

# MCP120/130

# Microcontroller Supervisory Circuit with Open Drain Output

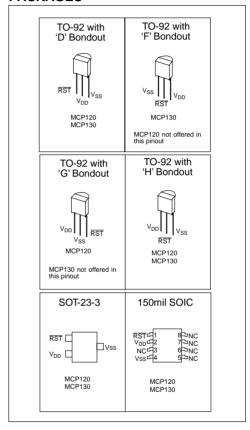
# **FEATURES**

- Holds microcontroller in reset until supply voltage reaches stable operating level
- · Resets microcontroller during power loss
- · Precision monitoring of 3V, 3.3V, and 5V systems
- 7 voltage trip points available
- Active low RESET pin
- · Open drain output
- Internal pullup resistor (5KΩ) for MCP130
- Holds RESET for 350 ms (typical)
- Guaranteed RESET to V<sub>CC</sub> = 1.0V
- Accuracy of ±125mV for 5V systems and ±75mV for 3V systems over temperature
- 45 µA typical operating current
- · Temperature range:
  - Industrial (I): -40°C to +85°C

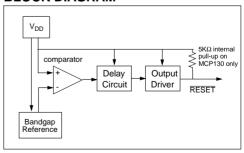
# **DESCRIPTION**

The Microchip Technology Inc. MCP120/130 is a voltage supervisory device designed to keep a microcontroller in reset until the system voltage has reached the proper level and stabilized. It also operates as protection from brown-out conditions when the supply voltage drops below a safe operating level. Both devices are available with a choice of seven different trip voltages and both have open drain outputs. The MCP130 has an internal  $5\mathrm{K}\Omega$  pullup resistor. Both devices have active low RESET pins. The MCP120/130 will assert the RESET signal whenever the voltage on the  $\mathrm{V}_{\mathrm{DD}}$  pin is below the trip-point voltage.

## **PACKAGES**



### **BLOCK DIAGRAM**



# 1.0 ELECTRICAL CHARACTERISTICS

# 1.1 Maximum Ratings\*

V <sub>DD</sub>	7 0\/
All inputs and outputs w.r.t. V <sub>SS</sub> 0.6V to V <sub>DD</sub>	
Storage temperature65°C to -	
Ambient temp. with power applied65°C to	
Soldering temperature of leads (10 seconds)	
ESD protection on all pine	> 2 1/1

\*Notice: Stresses above those listed under "Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operational listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

# DC AND AC CHARACTERISTICS

All parameters apply at the specified temp and voltage ranges unless otherwise noted.		V <sub>DD</sub> = 1.0 - 5.5V Industrial (I):-40°C to +85°C					
PARAMETER		SYMBOL	MIN	TYP	MAX	UNITS	TEST CONDITIONS
Operating Voltage Range		V <sub>DD</sub>	1.0		5.5	V	
V <sub>DD</sub> Value to Guarantee RESET		V <sub>DDMIN</sub>	1.0			V	
Operating Current		I <sub>DD</sub>		45	60	μA	V <sub>DD</sub> = 5.5V (no load)
V <sub>DD</sub> Trip Point	MCP1X0-270 MCP1X0-300 MCP1X0-315 MCP1X0-450 MCP1X0-460 MCP1X0-475 MCP1X0-485	$V_{TRIP}$	2.55 2.85 3.0 4.25 4.35 4.50 4.60	2.625 2.925 3.075 4.375 4.475 4.625 4.725	2.7 3.0 3.15 4.50 4.60 4.75 4.85	V	
RESET Low Level Output Voltage	MCP1X0-270 MCP1X0-300 MCP1X0-315				0.4	V	$I_{OL} = 3.2 \text{mA},$ $V_{DD} = V_{TRIPMIN}$
	MCP1X0-450 MCP1X0-460 MCP1X0-475 MCP1X0-485	V <sub>OL</sub>			0.6		$I_{OL} = 8.5$ mA, $V_{DD} = V_{TRIPMIN}$
RESET High Level Output Voltage (MCP130 Only)	MCP130-XXX (All V <sub>TRIP</sub> Points)	V <sub>OH</sub>	V <sub>DD</sub> -0.7			V	$I_{OH} = 50\mu A, V_{DD} > V_{TRIPMAX}$
Pullup Resistor (MCP130 Only)				5		kΩ	
Output Leakage (MCP120 Only)				1		μΑ	
Threshold Hysteresis		V <sub>HYS</sub>		50		mV	
V <sub>DD</sub> Detect to RESET Inactive		t <sub>RPU</sub>	150	350	700	ms	
V <sub>DD</sub> Detect to RESET		t <sub>RPD</sub>		10		μs	V <sub>DD</sub> ramped from V <sub>TRIPMAX</sub> + 250mV down to V <sub>TRIPMIN</sub> - 250mV
Note: Typica	al values are for 2	5°C and V <sub>DI</sub>	o = 5.0V			<u> </u>	

