# ATV212HU55M3X

variable speed drive ATV212 - 5.5kW - 7.5hp - 240V - 3ph - wo EMC - IP21





#### Main

Range of product	Altivar 212
Product or component type	Variable speed drive
Device short name	ATV212
Product destination	Asynchronous motors
Product specific application	Pumps and fans in HVAC
Assembly style	With heat sink
Network number of phases	3 phases
Motor power kW	5.5 kW
Motor power hp	7.5 hp
[Us] rated supply voltage	200240 V - 1510 %
Supply voltage limits	170264 V
Supply frequency	5060 Hz - 55 %
Network frequency	47.563 Hz
EMC filter	Without EMC filter
Line current	17.3 A 240 V 20.8 A 200 V

#### Complementary

9.2 kVA 240 V	
22 kA	
24.2 A 230 V	
26.6 A 60 s	
0.5200 Hz	
12 kHz	
1216 kHz with derating factor 616 kHz adjustable	
110	
+/- 10 % of nominal slip 0.2 Tn to Tn	
+/- 15 %	
120 % of nominal motor torque +/- 10 % 60 s	
Voltage/frequency ratio, 2 points Voltage/frequency ratio, 5 points Flux vector control without sensor, standard Voltage/frequency ratio - Energy Saving, quadratic U/f Voltage/frequency ratio, automatic IR compensation (U/f + automatic Uo)	
Adjustable PI regulator	
Adjustable Automatic whatever the load Not available in voltage/frequency ratio motor control	
1 LED red DC bus energized	
<= power supply voltage	
Electrical between power and control	
IEC cable without mounting kit 1 45 °C copper 90 °C XLPE/EPR IEC cable without mounting kit 1 45 °C copper 70 °C PVC UL 508 cable with UL Type 1 kit 3 40 °C copper 75 °C PVC	
Terminal 2.5 mm² AWG 14 VIA, VIB, FM, FLA, FLB, FLC, RY, RC, F, R, RES Terminal 16 mm² AWG 6 L1/R, L2/S, L3/T	
2.5 N.m 22 lb.in L1/R, L2/S, L3/T 0.6 N.m VIA, VIB, FM, FLA, FLB, FLC, RY, RC, F, R, RES	

Supply	Internal supply for reference potentiometer (1 to 10 kOhm) 10.5 V DC +/- 5 % <= 10 A overload and short-circuit protection Internal supply 24 V DC 2127 V <= 200 A overload and short-circuit protection	
Analogue input number	2	
Analogue input type	Switch-configurable voltage VIA 010 V DC 24 V max 30000 Ohm 10 bits Configurable voltage VIB 010 V DC 24 V max 30000 Ohm 10 bits Configurable PTC probe VIB 06 probes 1500 Ohm Switch-configurable current VIA 020 mA 250 Ohm 10 bits	
Sampling duration	2 ms +/- 0.5 ms F discrete 2 ms +/- 0.5 ms R discrete 2 ms +/- 0.5 ms RES discrete 3.5 ms +/- 0.5 ms VIA analog 22 ms +/- 0.5 ms VIB analog	
Response time	2 ms +/- 0.5 ms FM analog 7 ms +/- 0.5 ms FLA, FLC discrete 7 ms +/- 0.5 ms FLB, FLC discrete 7 ms +/- 0.5 ms RY, RC discrete	
Accuracy	+/- 0.6 % VIA for a temperature variation 60 °C +/- 0.6 % VIB for a temperature variation 60 °C +/- 1 % FM for a temperature variation 60 °C	
Linearity error	+/- 0.15 % of maximum value input VIA +/- 0.15 % of maximum value input VIB +/- 0.2 % output FM	
Analogue output number	1	
Analogue output type	Switch-configurable voltage FM 010 V DC 7620 Ohm 10 bits Switch-configurable current FM 020 mA 970 Ohm 10 bits	
Discrete output number	2	
Discrete output type	Configurable relay logic FLA, FLC NO 100000 cycles Configurable relay logic FLB, FLC NC 100000 cycles Configurable relay logic RY, RC NO 100000 cycles	
Minimum switching current	3 mA 24 V DC configurable relay logic	
Maximum switching current	5 A 250 V AC resistive cos phi = 1 L/R = 0 ms FL, R 5 A 30 V DC resistive cos phi = 1 L/R = 0 ms FL, R 2 A 250 V AC inductive cos phi = 0.4 L/R = 7 ms FL, R 2 A 30 V DC inductive cos phi = 0.4 L/R = 7 ms FL, R	
Discrete input type	Programmable F 24 V DC level 1 PLC 4700 Ohm Programmable R 24 V DC level 1 PLC 4700 Ohm Programmable RES 24 V DC level 1 PLC 4700 Ohm	
Discrete input logic	Positive logic (source) F, R, RES <= 5 V >= 11 V Negative logic (sink) F, R, RES >= 16 V <= 10 V	
Acceleration and deceleration ramps	Automatic based on the load Linear adjustable separately from 0.01 to 3200 s	
Braking to standstill	By DC injection	
Protection type	Input phase breaks drive Line supply overvoltage and undervoltage drive Line supply undervoltage drive Overcurrent between output phases and earth drive Overheating protection drive Short-circuit between motor phases drive Thermal protection motor Motor phase break motor Break on the control circuit drive Thermal power stage drive Overvoltages on the DC bus drive Against exceeding limit speed drive Against input phase loss drive With PTC probes motor	
Dielectric strength	2830 V DC between earth and power terminals 4230 V DC between control and power terminals	
Insulation resistance	>= 1 MOhm 500 V DC for 1 minute	
Frequency resolution	0.1 Hz display unit 0.024/50 Hz analog input	
Communication port protocol	APOGEE FLN BACnet LonWorks METASYS N2 Modbus	
Connector type	1 RJ45 1 open style	



