Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

General Description

The MAX16984A combines a 5V automotive-grade stepdown converter capable of driving up to 3.0A, a USB host charger adapter emulator, and USB protection switches for automotive USB host applications. The USB protection switches provide high-ESD, short-circuit protection and feature integrated host-charger port-detection circuitry adhering to the USB 2.0 BC 1.2 Battery Charging Specification, Samsung® and Chinese Telecommunication Industry Standard YD/T 1591-2009. They also include circuitry for Samsung 2.0A, iPod®/iPhone®/iPad® 2.4A dedicated charging modes. The HVD+ and HVD- ESD protection features include protection to \pm 15kV Air/ \pm 8kV Contact on the HVD+ and HVD- outputs to the IEC 61000-4-2 model and 330 Ω , 330pF ISO model.

The high-efficiency step-down DC-DC converter operates from a voltage up to 28V and is protected from load dump transients up to 40V. The device is optimized for high-frequency operation and includes resistor-programmable frequency selection from 310kHz to 2.2MHz to allow optimization of efficiency, noise, and board space based on application requirements. The fully synchronous DC-DC converter integrates high-side and low-side MOS-FETs with an external SYNC input/output, and can be configured for spread-spectrum operation. Skip mode is available in light/no-load conditions to minimize quiescent current. The converter can deliver up to 3A of continuous current at 105°C. The MAX16984A has an integrated spreadspectrum oscillator to improve EMI performance.

The MAX16984A also includes a USB load current-sense amplifier and configurable feedback adjustment circuit designed to provide automatic USB voltage adjustment to compensate for voltage drops in captive cables associated with automotive applications. The MAX16984A limits the USB load current using both a fixed internal peak current threshold of the DC-DC converter and a user-configurable external USB load current-sense amplifier threshold.

Applications

- Automotive Radio and Navigation
- USB Port for Host and Hub Applications
- Automotive Connectivity
- Telematics
- Dedicated USB Power Charger

Benefits and Features

- Integrated DC-DC and USB Host Charge Emulator Enables 1-Chip Solution Directly from Car Battery to Portable Device
 - 4.5V to 28V (40V Load Dump) Operating Voltage
 - 5V, 3.0A Output Current Capability
 - · Low-Q Current Skip and Shutdown Modes
 - Soft-Start Reduces Inrush Current
- Low-Noise Features Prevent Interference with AM Band and Portable Devices
 - Fixed-Frequency 310kHz to 2.2MHz Operation
 - Forced-PWM Option at No Load
 - Spread Spectrum for EMI Reduction
 - SYNC Input/Output for Frequency Parking
- Optimal USB Power and Communication for Portable
 Devices
 - User-Adjustable Voltage Gain Adjusts Output Between 5V and 7V for Cable Compensation
 - ±5% Accuracy User-Adjustable USB Current Limit
 - 4Ω USB 2.0 1GHz Data Switches
 - Integrated Samsung/iPod/iPhone/iPad Charge-Detection Termination Resistors
 - Supports USB BC1.2 Charging Downstream Port (CDP) and Dedicated Charging Port (DCP) Modes
 - Supports Chinese Telecommunication Industry Standard YD/T 1591-2009
 - · Compatible with USB On-the-Go Specification
 - High-Speed Pass-Through Mode (SDP)
- Robust Design Keeps Vehicle System and Portable
 Devices Safe in Automotive Environment
 - Short-to-Battery Protection on DC-DC Converter
 - · Short-to-Battery Protection on USB Pins
 - ±15kV Air/±8kV Contact ISO 10605*
 - ±15kV Air/±8kV Contact IEC 61000-4-2*
 - ±15kV Air/±8kV Contact (330Ω, 330pF)*
 - Fault-Indication Active-Low, Open-Drain Output
 - Reduced Inrush Current with Soft-Start
 - Overtemperature Protection
 - -40°C to +125°C Operating Temperature Range
 - 32-Pin, 5mm x 5mm, TQFN Package

*Tested in Typical Application Circuit as used on the MAX16984A Evaluation Kit

<u>Ordering Information</u> and <u>Typical Application Circuit</u> appear at end of data sheet.

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Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

Simplified Block Diagram



Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

Absolute Maximum Ratings

SUPSW to PGND0.3V to +40V	Output Short-Circuit Duration	Continuous
HVEN to PGND0.3V to V _{SUPSW} + 0.3V	Thermal Characteristics	
LX to PGND (Note 1)0.3V to V _{SUPSW} + 0.3V	Continuous Power Dissipation (T _A = +70°C)	
SYNC to AGND0.3V to V _{BIAS} + 0.3V	TQFN Single-Layer Board	
SENSN, SENSP, VBMON to AGND0.3V to V _{SUPSW} + 0.3V	(derate 21.3mW/°C above +70°C)	1702.10mW
AGND to PGND0.3V to +0.3V	TQFN Multilayer Board	
BST to PGND0.3V to +46V	(derate 34.5mW/°C above +70°C)	2758.6mW
BST to LX0.3V to +6V	Operating Temperature Range	40°C to 125°C
IN, CONFIG1, ENBUCK, CONFIG2, CONFIG3, BIAS,	Junction Temperature	+150°C
DATA_MODE, FAULT, SHIELD, ATTACH to AGND-0.3V to +6V	Storage Temperature Range	40°C to +150°C
HVDP, HVDM to AGND	Lead Temperature (soldering, 10s)	300°C
DP, DM to AGND0.3V to V _{IN} + 0.3V	Soldering Temperature (reflow)	+260°C
LX Continuous RMS Current		

Note 1: Self-protected from transient voltages exceeding these limits ≤ 50ns in circuit under normal operation.

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Package Information

32-Pin TQFN

Package Code	T3255+4C					
Outline Number	<u>21-0140</u>					
Land Pattern Number	<u>90-0012</u>					
THERMAL RESISTANCE, SINGLE-LAYER BOARD						
Junction-to-Ambient (0 _{JA})	47°C/W					
Junction-to-Case Thermal Resistance (θ_{JC})	1.70°C/W					
THERMAL RESISTANCE, FOUR-LAYER BOARD						
Junction-to-Ambient (θ _{JA})	29°C/W					
Junction-to-Case Thermal Resistance (θ_{JC})	1.70°C/W					

For the latest package outline information and land patterns (footprints), go to <u>www.maximintegrated.com/packages</u>. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to <u>www.maximintegrated.com/</u> <u>thermal-tutorial</u>.

Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

Electrical Characteristics

PARAMETER	SYMBOL	CONDITIONS MIN TYP MAX		MAX	UNITS	
POWER SUPPLY AND E	NABLE					
Supply Voltage Range	V _{SUPSW}	(Note 2) 4.5 28				V
Load Dump Event Supply Voltage Range	V _{SUPSW_LD}	t < 1s	40			V
		V_{SUPSW} = 18V; V_{HVEN} = 0V; V_{IN} = 0V; V_{CONN} = 0V, Off State		10	20	μA
Supply Current	ISUPSW	HVEN = 14V; buck switching; no load; skip mode		1.8		
		HVEN = 14V; buck switching; no load; FPWM mode		28		
BIAS Voltage	V _{BIAS}	$5.75V \le V_{SUPSW} \le 28V$	4.5	4.7	5.25	V
BIAS Current Limit			50	150		mA
BIAS Undervoltage Lockout	V _{UV_BIAS}	V _{BIAS} rising	3.0	3.3	3.6	V
BIAS Undervoltage Lockout Hysteresis				0.2		V
SUPSW Undervoltage Lockout		V _{SUPSW} rising	3.9		4.42	v
SUPSW Undervoltage Lockout Hysteresis				0.2		V
IN Voltage Range	V _{IN}		3		3.6	V
IN Overvoltage Lockout	V _{IN_OVLO}	V _{IN} rising	3.8	4	4.3	V
IN Input Current	I _{IN}				10	μA
HVEN rising Threshold	V _{HVEN_R}		0.6	1.5	2.4	V
HVEN falling Threshold	V _{HVEN_} F				0.4	V
HVEN Hysteresis	V _{HVEN}			0.2		V
HVEN Delay Rising	t _{HVEN_R}		2.5		15	μs
HVEN Delay Falling	^t HVEN_F		5	12	25	μs
HVEN Input Leakage		V _{HVEN} = V _{SUPSW} = 18V, V _{HVEN} = 0V			10	μA
DP, DM ANALOG USB S	WITCHES					
On-Channel -3dB Bandwidth	BW	$R_L = R_S = 50\Omega$		1000		MHz
Analog Signal Range			0		3.6	V
Protection Trip Threshold	V _{OV_D}		3.65	3.85	4.1	V
Protection Response Time	t _{FP_D}	$ \begin{array}{l} V_{IN} = 4.0V, V_{HVD\pm} = 3.3V \text{ to } 4.3V \text{ step}, \\ R_L = 15 \mathrm{k}\Omega \text{ on } \mathrm{D} \pm, \text{delay to } V_{D\pm} < 3V \end{array} $		2		μs
On-Resistance Switch A	R _{ON_SA}	$I_{L} = 10 \text{mA}, V_{D} = 0 \text{V to } V_{\text{IN}}, V_{\text{IN}} = 3.0 \text{V}$ to 3.6V		4	8	Ω

Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

Electrical Characteristics (continued)

PARAMETER	SYMBOL	CONDITIONS	MIN	ТҮР	MAX	UNITS
On-Resistance Match between Channels Switch A	∆R _{ON_SA}	I _L = 10mA, V _D _= 1.5V or 3.0V	= 10mA, V _D = 1.5V or 3.0V 0.2		0.2	Ω
On-Resistance Flatness Switch A	R _{FLAT(ON)} A	I _L = 10mA,V _D _= 0V or 0.4V		0.01		Ω
On-Resistance of HVD+/HVD- short	R _{SHORT}	V _{DP} = 1V, I _{DM} = 500μA		90	180	Ω
HVD+/HVD- On- Leakage Current	IHVD_ON	V _{HVD±} = 3.6V or 0V	-7		+7	μA
HVD+/HVD- Off- Leakage Current	IHVD_OFF	V_{HVD+} -= 18V or V_{HVD-} = 18V, $V_{D\pm}$ = 0V			150	μA
D+/D- Off-Leakage Current	ID_OFF	V _{HVD±} = 18V, V _{D±} = 0V	-1		+1	μA
CURRENT-SENSE AMPI	LIFIER (SENSP,	SENSN) AND ANALOG INPUTS (VBMON)				
Gain		10mV < V _{SENSP} - V _{SENSN} < 110mV, GAIN[4:0] = 0b11111		19.4		V/V
Cable Compensation	R _{LSB}			18		mΩ
		CONFIG3 step = 3 or 7, $R_{SENSE} = 33m\Omega$	3.04	3.14	3.30	
Overcurrent Threshold	ILIM_SET	CONFIG3 step = 2 or 6, $R_{SENSE} = 33m\Omega$	2.6	2.6 2.75 2.9		
		CONFIG3 step = 1 or 5, $R_{SENSE} = 33m\Omega$	1.62	1.7	1.78	
		CONFIG3 step = 0 or 4, $R_{SENSE} = 33m\Omega$	0.55 0.6 0.65			
SENSN Discharge Current	ISENSN_DIS		11	18	32	mA
Startup Wait Time	^t BUCK_WAIT			100		ms
	t _{DIS_POR}	Discharge after POR		10		ms
SENSN Discharge Time	^t DIS_CD	DATA_MODE toggle (into and out of DCP mode), ENBUCK toggle		2		s
Forced Buck Off-Time	^t BUCKOFF_CD	DATA_MODE toggle (into and out of DCP mode), ENBUCK toggle; see reset criteria		2		S
Attach Comparator Load Current Rising Threshold		Common mode input = 5.15V	5	16	28	mA
Attach Comparator Hysteresis		Common mode input = 5.15V		2.5		mA
SENSN Undervoltage Threshold (Falling)	V _{UV_SENSN}		4	4.375	4.75	V
SENSN Overvoltage Threshold (Rising)	V _{OV_SENSN}		7	7.46	7.9	V
SENSN Short-Circuit Threshold (Falling)			1.75	2	2.25	V

Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

Electrical Characteristics (continued)

PARAMETER	SYMBOL	CONDITIONS	MIN	MIN TYP MAX		UNITS
SENSN Undervoltage Fault Blanking Time				16		ms
SENSN Overvoltage Fault Blanking Time	^t B,OV_SENSN	From overvoltage condition to FAULT asserted		3	6	μs
SENSN Discharge Threshold Falling		V _{SENSN} falling	0.47	0.51	0.57	V
REMOTE FEEDBACK A	DJUSTMENT					
SHIELD Input Voltage Range			0.1		0.75	V
Gain			1.935	2	2.065	V/V
Input Referred Offset Voltage				±2.0		mV
DIGITAL INPUTS (ENBU	CK, DATA_MOD	DE)				
Input Leakage Current		V _{PIN} = 5.5V, 0V	-5		+5	μA
Logic-High	V _{IH}		1.6			V
Logic-Low	VIL				0.5	V
USB 2.0 HOST CHARGE	R EMULATOR (HVD+/HVD-, D+/D-)				
Input Logic-High	VIH		2.0			V
Input Logic-Low	VIL				0.8	V
Data Sink Current	IDAT_SINK	V _{DAT_SINK} = 0.25V to 0.4V	50	100	150	μA
Data Detect Voltage High	V _{DAT_REFH}		0.4			V
Data Detect Voltage Low	V _{DAT_REFL}				0.25	V
Data Detect Voltage Hysteresis	V _{DAT_HYST}			60		mV
Data Source Voltage	V _{DAT_SRC}	I _{SRC} = 200μA	0.5		0.7	V
SYNCHRONOUS STEP-I	DOWN DC-DC C	ONVERTER				
PWM Output Voltage	V _{SENSP}	$7V \le V_{SUPSW} \le 28V$, no load		5.15		V
Skip Mode Output Voltage	V _{SENSP_SKIP}	$7V \le V_{SUPSW} \le 18V$, no load (Note 2)		5.25		V
Load Regulation		7V ≤ V _{SUPSW} ≤ 18V, for 5V nominal output setting		51		mΩ
Output Voltage Accuracy		$8V \le V_{SUPSW} \le 18V$, 2.4A, V_{SENSP} - $V_{SENSN} = 79.2mV$, GAIN[4:0] = 0b11111 cable compensation.	6.33		6.68	V
Spread-Spectrum Range		SS enabled		±3.4		%
SYNC Switching Threshold High	V _{SYNC_} HI	Rising	1.4			V

Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

Electrical Characteristics (continued)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
SYNC Switching Threshold Low	V _{SYNC_LO}	Falling			0.4	V
SYNC Internal Pulldown				200		kΩ
SYNC Input Clock Acquisition Time	^t SYNC	(Note 3)		1		Cycles
High-Side Switch On- Resistance	R _{ONH}	I _{LX} = 1A		54	95	mΩ
Low-Side Switch On- Resistance	R _{ONL}	I _{LX} = 1A		72	135	mΩ
BST Input Current	I _{BST}	V_{BST} - V_{LX} = 5V, high-side on		2.2		mA
LX Current-Limit Threshold				5		А
Skip Mode Peak Current Threshold	ISKIP_TH			1		А
Negative Current Limit				1.2		А
Soft-Start Ramp Time	t _{SS}			8		ms
LX Rise Time		(Note 3)		3		ns
LX Fall Time		(Note 3)		4		ns
BST Refresh Algorithm Low-Side Minimum On- Time				60		ns
FAULT, ATTACH, SYNC	OUTPUTS		I			
Output-High Leakage Current		FAULT, ATTACH, = 5.5V	-10		+10	μA
Output Low Level		Sinking 1mA			0.4	V
SYNC Output High Level		Sourcing 1mA, SYNC configured as output	V _{BIAS} - 0.4			V
CONFIG RESISTORS CO	NVERTER					
CONFIG1-3 Current Leakage		V _{CONFIG} = 0V to 4V			±5	μA
Minimum Window Amplitude			-4		+4	%
OSCILLATORS						
Internal High-Frequency Oscillator	HFOSC		7	8	9	MHz
Buck Oscillator Frequency	fsw	FSW = 2.2MHz	1.95	2.2	2.45	MHz
THERMAL OVERLOAD			·			
Thermal Shutdown Temperature				165		°C
Thermal Shutdown Hysteresis				10		°C

Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

Electrical Characteristics (continued)

 $(V_{SUPSW} = 14V, V_{ENBUCK} = V_{IN} = 3.3V$, temperature = $T_A = T_J = -40^{\circ}C$ to +125°C, unless otherwise noted. Typical values are $T_A = +25^{\circ}C$ under normal conditions.) (Note 3)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
ESD PROTECTION (ALL	PINS)		•			
ESD Protection Level	V _{ESD}	Human Body Model		±2		kV
ESD PROTECTION (HVD	P, HVDM)					
	V _{ESD}	ISO 10605 Air-Gap (330pF, 2kΩ)	±15			
		ISO 10605 Contact (330pF, 2kΩ)	±8			
ECD Drotaction Loval		IEC 61000-4-2 Air-Gap (150pF, 330Ω)	±15			LA) /
ESD Protection Level		IEC 61000-4-2 Contact (150pF, 330Ω)		±8		ĸv
		ISO 10605 Air-Gap (330pF, 330Ω)	±15			
		ISO 10605 Contact (330pF, 330Ω)	±8			

Note 2: Device is designed for use in applications with continuous operation of 14V. Device meets electrical table up to maximum supply voltage.

Note 3: Specification with minimum and maximum limits are 100% production tested at $T_A = 25^{\circ}C$ and are guaranteed over the operating temperature range by design and characterization. Actual typical values may vary and are not guaranteed.

Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

Typical Operating Characteristics

(T_A = +25°C, unless otherwise noted.)



















Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

Typical Operating Characteristics (continued)





Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

Typical Operating Characteristics (continued)

(T_A = +25°C, unless otherwise noted.)







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Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

Pin Configuration



Pin Description

PIN	NAME	FUNCTION
1–5	AGND	Analog Ground
6	HVDM	High-Voltage-Protected USB Differential Data D- Output. Connect HVD- to the downstream USB connector D- pin.
7	HVDP	High-Voltage-Protected USB Differential Data D+ Output. Connect HVD+ to the downstream USB connector D+ pin.
8	SHIELD	Remote feedback input, special order only. See Figure 2.
9	DP	USB Differential Data D+ Input. Connect D+ to the low-voltage USB transceiver D+ pin.
10	DM	USB Differential Data D- Input. Connect D- to the low-voltage USB transceiver D- pin.
11	IN	Logic Enable Input. Connect to I/O voltage of USB transceiver. IN is also used for clamping during overvoltage events on HVD+ or HVD Connect a 1μ F– 10μ F ceramic capacitor from IN to GND.
12	ATTACH	Functions as an active-low attach output pin. Connect a $100k\Omega$ pullup resistor to IN. Tie to AGND if not used.
13	SYNC	Switching Frequency Input/Output for Synchronization with Other DC-DC Supplies. See <u>Applications Information</u> section.
14	FAULT	Active-Low, Open-Drain Fault Indicator Output. Connect a $100k\Omega$ pullup resistor to the IN pin. Tie to AGND if not used.
15	CONFIG3	Config3 input. Connect a resistor to GND or directly to BIAS. See <u>Table 4</u> .
16	CONFIG2	Config2 input. Connect a resistor to GND or directly to BIAS. See <u>Table 4</u> .
17	DATA_MODE	Selects Between the Two Default Modes of Data Switch Operation. See <u>Table 2</u> .
18	ENBUCK	DC-DC Enable Input. Drive high/low to enable/disable the buck converter.

Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

Pin Description (continued)

PIN	NAME	FUNCTION
19	BST	High-Side Driver Supply. Connect a 0.1µF capacitor from BST to LX.
20, 21	LX	Inductor Connection. Connect an inductor from LX to the DC-DC converter output (SENSP).
22, 23	PGND	Power Ground.
24	CONFIG1	Config1 input. Connect a resistor to GND or directly to BIAS. See <u>Table 3</u> .
25	HVEN	Active-High System Enable. HVEN is battery-voltage tolerant.
26, 27	SUPSW	Internal High-Side Switch Supply Input. V _{SUPSW} provides power to the internal switch and LDO. Connect a 10 μ F ceramic capacitor in parallel with a 47 μ F electrolytic capacitor from SUPSW to PGND. See the <u>DC-DC Switching Frequency Selection</u> section.
28	VBMON	USB V _{BUS} Monitor
29	SENSP	DC-DC Converter Feedback Input and Current-Sense Amplifier Positive Input. DC-DC bulk capacitance placed here. Connect to positive terminal of current-sense resistor and the main output of the converter. Used for internal voltage regulation loop.
30	SENSN	Current-Sense Amp Negative Input. Connect to negative terminal of current sense resistor.
31	N.C.	No connection.
32	BIAS	5V Linear Regulator Output. Connect a 2.2µF ceramic capacitor from BIAS to GND. BIAS powers the internal circuitry.
	EP	Exposed Pad. Connect EP to multiple GND planes with 3 x 3 via grid (minimum).

Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

Functional Diagrams

On-Channel -3dB Bandwidth and Crosstalk



DCP Reset Behavior and Timing Diagram



Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

Functional Diagrams (continued)

ENBUCK Reset Behavior and Timing Diagram



Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

Detailed Description

The MAX16984A combines a 5V/3A automotive grade step-down converter, a USB host charger adapter emulator, and USB protection switches. It is designed for high-power USB ports in automotive radio, navigation, connectivity, and USB hub applications.

The USB protection switches provide high-ESD and short- circuit protection for the low-voltage internal data lines of the multimedia processor's USB transceiver and support USB Hi-Speed (480Mbps) and USB Full-Speed (12Mbps) pass-through operation. The MAX16984A features integrated host-charger port-detection circuitry adhering to the USB 2.0 Battery Charging Specification BC1.2 and also includes dedicated bias resistors for Samsung 2.0A/iPod/iPhone/iPad 2.4A dedicated charging modes.

The high-efficiency step-down DC-DC converter operates from a voltage up to 28V and is protected from load-dump transients up to 40V. The device includes resistor-programmable frequency selection from 310kHz to 2.2MHz to allow optimization of efficiency, noise, and board space based on the application requirements. The converter can deliver up to 3A of continuous current at 105°C.

The MAX16984A also includes a high-side current-sense amplifier and configurable feedback-adjustment circuit designed to provide automatic USB voltage adjustment to compensate for voltage drops in captive cables associated with automotive applications.



