

# ATV650U55N4E

variable speed drive ATV650 - 5.5kW/7.5HP -  
380...480V - IP55 - disconnect switch



## Main

Range of product	Altivar Process ATV600
Product or component type	Variable speed drive
Product specific application	Process and utilities
Device short name	ATV650
Variant	With disconnect switch
Product destination	Asynchronous motors Synchronous motors
Mounting mode	Wall mount
EMC filter	Integrated EN/IEC 61800-3 category C3 <= 150 m Integrated EN/IEC 61800-3 category C2 <= 50 m
IP degree of protection	IP55 conforming to IEC 60529 IP55 conforming to IEC 61800-5-1
Type of cooling	Forced convection
Supply frequency	50...60 Hz - 5...5 %
Network number of phases	3 phases
[Us] rated supply voltage	380...480 V - 15...10 %
Motor power kW	5.5 kW normal duty 4 kW heavy duty
Motor power hp	7.5 hp normal duty 5 hp heavy duty
Line current	10.4 A 380 V normal duty 9.1 A 480 V normal duty 8 A 380 V heavy duty 7.2 A 480 V heavy duty
Prospective line I <sub>sc</sub>	50 kA
Apparent power	7.6 kVA 480 V normal duty 6 kVA 480 V heavy duty
Continuous output current	12.7 A 4 kHz normal duty 9.3 A 4 kHz heavy duty
Maximum transient current	14 A 60 s normal duty 14 A 60 s heavy duty
Asynchronous motor control profile	Constant torque standard Variable torque standard Optimized torque mode
Synchronous motor control profile	Permanent magnet motor Synchronous reluctance motor
Output frequency	0.0001...0.5 kHz
Speed drive output frequency	0.1...599 Hz
Nominal switching frequency	4 kHz
Switching frequency	2...12 kHz adjustable 4...12 kHz with derating factor
Safety function	STO (safe torque off) SIL 3
Discrete input logic	16 preset speeds
Communication port protocol	Ethernet Modbus serial Modbus TCP
Option card	Communication module Profibus DP V1 slot A Communication module Profinet slot A Communication module DeviceNet slot A Communication module Modbus TCP/EtherNet/IP slot A Communication module CANopen daisy chain RJ45 slot A

The information provided in this documentation contains general descriptions and/or technical characteristics of the performance of the products contained herein. This documentation is not intended as a substitute for and is not to be used for determining suitability or reliability of these products for specific user applications. It is the duty of any such user or integrator to perform the appropriate and complete risk analysis, evaluation and testing of the products with respect to the relevant specific application or use thereof. Neither Schneider Electric Industries SAS nor any of its affiliates or subsidiaries shall be responsible or liable for misuse of the information contained herein.

Communication module CANopen SUB-D 9 slot A  
 Communication module CANopen screw terminals slot A  
 Digital and analog I/O extension module slot A/slot B  
 Output relay extension module slot A/slot B  
 Communication module Ethernet IP/Modbus TCP/MD-Link slot A  
 Communication module BACnet MS/TP  
 Communication module Ethernet Powerlink

