R88M-K□, R88M-KH□

G5 Rotary Servo Motors

Servo family for accurate motion control.
Power range extended up to 15 kW.

- Standard and high inertia servo motor models
- Peak torque 300% of rated torque during 3 seconds or more depending on model
- High resolution serial encoder provided by 20 bits encoder
- IP67 protection in all models
- Ultra-light and compact size motor
- Low speed ripple and low torque ripple due to low torque cogging
- Various shaft, brake and seal options

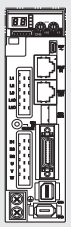
Ratings

- 230 VAC from 50 W to 1.5 kW (rated torque from 0.16 to 8.59 Nm)
- 400 VAC from 400 W to 15 kW (rated torque from 1.91 Nm to 95.5 Nm)

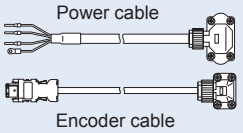
System configuration

(Refer to servo drive chapter)

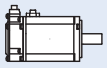
Servo drive options



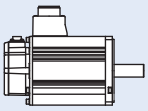
G5 servo drives
EtherCAT and
Analogue/pulse models



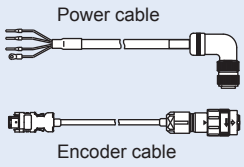
Standard servo motors

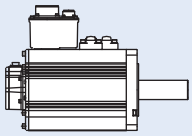


3000 rpm (50 W to 750 W)

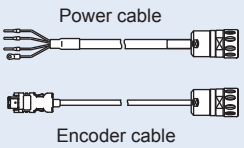


3000 rpm (750 W to 5 kW)
2000 rpm (400 W to 5 kW)
1000 rpm (900 W to 3 kW)

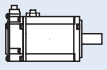




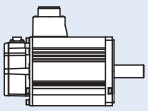
1500 rpm (7.5 kW to 15 kW)
1000 rpm (4.5 kW to 6 kW)



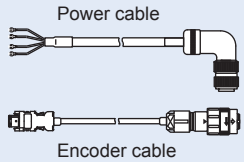
High inertia servo motors

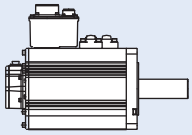


3000 rpm (200 W to 750 W)



2000 rpm (1 kW to 5 kW)





1500 rpm (7.5 kW)

Servo motor / servo drive combination

Standard servo motors

G5 rotary servo motor						G5 rotary servo drive models	
	Voltage	Speed	Rated torque	Capacity	Model	EtherCAT	Analog/pulse
	230 V	3000 min^{-1}	0.16 Nm	50 W	R88M-K05030(H/T)-□	R88D-KN01H-ECT	R88D-KT01H
			0.32 Nm	100 W	R88M-K10030(H/T)-□	R88D-KN01H-ECT	R88D-KT01H
			0.64 Nm	200 W	R88M-K20030(H/T)-□	R88D-KN02H-ECT	R88D-KT02H
			1.3 Nm	400 W	R88M-K40030(H/T)-□	R88D-KN04H-ECT	R88D-KT04H
			2.4 Nm	750 W	R88M-K75030(H/T)-□	R88D-KN08H-ECT	R88D-KT08H
			3.18 Nm	1000 W	R88M-K1K030(H/T)-□	R88D-KN15H-ECT	R88D-KT15H
			4.77 Nm	1500 W	R88M-K1K530(H/T)-□	R88D-KN15H-ECT	R88D-KT15H
	400 V		2.39 Nm	750 W	R88M-K75030(F/C)-□	R88D-KN10F-ECT	R88D-KT10F
			3.18 Nm	1000 W	R88M-K1K030(F/C)-□	R88D-KN15F-ECT	R88D-KT15F
			4.77 Nm	1500 W	R88M-K1K530(F/C)-□	R88D-KN15F-ECT	R88D-KT15F
			6.37 Nm	2000 W	R88M-K2K030(F/C)-□	R88D-KN20F-ECT	R88D-KT20F
			9.55 Nm	3000 W	R88M-K3K030(F/C)-□	R88D-KN30F-ECT	R88D-KT30F
230 V (1 kW to 1.5 kW) 400 V (400 W to 5 kW)			12.7 Nm	4000 W	R88M-K4K030(F/C)-□	R88D-KN50F-ECT	R88D-KT50F
			15.9 Nm	5000 W	R88M-K5K030(F/C)-□	R88D-KN50F-ECT	R88D-KT50F
	230 V	2000 min^{-1}	4.77 Nm	1000 W	R88M-K1K020(H/T)-□	R88D-KN10H-ECT	R88D-KT10H
			7.16 Nm	1500 W	R88M-K1K520(H/T)-□	R88D-KN15H-ECT	R88D-KT15H
	400 V		1.91 Nm	400 W	R88M-K40020(F/C)-□	R88D-KN06F-ECT	R88D-KT06F
			2.86 Nm	600 W	R88M-K60020(F/C)-□	R88D-KN06F-ECT	R88D-KT06F
			4.77 Nm	1000 W	R88M-K1K020(F/C)-□	R88D-KN10F-ECT	R88D-KT10F
			7.16 Nm	1500 W	R88M-K1K520(F/C)-□	R88D-KN15F-ECT	R88D-KT15F
			9.55 Nm	2000 W	R88M-K2K020(F/C)-□	R88D-KN20F-ECT	R88D-KT20F
			14.3 Nm	3000 W	R88M-K3K020(F/C)-□	R88D-KN30F-ECT	R88D-KT30F
7.5 KW to 15 kW			19.1 Nm	4000 W	R88M-K4K020(F/C)-□	R88D-KN50F-ECT	R88D-KT50F
			23.9 Nm	5000 W	R88M-K5K020(F/C)-□	R88D-KN50F-ECT	R88D-KT50F
	400 V	1500 min^{-1}	47.8 Nm	7500 W	R88M-K7K515C-□	R88D-KN75F-ECT	R88D-KT75F
			70.0 Nm	11000 W	R88M-K11K015C-□	R88D-KN150F-ECT	R88D-KT150F
			95.5 Nm	15000 W	R88M-K15K015C-□	R88D-KN150F-ECT	R88D-KT150F
	230 V	1000 min^{-1}	8.59 Nm	900 W	R88M-K90010(H/T)-□	R88D-KN15H-ECT	R88D-KT15H
	400 V		8.59 Nm	900 W	R88M-K90010(F/C)-□	R88D-KN15F-ECT	R88D-KT15F
			19.1 Nm	2000 W	R88M-K2K010(F/C)-□	R88D-KN30F-ECT	R88D-KT30F
			28.7 Nm	3000 W	R88M-K3K010(F/C)-□	R88D-KN50F-ECT	R88D-KT50F
			43.0 Nm	4500 W	R88M-K4K510C-□	R88D-KN50F-ECT	R88D-KT50F
			57.3 Nm	6000 W	R88M-K6K010C-□	R88D-KN75F-ECT	R88D-KT75F

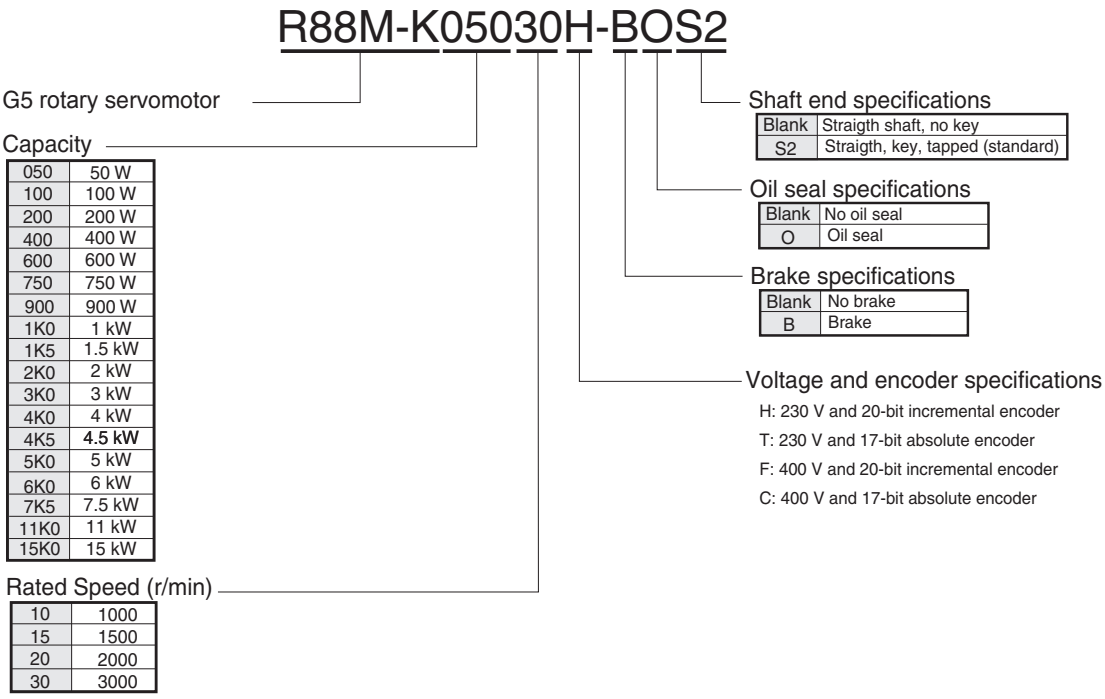
High inertia servo motors

G5 rotary servo motor						G5 rotary servo drive models	
	Voltage	Speed	Rated torque	Capacity	Model	EtherCAT	Analog/pulse
	230 V	3000 min^{-1}	0.64 Nm	200 W	R88M-KH20030(H/T)-□	R88D-KN02H-ECT	R88D-KT02H
			1.3 Nm	400 W	R88M-KH40030(H/T)-□	R88D-KN04H-ECT	R88D-KT04H
			2.4 Nm	750 W	R88M-KH75030(H/T)-□	R88D-KN08H-ECT	R88D-KT08H
	400 V	2000 min^{-1}	4.77 Nm	1000 W	R88M-KH1K020(F/C)-□	R88D-KN10F-ECT	R88D-KT10F
			7.16 Nm	1500 W	R88M-KH1K520(F/C)-□	R88D-KN15F-ECT	R88D-KT15F
			9.55 Nm	2000 W	R88M-KH2K020(F/C)-□	R88D-KN20F-ECT	R88D-KT20F
1 kW to 5 kW			14.3 Nm	3000 W	R88M-KH3K020(F/C)-□	R88D-KN30F-ECT	R88D-KT30F
			19.1 Nm	4000 W	R88M-KH4K020(F/C)-□	R88D-KN50F-ECT	R88D-KT50F
			23.9 Nm	5000 W	R88M-KH5K020(F/C)-□	R88D-KN50F-ECT	R88D-KT50F
		1500 min^{-1}	47.8 Nm	7500 W	R88M-KH7K515C-□	R88D-KN75F-ECT	R88D-KT75F
7.5 KW							

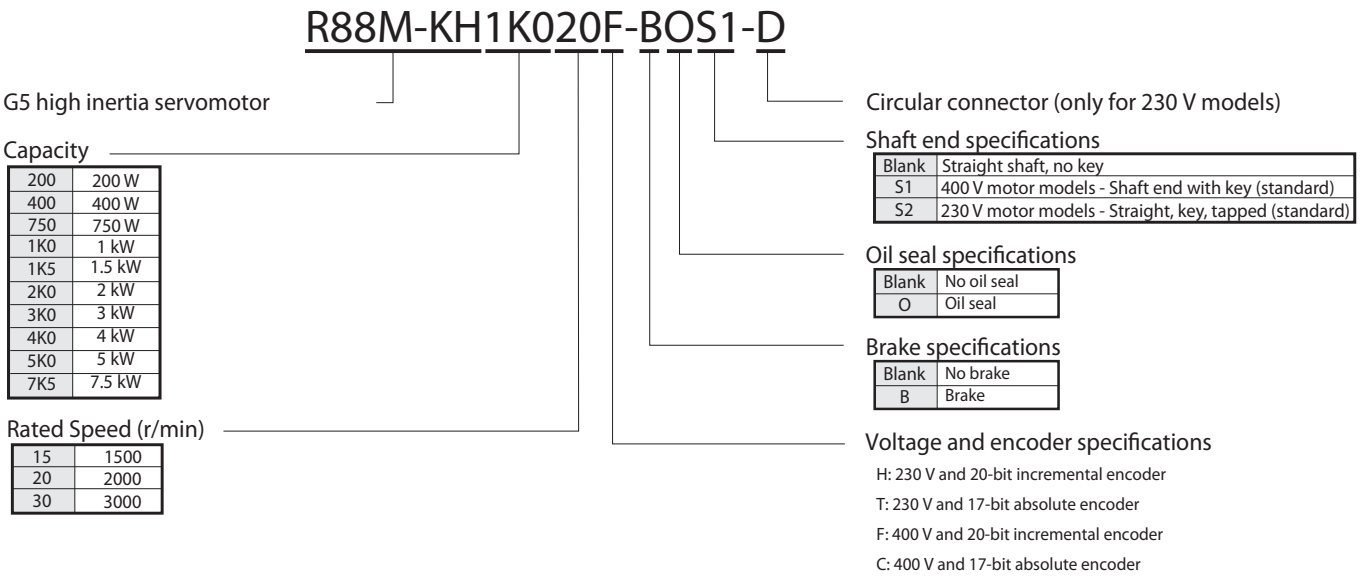
Note: 1. For servo motor and cables part numbers refer to ordering information at the end of this chapter
2. Refer to the servo drive chapter for drive options selection and detailed specifications

Servo motor type designation

Standard servo motors



High inertia servo motors



Servo motor specifications

Standard servo motors 3000 r/min, 230 V

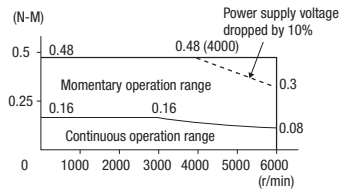
Ratings and specifications

Voltage			230 V						
Servo motor model R88M-K□		20-bit incremental encoder	05030H-□	10030H-□	20030H-□	40030H-□	75030H-□	1K030H-□	1K530H-□
		17-bit absolute encoder	05030T-□	10030T-□	20030T-□	40030T-□	75030T-□	1K030T-□	1K530T-□
Rated output		W	50	100	200	400	750	1000	1500
Rated torque		N·m	0.16	0.32	0.64	1.3	2.4	3.18	4.77
Instantaneous peak torque		N·m	0.48	0.95	1.91	3.8	7.1	9.55	14.3
Rated current		A (rms)	1.1	1.1	1.5	2.4	4.1	6.6	8.2
Instantaneous max. current		A (rms)	4.7	4.7	6.5	10.2	17.4	28	35
Rated speed		min^{-1}	3000						
Max. speed		min^{-1}	6000					5000	
Torque constant		N·m/A	0.11±10%	0.21±10%	0.31±10%	0.39±10%	0.42±10%	0.37	0.45
Rotor moment of inertia (JM)		$kg·m^2×10^{-4}$ (without brake)	0.025	0.051	0.14	0.26	0.87	2.03	2.84
		$kg·m^2×10^{-4}$ (with brake)	0.027	0.054	0.16	0.28	0.97	2.35	3.17
Allowable load moment of inertia (JL)		Multiple of (JM)	30 *1				20 *1	15 *1	
Rated power rate		kW/s (without brake)	10.1	19.9	29.0	62.4	65.6	49.8	80.1
		kW/s (with brake)	9.4	18.8	25.4	58	58.8	43	71.8
Allowable radial load		N	68		245		490		
Allowable thrust load		N	58		98		196		
Approx. mass		kg (without brake)	0.32	0.47	0.82	1.2	2.3	3.5	4.4
		kg (with brake)	0.53	0.68	1.3	1.7	3.1	4.5	5.4
Brake specifications	Rated voltage		24 VDC ±10%						
	Holding brake moment of inertia J	$kg·m^2×10^{-4}$	0.002		0.0018		0.33		
	Power consumption (at 20°C)	W	7		9		17	19	
	Current consumption (at 20°C)	A	0.3		0.36		0.70±10%	0.81±10%	
	Static friction torque	N.m (minimum)	0.29		1.27		2.5	7.8	
	Rise time for holding torque	ms (max.)	35		50				
	Release time	ms (max)	20		15				
Basic specifications	Time Rating		Continuous						
	Insulation class		Type B					Type F	
	Ambient operating/ storage temperature		0 to +40°C/–20 to 65°C						
	Ambient operating/ storage humidity		20% to 80% (non-condensing)					20% to 85% (non-condensing)	
	Vibration class		V-15						
	Insulation resistance		20 MΩ min. at 500 VDC between the power terminals and FG terminal						
	Enclosure		Totally-enclosed, self-cooling, IP67 (excluding shaft opening)						
	Vibration resistance		Vibration acceleration 49 m/s^2						
	Mounting		Flange-mounted						

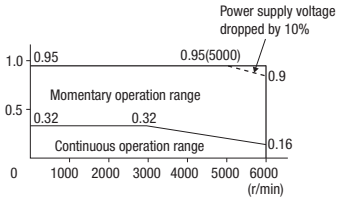
*1 Applicable load inertia: The operable load inertia ratio (load inertia/rotor inertia) depends on the mechanical configuration and its rigidity. For a machine with high rigidity, operation is possible even with high load inertia. Select an appropriate motor and confirm that operation is possible.

Torque-speed characteristics

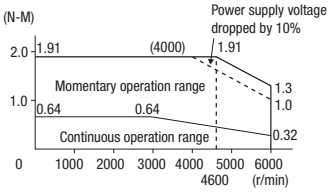
R88M-K05030H/T (50 W)



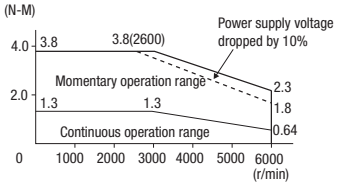
R88M-K10030H/T (100 W)



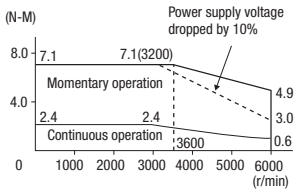
R88M-K20030H/T (200 W)



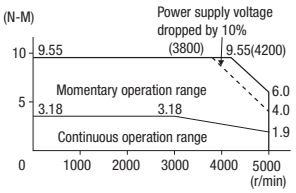
R88M-K40030H/T (400 W)



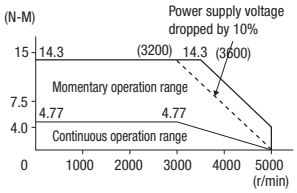
R88M-K75030H/T (750 W)



R88M-K1K030H/T (1 kW)



R88M-K1K530H/T (1.5 kW)



Standard servo motors 3000 r/min, 400 V

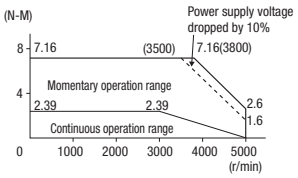
Ratings and specifications

Voltage			400 V						
Servo motor model R88M-K□		20-bit incremental encoder	75030F-□	1K030F-□	1K530F-□	2K030F-□	3K030F-□	4K030F-□	5K030F-□
		17-bit absolute encoder	75030C-□	1K030C-□	1K530C-□	2K030C-□	3K030C-□	4K030C-□	5K030C-□
Rated output		W	750	1000	1500	2000	3000	4000	5000
Rated torque		N·m	2.39	3.18	4.77	6.37	9.55	12.7	15.9
Instantaneous peak torque		N·m	7.16	9.55	14.3	19.1	28.6	38.2	47.7
Rated current		A (rms)	2.4	3.3	4.2	5.7	9.2	9.9	12
Instantaneous max. current		A (rms)	10	14	18	24	39	42	51
Rated speed		min^{-1}	3000						
Max. speed		min^{-1}	5000					4500	
Torque constant		N·m/A	0.78	0.75	0.89	0.87	0.81	0.98	
Rotor moment of inertia (JM)		$kg·m^2×10^{-4}$ (without brake)	1.61	2.03	2.84	3.68	6.5	12.9	17.4
		$kg·m^2×10^{-4}$ (with brake)	1.93	2.35	3.17	4.01	7.85	14.2	18.6
Allowable load moment of inertia (JL)		Multiple of (JM)	20*1	15*1					
Rated power rate		kW/s (without brake)	35.5	49.8	80.1	110	140	126	146
		kW/s (with brake)	29.6	43	71.8	101	116	114	136
Allowable radial load		N	490					784	
Allowable thrust load		N	196					343	
Approx. mass		kg (without brake)	3.1	3.5	4.4	5.3	8.3	11	14
		kg (with brake)	4.1	4.5	5.4	6.3	9.4	12.6	16
Brake specifications	Rated voltage		24 VDC ±10%						
	Holding brake moment of inertia J	$kg·m^2×10^{-4}$	0.33						1.35
	Power consumption (at 20°C)	W	17	19				22	
	Current consumption (at 20°C)	A	0.70±10%	0.81±10%				0.90±10%	
	Static friction torque	N.m (minimum)	2.5	7.8			11.8	16.1	
	Rise time for holding torque	ms (max.)	50					110	
	Release time	ms (max)	15					50	
Basic specifications	Time Rating		Continuous						
	Insulation class		Type F						
	Ambient operating/ storage temperature		0 to +40°C/–20 to 65°C						
	Ambient operating/ storage humidity		20% to 85% (non-condensing)						
	Vibration class		V-15						
	Insulation resistance		20 MΩ min. at 500 VDC between the power terminals and FG terminal						
	Enclosure		Totally-enclosed, self-cooling, IP67(excluding shaft opening)						
	Vibration resistance		Vibration acceleration 49 m/s²						
	Mounting		Flange-mounted						

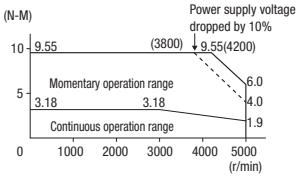
*1 Applicable load inertia: The operable load inertia ratio (load inertia/rotor inertia) depends on the mechanical configuration and its rigidity. For a machine with high rigidity, operation is possible even with high load inertia. Select an appropriate motor and confirm that operation is possible.

Torque-speed characteristics

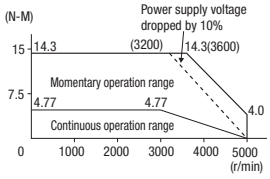
R88M-K75030F/C (750 W)



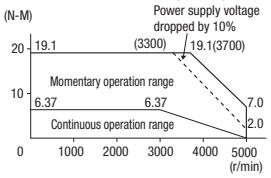
R88M-K1K030F/C (1 kW)



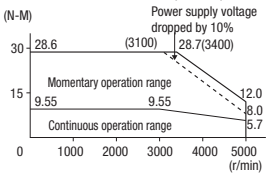
R88M-K1K530F/C (1.5 kW)



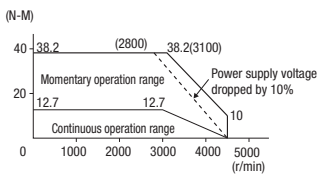
R88M-K2K030F/C (2 kW)



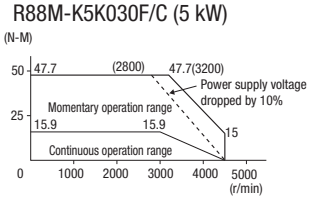
R88M-K3K030F/C (3 kW)



R88M-K4K030F/C (4 kW)



R88M-K5K030F/C (5 kW)



Standard servo motors 2000 r/min, 230 V/400 V

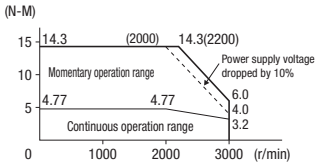
Ratings and specifications

Voltage			230 V		400 V							
Servo motor model R88M-K□	20-bit incremental encoder		1K020H-□	1K520H-□	40020F-□	60020F-□	1K020F-□	1K520F-□	2K020F-□	3K020F-□	4K020F-□	5K020F-□
	17-bit absolute encoder		1K020T-□	1K520T-□	40020C-□	60020C-□	1K020C-□	1K520C-□	2K020C-□	3K020C-□	4K020C-□	5K020C-□
Rated output		W	1000	1500	400	600	1000	1500	2000	3000	4000	5000
Rated torque		N·m	4.77	7.16	1.91	2.86	4.77	7.16	9.55	14.3	19.1	23.9
Instantaneous peak torque		N·m	14.3	21.5	5.73	8.59	14.3	21.5	28.7	43	57.3	71.6
Rated current		A (rms)	5.7	9.4	1.2	1.5	2.8	4.7	5.9	8.7	10.6	13
Instantaneous max. current		A (rms)	24	40	4.9	6.5	12	20	25	37	45	55
Rated speed		min^{-1}	2000									
Max. speed		min^{-1}	3000									
Torque constant		N·m/A	0.63	0.58	1.27	1.38	1.27	1.16	1.27	1.18	1.40	1.46
Rotor moment of inertia (JM)		$kg·m^2×10^{-4}$ (without brake)	4.60	6.70	1.61	2.03	4.60	6.70	8.72	12.9	37.6	48
		$kg·m^2×10^{-4}$ (with brake)	5.90	7.99	1.90	2.35	5.90	7.99	10	14.2	38.6	48.8
Max. load moment of inertia (JL)		Multiple of (JM)	10*1									
Rated power rate		kW/s (without brake)	49.5	76.5	22.7	40.3	49.5	76.5	105	159	97.1	119
		kW/s (with brake)	38.6	64.2	19.2	34.8	38.6	64.2	91.2	144	94.5	117
Allowable radial load		N	490							784		
Allowable thrust load		N	196							343		
Approx. mass		kg (without brake)	5.2	6.7	3.1	3.5	5.2	6.7	8	11	15.5	18.6
		kg (with brake)	6.7	8.2	4.1	4.5	6.7	8.2	9.5	12.6	18.7	21.8
Brake specifications	Rated voltage		24VDC ±10%									
	Holding brake moment inertia	(J) $kg·m^2×10^{-4}$	1.35								4.7	
	Power consumption (20°C)	W	14	19	17		14	19		22	31	
	Current consumption (20°C)	A	0.59±10%	0.79±10%	0.70 ±10%		0.59±10%	0.79 ±10%		0.90±10%	1.3±10%	1.3 ±-10%
	Static friction torque	N.m (minimum)	4.9	13.7	2.5		4.9	13.7		16.2	24.5	
	Rise time for holding torque	ms (max.)	80	100	50		80	100		110	80	
	Release time	ms (max)	70	50	15		70	50			25	
Basic specifications	Time Rating		Continuous									
	Insulation class		Type F									
	Ambient operating/ storage temperature		0 to +40°C/–20 to 65°C									
	Ambient operating/ storage humidity		20% to 85% (non-condensing)									
	Vibration class		V-15									
	Insulation resistance		20 MΩ min. at 500 VDC between the power terminals and FG terminal									
	Enclosure		Totally-enclosed, self-cooling, IP67 (excluding shaft opening)									
	Vibration resistance		Vibration acceleration 49 m/s²									
	Mounting		Flange-mounted									

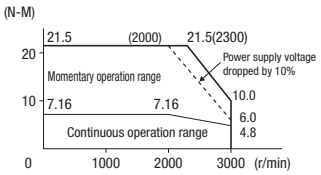
*1. Applicable load inertia: The operable load inertia ratio (load inertia/rotor inertia) depends on the mechanical configuration and its rigidity. For a machine with high rigidity, operation is possible even with high load inertia. Select an appropriate motor and confirm that operation is possible.