Detailed Block Diagram

Figure 1. Detailed Block Diagram

Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

Power-Up and Enabling

System Enable (HVEN)

HVEN is used as the main enable to the device and initiates system start-up and configuration. If HVEN is at a logic-low level, SUPSW power consumption is reduced and the device enters a standby, low quiescent current level. HVEN is compatible with inputs from 3.3V logic up to automotive battery.

DC-DC Enable (ENBUCK)

The buck regulator on the MAX16984A is controlled by the ENBUCK pin. The DC-DC converter is activated by driving ENBUCK high, and disabled by driving ENBUCK low. For a typical USB hub application, connect ENBUCK to the enable output of the USB hub controller. This allows the USB hub controller to enable and disable the USB power port using software commands. ENBUCK can be directly connected to the BIAS or IN pin for applications that do not require GPIO control of the DC-DC converter enable.

3.3V Input (IN)

IN is used to clamp the D+ and D- pins during an ESD or overvoltage event on the HVD+ and HVD- pins. This clamping protects the downstream USB transceiver. The presence of these clamping diodes requires that IN remain set to 3.3V at all times for USB communication to occur. The IN pin features an overvoltage lockout that disables the data switches if IN is above V_{IN}_{OVLO} . Bypass IN with a 1µF ceramic capacitor, place it close to the IN pin, and connect it to the same 3.3V supply that is shared with the multimedia processor or hub transceiver.

Linear Regulator Output (BIAS)

BIAS is the output of a 5V linear regulator that powers the internal logic and control circuitry for the device. BIAS is internally powered from SUPSW or SENSP and automatically powers up when HVEN is high and SUPSW voltage exceeds V_{UV_SUPSW} . The BIAS output contains an undervoltage lockout that keeps the internal circuitry disabled when BIAS is below V_{UV_BIAS} . The linear regulator automatically powers down when HVEN is low, and a low shutdown current mode is entered. Bypass BIAS to GND with a 2.2µF ceramic capacitor.

Power-On Sequencing

HVEN, ENBUCK, and IN do not have a power-up sequence requirement by design. However, the desired system behavior should be considered for the state of these pins at startup. The D+ and D- pins are clamped to IN, therefore IN should be set to 3.3V before any USB communication is required. It is recommended that IN is set to 3.3V before HVEN is set high. ENBUCK acts as the master disable for the DC-DC converter. If ENBUCK is low when HVEN is set high, all variants keep the buck converter in the disabled state until ENBUCK is set high.

Step-Down DC-DC Regulator

Step-Down Regulator

The MAX16984A features a current-mode, step-down converter with integrated high-side and low-side MOSFETs. The low-side MOSFET enables fixed-frequency, forced-PWM operation under light loads. The DC-DC regulator features a cycle-by-cycle current limit and intelligent transition from skip mode to forced-PWM mode that makes the device ideal for automotive applications.

Wide Input Voltage Range

The device is specified for a wide 4.5V to 28V input voltage range. SUPSW provides power to the internal BIAS linear regulator and internal power switch. Certain conditions such as cold cranking can cause the voltage at the output to drop below the programmed output voltage. Under such conditions, the device operates in a high duty-cycle mode to facilitate minimum dropout from input to output.

Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

Maximum Duty-Cycle Operation

The MAX16984A has a maximum duty cycle of 98% (typ). The IC monitors the off-time (time for which the low-side FET is on) in both PWM and skip modes for every switching cycle. Once the off-time of 150ns (typ) is detected continuously for 7.5µs, the low-side FET is forced on for 60ns (typ) every 7.5µs. The input voltage at which the device enters dropout changes depending on the input voltage, output voltage, switching frequency, load current, and design efficiency. The input voltage at which the devices enter dropout can be approximated as:

$$V_{SUPSW} = \frac{V_{OUT} + \left(I_{LOAD} \times R_{ONH}\right)}{0.98}$$

Note: The equation above does not take into account the efficiency and switching frequency but will provide a good first-order approximation. Use the R_{ONH} number from the maximum column in the <u>Electrical Characteristics</u> table.

Output Voltage (SENSP)

The device features a precision internal feedback network that is connected to SENSP and that is used to set the output voltage of the DC-DC converter. The network nominally sets the average DC-DC converter output voltage to 5.15V in forced-PWM and 5.25V in skip mode.

Soft-Start

When the DC-DC converter is enabled, the regulator soft-starts by gradually ramping up the output voltage from 0V to 5.15V over approximately 8ms. This soft-start feature reduces inrush current during startup. Soft-start is guaranteed into compliant USB loads (see the <u>USB Loads</u> section).

Reset Behavior

The MAX16984A implements a discharge function on SENSN any time that the DC-DC regulator is disabled for any reason. When the discharge function is activated, current (I_{SENSN_DIS}) is drained through a current-limited FET, and a reset timer is also started. This timer prevents the DC-DC regulator from starting up again until the timer has expired. This allows for easy compatibility with USB specifications and removes the need for long discharge algorithms to be implemented in system software. See the relevant *Functional Diagrams* for reset timer details.

Reset Criteria

The MAX16984A DC-DC converter automatically resets for all undervoltage, overvoltage, overcurrent and overtemperature fault conditions. See <u>Table 5</u> for details. This 2s timer is activated after a fault condition is removed and prevents the buck converter from switching on until the timer expires. Another internal retry timer is enabled after ENBUCK is set low, or a transition of the DATA_MODE pin (switching between a data mode and a dedicated charging mode). These conditions start an internal 2s timer that prevents the buck from switching on until the timer expires.

Switching Frequency Configuration

The DC-DC switching frequency can be referenced to an internal oscillator or from an external clock signal on the SYNC pin. The internal oscillator frequency is set from the CONFIG1 pin at startup. The internal oscillator can be programmed to four discrete values from 310kHz to 2.2MHz.

Switching Frequency Synchronization (SYNC Pin)

When the SYNC pin is configured to operate as an output, skip mode operation is disallowed, and the internal oscillator frequency is driven by the SYNC pin. This allows other devices to synchronize with the MAX16984A 180 degrees out of phase for EMI reduction.

When SYNC is configured as an input, the SYNC pin becomes a logic-level input that can be used for both operatingmode selection and frequency control. Connecting SYNC to GND or an external clock enables fixed-frequency, forced-PWM mode. Connecting SYNC to a logic-high signal allows intelligent skip-mode operation. The device can be externally synchronized to frequencies within ±20% of the programmed internal oscillator frequency.

Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

Forced-PWM Operation

In forced-PWM mode, the device maintains fixed-frequency PWM operation over all load conditions, including no-load conditions.

Intelligent Skip-Mode Operation and Attach Detection

When the SYNC pin is configured as an input, but neither a clocked signal nor a logic-low level exists on the SYNC pin, the MAX16984A operates in skip mode at very light load/no load conditions. Intelligent device attach detection is used to determine when a device is attached to the USB port. The device intelligently exits skip mode and enters forced-PWM mode when a device is attached and remains in forced-PWM mode as long as the attach signal persists. This minimizes the EMI concerns caused by automotive captive USB cables and poorly shielded consumer USB cables. The device attach event is also signaled by the ATTACH pin. The criteria for device attach detection and intelligent skip-mode operation are shown in Table 1.

