Magnetic rotary hollow-shaft position sensor/control

Contactless sensor
PST-360

The PST-360 through hole / hollow-shaft position sensors combine three critical design features; 1) through hole where the shaft passes through the sensor, 2) high accuracy absolute position feedback over up to 360 degrees, and 3) a true non-contacting sensing element. Piher’s design does not rely on gears or other rotating parts.

This innovative and unique patented design features the following advantages:
- Complements the attributes of the target application.
- Mechanical integrity that matches customer’s application by design.
- Unique shaft mounted design that mounts at the pivot point of the application.
- No levers, connecting rods or mechanical interfaces needed.
- Adapts to shaft’s eccentricity, mounting tolerances and mechanical wear over the life of the application.

### Mechanical specifications

<table>
<thead>
<tr>
<th>Specification</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Rotational life (depends on application and mounting)</td>
<td>up to 50,000,000 cycles.</td>
</tr>
<tr>
<td>Operating temperature</td>
<td>-40°C to +125°C.</td>
</tr>
</tbody>
</table>

### Electrical specifications

<table>
<thead>
<tr>
<th>Specification</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Linearity</td>
<td>±1% absolute (0.5% upon request).</td>
</tr>
<tr>
<td>Angular range</td>
<td>Programmable from 15 to 360 degrees.</td>
</tr>
<tr>
<td>Output</td>
<td>Analog (Ratiometric), PWM, Serial protocol (SPI) and CAN SAE J1939 upon request.</td>
</tr>
<tr>
<td>Switch output</td>
<td>Upon request. Programmable.</td>
</tr>
<tr>
<td>Angular Resolution</td>
<td>Analog &amp; PWM: up to 12 bits.</td>
</tr>
<tr>
<td>(depends on electrical angle and rotational speed)</td>
<td>Serial protocol (SPI): up to 14 bits.</td>
</tr>
<tr>
<td>Supply voltage</td>
<td>Up to 25V.</td>
</tr>
<tr>
<td>Supply current</td>
<td>Typ 8.5mA for single version.</td>
</tr>
<tr>
<td></td>
<td>Typ 17mA for redundant version.</td>
</tr>
</tbody>
</table>

1. Others-check availability. Ferromagnetic materials close to the sensor (i.e. shaft, mounting surface) may affect the sensor’s linearity. Please contact Piher for advice.

2. CAN protocol model: physical dimensions may vary. Check available versions before ordering.

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Piher Sensing Systems

Our product competencies and services:
- Potentiometers | Angular sensors | Rotary switches | Incremental encoders
- Printed circuit resistors | Mechatronics | Value added assemblies

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Key features

- Simple and robust magnetic design.
- High resolution (up to 14-bit).
- Ratiometric analog or PWM.
- Absolute position feedback up to 360° (keeps position on power loss).
- True full redundant version.
- Sealed construction for harsh environments such as off-highway and marine.
- Protected from dust, moisture, vibration and extreme temperatures.
- Endless rotation.
- Fully programmable transfer function output at the factory with electrical outputs up to 360°.
- Self-diagnostic features.
- Over voltage protection and reverse voltage protection.
- Extended voltage input supply values.

Also upon request:
- Programmable switch output.
- CAN and SPI output.

Industries served

- Automotive and On-highway (road vehicles, trucks, recreational vehicles, road sweepers).
- Off-highway (agriculture, construction and forestry, motorsport, airport operations).
- Material handling.
- Marine engines.
- Medical.
- Industrial.

Applications

- Non-contacting long life angle / position sensor.
- Absolute rotary position sensor.
- Pedal position sensor.
- Throttle / EGR valve and gear position sensor.
- Height and suspension sensor.
- Motor-shaft position sensor.
- Pivot point angle sensing.
- Off road / highway steering.
- Agricultural machinery hydraulic lift arms, scoops, articulation/joints.
- Forklifts / material handling.
- Industrial pumps.
- Accelerator / Steering / Shifter position sensor for marine outboard engine.
- Precision robotics, industrial equipment, HVACR monitoring & control, etc.
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How to order (example: PST360-1A-C0018-ERA190-05K)