Torque-speed characteristics

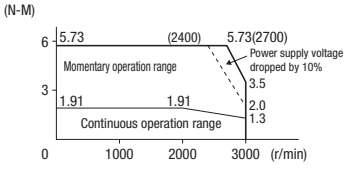
R88M-K1K020H/T (230V, 1 kW)



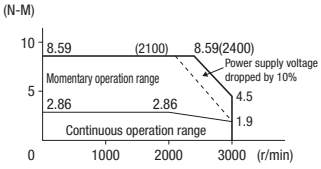
R88M-K1K520H/T (230V, 1.5 kW)



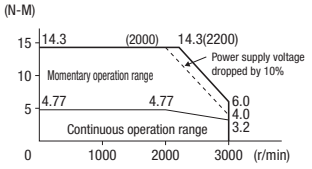
R88M-K40020F/C (400V, 400 W)



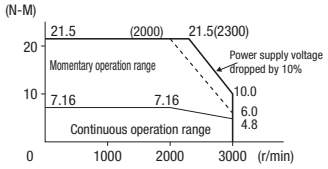
R88M-K60020F/C (400V, 600 W)



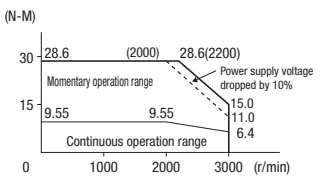
R88M-K1K020F/C (400V, 1 kW)



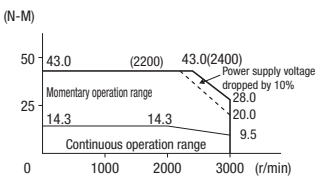
R88M-K1K520F/C (400V, 1.5 kW)



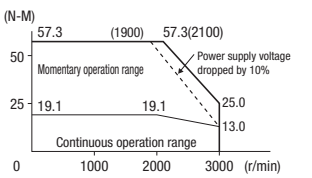
R88M-K2K020F/C (400V, 2 kW)



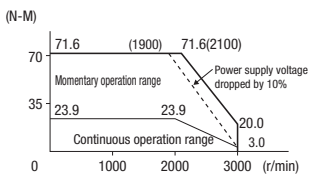
R88M-K3K020F/C (400V, 3 kW)



R88M-K4K020F/C (400V, 4 kW)



R88M-K5K020F/C (400V, 5 kW)



Standard servo motors 1500 r/min, 400 V

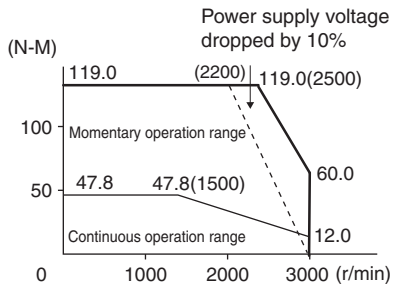
Ratings and specifications

Applied voltage			400 V		
Servo motor model R88M-K□		**17-bit absolute encoder**	**7K515C-□**	**11K015C-□**	**15K015C-□**
Rated output		W	7500	11000	15000
Rated torque		N·m	47.8	70.0	95.5
Instantaneous peak torque		N·m	119.0	175.0	224.0
Rated current		A (rms)	22.0	27.1	33.1
Instantaneous max. current		A (rms)	83	101	118
Rated speed		min^{-1}	1500		
Max. speed		min^{-1}	3000	2000	
Torque constant		N·m/A	1.54	1.84	2.10
Rotor moment of inertia (JM)		$kg·m^2×10^{-4}$ (without brake)	101	212	302
		$kg·m^2×10^{-4}$ (with brake)	107	220	311
Allowable load moment of inertia (JL)		Multiple of (JM)	10*1		
Rated power rate		kW/s (without brake)	226	231	302
		kW/s (with brake)	213	223	293
Allowable radial load		N	1176	2254	
Allowable thrust load		N	490	686	
Approx. mass		kg (without brake)	36.4	52.7	70.2
		kg (with brake)	40.4	58.9	76.3
Brake specifications	Rated voltage		24VDC ±10%		
	Holding brake moment of inertia J	$kg·m^2×10^{-4}$	4.7	7.1	
	Power consumption (at 20°C)	W	34	26	
	Current consumption (at 20°C)	A	1.4±10%	1.08±10%	
	Static friction torque	N·m (minimum)	58.8	100	
	Rise time for holding torque	ms (max.)	150	300	
	Release time	ms (max)	50	140	
Basic specifications	Time Rating		Continuous		
	Insulation class		Type F		
	Ambient operating/ storage temperature		0 to +40°C/–20 to 65°C		
	Ambient operating/ storage humidity		20% to 85% RH (non-condensing)		
	Vibration class		V-15		
	Insulation resistance		20 MΩ min. at 500 VDC between the power terminals and FG terminal		
	Enclosure		Totally-enclosed, self-cooling, IP67 (excluding shaft opening)		
	Vibration resistance		Vibration acceleration 49 m/s^2		
	Mounting		Flange-mounted		

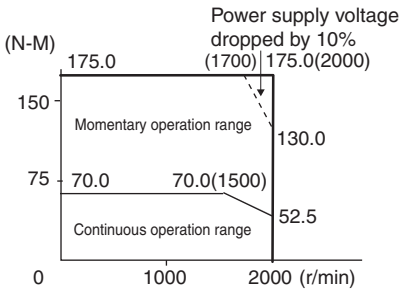
*1 Applicable load inertia: The operable load inertia ratio (load inertia/rotor inertia) depends on the mechanical configuration and its rigidity. For a machine with high rigidity, operation is possible even with high load inertia. Select an appropriate motor and confirm that operation is possible.

Torque-speed characteristics

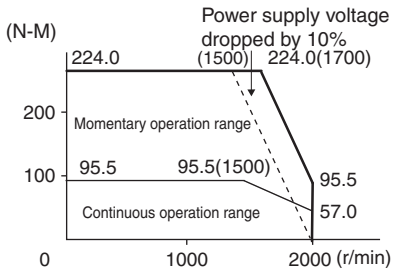
R88M-K7K515C (7.5 kW)



R88M-K11K015C (11 kW)



R88M-K15K015C (15 kW)



Standard servo motors 1000 r/min, 230 V/400 V

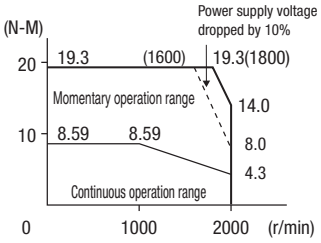
Ratings and specifications

Applied voltage		230 V	400 V				
Servo motor model R88M-K□	20-bit incremental encoder	90010H-□	90010F-□	2K010F-□	3K010F-□		
	17-bit absolute encoder	90010T-□	90010C-□	2K010C-□	3K010C-□	4K510C-□	6K010C-□
Rated output	W	900	900	2000	3000	4500	6000
Rated torque	N·m	8.59		19.1	28.7	43.0	57.3
Instantaneous peak torque	N·m	19.3		47.7	71.7	107.0	143.0
Rated current	A (rms)	7.6	3.8	8.5	11.3	14.8	19.4
Instantaneous max. current	A (rms)	24	12	30	40	55	74
Rated speed	min^{-1}	1000					
Max. speed	min^{-1}	2000					
Torque constant	N·m/A	0.86	1.72	1.76	1.92	2.05	2.08
Rotor moment of inertia (JM)	$kg·m^2×10^{-4}$ (without brake)	6.70		30.3	48.4	79.1	101
	$kg·m^2×10^{-4}$ (with brake)	7.99		31.4	49.2	84.4	107
Allowable load moment of inertia (JL)	Multiple of (JM)	10 *1					
Rated power rate	kW/s (without brake)	110		120	170	233	325
	kW/s (with brake)	92.4		116	167	219	307
Allowable radial load	N	686		1176	1470		1764
Allowable thrust load	N	196		490			588
Approx. mass	kg (without brake)	6.7		14	20	29.4	36.4
	kg (with brake)	8.2		17.5	23.5	33.3	40.4
Brake specifications: Rated voltage		24VDC ±10%					
Brake specifications: Holding brake moment of inertia J	$kg·m^2×10^{-4}$	1.35		4.7			
Brake specifications: Power consumption (at 20°C)	W	19		31	34		
Brake specifications: Current consumption (at 20°C)	A	0.79±10%		1.3±10%	1.4±10%		
Brake specifications: Static friction torque	N·m (minimum)	13.7		24.5	58.8		
Brake specifications: Rise time for holding torque	ms (max.)	100		80	150		
Brake specifications: Release time	ms (max)	50		25	50		
Basic specifications: Time Rating		Continuous					
Basic specifications: Insulation class		Type F					
Basic specifications: Ambient operating/ storage temperature		0 to +40°C/–20 to 65°C					
Basic specifications: Ambient operating/ storage humidity		20% to 85% RH (non-condensing)					
Basic specifications: Vibration class		V-15					
Basic specifications: Insulation resistance		20 MΩ min. at 500 VDC between the power terminals and FG terminal					
Basic specifications: Enclosure		Totally-enclosed, self-cooling, IP67 (excluding shaft opening)					
Basic specifications: Vibration resistance		Vibration acceleration 49 m/s^2					
Basic specifications: Mounting		Flange-mounted					

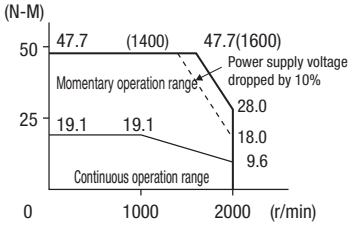
*1 Applicable load inertia: The operable load inertia ratio (load inertia/rotor inertia) depends on the mechanical configuration and its rigidity. For a machine with high rigidity, operation is possible even with high load inertia. Select an appropriate motor and confirm that operation is possible.

Torque-speed characteristics

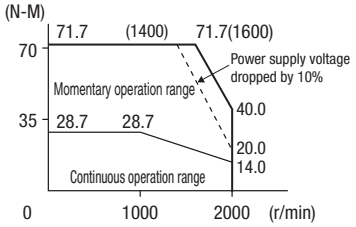
R88M-K90010H/T/F/C



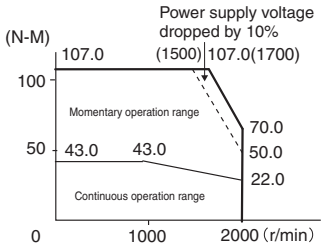
R88M-K2K010F/C



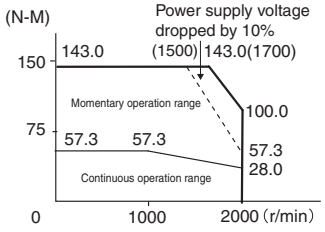
R88M-K3K010F/C



R88M-K4K510C



R88M-K6K010C



High inertia servo motors 3000 r/min, 230 V

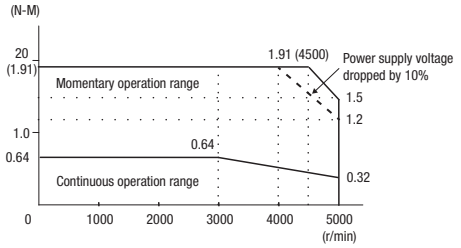
Ratings and specifications

Voltage			230 V		
Servo motor model R88M-KH□	**20-bit incremental encoder**		**20030H-□**	**40030H-□**	**75030H-□**
	17-bit absolute encoder		**20030T-□**	**40030T-□**	**75030T-□**
Rated output	W		200	400	750
Rated torque	N·m		0.64	1.3	2.4
Instantaneous peak torque	N·m		1.91	3.8	7.1
Rated current	A (rms)		1.6	2.6	4.0
Instantaneous max. current	A (rms)		6.9	11.0	17.0
Rated speed	min^{-1}		3000		
Max. speed	min^{-1}		5000		4500
Torque constant	N·m/A		0.29±10%	0.36±10%	0.45±10%
Rotor moment of inertia (JM)	$kg·m^2×10^{-4}$ (without brake)		0.42	0.67	1.51
	$kg·m^2×10^{-4}$ (with brake)		0.45	0.70	1.61
Allowable load moment of inertia (JL)	Multiple of (JM)		30*1		20*1
Rated power rate	kW/s (without brake)		9.58	24.1	37.7
	kW/s (with brake)		9.06	23.3	35.3
Allowable radial load	N		245		392
Allowable thrust load	N		98		147
Approx. mass	kg (without brake)		0.96	1.4	2.5
	kg (with brake)		1.4	1.8	3.3
Brake specifications	Rated voltage		24 VDC ±5%		
	Holding brake moment of inertia J	$kg·m^2×10^{-4}$	0.018		0.075
	Power consumption (at 20°C)	W	9		10
	Current consumption (at 20°C)	A	0.36		0.42
	Static friction torque	N.m (minimum)	1.27		2.45
	Rise time for holding torque	ms (max.)	50		70
	Release time	ms (max)	15		20
Basic specifications	Time Rating		Continuous		
	Insulation class		Type B		
	Ambient operating/ storage temperature		0 to +40°C/–20 to 65°C		
	Ambient operating/ storage humidity		20% to 85% RH (non-condensing)		
	Vibration class		V-15		
	Insulation resistance		20 MΩ min. at 500 VDC between the power terminals and FG terminal		
	Enclosure		Totally-enclosed, self-cooling, IP65 (excluding shaft opening and lead wire ends)		
	Vibration resistance		Vibration acceleration 49 m/s^2		
	Mounting		Flange-mounted		

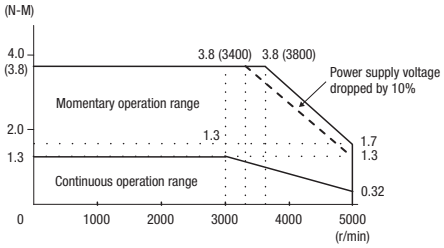
*1 Applicable load inertia: The operable load inertia ratio (load inertia/rotor inertia) depends on the mechanical configuration and its rigidity. For a machine with high rigidity, operation is possible even with high load inertia. Select an appropriate motor and confirm that operation is possible.

Torque-speed characteristics

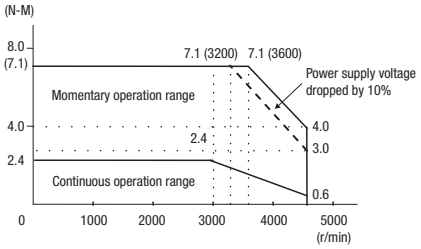
R88M-KH20030H/T (230 V, 200 W)



R88M-KH40030H/T (230 V, 400 W)



R88M-KH75030H/T (230 V, 750 W)



High inertia servo motors 2000 and 1500 r/min, 400 V

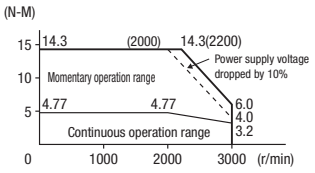
Ratings and specifications

R/min, Voltage		2000 r/min, 400 V						1500 r/min, 400 V
Servo motor model R88M-KH□	20-bit incremental encoder	1K020F-□	1K520F-□	2K020F-□	3K020F-□	4K020F-□	5K020F-□	
	17-bit absolute encoder	1K020C-□	1K520C-□	2K020C-□	3K020C-□	4K020C-□	5K020C-□	7K515C-□
Rated output	W	1000	1500	2000	3000	4000	5000	7500
Rated torque	N·m	4.77	7.16	9.55	14.3	19.1	23.9	47.8
Instantaneous peak torque	N·m	14.3	21.5	28.6	43.0	57.3	71.6	119
Rated current	A (rms)	2.9	4.7	5.5	8.0	10.5	13.0	22.0
Instantaneous max. current	A (rms)	12	20	24	34	45	55	83
Rated speed	min^{-1}	2000						1500
Max. speed	min^{-1}	3000						3000
Torque constant	N·m/A	1.27	1.16	1.31	1.34	1.38	1.39	1.54
Rotor moment of inertia (JM)	$kg·m^2×10^{-4}$ (without brake)	24.7	37.1	57.8	90.2	112	162	273
	$kg·m^2×10^{-4}$ (with brake)	26.0	38.4	62.9	95.3	117	167	279
Max. load moment of inertia (JL)	Multiple of (JM)	5*1						
Rated power rate	kW/s (without brake)	9.2	13.8	15.8	22.7	32.5	35.1	86.7
	kW/s (with brake)	8.8	13.4	14.5	21.5	31.1	34.1	85.1
Allowable radial load	N	490		784				1176
Allowable thrust load	N	196		343				490
Approx. mass	kg (without brake)	6.7	8.6	12.2	16.0	18.6	23.0	42.3
	kg (with brake)	8.1	10.1	15.5	19.2	21.8	26.2	46.2
Brake specifications: Rated voltage		24 VDC ±10%						
Brake specifications: Holding brake moment inertia	(J) $kg·m^2×10^{-4}$	1.35		4.7				
Brake specifications: Power consumption (20°C)	W	14	19	31				34
Brake specifications: Current consumption (20°C)	A	0.59±10%	0.79±10%	1.30±10%				1.40±10%
Brake specifications: Static friction torque	N·m (minimum)	4.9	13.7	24.5				58.8
Brake specifications: Rise time for holding torque	ms (max.)	80	100	80				150
Brake specifications: Release time	ms (max)	70	50	25				50
Basic specifications: Time Rating		Continuous						
Basic specifications: Insulation class		Type F						
Basic specifications: Ambient operating/ storage temperature		0 to +40°C/–20 to 65°C						
Basic specifications: Ambient operating/ storage humidity		20% to 85% RH (non-condensing)						
Basic specifications: Vibration class		V-15						
Basic specifications: Insulation resistance		20 MΩ min. at 500 VDC between the power terminals and FG terminal						
Basic specifications: Enclosure		Totally-enclosed, self-cooling, IP67 (excluding shaft opening)						
Basic specifications: Vibration resistance		Vibration acceleration 49 m/s^2						
Basic specifications: Mounting		Flange-mounted						

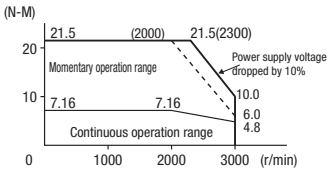
*1 Applicable load inertia: The operable load inertia ratio (load inertia/rotor inertia) depends on the mechanical configuration and its rigidity. For a machine with high rigidity, operation is possible even with high load inertia. Select an appropriate motor and confirm that operation is possible.

Torque-speed characteristics

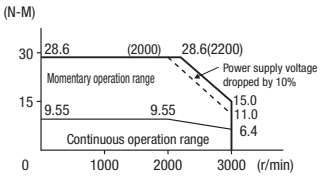
R88M-KH1K020F/C (400 V, 1 kW)



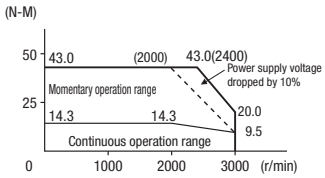
R88M-KH1K520F/C (400 V, 1.5 kW)



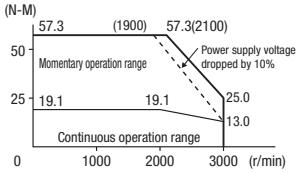
R88M-KH2K020F/C (400 V, 2 kW)



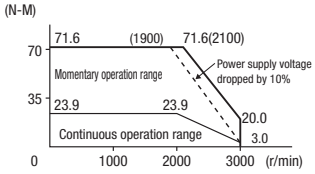
R88M-KH3K020F/C (400 V, 3 kW)



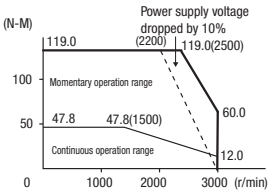
R88M-KH4K020F/C (400 V, 4 kW)



R88M-KH5K020F/C (400 V, 5 kW)



R88M-KH7K515C (7.5 kW)

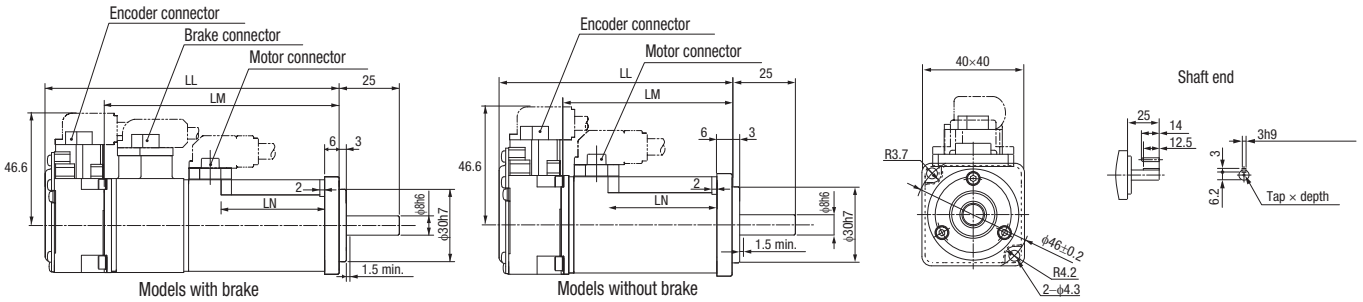


Dimensions

Standard servo motors

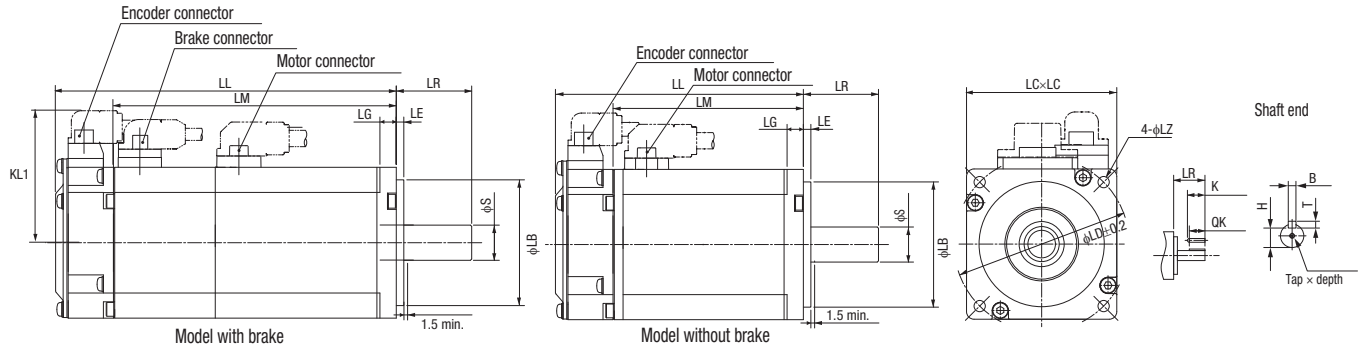
Type 3000 r/min motors (230 V, 50 to 100 W)

Dimensions (mm)	Without brake		With brake		LN	Shaft end dimensions	Approx. mass (kg)	
Model	LL	LM	LL	LM		Tap × Depth	Without brake	With brake
R88M-K05030(H/T)-□S2	72	48	102	78	23	M3 × 6L	0.32	0.53
R88M-K10030(H/T)-□S2	92	68	122	98	43		0.47	0.68



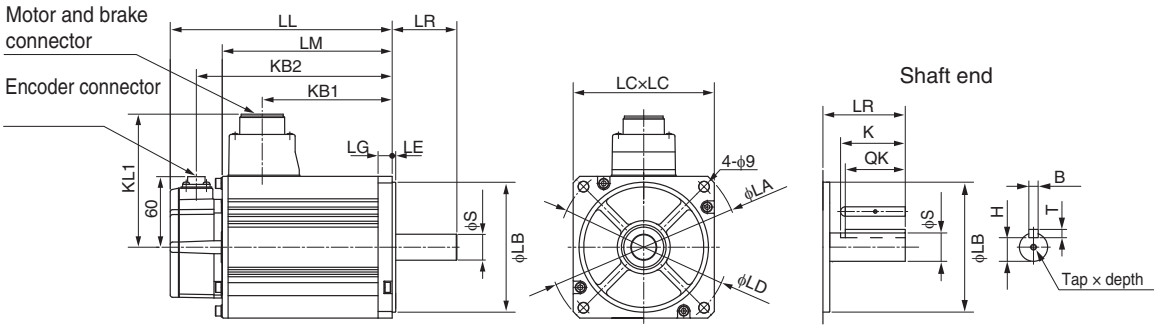
Type 3000 r/min motors (230 V, 200 to 750 W)

Dimensions (mm)	Without brake			With brake			LR	Flange surface						Shaft end dimensions							Approx. mass kg	
Model	LL	LM	KL1	LL	LM	KL1		LB	LC	LD	LE	LG	LZ	S	K	QK	H	B	T	Tap × Depth	Without brake	With brake
R88M-K20030(H/T)-□S2	79.5	56.5	52.5	116	93	52.5	30	50^{h7}	60	70	3	6.5	4.5	11^{h6}	20	18	8.5	4^{h9}	4	M4 × 8L	0.82	1.3
R88M-K40030(H/T)-□S2	99	76	52.5	135.5	112.5	52.5								14^{h6}	25	22.5	11	5^{h9}	5	M5 × 10L	1.2	1.7
R88M-K75030(H/T)-□S2	112.2	86.2	60	148.2	122.2	61.6	35	70^{h7}	80	90		8	6	19^{h6}		22	15.5	6^{h9}	6		2.3	3.1



