

## **Product Change Notification - SYST-14YADM309**

Date:

17 Jun 2019

**Product Category:** 

Memory

**Affected CPNs:** 



#### **Notification subject:**

Data Sheet - AT25512 - SPI Serial EERPOM 512 Kbits Complete Datasheet

#### **Notification text:**

SYST-14YADM309

Microchip has released a new DeviceDoc for the AT25512 - SPI Serial EERPOM 512 Kbits Complete Datasheet of devices. If you are using one of these devices please read the document located at AT25512 - SPI Serial EERPOM 512 Kbits Complete Datasheet.

**Notification Status: Final** 

**Description of Change:** 1) Updated to the Microchip template. 2) Microchip DS20006218 replaces Atmel document 5165. 3) Updated Part Marking Information. 4) Added ESD rating. 5) Removed lead finish designation. 6) Added POR recommendations section. 7) Changed Data Retention spec to 100 year. 8) Updated trace code format in package markings. 9) Updated section content throughout for clarification. 10) Updated the SOIC, TSSOP and UDFN package drawings to the Microchip equivalents.

Impacts to Data Sheet: None

**Reason for Change:** To Improve Manufacturability

**Change Implementation Status:** Complete

**Date Document Changes Effective:** 17 Jun 2019

**NOTE:** Please be advised that this is a change to the document only the product has not been changed.

Markings to Distinguish Revised from Unrevised Devices: N/A Attachment(s):

AT25512 - SPI Serial EERPOM 512 Kbits Complete Datasheet

Please contact your local <u>Microchip sales office</u> with questions or concerns regarding this notification.

#### **Terms and Conditions:**

If you wish to <u>receive Microchip PCNs via email</u> please register for our PCN email service at our <u>PCN home page</u> select register then fill in the required fields. You will find instructions about registering for Microchips PCN email service in the <u>PCN FAQ</u> section.

If you wish to <u>change your PCN profile</u>, <u>including opt out</u>, please go to the <u>PCN home page</u> select login and sign into your myMicrochip account. Select a profile option from the left navigation bar and make the applicable selections.

## SYST-14YADM309 - Data Sheet - AT25512 - SPI Serial EERPOM 512 Kbits Complete Datasheet

## Affected Catalog Part Numbers (CPN)

AT25512-TH-B

AT25512-TH-B-899

AT25512-TH-T

AT25512-TH-T-899

AT25512-THAR-T

AT25512-W-27

AT25512-W-7-T

AT25512-W-9

AT25512-WU-7-T

AT25512-WU-9

AT25512N-SH-B

AT25512N-SH-B-899

AT25512N-SH-T

AT25512N-SH-T-834

AT25512N-SH-T-899

AT25512Y7-YH-T



# SPI Serial EEPROM 512 Kbits (65,536 x 8)

## **Features**

- · Serial Peripheral Interface (SPI) Compatible
- Supports SPI Modes 0 (0,0) and 3 (1,1):
  - Data sheet describes mode 0 operation
- · Low-Voltage Operation:
  - 1.8V (V<sub>CC</sub> = 1.8V to 5.5V)
- Industrial Temperature Range: -40°C to +85°C
- 20 MHz Clock Rate (5V)
- · 128-Byte Page Mode
- · Block Write Protection:
  - Protect 1/4, 1/2 or entire array
- Write-Protect (WP) Pin and Write Disable Instructions for Both Hardware and Software Data Protection
- Self-Timed Write Cycle within 5 ms Maximum
- ESD Protection > 4,000V
- · High Reliability:
  - Endurance: 1,000,000 write cycles
  - Data retention: 100 years
- · Green (Lead-free/Halide-free/RoHS Compliant) Package Options
- Die Sale Options: Wafer Form and Bumped Wafers

