Mini slide units EGSS-BS

This product is also available as a modular mechanical system
Mini slide EGSC-BS

NEW

Key features

At a glance
Plug and work with the Simplified Motion Series

IO-Link

The simplicity of pneumatics is now combined for the first time with the advantages of electric automation thanks to the Simplified Motion Series.
These integrated drives are the perfect solution for all users who are looking for an electric alternative for very simple movement and positioning tasks between two mechanical end positions, but don't want the commissioning process for traditional electric drive systems that can often be quite complex.

There is no need for any software since operation is simply based on the "plug and work" principle. Digital I/O (DIO) and IO-Link are always automatically included – a product with two types of control as standard.

Integrated

The integrated electronics in the drive are at the heart of the Simplified Motion Series.

Easy

For commissioning, simply set all relevant parameters directly on the drive:
- Speed and force
- Reference end position and cushioning
- Manual operation

Standardised

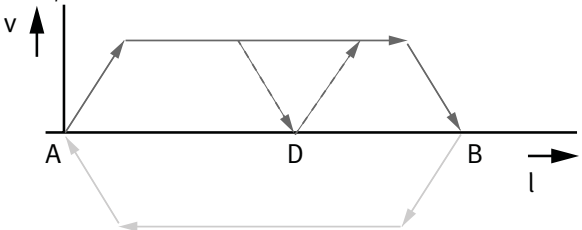
Electrical connection via
M12 plug design
- Power (4-pin): power supply for the motor
- Logic (8-pin): control signal, sensor signal and power for the integrated electronics

Connected

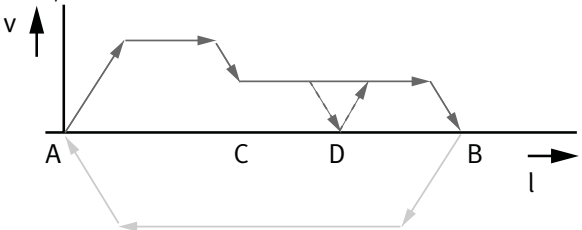
Use of extended functions possible via IO-Link:
- Remote configuration of motion parameters
- Copy and backup function for transferring parameters
- Read function for extended process parameters
- Freely definable intermediate position
- Firmware update

The functions of the Simplified Motion Series

Basic profile for movement between two end positions:
with speed control



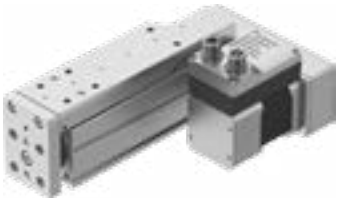
Extended motion profile for simplified press-fitting and clamping functions:
with speed and force control



- These drives are designed for simple movements between two end positions.
- Proximity switches are required in order to implement any intermediate positions.
- With the intermediate position that can be freely configured via IO-Link, movements can be stopped at a freely defined point between the end positions, without the need for proximity switches or external stops

Key features

At a glance



- Without external servo drive: all the necessary electronic components are combined in the integrated drive
- Two control options integrated as standard: digital I/O and IO-Link
- Complete solution for simple movements between mechanical end positions
- Simplified commissioning: all parameters can be manually set directly on the drive
- No special expertise required for commissioning
- End-position feedback similar to that of a conventional proximity switch is integrated as standard
- Very high-quality ball screw with low internal friction
- Rigid, high load-bearing and precise linear guide for absorbing lateral forces and increased anti-twist protection

The products in the Simplified Motion Series

Electric cylinder unit
EPCE

Electric cylinder unit
EPCS

Electric cylinder unit with parallel motor mounting
EPCS

Mini slide unit
EGSS-BS-KF

Mini slide unit with parallel motor mounting
EGSS-BS-KF

Spindle axis unit
ELGS-BS-KF

Spindle axis unit with parallel motor mounting
ELGS-BS-KF

Toothed belt axis unit
ELGS-TB-KF

Toothed belt axis unit
ELGE

Rotary drive unit
ERMS

Modular and flexible with motor, motor mounting kit and servo drive

This product is also available as a modular mechanical system as spindle axis EGSC-BS:

When compact dimensions and optimised installation space are important, e.g. for assembly systems, test and inspection systems, small parts handling, the electronics industry and desktop applications. Either as an individual axis or as a handling system.