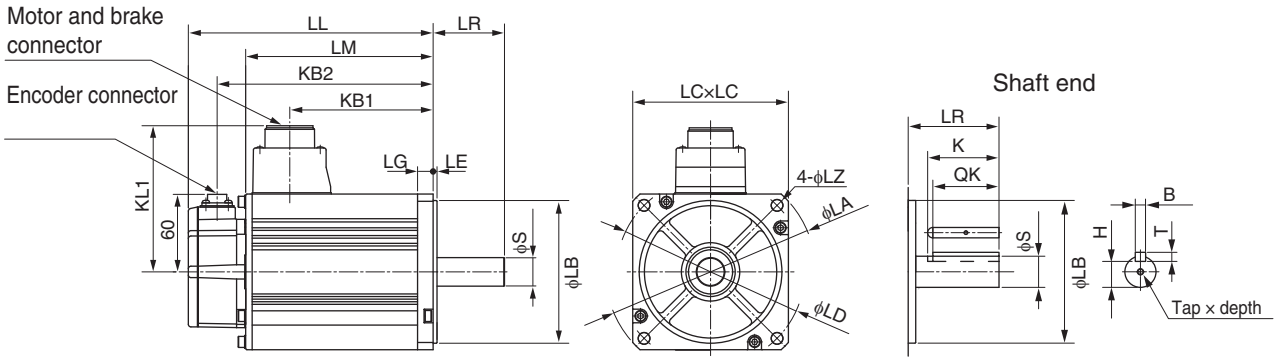
Type 3000 r/min motors (230 V, 1 to 1.5 kW/400V, 750 W to 5 kW)

Dimensions (mm)		Without brake					With brake					LR	Flange surface						Shaft end dimensions							Approx. Mass (kg)	
Voltage	Model R88M-K□	LL	LM	KB1	KB2	KL1	LL	LM	KB1	KB2	KL1		LA	LB	LC	LD	LE	LG	S	Tap × Depth	K	QK	H	B	T	Without brake	With brake
230	1K030(H/T)-□S2	141	97	66	119	101	168	124	66	146	101	55	135	95^{h7}	100	115	3	10	19^{h6}	M5 × 12L	45	42	15.5	6^{h9}	6	3.5	4.5
	1K530(H/T)-□S2	159.5	115.5	84.5	137.5		186.5	142.5	84.5	164.5																4.4	5.4
400	75030(F/C)-□S2	131.5	87.5	56.5	109.5		158.5	114.5	53.5	136.5	103															3.1	4.1
	1K030(F/C)-□S2	141	97	66	119		168	124	63	146																3.5	4.5
	1K530(F/C)-□S2	159.5	115.5	84.5	137.5		186.5	142.5	81.5	164.5																4.4	5.4
	2K030(F/C)-□S2	178.5	134.5	103.5	156.5		205.5	161.5	100.5	183.5																5.3	6.3
	3K030(F/C)-□S2	190	146	112	168	113	215	171	112	193	113		162	110^{h7}	120	145		12	22^{h6}			41	18	8^{h9}	7	8.3	9.4
	4K030(F/C)-□S2	208	164	127	186	118	233	189	127	211	118	65	165		130		6		24^{h6}	M8 × 20L	55	51	20			11	12.6
	5K030(F/C)-□S2	243	199	162	221		268	224	162	246																14	16



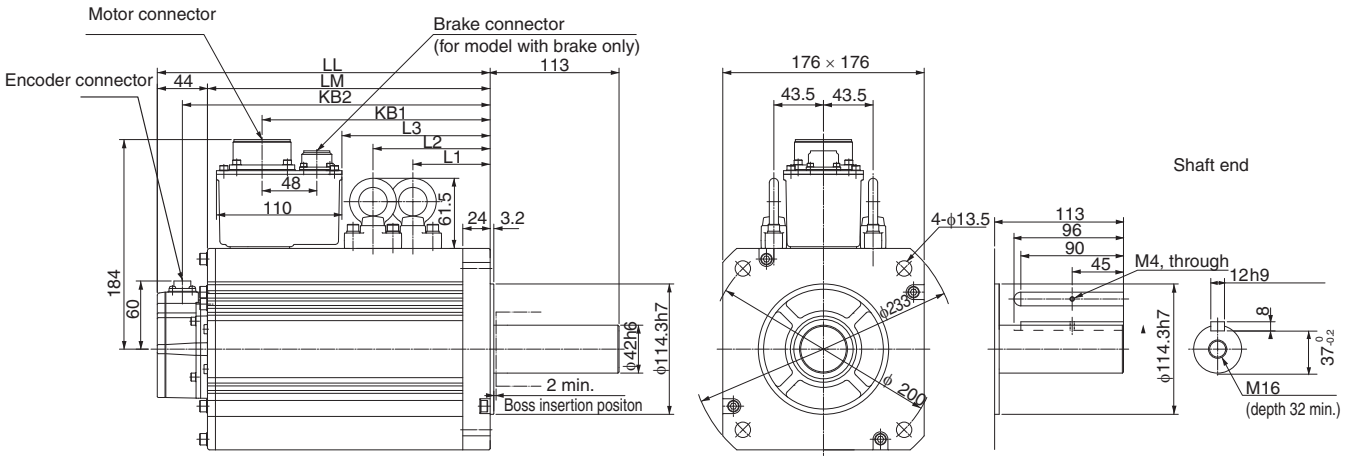
Type 2000 r/min motors (230 V, 1 to 1.5 kW /400 V, 400 W to 5 kW)

Dimensions (mm)		Without brake					With brake					LR	Flange surface							Shaft end dimensions							Approx. mass (kg)	
Voltage	Model R88M-K□	LL	LM	KB1	KB2	KL1	LL	LM	KB1	KB2	KL1		LA	LB	LC	LD	LE	LG	LZ	S	Tap × Depth	K	QK	H	B	T	Without brake	With brake
230	1K020(H/T)-□S2	138	94	60	116	116	163	119	60	141	116	55	165	110^{h7}	130	145	6	12	9	22^{h6}	M5 × 12L	45	41	18	8^{h9}	7	5.2	6.7
	1K520(H/T)-□S2	155.5	111.5	77.5	133.5		180.5	136.5	77.5	158.5																	6.7	8.2
400	40020(F/C)-□S2	131.5	87.5	56.5	109.5	101	158.5	114.5	53.5	136.5	103		135	95^{h7}	100	115	3	10		19^{h6}			42	15.5	6^{h9}	6	3.1	4.1
	60020(F/C)-□S2	141	97	66	119		168	124	63	146																	3.5	4.5
	1K020(F/C)-□S2	138	94	60	116	116	163	119	57	141	118		165	110^{h7}	130	145	6	12		22^{h6}			41	18	8^{h9}	7	5.2	6.7
	1K520(F/C)-□S2	155.5	111.5	77.5	133.5		180.5	136.5	74.5	158.5																	6.7	8.2
	2K020(F/C)-□S2	173	129	95	151		198	154	92	176																	8	9.5
	3K020(F/C)-□S2	208	164	127	186	118	233	189	127	211		65								24^{h6}	M8 × 20L	55	51	20			11	12.6
	4K020(F/C)-□S2	177	133	96	155	140	202	158	96	180	140	70	233	114.3^{h7}	176	200	3.2	18	13.5	35^{h6}	M12 × 25L		50	30	10^{h9}	8	15.5	18.7
	5K020(F/C)-□S2	196	152	115	174		221	177	115	199																	18.6	21.8



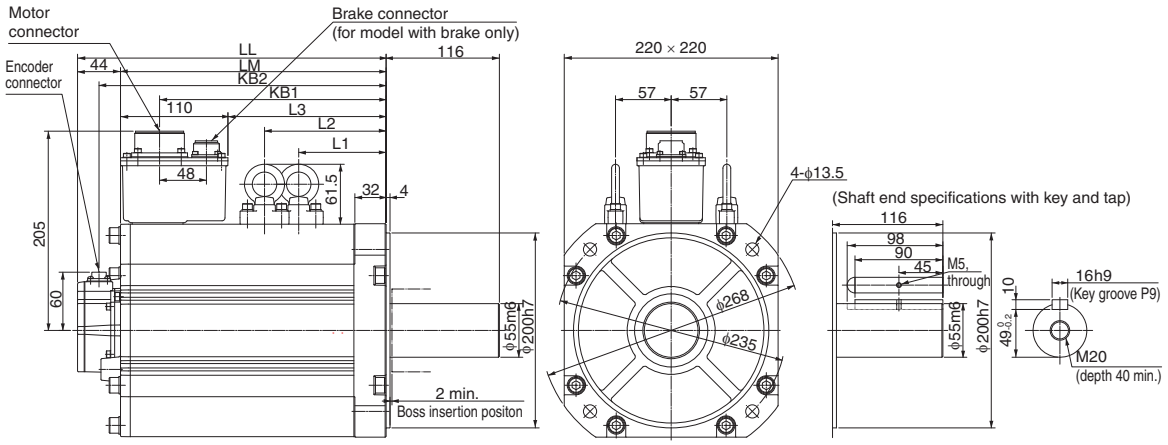
Type 1500 r/min motors (400 V, 7.5kW)

Dimensions (mm)		Without brake							With brake							Approx. mass (kg)	
Voltage	Model R88M-K□	LL	LM	KB1	KB2	L1	L2	L3	LL	LM	KB1	KB2	L1	L2	L3	Without brake	With brake
400	7K515C-□S2	312	268	219	290	117.5	117.5	149	337	293	253	315	117.5	152.5	183	36.4	40.4



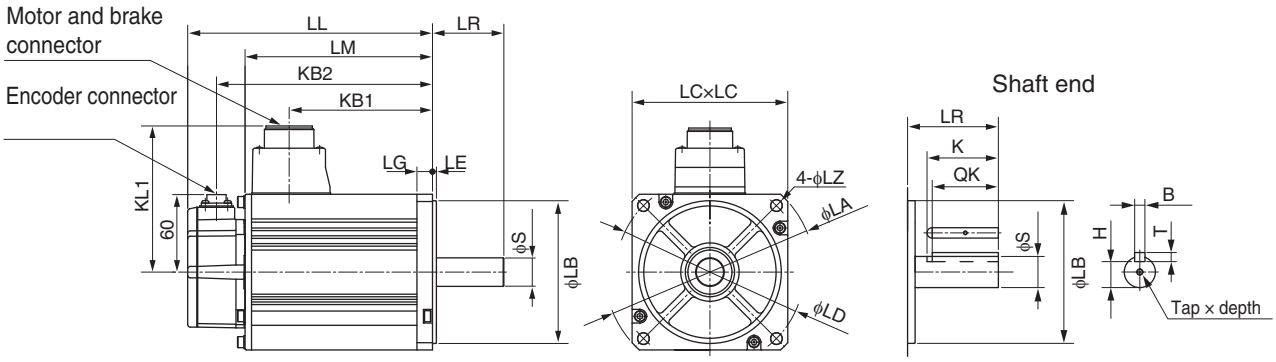
Type 1500 r/min motors (400 V, 11 to 15 kW)

Dimensions (mm)		Without brake							With brake							Approx. Mass (kg)	
Voltage	Model R88M-K□	LL	LM	KB1	KB2	L1	L2	L3	LL	LM	KB1	KB2	L1	L2	L3	Without brake	With brake
400	11K015C-□S2	316	272	232	294	124.5	124.5	162	364	320	266	342	124.5	159.5	196	52.7	58.9
	15K015C-□S2	384	340	300	362	158.5	158.5	230	432	388	334	410	158.5	193.5	264	70.2	76.3



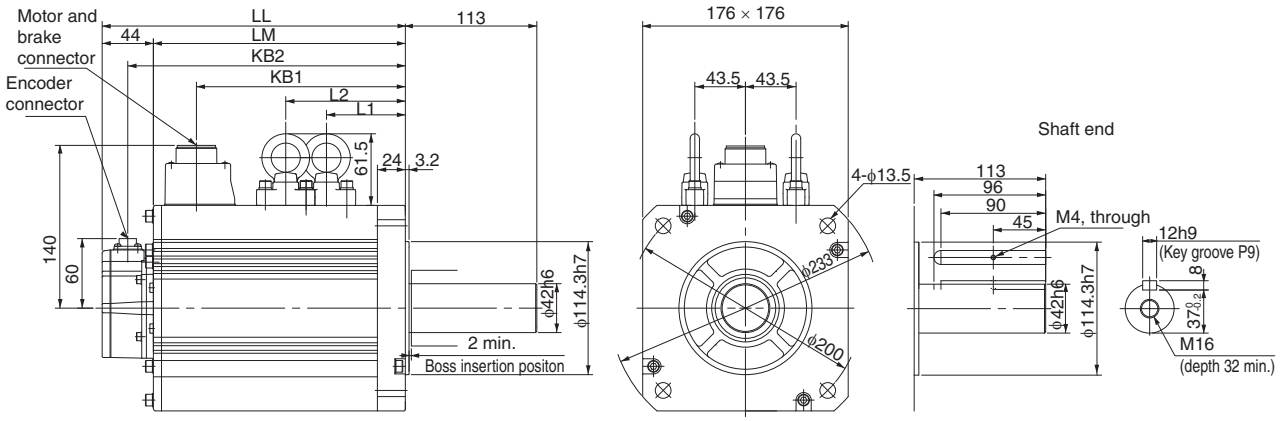
Type 1000 r/min motors (230 V, 900W/400 V, 900 W to 3 kW)

Dimensions (mm)		Without brake					With brake					LR	Flange surface							Shaft end dimensions							Approx. mass (kg)	
Voltage	Model R88M-K□	LL	LM	KB1	KB2	KL1	LL	LM	KB1	KB2	KL1		LA	LB	LC	LD	LE	LG	LZ	S	Tap × Depth	K	QK	H	B	T	Without brake	With brake
230	90010(H/T)-□S2	155.5	111.5	77.5	133.5	116	180.5	136.5	77.5	158.5	116	70	165	110^{h7}	130	145	6	12	9	22^{h6}	M5 × 12L	45	41	18	8^{h9}	7	6.7	8.2
400	90010(F/C)-□S2								74.5		118																	
	2K010(F/C)-□S2	163.5	119.5	82.5	141.5	140	188.5	144.5	82.5	166.5	140	80	233	114.3^{h7}	176	200	3.2	18	13.5	35^{h6}	M12 × 25L	55	50	30	10^{h9}	8	14	17.5
	3K010(F/C)-□S2	209.5	165.5	128.5	187.5		234.5	190.5	128.5	212.5																	20	23.5



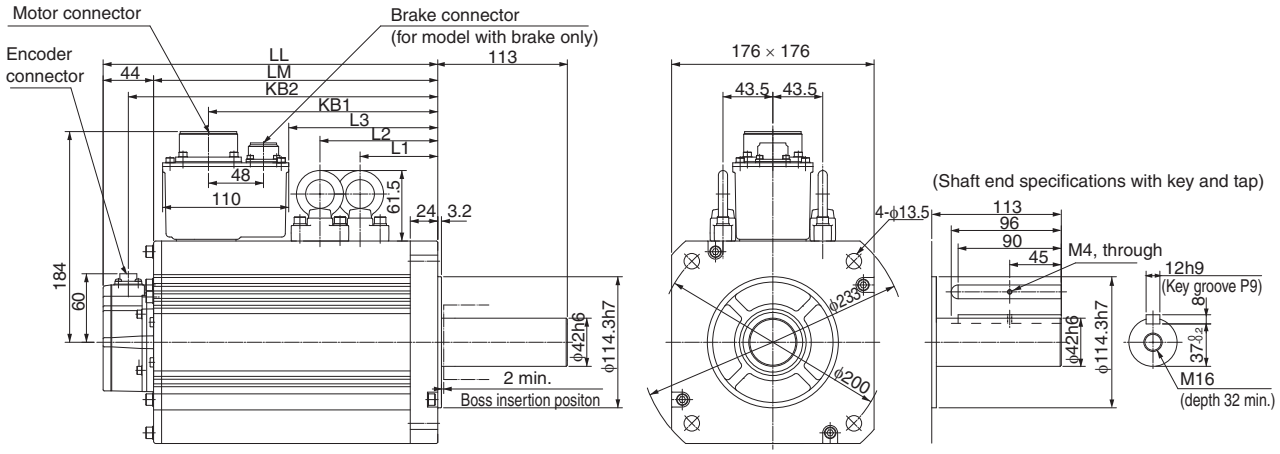
Type 1000 r/min motors (400 V, 4.5 kW)

Dimensions (mm)		Without brake						With brake						Approx. mass (kg)	
Voltage	Model R88M-K□	LL	LM	KB1	KB2	L1	L2	LL	LM	KB1	KB2	L1	L2	Without brake	With brake
400	4K510C-□S2	266	222	185	244	98	98	291	247	185	269	98	133	29.4	33.3



Type 1000 r/min motors (400 V, 6 kW)

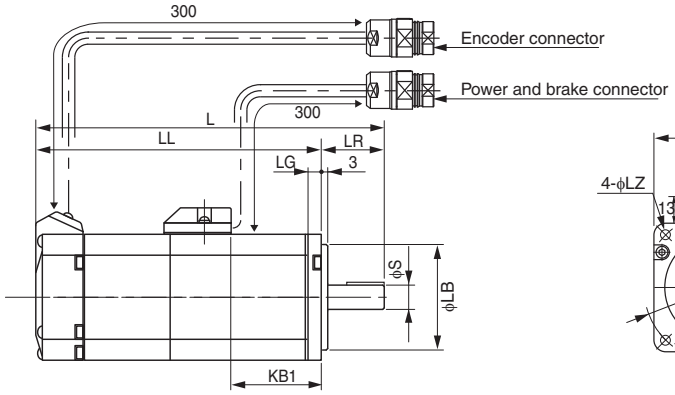
Dimensions (mm)		Without brake							With brake							Approx. mass (kg)	
Voltage	Model R88M-K□	LL	LM	KB1	KB2	L1	L2	L3	LL	LM	KB1	KB2	L1	L2	L3	Without brake	With brake
400	6K010C-□S2	312	268	219	290	117.5	117.5	149	337	293	253	315	117.5	152.5	183	36.4	40.4

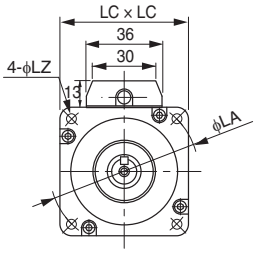


High inertia servo motors

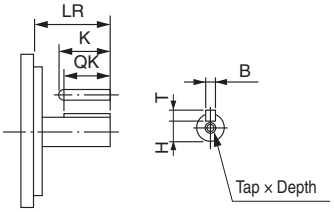
Type 3000 r/min motors (230 V, 200 W to 750 W)

Dimensions (mm)		Without brake		With brake		KB1	LR	Flange surface					Shaft end dimensions							Approx. mass (kg)	
Voltage	Model R88M-KH□	L	LL	L	LL			LA	LB	LC	LG	LZ	S	Tap x Depth	K	QK	H	B	T	Without brake	With brake
230	20030(H/T)-□S2-D	129	99	165.5	135.5	42	30	70	50^{h7}	60	6.5	4.5	11^{h6}	M4x8L	20	18	8.5	4^{h9}	4	0.96	1.4
	40030(H/T)-□S2-D	148.5	118.5	185	155	61.5							14^{h6}	M5x10L	25	22.5	11	5^{h9}	5	1.4	1.8
	75030(H/T)-□S2-D	162.2	127.2	199.2	164.2	67.2	35	90	70^{h7}	80	8	6	19^{h6}	M5x10L	25	22	15.5	6^{h9}	6	2.5	3.3





(Dimensions of shaft end with key and tap)



Encoder connector wiring

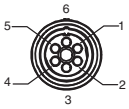
Cable length 300±30
Connector optional
Made by Hypertac
SRUC-17G-MRWN040 (MALE)

Encoder connector	
Pin No.	Signal
1	BAT - (0 V)
2	BAT +
3	S +
4	S -
5 to 7	Free
8	E5V (power supply)
9	E0V (power supply)
10 to 17	Free
Connector case	FG (Ground)

*Note: Pins 1 and 2 used only for motors with ABS encoder.

Mating connector:
Plug type: SPOC-17H-FRON169 (FEMALE)

Power and brake connector wiring



Cable length 300±30
Connector optional
Made by Hypertac
SRUC-06J-MSCN236 (MALE)

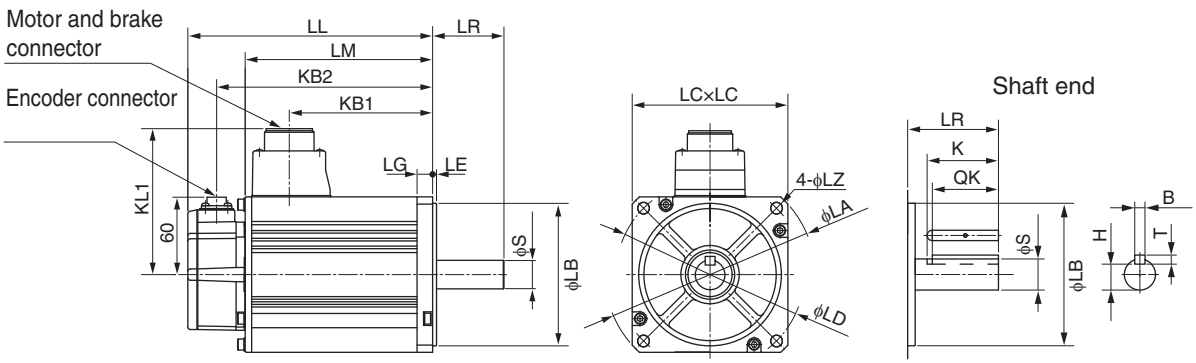
Power and brake connector	
Pin No.	Output
1	Phase U
2	Phase V
3	Phase W
4	*Brake terminal
5	*Brake terminal
6	FG (ground)

*Note: Pins 4 and 5 used only for motors with brake.

Mating connector:
Plug type: SPOC-06K-FSDN169 (FEMALE)

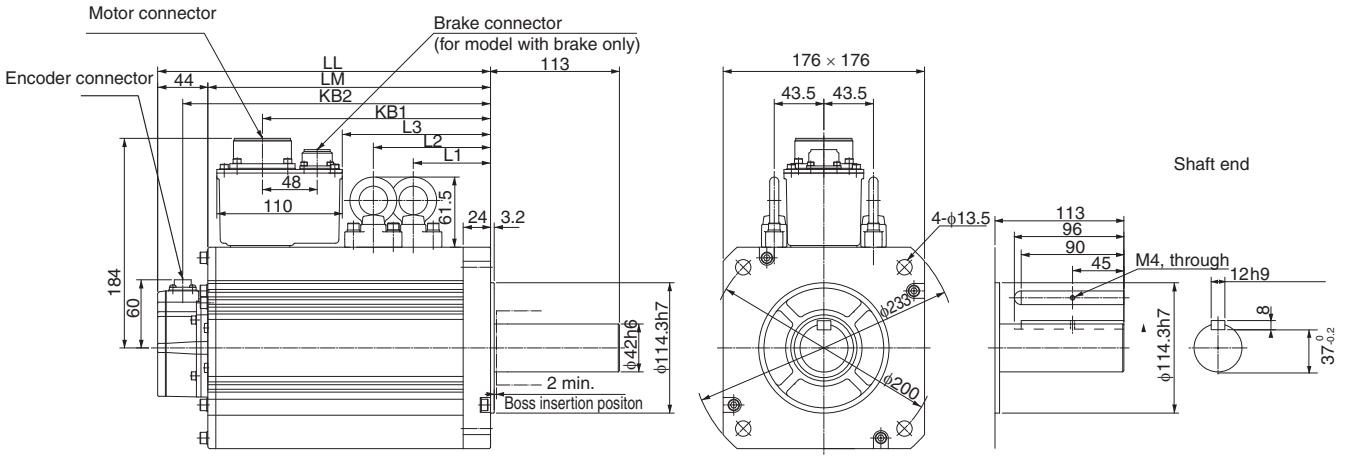
Type 2000 r/min motors (400 V, 1 kW to 5 kW)

Dimensions (mm)		Without brake					With brake					LR	Flange surface							Shaft end dimensions						Approx. mass (kg)	
Voltage	Model R88M-KH□	LL	LM	KB1	KB2	KL1	LL	LM	KB1	KB2	KL1		LA	LB	LC	LD	LE	LG	LZ	S	K	QK	H	B	T	Without brake	With brake
400	1K020(F/C)-□S1	173	129	95	151	116	201	157	92	179	118	70	165	110^{h7}	130	145	6	12	9	22^{h6}	45	41	18	8^{h9}	7	6.7	8.1
	1K520(F/C)-□S1	190.5	146.5	112.5	168.5		218.5	174.5	109.5	196.5																8.6	10.1
	2K020(F/C)-□S1	177	133	96	155	140	206	162	96	184	140	80	233	114.3^{h7}	176	200	3.2	18	13.5	35^{h6}	55	50	30	10^{h9}	8	12.2	15.5
	3K020(F/C)-□S1	196	152	115	174		225	181	115	203																16.0	19.2
	4K020(F/C)-□S1	209.5	165.5	128.5	187.5		238.5	194.5	128.5	216.5																18.6	21.8
	5K020(F/C)-□S1	238.5	194.5	157.5	216.5		267.5	223.5	157.5	245.5																23.0	26.2



Type 1500 r/min motors (400 V, 7.5 kW)

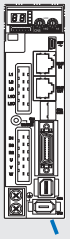
Dimensions (mm)		Without brake							With brake							Approx. mass (kg)	
Voltage	Model R88M-KH□	LL	LM	KB1	KB2	L1	L2	L3	LL	LM	KB1	KB2	L1	L2	L3	Without brake	With brake
400	7K515C-□S1	357	313	264	335	146.5	146.5	194	382	338	298	360	146.5	181.5	228	42.3	46.2



Ordering information

(Refer to servo drive chapter)

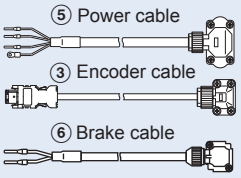
② Drive options

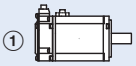


G5 rotary servo drive
EtherCAT and
Analogue/pulse models

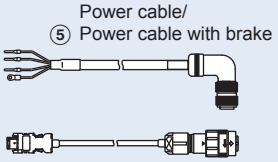
④ Extension cable for absolute encoder (with battery holder)

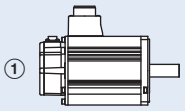
Standard servo motors



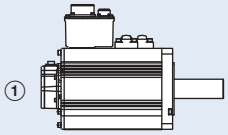


3000 rpm (50 W to 750 W)



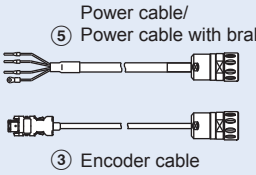


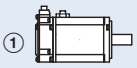
3000 rpm (750 W to 5 kW)
2000 rpm (400 W to 5 kW)
1000 rpm (900 W to 3 kW)



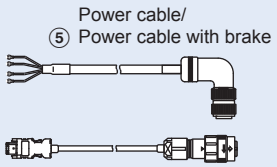
1500 rpm (7.5 kW to 15 kW)
1000 rpm (4.5 kW to 6 kW)

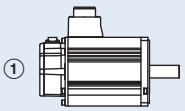
High inertia servo motors



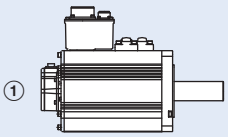


3000 rpm (200 W to 750 W)





2000 rpm (1 kW to 5 kW)



1500 rpm (7.5 kW)

Note: The symbols ①②③... show the recommended sequence to select the servo motor and cables

Servo motor

① Select motor from R88M-K or R88M-KH families using motor tables in next pages.