## Complementary

Output voltage	<= power supply voltage
Permissible temporary current boost	1.1 x I <sub>n</sub> 60 s normal duty 1.5 x I <sub>n</sub> 60 s heavy duty
Motor slip compensation	Adjustable Automatic whatever the load Can be suppressed Not available in permanent magnet motor law
Acceleration and deceleration ramps	Linear adjustable separately from 0.01...9999 s
Braking to standstill	By DC injection
Protection type	Line supply overvoltage drive Line supply phase loss drive Line supply undervoltage drive Overcurrent between output phases and earth drive Thermal protection motor Thermal protection drive Safe torque off motor Motor phase break motor Safe torque off drive Overheating drive Short-circuit protection drive Motor phase break drive Overspeed drive Break on the control circuit drive Overvoltages on the DC bus drive Overload of output voltage drive
Frequency resolution	Display unit Analog input
Electrical connection	Removable screw terminals 0.5...1.5 mm <sup>2</sup> control Screw terminal 4...6 mm <sup>2</sup> line side Screw terminal 4...6 mm <sup>2</sup> motor
Connector type	RJ45 Ethernet/Modbus TCP on the remote graphic terminal RJ45 Modbus serial on the remote graphic terminal
Physical interface	2-wire RS 485 Modbus serial
Transmission frame	RTU Modbus serial
Transmission rate	10/100 Mbit/s Ethernet IP/Modbus TCP 4.8, 9.6, 19.2, 38.4 kbit/s Modbus serial
Exchange mode	Half duplex, full duplex, autonegotiation Ethernet/Modbus TCP
Data format	8 bits, configurable odd, even or no parity Modbus serial
Type of polarization	No impedance Modbus serial
Number of addresses	1...247 Modbus serial
Method of access	Slave Modbus TCP
Supply	Internal supply for reference potentiometer (1 to 10 kOhm) 10.5 V DC +/- 5 % <= 10 mA overload and short-circuit protection External supply for digital inputs 24 V DC 19...30 V <= 1.25 mA overload and short-circuit protection Internal supply for digital inputs and STO 24 V DC 21...27 V <= 200 mA overload and short-circuit protection
Local signalling	3 LEDs local diagnostic 3 LEDs dual colour embedded communication status 4 LEDs dual colour communication module status 1 LED red presence of voltage
Width	264 mm
Height	678 mm
Depth	300 mm
Product weight	10.7 kg
Analogue input number	3

Analogue input type	Software-configurable voltage AI1, AI2, AI3 0...10 V DC 30 kOhm 12 bits Software-configurable current AI1, AI2, AI3 0...20 mA/4...20 mA 250 Ohm 12 bits
Discrete input number	8
Discrete input type	Programmable DI1...DI6 24 V DC 3.5 kOhm Programmable as pulse input DI5, DI6 0...30 kHz 24 V DC Safe torque off STOA, STOB 24 V DC > 2.2 kOhm
Input compatibility	Level 1 PLC EN/IEC 61131-2 DI1...DI6 discrete input Level 1 PLC IEC 65A-68 DI5, DI6 discrete input Level 1 PLC EN/IEC 61131-2 STOA, STOB discrete input
Discrete input logic	Positive logic (source) DI1...DI6 < 5 V > 11 V Negative logic (sink) DI1...DI6 > 16 V < 10 V Positive logic (source) DI5, DI6 < 0.6 V > 2.5 V Positive logic (source) STOA, STOB < 5 V > 11 V
Analogue output number	2
Analogue output type	Software-configurable voltage AO1, AO2 0...10 V DC 470 Ohm 10 bits Software-configurable current AO1, AO2 0...20 mA 10 bits
Sampling duration	2 ms +/- 0.5 ms DI1...DI4 discrete input 5 ms +/- 1 ms DI5, DI6 discrete input 5 ms +/- 0.1 ms AI1, AI2, AI3 analog input 10 ms +/- 1 ms AO1 analog output
Accuracy	+/- 0.6 % AI1, AI2, AI3 for a temperature variation 60 °C analog input +/- 1 % AO1, AO2 for a temperature variation 60 °C analog output
Linearity error	+/- 0.15 % of maximum value analog input AI1, AI2, AI3 +/- 0.2 % analog output AO1, AO2
Relay output number	3
Relay output type	Configurable relay logic R1 fault relay NO/NC 100000 cycles Configurable relay logic R2 sequence relay NO 100000 cycles Configurable relay logic R3 sequence relay NO 100000 cycles
Refresh time	5 ms +/- 0.5 ms R1, R2, R3 relay output
Minimum switching current	5 mA 24 V DC R1, R2, R3 relay output
Maximum switching current	3 A 250 V AC resistive 1 R1, R2, R3 relay output 3 A 30 V DC resistive 1 R1, R2, R3 relay output 2 A 250 V AC inductive 0.4 7 ms R1, R2, R3 relay output 2 A 30 V DC inductive 0.4 7 ms R1, R2, R3 relay output
Isolation	Between power and control terminals
IP degree of protection	IP55