- Compact: optimum ratio of installation space to working space
- Unique: "one-size-down" mounting system
- Modular: individual combinations with motor, motor mounting kit and servo drive
- Flexible: wide range of mounting options for optimum machine integration

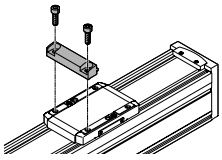
Key features

Combination matrix between axis ELGC-TB/ELGS-TB, ELGC-BS/ELGS-BS, mini slide EGSC-BS/EGSS-BS, electric cylinder EPCC-BS/EPCS-BS and guide axis ELFC

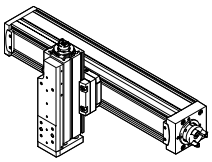
Mounting options with profile mounting and with angle kit

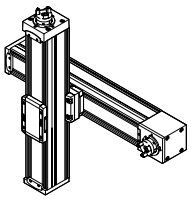
		Assembly axis ELGC-BS/-TB; ELFC; EGSC-BS; EPCC-BS; ELGS-BS/-TB; EGSS-BS, EPCS-BS			
	Size	25	32	45	60
Base axis ELGC-BS/-TB; ELFC; ELGS-BS/-TB	32	■	–	–	–
	45	–	■	–	–
	60	–	–	■	–
	80	–	–	–	■

With profile mounting EAHF-L2-...-P-D...

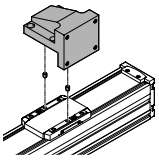


- Mounting option: base axis with one-size-down assembly axis

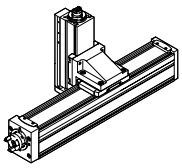


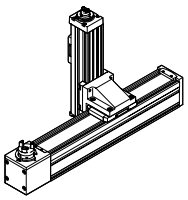


With angle kit EHAA-D-L2-...-AP



- Mounting option: base axis rotated through 90° with one-size-down assembly axis





Key features

Combination matrix between axis ELGC-TB/ELGS-TB, ELGC-BS/ELGS-BS, mini slide EGSC-BS/EGSS-BS, electric cylinder EPCC-BS/EPCS-BS and guide axis ELFC

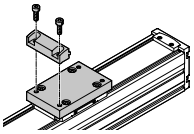
Mounting options with adapter kit or direct fastening

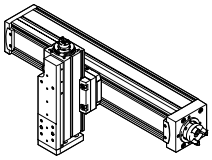
		Assembly axis ELGC-BS/-TB; ELFC; EGSC-BS; EPCC-BS; ELGS-BS/-TB; EGSS-BS, EPCS-BS				
	Size	25	32	45	60	80
Base axis ELGC-BS/-TB; ELFC; ELGS-BS/-TB	32	■		–	–	–
	45	–	■		–	–
	60	–	–	■		–
	80	–	–	–	■	

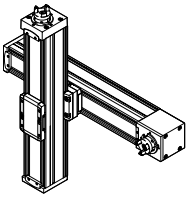
		Assembly axis EGSC-BS; EGSS-BS			
	Size	25	32	45	60
Base axis EGSC-BS; EGSS-BS	25	■	–	–	–
	32	–	■	–	–
	45	–	–	■	–
	60	–	–	–	■

With adapter kit EHAA-D-L2

- Mounting option: base axis with the same size assembly axis
- Mounting option: base axis with height compensation for one-size-down assembly axis
- When motors are mounted using parallel kits, this may lead to interfering contours. In this case, the adapter plate is required for height compensation