Servo drive

② Refer to G5 servo drive chapter for detailed drive specifications and selection of drive accessories.

Standard servo motors

Servo motors 3000 r/min (50 to 5000 W)

Symbol	Specifications					Servo motor model	Compatible servo drives ②	
	Voltage	Encoder and design		Rated torque	Capacity		G5 EtherCAT/ ML2	G5 Analog/pulse
①  230V (50 to 750 W)  230 V (1 kW to 1.5 kW) 400 V (750 W to 5 kW)	230 V	Incremental encoder (20 bit) Straight shaft with key and tap	Without brake	0.16 Nm	50 W	R88M-K05030H-S2	R88D-KN01H-□	R88D-KT01H
				0.32 Nm	100 W	R88M-K10030H-S2	R88D-KN01H-□	R88D-KT01H
				0.64 Nm	200 W	R88M-K20030H-S2	R88D-KN02H-□	R88D-KT02H
				1.3 Nm	400 W	R88M-K40030H-S2	R88D-KN04H-□	R88D-KT04H
				2.4 Nm	750 W	R88M-K75030H-S2	R88D-KN08H-□	R88D-KT08H
				3.18 Nm	1000 W	R88M-K1K030H-S2	R88D-KN15H-□	R88D-KT15H
				4.77 Nm	1500 W	R88M-K1K530H-S2	R88D-KN15H-□	R88D-KT15H
			With brake	0.16 Nm	50 W	R88M-K05030H-BS2	R88D-KN01H-□	R88D-KT01H
				0.32 Nm	100 W	R88M-K10030H-BS2	R88D-KN01H-□	R88D-KT01H
				0.64 Nm	200 W	R88M-K20030H-BS2	R88D-KN02H-□	R88D-KT02H
				1.3 Nm	400 W	R88M-K40030H-BS2	R88D-KN04H-□	R88D-KT04H
				2.4 Nm	750 W	R88M-K75030H-BS2	R88D-KN08H-□	R88D-KT08H
				3.18 Nm	1000 W	R88M-K1K030H-BS2	R88D-KN15H-□	R88D-KT15H
				4.77 Nm	1500 W	R88M-K1K530H-BS2	R88D-KN15H-□	R88D-KT15H
		Absolute encoder (17 bit) Straight shaft with key and tap	Without brake	0.16 Nm	50 W	R88M-K05030T-S2	R88D-KN01H-□	R88D-KT01H
				0.32 Nm	100 W	R88M-K10030T-S2	R88D-KN01H-□	R88D-KT01H
				0.64 Nm	200 W	R88M-K20030T-S2	R88D-KN02H-□	R88D-KT02H
				1.3 Nm	400 W	R88M-K40030T-S2	R88D-KN04H-□	R88D-KT04H
				2.4 Nm	750 W	R88M-K75030T-S2	R88D-KN08H-□	R88D-KT08H
				3.18 Nm	1000 W	R88M-K1K030T-S2	R88D-KN15H-□	R88D-KT15H
				4.77 Nm	1500 W	R88M-K1K530T-S2	R88D-KN15H-□	R88D-KT15H
			With brake	0.16 Nm	50 W	R88M-K05030T-BS2	R88D-KN01H-□	R88D-KT01H
				0.32 Nm	100 W	R88M-K10030T-BS2	R88D-KN01H-□	R88D-KT01H
				0.64 Nm	200 W	R88M-K20030T-BS2	R88D-KN02H-□	R88D-KT02H
				1.3 Nm	400 W	R88M-K40030T-BS2	R88D-KN04H-□	R88D-KT04H
				2.4 Nm	750 W	R88M-K75030T-BS2	R88D-KN08H-□	R88D-KT08H
				3.18 Nm	1000 W	R88M-K1K030T-BS2	R88D-KN15H-□	R88D-KT15H
				4.77 Nm	1500 W	R88M-K1K530T-BS2	R88D-KN15H-□	R88D-KT15H
	400 V	Incremental encoder (20 bit) Straight shaft with key and tap	Without brake	2.39 Nm	750 W	R88M-K75030F-S2	R88D-KN10F-□	R88D-KT10F
				3.18 Nm	1000 W	R88M-K1K030F-S2	R88D-KN15F-□	R88D-KT15F
				4.77 Nm	1500 W	R88M-K1K530F-S2	R88D-KN15F-□	R88D-KT15F
				6.37 Nm	2000 W	R88M-K2K030F-S2	R88D-KN20F-□	R88D-KT20F
				9.55 Nm	3000 W	R88M-K3K030F-S2	R88D-KN30F-□	R88D-KT30F
				12.7 Nm	4000 W	R88M-K4K030F-S2	R88D-KN50F-□	R88D-KT50F
				15.9 Nm	5000 W	R88M-K5K030F-S2	R88D-KN50F-□	R88D-KT50F
			With brake	2.39 Nm	750 W	R88M-K75030F-BS2	R88D-KN10F-□	R88D-KT10F
				3.18 Nm	1000 W	R88M-K1K030F-BS2	R88D-KN15F-□	R88D-KT15F
				4.77 Nm	1500 W	R88M-K1K530F-BS2	R88D-KN15F-□	R88D-KT15F
				6.37 Nm	2000 W	R88M-K2K030F-BS2	R88D-KN20F-□	R88D-KT20F
				9.55 Nm	3000 W	R88M-K3K030F-BS2	R88D-KN30F-□	R88D-KT30F
				12.7 Nm	4000 W	R88M-K4K030F-BS2	R88D-KN50F-□	R88D-KT50F
				15.9 Nm	5000 W	R88M-K5K030F-BS2	R88D-KN50F-□	R88D-KT50F
		Absolute encoder (17 bit) Straight shaft with key and tap	Without brake	2.39 Nm	750 W	R88M-K75030C-S2	R88D-KN10F-□	R88D-KT10F
				3.18 Nm	1000 W	R88M-K1K030C-S2	R88D-KN15F-□	R88D-KT15F
				4.77 Nm	1500 W	R88M-K1K530C-S2	R88D-KN15F-□	R88D-KT15F
				6.37 Nm	2000 W	R88M-K2K030C-S2	R88D-KN20F-□	R88D-KT20F
				9.55 Nm	3000 W	R88M-K3K030C-S2	R88D-KN30F-□	R88D-KT30F
				12.7 Nm	4000 W	R88M-K4K030C-S2	R88D-KN50F-□	R88D-KT50F
				15.9 Nm	5000 W	R88M-K5K030C-S2	R88D-KN50F-□	R88D-KT50F
			With brake	2.39 Nm	750 W	R88M-K75030C-BS2	R88D-KN10F-□	R88D-KT10F
				3.18 Nm	1000 W	R88M-K1K030C-BS2	R88D-KN15F-□	R88D-KT15F
				4.77 Nm	1500 W	R88M-K1K530C-BS2	R88D-KN15F-□	R88D-KT15F
				6.37 Nm	2000 W	R88M-K2K030C-BS2	R88D-KN20F-□	R88D-KT20F
				9.55 Nm	3000 W	R88M-K3K030C-BS2	R88D-KN30F-□	R88D-KT30F
				12.7 Nm	4000 W	R88M-K4K030C-BS2	R88D-KN50F-□	R88D-KT50F
				15.9 Nm	5000 W	R88M-K5K030C-BS2	R88D-KN50F-□	R88D-KT50F

Servo motors 2000 r/min (1 to 5 kW)

Symbol	Specifications					Servo motor model	Compatible servo drives ②	
	Voltage	Encoder and design		Rated torque	Capacity		G5 EtherCAT/ ML2	G5 Analog/pulse
① 	230 V	**Incremental encoder (20 bit)** Straight shaft with key and tap	Without brake	4.77 Nm	1000 W	R88M-K1K020H-S2	R88D-KN10H-□	R88D-KT10H
				7.16 Nm	1500 W	R88M-K1K520H-S2	R88D-KN15H-□	R88D-KT15H
			With brake	4.77 Nm	1000 W	R88M-K1K020H-BS2	R88D-KN10H-□	R88D-KT10H
				7.16 Nm	1500 W	R88M-K1K520H-BS2	R88D-KN15H-□	R88D-KT15H
		Absolute encoder (17 bit) Straight shaft with key and tap	Without brake	4.77 Nm	1000 W	R88M-K1K020T-S2	R88D-KN10H-□	R88D-KT10H
				7.16 Nm	1500 W	R88M-K1K520T-S2	R88D-KN15H-□	R88D-KT15H
			With brake	4.77 Nm	1000 W	R88M-K1K020T-BS2	R88D-KN10H-□	R88D-KT10H
				7.16 Nm	1500 W	R88M-K1K520T-BS2	R88D-KN15H-□	R88D-KT15H
	400 V	**Incremental encoder (20 bit)** Straight shaft with key and tap	Without brake	1.91 Nm	400 W	R88M-K40020F-S2	R88D-KN06F-□	R88D-KT06F
				2.86 Nm	600 W	R88M-K60020F-S2	R88D-KN06F-□	R88D-KT06F
				4.77 Nm	1000 W	R88M-K1K020F-S2	R88D-KN10F-□	R88D-KT10F
				7.16 Nm	1500 W	R88M-K1K520F-S2	R88D-KN15F-□	R88D-KT15F
				9.55 Nm	2000 W	R88M-K2K020F-S2	R88D-KN20F-□	R88D-KT20F
				14.3 Nm	3000 W	R88M-K3K020F-S2	R88D-KN30F-□	R88D-KT30F
				19.1 Nm	4000 W	R88M-K4K020F-S2	R88D-KN50F-□	R88D-KT50F
				23.9 Nm	5000 W	R88M-K5K020F-S2	R88D-KN50F-□	R88D-KT50F
			With brake	1.91 Nm	400 W	R88M-K40020F-BS2	R88D-KN06F-□	R88D-KT06F
				2.86 Nm	600 W	R88M-K60020F-BS2	R88D-KN06F-□	R88D-KT06F
				4.77 Nm	1000 W	R88M-K1K020F-BS2	R88D-KN10F-□	R88D-KT10F
				7.16 Nm	1500 W	R88M-K1K520F-BS2	R88D-KN15F-□	R88D-KT15F
				9.55 Nm	2000 W	R88M-K2K020F-BS2	R88D-KN20F-□	R88D-KT20F
				14.3 Nm	3000 W	R88M-K3K020F-BS2	R88D-KN30F-□	R88D-KT30F
				19.1 Nm	4000 W	R88M-K4K020F-BS2	R88D-KN50F-□	R88D-KT50F
				23.9 Nm	5000 W	R88M-K5K020F-BS2	R88D-KN50F-□	R88D-KT50F
		Absolute encoder (17 bit) Straight shaft with key and tap	Without brake	1.91 Nm	400 W	R88M-K40020C-S2	R88D-KN06F-□	R88D-KT06F
				2.86 Nm	600 W	R88M-K60020C-S2	R88D-KN06F-□	R88D-KT06F
				4.77 Nm	1000 W	R88M-K1K020C-S2	R88D-KN10F-□	R88D-KT10F
				7.16 Nm	1500 W	R88M-K1K520C-S2	R88D-KN15F-□	R88D-KT15F
				9.55 Nm	2000 W	R88M-K2K020C-S2	R88D-KN20F-□	R88D-KT20F
				14.3 Nm	3000 W	R88M-K3K020C-S2	R88D-KN30F-□	R88D-KT30F
				19.1 Nm	4000 W	R88M-K4K020C-S2	R88D-KN50F-□	R88D-KT50F
				23.9 Nm	5000 W	R88M-K5K020C-S2	R88D-KN50F-□	R88D-KT50F
			With brake	1.91 Nm	400 W	R88M-K40020C-BS2	R88D-KN06F-□	R88D-KT06F
				2.86 Nm	600 W	R88M-K60020C-BS2	R88D-KN06F-□	R88D-KT06F
				4.77 Nm	1000 W	R88M-K1K020C-BS2	R88D-KN10F-□	R88D-KT10F
				7.16 Nm	1500 W	R88M-K1K520C-BS2	R88D-KN15F-□	R88D-KT15F
				9.55 Nm	2000 W	R88M-K2K020C-BS2	R88D-KN20F-□	R88D-KT20F
				14.3 Nm	3000 W	R88M-K3K020C-BS2	R88D-KN30F-□	R88D-KT30F
				19.1 Nm	4000 W	R88M-K4K020C-BS2	R88D-KN50F-□	R88D-KT50F
				23.9 Nm	5000 W	R88M-K5K020C-BS2	R88D-KN50F-□	R88D-KT50F

Servo motors 1500 r/min (7.5 to 15 KW)

Symbol	Specifications					Servo motor model	Compatible servo drives ②	
	Voltage	Encoder and design		Rated torque	Capacity		G5 EtherCAT	G5 Analog/pulse
① 	400 V	**Absolute encoder (17 bit)** Straight shaft with key and tap	Without brake	47.8 Nm	7500 W	R88M-K7K515C-S2	R88D-KN75F-ECT	R88D-KT75F
				70.0 Nm	11000 W	R88M-K11K015C-S2	R88D-KN150F-ECT	R88D-KT150F
				95.5 Nm	15000 W	R88M-K15K015C-S2	R88D-KN150F-ECT	R88D-KT150F
			With brake	47.8 Nm	7500 W	R88M-K7K515C-BS2	R88D-KN75F-ECT	R88D-KT75F
				70.0 Nm	11000 W	R88M-K11K015C-BS2	R88D-KN150F-ECT	R88D-KT150F
				95.5 Nm	15000 W	R88M-K15K015C-BS2	R88D-KN150F-ECT	R88D-KT150F

Servo motors 1000 r/min (900 to 6000 W)

Symbol	Specifications					Servo motor model	Compatible servo drives ②	
	Voltage	Encoder and design		Rated torque	Capacity		G5 EtherCAT/ML2	G5 Analog/pulse
①  900 W - 3 kW  4.5 kW - 6 kW	230 V	**Incremental encoder (20 bit)** Straight shaft with key and tap	No brake	8.59 Nm	900 W	R88M-K90010H-S2	R88D-KN15H-□	R88D-KT15H
			With brake	8.59 Nm	900 W	R88M-K90010H-BS2	R88D-KN15H-□	R88D-KT15H
		Absolute encoder (17 bit) Straight shaft with key and tap	No brake	8.59 Nm	900 W	R88M-K90010T-S2	R88D-KN15H-□	R88D-KT15H
			With brake	8.59 Nm	900 W	R88M-K90010T-BS2	R88D-KN15H-□	R88D-KT15H
	400 V	**Incremental encoder (20 bit)** Straight shaft with key and tap	No brake	8.59 Nm	900 W	R88M-K90010F-S2	R88D-KN15F-□	R88D-KT15F
				19.1 Nm	2000 W	R88M-K2K010F-S2	R88D-KN30F-□	R88D-KT30F
				28.7 Nm	3000 W	R88M-K3K010F-S2	R88D-KN50F-□	R88D-KT50F
			With brake	8.59 Nm	900 W	R88M-K90010F-BS2	R88D-KN15F-□	R88D-KT15F
				19.1 Nm	2000 W	R88M-K2K010F-BS2	R88D-KN30F-□	R88D-KT30F
				28.7 Nm	3000 W	R88M-K3K010F-BS2	R88D-KN50F-□	R88D-KT50F
		Absolute encoder (17 bit) Straight shaft with key and tap	No brake	8.59 Nm	900 W	R88M-K90010C-S2	R88D-KN15F-□	R88D-KT15F
				19.1 Nm	2000 W	R88M-K2K010C-S2	R88D-KN30F-□	R88D-KT30F
				28.7 Nm	3000 W	R88M-K3K010C-S2	R88D-KN50F-□	R88D-KT50F
				43.0 Nm	4500 W	R88M-K4K510C-S2	R88D-KN50F-□	R88D-KT50F
				57.3 Nm	6000 W	R88M-K6K010C-S2	R88D-KN75F-ECT	R88D-KT75F
			With brake	8.59 Nm	900 W	R88M-K90010C-BS2	R88D-KN15F-□	R88D-KT15F
				19.1 Nm	2000 W	R88M-K2K010C-S2	R88D-KN30F-□	R88D-KT30F
				28.7 Nm	3000 W	R88M-K3K010C-S2	R88D-KN50F-□	R88D-KT50F
				43.0 Nm	4500 W	R88M-K4K510C-BS2	R88D-KN50F-□	R88D-KT50F
				57.3 Nm	6000 W	R88M-K6K010C-BS2	R88D-KN75F-ECT	R88D-KT75F

High inertia servo motors

Servo motors 3000 r/min (200 to 750 W)

Symbol	Specifications					Servo motor model	Compatible servo drives ②	
	Voltage	Encoder and design		Rated torque	Capacity		G5 EtherCAT/ ML2	G5 Analog/pulse
① 	230 V	**Incremental encoder (20 bit)** Straight shaft with key and tap	Without brake	0.64 Nm	200 W	R88M-KH20030H-S2-D	R88D-KN02H-□	R88D-KT02H
				1.3 Nm	400 W	R88M-KH40030H-S2-D	R88D-KN04H-□	R88D-KT04H
				2.4 Nm	750 W	R88M-KH75030H-S2-D	R88D-KN08H-□	R88D-KT08H
			With brake	0.64 Nm	200 W	R88M-KH20030H-BS2-D	R88D-KN02H-□	R88D-KT02H
				1.3 Nm	400 W	R88M-KH40030H-BS2-D	R88D-KN04H-□	R88D-KT04H
				2.4 Nm	750 W	R88M-KH75030H-BS2-D	R88D-KN08H-□	R88D-KT08H
		Absolute encoder (17 bit) Straight shaft with key and tap	Without brake	0.64 Nm	200 W	R88M-KH20030T-S2-D	R88D-KN02H-□	R88D-KT02H
				1.3 Nm	400 W	R88M-KH40030T-S2-D	R88D-KN04H-□	R88D-KT04H
				2.4 Nm	750 W	R88M-KH75030T-S2-D	R88D-KN08H-□	R88D-KT08H
			With brake	0.64 Nm	200 W	R88M-KH20030T-BS2-D	R88D-KN02H-□	R88D-KT02H
				1.3 Nm	400 W	R88M-KH40030T-BS2-D	R88D-KN04H-□	R88D-KT04H
				2.4 Nm	750 W	R88M-KH75030T-BS2-D	R88D-KN08H-□	R88D-KT08H

Servo motors 2000 r/min (1 to 5 kW)

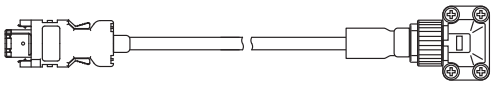
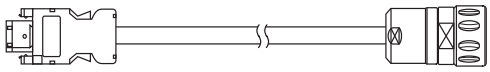
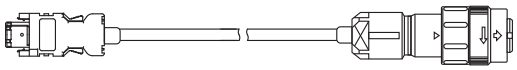
Symbol	Specifications					Servo motor model	Compatible servo drives ②	
	Voltage	Encoder and design		Rated torque	Capacity		G5 EtherCAT/ML2	G5 Analog/pulse
① 	400 V	**Incremental encoder (20 bit)** Shaft end with key	Without brake	4.77 Nm	1000 W	R88M-KH1K020F-S1	R88D-KN10F-□	R88D-KT10F
				7.16 Nm	1500 W	R88M-KH1K520F-S1	R88D-KN15F-□	R88D-KT15F
				9.55 Nm	2000 W	R88M-KH2K020F-S1	R88D-KN20F-□	R88D-KT20F
				14.3 Nm	3000 W	R88M-KH3K020F-S1	R88D-KN30F-□	R88D-KT30F
				19.1 Nm	4000 W	R88M-KH4K020F-S1	R88D-KN50F-□	R88D-KT50F
				23.9 Nm	5000 W	R88M-KH5K020F-S1	R88D-KN50F-□	R88D-KT50F
			With brake	4.77 Nm	1000 W	R88M-KH1K020F-BS1	R88D-KN10F-□	R88D-KT10F
				7.16 Nm	1500 W	R88M-KH1K520F-BS1	R88D-KN15F-□	R88D-KT15F
				9.55 Nm	2000 W	R88M-KH2K020F-BS1	R88D-KN20F-□	R88D-KT20F
				14.3 Nm	3000 W	R88M-KH3K020F-BS1	R88D-KN30F-□	R88D-KT30F
				19.1 Nm	4000 W	R88M-KH4K020F-BS1	R88D-KN50F-□	R88D-KT50F
				23.9 Nm	5000 W	R88M-KH5K020F-BS1	R88D-KN50F-□	R88D-KT50F
		Absolute encoder (17 bit) Shaft end with key	Without brake	4.77 Nm	1000 W	R88M-KH1K020C-S1	R88D-KN10F-□	R88D-KT10F
				7.16 Nm	1500 W	R88M-KH1K520C-S1	R88D-KN15F-□	R88D-KT15F
				9.55 Nm	2000 W	R88M-KH2K020C-S1	R88D-KN20F-□	R88D-KT20F
				14.3 Nm	3000 W	R88M-KH3K020C-S1	R88D-KN30F-□	R88D-KT30F
				19.1 Nm	4000 W	R88M-KH4K020C-S1	R88D-KN50F-□	R88D-KT50F
				23.9 Nm	5000 W	R88M-KH5K020C-S1	R88D-KN50F-□	R88D-KT50F
			With brake	4.77 Nm	1000 W	R88M-KH1K020C-BS1	R88D-KN10F-□	R88D-KT10F
				7.16 Nm	1500 W	R88M-KH1K520C-BS1	R88D-KN15F-□	R88D-KT15F
				9.55 Nm	2000 W	R88M-KH2K020C-BS1	R88D-KN20F-□	R88D-KT20F
				14.3 Nm	3000 W	R88M-KH3K020C-BS1	R88D-KN30F-□	R88D-KT30F
				19.1 Nm	4000 W	R88M-KH4K020C-BS1	R88D-KN50F-□	R88D-KT50F
				23.9 Nm	5000 W	R88M-KH5K020C-BS1	R88D-KN50F-□	R88D-KT50F

Servo motors 1500 r/min (7.5 kW)

Symbol	Specifications					Servo motor model	Compatible servo drives ②	
	Voltage	Encoder and design		Rated torque	Capacity		G5 EtherCAT	G5 Analog/pulse
① 	400 V	**Absolute encoder (17 bit)** Shaft end with key	Without brake	47.8 Nm	7500 W	R88M-KH7K515C-S1	R88D-KN75F-ECT	R88D-KT75F
			With brake	47.8 Nm	7500 W	R88M-KH7K515C-BS1	R88D-KN75F-ECT	R88D-KT75F

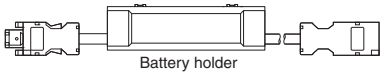
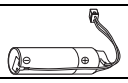
Encoder cables

For absolute and incremental encoders

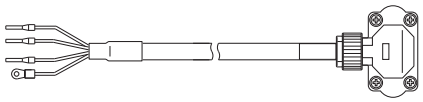
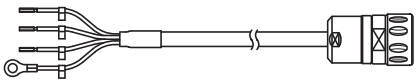
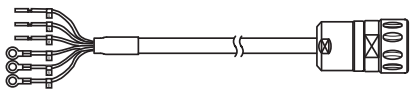
Symbol	Specifications		Model	Appearance
③	Encoder cable for servomotors R88M-K(050/100/200/400/750)30(H/T)□	1.5 m	R88A-CRKA001-5CR-E	
		3 m	R88A-CRKA003CR-E	
		5 m	R88A-CRKA005CR-E	
		10 m	R88A-CRKA010CR-E	
		15 m	R88A-CRKA015CR-E	
		20 m	R88A-CRKA020CR-E	
	Encoder cable for servomotors R88M-KH(200/400/750)30(H/T)□	3 m	R88A-CRWA003C-DE	
		5 m	R88A-CRWA005C-DE	
		10 m	R88A-CRWA010C-DE	
		15 m	R88A-CRWA015C-DE	
		20 m	R88A-CRWA020C-DE	
	Encoder cable for servomotors R88M-K(1K0/1K5)30(H/T)□ R88M-K(750/1K0/1K5/2K0/3K0/4K0/5K0)30(F/C)□ R88M-K(400/600/1K0/1K5/2K0/3K0/4K0/5K0)20□ R88M-K(7K5/11K0/15K0)15□ R88M-K(900/2K0/3K0/4K5/6K0)10□ R88M-KH(1K0/1K5/2K0/3K0/4K0/5K0)20(F/C)□ R88M-KH7K515C□	1.5 m	R88A-CRKC001-5NR-E	
		3 m	R88A-CRKC003NR-E	
		5 m	R88A-CRKC005NR-E	
		10 m	R88A-CRKC010NR-E	
		15 m	R88A-CRKC015NR-E	
		20 m	R88A-CRKC020NR-E	

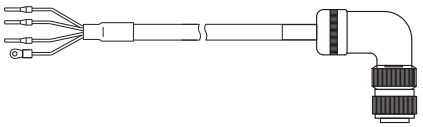
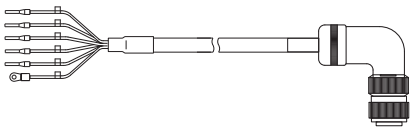
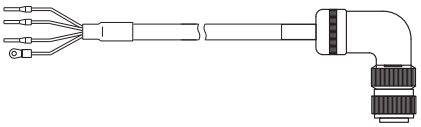
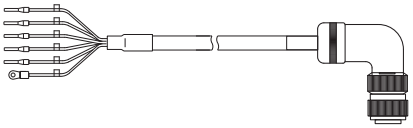
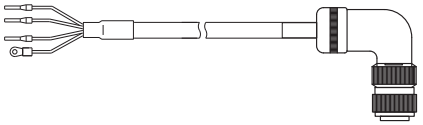
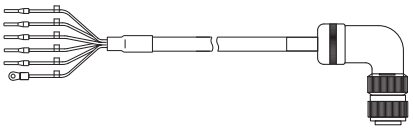
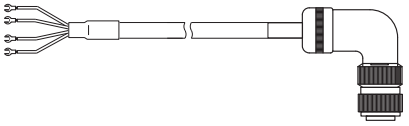
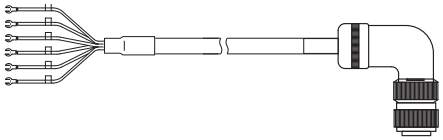
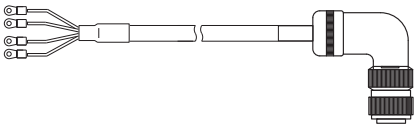
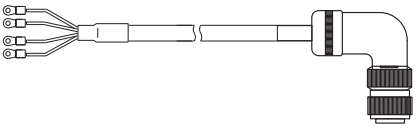
Note: For servomotors fitted with an absolute encoder you have to add the extension battery cable R88A-CRGD0R3C□ (see below) or connect a backup battery in the CN1 I/O connector.