Table 1. DC-DC Converter Intelligent Skip Mode Truth Table

SYNC PIN	SYNC_DIR	DATA SWITCH CHARGE DETECTION MODE	CDP ATTACH DETECTION	DCP ATTACH DETECTION	CURRENT SENSE ATTACH DETECTION	DC-DC CONVERTER OPERATION
x	OUT	x	x	x	x	Forced-PWM Mode: Continuous
0	IN	x	x	x	x	Forced-PWM Mode: Continuous
Clocked	IN	x	x	x	х	Forced-PWM Mode: Continuous
1	IN	High-Speed Pass Through (SDP) Mode	High-Speed Pass Through (SDP) Mode x x 0		Intelligent Skip Mode: No Device Attached	
1	IN	High-Speed Pass Through (SDP) Mode	High-Speed Pass Through (SDP) Mode x x 1		Forced-PWM Mode: Device Attached	
1	IN	BC1.2 Auto CDP Mode	0	x	0	Intelligent Skip Mode: No Device Attached
1	IN	BC1.2 Auto CDP Mode	1	x	x	Forced-PWM Mode: Device Attached
1	IN	BC1.2 Auto CDP Mode	x	x	1	Forced-PWM Mode: Device Attached
1	IN	2.4A Auto DCP Mode x 0 0		Intelligent Skip Mode: No Device Attached		
1	IN	2.4A Auto DCP Mode	A Auto DCP Mode x 1 x		Forced-PWM Mode: Device Attached	

Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

Table 1. DC-DC Converter Intelligent Skip Mode Truth Table (continued)

SYNC PIN	SYNC_DIR	DATA SWITCH CHARGE DETECTION MODE	CDP ATTACH DETECTION	DCP ATTACH DETECTION	CURRENT SENSE ATTACH DETECTION	DC-DC CONVERTER OPERATION
1	IN	2.4A Auto DCP Mode	x	х	1	Forced-PWM Mode: Device Attached

Spread-Spectrum Option

Spread-spectrum operation is offered to improve the EMI performance of the MAX16984A. Spread-spectrum operation is preloaded on startup from the CONFIG1 pin. The internal operating frequency modulates the switching frequency by up to $\pm 3.4\%$ relative to the internally generated operating frequency. This results in a total spread-spectrum range of 6.8%. Spread-spectrum mode is only active when operating from the internal oscillator. Spread-spectrum clock dithering is not possible when operating from an external clock.

Current Limit

The MAX16984A limits the USB load current using both a fixed internal peak current threshold of the DC-DC converter, as well as a user-programmable external DC load current-sense amplifier threshold. This allows the current limit to be adjusted between 500mA to 3A depending on the application requirements, while protecting the system in the event of a fault. Upon exceeding either the DC-DC peak or user-programmable current thresholds, the high-side FET is immediately switched off and current-limit algorithms are initiated. When the external current limit lasts for longer than 16ms, the FAULT pin asserts. Once the load current exceeds the programmed threshold, the DC-DC converter acts as a constant-current source. This may cause the output voltage to droop. If the USB current limit is detected for 16ms, and the output voltage falls below the reset threshold, the DC-DC converter resets. The DC-DC converter also resets if the internal LX peak current threshold is exceeded for four consecutive switching cycles, and the output voltage droops to less than 2.0V.

In some cases, the designer may want to increase the load to 160%, refer to USB Output Current Limit for details.

Output Short-Circuit Protection

The DC-DC converter output (SENSP, SENSN) is protected against both short-to-ground and short-to-battery conditions. If a short-to-ground or undervoltage condition is encountered, the DC-DC converter immediately resets, asserts the FAULT pin, and then reattempts soft-start after the 2s reset delay. This pattern repeats until the short circuit has been removed.

If a short-to-battery is encountered ($V_{SENSN} > V_{OV_SENSN}$), the buck converter shuts down and the FAULT pin is asserted. The buck converter stays shut down until the fault condition resolves and the 2s timer expires.

Thermal Overload Protection

Thermal-overload protection limits the total power dissipated by the device. A thermal protection circuit monitors the die temperature. If the die temperature exceeds +165°C, the device shuts down, so it can cool. Once the device has cooled by 10°C, the device is enabled again. This results in a pulsed output during continuous thermal-overload conditions, protecting the device during fault conditions. For continuous operation, do not exceed the absolute maximum junction temperature of +150°C. See the Thermal Considerations section for more information.

USB Current Limit and Output Voltage Adjustment

Current-Sense Amplifier (SENSP, SENSN)

MAX16984A features an internal USB load current-sense amplifier to monitor the DC load current delivered to the USB port. The V_{SENSE} voltage (V_{SENSP} - V_{SENSN}) is used internally to provide precision DC current-limit and voltage-compensation functionality. A 33m Ω sense resistor should be placed between SENSP and SENSN.

Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

In some cases, the designer may want to increase the load to 160%, refer to USB Output Current Limit for details.

USB DC Current Limit Configuration

The MAX16984A allows configuration of the precision DC current limit by four available current limit options by reading the CONFIG3 resistor. See <u>Table 4</u> and the <u>Applications Information</u> section for more information.

In some cases, the designer may want to increase the load to 160%, refer to USB Output Current Limit for details.

Voltage Feedback Adjustment Configuration

The MAX16984A compensates voltage drop for up to $474m\Omega$ of USB cable in typical USB charging applications. The device allows configuration by the CONFIG2 resistor, which sets GAIN[3:0], and the CONFIG3 resistor, which sets GAIN[4]. See the <u>Applications Information</u> section for more information.

In some cases, the designer may want to increase the load to 160%, refer to USB Output Current Limit for details.

Remote-Sense Feedback Adjustment

The remote-sense feature (available by custom order only) provides another option to adjust the output voltage by sensing the ground node on the USB port at the far-end of the captive cable; either with the cable shield or with an additional sensing wire. This feature automatically senses the cable resistance and adjusts the voltage compensation without changing the GAIN[4:0] setting.

The user needs to compensate the voltage drop because of the sense resistor, the load line behavior of the buck, and any difference between the V_{BUS} and GND conductors. See Figure 2 and contact the factory for support and how to order.



Figure 2. Remote Cable-Sense Diagram

USB Protection Switches and BC1.2 Host Charger Emulation

USB Protection Switches

MAX16984A provides automotive-grade ESD and shortcircuit protection for the low-voltage USB data lines of highintegration multimedia processors. HVDP/HVDM protection consists of ESD and OVP (overvoltage protection) for 1.5Mbps, 12Mbps, and 480Mbps USB transceiver applications. This is accomplished with a very low-capacitance FET in series with the D+ and D- data paths.

The MAX16984A high-voltage variant does not require an external ESD array, and protects the HVD+ and HVD pins to ± 15 kV Air-Gap/ ± 8 kV Contact Discharge with the 150pF/330 Ω IEC 61000-4-2 model and the 330pF/330 Ω model, as well as protecting up to ± 15 kV Air-Gap/ ± 8 kV Contact Discharge with the 330pF/2k Ω ISO 10605 model. The MAX16984A provides robust, automotive-grade protection while maintaining a 1GHz -3dB insertion loss. This ensures optimum eye diagram at the end of a captive cable. The HVD+ and HVD- short-circuit protection features include protection for a short to the USB +5V BUS and a short to the +18V car battery. These protection features prevent damage to the low-voltage

Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

USB transceiver when shorts occur in the vehicle harness or customer USB connector/cable. Short-to-GND protection is provided by the upstream USB transceiver.

USB Host Charger Emulator

The USB protection switches integrate the latest USB-IF Battery Charging Specification Revision 1.2 SDP, CDP and DCP circuitry, as well as 2.4A resistor bias for Apple-compliant devices. Legacy Samsung Galaxy 1.2V divider and China YD/T1591-2009 compatibility is also provided in DCP mode.