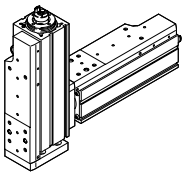






With direct mounting

- Mounting option: base axis with the same size assembly axis

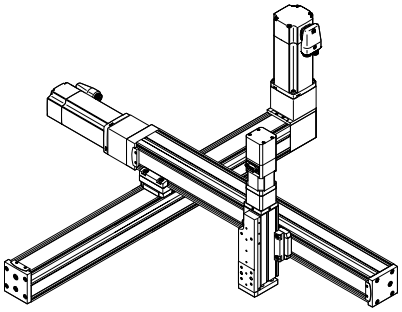


Key features

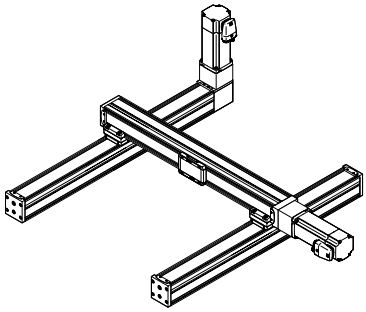
Typical handling systems

For applications where compact dimensions are essential, the axes ELGC can be combined into very space-saving handling systems that are suitable for assembly systems, test and inspection systems, small parts handling, the electronics industry and desktop applications. Combining the very compact linear axes ELGC, mini slide EGSC and electric cylinder EPCC offers an optimum ratio of installation space to working space. These feature a common system approach and platform architecture and the connections are largely adapterless.

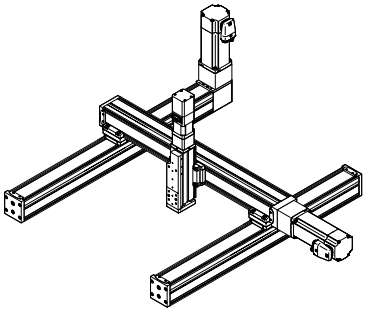
Cantilever system



Planar surface gantry



Three dimensional gantry



Type codes

001	Series	
EGSS	Electric slide drive	

002	Drive system	
BS	Ball screw drive	

003	Guide	
KF	Recirculating ball bearing guide	

004	Size	
32	32	
45	45	
60	60	

005	Stroke [mm]	
25	25	
50	50	
75	75	
100	100	
125	125	
150	150	
200	200	

006	Spindle pitch	
8P	8 mm	
10P	10 mm	
12P	12 mm	

007	Motor type	
ST	Stepper motor ST	

008	Controller	
M	Integrated	

009	Control panel	
H1	Integrated	

010	Bus protocol/activation	
PLK	PNP and IO-Link®	
NLK	NPN and IO-Link®	

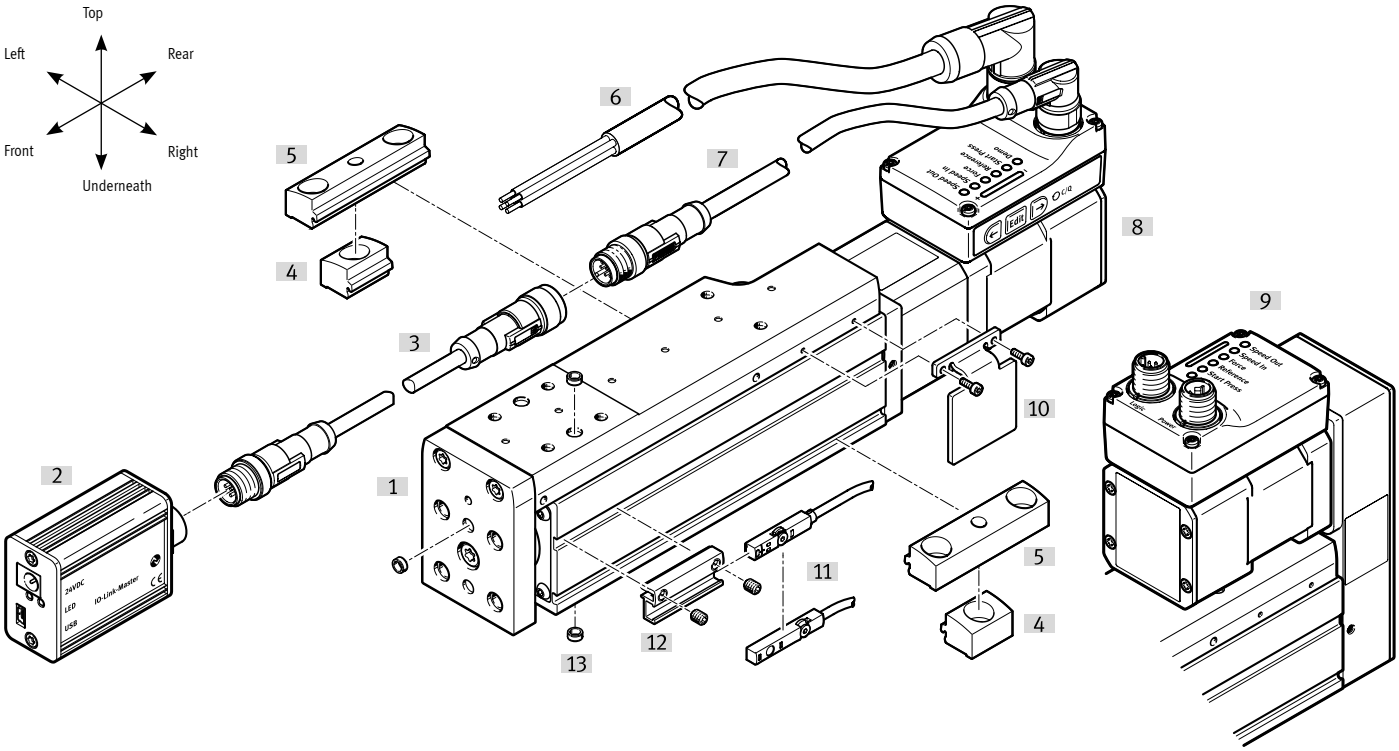
011	End-position sensing	
AA	With integrated end-position sensing	