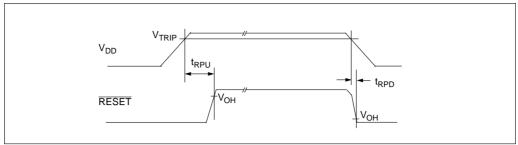


FIGURE 1: MCP120/130 Timing Diagram

# 2.0 APPLICATIONS INFORMATION

# 2.1 The Need for Supervisory Circuits

For many of today's microcontroller applications, care must be taken to prevent low power conditions that can cause many different system problems. The most common causes are brown-out conditions where the system supply drops below the operating level momentarily, and the second, is when a slowly decaying power supply causes the microcontroller to begin executing instructions without enough voltage to sustain SRAM and producing indeterminate results.

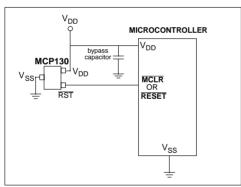


FIGURE 2-1: Typical Application

# 2.2 Negative Going V<sub>DD</sub> Transients

Many system designers implementing POR circuits are concerned about the minimum pulse width required to cause a reset. Figure 2-2 shows typical transient voltage below the trip point (V<sub>TRIP</sub> - V<sub>DD</sub>) vs. transient duration. It shows that the farther below the trip point the transient pulse goes, the duration of the pulse required to cause a reset gets shorter. A 0.1  $\mu F$  bypass cap mounted as close as possible to the V<sub>DD</sub> pin provides additional transient immunity.

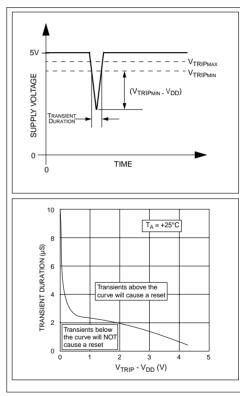


FIGURE 2-2: Typical Transient Response

# 2.3 <u>Effect of Temperature on Timeout</u> <u>Period</u> (t<sub>RPU</sub>)

The timeout period ( $t_{RPU}$ ) determines how long the device remains in the reset condition. This is controlled by an internal RC timer and is effected by both  $V_{DD}$  and temperature. The graph shown in Figure 2-3 shows typical response for different  $V_{DD}$  values and temperatures.

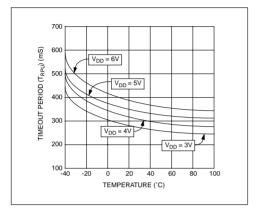


FIGURE 2-3: t<sub>RPU</sub> vs. Temperature

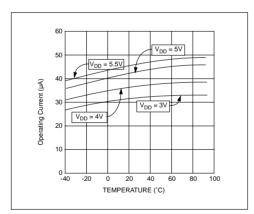


FIGURE 2-4: IDD vs. Temperature

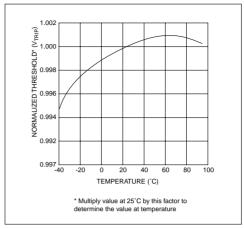


FIGURE 2-5: Normalized V<sub>TRIP</sub> vs. Temperature

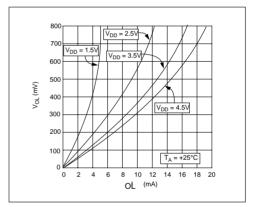


FIGURE 2-6: V<sub>OL</sub> vs. I<sub>OL</sub>

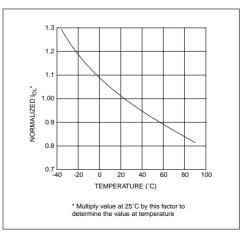
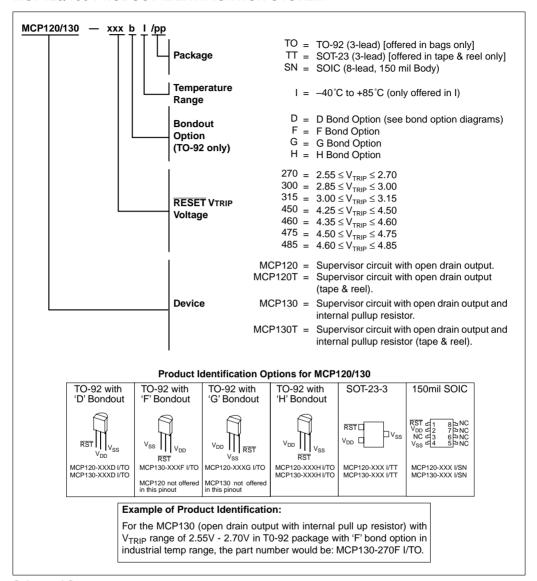


FIGURE 2-7: Normalized I<sub>OL</sub> vs. Temperature

## MCP120/130 PRODUCT IDENTIFICATION SYSTEM



## Sales and Support

#### Data Sheets

Products supported by a preliminary Data Sheet may have an errata sheet describing minor operational differences and recommended workarounds. To determine if an errata sheet exists for a particular device, please contact one of the following:

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Please specify which device, revision of silicon and Data Sheet (include Literature #) you are using.