## **Packages**

· 8-Lead SOIC, 8-Lead TSSOP and 8-Pad UDFN

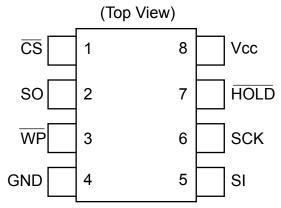
# **Table of Contents**

Packages       1         1. Package Types (not to scale)       4         2. Pin Description       5         2.1. Chip Select (CS)       5         2.2. Serial Data Output (SO)       5         2.3. Write-Protect (WP)       5         2.4. Ground       5         2.5. Serial Data Input (SI)       6         2.6. Serial Data Clock (SCK)       6         2.7. Device Power Supply (V <sub>CC</sub> )       6         3. Description       7         3.1. SPI Bus Master Connections to Serial EEPROMs       7         3.2. Block Diagram       8         4. Electrical Characteristics       9         4.1. Absolute Maximum Ratings       9         4.2. DC and AC Operating Range       9         4.3. DC Characteristics       9         4.4. AC Characteristics       9         4.5. SPI Synchronous Data Timing       13         4.6. Electrical Specifications       13         5. Device Operation       15         5.1. Interfacing the AT25512 on the SPI Bus       15         5.2. Device Opcodes       16         6.1. STATUS Register Bit Definition and Function       16         5.4. Write Protection       17         6. Device Commands and Addressing       18 <th>Fe</th> <th>atures</th> <th>S</th> <th>1</th>	Fe	atures	S	1
2. Pin Description.       5         2.1. Chip Select (CS).       5         2.2. Serial Data Output (SO).       5         2.3. Write-Protect (WP).       5         2.4. Ground.       5         2.5. Serial Data Input (SI).       6         2.6. Serial Data Clock (SCK).       6         2.7. Device Power Supply (V <sub>CC</sub> ).       6         3. Description.       7         3.1. SPI Bus Master Connections to Serial EEPROMs.       7         3.2. Block Diagram.       8         4. Electrical Characteristics.       9         4.1. Absolute Maximum Ratings.       9         4.2. DC and AC Operating Range.       9         4.3. DC Characteristics.       9         4.4. AC Characteristics.       9         4.5. SPI Synchronous Data Timing.       13         4.6. Electrical Specifications.       13         5. Device Operation.       15         5.1. Interfacing the AT25512 on the SPI Bus.       15         5.2. Device Opcodes.       16         5.3. Hold Function.       16         5.4. Write Protection.       17         6. Device Commands and Addressing.       18         6.1. STATUS Register Bit Definition and Function.       18         6.2. Read STATU	Pa	ckage	es	1
2.1. Chip Select (CS).       5         2.2. Serial Data Output (SO).       5         2.3. Write-Protect (WP).       5         2.4. Ground.       5         2.5. Serial Data Input (SI).       6         2.6. Serial Data Clock (SCK).       6         2.7. Device Power Supply (V <sub>CC</sub> ).       6         3. Description.       7         3.1. SPI Bus Master Connections to Serial EEPROMs.       7         3.2. Block Diagram.       8         4. Electrical Characteristics.       9         4.1. Absolute Maximum Ratings.       9         4.2. DC and AC Operating Range.       9         4.3. DC Characteristics.       9         4.4. AC Characteristics.       9         4.5. SPI Synchronous Data Timing.       13         4.6. Electrical Specifications.       13         5. Device Operation.       15         5.1. Interfacing the AT25512 on the SPI Bus.       15         5.2. Device Opcodes.       16         5.3. Hold Function.       16         5.4. Write Protection.       17         6. Device Commands and Addressing.       18         6.1. STATUS Register (RDSR).       19         6.3. Write Enable (WREN) and Write Disable (WRDI).       19         6.4.	1.	Pack	rage Types (not to scale)	4
2.2. Serial Data Output (SO)	2.	Pin [	Description	5
2.3. Write-Protect (WP)		2.1.	Chip Select (CS)	5
2.4. Ground       5         2.5. Serial Data Input (SI)       6         2.6. Serial Data Clock (SCK)       6         2.7. Device Power Supply (V <sub>CC</sub> )       6         3. Description       7         3.1. SPI Bus Master Connections to Serial EEPROMS       7         3.2. Block Diagram       8         4. Electrical Characteristics       9         4.1. Absolute Maximum Ratings       9         4.2. DC and AC Operating Range       9         4.3. DC Characteristics       10         4.5. SPI Synchronous Data Timing       13         4.6. Electrical Specifications       13         5. Device Operation       15         5.1. Interfacing the AT25512 on the SPI Bus       15         5.2. Device Opcodes       16         5.3. Hold Function       16         5.4. Write Protection       17         6. Device Commands and Addressing       18         6.1. STATUS Register Bit Definition and Function       18         6.2. Read STATUS Register (RDSR)       19         6.3. Write Enable (WREN) and Write Disable (WRDI)       19         6.4. Write STATUS Register (WRSR)       20         7. Read Sequence       23         8. Write Sequence       24		2.2.	. ,	
2.5. Serial Data Input (SI)       6         2.6. Serial Data Clock (SCK)       6         2.7. Device Power Supply (V <sub>CC</sub> )       6         3. Description       7         3.1. SPI Bus Master Connections to Serial EEPROMs       7         3.2. Block Diagram       8         4. Electrical Characteristics       9         4.1. Absolute Maximum Ratings       9         4.2. DC and AC Operating Range       9         4.3. DC Characteristics       9         4.4. AC Characteristics       10         4.5. SPI Synchronous Data Timing       13         4.6. Electrical Specifications       13         5. Device Operation       15         5.1. Interfacing the AT25512 on the SPI Bus       15         5.2. Device Opcodes       16         5.3. Hold Function       16         5.4. Write Protection       17         6. Device Commands and Addressing       18         6.1. STATUS Register Bit Definition and Function       18         6.2. Read STATUS Register (RDSR)       19         6.3. Write Enable (WREN) and Write Disable (WRDI)       19         6.4. Write STATUS Register (WRSR)       20         7. Read Sequence       23         8. Write Sequence       24 <tr< td=""><td></td><td>2.3.</td><td>Write-Protect (WP)</td><td>5</td></tr<>		2.3.	Write-Protect (WP)	5
2.6. Serial Data Clock (SCK)		2.4.	Ground	5
2.7. Device Power Supply (V <sub>CC</sub> )		2.5.	Serial Data Input (SI)	6
3. Description.       7         3.1. SPI Bus Master Connections to Serial EEPROMs.       7         3.2. Block Diagram.       8         4. Electrical Characteristics.       9         4.1. Absolute Maximum Ratings.       9         4.2. DC and AC Operating Range.       9         4.3. DC Characteristics.       9         4.4. AC Characteristics.       10         4.5. SPI Synchronous Data Timing.       13         4.6. Electrical Specifications.       13         5. Device Operation.       15         5.1. Interfacing the AT25512 on the SPI Bus.       15         5.2. Device Opcodes.       16         5.3. Hold Function.       16         5.4. Write Protection.       17         6. Device Commands and Addressing.       18         6.1. STATUS Register Bit Definition and Function.       18         6.2. Read STATUS Register (RDSR).       19         6.3. Write Enable (WREN) and Write Disable (WRDI).       19         6.4. Write STATUS Register (WRSR).       20         7. Read Sequence.       23         8. Write Sequence.       24         8.1. Byte Write.       24         8.2. Page Write.       24		2.6.	Serial Data Clock (SCK)	6
3.1. SPI Bus Master Connections to Serial EEPROMs       7         3.2. Block Diagram.       8         4. Electrical Characteristics.       9         4.1. Absolute Maximum Ratings.       9         4.2. DC and AC Operating Range.       9         4.3. DC Characteristics.       9         4.4. AC Characteristics.       10         4.5. SPI Synchronous Data Timing.       13         4.6. Electrical Specifications.       13         5. Device Operation.       15         5.1. Interfacing the AT25512 on the SPI Bus.       15         5.2. Device Opcodes.       16         5.3. Hold Function.       16         5.4. Write Protection.       17         6. Device Commands and Addressing.       18         6.1. STATUS Register Bit Definition and Function.       18         6.2. Read STATUS Register (RDSR).       19         6.3. Write Enable (WREN) and Write Disable (WRDI).       19         6.4. Write STATUS Register (WRSR).       20         7. Read Sequence.       23         8. Write Sequence.       24         8.1. Byte Write.       24         8.2. Page Write.       24		2.7.	Device Power Supply (V <sub>CC</sub> )	6
3.2. Block Diagram	3.	Desc	cription	7
4. Electrical Characteristics       9         4.1. Absolute Maximum Ratings       9         4.2. DC and AC Operating Range       9         4.3. DC Characteristics       10         4.5. SPI Synchronous Data Timimg       13         4.6. Electrical Specifications       13         5. Device Operation       15         5.1. Interfacing the AT25512 on the SPI Bus       15         5.2. Device Opcodes       16         5.3. Hold Function       16         5.4. Write Protection       17         6. Device Commands and Addressing       18         6.1. STATUS Register Bit Definition and Function       18         6.2. Read STATUS Register (RDSR)       19         6.3. Write Enable (WREN) and Write Disable (WRDI)       19         6.4. Write STATUS Register (WRSR)       20         7. Read Sequence       23         8. Write Sequence       24         8.1. Byte Write       24         8.2. Page Write       24		3.1.	SPI Bus Master Connections to Serial EEPROMs	7
4.1. Absolute Maximum Ratings.       9         4.2. DC and AC Operating Range.       9         4.3. DC Characteristics.       9         4.4. AC Characteristics.       10         4.5. SPI Synchronous Data Timing.       13         4.6. Electrical Specifications.       13         5. Device Operation.       15         5.1. Interfacing the AT25512 on the SPI Bus.       15         5.2. Device Opcodes.       16         5.3. Hold Function.       16         5.4. Write Protection.       17         6. Device Commands and Addressing.       18         6.1. STATUS Register Bit Definition and Function.       18         6.2. Read STATUS Register (RDSR).       19         6.3. Write Enable (WREN) and Write Disable (WRDI).       19         6.4. Write STATUS Register (WRSR).       20         7. Read Sequence.       23         8. Write Sequence.       24         8.1. Byte Write.       24         8.2. Page Write.       24		3.2.	Block Diagram	8
4.2. DC and AC Operating Range.       9         4.3. DC Characteristics.       9         4.4. AC Characteristics.       10         4.5. SPI Synchronous Data Timing.       13         4.6. Electrical Specifications.       13         5. Device Operation.       15         5.1. Interfacing the AT25512 on the SPI Bus.       15         5.2. Device Opcodes.       16         5.3. Hold Function.       16         5.4. Write Protection.       17         6. Device Commands and Addressing.       18         6.1. STATUS Register Bit Definition and Function.       18         6.2. Read STATUS Register (RDSR).       19         6.3. Write Enable (WREN) and Write Disable (WRDI).       19         6.4. Write STATUS Register (WRSR).       20         7. Read Sequence.       23         8. Write Sequence.       24         8.1. Byte Write.       24         8.2. Page Write.       24	4.	Elec	trical Characteristics	9
4.3. DC Characteristics.       9         4.4. AC Characteristics.       10         4.5. SPI Synchronous Data Timing.       13         4.6. Electrical Specifications.       13         5. Device Operation.       15         5.1. Interfacing the AT25512 on the SPI Bus.       15         5.2. Device Opcodes.       16         5.3. Hold Function.       16         5.4. Write Protection.       17         6. Device Commands and Addressing.       18         6.1. STATUS Register Bit Definition and Function.       18         6.2. Read STATUS Register (RDSR).       19         6.3. Write Enable (WREN) and Write Disable (WRDI).       19         6.4. Write STATUS Register (WRSR).       20         7. Read Sequence.       23         8. Write Sequence.       24         8.1. Byte Write.       24         8.2. Page Write.       24		4.1.	Absolute Maximum Ratings	9
4.3. DC Characteristics.       9         4.4. AC Characteristics.       10         4.5. SPI Synchronous Data Timing.       13         4.6. Electrical Specifications.       13         5. Device Operation.       15         5.1. Interfacing the AT25512 on the SPI Bus.       15         5.2. Device Opcodes.       16         5.3. Hold Function.       16         5.4. Write Protection.       17         6. Device Commands and Addressing.       18         6.1. STATUS Register Bit Definition and Function.       18         6.2. Read STATUS Register (RDSR).       19         6.3. Write Enable (WREN) and Write Disable (WRDI).       19         6.4. Write STATUS Register (WRSR).       20         7. Read Sequence.       23         8. Write Sequence.       24         8.1. Byte Write.       24         8.2. Page Write.       24		4.2.	•	
4.5. SPI Synchronous Data Timing.       13         4.6. Electrical Specifications.       13         5. Device Operation.       15         5.1. Interfacing the AT25512 on the SPI Bus.       15         5.2. Device Opcodes.       16         5.3. Hold Function.       16         5.4. Write Protection.       17         6. Device Commands and Addressing.       18         6.1. STATUS Register Bit Definition and Function.       18         6.2. Read STATUS Register (RDSR).       19         6.3. Write Enable (WREN) and Write Disable (WRDI).       19         6.4. Write STATUS Register (WRSR).       20         7. Read Sequence.       23         8. Write Sequence.       24         8.1. Byte Write.       24         8.2. Page Write.       24		4.3.		
4.6. Electrical Specifications.       13         5. Device Operation.       15         5.1. Interfacing the AT25512 on the SPI Bus.       15         5.2. Device Opcodes.       16         5.3. Hold Function.       16         5.4. Write Protection.       17         6. Device Commands and Addressing.       18         6.1. STATUS Register Bit Definition and Function.       18         6.2. Read STATUS Register (RDSR).       19         6.3. Write Enable (WREN) and Write Disable (WRDI).       19         6.4. Write STATUS Register (WRSR).       20         7. Read Sequence.       23         8. Write Sequence.       24         8.1. Byte Write.       24         8.2. Page Write.       24		4.4.	AC Characteristics	10
5. Device Operation       15         5.1. Interfacing the AT25512 on the SPI Bus       15         5.2. Device Opcodes       16         5.3. Hold Function       16         5.4. Write Protection       17         6. Device Commands and Addressing       18         6.1. STATUS Register Bit Definition and Function       18         6.2. Read STATUS Register (RDSR)       19         6.3. Write Enable (WREN) and Write Disable (WRDI)       19         6.4. Write STATUS Register (WRSR)       20         7. Read Sequence       23         8. Write Sequence       24         8.1. Byte Write       24         8.2. Page Write       24		4.5.	SPI Synchronous Data Timimg	13
5.1. Interfacing the AT25512 on the SPI Bus.       15         5.2. Device Opcodes.       16         5.3. Hold Function.       16         5.4. Write Protection.       17         6. Device Commands and Addressing.       18         6.1. STATUS Register Bit Definition and Function.       18         6.2. Read STATUS Register (RDSR).       19         6.3. Write Enable (WREN) and Write Disable (WRDI).       19         6.4. Write STATUS Register (WRSR).       20         7. Read Sequence.       23         8. Write Sequence.       24         8.1. Byte Write.       24         8.2. Page Write.       24		4.6.	Electrical Specifications	13
5.2. Device Opcodes.       16         5.3. Hold Function.       16         5.4. Write Protection.       17         6. Device Commands and Addressing.       18         6.1. STATUS Register Bit Definition and Function.       18         6.2. Read STATUS Register (RDSR).       19         6.3. Write Enable (WREN) and Write Disable (WRDI).       19         6.4. Write STATUS Register (WRSR).       20         7. Read Sequence.       23         8. Write Sequence.       24         8.1. Byte Write.       24         8.2. Page Write.       24	5.	Devi	ce Operation	15
5.3. Hold Function		5.1.	Interfacing the AT25512 on the SPI Bus	15
5.4. Write Protection		5.2.	Device Opcodes	16
6. Device Commands and Addressing.       18         6.1. STATUS Register Bit Definition and Function.       18         6.2. Read STATUS Register (RDSR).       19         6.3. Write Enable (WREN) and Write Disable (WRDI).       19         6.4. Write STATUS Register (WRSR).       20         7. Read Sequence.       23         8. Write Sequence.       24         8.1. Byte Write.       24         8.2. Page Write.       24		5.3.	Hold Function	16
6.1. STATUS Register Bit Definition and Function.       18         6.2. Read STATUS Register (RDSR).       19         6.3. Write Enable (WREN) and Write Disable (WRDI).       19         6.4. Write STATUS Register (WRSR).       20         7. Read Sequence.       23         8. Write Sequence.       24         8.1. Byte Write.       24         8.2. Page Write.       24		5.4.	Write Protection	17
6.2. Read STATUS Register (RDSR)       19         6.3. Write Enable (WREN) and Write Disable (WRDI)       19         6.4. Write STATUS Register (WRSR)       20         7. Read Sequence       23         8. Write Sequence       24         8.1. Byte Write       24         8.2. Page Write       24	6.	Devi	ce Commands and Addressing	18
6.3. Write Enable (WREN) and Write Disable (WRDI)       19         6.4. Write STATUS Register (WRSR)       20         7. Read Sequence       23         8. Write Sequence       24         8.1. Byte Write       24         8.2. Page Write       24		6.1.	STATUS Register Bit Definition and Function	18
6.3. Write Enable (WREN) and Write Disable (WRDI)       19         6.4. Write STATUS Register (WRSR)       20         7. Read Sequence       23         8. Write Sequence       24         8.1. Byte Write       24         8.2. Page Write       24		6.2.	Read STATUS Register (RDSR)	19
6.4. Write STATUS Register (WRSR).       20         7. Read Sequence.       23         8. Write Sequence.       24         8.1. Byte Write.       24         8.2. Page Write.       24		6.3.		
8. Write Sequence		6.4.		
8.1. Byte Write	7.	Read	d Sequence	23
8.1. Byte Write	8.	Write	e Sequence	24
8.2. Page Write24		8.1.	Byte Write	24
•		_	•	
			· ·	

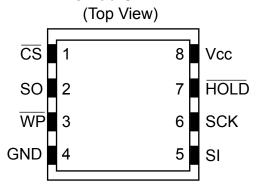
9.	Pac	kaging Information	26
	9.1.	Package Marking Information	.26
10.	Rev	ision History	35
Th	e Mic	rochip Website	36
Pro	duct	Change Notification Service	36
Cu	stom	er Support	36
Pro	duct	Identification System	37
Mic	croch	ip Devices Code Protection Feature	37
Le	gal N	otice	38
Tra	dem	arks	38
Qu	ality	Management System	39
Wo	rldwi	de Sales and Service	40

# 1. Package Types (not to scale)

## 8-Lead SOIC/TSSOP



## 8-Pad UDFN



#### 2. Pin Description

The descriptions of the pins are listed in Table 2-1.

**Table 2-1. Pin Function Table** 

Name	8-Lead SOIC	8-Lead TSSOP	8-Pad UDFN <sup>(1)</sup>	Function
CS	1	1	1	Chip Select
SO	2	2	2	Serial Data Output
WP <sup>(2)</sup>	3	3	3	Write-Protect
GND	4	4	4	Ground
SI	5	5	5	Serial Data Input
SCK	6	6	6	Serial Data Clock
HOLD <sup>(2)</sup>	7	7	7	Suspends Serial Input
Vcc	8	8	8	Device Power Supply

#### Note:

- The exposed pad on this package can be connected to GND or left floating.
- The Write-Protect (WP) and Hold (HOLD) pins should be driven high or low as appropriate.

