Stepping Motors



₽Z mm sq.

1.8°/step RoHS

Bipolar winding, Connector type

Unipolar winding, Connector type ▶p. 45

Customizing

Shaft length Shaft shape

Varies depending on the model number and quantity. Contact us for details.

Bipolar winding, Connector type

| Model no. | | Holding torque at 2-phase energization | Rated current | Wiring resistance | Winding inductance | Rotor inertia | Mass | Motor length (L) |
|--------------|--------------|--|---------------|-------------------|--------------------|-------------------------|------|---------------------|
| Single shaft | Dual shaft | N·m min. | A/phase | Ω/phase | mH/phase | ×10 ⁻⁴ kg⋅m² | kg | mm |
| SF2421-10B41 | SF2421-10B11 | 0.29 | 1 | 3.6 | 7 | 0.031 | 0.23 | 33±0.5 |
| SF2422-10B41 | SF2422-10B11 | 0.43 | 1 | 4.6 | 9.6 | 0.046 | 0.3 | 39±0.5 |
| SF2423-10B41 | SF2423-10B11 | 0.56 | 1 | 5.3 | 12.5 | 0.063 | 0.38 | 48±0.5 |
| SF2424-10B41 | SF2424-10B11 | 0.8 | 1 | 6.5 | 16 | 0.094 | 0.51 | 59.5±1 |

Characteristics diagram

SF2421-10B41 SF2421-10B11

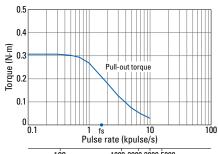
Constant current circuit Source voltage: 24 VDC Operating current: 1 A/phase, 2-phase energization (full-step) Pull-out torque: J.=0.94×10-⁴kg·m² (use the rubber coupling) fs: Maximum self-start fragespace whose part frequency when not loaded

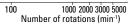
SF2423-10B41

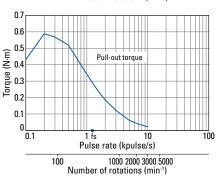
SF2423-10B11

Constant current circuit
Source voltage: 24 VDC
Operating current:
1 A/phase, 2-phase
energization (full-step)
Pull-out torque:
J.=0.94×10-4kg·m² (use the
rubber coupling)
fs: Maximum self-start
frequency when not
loaded

loaded





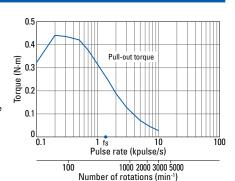


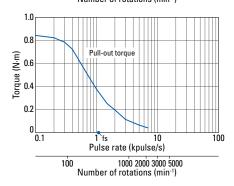
SF2422-10B41 SF2422-10B11

Constant current circuit
Source voltage: 24 VDC
Operating current:
1 A/phase, 2-phase
energization (full-step)
Pull-out torque:
J₁=0.94×10⁻⁴kg·m² (use the
rubber coupling)
fs: Maximum self-start
fraguspay whop pet frequency when not loaded

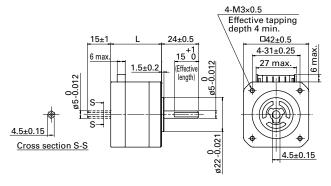
SF2424-10B41 SF2424-10B11

Constant current circuit Source voltage: 24 VDC Operating current: 1 A/phase, 2-phase energization (full-step) Pull-out torque: Ju-2.6x10-4g-m² (use the rubber coupling) fs: Maximum self-start frequency when not loaded





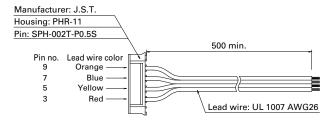
Dimensions (Unit: mm)



Internal wiring () connector pin number



Option (sold separately): Motor cable model no. 4835775-1



This motor cable is for model no. SF242□-10B□1.

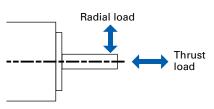
■ Compatible drivers ■

Model no.: BS1D200P10

Operating current select switch setting: A

The characteristics diagram shown above is from our experimental circuit.