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### **AMERICAS**

#### Corporate Office

Microchip Technology Inc. 2355 West Chandler Blvd. Chandler, AZ 85224-6199 Tel: 602-786-7200 Fax: 602-786-7277 Technical Support: 602 786-7627 Web: http://www.microchip.com

#### Atlanta

Microchip Technology Inc. 500 Sugar Mill Road, Suite 200B Atlanta, GA 30350 Tel: 770-640-0034 Fax: 770-640-0307

#### **Boston**

Microchip Technology Inc. 5 Mount Royal Avenue Marlborough, MA 01752 Tel: 508-480-9990 Fax: 508-480-8575

#### Chicago

Microchip Technology Inc. 333 Pierce Road, Suite 180 Itasca, IL 60143 Tel: 630-285-0071 Fax: 630-285-0075

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Microchip Technology Inc. Two Prestige Place, Suite 150 Miamisburg, OH 45342 Tel: 937-291-1654 Fax: 937-291-9175

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#### Los Angeles

Microchip Technology Inc. 18201 Von Karman, Suite 1090 Irvine, CA 92612 Tel: 714-263-1888 Fax: 714-263-1338

#### **New York**

Microchip Technology Inc. 150 Motor Parkway, Suite 202 Hauppauge, NY 11788 Tel: 516-273-5305 Fax: 516-273-5335

# AMERICAS (continued)

#### Toronto

Microchip Technology Inc. 5925 Airport Road, Suite 200 Mississauga, Ontario L4V 1W1, Canada Tel: 905-405-6279 Fax: 905-405-6253

Microchip Technology Inc. 2107 North First Street, Suite 590 San Jose, CA 95131 Tel: 408-436-7950 Fax: 408-436-7955

## ASIA/PACIFIC

#### Hong Kong

Microchip Asia Pacific RM 3801B, Tower Two Metroplaza 223 Hing Fong Road

Microchip Technology Inc.

Kwai Fong, N.T., Hong Kong Tel: 852-2-401-1200 Fax: 852-2-401-3431

India Liaison Office No. 6, Legacy, Convent Road Bangalore 560 025, India Tel: 91-80-229-0061 Fax: 91-80-229-0062

#### Japan

Microchip Technology Intl. Inc. Benex S-1 6F 3-18-20, Shinyokohama Kohoku-Ku, Yokohama-shi Kanagawa 222-0033 Japan Tel: 81-45-471- 6166 Fax: 81-45-471-6122

#### Korea

Microchip Technology Korea 168-1, Youngbo Bldg. 3 Floor Samsung-Dong, Kangnam-Ku Seoul, Korea Tel: 82-2-554-7200 Fax: 82-2-558-5934

### Shanghai

Microchip Technology RM 406 Shanghai Golden Bridge Bldg. 2077 Yan'an Road West, Hong Qiao District Shanghai, PRC 200335 Tel: 86-21-6275-5700 Fax: 86 21-6275-5060

# ASIA/PACIFIC (continued)

#### Singapore

Microchip Technology Singapore Pte Ltd. 200 Middle Road #07-02 Prime Centre Singapore 188980 Tel: 65-334-8870 Fax: 65-334-8850

#### Taiwan, R.O.C

Microchip Technology Taiwan 10F-1C 207 Tung Hua North Road Taipei, Taiwan, ROC Tel: 886-2-2717-7175 Fax: 886-2-2545-0139

# **EUROPE**

#### **United Kingdom**

Arizona Microchip Technology Ltd. 505 Eskdale Road Winnersh Triangle Wokingham Berkshire, England RG41 5TU Tel: 44-1189-21-5858 Fax: 44-1189-21-5835

Arizona Microchip Technology SARL Zone Industrielle de la Bonde 2 Rue du Buisson aux Fraises 91300 Massy, France Tel: 33-1-69-53-63-20 Fax: 33-1-69-30-90-79

#### Germany

Arizona Microchip Technology GmbH Gustav-Heinemann-Ring 125 D-81739 München, Germany Tel: 49-89-627-144 0 Fax: 49-89-627-144-44

# Italy

Arizona Microchip Technology SRL Centro Direzionale Colleoni Palazzo Taurus 1 V. Le Colleoni 1 20041 Agrate Brianza Milan, Italy Tel: 39-39-6899939 Fax: 39-39-6899883

9/29/98

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