## Environment

insulation resistance	> 1 mOhm 500 V DC for 1 minute to earth
noise level	52 dB 86/188/EEC
operating position	Vertical +/- 10 degree
THDI	<= 48 % full load IEC 61000-3-12
electromagnetic compatibility	1.2/50 µs - 8/20 µs surge immunity test level 3 IEC 61000-4-5 Electrical fast transient/burst immunity test level 4 IEC 61000-4-4 Electrostatic discharge immunity test level 3 IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 IEC 61000-4-3 Conducted radio-frequency immunity test level 3 IEC 61000-4-6
pollution degree	2 EN/IEC 61800-5-1
vibration resistance	1.5 mm peak to peak 2...13 Hz IEC 60068-2-6 1 gn 13...200 Hz IEC 60068-2-6
shock resistance	15 gn 11 ms IEC 60068-2-27
relative humidity	5...95 % without condensation IEC 60068-2-3
ambient air temperature for operation	-15...40 °C without derating 40...50 °C with derating factor
ambient air temperature for storage	-40...70 °C
operating altitude	<= 1000 m without derating 1000...4800 m with current derating 1 % per 100 m
environmental characteristic	Chemical pollution resistance class 3C3 EN/IEC 60721-3-3 Dust pollution resistance class 3S3 EN/IEC 60721-3-3
standards	EN/IEC 61800-3 EN/IEC 61800-3 environment 1 category C2 EN/IEC 61800-3 environment 2 category C3 EN/IEC 61800-5-1 IEC 61000-3-12

IEC 60721-3  
IEC 61508  
IEC 13849-1

product certifications

ATEX INERIS  
ATEX zone 2/22  
CSA  
TÜV  
UL  
REACH  
DNV-GL

marking

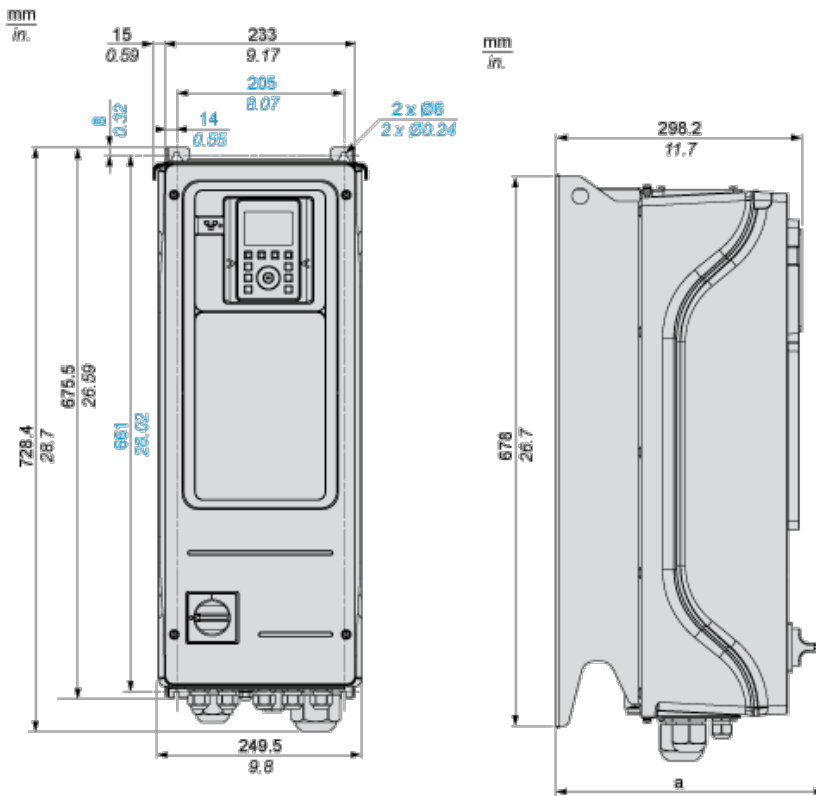
CE

## Offer Sustainability

Sustainable offer status	Green Premium product
RoHS (date code: YYWW)	Compliant - since 1526 - Schneider Electric declaration of conformity
REACH	Reference not containing SVHC above the threshold
Product environmental profile	Available
Product end of life instructions	Available

## Dimensions

### Front and Left Views



(a) = 300 mm (11.8 in.)

