text{Resolution}} \times 60$ Resolution

^{*1.} An inrush current of approximately 9 A will flow for approximately 0.3 ms when the power is turned ON.
*2. The maximum electrical response speed is determined by the resolution and maximum response frequency as follows:

This means that the E6A2-C Rotary Encoder will not operate electrically if its speed exceeds the maximum electrical response speed. *3. No protection is provided against water or oil.

I/O Circuit Diagrams



Note: 1. *(H) and (L) indicate the output levels of Voltage Output Models.

Output A leads B by 1/4 T±1/8 T when the shaft revolves clockwise, while A lags behind B by 1/4 T±1/8 T when the shaft revolves counterclockwise.

Safety Precautions

Refer to Warranty and Limitations of Liability.



This product is not designed or rated for ensuring safety of persons either directly or indirectly. Do not use it for such purposes.



Precautions for Correct Use

Do not use the Encoder under ambient conditions that exceed the ratings.

Wiring

Spurious pulses may be generated when power is turned ON and OFF. Wait at least 0.1 s after turning ON the power to the Encoder before using the connected device, and stop using the connected device at least 0.1 s before turning OFF the power to the Encoder. Also, turn ON the power to the load only after turning ON the power to the Encoder.

3

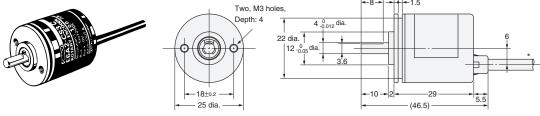
(Unit: mm)

Dimensions

Tolerance class IT16 applies to dimensions in this datasheet unless otherwise specified.

Encoder

E6A2-C



* 4-dia. vinyl-insulated round cable with 5 conductors (Conductor cross section: 0.14 mm², Insulator diameter: 0.9 mm), Standard length: 500 mm

Accessories (Order Separately)

Coupling Servo Mounting Bracket

E69-C04B E69-1 Refer to *Accessories* for details.

4

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