012	Cable outlet direction	
	Standard	
D	Underneath	
L	Left	
R	Right	

013	Motor attachment position	
	Standard	
PL	Parallel, left	
PR	Parallel, right	
PD	Parallel, bottom	
PT	Parallel, top	

014	Electrical accessories	
	None	
L1	Adapter for operation as IO-Link® device	

Peripherals overview



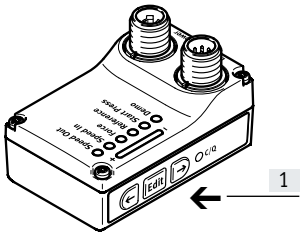
Accessories

	Type/order code	Description	→ Page/Internet
[1]	Mini slide unit EGSS-BS	Electric drive	9
[2]	IO-Link master USB CDSU-1	For straightforward use of the mini slide unit via IO-Link	32
[3]	Adapter NEFC-M12G8	Connection between the motor and the IO-Link master	32
[4]	Profile mounting EAHF-L2-...-P-S	For mounting the axis on the side of the profile	29
[5]	Profile mounting EAHF-L2-...-P	For mounting the axis on the side of the profile. The profile mounting can be attached to the mounting surface using the drill hole in the centre	28
[6]	Supply cable NEBL-T12	For connecting load and logic supply	33
[7]	Connecting cable NEBC-M12	For connection to a controller	33
[8]	Axial kit	For axial motor mounting (included in the scope of delivery)	9
[9]	Parallel kit	For parallel motor mounting (included in the scope of delivery)	9
[10]	Switch lug[1)] EAPM-...-SLS	For sensing the slide position in conjunction with inductive proximity switches SIES-8M	30
[11]	Proximity switches[1)] SIES-8M	Inductive proximity switches, for T-slot	31
	Proximity switches[1)] SMT-8M	Magnetic proximity switches, for T-slot	31
[12]	Sensor bracket[1)] EAPM-L2	For mounting the proximity switches on the axis. The proximity switches can only be mounted using the sensor bracket	30
[13]	Centring pin/sleeve ZBS, ZBH	For centring loads and attachments	31

1) Proximity switches are optional and only required in order to sense any intermediate positions.

Peripherals overview

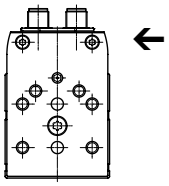
Control elements



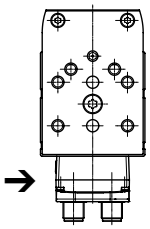
[1] Pushbutton actuators for parameterisation and control