Allowable Radial/Thrust Load



| | | Distance f | Distance from end of shaft: mm | | | |
|---------------|------------|-------------|--------------------------------|-----|-----|----------------------|
| Motor size | Model no. | 0 | 5 | 10 | 15 | - Thrust load - N |
| | | Radial load | d: N | | | - 11 |
| 14 mm sq. | SH214 🗌 | 10 | 11 | 13 | _ | 0.7 |
| 28 mm sq. | SH228 🗌 | 42 | 48 | 56 | 66 | 3 |
| 35 mm sq. | SH353 🗌 | 40 | 50 | 67 | 98 | 10 |
| | SF242 □ | 20 | 29 | 49 | 68 | - 10 |
| 42 mm sq. | SH142 🗌 | 22 | 26 | 33 | 46 | - 10 |
| | SS242 🗌 | 10 | _ | - | _ | 4.9 |
| E0 mm og | 103H670 🗌 | 71 | 87 | 115 | 167 | 15 |
| 50 mm sq. | SS250 🗆 | 8.5 | - | - | - | 4.9 |
| E6 mm oa | 103H712 🗌 | 52 | 65 | 85 | 123 | 15 |
| 56 mm sq. | 103H7128 | 85 | 105 | 138 | 200 | 15 |
| 60 mm sq. | 103H782 🗌 | - 70 | 87 | 114 | 165 | 20 |
| oo iiiii sq. | SH160 🗌 | 70 | 67 | 114 | 105 | 15 |
| 86 mm sq. | SM286 □ | 167 | 193 | 229 | 280 | 60 |
| | SH286 🗆 | | | | | |
| º86 mm | 103H822 🗌 | 191 | 234 | 301 | 421 | 60 |
| °106 mm | 103H8922 🗌 | 321 | 356 | 401 | 457 | 100 |

Internal Wiring and Rotation Direction

Unipolar winding

Connector type model no.: SF242

■ Internal wire connection

() connector pin number



Direction of motor rotation

When excited by a direct current in the order shown below, the direction of rotation is clockwise as viewed from the output shaft side.

| | | Connecto | Connector pin no. | | | | | | | |
|----------------|---|----------|-------------------|-----|-----|------|--|--|--|--|
| | | (3, 9) | (1) | (7) | (5) | (11) | | | | |
| | 1 | + | _ | _ | | | | | | |
| Exciting | 2 | + | | - | - | | | | | |
| Exciting order | 3 | + | | | - | - | | | | |
| | 4 | + | - | | | - | | | | |

Connector type model no.: 103H782 □□

Internal wire connection

() connector pin number



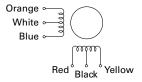
Direction of motor rotation

When excited by a direct current in the order shown below, the direction of rotation is clockwise as viewed from the output shaft side.

| | | Connector pin no. | | | | | | | |
|----------------|---|-------------------|-----|-----|-----|-----|--|--|--|
| | | (1, 6) | (4) | (3) | (5) | (2) | | | |
| | 1 | + | - | - | | | | | |
| Exciting | 2 | + | | - | - | | | | |
| Exciting order | 3 | + | | | - | - | | | |
| | 4 | + | - | | | - | | | |

Lead wire type

Internal wire connection



Direction of motor rotation

When excited by a direct current in the order shown below, the direction of rotation is clockwise as viewed from the output shaft side.

| | | Lead wire color | | | | | | |
|----------|---|-----------------|-----|------|--------|--------|--|--|
| | | White, black | Red | Blue | Yellow | Orange | | |
| | 1 | + | - | - | | | | |
| Exciting | 2 | + | | - | - | | | |
| order | 3 | + | | | - | - | | |
| | 4 | + | _ | | | - | | |

Bipolar winding

Connector type model no.: SF242

Internal wire connection

() connector pin number



Direction of motor rotation

When excited by a direct current in the order shown below, the direction of rotation is clockwise as viewed from the output shaft side.

| | _ | Connect | or pin no. | | |
|----------------|---|---------|------------|-----|-----|
| | | (3) | (7) | (5) | (9) |
| | 1 | - | - | + | + |
| Exciting | 2 | + | _ | - | + |
| Exciting order | 3 | + | + | - | - |
| | 4 | _ | + | + | _ |