	DEVICE INPUTS		64	ер			
DEVICE SUFFIX	HVEN	IN	DATA_MODE	34	30	DATA SWITCH MODE	
Х	0	Х	Х	0	0	Off	
ATJA	1	0	Х	Invalid Mode (IN = 3.3V required for data mode)			
ATJA	1	1	0	On if CDP = 0	On if CDP = 1	BC1.2 Auto-CDP (CDP)	
ATJA	1	1	1	0	1	Auto-DCP/Apple 2.4A (DCP)	
ATJB	1	0	Х	Inv	valid mode (IN	= 3.3V required for data mode)	
ATJB	1	1	0	1	0	Hi-Speed Pass-Through (SDP)	
ATJB	1	1	1	On if CDP = 0	On if CDP = 1	BC1.2 Auto-CDP (CDP)	

Table 2. Data Switch Mode Truth Table

Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator



Figure 3. Data Switch and Charge-Detection Block Diagram

USB On-The-Go and Dual-Role Applications

The MAX16984A is fully compatible with USB on-the-go (OTG) and dual-role applications. A negotiated role swap (HNP or Apple CarPlay) requires no software interaction with the IC. When there is no negotiation before the SoC enters peripheral mode, the MAX16984A must be in Hi-Speed pass-through (SDP mode) before and during the role swap. The MAX16984AATJB/V+ defaults to SDP mode on startup if the DATA_MODE pin is logic-low. This configuration allows a role swap immediately on startup without microcontroller interaction.

Configuration (CONFIG1–CONFIG3)

The MAX16984A allows full device configuration from three resistors placed among the three CONFIG pins and GND.

CONFIG1 sets the internal oscillator switching frequency, the SYNC pin direction, and enables the DC-DC spreadspectrum mode. CONFIG2 sets the 4 LSBs of the voltage adjustment gain (GAIN[3:0]). CONFIG3 sets the USB DC current limit, and sets the MSB of voltage adjustment gain (GAIN[4]). See <u>Table 3</u> and <u>Table 4</u> CONFIG options. See the <u>Applications Information</u> section for setting selection and <u>Ordering Information</u> for variant part number information.

In some cases, the designer may want to increase the load to 160%, refer to USB Output Current Limit for details.

Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

Table 3. CONFIG1 Pin Table

RESISTANCE (typ, Ω)	STEP	SS_EN	SYNC_DIR	FSW (kHz)
Short to GND	0	ON	IN	2200
619	1	ON	IN	488
976	2	ON	IN	350
1370	3	ON	IN	310
1820	4	ON	OUT	2200
2370	5	ON	OUT	488
3090	6	ON	OUT	350
3920	7	ON	OUT	310
4990	8	OFF	IN	2200
6340	9	OFF	IN	488
8250	10	OFF	IN	350
11000	11	OFF	IN	310
15400	12	OFF	OUT	2200
23700	13	OFF	OUT	488
44200	14	OFF	OUT	350
Short to BIAS (or R > 71.5k Ω)	15	OFF	OUT	310

Table 4. CONFIG2 and CONFIG3 Pin Table

		CONFIG2	CONFIG3	
RESISTANCE (typ, Ω)	STEP	GAIN[3:0]	GAIN[4]	CURRENT LIMIT (A, min)
Short to GND	0	0000	0	0.55
619	1	0001	0	1.62
976	2	0010	0	2.60
1370	3	0011	0	3.04
1820	4	0100	1	0.55
2370	5	0101	1	1.62
3090	6	0110	1	2.60
3920	7	0111	1	3.04
4990	8	1000	X	Х
6340	9	1001	X	Х
8250	10	1010	X	Х
11000	11	1011	X	Х
15400	12	1100	X	Х
23700	13	1101	X	Х
44200	14	1110	X	Х
Short to BIAS (or R > 71.5k Ω)	15	1111	X	Х

Attach Output (ATTACH)

The MAX16984A ATTACH pin functions as an open-drain, active-low attach detection output. The ATTACH pin can be used for GPIO input to a microprocessor, or to drive an LED for attach/charge indication.

Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

Fault Detection and Diagnostics

Fault Detection

The MAX16984A features advanced device protection features with automatic fault handing and recovery. <u>Table 5</u> summarizes the conditions that generate a fault, and the actions taken by the device. For all variants, the FAULT output remains asserted as long as a fault condition persists.

Table 5. Fault Conditions

EVENT	DEBOUNCE PRIOR TO ACTION	ACTION TAKEN
Thermal Shutdown	Immediate	Assert FAULT pin, shut down DC-DC converter, open data switches. When fault resolves and 2s timer expires, release FAULT pin, close data switches and enable DC-DC converter.
IN Overvoltage	Immediate	Assert FAULT pin, shut down DC-DC converter, open data switches, and reset BC1.2. When fault resolves and 2s timer expires, release FAULT pin, close data switches and enable DC-DC converter.
HVDP/HVDM Overvoltage	Immediate	Assert FAULT pin, shut down DC-DC converter, open data switches, and reset BC1.2. When fault resolves and 2s timer expires, release FAULT pin, close data switches, enable DC-DC converter.
USB DC Overcurrent	16ms	Assert \overline{FAULT} pin after overcurrent condition persists for 16ms. When fault resolves, release FAULT pin after 2s timer.
USB DC Overcurrent and SENSN < 4.38V	16ms	Assert FAULT pin and shut down DC-DC converter after overcurrent and undervoltage condition persists for 16ms. Release FAULT pin, enable DC-DC converter once 2s timer expires after shutdown.
SENSN < 4.38V	16ms	Assert \overline{FAULT} pin after undervoltage condition persists for 16ms. When fault resolves, release \overline{FAULT} pin after 2s timer.
USB DC Overcurrent and SENSN < 2V	Immediate	Assert FAULT pin, shut down DC-DC converter and open data switches. Release FAULT pin, close data switches and enable DC-DC converter once 2s timer expires after shutdown.
LX Overcurrent for Four Consecutive Cycles and SENSN < 2V	Immediate	Assert FAULT pin, shut down DC-DC converter, and open data switches. Release FAULT pin, close data switches and enable DC-DC converter once 2s timer expires after shutdown.
SENSN Overvoltage	Immediate	Assert FAULT pin, shut down DC-DC converter, open data switches. When fault resolves and 2s timer expires, release FAULT pin, close data switches and enable DC-DC converter.

Fault Output Pin (FAULT)

The MAX16984A features an open-drain, active-low FAULT output. The MAX16984A is designed to eliminate false FAULT reporting by using an internal deglitch and fault blanking timer. This ensures FAULT is not incorrectly asserted during normal operation such as starting into high-capacitance loads. The FAULT pin can be tied directly to the over-current fault input of a hub controller or SoC.

Applications Information

Migrating from MAX16984 to MAX16984A

The MAX16984A offers several improvements compared to the original MAX16984, such as higher USB protection switch bandwidth and greater output current capability. There are, however, some notable differences between the devices that prevent drop-in replacement. In <u>Table 6</u> below, the differing pins and associated functions are summarized as a guide for migrating to the MAX16984A.

Table 6. Feature and Function Differences Between MAX16984 and MAX16984A.