Absolute encoder battery cable (encoder extension cable only)

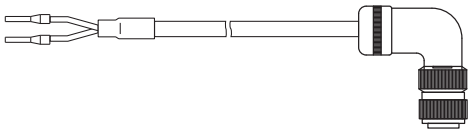
Symbol	Specifications			Model	Appearance
④	Absolute encoder battery cable	Battery not included	0.3 m	R88A-CRGD0R3C-E	 Battery holder
		Battery included	0.3 m	R88A-CRGD0R3C-BS-E	
	Absolute encoder backup battery	2,000 mA.h 3.6V	-	R88A-BAT01G	

Power cables

Symbol	Specifications			Model	Appearance
⑤	For 200 V servomotors R88M-K(050/100/200/400/750)30(H/T)-□□S2 **Note:** for servomotors with brake R88M-K(050/100/200/400/750)30(H/T)-BS2, the separate brake cable R88A-CAKA□□□BR-E is needed	Power cable only (without brake)	1.5 m	R88A-CAKA001-5SR-E	
			3 m	R88A-CAKA003SR-E	
			5 m	R88A-CAKA005SR-E	
			10 m	R88A-CAKA010SR-E	
			15 m	R88A-CAKA015SR-E	
			20 m	R88A-CAKA020SR-E	
	For 200 V servomotors R88M-KH(200/400/750)30(H/T)-□□S2	without brake	3 m	R88A-CAWA003S-DE	
			5 m	R88A-CAWA005S-DE	
			10 m	R88A-CAWA010S-DE	
			15 m	R88A-CAWA015S-DE	
			20 m	R88A-CAWA020S-DE	
		with brake	3 m	R88A-CAWA003B-DE	
			5 m	R88A-CAWA005B-DE	
			10 m	R88A-CAWA010B-DE	
			15 m	R88A-CAWA015B-DE	
			20 m	R88A-CAWA020B-DE	

Symbol	Specifications			Model	Appearance
⑤	For 200 V servomotors R88M-K(1K0/1K5)30(H/T)-□□S2 R88M-K(1K0/1K5)20(H/T)-□□S2 R88M-K90010(H/T)-□□S2	without brake	1.5 m	R88A-CAGB001-5SR-E	
			3 m	R88A-CAGB003SR-E	
			5 m	R88A-CAGB005SR-E	
			10 m	R88A-CAGB010SR-E	
			15 m	R88A-CAGB015SR-E	
			20 m	R88A-CAGB020SR-E	
		with brake	1.5 m	R88A-CAGB001-5BR-E	
			3 m	R88A-CAGB003BR-E	
			5 m	R88A-CAGB005BR-E	
			10 m	R88A-CAGB010BR-E	
			15 m	R88A-CAGB015BR-E	
			20 m	R88A-CAGB020BR-E	
	For 400 V servomotors R88M-K(750/1K0/1K5/2K0)30(F/C)-□□S2 R88M-K(400/600/1K0/1K5/2K0)20(F/C)-□□S2 R88M-K90010(F/C)-□□S2 R88M-KH(1K0/1K5)20(F/C)-□S1	without brake	1.5 m	R88A-CAGB001-5SR-E	
			3 m	R88A-CAGB003SR-E	
			5 m	R88A-CAGB05SR-E	
			10 m	R88A-CAGB010SR-E	
			15 m	R88A-CAGB015SR-E	
			20 m	R88A-CAGB020SR-E	
		with brake	1.5 m	R88A-CAKF001-5BR-E	
			3 m	R88A-CAKF003BR-E	
			5 m	R88A-CAKF005BR-E	
			10 m	R88A-CAKF010BR-E	
			15 m	R88A-CAKF015BR-E	
			20 m	R88A-CAKF020BR-E	
	For 400 V servomotors R88M-KH2K020(F/C)-□S1	without brake	1.5 m	R88A-CAKC001-5SR-E	
			3 m	R88A-CAKC003SR-E	
			5 m	R88A-CAKC005SR-E	
			10 m	R88A-CAKC010SR-E	
			15 m	R88A-CAKC015SR-E	
			20 m	R88A-CAKC020SR-E	
		with brake	1.5 m	R88A-CAKF001-5BR-E	
			3 m	R88A-CAKF003BR-E	
			5 m	R88A-CAKF005BR-E	
			10 m	R88A-CAKF010BR-E	
			15 m	R88A-CAKF015BR-E	
			20 m	R88A-CAKF020BR-E	
	For 400 V servomotors R88M-K(3K0/4K0/5K0)30(F/C)-□□S2 R88M-K(3K0/4K0/5K0)20(F/C)-□□S2 R88M-K(2K0/3K0)10(F/C)-□□S2 R88M-K4K510C-□□S2 R88M-KH(3K0/4K0/5K0)20(F/C)-□S1	without brake	1.5 m	R88A-CAGD001-5SR-E	
			3 m	R88A-CAGD003SR-E	
			5 m	R88A-CAGD005SR-E	
			10 m	R88A-CAGD010SR-E	
			15 m	R88A-CAGD015SR-E	
			20 m	R88A-CAGD020SR-E	
		with brake	1.5 m	R88A-CAGD001-5BR-E	
			3 m	R88A-CAGD003BR-E	
			5 m	R88A-CAGD005BR-E	
			10 m	R88A-CAGD010BR-E	
			15 m	R88A-CAGD015BR-E	
			20 m	R88A-CAGD020BR-E	
	For 400 V servomotors R88M-K6K010C-□□S2 R88M-K7K515C-□□S2 R88M-KH7K515C-□S1 **Note:** for servomotors with brake R88M- K(6K010/7K515)C-BS2 and R88M-KH7K515C-BS1 the separate brake cable R88A-CAGE□□□BR-E is needed	Power cable only (without brake)	1.5 m	R88A-CAKE001-5SR-E	
			3 m	R88A-CAKE003SR-E	
			5 m	R88A-CAKE005SR-E	
			10 m	R88A-CAKE010SR-E	
			15 m	R88A-CAKE015SR-E	
			20 m	R88A-CAKE020SR-E	
	For 400 V servomotors R88M-K(11K0/15K0)15C-□□S2 **Note:** for servomotors with brake R88M-K(11K0/15K0)15C-BS2, the separate brake cable R88A-CAGE□□□BR-E is needed	Power cable only (without brake)	1.5 m	R88A-CAKG001-5SR-E	
			3 m	R88A-CAKG003SR-E	
			5 m	R88A-CAKG005SR-E	
			10 m	R88A-CAKG010SR-E	
			15 m	R88A-CAKG015SR-E	
			20 m	R88A-CAKG020SR-E	

Brake cables (for 200 V 50 to 750 W servo motors and 400 V 6 to 15 kW servo motors)

Symbol	Specifications		Model	Appearance
⑥	Brake cable only. For 200 V servo motors with brake R88M-K(050/100/200/400/750)30(H/T)-BS2	1.5 m	R88A-CAKA001-5BR-E	
		3 m	R88A-CAKA003BR-E	
		5 m	R88A-CAKA005BR-E	
		10 m	R88A-CAKA010BR-E	
		15 m	R88A-CAKA015BR-E	
		20 m	R88A-CAKA020BR-E	
	Brake cable only. For 400 V servo motors with brake R88M-K6K010C-BS2 R88M-K(7K5/11K0/15K0)15C-BS2 R88M-KH7K515C-BS1	1.5 m	R88A-CAGE001-5BR-E	
		3 m	R88A-CAGE003BR-E	
		5 m	R88A-CAGE005BR-E	
		10 m	R88A-CAGE0010BR-E	
		15 m	R88A-CAGE015BR-E	
		20 m	R88A-CAGE020BR-E	

Connectors for encoder, power and brake cables

Specifications		Applicable Servomotor	Model
Connectors for making encoder cables	Drive side (CN2)	All models	R88A-CNW01R
	Motor side	R88M-K(050/100/200/400/750)30(H/T)□	R88A-CNK02R
	Motor side	R88M-KH(200/400/750)□	SPOC-17H-FRON169
	Motor side	R88M-K(1K0/1K5)30(H/T)□ R88M-K(750/1K0/1K5/2K0/3K0/4K0/5K0)30(F/C)□ R88M-K(400/600/1K0/1K5/2K0/3K0/4K0/5K0)20□ R88M-K(900/2K0/3K0)10□ R88M-K(4K5/6K0)10C-□ R88M-K(7K5/11K0/15K0)15C-□ R88M-KH(1K0/1K5/2K0/3K0/4K0/5K0/7K5)□	R88A-CNK04R
Connectors for making power cables	Motor side	R88M-K(050/100/200/400/750)30(H/T)□	R88A-CNK11A
	Motor side	R88M-KH(200/400/750)30(H/T)□	SPOC-06K-FSDN169
	Motor side	R88M-K(1K0/1K5)30(H/T)-S2 R88M-K(1K0/1K5)20(H/T)-S2 R88M-K90010(H/T)-S2 R88M-K(750/1K0/1K5/2K0)30(F/C)-S2, R88M-K(400/600/1K0/1K5/2K0)20(F/C)-S2 R88M-K90010(F/C)-S2 R88M-KH(1K0/1K5)20(F/C)-S1	MS3108E20-4S
	Motor side	R88M-K(1K0/1K5)30(H/T)-BS2 R88M-K(1K0/1K5)20(H/T)-BS2 R88M-K90010(H/T)-BS2	MS3108E20-18S
	Motor side	R88M-K(750/1K0/1K5/2K0/3K0/4K0/5K0)30(F/C)-BS2 R88M-K(400/600/1K0/1K5/2K0/3K0/4K0/5K0)20(F/C)-BS2 R88M-K(900/2K0/3K0)10(F/C)-BS2 R88M-K4K510C-BS2 R88M-KH(1K0/1K5/2K0/3K0/4K0/5K0)20(F/C)-BS1	MS3108E24-11S
	Motor side	R88M-K(3K0/4K0/5K0)30(F/C)-S2 R88M-K(3K0/4K0/5K0)20(F/C)-S2 R88M-K(2K0/3K0)10(F/C)-S2 R88M-K4K510C-S2 R88M-KH(2K0/3K0/4K0/5K0)20(F/C)-S1	MS3108E22-22S
	Motor side	R88M-K6K010C-□ R88M-K(7K5/11K0/15K0)15C-□ R88M-KH7K515C-□S1	MS3108E32-17S
Connector for brake cable	Motor side	R88M-K(050/100/200/400/750)30(H/T)-BS2	R88A-CNK11B
	Motor side	R88M-K6K010C-BS2 R88M-K(7K5/11K0/15K0)15C-BS2 R88M-KH7K515C-BS1	MS3108E14S-2S

Note: 1. All cables listed are flexible and shielded (except the R88A-CAKA□□□-BR-E which is only a flexible cable).
2. All connectors and cables listed have IP67 class (except R88A-CNW01R connector and R88A-CRGD0R3C cable).

R88D-KN□□□-ECT, R88D-KN□□□-ML2, R88D-KT□

G5 Rotary Servo Drives

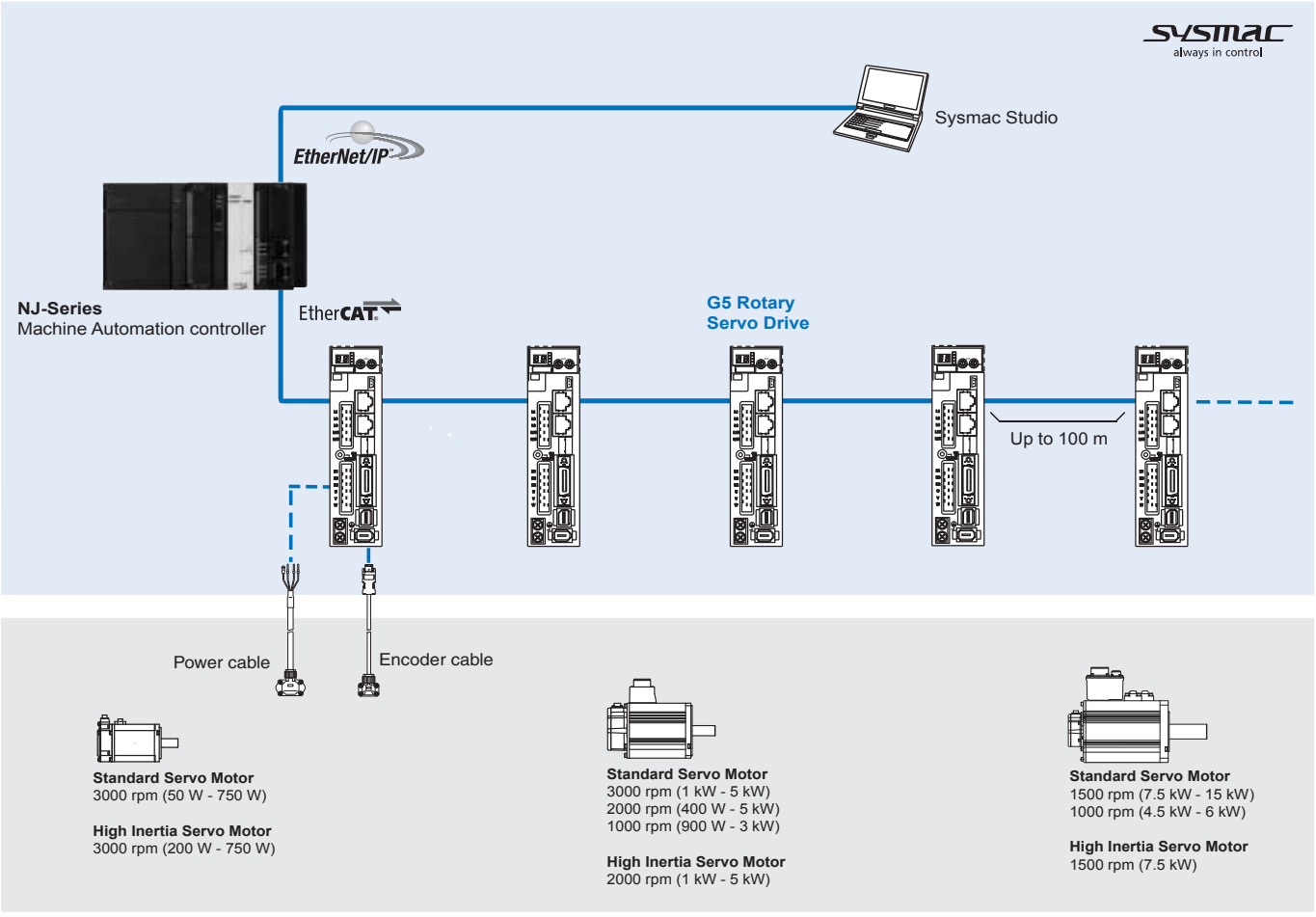
Accurate motion control in a compact size servo drive family. EtherCAT and safety built-in.

- EtherCAT, ML-II and Analog/pulse servo drive models
- Safety conforming ISO13849-1 PL-d
- High-response frequency of 2 kHz
- High resolution provided by 20 bits encoder
- Drive Programming: embedded indexer functionality in the Analogue/pulse models
- External encoder input for full closed loop
- Real time auto-tuning
- Advanced tuning algorithms (Anti-vibration function, torque feedforward, disturbance observer)

Ratings

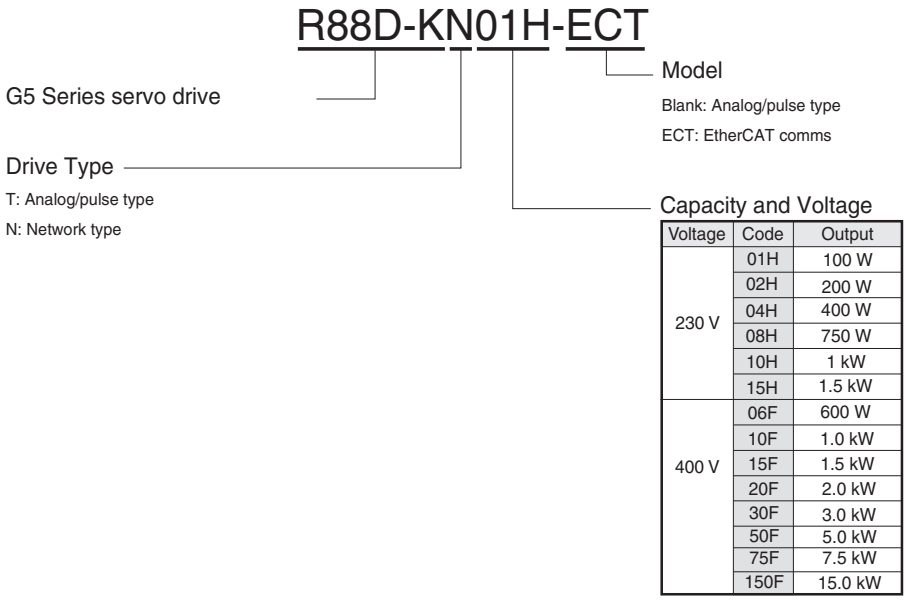
- 230 VAC single-phase 100 W to 1.5 kW (8.59 Nm)
- 400 VAC three-phase 600 W to 15 kW (95.5 Nm)

System configuration



Type designation

Servo drive



Voltage	Code	Output
230 V	01H	100 W
	02H	200 W
	04H	400 W
	08H	750 W
	10H	1 kW
	15H	1.5 kW
400 V	06F	600 W
	10F	1.0 kW
	15F	1.5 kW
	20F	2.0 kW
	30F	3.0 kW
	50F	5.0 kW
	75F	7.5 kW
	150F	15.0 kW

Servo drive specifications

Single-phase, 230 V

Servo drive type		R88D-K□	01H□	02H□	04H□	08H□	10H□	15H□
Applicable servo motor		R88M-K□	05030(H/T)-□	20030(H/T)-□	40030(H/T)-□	75030(H/T)-□	1K020(H/T)-□	1K030(H/T)-□
			10030(H/T)-□	–	–	–	–	1K530(H/T)-□
			–	–	–	–	–	1K520(H/T)-□
			–	–	–	–	–	90010(H/T)-□
Basic specifications	Max. applicable motor capacity W		100	200	400	750	1000	1500
	Continuous output current Arms		1.2	1.6	2.6	4.1	5.9	9.4
	Input power	Main circuit	Single-phase/3-phase, 200 to 240 VAC +10 to –15% (50/60 Hz)					
	Supply	Control circuit	Single-phase, 200 to 240 VAC +10 to –15% (50/60 Hz)					
	Control method		IGBT-driven PWM method, sinusoidal drive					
	Feedback		Serial encoder (incremental/absolute value)					
	Conditions: Usage/storage temperature		0 to +55°C/–20 to 65°C					
	Conditions: Usage/storage humidity		90% RH or less (non-condensing)					
	Conditions: Altitude		1000m or less above sea level					
	Conditions: Vibration/shock resistance (max.)		5.88 m/s^2 10 to 60 Hz (Continuous operation at resonance point is not allowed) / 19.6 m/s^2					
	Configuration		Base mounted					
	Approx. weight	kg	0.8		1.1	1.6	1.8	

Three-phase, 400 V

Servo drive type		R88D-K□	06F□	10F□	15F□	20F□	30F□	50F□	75F□	150F□
Applicable servo motor		R88M-K□	40020(F/C)-□	75030(F/C)-□	1K030(F/C)-□	2K030(F/C)-□	3K030(F/C)-□	4K030(F/C)-□	6K010C-□	11K015C-□
			60020(F/C)-□	1K020(F/C)-□	1K530(F/C)-□	2K020(F/C)-□	3K020(F/C)-□	5K030(F/C)-□	7K515C-□	15K015C-□
			–	–	1K520(F/C)-□	–	2K010(F/C)-□	4K020(F/C)-□	–	–
			–	–	90010(F/C)-□	–	–	5K020(F/C)-□	–	–
			–	–	–	–	–	4K510C-□	–	–
			–	–	–	–	–	3K010(F/C)-□	–	–
Basic specifications	Max. applicable motor capacity	kW	0.6	1.0	1.5	2.0	3.0	5.0	7.5	15.0
	Continuous output current	Arms	1.5	2.9	4.7	6.7	9.4	16.5	22.0	33.4
	Input power	Main circuit	3-phase, 380 to 480 VAC +10 to –15% (50/60Hz)							
	Supply	Control circuit	24 VDC ±15%							
	Control method		IGBT-driven PWM method, sinusoidal drive							
	Feedback	Serial encoder	Incremental or absolute encoder						Absolute encoder	
	Conditions: Usage/storage temperature		0 to 55°C/–20 to 65°C							
	Conditions: Usage/storage humidity		90% RH or less (non-condensing)							
	Conditions: Altitude		1000 m or less above sea level							
	Conditions: Vibration/shock resistance		5.88 m/s^2 10 to 60 Hz (Continuous operation at resonance point is not allowed)/19.6 m/s^2							
	Configuration		Base mounted							
	Approx. weight	kg	1.9			2.7	4.7		13.5	21.0

General specifications (for EtherCAT servo drives)

Performance		Frequency characteristics	2 kHz
EtherCAT interface	Command input		EtherCAT commands (for sequence, motion, data setting/reference, monitor, adjustment, and other commands).
	Drive Profile[*1]		CSP, CSV, CST, Homing and Position Profile modes (CiA402 Drive Profile) Homing mode Position profile mode Dual touch probe function (Latch function) Torque limit function
I/O signal	Sequence input signal		Multi-function input × 8 by parameter setting (forward/reverse drive prohibition, emergency stop, external latch, origin proximity, forward/reverse torque limit, general purpose monitor input).
	Sequence output signal		1 × servo drive error output 2 × multi-function outputs by parameters setting (servo ready, brake release, torque limit detection, zero speed detection, warning output, position completion, error clear attributed, programmable output …)
Integrated functions	USB communications	Interface	Personal computer/ Connector mini-USB
		Communications standard	Compliant with USB 2.0 standard
		Function	Parameter setting, status monitoring and tuning
	EtherCAT communications	Communications protocol	IEC 61158 Type 12, IEC 61800-7
		Physical layer	100BASE-TX (IEEE802.3)
		Connectors	RJ45 × 2 ECAT IN: EtherCAT input × 1 ECAT OUT: EtherCAT output × 1
		Communications media	Category 5 or higher (cable with double, aluminium tape and braided shielding is recommended)
		Communications distance	Distance between nodes: 100 m max.
		LED indicators	RUN × 1 ERR × 1 L/A IN (Link/Activity IN) × 1 L/A OUT (Link/activity OUT) × 1
	Autotuning		Automatic motor parameter setting. One parameter rigidity setting. Inertia detection.
	Dynamic brake (DB)		Built-in. Operates during main power OFF, servo alarm, servo OFF or overtravel.
	Regenerative processing		Internal resistor included in models from 600 W to 5 kW. Regenerative resistor externally mounted (option).
	Overtravel (OT) prevention function		DB stop, deceleration stop or coast to stop during P-OT, N-OT operation
	Encoder divider function		Gear ratio
	Protective functions		Overcurrent, overvoltage, undervoltage, overspeed, overload, encoder error, overheat...
	Analog monitor functions for supervision		Analog monitor of motor speed, speed reference, torque reference, command following error, analog input... The monitoring signals to output and their scaling can be specified with parameters. Number of channels: 2 (Output voltage: ±10V DC)
	Panel operator	Display functions	2 × digit 7-segment LED display shows the drive status, alarm codes, parameters...
		Switches	2 × rotary switches for setting the node address
	CHARGE lamp		Lits when the main circuit power supply is turned ON.
	Safety terminal	Functions	Safety Torque OFF function to cut off the motor current and stop the motor. Output signal for failure monitoring function.
		Conformed standards	EN ISO13849-1:2008 (PL- d, Performance Level d), IEC61800-5 -2:2007 (function STO, Safe Torque OFF), EN61508:2001 (Safety Integrity Level 2, SIL2), EN954-1:1996 (CAT3).
	External encoder feedback		Serial signal and line-driver A-B-Z encoder for full-closed control

[*1] The CSV, CST and Homing modes are supported in the servo drive with version 2.0 or higher.