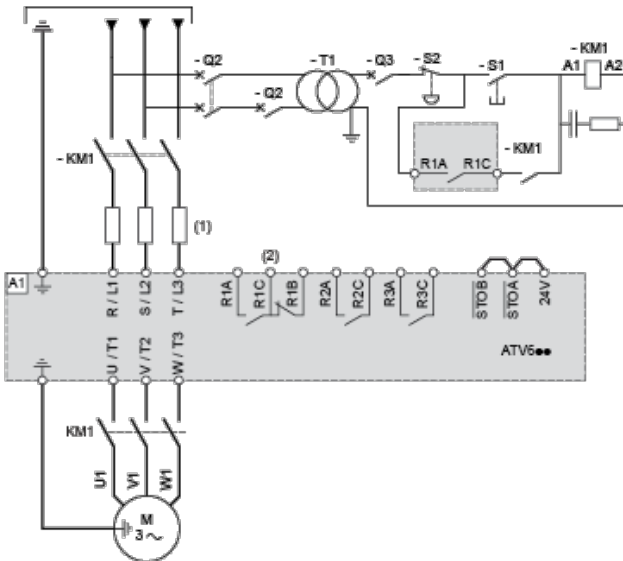
## Clearances



X1	X2	X3
≥ 100 mm (3.94 in.)	≥ 100 mm (3.94 in.)	≥ 10 mm (0.39 in.)

### Three-Phase Power Supply with Upstream Breaking via Line Contactor

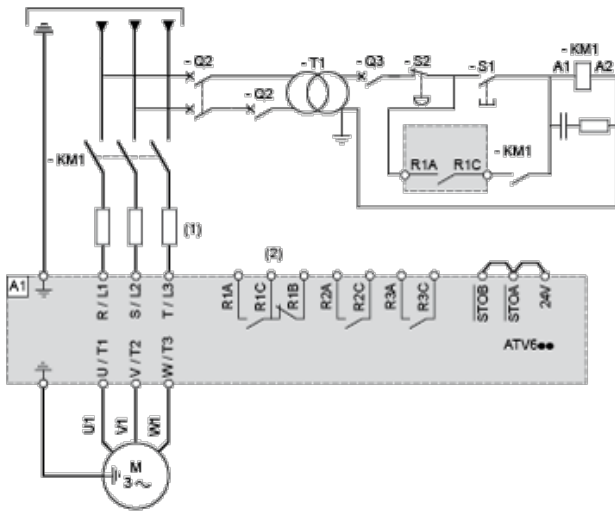
Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1



- (1) Line choke if used
  - (2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.
- A1 : Drive  
 KM1 :Line Contactor  
 Q2, Circuit breakers  
 Q3 :  
 S1, Pushbuttons  
 S2 :  
 T1 : Transformer for control part

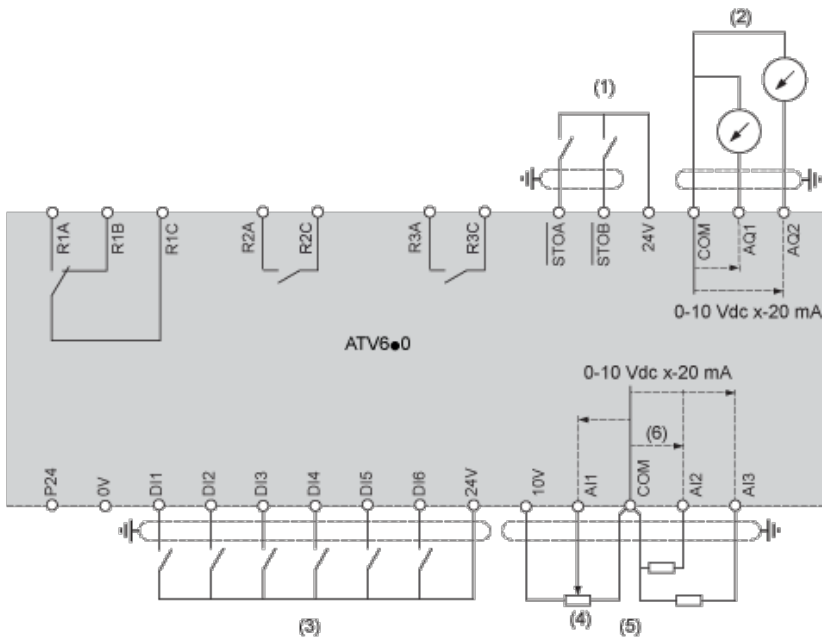
### Three-Phase Power Supply with Downstream Breaking via Contactor

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1



- (1) Line choke if used
  - (2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.
- A1 : Drive  
 KM1 : Contactor