Connector type model no.: 103H782

Internal wire connection

() connector pin number



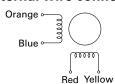
■ Direction of motor rotation

When excited by a direct current in the order shown below, the direction of rotation is clockwise as viewed from the output shaft side.

| | | Connect | or pin no. | | |
|----------------|---|---------|------------|-----|-----|
| | | (3) | (2) | (4) | (1) |
| | 1 | - | - | + | + |
| Exciting | 2 | + | - | - | + |
| Exciting order | 3 | + | + | - | - |
| | 4 | - | + | + | - |

Lead wire type

Internal wire connection



Direction of motor rotation

When excited by a direct current in the order shown below, the direction of rotation is clockwise as viewed from the output shaft side.

| | Lead wir | e color | | | |
|----------|----------|---------|------|--------|--------|
| | | Red | Blue | Yellow | Orange |
| | 1 | _ | _ | + | + |
| Exciting | 2 | + | _ | _ | + |
| order | 3 | + | + | _ | - |
| | 4 | - | + | + | - |

General Specifications

| Motor model no. | SH214 🗌 | SH228 🗌 | SH353 🗌 | SS242 🗌 | SH142 🗌 | SF242 🗌 | SS250 🗆 | 103H670 🗆 | 103H712 🗌 |
|---|---------------------------------------|--|---|---------------------------------|---------------------------------|-------------------------|----------------------------------|--------------------------|--------------------------|
| Туре | _ | | | | | | | | |
| Operating ambient temperature | -10 to +50°C | ; | | | | | | | |
| Storage temperature | -20 to +65°C | | | | | | | | |
| Operating ambient humidity | 20 to 90% R | H (no conder | nsation) | | | | | | |
| Storage humidity | 5 to 95% RH | I (no condens | sation) | | | | | | |
| Operation altitude | 1000 m max | c. above sea | evel | | | | | | |
| Vibration resistance | | | 500 Hz, tota cycle, 12 swee | | | | ration accele | ration 150 m/s | s² (70 to 500 |
| Impact resistance | 500 m/s ² of a | cceleration fo | r 11 ms with h | half-sine wave | applying th | ree times for λ | (, Y, and Z axe | s each, 18 tim | es in total. |
| Thermal class | Class B (+13 | 30°C) | | | | | | | |
| Withstandable voltage | | | nd humidity, vinding and f | | ith 500 VAC | @50/60 Hz ар | oplied for one | @50/60 Hz applie | |
| Insulation resistance | At normal to | emperature a | nd humidity, | not less that | n 100 MΩ be | tween windir | ng and frame | by 500 VDC n | negger. |
| Protection grade | _ | | | | | | | | |
| Winding temperature rise | 80 K max. (I | Based on SAI | NYO DENKI s | tandard) | | | | | |
| Static angle error | ±0.09° | | | | ±0.054° | ±0.09° | | | ±0.054° |
| Thrust play *1 | 0.075 mm max. (load: 0.35 N) | 0.075 mm max. (load: 1.5 N) | 0.075 mm max. (load: 5 N) | 0.075 mm max. (load: 4 N) | 0.075 mm max. (load: 5 N) | 0.075 mm (load: 5 N) | 0.075 mm max. (load: 4 N) | 0.075 mm (load: 10 N) | 0.075 mm (load: 10 N) |
| Radial play *2 | | nax. (load: 5 l | U) | | | | 1 | l | l . |
| Shaft runout | 0.025 mm | iax. (load. o l | • | | | | | | |
| Concentricity of mounting pilot relative to shaft | ø0.05 mm | ø0.05 mm | ø0.075 mm | ø0.075 mm | ø0.05 mm | ø0.05 mm | ø0.075 mm | ø0.075 mm | ø0.075 mm |
| Squareness of mounting surface relative to shaft | 0.1 mm | 0.1 mm | 0.1 mm | 0.1 mm | 0.1 mm | 0.1 mm | 0.1 mm | 0.075 mm | 0.075 mm |