#### 2.1 Chip Select (CS)

The AT25512 is selected when the Chip Select (CS) pin is low. When the device is not selected, data will not be accepted via the Serial Data Input (SI) pin, and the Serial Output (SO) pin will remain in a highimpedance state.

To ensure robust operation, the  $\overline{CS}$  pin should follow  $V_{CC}$  upon power-up. It is therefore recommended to connect  $\overline{CS}$  to  $V_{CC}$  using a pull-up resistor (less than or equal to 10 k $\Omega$ ). After power-up, a low level on CS is required prior to any sequence being initiated.

#### 2.2 Serial Data Output (SO)

The Serial Data Output (SO) pin is used to transfer data out of the AT25512. During a read sequence, data is shifted out on this pin after the falling edge of the Serial Data Clock (SCK).

#### 2.3 Write-Protect (WP)

The Write-Protect (WP) pin will allow normal read/write operations when held high. When the WP pin is brought low and WPEN bit is set to a logic '1', all write operations to the STATUS register are inhibited. WP going low while CS is still low will interrupt a write operation to the STATUS register. If the internal write cycle has already been initiated, WP going low will have no effect on any write operation to the STATUS register. The WP pin function is blocked when the WPEN bit in the STATUS register is set to a logic '0'. This will allow the user to install the AT25512 in a system with the WP pin tied to ground and still be able to write to the STATUS register. All WP pin functions are enabled when the WPEN bit is set to a logic '1'.

#### 2.4 Ground

The ground reference for the power supply. GND should be connected to the system ground.

DS20006218A-page 5 **Datasheet** 

## 2.5 Serial Data Input (SI)

The Serial Data Input (SI) pin is used to transfer data into the device. It receives instructions, addresses and data. Data is latched on the rising edge of the Serial Data Clock (SCK).

## 2.6 Serial Data Clock (SCK)

The Serial Data Clock (SCK) pin is used to synchronize the communication between a master and the AT25512. Instructions, addresses or data present on the Serial Data Input (SI) pin is latched in on the rising edge of SCK, while output on the Serial Data Output (SO) pin is clocked out on the falling edge of SCK.

## 2.7 Device Power Supply (V<sub>CC</sub>)

The Device Power Supply  $(V_{CC})$  pin is used to supply the source voltage to the device. Operations at invalid  $V_{CC}$  voltages may produce spurious results and should not be attempted.

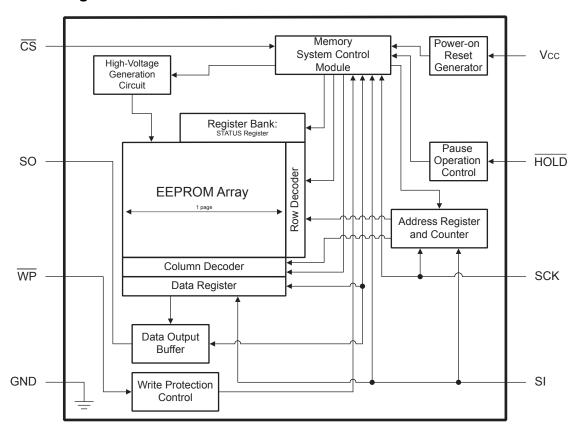
## 3. Description

The AT25512 provides 524,288 bits of Serial Electrically Erasable and Programmable Read-Only Memory (EEPROM) organized as 65,536 words of 8 bits each. The device is optimized for use in many industrial and commercial applications where low-power and low-voltage operation are essential. The device is available in space-saving 8-lead SOIC, 8-lead TSSOP and 8-pad UDFN packages. All packages operate from 1.8V to 5.5V.

## 3.1 SPI Bus Master Connections to Serial EEPROMs

#### SPI Master: Microcontroller Data Clock (SCK) Data Output (SO) Data Input (SI) SI SO SCK SO SCK SI SO SCK SO SCK Slave 0 Slave 1 Slave 2 Slave 3 AT25XXX AT25XXX AT25XXX AT25XXX CS CS CS CS CS3 CS2 CS1 CS0

## 3.2 Block Diagram



## 4. Electrical Characteristics

## 4.1 Absolute Maximum Ratings

Operating temperature  $-55^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$  Storage temperature  $-65^{\circ}\text{C}$  to  $+150^{\circ}\text{C}$  Voltage on any pin with respect to ground -1.0V to +7.0V 6.25V

DC output current 5.0 mA
ESD protection > 4 kV

**Note:** Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## 4.2 DC and AC Operating Range

## Table 4-1. DC and AC Operating Range

AT25512		
Operating Temperature (Case)	Industrial Temperature Range	-40°C to +85°C
V <sub>CC</sub> Power Supply	Low-Voltage Grade	1.8V to 5.5V

## 4.3 DC Characteristics

#### Table 4-2. DC Characteristics<sup>(1)</sup>

Parameter	Symbol	Minimum	Typical	Maximum	Units	Conditions
Supply Voltage	V <sub>CC1</sub>	1.8	_	5.5	V	
Supply Voltage	V <sub>CC2</sub>	2.7	_	5.5	V	
Supply Voltage	V <sub>CC3</sub>	4.5	_	5.5	V	
Supply Current	I <sub>CC1</sub>	_	9.0	10.0	mA	V <sub>CC</sub> = 5.0V at 20 MHz, SO = Open, Read
Supply Current	I <sub>CC2</sub>	_	5.0	7.0	mA	V <sub>CC</sub> = 5.0V at 10 MHz, SO = Open, Read, Write
Supply Current	I <sub>CC3</sub>	_	2.2	3.5	mA	V <sub>CC</sub> = 5.0V at 1 MHz, SO = Open, Read, Write
Standby Current	I <sub>SB1</sub>	_	0.2	3.0	μΑ	$V_{CC}$ = 1.8V, $\overline{CS}$ = $V_{CC}$

continued								
Parameter	Symbol	Minimum	Typical	Maximum	Units	Conditions		
Standby Current	I <sub>SB2</sub>	_	0.5	3.0	μA	$V_{CC} = 2.7V, \overline{CS} = V$	′cc	
Standby Current	I <sub>SB3</sub>	_	2.0	5.0	μA	$V_{CC} = 5.0V, \overline{CS} = V$	′cc	
Input Leakage	I <sub>IL</sub>	-3.0	_	3.0	μA	$V_{IN}$ = 0V to $V_{CC}$		
Output Leakage	I <sub>OL</sub>	-3.0	_	3.0	μA	$V_{IN} = 0V \text{ to } V_{CC},$ $T_A = 0^{\circ}\text{C to } +70^{\circ}\text{C}$		
Input Low-Voltage	V <sub>IL</sub> <sup>(2)</sup>	-1.0	_	V <sub>CC</sub> x 0.3	V			
Input High-Voltage	V <sub>IH</sub> <sup>(2)</sup>	V <sub>CC</sub> x 0.7	_	V <sub>CC</sub> + 0.5	V			
Output Low-Voltage	V <sub>OL1</sub>	_	_	0.4	V	$3.6V \le V_{CC} \le 5.5V$	I <sub>OL</sub> = 3.0 mA	
Output High-Voltage	V <sub>OH1</sub>	V <sub>CC</sub> - 0.8	_	_	V	3.6V ≤ V <sub>CC</sub> ≤ 5.5V	I <sub>OH</sub> = -1.6 mA	
Output Low-Voltage	V <sub>OL2</sub>	<del>_</del>	_	0.2	V	1.8V ≤ V <sub>CC</sub> ≤ 3.6V	I <sub>OL</sub> = 0.15 mA	
Output High-Voltage	V <sub>OH2</sub>	V <sub>CC</sub> - 0.2	_	<u> </u>	V	1.8V ≤ V <sub>CC</sub> ≤ 3.6V	I <sub>OH</sub> = -100 μA	

#### Note:

- 1. Applicable over recommended operating range from:  $T_A = -40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$ ,  $V_{CC} = 1.8\text{V}$  to 5.5V (unless otherwise noted).
- 2.  $V_{IL}$  min. and  $V_{IH}$  max. are reference only and are not tested.

## 4.4 AC Characteristics

Table 4-3. AC Characteristics<sup>(1)</sup>

Parameter	Symbol	Minimum	Maximum	Units	Conditions
SCK Clock Frequency	f <sub>SCK</sub>	0	20	MHz	V <sub>CC</sub> = 4.5V to 5.5V
		0	10	MHz	V <sub>CC</sub> = 2.7V to 5.5V
		0	5	MHz	V <sub>CC</sub> = 1.8V to 5.5V
Input Rise Time	t <sub>RI</sub>	_	2000	ns	V <sub>CC</sub> = 4.5V to 5.5V
			2000	ns	V <sub>CC</sub> = 2.7V to 5.5V
			2000	ns	V <sub>CC</sub> = 1.8V to 5.5V

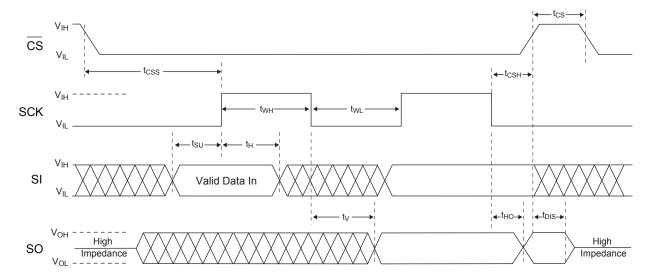
continued	continued								
Parameter	Symbol	Minimum	Maximum	Units	Conditions				
Input Fall Time	t <sub>FI</sub>	_	2000	ns	V <sub>CC</sub> = 4.5V to 5.5V				
		_	2000	ns	V <sub>CC</sub> = 2.7V to 5.5V				
		_	2000	ns	V <sub>CC</sub> = 1.8V to 5.5V				
SCK High Time	t <sub>WH</sub>	20	_	ns	V <sub>CC</sub> = 4.5V to 5.5V				
		40	_	ns	V <sub>CC</sub> = 2.7V to 5.5V				
		80	_	ns	V <sub>CC</sub> = 1.8V to 5.5V				
SCK Low Time	t <sub>WL</sub>	20	_	ns	V <sub>CC</sub> = 4.5V to 5.5V				
		40	_	ns	V <sub>CC</sub> = 2.7V to 5.5V				
		80	_	ns	V <sub>CC</sub> = 1.8V to 5.5V				
CS High Time	t <sub>CS</sub>	100	_	ns	V <sub>CC</sub> = 4.5V to 5.5V				
		100	_	ns	V <sub>CC</sub> = 2.7V to 5.5V				
		200	_	ns	V <sub>CC</sub> = 1.8V to 5.5V				
CS Setup Time	t <sub>CSS</sub>	100	_	ns	V <sub>CC</sub> = 4.5V to 5.5V				
		100	_	ns	V <sub>CC</sub> = 2.7V to 5.5V				
		200	_	ns	V <sub>CC</sub> = 1.8V to 5.5V				
CS Hold Time	t <sub>CSH</sub>	100	_	ns	V <sub>CC</sub> = 4.5V to 5.5V				
		100	_	ns	V <sub>CC</sub> = 2.7V to 5.5V				
		200	_	ns	V <sub>CC</sub> = 1.8V to 5.5V				
Data In Setup Time	t <sub>SU</sub>	5	_	ns	V <sub>CC</sub> = 4.5V to 5.5V				
		10	_	ns	V <sub>CC</sub> = 2.7V to 5.5V				
		20	_	ns	V <sub>CC</sub> = 1.8V to 5.5V				
Data In Hold Time	t <sub>H</sub>	5	_	ns	V <sub>CC</sub> = 4.5V to 5.5V				
		10	_	ns	V <sub>CC</sub> = 2.7V to 5.5V				
		20	_	ns	V <sub>CC</sub> = 1.8V to 5.5V				
HOLD Setup Time	t <sub>HD</sub>	5	_	ns	V <sub>CC</sub> = 4.5V to 5.5V				
		10	_	ns	V <sub>CC</sub> = 2.7V to 5.5V				
		20	_	ns	V <sub>CC</sub> = 1.8V to 5.5V				
HOLD Hold Time	t <sub>CD</sub>	5	_	ns	V <sub>CC</sub> = 4.5V to 5.5V				
		10	_	ns	V <sub>CC</sub> = 2.7V to 5.5V				
		20	_	ns	V <sub>CC</sub> = 1.8V to 5.5V				