Physical interface	2-wire RS 485	
Transmission frame	RTU	
Transmission rate	9600 bps or 19200 bps	
Data format	8 bits, 1 stop, odd even or no configurable parity	
Type of polarization	No impedance	
Number of addresses	1247	
Communication service	Monitoring inhibitable Read device identification (43) Read holding registers (03) 2 words maximum Time out setting from 0.1 to 100 s Write multiple registers (16) 2 words maximum Write single register (06)	
Option card	Communication card LonWorks	
Operating position	Vertical +/- 10 degree	
Width	180 mm	
Height	232 mm	
Depth	170 mm	
Product weight	6.1 kg	
Power dissipation in W	249 W	
Air flow	85 m3/h	
Specific application	HVAC	
IP degree of protection	IP21	
Discrete and process manufacturing	Building - HVAC : compressor for scroll Building - HVAC : fan Building - HVAC : pump	
Power range	46 kW at 200240 V 3 phases	
Motor starter type	Variable speed drive	

# **Environment**

electromagnetic compatibility	1.2/50 µs - 8/20 µs surge immunity test level 3 IEC 61000-4-5 Electrical fast transient/burst immunity test level 4 IEC 61000-4-4 Electrostatic discharge immunity test level 3 IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 IEC 61000-4-3 Conducted radio-frequency immunity test level 3 IEC 61000-4-6	
nallytian dagge	Voltage dips and interruptions immunity test IEC 61000-4-11  3 IEC 61800-5-1	
pollution degree  IP degree of protection	IP20 on upper part without blanking plate on cover EN/IEC 61800-5-1 IP20 on upper part without blanking plate on cover EN/IEC 60529 IP21 EN/IEC 61800-5-1 IP21 EN/IEC 60529 IP41 on upper part EN/IEC 61800-5-1 IP41 on upper part EN/IEC 60529	
vibration resistance	1.5 mm 313 Hz EN/IEC 60068-2-6 1 gn 13200 Hz EN/IEC 60068-2-8	
shock resistance	15 gn 11 ms IEC 60068-2-27	
environmental characteristic	Classes 3C1 IEC 60721-3-3 Classes 3S2 IEC 60721-3-3	
noise level	51 dB 86/188/EEC	
operating altitude	<= 1000 m without derating 10003000 m limited to 2000 m for the Corner Grounded distribution network with current derating 1 % per 100 m	
relative humidity	595 % without condensation IEC 60068-2-3 595 % without dripping water IEC 60068-2-3	
ambient air temperature for operation	-1040 °C without derating > 4050 °C with derating factor	
ambient air temperature for storage	-2570 °C	
standards	EN 61800-3 EN 61800-3 environments 1 category C1 EN 61800-3 environments 1 category C2 EN 61800-3 environments 1 category C3 EN 61800-3 environments 2 category C1 EN 61800-3 environments 2 category C2 EN 61800-3 environments 2 category C3 EN 61800-5-1	



marking	CE	
product certifications	CSA C-Tick NOM 117 UL	
	IEC 61800-3 IEC 61800-3 environments 1 category C1 IEC 61800-3 environments 1 category C2 IEC 61800-3 environments 1 category C3 IEC 61800-3 environments 2 category C1 IEC 61800-3 environments 2 category C2 IEC 61800-3 environments 2 category C3 IEC 61800-5-1 UL Type 1	

# Offer Sustainability

Sustainable offer status	Green Premium product	
RoHS (date code: YYWW)	Compliant - since 1101 - Schneider Electric declaration of conformity	
REACh	Reference not containing SVHC above the threshold	
Product environmental profile	Available	
Product end of life instructions	Available	

### Contractual warranty

<u>-</u>		
Warranty period	18 months	

### **Dimensions**

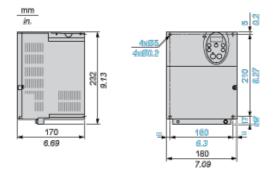
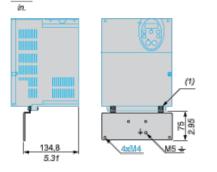


Plate for EMC mounting (supplied with the drive)



(1) 2 x M5 screws

# **Mounting Recommendations**

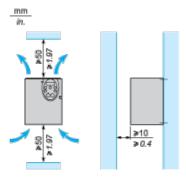
#### Clearance

Depending on the conditions in which the drive is to be used, its installation will require certain precautions and the use of appropriate accessories.