Cable outlet direction

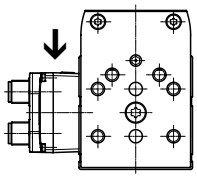
Standard



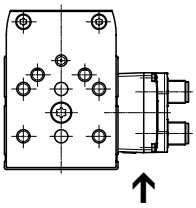
[D] Underneath



[L] Left

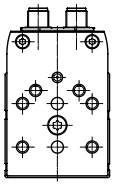


[R] Right

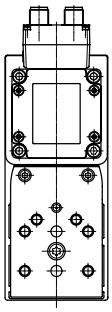


Motor mounting variants

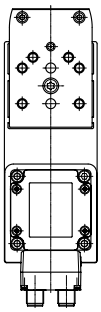
Standard



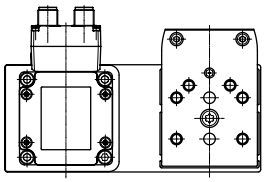
[PT] Top



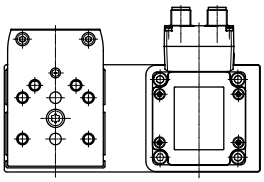
[PD] Underneath



[PL] Left

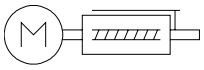


[PR] Right

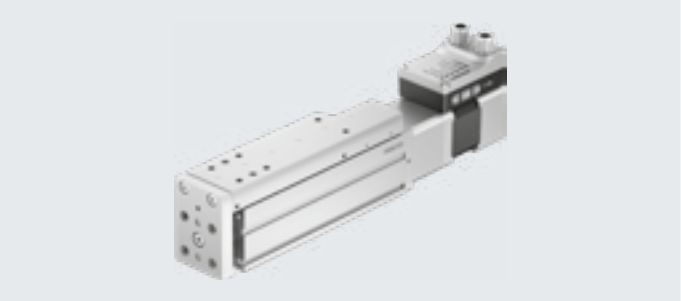


NEW

Datasheet



- Ø - Size
  32 ... 60
- | - Stroke length
  25 ... 200 mm



General technical data				
Size		32	45	60
Design		Electric mini slide with ball screw and integrated drive		
Motor type		Stepper motor		
Guide		Recirculating ball bearing guide		
Mounting position		Any		
Working stroke	[mm]	25, 50, 75, 100	25, 50, 75, 100, 125, 150	50, 75, 100, 125, 150, 200
Stroke reserve	[mm]	0		
Additional functions		Built-in end-position sensing		
		User interface		
Display		LED		
Homing		Positive fixed stop block		
		Negative fixed stop block		
Type of mounting		With female thread		
		With accessories		
		With centring pin, centring sleeve		
Max. cable length				
Inputs/outputs	[m]	15		
IO-Link operation	[m]	20		

Mechanical data				
Size		32	45	60
Max. payload				
Horizontal	[kg]	2	6	10
Vertical	[kg]	2	6	10
Max. feed force F_x	[N]	60	120	250
Max. radial force[1]	[N]	140	340	420
Repetition accuracy	[mm]	±0.015		
Reversing backlash	[µm]	150		
Position sensing		Via proximity switch		
		Via IO-Link		
With axial motor mounting				
Max. speed[2]	[m/s]	0.19	0.25	0.24
Speed “Speed Press”[3]	[m/s]	0.01		
Max. acceleration[3]	[m/s²]	5		
With parallel motor mounting				
Max. speed[2]	[m/s]	0.19	0.235	0.205
Speed “Speed Press”[3]	[m/s]	0.01		
Max. acceleration[3]	[m/s²]	3		

1) At the drive shaft
2) Adjustable in increments of 10%
3) Unchangeable parameter

Spindle				
Size		32	45	60
Diameter	[mm]	8	10	12
Pitch	[mm/rev]	8	10	12

Datasheet

Electrical data				
Size		32	45	60
Motor				
Nominal voltage DC	[V]	24 (±15%)		
Nominal current	[A]	3	3	5.3
Max. current consumption (load)	[A]	3	3	5.3
Max. current consumption (logic)	[mA]	300		
Encoder				
Rotor position sensor		Absolute encoder, single turn		
Rotor position sensor measuring principle		Magnetic		
Rotor position encoder resolution	[bit]	16		

Interfaces				
Size		32	45	60
Parameterisation interface				
IO-Link		Yes		
User interface		Yes		
Digital inputs				
Number		2		
Switching logic		PNP		
		NPN		
Characteristics		Not galvanically isolated		
		Configurable		
Specification		Based on IEC 61131-2, type 1		
Operating range	[V]	24		
Digital outputs				
Number		2		
Switching logic		PNP		
		NPN		
Rotor position sensor		Absolute encoder, single turn		
Characteristics		Not galvanically isolated		
		Configurable		
Max. current	[mA]	100		