continued	continued								
Parameter	Symbol	Minimum	Maximum	Units	Conditions				
Output Valid	t <sub>V</sub>	0	20	ns	V <sub>CC</sub> = 4.5V to 5.5V				
		0	40	ns	V <sub>CC</sub> = 2.7V to 5.5V				
		0	80	ns	V <sub>CC</sub> = 1.8V to 5.5V				
Output Hold Time	t <sub>HO</sub>	0	_	ns	V <sub>CC</sub> = 4.5V to 5.5V				
		0	_	ns	V <sub>CC</sub> = 2.7V to 5.5V				
		0	_	ns	V <sub>CC</sub> = 1.8V to 5.5V				
HOLD to Output Low Z	t <sub>LZ</sub>	0	25	ns	V <sub>CC</sub> = 4.5V to 5.5V				
		0	50	ns	V <sub>CC</sub> = 2.7V to 5.5V				
		0	100	ns	V <sub>CC</sub> = 1.8V to 5.5V				
HOLD to Output High Z	t <sub>HZ</sub>	_	25	ns	V <sub>CC</sub> = 4.5V to 5.5V				
			50	ns	V <sub>CC</sub> = 2.7V to 5.5V				
			100	ns	V <sub>CC</sub> = 1.8V to 5.5V				
Output Disable Time	t <sub>DIS</sub>	_	25	ns	V <sub>CC</sub> = 4.5V to 5.5V				
			50	ns	V <sub>CC</sub> = 2.7V to 5.5V				
		_	100	ns	V <sub>CC</sub> = 1.8V to 5.5V				
Write Cycle Time	t <sub>WC</sub>	_	5	ms	V <sub>CC</sub> = 4.5V to 5.5V				
		_	5	ms	V <sub>CC</sub> = 2.7V to 5.5V				
		_	5	ms	V <sub>CC</sub> = 1.8V to 5.5V				

## Note:

1. Applicable over recommended operating range from  $T_A$  = -40°C to +85°C,  $V_{CC}$  = As Specified,  $C_L$  = 1 TTL Gate and 30 pF (unless otherwise noted).

## 4.5 SPI Synchronous Data Timimg



## 4.6 Electrical Specifications

#### 4.6.1 Power-Up Requirements and Reset Behavior

During a power-up sequence, the  $V_{CC}$  supplied to the AT25512 should monotonically rise from GND to the minimum  $V_{CC}$  level, as specified in Table 4-1, with a slew rate no faster than 0.1 V/ $\mu$ s.

#### 4.6.1.1 Device Reset

To prevent inadvertent write operations or any other spurious events from occurring during a power-up sequence, the AT25512 includes a Power-on Reset (POR) circuit. Upon power-up, the device will not respond to any instructions until the  $V_{CC}$  level crosses the internal voltage threshold ( $V_{POR}$ ) that brings the device out of Reset and into Standby mode.

The system designer must ensure the instructions are not sent to the device until the  $V_{CC}$  supply has reached a stable value greater than or equal to the minimum  $V_{CC}$  level. Additionally, once the  $V_{CC}$  is greater than or equal to the minimum  $V_{CC}$  level, the bus master must wait at least  $t_{PUP}$  before sending the first instruction to the device. See Table 4-4 for the values associated with these power-up parameters.

Table 4-4. Power-Up Conditions<sup>(1)</sup>

Symbol	Parameter	Min.	Max.	Units
t <sub>PUP</sub>	Time required after $V_{\text{CC}}$ is stable before the device can accept instructions	100	_	μs
V <sub>POR</sub>	Power-on Reset Threshold Voltage	_	1.5	V
t <sub>POFF</sub>	Minimum time at V <sub>CC</sub> = 0V between power cycles	500	_	ms

#### Note:

1. These parameters are characterized but they are not 100% tested in production.

If an event occurs in the system where the  $V_{CC}$  level supplied to the AT25512 drops below the maximum  $V_{POR}$  level specified, it is recommended that a full-power cycle sequence be performed by first driving the  $V_{CC}$  pin to GND in less than 1 ms, waiting at least the minimum  $t_{POFF}$  time and then performing a new power-up sequence in compliance with the requirements defined in this section.

#### 4.6.2 Pin Capacitance

## Table 4-5. Pin Capacitance<sup>(1,2)</sup>

Symbol	Test Condition	Max.	Units	Conditions
C <sub>OUT</sub>	Output Capacitance (SO)	8	pF	V <sub>OUT</sub> = 0V
C <sub>IN</sub>	Input Capacitance (CS, SCK, SI, WP, HOLD)	6	pF	V <sub>IN</sub> = 0V

#### Note:

- 1. This parameter is characterized but is not 100% tested in production.
- 2. Applicable over recommended operating range from:  $T_A = 25$ °C,  $f_{SCK} = 1.0$  MHz,  $V_{CC} = 5.0$ V (unless otherwise noted).

#### 4.6.3 EEPROM Cell Performance Characteristics

#### Table 4-6. EEPROM Cell Performance Characteristics

Operation	Test Condition	Min.	Max.	Units
Write Endurance <sup>(1)</sup>	T <sub>A</sub> = 25°C, V <sub>CC</sub> = 5.0V, Page Write mode	1,000,000	_	Write Cycles
Data Retention <sup>(1)</sup>	T <sub>A</sub> = 55°C	100		Years

#### Note:

1. Performance is determined through characterization and the qualification process.

#### 4.6.4 Software Reset

The SPI interface of the AT25512 can be reset by toggling the  $\overline{CS}$  input. If the  $\overline{CS}$  line is already in the active state, it must complete a transition from the inactive state ( $\geq V_{IH}$ ) to the active state ( $\leq V_{IL}$ ) and then back to the inactive state ( $\geq V_{IH}$ ) without sending clocks on the SCK line. Upon completion of this sequence, the device will be ready to receive a new opcode on the SI line.

#### 4.6.5 Device Default State at Power-Up

The AT25512 default state upon power-up consists of:

- · Standby Power mode
- A high-to-low-level transition on  $\overline{CS}$  is required to enter active state
- Write Enable Latch (WEL) bit in the STATUS register = 0
- Ready/Busy bit in the STATUS register = 0, indicating the device is ready to accept a new command
- · Device is not selected
- · Not in Hold condition
- WPEN, BP1 and BP0 bits in the STATUS register are unchanged from their previous state due to the fact that they are nonvolatile values

#### 4.6.6 Device Default Condition

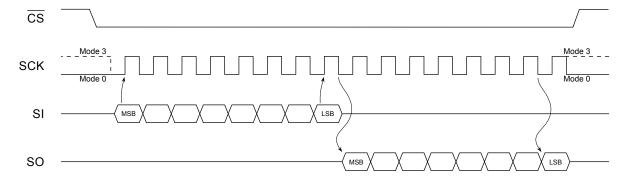
The AT25512 is shipped from Microchip to the customer with the EEPROM array set to an all FFh data pattern (logic '1' state). The Write-Protect Enable bit in the STATUS register is set to logic '0' and the Block Write-Protection bits in the STATUS register are set to logic '0'.

## 5. Device Operation

The AT25512 is controlled by a set of instructions that are sent from a host controller, commonly referred to as the SPI Master. The SPI Master communicates with the AT25512 via the SPI bus which is comprised of four signal lines: Chip Select  $(\overline{CS})$ , Serial Data Clock (SCK), Serial Data Input (SI) and Serial Data Output (SO).

The SPI protocol defines a total of four modes of operation (Mode 0, 1, 2 or 3) with each mode differing in respect to the SCK polarity and phase and how the polarity and phase control the flow of data on the SPI bus. The AT25512 supports the two most common modes, SPI Modes 0 and 3. With SPI Modes 0 and 3, data is always latched in on the rising edge of SCK and always output on the falling edge of SCK. The only difference between SPI Modes 0 and 3 is the polarity of the SCK signal when in the inactive state (when the SPI Master is in Standby mode and not transferring any data). SPI Mode 0 is defined as a low SCK while  $\overline{\text{CS}}$  is not asserted (at  $V_{\text{CC}}$ ) and SPI Mode 3 has SCK high in the inactive state. The SCK Idle state must match when the  $\overline{\text{CS}}$  is deasserted both before and after the communication sequence in SPI Mode 0 and 3. The figures in this document depict Mode 0 with a solid line on SCK while  $\overline{\text{CS}}$  is inactive and Mode 3 with a dotted line.

Figure 5-1. SPI Mode 0 and Mode 3



## 5.1 Interfacing the AT25512 on the SPI Bus

Communication to and from the AT25512 must be initiated by the SPI Master device, such as a microcontroller. The SPI Master device must generate the serial clock for the AT25512 on the Serial Data Clock (SCK) pin. The AT25512 always operates as a slave due to the fact that the SCK is always an input.

#### 5.1.1 Selecting the Device

The AT25512 is selected when the Chip Select ( $\overline{CS}$ ) pin is low. When the device is not selected, data will not be accepted via the Serial Data Input (SI) pin, and the Serial Data Output (SO) pin will remain in a high-impedance state.

## 5.1.2 Sending Data to the Device

The AT25512 uses the SI pin to receive information. All instructions, addresses and data input bytes are clocked into the device with the Most Significant bit (MSb) first. The SI pin samples on the first rising edge of the SCK line after the  $\overline{CS}$  has been asserted.

## 5.1.3 Receiving Data from the Device

Data output from the device is transmitted on the SO pin, with the MSb output first. The SO data is latched on the first falling edge of SCK after the instruction has been clocked into the device, such as the Read from Memory Array (READ) and Read STATUS Register (RDSR) instructions. See Read Sequence for more details.

## 5.2 Device Opcodes

#### 5.2.1 Serial Opcode

After the device is selected by driving  $\overline{\text{CS}}$  low, the first byte will be received on the SI pin. This byte contains the opcode that defines the operation to be performed. Refer to Table 6-1 for a list of all opcodes that the AT25512 will respond to.

#### 5.2.2 Invalid Opcode

If an invalid opcode is received, no data will be shifted into AT25512 and the SO pin will remain in a high-impedance state until the falling edge of  $\overline{CS}$  is detected again. This will reinitialize the serial communication.

#### 5.3 Hold Function

The Suspend Serial Input (HOLD) pin is used to pause the serial communication with the device without having to stop or reset the clock sequence. The Hold mode, however, does not have an effect on the internal write cycle. Therefore, if a write cycle is in progress, asserting the HOLD pin will not pause the operation and the write cycle will continue to completion.