MAX16984 PIN OR FUNCTION	FUNCTION DESCRIPTION	MAX16984A EQUIVALENT
SYNC pin	Synchronization input or sets FPWM/ skip-mode using internal clock source.	SYNC pin with same behavior as MAX16984 when configured as input. SYNC direction is configured via CONFIG1 resistor.
FOSC pin	Resistor-programmable switching frequency input.	Switching frequency is configured via CONFIG1 resistor.
CD0, CD1 pins	Charger detection configuration (HS pass-through/CDP/Auto-DCP)	Use of device suffix (ATJA or ATJB) combined with DATA_MODE pin enables support for HS pass-through/Auto-CDP/Auto-DCP modes.
FBPER, FBMAX, FBCAP pins	Feedback voltage percentage, feedback voltage compensation ratio and feedback compensation capacitor connections.	Voltage compensation feedback is fully integrated, external components no longer needed. Voltage compensation, measured in m Ω of cable resistance between MAX16984A and the load, is configured with the Gain setting via CONFIG2/CONFIG3 resistors.
SENSO pin	Resistor-programmable DC current- limit.	DC current-limit configured via CONFIG3 and R _{SENSE} resistors.
SUP pin	Bias regulator supply input.	No equivalent. Bias regulator for MAX16984A is supplied directly from main input (SUPSW).
ENBUCK pin	Active-high system enable, battery- voltage tolerant.	HVEN pin with same behavior as MAX16984.
Spread- spectrum	Internally generated switching frequency is modulated ±3.25% with MAX16984S device suffix.	Spread-spectrum is configured via CONFIG1 resistor.
CDP handshake	Requires active management by the USB host to toggle CD0 after a USB device begins enumeration or enters High-Speed mode.	MAX16984A implements Auto-CDP, which automatically transitions to HS pass-through mode when the device may attempt USB enumeration. No active management is necessary by the host with Auto-CDP.
Auto-DCP handshake	Auto-DCP includes USB BC1.2 DCP, Apple (1A or 2.1A) and China YD/T 1591-2009.	MAX16984A Auto-DCP adds Samsung 1.2V divider network support and replaces Apple 2.1A with Apple 2.4A divider networks.

DC-DC Switching Frequency Selection

The switching frequency (f_{SW}) for the MAX16984A is programmable through the CONFIG1 resistor.

Higher switching frequencies allow for smaller PCB area designs with lower inductor values and less output capacitance. Consequently, peak currents and I²R losses are lower at higher switching frequencies, but core losses, gate charge currents, and switching losses increase.

To avoid AM band interference, operation between 500kHz and 1.8MHz is not recommended.

Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

DC-DC Input Capacitor Selection

The input capacitor supplies the instantaneous current needs of the buck converter and reduces the peak currents drawn from the upstream power source. The input bypass capacitor is a determining factor in the input voltage ripple.

The input capacitor RMS current rating requirement (I_{IN(RMS)}) is defined by the following equation:

 $I_{IN(RMS)} = I_{LOAD} \frac{\sqrt{V_{SENSP} \times (V_{SUPSW} - V_{SENSP})}}{V_{SUPSW}}$ $I_{IN(RMS)}$ has a maximum value when the input voltage equals twice the output voltage ($V_{SUPSW} = 2 \cdot V_{SENSP}$), so $I_{IN(MAX)} = \frac{1}{2} \cdot I_{LOAD(MAX)}$. I_{LOAD} is the measured operating load current, while $I_{LOAD(MAX)}$ refers to the maximum load current.

Choose an input capacitor that exhibits less than 10°C self-heating temperature rise at the RMS input current for optimal long-term reliability.

The input voltage ripple is composed of VQ (caused by the capacitor discharge) and VESR (caused by the ESR of the capacitor). Use low-ESR ceramic capacitors with high ripple current capability at the input. Assume the contribution from the ESR and capacitor discharge is equal to 50%. Calculate the input capacitance and ESR required for a specified input voltage ripple using the following equations:

$$ESR_{IN} = \frac{\Delta V_{ESR}}{I_{LOAD(MAX)} + \frac{\Delta I_L}{2}}$$

where:

$$\Delta I_{L} = \frac{\left(V_{SUPSW} - V_{SENSP}\right) \times V_{SENSP}}{V_{SUPSW} \times f_{SW} \times L}$$

and:

$$C_{IN} = \frac{I_{LOAD(MAX)} \times D(1 - D)}{\Delta V_Q \times f_{SW}} \text{ where } D = \frac{V_{SENSP}}{V_{SUPSW}}$$

Where D is the buck converter duty cycle.

Bypass SUPSW with 0.1µF parallel to 10µF of ceramic capacitance close to the SUPSW and PGND pins. The ceramic input capacitor of a buck converter has a high $\frac{di}{dt}$, minimize the PCB current-loop area to reduce EMI. Bypass SUPSW with 47µF of bulk electrolytic capacitance to dampen line transients.

DC-DC Output Capacitor Selection

To ensure stability and compliance with USB and Apple specifications, follow the recommended output filters listed in Table 7. For proper functionality, a minimum amount of ceramic capacitance must be used, regardless of f_{SW}. Additional capacitance for lower switching frequencies can be low-ESR electrolytic types (< 0.25Ω).

DC-DC Output Inductor Selection

Three key inductor parameters must be considered when selecting an inductor: inductance value (L), inductor saturation current (I_{SAT}), and DC resistance (R_{DCR}). To select the proper inductance value, the ratio of inductor peak-to-peak AC current to DC average current (LIR) must be selected. A small LIR will reduce the RMS current in the output capacitor and results in small output ripple voltage, but this requires a larger inductor. A good compromise between size and loss is LIR = 0.35 (35%). Determine the inductor value using the equation below,

$$L = \frac{V_{SENSP} \times \left(V_{SUPSW} - V_{SENSP}\right)}{V_{SUPSW} \times f_{SW} \times I_{LOAD(MAX)} \times LIR}$$

Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

where V_{SUPSW} and V_{SENSP} are typical values (such that efficiency is optimum for nominal operating conditions). Ensure the inductor I_{SAT} is above the buck converter's cycle-by-cycle peak current limit.

Layout Considerations

Proper PCB layout is critical for robust system performance. See the MAX16984A EV kit data sheet for a recommended layout. Minimize the current-loop area and the parasitics of the DC-DC conversion circuitry to reduce EMI. The input

capacitor placement should be prioritized because in a buck converter the ceramic input capacitor has high $\frac{di}{dt}$.

Place the input capacitor, power inductor, and output capacitor as close as possible to the IC SUPSW and PGND pins. Shorter traces should be prioritized over wider traces.

A low-impedance ground connection between the input and output capacitor is required (route through the ground pour on the exposed pad). Connect the exposed pad to ground. Place multiple vias in the pad to connect to all other ground layers for proper heat dissipation. Failure to do so can result in the IC repeatedly reaching thermal shutdown. Do not use separate power and analog ground planes. Instead, use a single common ground and manage currents through component placement. High-frequency return current flows through the path of least impedance (through the ground pour directly underneath the corresponding traces).

USB traces must be routed as a 90Ω differential pair with an appropriate keep-out area. Avoid routing USB traces near clocks and high-frequency switching nodes. The length of the routing should be minimized and avoid 90° turns, excessive vias, and RF stubs.

Determining USB System Requirements

The nominal cable resistance (with tolerance) for both the USB power wire (BUS) and return GND should be determined from the cable manufacturer. In addition, be sure to include the resistance from any inline or PCB connectors. Determine the desired operating temperature range for the application, and consider the change in resistance over temperature.

A typical application presents a $200m\Omega$ BUS resistance with a matching $200m\Omega$ resistance in the ground path. In this application, the voltage drop at the far end of the captive cable is 800mV when the load current is 2A. This voltage drop requires the voltage-adjustment circuitry of the ICs to increase the output voltage to comply with the USB and Apple specifications.

USB Loads

The MAX16984A is compatible with both USB-compliant and non-compliant loads. A compliant USB device is not allowed to sink more then 30mA and must not present more than 10μ F of capacitance when initially attached to the port. The device then begins its D+/D- connection and enumeration process. After completion of the connect process, the device can pull 100mA/150mA and must not present a capacitance > 10μ F. This is considered the hot-inserted, USB-compliant load of 44Ω || 10μ F.

For non-compliant USB loads, the ICs can also support both hot insertion and soft-start into a USB load of 2Ω||330μF.