General specifications (for MECHATROLINK-II servo drives)

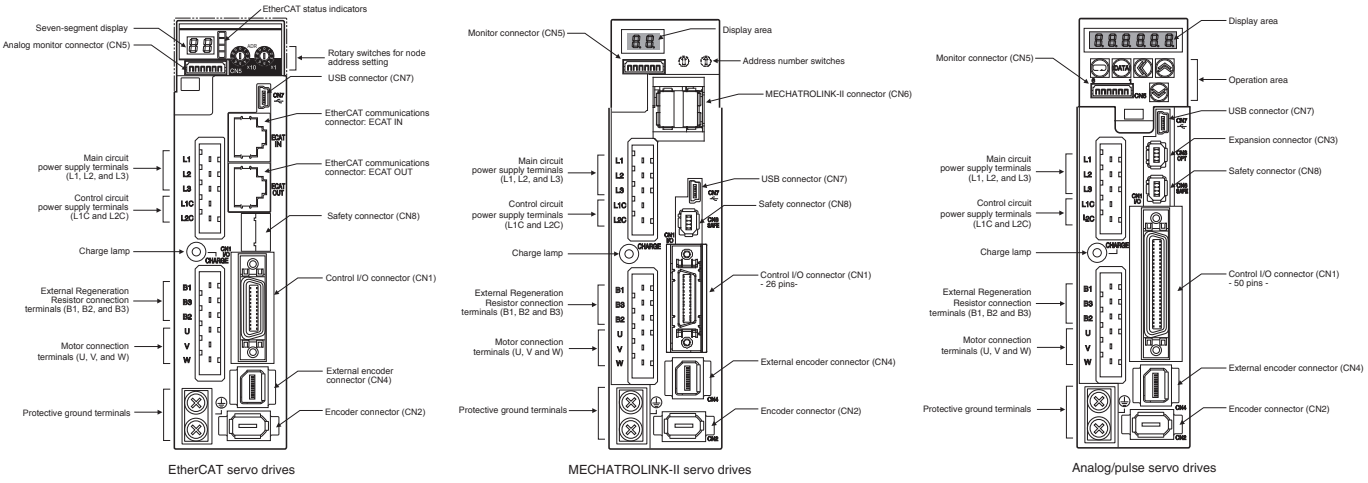
Control mode			Position control, velocity control, torque control, full-closed control.
Performance		Frequency characteristics	2 kHz
		Speed zero clamp	Preset velocity command can be clamped to zero by the speed zero clamp input.
		soft start time setting	0 to 10 s (acceleration, deceleration can be set separately).
Command input		MECHATROLINK-II communication	MECHATROLINK-II commands (for sequence, motion, data setting/reference, monitor, adjustment and other commands)
I/O signal	Sequence input signal		Multi-function input × 8 by parameter setting (forward/reverse drive prohibition, emergency stop, external latch, origin proximity, forward/reverse torque limit, general purpose monitor input).
	Sequence output signal		It is possible to output three types of signal form incl.: brake release, servo ready, servo alarm, positioning complete, motor rotation speed detection, torque limit detection, zero speed detection, speed coincidence detection, warning, position command status, speed limit detection, alarm output, speed command status.
Integrated functions	USB communications	Interface	Personal computer/ Connector mini-USB
		Communications standard	Compliant with USB 2.0 standard
		Function	Parameter setting, status monitoring and tuning
	MECHATROLINK-II communications	Communications protocol	MECHATROLINK-II
		Station address	41H to 51 FH (max. number of slaves: 30)
		Transmission speed	10 Mbps
		Transmission cycle	1, 2 & 4 ms
		Data length	32 bytes
	Autotuning		Automatic motor parameter setting. One parameter rigidity setting. Inertia detection.
	Dynamic brake (DB)		Built-in. Operates during main power OFF, servo alarm, servo OFF or overtravel.
	Regenerative processing		Internal resistor included in models from 600 W to 5 kW. Regenerative resistor externally mounted (option).
	Overtravel (OT) prevention function		DB stop, deceleration stop or coast to stop during P-OT, N-OT operation
	Encoder divider function		Optional division possible
	Protective functions		Overcurrent, overvoltage, undervoltage, overspeed, overload, encoder error, overheat...
	Analog monitor functions for supervision		Analog monitor of motor speed, speed reference, torque reference, command following error, analog input... The monitoring signals to output and their scaling can be specified with parameters. Number of channels: 2 (Output voltage: ±10V DC)
	Panel operator	Display functions	2-digit 7-segment LED display shows the drive status, alarm codes, parameters...
			MECHATROLINK-II communications status LED indicator (COM)
		Switches	2 × rotary switches for setting the MECHATROLINK-II node address
	CHARGE lamp		Lits when the main circuit power supply is turned ON.
	Safety terminal	Functions	Safety Torque OFF function to cut off the motor current and stop the motor. Output signal for failure monitoring function.
		Conformed standards	EN ISO13849-1:2008 (PL- d, Performance Level d), IEC61800-5 -2:2007 (function STO, Safe Torque OFF), EN61508:2001 (Safety Integrity Level 2, SIL2), EN954-1:1996 (CAT3).
	External encoder feedback		Serial signal and line-driver A-B-Z encoder for full-closed control

General specifications (for Analog/pulse servo drives)

Control modes			External control	(1) position control, (2) velocity control, (3) torque control, (4) position/velocity control, (5) position/torque control, (6) velocity/torque control and (7) full-closed control.
			Internal positioning	Drive Programming: indexer functionality enabled by parameter.
Speed/torque control	**Performance**		Frequency characteristics	2 kHz
			Speed zero clamp	Preset velocity command can be clamped to zero by the speed zero clamp input.
			Soft start time setting	0 to 10 s (acceleration, deceleration can be set separately). S-curve acceleration/deceleration is also available.
	Input signal	Speed control	Speed reference voltage	6 VDC at rated speed: set at delivery (the scale and polarity can be set by parameters)
			Torque limit	3 VDC at rated torque (torque can be limited separately in positive/negative direction).
			Preset speed control	Preset speed is selectable from 8 internal settings by digital inputs.
		Torque control	Torque reference voltage	3 VDC at rated torque: set at delivery (the scale and polarity can be set by parameters).
			Speed limit	Speed limit can be set by parameter.
Position control	**Input signal**	Command pulse	Input pulse type	Sign + pulse train, 90° phase displacement 2-phase pulse (A-phase+ B-phase) or CCW/CW pulse train
			Input pulse frequency	4 Mpps max. (200 Kpps max. at open collector).
			Command pulse scaling (Electronic Gear)	Applicable scaling ratio: 1/1000 to 1000 Any value of 1 to 2^{30} can be set for numerator (encoder resolution) and denominator (command pulse resolution per motor revolution). The combination has to be within the range shown above.
Full-closed control	**Input signal**	Command pulse	Input pulse type	Sign + pulse train, 90° phase displacement 2-phase pulse (A-phase+ B-phase) or CCW/CW pulse train
			Input pulse frequency	4 Mpps max. (200 Kpps max. at open collector).
			Command pulse scaling (Electronic Gear)	Applicable scaling ratio: 1/1000 to 1000 Any value of 1 to 2^{30} can be set for numerator (encoder resolution) and denominator (command pulse resolution). The combination has to be within the range shown above.
	External encoder scaling			Applicable scaling ratio: 1/20 to 160 Any value of 1 to 2^{30} can be set for numerator (encoder resolution) and denominator (external encoder resolution per motor revolution). The combination has to be within the range shown above.
Drive Programming	Functionality selection			Functionality enabled by parameter.
	Supported functionality			G5 Analogue/pulse servo drive with firmware 1.10 or higher.
	Software			CX-Drive version 2.30 or higher.
	Communication			The program can be downloaded via USB communication (CX-Drive)
	Command types			Move relative, Move absolute, Jog, Homing, Deceleration stop, Velocity update, Timer, Output signal control, Jump, Conditional branching,
	Number of commands			Up to 32 commands (0 to 31)
	Command execution			Strobe input to execute the selected command or to execute a complex sequence (combination of various commands).
	Command selection			Up to 5 digital inputs to select the individual commands or sequences

I/O signal	Position signal output		A-phase, B.phase, Z-phase line driver output and Z-phase open-collector output.
	Sequence input signal	External control	- Multi-function input × 10 by parameter setting: servo ON, control mode switching, forward/reverse drive prohibition, vibration filter switching, gain switching, electronic gear switching, error counter reset, pulse prohibition, alarm reset, internal speed selection, torque limit switching, zero speed, emergency stop, inertia ratio switching, velocity/torque command sign. - Dedicated input × 1 (SEN: sensor ON, ABS data request).
		Internal positioning (Drive programming mode)	- Multi-function input × 10 by parameter setting: servo ON, forward/reverse drive prohibition, damping filter switching, gain switching, alarm reset, torque limit switching, emergency stop, immediate stop, deceleration stop input, inertia ratio switching, latch input, origin proximity input, strobe and 5 × input command selection. - Dedicated input × 1 (SEN: sensor ON, ABS data request).
	Sequence output signal	External control	- 3 × outputs signals configured by parameter settings: brake release, servo ready, servo alarm, positioning complete, motor rotation speed detection, torque limit detection, zero speed detection, speed coincidence detection, warning, position command status, speed limit detection, speed command status. - 1 output fixed to Alarm output.
		Internal positioning (Drive programming enabled)	3 × outputs signals configured by parameter settings: ready, Brake, position completed, motor speed detection, torque limit status, zero speed detection, speed conformity, warning, position command status, position completed, drive programming command output and output during drive programming. - 1 output fixed to Alarm output.
Integrated functions	USB Communications	Interface	Personal computer/ Connector mini-USB
		Communications standard	Compliant with USB 2.0 standard
		Function	Parameter setting, status monitoring and tuning
	Autotuning		Automatic motor parameter setting. One parameter rigidity setting. Inertia detection.
	Dynamic brake (DB)		Built-in. Operates during main power OFF, servo alarm, servo OFF or overtravel.
	Regenerative processing		Internal resistor included in models from 600 W to 5 kW. Regenerative resistor externally mounted (option).
	Overtravel (OT) prevention function		DB stop, deceleration stop or coast to stop during P-OT, N-OT operation
	Encoder divider function		Optional division possible
	Electronic gearing (Numerator/Denominator)		Up to 4 electronic gear numerators by combining with inputs.
	Internal speed setting function		8 speeds may be set internally
	Protective functions		Overcurrent, overvoltage, undervoltage, overspeed, overload, encoder error, overheat...
	Analog monitor functions for supervision		Analog monitor of motor speed, speed reference, torque reference, command following error, analog input... The monitoring signals to output and their scaling can be specified by parameters. Number of channels: 2 (Output voltage: ±10V DC)
	Panel operator	Display functions	6-digit 7-segment LED display shows the drive status, alarm codes, parameters...
		Panel operator keys	Used to set/monitor parameters and drive condition (5 key switches).
	CHARGE lamp		Lits when the main circuit power supply is turned ON.
	Safety terminal	Functions	Safety torque OFF function to cut off the motor current and stop the motor. Output signal for failure monitoring function.
		Conformed standards	EN ISO13849-1:2008 (PL- d, Performance Level d), IEC61800-5 -2:2007 (function STO, Safe Torque OFF), EN61508:2001 (Safety Integrity Level 2, SIL2), EN954-1:1996 (CAT3).
	External encoder feedback		Serial signal and line-driver A-B-Z encoder for full-closed control
	Expansion connector		Serial bus for option board

Servo drive part names



Note: The above pictures show 230 V servo drives models only. The 400 V servo drives have 24 VDC power input terminals for control circuit instead of L1C and L2C terminals.

I/O specifications

Terminals specifications (for all servo drives)

Symbol	Name	Function
L1	Main power supply input terminal	AC power input terminals for the main circuit **Note:** for single-phase servo drives connect the power supply input to L1 and L3.
L2		
L3		
L1C	Control power supply input terminal	AC power input terminals for the control circuit (for 200 V single/three-phase servo drives only).
L2C		
24 V		DC power input terminals for the control circuit (for 400 V three-phase servo drives only).
0 V		
B1	External regeneration resistor connection terminals	Servo drives 200 V below 750 W: no internal resistor is connected. Leave B2 and B3 open. Connect an external regenerative resistor between B1 and B2. Servo drives from 600 W to 5 kW: short-circuit in B2 and B3 for internal regenerative resistor. If the internal regenerative resistor is insufficient, connect an external regenerative resistor between B1 and B2 and remove the wire between B2 and B3.
B2		
B3		
U	Servo motor connection terminals	Terminals for outputs to the servomotor.
V		
W		

I/O signals (CN1) - Input signals (for EtherCAT and MECHATROLINK-II servo drives)

Pin No.	Signal name	Function	
6	I-COM	± pole of external DC power. The power must use 12 V to 24 V (±5%)	
5	E-STOP	Emergency stop	The signal name shows the factory setting. The function can be changed by parameter setting.
7	P-OT	Forward run prohibited	
8	N-OT	Reverse run prohibited	
9	DEC	Origin proximity	
10	EXT3	External latch input 3	
11	EXT2	External latch input 2	
12	EXT1	External latch input 1	
13	SI-MON0	General purpose monitor input 0	
14	BTP-I	Connecting pin for the absolute encoder backup battery. Do not connect when a battery is connected to the encoder cable (CN2 connector).	
15	BTN-I		
17	–	Terminals not used. Do not connect.	
18	–		
19	–		
20	–		
21	–		
22	–		
23	–		
24	–		
–	PCL	Forward torque limit	The function of input signals allocated to pins 5 and 7 to 13 can be changed with these options by parameters settings.
	NCL	Reverse torque limit	
	SI-MON1	General-purpose monitor input 1	
	SI-MON2	General-purpose monitor input 2	
Shell	FG	Shield ground. Connected to frame ground if the shield wire of the I/O signal cable is connected to the connector shell.	
16	GND	Signal ground. It is insulated with power supply (I-COM) for the control signal in the servo drive.	

I/O signals (CN1) - Output signals (for EtherCAT and MECHATROLINK-II servo drives)

Pin No.	Signal name	Function	
1	BRK-OFF+	External brake release signal	
2	BRK-OFF		
25	S-RDY+	Servo ready: ON when there is no servo alarm and control/main circuit power supply is ON	
26	S-RDY–		
3	ALM+	Servo alarm: Turns OFF when an error is detected	
4	ALM–		
–	INP1	Position completed output 1	The function of output signals allocated to pins 1, 2, 25 and 26 can be changed with these options by parameters settings
	TGON	Speed detection	
	T_LIM	Torque limit	
	ZSP	Zero speed	
	VCMP	Speed command status	
	INP2	Position completed output 2	
	WARN1	Warning 1	
	WARN2	Warning 2	
	PCMD	Position command status	
	V_LIM	Speed limit	
	ALM-ATB	Error clear attribute (for ECT model only)	
	R-OUT1	Programmable output 1 (for ECT model only)	
	R-OUT2	Programmable output 2 (for ECT model only)	

I/O signals (CN1) - Input signals (for Analog/pulse servo drives)

Pin No.	Control mode	Signal name	Function	
1	Position/ Full closed loop	+24 VCW	Reference pulse input for line driver and open collector according to parameter setting. Input mode: Sign + pulse string Reverse/forward pulse (CCW/CW pulse) Two-phase pulse (90° phase differential)	
3		+CW		
4		–CW		
2		+24 VCW		
5		+CCW		
6		–CCW		
44		+CWLD	Reference pulse input for line driver only. Input mode: Reverse/forward pulse (CCW/CW pulse)	
45		–CWLD		
46		+CCWLD		
47		–CCWLD		
14	Speed	REF	Speed reference input: ±10 V/rated motor speed (input gain can be modified using a parameter).	
	Torque	TREF1	Torque reference input: ±10 V/rated motor torque (input gain can be modified using a parameter).	
		VLIM	Speed limit input: ±10 V/rated motor speed (input gain can be modified using a parameter).	
15	–	AGND1	Analog signal ground	
16	Torque	TREF2	Torque reference input: ±10 V/rated motor torque (input gain can be modified using a parameter).	
	Position/Speed Full closed loop	PCL	Forward torque limit input: ±10 V/rated motor torque (input gain can be modified using a parameter).	
18		NCL	Reverse torque limit input: ±10 V/rated motor torque (input gain can be modified using a parameter).	
17	–	AGND1	Analog signal ground	
7	Common	+24 VIN	Control power supply input for sequence signals: users must provide the +24 V power supply (12 to 24 V).	
29		RUN	Servo ON: this turn ON the servo.	
26	Position/Full closed loop	DFSEL1	Vibration filter switching 1	Enables vibration filter according parameter setting.
27	Common	GSEL	Gain switching	Enables gain value according parameter setting.
28	Position/Full closed loop	GESEL1	Electronic gear switching 1	Switches the numerator fro electronic gear ratio.
	Speed	VSEL3	Internal speed selection 3	Input to select the desired speed setting during internally speed operation. The speed selection is combining this input with VSEL1 and VSEL2 inputs.
30	Position/Full closed loop	ECRST	Error counter reset input.	Resets the position error counter.
	Speed	VSEL2	Internal speed selection 2	Input to select the desired speed setting during internally speed operation. The speed selection is combining this input with VSEL1 and VSEL3 inputs.
31	Common	RESET	Alarm reset input.	Release the alarm status. The error counter is reset when the alarm is reset.
32	Position/Speed/ Torque	TVSEL	Control mode switching	Position ↔ speed Position ↔ torque Torque ↔ speed } Enables control mode switching
33	Position	IPG	Pulse prohibition input. Digital input to inhibit the position reference pulse.	
	Speed	VSEL1	Internal speed selection 1	Input to select the desired speed setting during internally speed operation. The speed selection is combining this input with VSEL2 and VSEL3 inputs.
8	Common	NOT	Reverse run prohibited	Overtravel prohibited: stops servomotor when movable part travels beyond the allowable range of motion.
9		POT	Forward run prohibited	
20	Position/Speed/ Torque	SEN	Sensor ON input. Initial data request signal when using an absolute encoder.	
13		SENGND	Sensor ON signal ground.	
42	Common	BAT (+)	Backup battery connection terminals when the absolute encoder power is interrupted. Do not connect when a absolute encoder battery cable for backup is used.	
43		BATGND (–)		
50		FG	Frame ground	
–	–	TLSEL	Torque limit switch	The function of input signals allocated to pins 8, 9 and 26 to 33 can be changed with these options by parameters settings
		DFSEL2	Vibration filter switching 2	
		GESEL2	Electronic gear switching 2	
		VZERO	Zero speed	
		VSIGN	Speed command signal	
		TSIGN	Torque command signal	
		E-STOP	Emergency stop	
		JSEL	Inertia ratio switching	
	Drive Programming	EXT1	Latch input 1	
		HOME	Origin proximity input	
		H-STOP	Immediate stop input	
		S-STOP	Deceleration stop input	
		STB	Strobe	
		B-SEL1	Command selection input 1	
		B-SEL2	Command selection input 2	
		B-SEL4	Command selection input 4	
		B-SEL8	Command selection input 8	
		B-SEL16	Command selection input 16	
12	–	Terminals not used. Do not connect.		
40	–			
41	–			

I/O signals (CN1) - Output signals (for Analog/pulse servo drives)

Pin No.	Control mode	Signal name	Function	
21	Position/ Full closed loop	+A	Encoder phase A+	Encoder signals (or external scale signals during full closing control) are output according Encoder Dividing Numerator parameter. This is the line-driver output (equivalent to R422). The maximum output frequency is 4 Mbps. Phase Z is output for encoder signals (or external scale signals during full closing control). This is the line-driver output (equivalent to R422).
22		–A	Encoder phase A–	
48		+B	Encoder phase B+	
49		–B	Encoder phase B–	
23		+Z	Encoder phase Z+	
24		–Z	Encoder phase Z–	
19		Z	Encoder phase-Z output	Phase Z is output for encoder signals (or external scale signals during full closing control). Open-collector output.
25		ZCOM	Encoder phase-Z common	
11	Common	BKIR	Brake release signal output	Timing signal for operating the electromagnetic brake on a motor.
10		BKIRCOM		
35		READY	Servo ready: ON if there is not servo alarm when the control/main circuit power supply is turned ON.	
34		READYCOM		
37		/ALM	Servo alarm: turns OFF when an error is detected.	
36		ALMCOM		
39	Speed/torque	TGON	Motor rotation speed detection. This output turns ON when the motor rotation speed reaches the speed set in a parameter.	
39	Position/ Full closed loop	INP1	Positioning complete output 1: turns ON when position error is equal to setting parameter.	
38		INP1COM		
–	–	INP2	Position complete output 2	The function of output signals allocated to pins 11, 10, 34 to 39 can be changed with these options by parameters settings.
		P-CMD	Position command status	
		ZSP	Zero speed	
		WARN1	Warning 1	
		WARN2	Warning 2	
		ALM-ATB	Error clear attribute	
		VCMP	Speed conformity output	
		V-CMD	Speed command status	
		V-LIMIT	Speed limit detection	
		T-LIMIT	Torque limit detection	
	Drive Programming	B-CTRL1	Drive Programming output 1	
		B-CTRL2	Drive Programming output 2	
		B-CTRL3	Drive Programming output 3	
		B-BUSY	Output during Drive Programming	
		HOME-CMP	Origin search complete	

External encoder connector (CN4) - (for all servo drives)

Pin No.	Signal name	Function
1	E5V	External scale power supply output. Use at 5.2 V ±5% and at or below 250 mA.
2	E0V	This is connected to the control circuit ground connected to connector CN1.
3	PS	External scale signal I/O (serial signal).
4	/PS	
5	EXA	External scale signal input (Phase A, B, and Z signals). Performs the input and output of phase A, B and Z signals.
6	/EXA	
7	EXB	
8	/EXB	
9	EXZ	
10	/EXZ	
Shell	FG	Shield ground

Monitor connector (CN5) - (for all servo drives)

Pin No.	Signal name	Function
1	AM1	Analog monitor output 1. Outputs the analog signal for the monitor. Use the parameters setting to select the output to monitor. Default setting: Motor rotation speed 1 V/(1000 r/min).
2	AM2	Analog monitor output 2. Outputs the analog signal for the monitor. Use the parameters setting to select the output to monitor. Default setting: Motor rotation speed 1 V/(1000 r/min).
3	GND	Ground for analog monitors 1, 2.
4	–	Terminals not used. Do not connect.
5	–	
6	–	

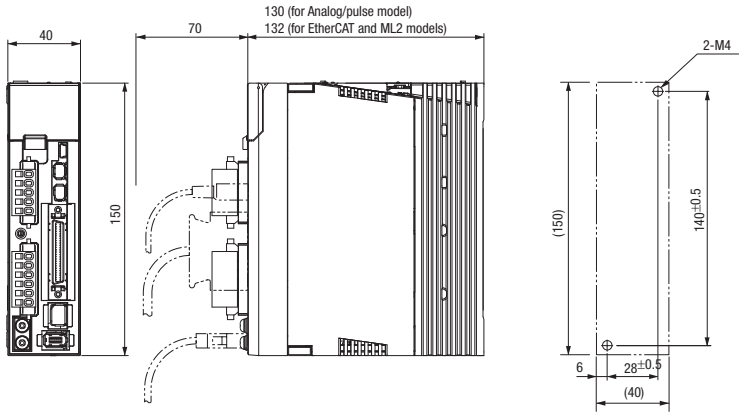
Safety connector (CN8) - (for all servo drives)

Pin No.	Signal name	Function
1	–	Not used. Do not connect
2	–	
3	SF1–	Safety input 1 & 2. This input turns OFF the power transistor drive signals in the servo drive to cut off the current output to the motor.
4	SF1+	
5	SF2–	
6	SF2+	
7	EDM–	A monitor signal is output to detect a safety function failure.
8	EDM+	
Shell	FG	Frame ground.