Simple output

<table>
<thead>
<tr>
<th>PST360Q2</th>
<th>Rotor</th>
<th>Type</th>
<th>Output1</th>
<th>Output function</th>
<th>Electrical rotation angle</th>
<th>Voltage supply</th>
<th>Temp. range</th>
<th>PWM Frequency (Hz.)</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Series</strong></td>
<td>[empty] = 14mm B = 14mm (see note 1)</td>
<td>1 = simple</td>
<td></td>
<td>C0000 C0001 (see note 2)</td>
<td>ERA015 ERA016 ERA360</td>
<td>05 RE</td>
<td>K = 40 lb +125°C</td>
<td>F100 F999 (see note 5)</td>
</tr>
</tbody>
</table>

Redundant output

<table>
<thead>
<tr>
<th>PST360Q2</th>
<th>Rotor</th>
<th>Type</th>
<th>Output</th>
<th>Output function</th>
<th>Electrical rotation angle</th>
<th>Voltage supply</th>
<th>Temp. range</th>
<th>PWM Frequency (Hz.)</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Series</strong></td>
<td>[empty] = 14mm B = 17mm (see note 1)</td>
<td>2 = redundant</td>
<td>AA = Analogic PP = PWM (see note 2)</td>
<td>C0002 C0003 (see note 2)</td>
<td>ERA015 ERA016 ERA360</td>
<td>05 RE</td>
<td>K = 40 lb +125°C</td>
<td>F100 F999 (see note 5)</td>
</tr>
</tbody>
</table>

Full redundant output

<table>
<thead>
<tr>
<th>PST360Q2</th>
<th>Rotor</th>
<th>Type</th>
<th>Output</th>
<th>Output function</th>
<th>Electrical rotation angle</th>
<th>Voltage supply</th>
<th>Temp. range</th>
<th>PWM Frequency (Hz.)</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Series</strong></td>
<td>[empty] = 14mm B = 14mm (see note 1)</td>
<td>3 = full redundant</td>
<td>AA = Analogic PP = PWM (see note 2)</td>
<td>C0002 C0003 (see note 2)</td>
<td>ERA015 ERA016 ERA360</td>
<td>05 (see note 3)</td>
<td>K = 40 lb +125°C</td>
<td>F100 F999 (see note 5)</td>
</tr>
</tbody>
</table>

Other product configurations will be studied case by case.

(1) Other rotors: check availability.

(2) The analog output is a ratiometric output, proportional to:
- For supply voltage 5V: to input supply voltage.
- For supply voltage RE: to 5V.

(3) 05: 5V ±10%
    RE: 7V - 25V

(4) Other output functions available check availability in the How To Order reference, enter CXXX meanwhile the new output function reference is not defined.
    E.g.: PST360-1A-CXXX-ERA190-05K

(5) Leave empty if no applicable. Default frequency is 200 Hz
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Dimensions

Hollow shaft diameter 14mm.
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Dimensions
Hollow shaft diameter 17mm.

Mounting instructions
1. Place the component on a flat surface.
2. Fit the shaft of the application (see recommended shaft dimensions) through the sensor’s rotor avoiding any mechanical play/wobble.
3. Fasten the two M5 screws (M5 washers are recommended).

Rotor is shown at zero position
Sensor is delivered at random position.

Rotor - Detail A
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Connections scheme

Simple analog output connection wiring scheme. Other versions available upon request.

- Brown = Power supply.
- Blue = Ground.
- Black = Signal output.
- White = Not used.
- Grey = Not used.

Fly leads with Wire: 0.35mm². TXL SAE J1128.
Check availability for the connector options.

Output examples

Disclaimer

Ferromagnetic parts close to the sensor, including the shaft, may modify the performance of the sensor. Therefore, this has to be communicated to Pihers for prior analysis.

No external magnetic perturbations are considered on the application where the sensor is mounted. If so, amplitude and direction of flux density generator type and characteristics (magnet, cable, motor...) must be notified to Pihers.

The product information in this catalogue is for reference purposes. Please consult for the most up to date and accurate design information.

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