Table 7. Recommended Output Filters For ILOAD of 3A

f _{SW} (kHz)	L _{OUT} (μΗ)	RECOMMENDED C _{OUT}
2200	1.5	22µF ceramic
488	8.2	3 x 22µF ceramic
488	8.2	22μ F ceramic + low-ESR 68μ F electrolytic (< 0.25Ω)
310	20	22μ F ceramic + low-ESR 68μ F electrolytic (< 0.25Ω)

USB Output Current Limit

The USB load current is monitored by an internal current-sense amplifier through the voltage created across R_{SENSE} . MAX16984A offers a digitally adjustable USB current-limit threshold. See <u>Table 4</u> to select an appropriate resistor value for the desired current limit.

Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

Some systems require the need to supply up to 160% of $I_{LOAD(MAX)}$ for brief periods. It is possible to increase the MAX16984A current limit beyond 3.04A (min) by decreasing R_{SENSE} using this scaling factor:

 $R_{\text{SENSE}} = 33 \text{m}\Omega \cdot \frac{3.04A}{1.6 \cdot I_{LOAD(MAX)}}$

USB Voltage Adjustment

<u>Figure 4</u> shows a DC model of the voltage-correction function of MAX16984A. Without voltage adjustment ($V_{ADJ} = 0$, GAIN[4:0] = 0), the voltage seen by the device at the end of the cable will decrease linearly as load current increases. To compensate for this, the output voltage of the buck converter should increase linearly with load current. The slope

of SENSP is called R_{COMP} such that $V_{ADJ} = R_{COMP} \cdot I_{LOAD}$ and $R_{COMP} = GAIN[4:0] \cdot R_{LSB} \cdot \frac{R_{SENSE}}{33m\Omega}$ (see Figure 5). The R_{COMP} adjustment values available on MAX16984A are listed in the GAIN[4:0] register description and are based on a 33m Ω sense resistor.

For $V_{DUT} = V_{NO_LOAD}$; $0 \le I_{LOAD}$, R_{COMP} must equal the sum of the system resistances. Calculate the minimum R_{COMP} for the system so that V_{DUT} stays constant:

 R_{COMP} SYS = $R_{LR} + R_{SENSE} + R_{PCB} + R_{CABLE}$ VBUS + R_{CABLE} GND

Where $R_{CABLE_VBUS} + R_{CABLE_GND}$ is the round-trip resistance of the USB cable (including the effect from the cable shield, if it conducts current), R_{LR} is the buck converter's load regulation expressed in m Ω (51m Ω typ.), and R_{PCB} is the resistance of any additional V_{BUS} parasitics (the V_{BUS} FET, PCB trace, ferrites, and the USB connectors). Find the setting for GAIN[4:0] using the minimum R_{COMP} .

 $\text{GAIN[4:0]} = ceiling \left(\frac{R_{COMP} \text{_}SYS}{R_{LSB}} \cdot \frac{33m\Omega}{R_{SENSE}} \right)$

The nominal DUT voltage can then be estimated at any load current by:

 $V_{DUT} = V_{NO_LOAD} + R_{LSB} \cdot GAIN[4:0] \cdot \frac{R_{SENSE}}{33m\Omega} \cdot I_{LOAD} - R_{COMP_SYS} \cdot I_{LOAD}$



Figure 4. DC Voltage Adjustment Model

Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator



Figure 5. Increase in SENSP vs. USB Current

Tuning of USB Data Lines

USB Hi-Speed mode requires careful PCB layout with 90Ω controlled differential impedance, with matched traces of equal length, and with no stubs or test points. The MAX16984A includes highbandwidth USB data switches (> 1GHz). This means data-line tuning may not be required. However, all designs are recommended to include pads that would allow LC components to be mounted on the data lines so that tuning can easily be performed later, if necessary. Tuning components should be placed as close as possible to the IC data pins, on the same layer of the PCB as the IC. The proper configuration of the tuning components is shown in Figure 6. Figure 7 shows the reference eye diagram used in the test setup. Figure 8 shows the MAX16984A high-voltage eye diagram on the standard EVKIT with no tuning components. Tuning inductors should be high-Q wire-wound inductors. Contact Maxim's application team for assistance with the tuning process for your specific application.



Figure 6. Tuning of Data Lines

Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator



Figure 7. Near-Eye Diagram (with No Switch)



Figure 8. Untuned Near-Eye Diagram (with MAX16984A)

USB Data Line Common-Mode Choke Placement

Most automotive applications use a USB-optimized common-mode choke to mitigate EMI signals from both leaving and entering the module. Optimal placement for this EMI choke is at the module's USB connector. This common-mode choke does not replace the need for the tuning inductors previously mentioned.

ESD Protection

The high-voltage MAX16984A requires no external ESD protection. All Maxim devices incorporate structures to protect against electrostatic discharges encountered during handling and assembly. While competing solutions can latch up and require cycling to resume operation after an ESD

event, the MAX16984A does not latch up after ESD events. When used with the configuration shown in the *Typical Application Circuit*, the MAX16984A is characterized for protection to the following limits:

- ±15kV ISO 10605 (330pF, 2kΩ) Air-Gap
- ±8kV ISO 10605 (330pF, 2kΩ) Contact
- ±15kV IEC 61000-4-2 (150pF, 330Ω) Air-Gap

Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

- ±8kV IEC 61000-4-2 (150pF, 330Ω) Contact
- ±15kV ISO 10605 (330pF, 330Ω) Air Gap
- ±8kV ISO 10605 (330pF, 330Ω) Contact

Note: All application-level ESD testing is performed on the standard evaluation kit.

ESD Test Conditions

ESD performance depends on a variety of conditions. Contact Maxim for test setup, test methodology, and test results.

Human Body Model

<u>Figure 9</u> shows the Human Body Model, and <u>Figure 11</u> shows the current waveform it generates when discharged into a low impedance. This model consists of a 100pF capacitor charged to the ESD voltage of interest, which is then discharged into the device through a $1.5k\Omega$ resistor.

IEC 61000-4-2

The IEC 61000-4-2 standard covers ESD testing and performance of finished equipment. MAX16984A helps users design equipment that meets Level 4 of IEC 61000-4-2. The main difference between tests done using the Human Body Model and IEC 61000-4-2 is a higher peak current in IEC 61000-4-2. Because the series resistance is lower in the IEC 61000-4-2 ESD test model (Figure 10), the ESD withstand-voltage measured to this standard is generally lower than that measured using the Human Body Model Figure 12 shows the current waveform for the 8kV, IEC 61000-4-2 Level 4 ESD Contact Discharge test. The Air-Gap Discharge test involves approaching the device with a charged probe. The Contact Discharge method requires connecting the probe to the device before the probe is energized.



Figure 9. Human Body ESD Test Model



Figure 10. IEC 61000-4-2 ESD Test Model

Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator



Figure 11. Human Body Current Waveform



Figure 12. IEC 61000-4-2 Current Waveform

Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

Typical Application Circuit



Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

Ordering Information

PART NUMBER	TEMP RANGE	PIN-PACKAGE	STARTUP MODE (DATA_MODE PIN = 0)	
MAX16984AATJA/V+	-40°C to +125°C	32 TQFN-EP*	Auto-CDP	
MAX16984AATJB/V+			SDP Mode	

/V Denotes automotive qualified parts.

+ Denotes a lead(Pb)-free/RoHS-compliant package.

*EP = Exposed pad.

Automotive High-Current Step-Down Converter with USB Protection/Host Charger Adapter Emulator

Revision History

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	2/20	Initial release	—
1	6/20	Updated Benefits and Features, Absolute Maximum Ratings, Package Information, Electrical Characteristics, Typical Operating Characteristics, Pin Descriptions, Detailed Description, Applications Information, and Ordering Information.	1, 2, 3, 5, 6, 10, 12, 15–23, 26, 30
2	12/20	Updated Benefits and Features, Electrical Characteristics, Detailed Description, and Applications Information	1, 5, 6, 18–26, 28–33

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