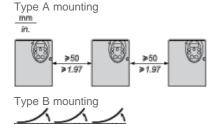
Install the unit vertically:

- Do not place it close to heating elements.
- Leave sufficient free space to ensure that the air required for cooling purposes can circulate from bottom to the top of the unit.

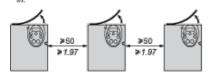




#### **Mounting Types**





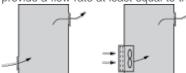


By removing the protective blanking cover from the top of the drive, the degree of protection for the drive becomes IP21. The protective blanking cover may vary according to the drive model, see opposite.

### Specific Recommendations for Mounting in an Enclosure

To help ensure proper air circulation in the drive:

- Fit ventilation grilles.
- Check that there is sufficient ventilation. If there is not, install a forced ventilation unit with a filter. The openings and/or fans must provide a flow rate at least equal to that of the drive fans (refer to the product characteristics).



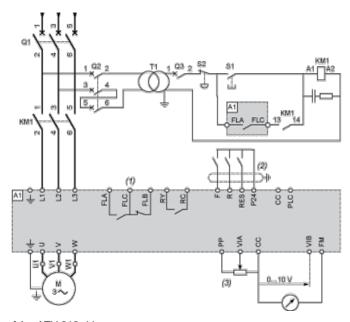
- Use special filters with UL Type 12/IP54 protection.
- Remove the blanking cover from the top of the drive.

### Sealed Metal Enclosure (IP54 Degree of Protection)

The drive must be mounted in a dust and damp proof enclosure in certain environmental conditions, such as dust, corrosive gases, high humidity with risk of condensation and dripping water, splashing liquid, etc. This enables the drive to be used in an enclosure where the maximum internal temperature reaches 50°C.

#### **Recommended Wiring Diagram**

3-Phase Power Supply



A1: ATV 212 drive

KM1:Contactor

Q1: Circuit breaker

Q2: GV2 L rated at twice the nominal primary current of T1

Q3: GB2CB05

S1, XB4 B or XB5 A pushbuttons

S2:

T1: 100 VA transformer 220 V secondary

- (1) Fault relay contacts for remote signalling of the drive status
- (2) Connection of the common for the logic inputs depends on the positioning of the switch (Source, PLC, Sink)
- (3) Reference potentiometer SZ1RV1202

**NOTE:** All terminals are located at the bottom of the drive. Install interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

#### **Switches (Factory Settings)**

Voltage/current selection for analog I/O (VIA and VIB)



Voltage/current selection for analog I/O (FM)



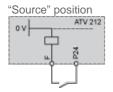
Selection of logic type

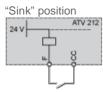


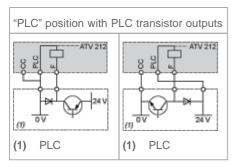
- (1) negative logic
- (2) positive logic

### **Other Possible Wiring Diagrams**

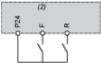
#### Logic Inputs According to the Position of the Logic Type Switch







2-wire control

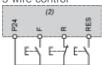


F: Forward

R: Preset speed

(2) ATV 212 control terminals

3-wire control



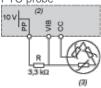
F: Forward

R: Stop

**RES:**Reverse

(2) ATV 212 control terminals

PTC probe

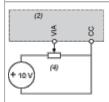


- (2) ATV 212 control terminals
- (3) Motor

#### **Analog Inputs**

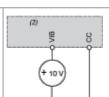
Voltage analog inputs





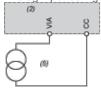
(2) ATV 212 control terminals

(4) Speed reference potentiometer 2.2 to  $10 \text{ k}\Omega$ 



(2) ATV 212 control terminals

Analog input configured for current: 0-20 mA, 4-20 mA, X-Y mA



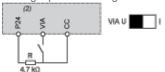
- (2) ATV 212 control terminals
- (5) Source 0-20 mA, 4-20 mA, X-Y mA

Analog input VIA configured as positive logic input ("Source" position)



### (2) ATV 212 control terminals

Analog input VIA configured as negative logic input ("Sink" position)

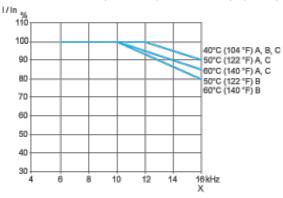


(2) ATV 212 control terminals

# **Derating Curves**

The derating curves for the drive nominal current (In) depend on the temperature, the switching frequency and the mounting type (A, B or C).

For intermediate temperatures (45°C for example), interpolate between 2 curves.



X Switching frequency