The Hold mode can only be entered while the  $\overline{CS}$  pin is asserted. The Hold mode is activated by asserting the  $\overline{HOLD}$  pin during the SCK low pulse. If the  $\overline{HOLD}$  pin is asserted during the SCK high pulse, then the Hold mode will not be started until the beginning of the next SCK low pulse. The device will remain in the Hold mode as long as the  $\overline{HOLD}$  pin and  $\overline{CS}$  pin are asserted.

While in Hold mode, the SO pin will be in a high-impedance state. In addition, both the SI pin and the SCK pin will be ignored. The Write-Protect (WP) pin, however, can still be asserted or deasserted while in the Hold mode.

To end the Hold mode and resume serial communication, the HOLD pin must be deasserted during the SCK low pulse. If the HOLD pin is deasserted during the SCK high pulse, then the Hold mode will not end until the beginning of the next SCK low pulse.

If the  $\overline{\text{CS}}$  pin is deasserted while the  $\overline{\text{HOLD}}$  pin is still asserted, then any operation that may have been started will be aborted and the device will reset the WEL bit in the STATUS register back to the logic '0' state.

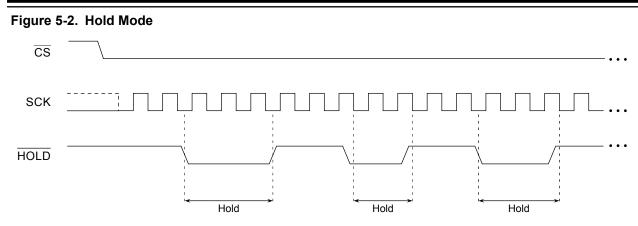
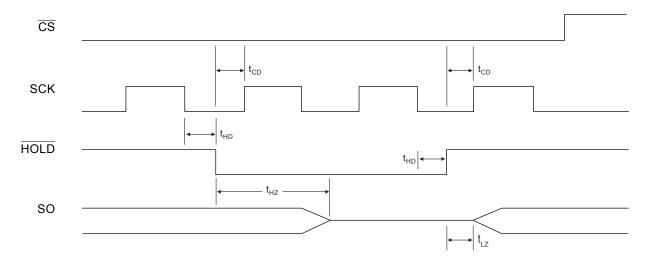


Figure 5-3. Hold Timing



#### 5.4 Write Protection

The Write-Protect  $(\overline{WP})$  pin will allow normal read and write operations when held high. When the  $\overline{WP}$  pin is brought low and WPEN bit is a logic '1', all write operations to the STATUS register are inhibited. The  $\overline{WP}$  pin going low while  $\overline{CS}$  is still low will interrupt a Write STATUS Register (WRSR). If the internal write cycle has already been initiated,  $\overline{WP}$  going low will have no effect on any write operation to the STATUS register. The  $\overline{WP}$  pin function is blocked when the WPEN bit in the STATUS register is a logic '0'. This will allow the user to install the AT25512 device in a system with the  $\overline{WP}$  pin tied to ground and still be able to write to the STATUS register. All  $\overline{WP}$  pin functions are enabled when the WPEN bit is set to a logic '1'.

## 6. Device Commands and Addressing

The AT25512 is designed to interface directly with the synchronous Serial Peripheral Interface (SPI). The AT25512 utilizes an 8-bit instruction register. The list of instructions and their operation codes are contained in Table 6-1. All instructions, addresses and data are transferred with the MSb first and start with a high-to-low  $\overline{CS}$  transition.

Table 6-1. Instruction Set for the AT25512

Instruction Name	Instruction Format	Operates On	Operation Description
WREN	0000 X110	STATUS Register	Set Write Enable Latch (WEL)
WRDI	0000 X100	STATUS Register	Reset Write Enable Latch (WEL)
RDSR	0000 X101	STATUS Register	Read STATUS Register
WRSR	0000 X001	STATUS Register	Write STATUS Register
READ	0000 X011	Memory Array	Read from Memory Array
WRITE	0000 X010	Memory Array	Write to Memory Array

## 6.1 STATUS Register Bit Definition and Function

The AT25512 includes an 8-bit STATUS register. The STATUS register bits modulate various features of the device as shown in Table 6-2 and Table 6-3. These bits can be changed by specific instructions that are detailed in the following sections.

Table 6-2. STATUS Register Format

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
WPEN	X	Х	Χ	BP1	BP0	WEL	RDY/BSY

Table 6-3. STATUS Register Bit Definition

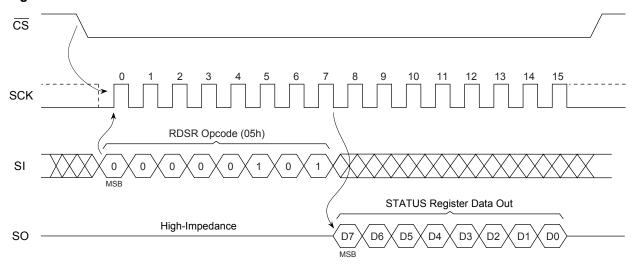
Bit		Name	Туре		Description													
7	WPEN	Write-Protect Enable		0	See Table 6-5 (Factory Default)													
				1	See Table 6-5 (Factory Default)													
6:4	RFU	Reserved for Future Use	R	0	Reads as zeros when the device is not in a write cycle													
				1	Reads as ones when the device is in a write cycle													
3:2	BP1	BP1 Block Write Protection		BP1 Block Write Protection	2 2.00	2 2.00	2   2.00.0	Zi i Ziook iiiko i iotookoii	z Ziook riinto i rotootiion		Block Write Protection	Block Write Protection	Block Write Protection	Block Write Protection F	. 2.00	R/W	00	No array write protection (Factory Default)
	BP0			01	Quarter array write protection (see Table 6-4)													
				10	Half array write protection (see Table 6-4)													
				11	Entire array write protection (see Table 6-4)													
1	WEL	Write Enable Latch	R	0	Device is not write enabled (Power-up Default)													
				1	Device is write enabled													

continued						
Bit		Name	Туре	ype Description		
0	RDY/BSY	Ready/Busy Status	R	R 0 Device is ready for a new sequence		
				1 Device is busy with an internal operation		

## 6.2 Read STATUS Register (RDSR)

The Read STATUS Register (RDSR) instruction provides access to the STATUS register. The ready/busy and write enable status of the device can be determined by the RDSR instruction. Similarly, the Block Write Protection (BP[1:0]) bits indicate the extent of memory array protection employed. The STATUS register is read by asserting the  $\overline{CS}$  pin, followed by sending in a 05h opcode on the SI pin. Upon completion of the opcode, the device will return the 8-bit STATUS register value on the SO pin.

Figure 6-1. RDSR Waveform

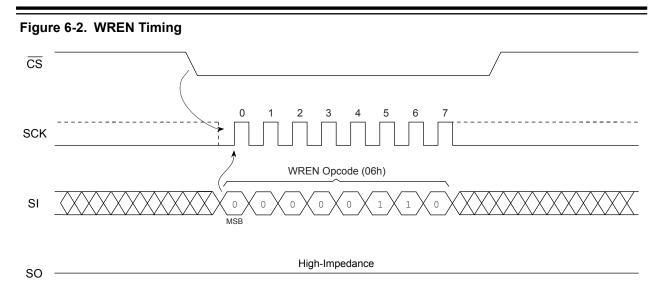


## 6.3 Write Enable (WREN) and Write Disable (WRDI)

Enabling and disabling writing to the STATUS register and EEPROM array is accomplished through the Write Enable (WREN) instruction and the Write Disable (WRDI) instruction. These functions change the status of the WEL bit in the STATUS register.

#### 6.3.1 Write Enable Instruction (WREN)

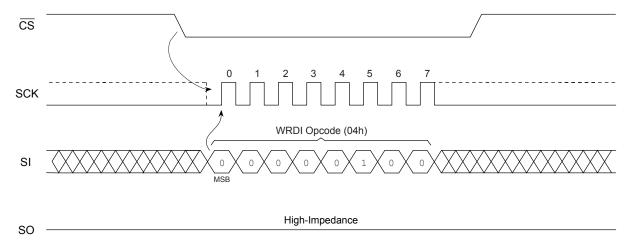
The Write Enable Latch (WEL) bit of the STATUS register must be set to a logic '1' prior to each Write STATUS Register (WRSR) and Write to Memory Array (WRITE) instructions. This is accomplished by sending a WREN (06h) instruction to the AT25512. First, the  $\overline{CS}$  pin is driven low to select the device and then a WREN instruction is clocked in on the SI pin. Then the  $\overline{CS}$  pin can be driven high and the WEL bit will be updated in the STATUS register to a logic '1'. The device will power-up in the Write Disable state (WEL = 0).



#### 6.3.2 Write Disable Instruction (WRDI)

To protect the device against inadvertent writes, the Write Disable (WRDI) instruction (opcode 04h) disables all programming modes by setting the WEL bit to a logic '0'. The WRDI instruction is independent of the status of the  $\overline{\text{WP}}$  pin.

Figure 6-3. WRDI Timing



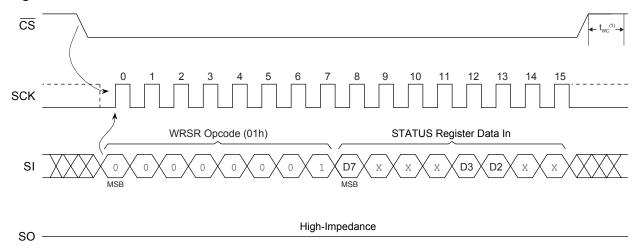
## 6.4 Write STATUS Register (WRSR)

The Write STATUS Register (WRSR) instruction enables the SPI Master to change selected bits of the STATUS register. Before a WRSR instruction can be initiated, a WREN instruction must be executed to set the WEL bit to logic '1'. Upon completion of a WREN instruction, a WRSR instruction can be executed.

Note: The WRSR instruction has no effect on bit 6, bit 5, bit 4, bit 1 and bit 0 of the STATUS register. Only bit 7, bit 3 and bit 2 can be changed via the WRSR instruction. These modifiable bits are the Write-Protect Enable (WPEN) and Block Protect (BP[1:0]) bits. These three bits are nonvolatile bits that have the same properties and functions as regular EEPROM cells. Their values are retained while power is removed from the device.

The AT25512 will not respond to commands other than a RDSR after a WRSR instruction until the self-timed internal write cycle has completed. When the write cycle is completed, the WEL bit in the STATUS register is reset to logic '0'.

Figure 6-4. WRSR Waveform



#### Note:

1. This instruction initiates a self-timed internal write cycle ( $t_{WC}$ ) on the rising edge of  $\overline{CS}$  after a valid sequence.

#### 6.4.1 Block Write-Protect Function

The WRSR instruction allows the user to select one of four possible combinations as to how the memory array will be inhibited from writing through changing the Block Write-Protect bits (BP[1:0]). The four levels of array protection are:

- · None of the memory array is protected.
- Upper quarter (1/4) address range is write-protected meaning the highest order address bits are read-only.
- Upper half (½) address range is write-protected meaning the highest order address bits are read-only.
- All of the memory array is write-protected meaning all address bits are read-only.

The Block Write Protection levels and corresponding STATUS register control bits are shown in Table 6-4.