Technical data – IO-Link				
Size		32	45	60
SIO mode support		Yes		
Communication mode		COM3 (230.4 kBd)		
Connection technology		Plug		
Port class		A		
No. of ports		1		
Process data width OUT	[byte]	2		
Process data content OUT	[bit]	1 (Move in)		
	[bit]	1 (Move out)		
	[bit]	1 (Move Intermediate)		
	[bit]	1 (Quit Error)		
Process data width IN	[byte]	2		
Process data content IN	[bit]	1 (State Device)		
	[bit]	1 (State Move)		
	[bit]	1 (State in)		
	[bit]	1 (State out)		
	[bit]	1 (State Intermediate)		
Service data content IN	[bit]	32 (Force)		
	[bit]	32 (Position)		
	[bit]	32 (Speed)		
Minimum cycle time	[ms]	1		
Data memory required	[kilobyte]	0.5		
Protocol version		Device V 1.1		

Datasheet

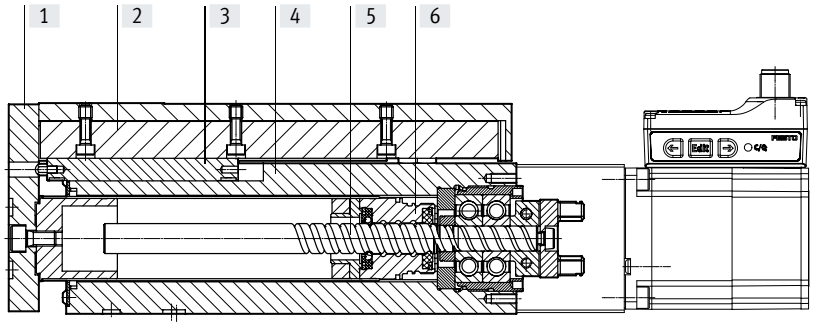
Operating and environmental conditions				
Size		32	45	60
Insulation class		B		
Ambient temperature	[°C]	0 ... +50		
Storage temperature	[°C]	–20 ... +60		
Note on ambient temperature		Above an ambient temperature of 30°C, the power must be reduced by 2% per K		
Temperature monitoring		Switch-off for excessive temperature		
		Integrated precise CMOS temperature sensor with analogue output		
Relative humidity	[%]	0 ... 90		
Protection class		III		
Degree of protection		IP40		
Duty cycle	[%]	100		
CE marking (see declaration of conformity)		To EU EMC Directive for EMCS-ST → festo.com/sp		
		To EU RoHS Directive		
UKCA marking (see declaration of conformity)		To UK instructions for EMC		
		To UK RoHS instructions		
KC mark		KC EMC		
Certification		RCM		
Vibration resistance		Transport application test with severity level 1 to FN 942017-4 and EN 61800-2 and EN 61800-5-1		
Shock resistance		Shock test with severity level 1 to FN 942017-5 and EN 61800-2		
Cleanroom class		Class 9 according to ISO 14644-1		
Maintenance interval		Lifetime lubrication		

Weight				
Size		32	45	60
With axial motor mounting				
Basic weight at 0 mm stroke	[g]	924	1238	2735
Additional weight per 10 mm stroke	[g]	30	63	95
Moving mass with 0 mm stroke	[g]	149	212	675
Additional moving mass per 10 mm stroke	[g]	12	30	40
With parallel motor mounting				
Basic weight at 0 mm stroke	[g]	1088	1361	2999
Additional weight per 10 mm stroke	[g]	30	63	95
Moving mass with 0 mm stroke	[g]	149	212	675
Additional moving mass per 10 mm stroke	[g]	12	30	40

Datasheet

Materials

Sectional view



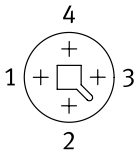
Axis		
[1]	Yoke plate	Anodised wrought aluminium alloy
[2]	Slide	Anodised wrought aluminium alloy
[3]	Guide rail	Rolling bearing steel
[4]	Housing	Anodised wrought aluminium alloy
[5]	Spindle	Rolling bearing steel
[6]	Spindle nut	Rolling bearing steel
	PWIS conformity	VDMA24364 zone III
	Note on materials	RoHS-compliant