| Direction of motor mounting | Can be free | ly mounted v | ertically or h | orizontally | | | | | |
| Motor model no. | SH160 🗆 | 103H782 🗆 | SH286 🗆 | 103H8922 | SM286 □ | 103H712 🗌 - | 6 🗆 0 103H822 CE Mod | | 3H8922 □ -63 □ 1 |
| Туре | _ | | | | S1 (contin | uous operati | | ei GE | Model |
| Operating ambient temperature | -10 to +50°C | • | | | -10 to +40 | | 011/ | | |
| Storage temperature | | | | | -20 to +60 | | | | |
| Operating ambient humidity | | | acation) | | | | r less (no con | donaction | |
| Operating ambient numicity | 20 to 90% K | n (no conder | isation) | | | | r less (no con r less, 57% RI | | C or loss |
| Storage humidity | | I (no condens | | | | | r less, 57% Ri | | or less, |
| Operation altitude Vibration resistance | Vibration fre | | 500 Hz, tota | | | | ration accele | ration 150 m/s | s² (70 to |
| | | | nin/cycle, 12 | | | | × V V 7 | woo oo b 10 | timaa in tat-l |
| Impact resistance | 500 m/s² of a | acceleration f | or 11 ms with | ı naıt-sine wa | | three times fo | or X, Y and Z a | exes each, 18 | urnes in total |
| Thermal class | Class B (+13 | | umidity no foil | | Class F (+155°C) | Class B (+ | | | |
| Withstandable voltage | ure with 1000 | At normal temperature and humidity, no failure with 1000 VAC @50/60 Hz applied for one minute between motor winding and frame. At normal temperature and humidity, no failure with 1500 VAC @50/60 Hz applied for one minute between motor winding and frame. | | | | | | @50/60 Hz | |
| Insulation resistance | | | | not less the | n 100 MΩ be | tween windir | ng and frame | by 500 VDC n | negger. |
| Protection grade | _ | | | | IP43 | | | | |
| Winding temperature rise | 80 K max. (E | Based on SAI | NYO DENKI s | tandard) | | | | | |
| Static angle error | ±0.054° | ±0.09° | | | | ±0.054° | ±0.09° | | |
| Thrust play *1 | 0.075 mm m | 0.075 mm max. (load: 10 N) | | | | | | | |
| Radial play *2 | 0.025 mm (load: 5 N) | 0.025 mm (load: 5 N) | 0.025 mm (load: 5 N) | 0.025 mm (load: 10 N | 0.025 mm) (load: 5 N | | | |)25 mm ad: 10 N) |
| Shaft runout | 0.025 mm | · · | | | | | | | |
| Concentricity of mounting pilot relative to shaft | ø0.075 mm | | | | | | | | |
| Squareness of mounting surface relative to shaft | 0.1 mm | 0.075 mm | 0.15 mm | 0.1 mm | 0.15 mm | 0.075 mm | 0.1 mr | n 0.1 | l mm |
| Direction of motor mounting | Can be free | ly mounted v | ertically or ho | orizontally | | | | | |

■ Safety standards

Model no.: SM286 ☐ CE/UL marked models

| CE | Standard category | | Applicable standard | |
|-------|-----------------------|----------------------|------------------------|--|
| (TÜV) | Low-voltage directive | es | EN 60034-1, EN 60034-5 | |
| | | Applicable standard | File no. | |
| UL | UL | UL 1004-1, UL 1004-6 | E170922 | |
| | UL for Canada | CSA C22.2 No.100 | - E1/9832 | |

| Model no.: 103H712 ☐ -6 ☐ 0, 103H822 ☐ -6 ☐ 0, 103H8922 ☐ -63 ☐ 1 CE marked model | | | | | | | |
|---|------------------------|------------------------|--|--|--|--|--|
| CE | Standard category | Applicable standard | | | | | |
| (TÜV) | Low-voltage directives | EN 60034-1, EN 60034-5 | | | | | |

^{*1} Thrust play: Shaft displacement under axial load.
*2 Radial play: Shaft displacement under radial load applied 1/3rd of the length from the end of the shaft.