Table 6-4. Block Write-Protect Bits

Level	STATUS Register Bits Write-Protected/Read-On		Write-Protected/Read-Only Address Range			
	BP1	BP0	AT25512			
0	0	0	None			
1(1/4)	0	1	C000h-FFFFh			
2(1/2)	1	0	8000h-FFFFh			
3(All)	1	1	0000h-FFFFh			

#### 6.4.2 Write-Protect Enable Function

The WRSR instruction also allows the user to enable or disable the Write-Protect (WP) pin through the use of the Write-Protect Enable (WPEN) bit. When the WPEN bit is set to logic '0', the ability to write the EEPROM array is dictated by the values of the Block Write-Protect (BP[1:0]) bits. The ability to write the STATUS register is controlled by the WEL bit. When the WPEN bit is set to logic '1', the STATUS register is read-only.

Hardware Write Protection is enabled when both the  $\overline{\text{WP}}$  pin is low and the WPEN bit has been set to a logic '1'. When the device is Hardware Write-Protected, writes to the STATUS register, including the Block Write-Protect, WEL and WPEN bits and to the sections in the memory array selected by the Block Write-Protect bits are disabled. When Hardware Write Protection is enabled, writes are only allowed to sections of the memory that are not block-protected.

Hardware Write Protection is disabled when either the  $\overline{\text{WP}}$  pin is high or the WPEN bit is a logic '0'. When Hardware Write Protection is disabled, writes are only allowed to sections of the memory that are not block-protected. Refer to Table 6-5 for additional information.

**Note:** When the WPEN bit is Hardware Write-Protected, it cannot be set back to a logic '0' as long as the WP pin is held low.

Table 6-5. WPEN Operation

WPEN	WP Pin	WEL	Protected Blocks	Unprotected Blocks	STATUS Register
0	Х	0	Protected	Protected	Protected
0	Х	1	Protected	Writable	Writable
1	Low	0	Protected	Protected	Protected
1	Low	1	Protected	Writable	Protected
Х	High	0	Protected	Protected	Protected
Х	High	1	Protected	Writable	Writable

## 7. Read Sequence

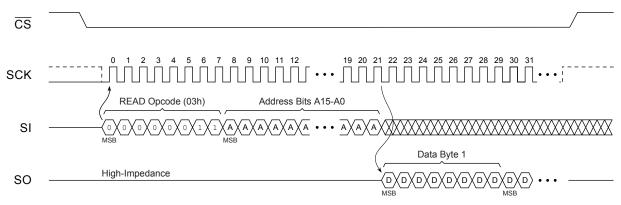
Reading the AT25512 via the SO pin requires the following sequence. After the  $\overline{CS}$  line is pulled low to select a device, the READ (03h) instruction is transmitted via the SI line followed by the 16-bit address to be read. Refer to Table 7-1 for the address bits for AT25512.

Table 7-1. AT25512 Address Bits

Address	AT25512
A <sub>N</sub>	A <sub>15</sub> —A <sub>0</sub>

Upon completion of the 16-bit address, any data on the SI line will be ignored. The data (D7-D0) at the specified address is then shifted out onto the SO line. If only one byte is to be read, the  $\overline{\text{CS}}$  line should be driven high after the data comes out. The read sequence can be continued since the byte address is automatically incremented and data will continue to be shifted out. When the highest-order address bit is reached, the address counter will rollover to the lowest-order address bit allowing the entire memory to be read in one continuous read cycle regardless of the starting address.

Figure 7-1. Read Waveform



#### 8. Write Sequence

In order to program the AT25512, two separate instructions must be executed. First, the device must be write enabled via the Write Enable (WREN) instruction. Then, one of the two possible write sequences described in this section may be executed.

Note: If the device is not Write Enabled (WREN), the device will ignore the WRITE instruction and will return to the standby state when  $\overline{CS}$  is brought high. A new  $\overline{CS}$  assertion is required to re-initiate communication.

The address of the memory location(s) to be programmed must be outside the protected address field location selected by the block write protection level. During an internal write cycle, all commands will be ignored except the RDSR instruction. Refer to Table 8-1 for the address bits for AT25512.

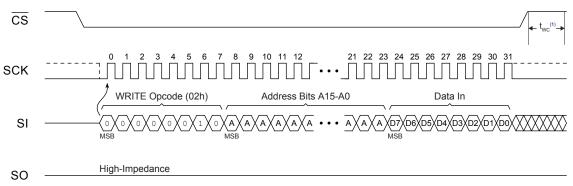
Table 8-1. AT25512 Address Bits

Address	AT25512
A <sub>N</sub>	A <sub>15</sub> —A <sub>0</sub>

#### 8.1 **Byte Write**

A Byte Write requires the following sequence and is depicted in Figure 8-1. After the CS line is pulled low to select the device, the WRITE (02h) instruction is transmitted via the SI line followed by the 16-bit address and the data (D7-D0) to be programmed. Programming will start after the  $\overline{CS}$  pin is brought high. The low-to-high transition of the  $\overline{\rm CS}$  pin must occur during the SCK low time (Mode 0) and SCK high time (Mode 3) immediately after clocking in the D0 (LSB) data bit. The AT25512 is automatically returned to the Write Disable state (STATUS register bit WEL = 0) at the completion of a write cycle.

Figure 8-1. Byte Write



#### Note:

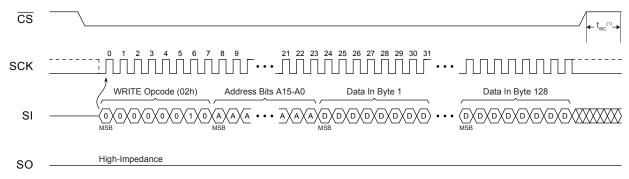
This instruction initiates a self-timed internal write cycle ( $t_{WC}$ ) on the rising edge of  $\overline{CS}$  after a valid sequence.

#### 8.2 **Page Write**

A Page Write sequence allows up to 128 bytes to be written in the same write cycle, provided that all bytes are in the same row of the memory array. Partial Page Writes of less than 128 bytes are allowed. After each byte of data is received, the seven lowest order address bits are internally incremented

**Datasheet** DS20006218A-page 24 following the receipt of each data byte. The higher order address bits are not incremented and retain the memory array page location. If more bytes of data are transmitted that what will fit to the end of that memory row, the address counter will rollover to the beginning of the same row. Nevertheless, creating a rollover event should be avoided as previously loaded data in the page could become unintentionally altered. The AT25512 is automatically returned to the Write Disable state (WEL = 0) at the completion of a write cycle.

Figure 8-2. Page Write



#### Note:

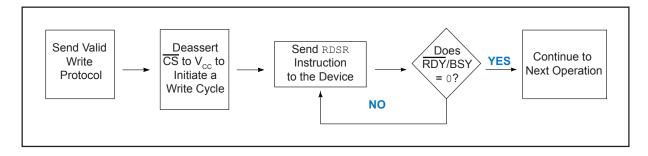
 This instruction initiates a self-timed internal write cycle (t<sub>WC</sub>) on the rising edge of CS after a valid sequence.

## 8.3 Polling Routine

A polling routine can be implemented to optimize time-sensitive applications that would not prefer to wait the fixed maximum write cycle time ( $t_{WC}$ ). This method allows the application to know immediately when the write cycle has completed to start a subsequent operation.

Once the internally-timed write cycle has started, a polling routine can be initiated. This involves repeatedly sending Read STATUS Register (RDSR) instruction to determine if the device has completed its self-timed internal write cycle. If the  $\overline{RDY}/BSY$  bit (bit 0 of STATUS register) = 1, the write cycle is still in progress. If bit 0 = 0, the write cycle has ended. If the  $\overline{RDY}/BSY$  bit = 1, repeated RDSR commands can be executed until the  $\overline{RDY}/BSY$  bit = 0, signaling that the device is ready to execute a new instruction. Only the Read STATUS Register (RDSR) instruction is enabled during the write cycle.

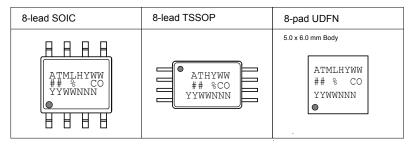
Figure 8-3. Polling Flowchart



# 9. Packaging Information

## 9.1 Package Marking Information

## AT25512: Package Marking Information



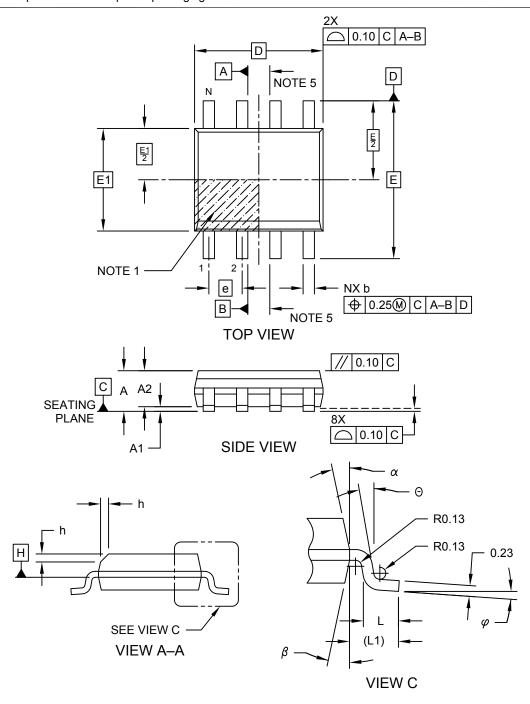
Note 1: designates pin 1

Note 2: Package drawings are not to scale

Catalog Number Truncation								
AT25512			Trun	cation Code ##: 5F				
Date Codes	\$				Voltages			
YY = Year		Y = Year		WW = Work Week of Assembly	% = Minimum Voltage			
16: 2016	20: 2020	6: 2016	0: 2020	02: Week 2	L or M: 1.8V min			
17: 2017	21: 2021	7: 2017	1: 2021	04: Week 4				
18: 2018	22: 2022	8: 2018	2: 2022					
19: 2019	23: 2023	9: 2019	3: 2023	52: Week 52				
Country of	Origin		Device	Grade	Atmel Truncation			
CO = Count	try of Origin		H or U:	Industrial Grade	AT: Atmel ATM: Atmel ATML: Atmel			
Lot Number or Trace Code								
NNN = Alphanumeric Trace Code (2 Characters for Small Packages)								

## 8-Lead Plastic Small Outline (SN) - Narrow, 3.90 mm (.150 ln.) Body [SOIC]

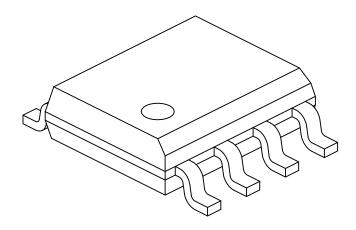
**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



Microchip Technology Drawing No. C04-057-SN Rev E Sheet 1 of 2

## 8-Lead Plastic Small Outline (SN) - Narrow, 3.90 mm (.150 ln.) Body [SOIC]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	MILLIMETERS				
Dimension	Limits	MIN	NOM	MAX	
Number of Pins	Ν		8		
Pitch	е		1.27 BSC		
Overall Height	Α	ı	ı	1.75	
Molded Package Thickness	A2	1.25	ı	-	
Standoff §	A1	0.10	ı	0.25	
Overall Width	Е	6.00 BSC			
Molded Package Width	E1	3.90 BSC			
Overall Length	D		4.90 BSC		
Chamfer (Optional)	h	0.25	ı	0.50	
Foot Length	L	0.40	ı	1.27	
Footprint	L1		1.04 REF		
Foot Angle	$\varphi$	0°	ı	8°	
Lead Thickness	С	0.17	ı	0.25	
Lead Width	b	0.31	1	0.51	
Mold Draft Angle Top	α	5°	-	15°	
Mold Draft Angle Bottom	β	5°	-	15°	

#### Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. § Significant Characteristic
- 3. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.15mm per side.
- 4. Dimensioning and tolerancing per ASME Y14.5M

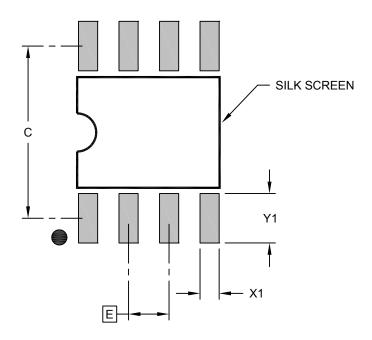
BSC: Basic Dimension. Theoretically exact value shown without tolerances. REF: Reference Dimension, usually without tolerance, for information purposes only.