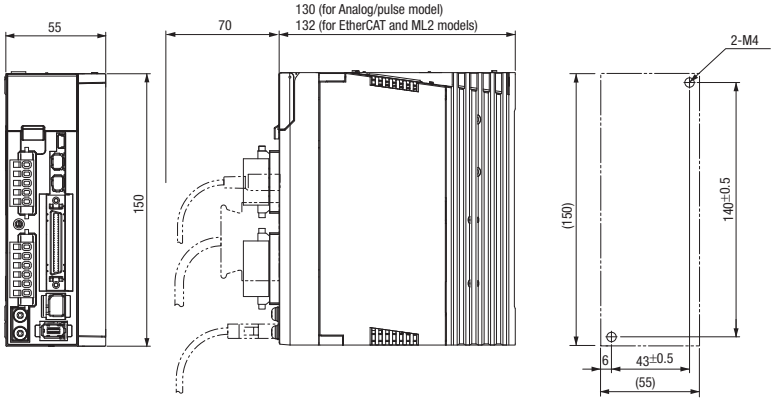
Dimensions

Servo drives

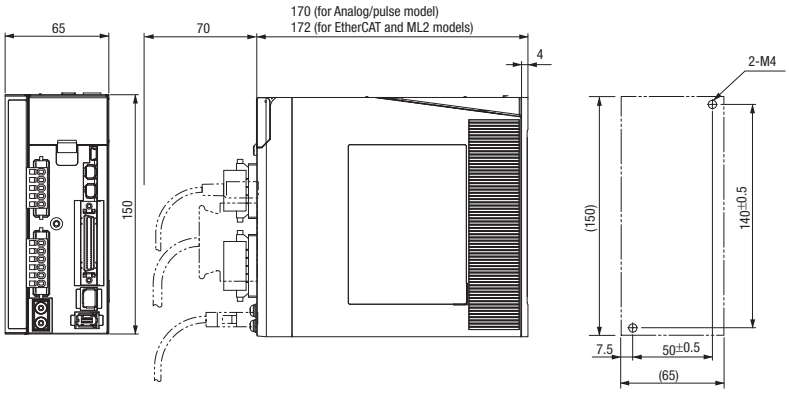
R88D-KT01/02H, R88D-KN01/02H-□ (230 V, 100 to 200 W)



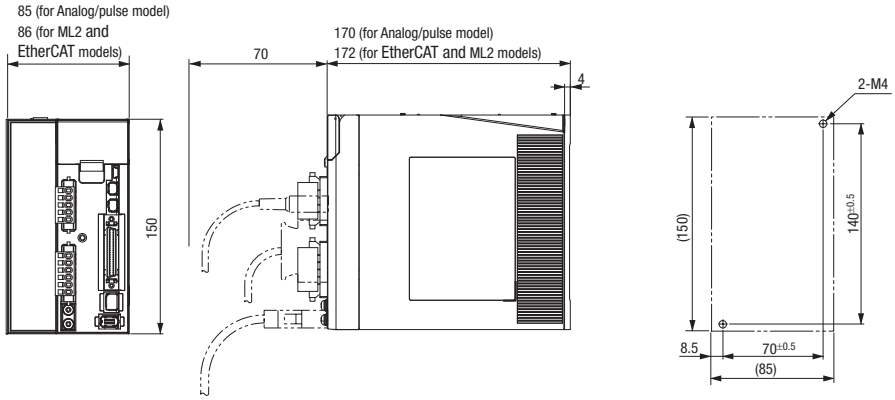
R88D-KT04H, R88D-KN04H-□ (230 V, 400 W)



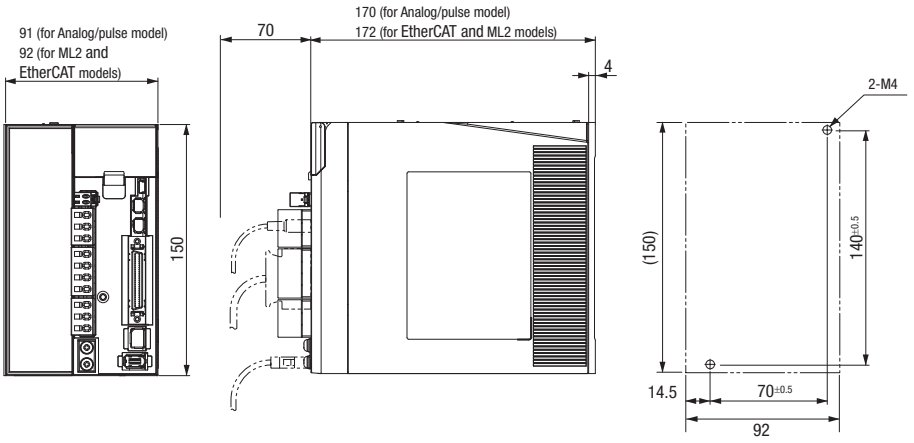
R88D-KT08H, R88D-KN08H-□ (230 V, 750 W)



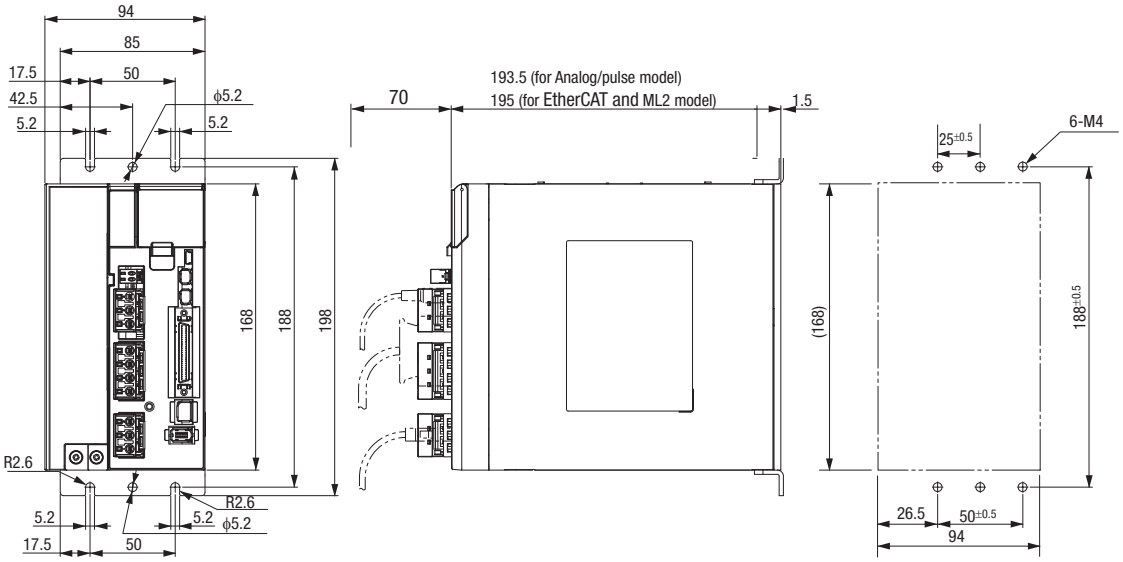
R88D-KT10/15H, R88D-KN10/15H-□ (230 V, 1 to 1.5 kW)



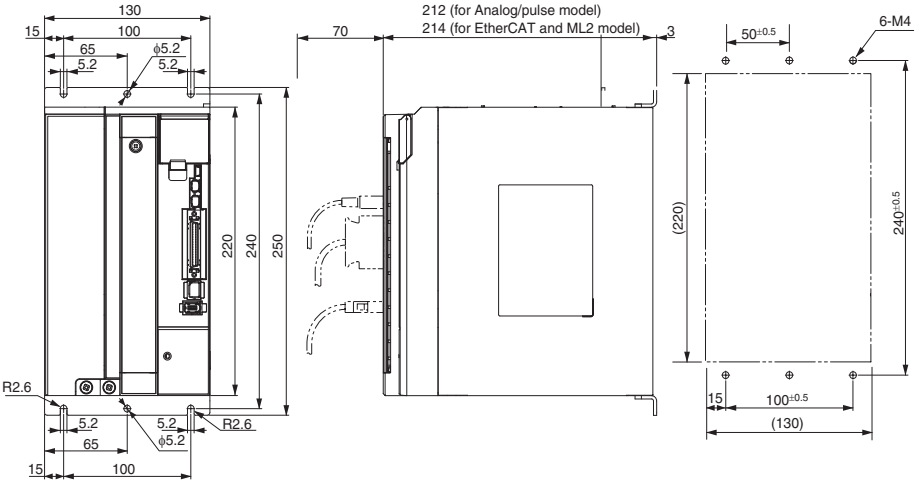
R88D-KT06/10/15F, R88D-KN06/10/15F-□ (400 V, 600 W to 1.5 kW)



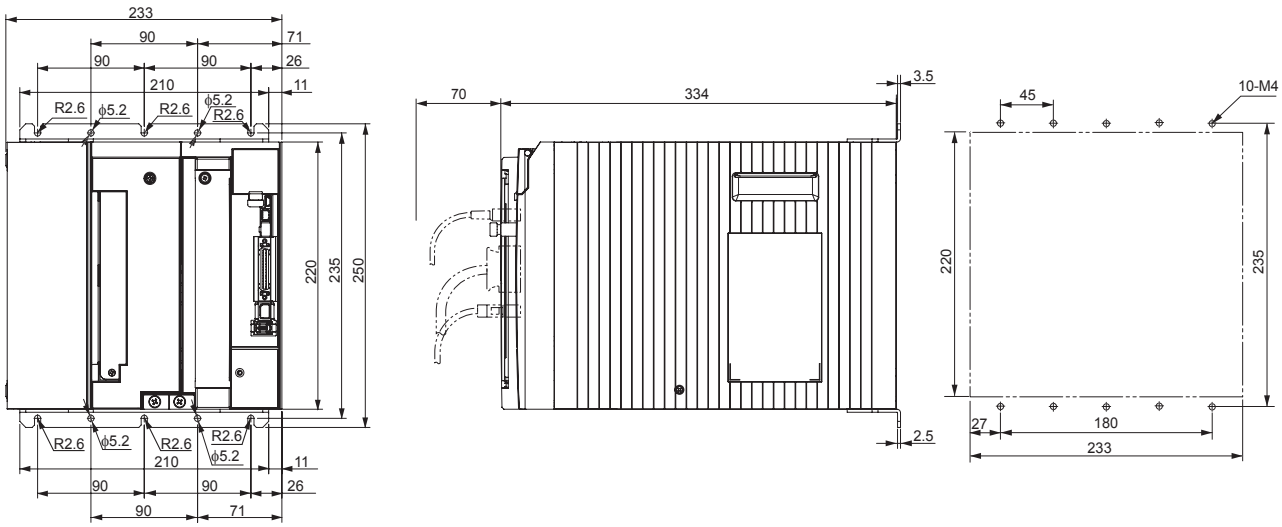
R88D-KT20F, R88D-KN20F-□ (400 V, 2 kW)



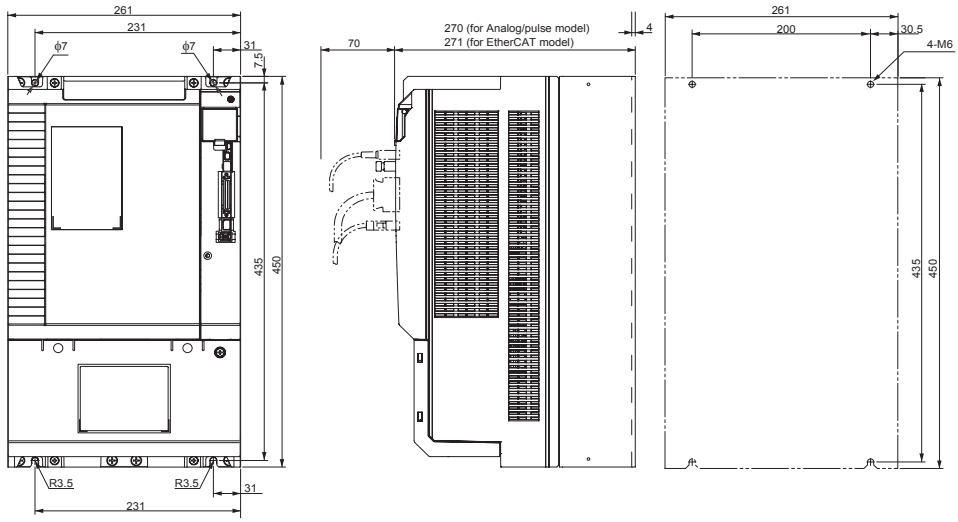
R88D-KT30/50F, R88D-KN30/50F-□ (400 V, 3 to 5 kW)



R88D-KT75F, R88D-KN75H-ECT (400 V, 7.5 kW)

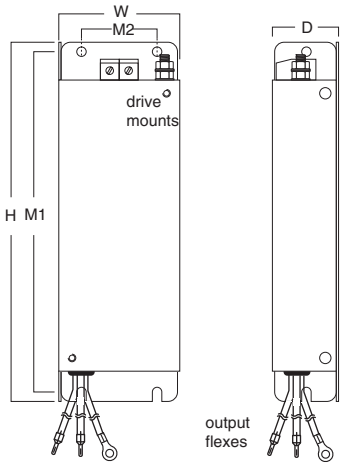


R88D-KT150F, R88D-KN150H-ECT (400 V, 15 kW)



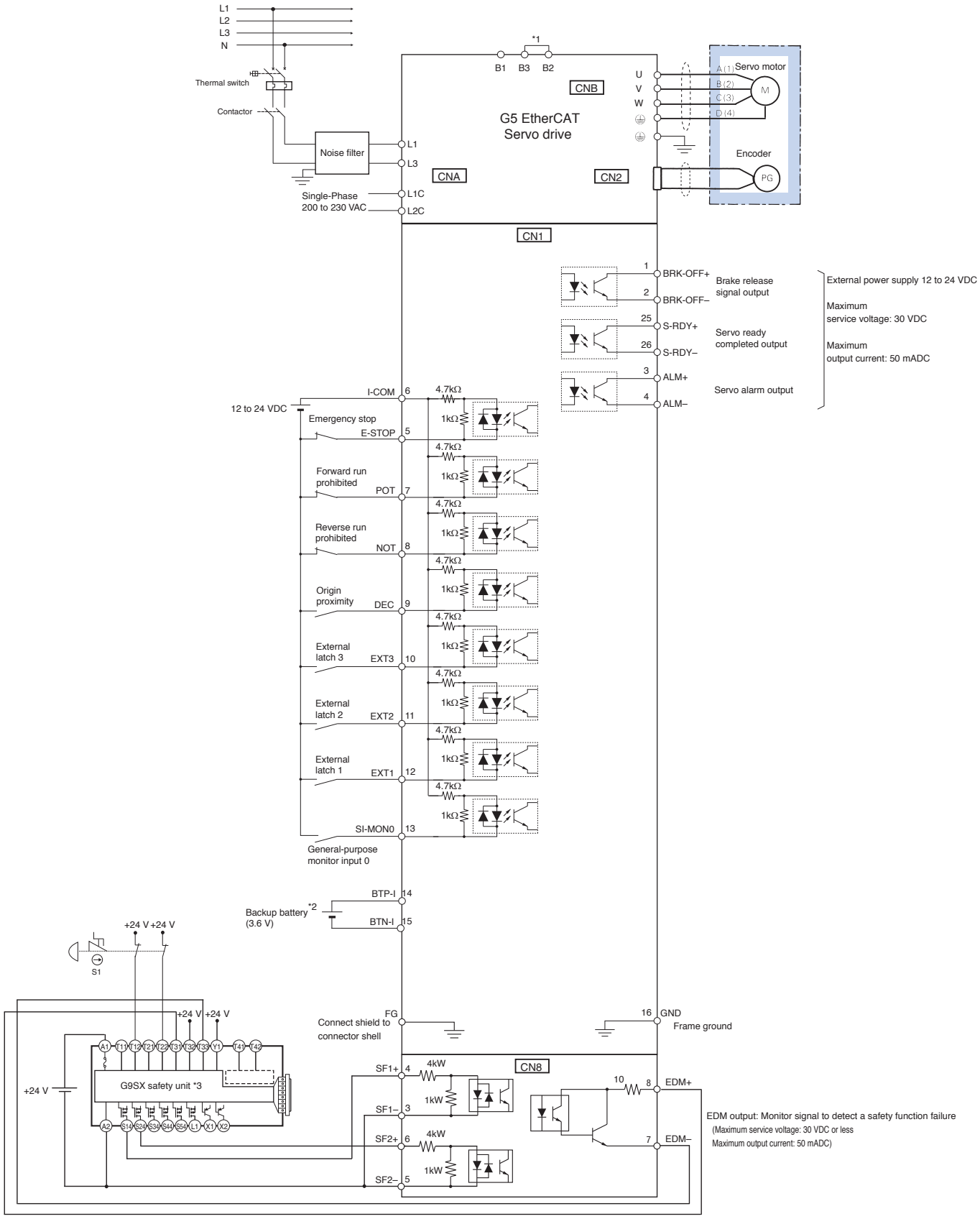
Filters

Filter model	External dimensions			Mount dimensions	
	H	W	D	M1	M2
R88A-FIK102-RE	190	42	44	180	20
R88A-FIK104-RE	190	57	30	180	30
R88A-FIK107-RE	190	64	35	180	40
R88A-FIK114-RE	190	86	35	180	60
R88A-FIK304-RE	196	92	40	186	70
R88A-FIK306-RE	238	94	40	228	70
R88A-FIK312-RE	291	130	40	278	100
R88A-FIK330-RE	310	233	50	293	180
R88A-FIK350-RE	506	261	52	491	200



Installation

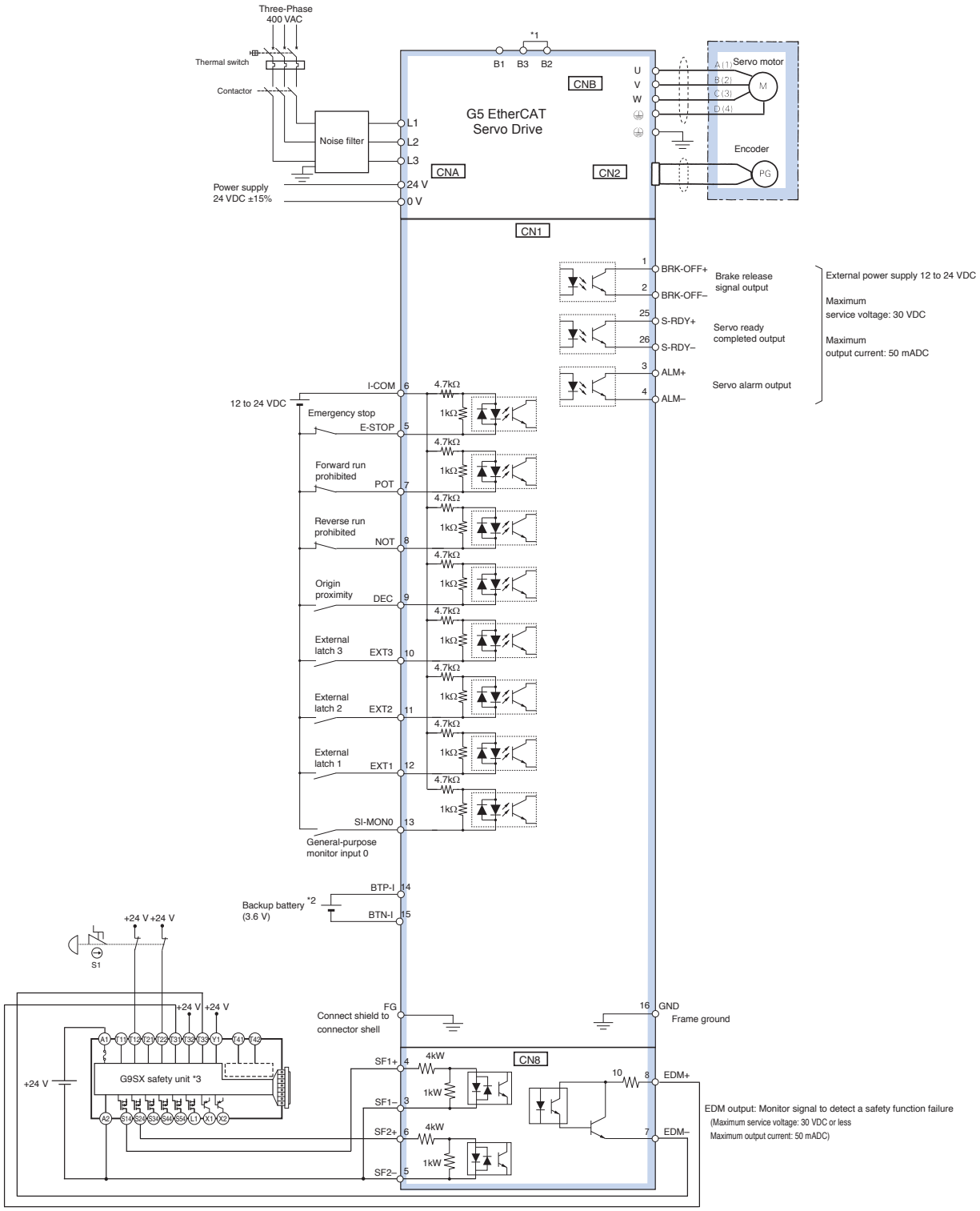
Single-phase, 230 VAC (for EtherCAT servo drives)



*1 For servo drives from 750 W, B2 and B3 are short-circuited. If the internal regenerative resistor is insufficient, remove the wire between B2 and B3 and connect an external regenerative resistor between B1 and B2.
*2 For use only with an absolute encoder. If a backup battery is connected to CN1 I/O connector, an encoder cable with a battery is not required.
*3 Wiring diagram example using the G9SX safety unit. If a safety unit is not used, keep the factory safety bypass connector installed in the CN8.

Note: The input function of pins 5 and 7 to 13, and output function of pins 1, 2, 25 and 26, can be changed via parameter settings.

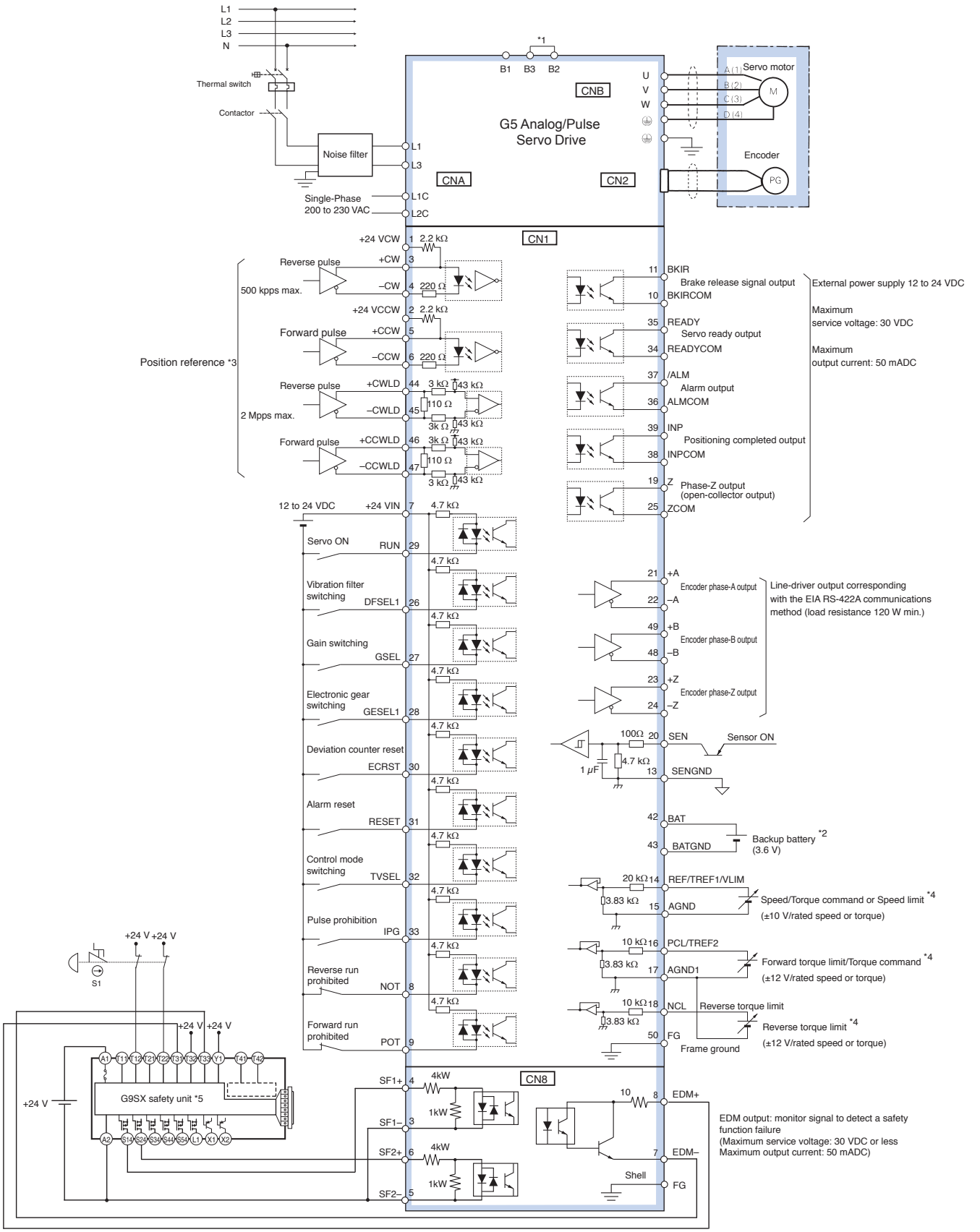
Three-phase, 400 VAC (for EtherCAT servo drives)



*1 Normally B2 and B3 are short-circuited. If the internal regenerative resistor is insufficient, remove the wire between B2 and B3 and connect an external regenerative resistor between B1 and B2.
*2 For use only with an absolute encoder. If a backup battery is connected to CN1 I/O connector, an encoder cable with a battery is not required.
*3 Wiring diagram example using the G9SX safety unit. If a safety unit is not used, keep the factory safety bypass connector installed in the CN8.

Note: The input function of pins 5 and 7 to 13, and output function of pins 1, 2, 25 and 26, can be changed via parameter settings.

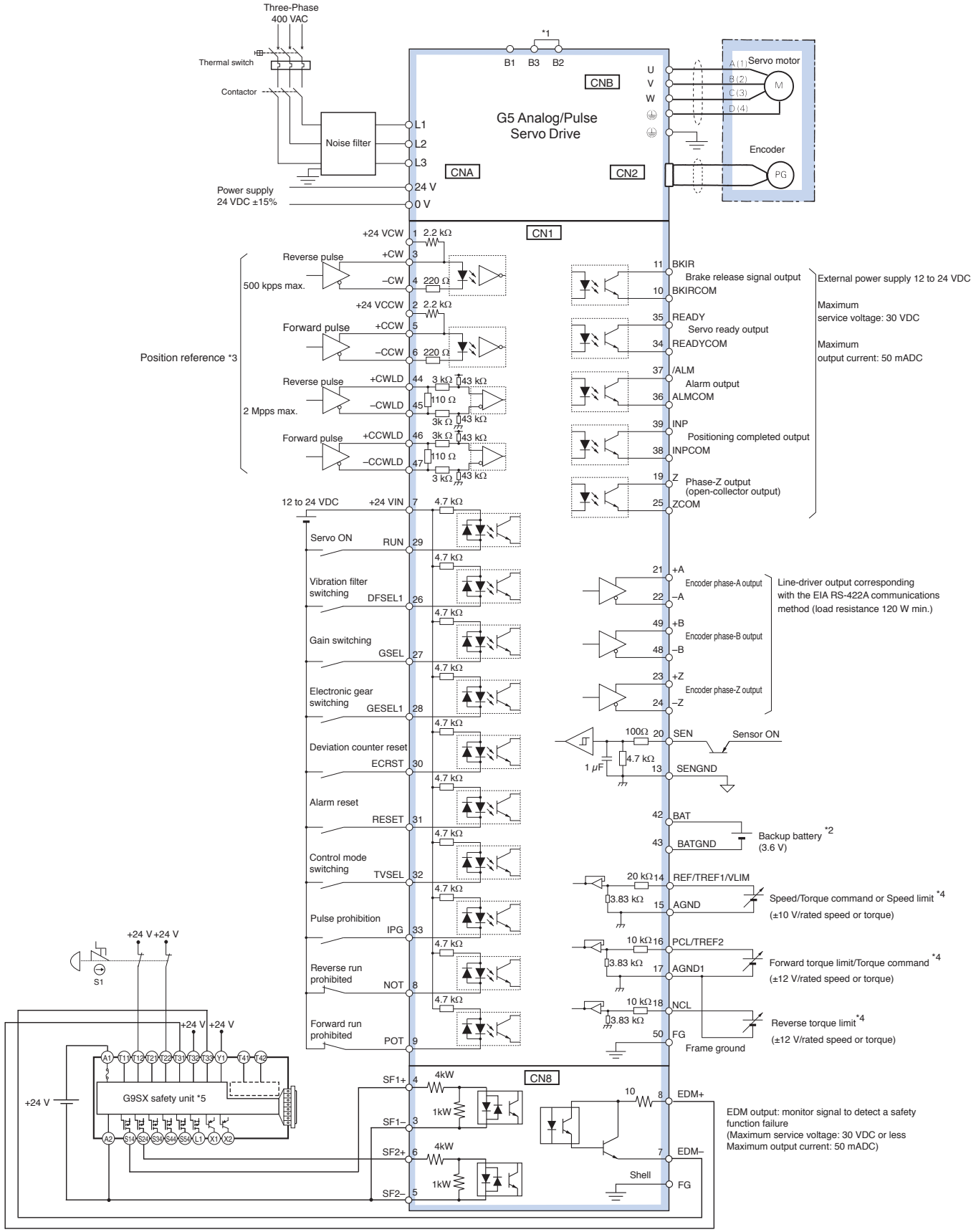
Single-phase, 230 VAC (for Analog/pulse servo drives)



*1 For servo drives from 750 W, B2 and B3 are short-circuited. If the internal regenerative resistor is insufficient, remove the wire between B2 and B3 and connect an external regenerative resistor between B1 and B2.
*2 For use only with an absolute encoder. If a backup battery is connected to CN1 I/O connector, an encoder cable with a battery is not required.
*3 Only available in Position control mode.
*4 The input function depends on control mode used (Position, speed or torque control).
*5 Wiring diagram example using the G9SX safety unit. If a safety unit is not used, keep the factory safety bypass connector installed in the CN8.