### Control Block Wiring Diagram

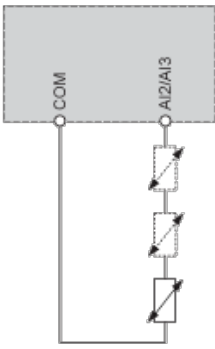


- (1) Safe Torque Off
- (2) Analog Output
- (3) Digital Input
- (4) Reference potentiometer
- (5) Analog Input

R1A, Fault relay  
 R1B,  
 R1C :  
 R2A, Sequence relay  
 R2C :  
 R3A, Sequence relay  
 R3C :

### Sensor Connection

It is possible to connect either 1 or 3 sensors on terminals AI2 or AI3.

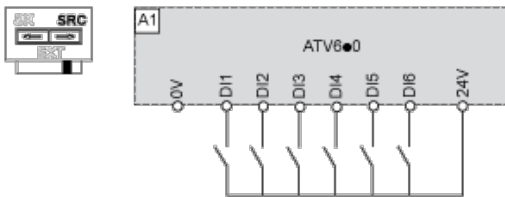


## Sink / Source Switch Configuration

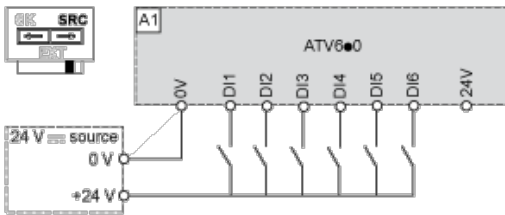
The switch is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs.

- ▮ Set the switch to Source (factory setting) if using PLC outputs with PNP transistors.
- ▮ Set the switch to Ext if using PLC outputs with NPN transistors.

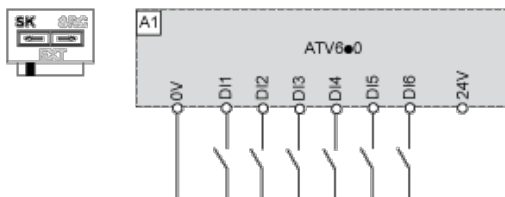
### Switch Set to SRC (Source) Position Using the Output Power Supply for the Digital Inputs



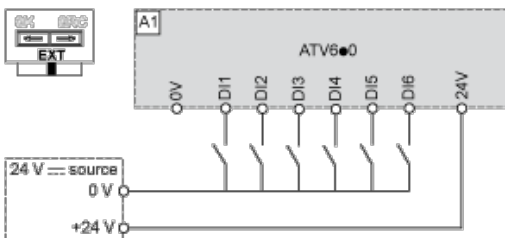
### Switch Set to SRC (Source) Position and Use of an External Power Supply for the DIs



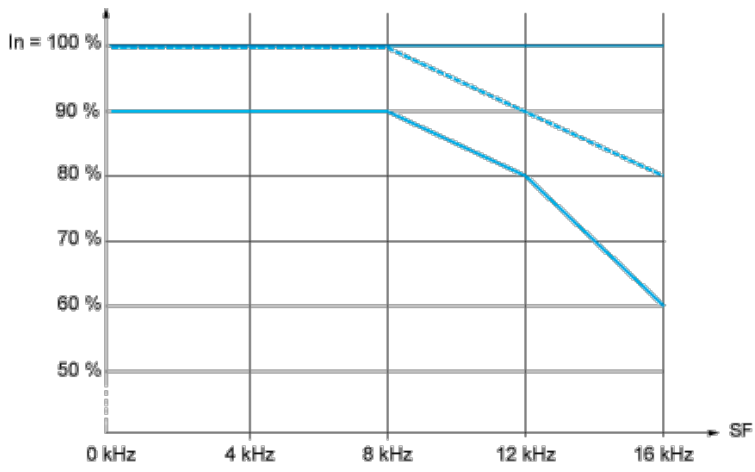
### Switch Set to SK (Sink) Position Using the Output Power Supply for the Digital Inputs



### Switch Set to EXT Position Using an External Power Supply for the DIs



## Derating Curves



— 40 °C (104 °F)

- - - 45 °C (113 °F)

— 50 °C (122 °F)

In : Nominal Drive Current

SF : Switching Frequency