5. Datums A & B to be determined at Datum H.

Microchip Technology Drawing No. C04-057-SN Rev E Sheet 2 of 2

## 8-Lead Plastic Small Outline (SN) - Narrow, 3.90 mm Body [SOIC]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



## RECOMMENDED LAND PATTERN

	MILLIMETERS			
Dimension	MIN	NOM	MAX	
Contact Pitch	1.27 BSC			
Contact Pad Spacing	С		5.40	
Contact Pad Width (X8)	X1			0.60
Contact Pad Length (X8)	Y1			1.55

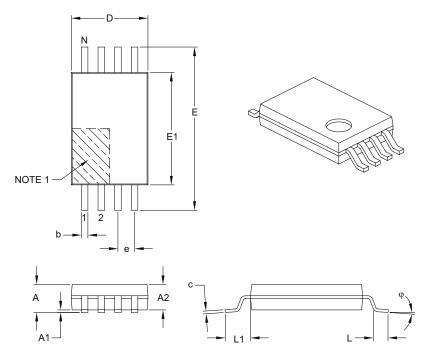
#### Notes:

Dimensioning and tolerancing per ASME Y14.5M
 BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing C04-2057-SN Rev E

## 8-Lead Plastic Thin Shrink Small Outline (ST) - 4.4 mm Body [TSSOP]

te: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units			
Dimension	Dimension Limits			
Number of Pins	N		8	
Pitch	е		0.65 BSC	
Overall Height	Α	-	-	1.20
Molded Package Thickness	A2	0.80	1.00	1.05
Standoff	A1	0.05	-	0.15
Overall Width	Е		6.40 BSC	
Molded Package Width	E1	4.30	4.40	4.50
Molded Package Length	D	2.90	3.00	3.10
Foot Length	L	0.45	0.60	0.75
Footprint	L1	1.00 REF		
Foot Angle	φ	0°	-	8°
Lead Thickness	С	0.09	-	0.20
Lead Width	b	0.19	_	0.30

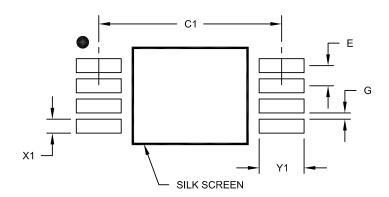
#### Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.15 mm per side.
- 3. Dimensioning and tolerancing per ASME Y14.5M.
  - BSC: Basic Dimension. Theoretically exact value shown without tolerances.
  - REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-086B

## 8-Lead Plastic Thin Shrink Small Outline (ST) - 4.4 mm Body [TSSOP]

For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



## RECOMMENDED LAND PATTERN

	Units			MILLIMETERS		
Dimension Limits		MIN	NOM	MAX		
Contact Pitch	Е		0.65 BSC			
Contact Pad Spacing	C1		5.90			
Contact Pad Width (X8)	X1			0.45		
Contact Pad Length (X8)	Y1			1.45		
Distance Between Pads	G	0.20				

#### Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

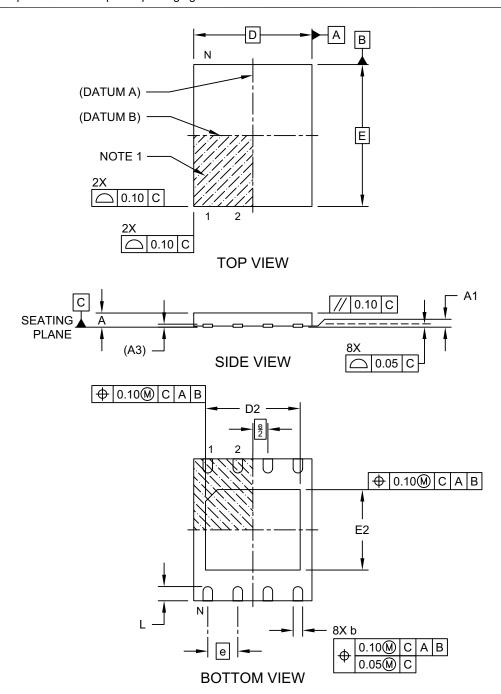
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2086A



# 8-Lead Ultra Thin Plastic Dual Flat, No Lead Package (Q5B) - 5x6 mm Body [UDFN] Atmel Legacy (YFG)

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging

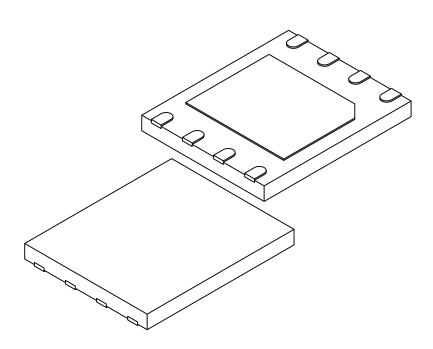


Microchip Technology Drawing C04-21356 Rev B Sheet 1 of 2



# 8-Lead Ultra Thin Plastic Dual Flat, No Lead Package (Q5B) - 5x6 mm Body [UDFN] Atmel Legacy (YFG)

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units		MILLIMETERS		
Dimension	Dimension Limits		NOM	MAX	
Number of Terminals	N	8			
Pitch	е	1.27 BSC			
Overall Height	Α	1	-	0.60	
Standoff	A1	0.00	0.02	0.05	
Terminal Thickness	A3	0.127 REF			
Overall Length	D	5.00 BSC			
Exposed Pad Length	D2	3.90	4.00	4.10	
Overall Width	Е	6.00 BSC			
Exposed Pad Width	E2	3.30 3.40 3.50			
Terminal Width	b	0.30 0.40 0.50			
Terminal Length	L	0.50 0.60 0.70			

#### Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. Package is saw singulated
- 3. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

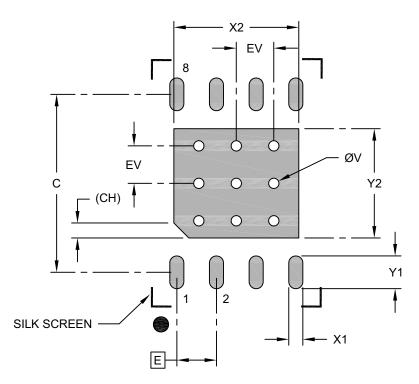
REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-21356 Rev B Sheet 2 of 2



# 8-Lead Ultra Thin Plastic Dual Flat, No Lead Package (Q5B) - 5x6 mm Body [UDFN] Atmel Legacy (YFG)

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



**RECOMMENDED LAND PATTERN** 

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	Е	0.50 BSC		
Optional Center Pad Width	X2			4.10
Optional Center Pad Length	Y2			3.50
Contact Pad Spacing	С		5.70	
Contact Pad Width (X8)	X1			0.45
Contact Pad Length (X8)	Y1			1.05
Corner Chamfer	CH	0.48 REF		
Thermal Via Diameter	V		0.33	
Thermal Via Pitch	EV	1.20		

#### Notes:

Dimensioning and tolerancing per ASME Y14.5M
 BSC: Basic Dimension. Theoretically exact value shown without tolerances.

2. For best soldering results, thermal vias, if used, should be filled or tented to avoid solder loss during reflow process

Microchip Technology Drawing C04-23356 Rev B

#### 10. **Revision History**

#### Revision A (June 2019)

Updated to the Microchip template. Microchip DS20006218 replaces Atmel document 5165. Updated Part Marking Information. Added ESD rating. Removed lead finish designation. Added POR recommendations section. Changed Data Retention spec to 100 year. Updated trace code format in package markings. Updated section content throughout for clarification. Updated the SOIC, TSSOP and UDFN package drawings to the Microchip equivalents.

#### Atmel Document 5165 Revision K (January 2017)

Removed waffle pack die sale option. Changed wafer sales note.

#### **Atmel Document 5165 Revision J (January 2015)**

Updated the 8X package outline drawing and the ordering information section.

#### Atmel Document 5165 Revision I (July 2013)

Correct ordering code table from 8A2 to 8X package option. Updated footers and disclaimer page.

#### Atmel Document 5165 Revision H (August 2012)

Updated part markings and package drawings. Updated template.

#### Atmel Document 5165 Revision G (September 2009)

Updated Part Marking Scheme.

#### Atmel Document 5165 Revision F (March 2009)

Changed Maximum Operating Voltage from 4.3V to 6.25V in the Absolute Maximum Table on page 2.

#### Atmel Document 5165 Revision E (August 2008)

Updated for 1.8V - 5.5V operation.

#### Atmel Document 5165 Revision D (May 2008)

Added part marking diagram information.

#### Atmel Document 5165 Revision C (August 2007)

Changed address bit number to seven on page 9. Removed Preliminary status.

#### Atmel Document 5165 Revision B (March 2007)

Changed spacing on table notes. Reworked Figure 4-8. Updated to new template. Change status to Preliminary.

#### Atmel Document 5165 Revision A (January 2007)

Initial document release.

DS20006218A-page 35 **Datasheet** 

## The Microchip Website

Microchip provides online support via our website at <a href="http://www.microchip.com/">http://www.microchip.com/</a>. This website is used to make files and information easily available to customers. Some of the content available includes:

- Product Support Data sheets and errata, application notes and sample programs, design resources, user's guides and hardware support documents, latest software releases and archived software
- General Technical Support Frequently Asked Questions (FAQs), technical support requests, online discussion groups, Microchip design partner program member listing
- Business of Microchip Product selector and ordering guides, latest Microchip press releases, listing of seminars and events, listings of Microchip sales offices, distributors and factory representatives

## **Product Change Notification Service**

Microchip's product change notification service helps keep customers current on Microchip products. Subscribers will receive email notification whenever there are changes, updates, revisions or errata related to a specified product family or development tool of interest.

To register, go to http://www.microchip.com/pcn and follow the registration instructions.

## **Customer Support**

Users of Microchip products can receive assistance through several channels:

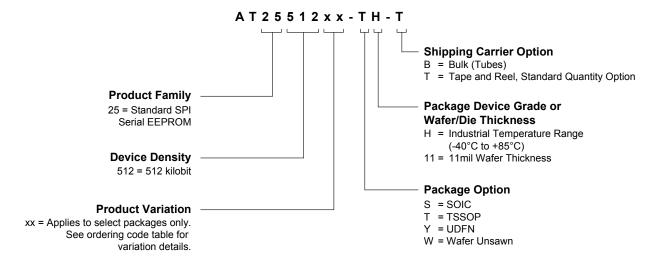
- · Distributor or Representative
- · Local Sales Office
- Embedded Solutions Engineer (ESE)
- Technical Support

Customers should contact their distributor, representative or ESE for support. Local sales offices are also available to help customers. A listing of sales offices and locations is included in this document.