Note: The input function of pins 8,9 and 26 to 33, and output function of pins 10, 11, 34, 35, 38 and 39, can be changed via parameter settings.

Three-phase, 400 VAC (for Analog/pulse servo drives)

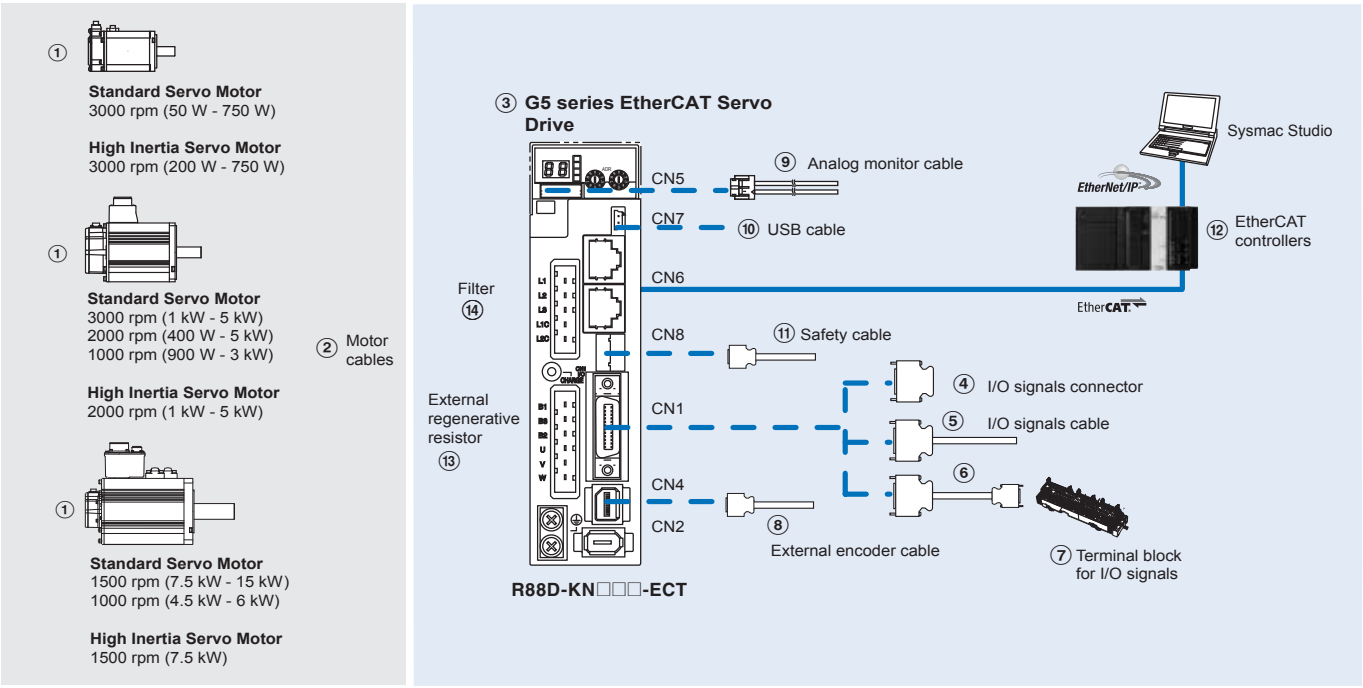


*1 Normally B2 and B3 are short-circuited. If the internal regenerative resistor is insufficient, remove the wire between B2 and B3 and connect an external regenerative resistor between B1 and B2.
*2 For use only with an absolute encoder. If a backup battery is connected to CN1 I/O connector, an encoder cable with a battery is not required.
*3 Only available in Position control mode.
*4 The input function depends on control mode used (Position, speed or torque control).
*5 Wiring diagram example using the G9SX safety unit. If a safety unit is not used, keep the factory safety bypass connector installed in the CN8.

Note: The input function of pins 8,9 and 26 to 33, and output function of pins 10, 11, 34, 35, 38 and 39, can be changed via parameter settings.

Ordering information

G5 series EtherCAT reference configuration



Note: The symbols ①②③④⑤... show the recommended sequence to select the components in G5 rotary servo system

Servo motors, power & encoder cables

Note: ①② Refer to the G5 servo motor chapter for servomotor, motor cables or connectors selection

Servo drives

Symbol	Specifications		Servo drive models	① Compatible G5 series rotary servo motors	
				Standard models	High Inertia models
③	1 phase 230 VAC	100 W	R88D-KN01H-ECT	R88M-K05030(H/T)-□	–
				R88M-K10030(H/T)-□	–
		200 W	R88D-KN02H-ECT	R88M-K20030(H/T)-□	R88M-KH20030(H/T)-□
		400 W	R88D-KN04H-ECT	R88M-K40030(H/T)-□	R88M-KH40030(H/T)-□
		750 W	R88D-KN08H-ECT	R88M-K75030(H/T)-□	R88M-KH75030(H/T)-□
		1.0 kW	R88D-KN10H-ECT	R88M-K1K020(H/T)-□	–
		1.5 kW	R88D-KN15H-ECT	R88M-K1K030(H/T)-□	–
				R88M-K1K530(H/T)-□	–
				R88M-K1K520(H/T)-□	–
				R88M-K90010(H/T)-□	–
	3 phase 400 VAC	600 W	R88D-KN06F-ECT	R88M-K40020(F/C)-□	–
				R88M-K60020(F/C)-□	–
		1.0 kW	R88D-KN10F-ECT	R88M-K75030(F/C)-□	–
				R88M-K1K020(F/C)-□	R88M-KH1K020(F/C)-□
		1.5 kW	R88D-KN15F-ECT	R88M-K1K030(F/C)-□	–
				R88M-K1K530(F/C)-□	–
				R88M-K1K520(F/C)-□	R88M-KH1K520(F/C)-□
				R88M-K90010(F/C)-□	–
		2.0 kW	R88D-KN20F-ECT	R88M-K2K030(F/C)-□	–
				R88M-K2K020(F/C)-□	R88M-KH2K020(F/C)-□
		3.0 kW	R88D-KN30F-ECT	R88M-K3K030(F/C)-□	–
				R88M-K3K020(F/C)-□	R88M-KH3K020(F/C)-□
				R88M-K2K010(F/C)-□	–
		5.0 kW	R88D-KN50F-ECT	R88M-K4K030(F/C)-□	–
				R88M-K5K030(F/C)-□	–
				R88M-K4K020(F/C)-□	R88M-KH4K020(F/C)-□
				R88M-K5K020(F/C)-□	R88M-KH5K020(F/C)-□
				R88M-K4K510C-□	–
				R88M-K3K010(F/C)-□	–
		7.5 kW	R88D-KN75F-ECT	R88M-K6K010C-□	–
				R88M-K7K515C-□	R88M-KH7K515C-□
		15 kW	R88D-KN150F-ECT	R88M-K11K015C-□	–
				R88M-K15K015C-□	–

Signals cables for I/O general purpose (CN1)

Symbol	Description	Connect to		Model
④	I/O connector kit (26 pins)	For I/O general purpose	–	R88A-CNW01C
⑤	I/O signals cable	For I/O general purpose	1 m	R88A-CPKB001S-E
			2 m	R88A-CPKB002S-E
⑥	Terminal block cable	For I/O general purpose	1 m	XW2Z-100J-B34
			2 m	XW2Z-200J-B34
⑦	Terminal block (M3 screw and for pin terminals)		–	XW2B-20G4
	Terminal block (M3.5 screw and for fork/round terminals)		–	XW2B-20G5
	Terminal block (M3 screw and for fork/round terminals)		–	XW2D-20G6

External encoder cable (CN4)

Symbol	Name		Model
⑧	External encoder cable	5 m	R88A-CRKM005SR-E
		10 m	R88A-CRKM010SR-E
		20 m	R88A-CRKM020SR-E

Analog monitor (CN5)

Symbol	Name		Model
⑨	Analog monitor cable	1 m	R88A-CMK001S

USB personal computer cable (CN7)

Symbol	Name		Model
⑩	USB mini-connector cable	2 m	AX-CUSBM002-E

Cable for safety (CN8)

Symbol	Name		Model
⑪	Safety cable	3 m	R88A-CSK003S-E

EtherCAT controllers

Symbol	Name		Model
⑫	NJ-series	CPU unit	NJ501-1500 (64 axes)
			NJ501-1400 (32 axes)
			NJ501-1300 (16 axes)
			NJ301-1200 (8 axes)
			NJ301-1100 (4 axes)
		Power supply unit	NJ-PA3001 (220 VDC)
			NJ-PD3001 (24 VDC)
	Trajexia stand-alone	Motion control unit	TJ2-MC64 (64 axes)
		EtherCAT master unit	TJ2-ECT64 (64 axes)
			TJ2-ECT16 (16 axes)
			TJ2-ECT04 (4 axes)
	Position controller unit for CJ1 PLC series		CJ1W-NCF8□ (16 axes)
			CJ1W-NC88□ (8 axes)
			CJ1W-NC48□ (4 axes)
			CJ1W-NC281(2 axes)

External regenerative resistor

Symbol	Regenerative resistor unit model	Specifications
⑬	R88A-RR08050S	50 Ω, 80 W
	R88A-RR080100S	100 Ω, 80 W
	R88A-RR22047S	47 Ω, 220 W
	R88A-RR50020S	20 Ω, 500 W

Filters

Symbol	Applicable servodrive	Filter model	Manufacturer	Rated current	Leakage current	Rated voltage
⑭	R88D-KN01H-ECT, R88D-KN02H-ECT	R88A-FIK102-RE	Rasmi Electronics Ltd	2.4 A	3.5 mA	250 VAC single-phase
	R88D-KN04H-ECT	R88A-FIK104-RE		4.1 A	3.5 mA	
	R88D-KN08H-ECT	R88A-FIK107-RE		6.6 A	3.5 mA	
	R88D-KN10H-ECT, R88D-KN15H-ECT	R88A-FIK114-RE		14.2 A	3.5 mA	
	R88D-KN06F-ECT, R88D-KN10F-ECT, R88D-KN15F-ECT	R88A-FIK304-RE		4 A	0.3 mA / 32 mA*1	400 VAC three-phase
	R88D-KN20F-ECT	R88A-FIK306-RE		6 A	0.3 mA / 32 mA*1	
	R88D-KN30F-ECT, R88D-KN50F-ECT	R88A-FIK312-RE		12.1 A	0.3 mA / 32 mA*1	
	R88D-KN75F-ECT	R88A-FIK330-RE		22 A	0.3 mA / 40 mA*1	
	R88D-KN150F-ECT	R88A-FIK350-RE		44 A	2 mA / 130 mA*1	

*1 Momentary peak leakage current for the filter at switch-on/off.

Connectors

Specifications	Model
External encoder connector (for CN4)	R88A-CNK41L
Safety I/O signal connector (for CN8)	R88A-CNK81S

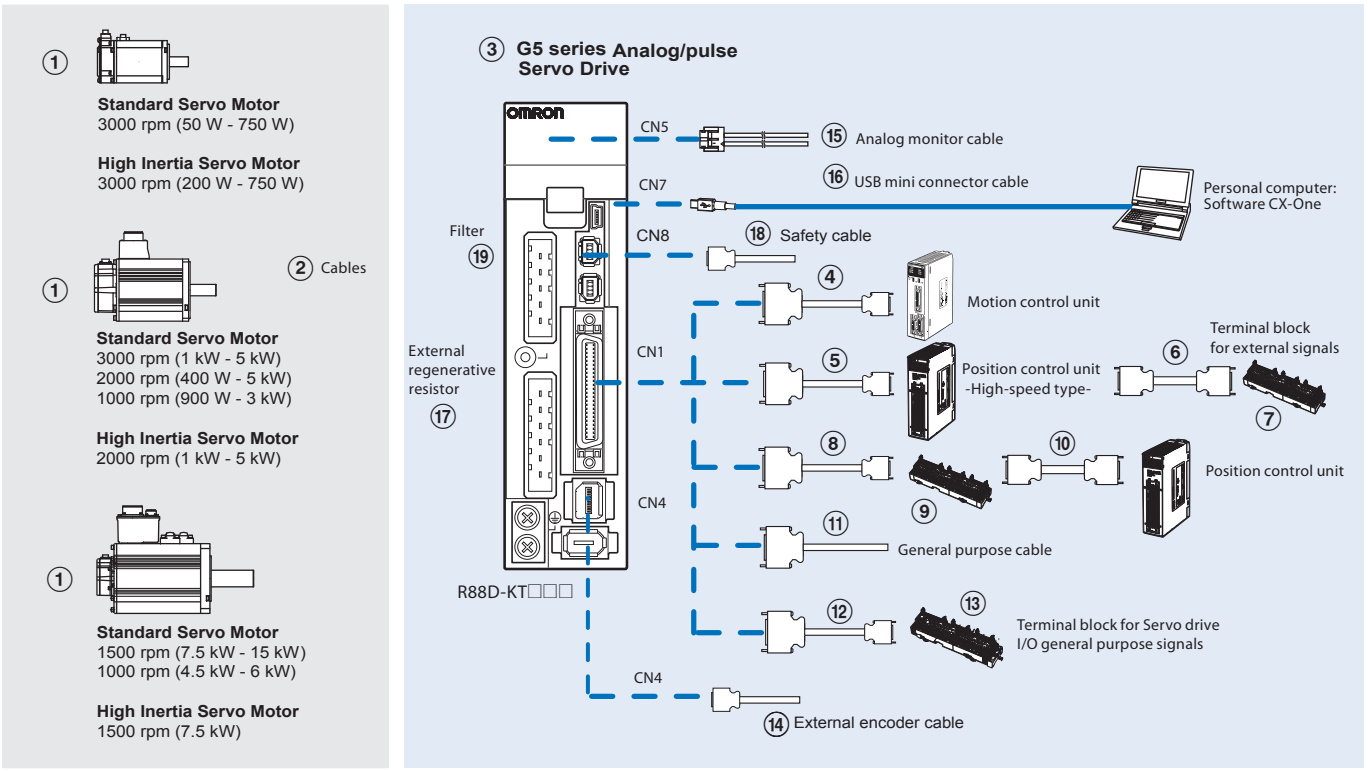
Computer software

Specifications	Model
Sysmac Studio version 1.0 or higher	SYSMAC-SE2□□□
CX-Drive version 2.10 or higher	CX-DRIVE 2.10
CX-One software package including CX-Drive 2.10 or higher	CX-ONE

Note: If CX-One is installed on the same computer as Sysmac Studio, it must be CX-One v4.2 or higher

Ordering information

G5 series Analog/pulse reference configuration



Note: The symbols ①②③④⑤... show the recommended sequence to select the components in G5 rotary servo system

Servo motors, power & encoder cables

Note: ①② Refer to the G5 rotary servo motor chapter for servomotor, motor cables or connectors selection

Servo drives

Symbol	Specifications		Servo drive models*1	① Compatible G5 series rotary servo motors	
				Standard models	High inertia models
③	1 phase 230 VAC	100 W	R88D-KT01H	R88M-K05030(H/T)-□	–
				R88M-K10030(H/T)-□	–
		200 W	R88D-KT02H	R88M-K20030(H/T)-□	R88M-KH20030(H/T)-□
		400 W	R88D-KT04H	R88M-K40030(H/T)-□	R88M-KH40030(H/T)-□
		750 W	R88D-KT08H	R88M-K75030(H/T)-□	R88M-KH75030(H/T)-□
		1.0 kW	R88D-KT10H	R88M-K1K020(H/T)-□	–
		1.5 kW	R88D-KT15H	R88M-K1K030(H/T)-□	–
				R88M-K1K530(H/T)-□	–
				R88M-K1K520(H/T)-□	–
				R88M-K90010(H/T)-□	–
	3 phase 400 VAC	600 W	R88D-KT06F	R88M-K40020(F/C)-□	–
				R88M-K60020(F/C)-□	–
		1.0 kW	R88D-KT10F	R88M-K75030(F/C)-□	–
				R88M-K1K020(F/C)-□	R88M-KH1K020(F/C)-□
		1.5 kW	R88D-KT15F	R88M-K1K030(F/C)-□	–
				R88M-K1K530(F/C)-□	–
				R88M-K1K520(F/C)-□	R88M-KH1K520(F/C)-□
				R88M-K90010(F/C)-□	–
		2.0 kW	R88D-KT20F	R88M-K2K030(F/C)-□	–
				R88M-K2K020(F/C)-□	R88M-KH2K020(F/C)-□
		3.0 kW	R88D-KT30F	R88M-K3K030(F/C)-□	–
				R88M-K3K020(F/C)-□	R88M-KH3K020(F/C)-□
				R88M-K2K010(F/C)-□	–
		5.0 kW	R88D-KT50F	R88M-K4K030(F/C)-□	–
				R88M-K5K030(F/C)-□	–
				R88M-K4K020(F/C)-□	R88M-KH4K020(F/C)-□
				R88M-K5K020(F/C)-□	R88M-KH5K020(F/C)-□
				R88M-K4K510C-□	–
				R88M-K3K010(F/C)-□	–
		7.5 kW	R88D-KT75F	R88M-K6K010C-□	–
				R88M-K7K515C-□	R88M-KH7K515C-□
		15 kW	R88D-KT150F	R88M-K11K015C-□	–
				R88M-K15K015C-□	–

*1 Drive Programming – embedded indexer functionality – is available in the G5 Analogue/pulse models with firmware 1.10 or higher.

Control cables (CN1)

Symbol	Description	Connect to		Model
④	Control cable (1 axis)	Motion control units CS1W-MC221 CS1W-MC421	1 m	R88A-CPG001M1
			2 m	R88A-CPG002M1
			3 m	R88A-CPG003M1
			5 m	R88A-CPG005M1
	Control cable (2 axes)	Motion control units CS1W-MC221 CS1W-MC421	1 m	R88A-CPG001M2
			2 m	R88A-CPG002M2
			3 m	R88A-CPG003M2
			5 m	R88A-CPG005M2
⑤	Control cable (line-driver output for 1 axis)	Position control units (high-speed type) CJ1W-NC234 CJ1W-NC434	1 m	XW2Z-100J-G9
			5 m	XW2Z-500J-G9
			10 m	XW2Z-10MJ-G9
	Control cable (open-collector output for 1 axis)	Position control units (high-speed type) CJ1W-NC214 CJ1W-NC414	1 m	XW2Z-100J-G13
			3 m	XW2Z-300J-G13
	Control cable (line-driver output for 2 axes)	Position control units (high-speed type) CJ1W-NC234 CJ1W-NC434	1 m	XW2Z-100J-G1
			5 m	XW2Z-500J-G1
			10 m	XW2Z-10MJ-G1
	Control cable (open-collector output for 2 axes)	Position control units (high-speed type) CJ1W-NC214 CJ1W-NC414	1 m	XW2Z-100J-G5
			3 m	XW2Z-300J-G5
⑥	Terminal block cable for external signals (for input common, forward/reverse run prohibited inputs, emergency stop input, origin proximity input and interrupt input)	Position control units (high-speed type) CJ1W-NC234 CJ1W-NC434 CJ1W-NC214 CJ1W-NC414	0.5 m	XW2Z-C50X
			1 m	XW2Z-100X
			2 m	XW2Z-200X
			3 m	XW2Z-300X
			5 m	XW2Z-500X
			10 m	XW2Z-010X
⑦	Terminal block for external signals (M3 screw, pin terminals)		–	XW2B-20G4
	Terminal block for ext. signals (M3.5 screw, fork/round terminals)		–	XW2B-20G5
	Terminal block for ext. signals (M3 screw, fork/round terminals)		–	XW2D-20G6
⑧	Cable from servo relay unit to servo drive	CS1W-NC1□3, CJ1W-NC1□3, C200HW-NC113, CS1W-NC2□3/4□3, CJ1W-NC2□3/4□3, C200HW-NC213/413, CQM1H-PLB21 or CQM1-CPU43	1 m	XW2Z-100J-B25
			2 m	XW2Z-200J-B25
		CJ1M-CPU21/22/23	1 m	XW2Z-100J-B31
			2 m	XW2Z-200J-B31
⑨	Servo relay unit	Position control units CS1W-NC1□3, CJ1W-NC1□3 or C200HW-NC113	–	XW2B-20J6-1B (1 axis)
		Position control units CS1W-NC2□3/4□3, CJ1W-NC2□3/4□3 or C200HW-NC213/413	–	XW2B-40J6-2B (2 axes)
		CQM1H-PLB21 or CQM1-CPU43	–	XW2B-20J6-3B (1 axis)
		CJ1M-CPU21/22/23	–	XW2B-20J6-8A (1 axis) XW2B-40J6-9A (2 axes)
⑩	Position control unit connecting cable	CQM1H-PLB21	0.5 m	XW2Z-050J-A3
			1 m	XW2Z-100J-A3
		CS1W-NC113 or C200HW-NC113	0.5 m	XW2Z-050J-A6
			1 m	XW2Z-100J-A6
		CS1W-NC213/413 or C200HW-NC213/413	0.5 m	XW2Z-050J-A7
			1 m	XW2Z-100J-A7
		CS1W-NC133	0.5 m	XW2Z-050J-A10
			1 m	XW2Z-100J-A10
		CS1W-NC233/433	0.5 m	XW2Z-050J-A11
			1 m	XW2Z-100J-A11
		CJ1W-NC113	0.5 m	XW2Z-050J-A14
			1 m	XW2Z-100J-A14
		CJ1W-NC213/413	0.5 m	XW2Z-050J-A15
			1 m	XW2Z-100J-A15
		CJ1W-NC133	0.5 m	XW2Z-050J-A18
			1 m	XW2Z-100J-A18
		CJ1W-NC233/433	0.5 m	XW2Z-050J-A19
			1 m	XW2Z-100J-A19
		CJ1M-CPU21/22/23	0.5 m	XW2Z-050J-A33
			1 m	XW2Z-100J-A33
⑪	General purpose cable	For general purpose controllers	1 m	R88A-CPG001S
			2 m	R88A-CPG002S
⑫	Terminal block cable	For general purpose controllers	1 m	XW2Z-100J-B24
			2 m	XW2Z-200J-B24
⑬	Terminal block (M3 screw and for pin terminals)		–	XW2B-50G4
	Terminal block (M3.5 screw and for fork/round terminals)		–	XW2B-50G5
	Terminal block (M3 screw and for fork/round terminals)		–	XW2D-50G6

External encoder cable (CN4)

Symbol	Name		Model
⑭	External encoder cable	5 m	R88A-CRKM005SR-E
		10 m	R88A-CRKM010SR-E
		20 m	R88A-CRKM020SR-E

Analog monitor (CN5)

Symbol	Name		Model
⑮	Analog monitor cable	1 m	R88A-CMK001S

USB personal computer cable (CN7)

Symbol	Name		Model
⑯	USB mini-connector cable	2 m	AX-CUSBM002-E

External regenerative resistor

Symbol	Regenerative resistor unit model	Specifications
⑰	R88A-RR08050S	50 Ω, 80 W
	R88A-RR080100S	100 Ω, 80 W
	R88A-RR22047S	47 Ω, 220 W
	R88A-RR50020S	20 Ω, 500 W

Cable for Safety Functions (CN8)

Symbol	Description	Model
⑱	Safety connector with 3 m cable (with loose wires at one end)	R88A-CSK003S-E

Filters

Symbol	Applicable servodrive	Filter model	Manufacturer	Rated current	Leakage current	Rated voltage
⑲	R88D-KT01H, R88D-KT02H	R88A-FIK102-RE	Rasmi Electronics Ltd	2.4 A	3.5 mA	250 VAC single-phase
	R88D-KT04H	R88A-FIK104-RE		4.1 A	3.5 mA	
	R88D-KT08H	R88A-FIK107-RE		6.6 A	3.5 mA	
	R88D-KT10H, R88D-KT15H	R88A-FIK114-RE		14.2 A	3.5 mA	
	R88D-KT06F, R88D-KT10F, R88D-KT15F	R88A-FIK304-RE		4 A	0.3 mA / 32 mA*1	400 VAC three-phase
	R88D-KT20F	R88A-FIK306-RE		6 A	0.3 mA / 32 mA*1	
	R88D-KT30F, R88D-KT50F	R88A-FIK312-RE		12.1 A	0.3 mA / 32 mA*1	
	R88D-KT75F	R88A-FIK330-RE		22 A	0.3 mA / 40 mA*1	
	R88D-KT150F	R88A-FIK350-RE		44 A	2 mA / 130 mA*1	

*1 Momentary peak leakage current for the filter at switch-on/off.

Connectors

Specifications	Model
I/O connector kit -50 pins-(for CN1)	R88A-CNU11C
External encoder connector (for CN4)	R88A-CNK41L
Safety I/O signal connector (for CN8)	R88A-CNK81S

Computer software

Specifications	Model
CX-Drive version 2.10 or higher	CX-DRIVE 2.10
CX-One software packaging including CX-Drive 2.10 or higher	CX-ONE

ALL DIMENSIONS SHOWN ARE IN MILLIMETERS.
To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.

Cat. No. I101E-EN-04A In the interest of product improvement, specifications are subject to change without notice.

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