Technical support is available through the web site at: http://www.microchip.com/support

## **Product Identification System**

To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office.



#### Examples:

Device	Package	Package Drawing Code	Package Option	Shipping Carrier Option	Device Grade
AT25512N-SH-B	SOIC	SN	S	Bulk (Tubes)	Industrial
AT25512N-SH-T	SOIC	SN	S	Tape and Reel	Temperature (-40°C to 85°C)
AT25512-TH-B	TSSOP	ST	Т	Bulk (Tubes)	(
AT25512-TH-T	TSSOP	ST	Т	Tape and Reel	
AT25512Y7-YH-T	UDFN	Q5B	Y	Tape and Reel	

# Microchip Devices Code Protection Feature

Note the following details of the code protection feature on Microchip devices:

- Microchip products meet the specification contained in their particular Microchip Data Sheet.
- Microchip believes that its family of products is one of the most secure families of its kind on the market today, when used in the intended manner and under normal conditions.
- There are dishonest and possibly illegal methods used to breach the code protection feature. All of
  these methods, to our knowledge, require using the Microchip products in a manner outside the
  operating specifications contained in Microchip's Data Sheets. Most likely, the person doing so is
  engaged in theft of intellectual property.
- Microchip is willing to work with the customer who is concerned about the integrity of their code.
- Neither Microchip nor any other semiconductor manufacturer can guarantee the security of their code. Code protection does not mean that we are guaranteeing the product as "unbreakable."

Code protection is constantly evolving. We at Microchip are committed to continuously improving the code protection features of our products. Attempts to break Microchip's code protection feature may be a

violation of the Digital Millennium Copyright Act. If such acts allow unauthorized access to your software or other copyrighted work, you may have a right to sue for relief under that Act.

## **Legal Notice**

Information contained in this publication regarding device applications and the like is provided only for your convenience and may be superseded by updates. It is your responsibility to ensure that your application meets with your specifications. MICROCHIP MAKES NO REPRESENTATIONS OR WARRANTIES OF ANY KIND WHETHER EXPRESS OR IMPLIED, WRITTEN OR ORAL, STATUTORY OR OTHERWISE, RELATED TO THE INFORMATION, INCLUDING BUT NOT LIMITED TO ITS CONDITION, QUALITY, PERFORMANCE, MERCHANTABILITY OR FITNESS FOR PURPOSE. Microchip disclaims all liability arising from this information and its use. Use of Microchip devices in life support and/or safety applications is entirely at the buyer's risk, and the buyer agrees to defend, indemnify and hold harmless Microchip from any and all damages, claims, suits, or expenses resulting from such use. No licenses are conveyed, implicitly or otherwise, under any Microchip intellectual property rights unless otherwise stated.

## **Trademarks**

The Microchip name and logo, the Microchip logo, Adaptec, AnyRate, AVR, AVR logo, AVR Freaks, BesTime, BitCloud, chipKIT, chipKIT logo, CryptoMemory, CryptoRF, dsPIC, FlashFlex, flexPWR, HELDO, IGLOO, JukeBlox, KeeLoq, Kleer, LANCheck, LinkMD, maXStylus, maXTouch, MediaLB, megaAVR, Microsemi, Microsemi logo, MOST, MOST logo, MPLAB, OptoLyzer, PackeTime, PIC, picoPower, PICSTART, PIC32 logo, PolarFire, Prochip Designer, QTouch, SAM-BA, SenGenuity, SpyNIC, SST, SST Logo, SuperFlash, Symmetricom, SyncServer, Tachyon, TempTrackr, TimeSource, tinyAVR, UNI/O, Vectron, and XMEGA are registered trademarks of Microchip Technology Incorporated in the U.S.A. and other countries.

APT, ClockWorks, The Embedded Control Solutions Company, EtherSynch, FlashTec, Hyper Speed Control, HyperLight Load, IntelliMOS, Libero, motorBench, mTouch, Powermite 3, Precision Edge, ProASIC, ProASIC Plus, ProASIC Plus logo, Quiet-Wire, SmartFusion, SyncWorld, Temux, TimeCesium, TimeHub, TimePictra, TimeProvider, Vite, WinPath, and ZL are registered trademarks of Microchip Technology Incorporated in the U.S.A.

Adjacent Key Suppression, AKS, Analog-for-the-Digital Age, Any Capacitor, Anyln, AnyOut, BlueSky, BodyCom, CodeGuard, CryptoAuthentication, CryptoAutomotive, CryptoCompanion, CryptoController, dsPICDEM, dsPICDEM.net, Dynamic Average Matching, DAM, ECAN, EtherGREEN, In-Circuit Serial Programming, ICSP, INICnet, Inter-Chip Connectivity, JitterBlocker, KleerNet, KleerNet logo, memBrain, Mindi, MiWi, MPASM, MPF, MPLAB Certified logo, MPLIB, MPLINK, MultiTRAK, NetDetach, Omniscient Code Generation, PICDEM, PICDEM.net, PICkit, PICtail, PowerSmart, PureSilicon, QMatrix, REAL ICE, Ripple Blocker, SAM-ICE, Serial Quad I/O, SMART-I.S., SQI, SuperSwitcher, SuperSwitcher II, Total Endurance, TSHARC, USBCheck, VariSense, ViewSpan, WiperLock, Wireless DNA, and ZENA are trademarks of Microchip Technology Incorporated in the U.S.A. and other countries.

SQTP is a service mark of Microchip Technology Incorporated in the U.S.A.

The Adaptec logo, Frequency on Demand, Silicon Storage Technology, and Symmcom are registered trademarks of Microchip Technology Inc. in other countries.

GestIC is a registered trademark of Microchip Technology Germany II GmbH & Co. KG, a subsidiary of Microchip Technology Inc., in other countries.

All other trademarks mentioned herein are property of their respective companies.

© 2019, Microchip Technology Incorporated, Printed in the U.S.A., All Rights Reserved.

ISBN: 978-1-5224-4657-6

AMBA, Arm, Arm7, Arm7TDMI, Arm9, Arm11, Artisan, big.LITTLE, Cordio, CoreLink, CoreSight, Cortex, DesignStart, DynamIQ, Jazelle, Keil, Mali, Mbed, Mbed Enabled, NEON, POP, RealView, SecurCore, Socrates, Thumb, TrustZone, ULINK, ULINK2, ULINK-ME, ULINK-PLUS, ULINKpro, µVision, Versatile are trademarks or registered trademarks of Arm Limited (or its subsidiaries) in the US and/or elsewhere.

## **Quality Management System**

For information regarding Microchip's Quality Management Systems, please visit http://www.microchip.com/quality.



# **Worldwide Sales and Service**

AMERICAS	ASIA/PACIFIC	ASIA/PACIFIC	EUROPE
Corporate Office	Australia - Sydney	India - Bangalore	Austria - Wels
2355 West Chandler Blvd.	Tel: 61-2-9868-6733	Tel: 91-80-3090-4444	Tel: 43-7242-2244-39
Chandler, AZ 85224-6199	China - Beijing	India - New Delhi	Fax: 43-7242-2244-393
Tel: 480-792-7200	Tel: 86-10-8569-7000	Tel: 91-11-4160-8631	Denmark - Copenhagen
Fax: 480-792-7277	China - Chengdu	India - Pune	Tel: 45-4450-2828
Technical Support:	Tel: 86-28-8665-5511	Tel: 91-20-4121-0141	Fax: 45-4485-2829
http://www.microchip.com/support	China - Chongqing	Japan - Osaka	Finland - Espoo
Web Address:	Tel: 86-23-8980-9588	Tel: 81-6-6152-7160	Tel: 358-9-4520-820
http://www.microchip.com	China - Dongguan	Japan - Tokyo	France - Paris
Atlanta	Tel: 86-769-8702-9880	Tel: 81-3-6880- 3770	Tel: 33-1-69-53-63-20
Duluth, GA	China - Guangzhou	Korea - Daegu	Fax: 33-1-69-30-90-79
Tel: 678-957-9614	Tel: 86-20-8755-8029	Tel: 82-53-744-4301	Germany - Garching
Fax: 678-957-1455	China - Hangzhou	Korea - Seoul	Tel: 49-8931-9700
Austin, TX	Tel: 86-571-8792-8115	Tel: 82-2-554-7200	Germany - Haan
Tel: 512-257-3370	China - Hong Kong SAR	Malaysia - Kuala Lumpur	Tel: 49-2129-3766400
Boston	Tel: 852-2943-5100	Tel: 60-3-7651-7906	Germany - Heilbronn
Westborough, MA	China - Nanjing	Malaysia - Penang	Tel: 49-7131-72400
Tel: 774-760-0087	Tel: 86-25-8473-2460	Tel: 60-4-227-8870	Germany - Karlsruhe
Fax: 774-760-0088	China - Qingdao	Philippines - Manila	Tel: 49-721-625370
Chicago	Tel: 86-532-8502-7355	Tel: 63-2-634-9065	Germany - Munich
Itasca, IL	China - Shanghai	Singapore	Tel: 49-89-627-144-0
Tel: 630-285-0071	Tel: 86-21-3326-8000	Tel: 65-6334-8870	Fax: 49-89-627-144-44
Fax: 630-285-0075	China - Shenyang	Taiwan - Hsin Chu	Germany - Rosenheim
Dallas	Tel: 86-24-2334-2829	Tel: 886-3-577-8366	Tel: 49-8031-354-560
Addison, TX	China - Shenzhen	Taiwan - Kaohsiung	Israel - Ra'anana
Tel: 972-818-7423	Tel: 86-755-8864-2200	Tel: 886-7-213-7830	Tel: 972-9-744-7705
Fax: 972-818-2924	China - Suzhou	Taiwan - Taipei	Italy - Milan
Detroit	Tel: 86-186-6233-1526	Tel: 886-2-2508-8600	Tel: 39-0331-742611
Novi, MI	China - Wuhan	Thailand - Bangkok	Fax: 39-0331-466781
Tel: 248-848-4000	Tel: 86-27-5980-5300	Tel: 66-2-694-1351	Italy - Padova
Houston, TX	China - Xian	Vietnam - Ho Chi Minh	Tel: 39-049-7625286
Tel: 281-894-5983	Tel: 86-29-8833-7252	Tel: 84-28-5448-2100	Netherlands - Drunen
Indianapolis	China - Xiamen		Tel: 31-416-690399
Noblesville, IN	Tel: 86-592-2388138		Fax: 31-416-690340
Tel: 317-773-8323	China - Zhuhai		Norway - Trondheim
Fax: 317-773-5453	Tel: 86-756-3210040		Tel: 47-72884388
Tel: 317-536-2380			Poland - Warsaw
Los Angeles			Tel: 48-22-3325737
Mission Viejo, CA			Romania - Bucharest
Tel: 949-462-9523			Tel: 40-21-407-87-50
Fax: 949-462-9608			Spain - Madrid
Tel: 951-273-7800			Tel: 34-91-708-08-90
Raleigh, NC			Fax: 34-91-708-08-91
Tel: 919-844-7510			Sweden - Gothenberg
New York, NY			Tel: 46-31-704-60-40
Tel: 631-435-6000			Sweden - Stockholm
San Jose, CA			Tel: 46-8-5090-4654
Tel: 408-735-9110			UK - Wokingham
Tel: 408-436-4270			Tel: 44-118-921-5800
Canada - Toronto			Fax: 44-118-921-5820
Tel: 905-695-1980			
Fax: 905-695-2078			