Pin allocation

Power supply

Plug

M12x1, 4-pin, T-coded to EN 61076-2-111

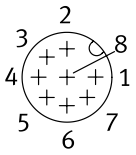


Pin	Function
1	Power voltage supply (24 V DC)
2	Reference potential, power voltage supply (GND)
3	Reserved, do not connect
4	Functional earth (FE)

Logic interface

Plug

M12x1, 8-pin, A-coded to EN 61076-2-101



When used with digital I/O

Pin	Function
1	Logic voltage supply (24 V DC)
2	Digital output 1 (State "In")
3	Digital output 2 (State "Out")
4	Reference potential, logic voltage supply (GND)
5	Digital input 1 (Move "In")
6	Digital input 2 (Move "Out")
7	Reserved, do not connect
8	Reference potential, logic voltage supply (GND)

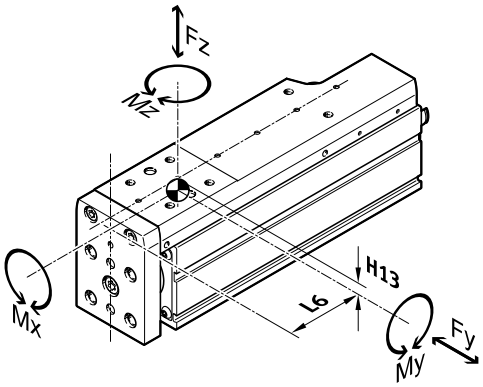
When used with IO-Link

Pin	Function
1	L+ IO-Link power supply (24 V DC)
2	Reserved, do not connect
3	C/Q communication with the IO-Link master
4	L – Reference potential, IO-Link power supply (0 V)
5	Reserved, do not connect
6	Reserved, do not connect
7	Reserved, do not connect
8	L – Reference potential, IO-Link power supply (0 V)

Datasheet

Dynamic characteristic load values

The indicated forces and torques refer to the centre of the guide.
These values must not be exceeded during dynamic operation.



Distance from the centre of the guide

Size		32	45	60
Dimension H13	[mm]	7.9	10.2	15.9
Dimension L6[1)]	[mm]	31.8	37.3	53.4

1) The dimension relates to the retracted position of the slide. In the advanced position, the dimension must be extended accordingly.

Max. permissible forces and torques for the guide calculation, for a service life of 5 x 10^6 cycles and max. stroke

Size		32	45	60
$Fy_{max.}$	[N]	991	1314	4937
$Fz_{max.}$	[N]	991	1314	4937
$Mx_{max.}$	[Nm]	3.4	8.1	20
$My_{max.}$	[Nm]	3.2	7	30
$Mz_{max.}$	[Nm]	3.2	7	30

Basic load ratings

Size		32	45	60
Dynamic				
Ball screw	[N]	2000	3200	4600
Linear guide	[N]	2135	3240	13400
Fixed bearing	[N]	3795	7413	13321
Static				
Ball screw	[N]	3700	5900	8500
Linear guide	[N]	3880	5630	26900
Fixed bearing	[N]	1792	3966	7000

Note

For a guide system to have a service life of 5x 10^6 cycles, the load comparison factor must have a value of fv ≤ 1, based on the maximum permissible forces and torques for a service life of 5x 10^6 cycles.
This formula can be used to calculate a guide value.
The engineering software "Electric Motion Sizing" is available for more precise calculations ➔ www.festo.com/x/electric-motion-sizing

If the axis is subjected to two or more of the indicated forces and torques simultaneously, the following equation must be satisfied in addition to the indicated maximum loads:

Calculating the load comparison factor:

$$f_v = \frac{|F_{y1}|}{F_{y2}} + \frac{|F_{z1}|}{F_{z2}} + \frac{|M_{x1}|}{M_{x2}} + \frac{|M_{y1}|}{M_{y2}} + \frac{|M_{z1}|}{M_{z2}} \leq 1$$

F_1/M_1 = dynamic value
F_2/M_2 = maximum value

Datasheet

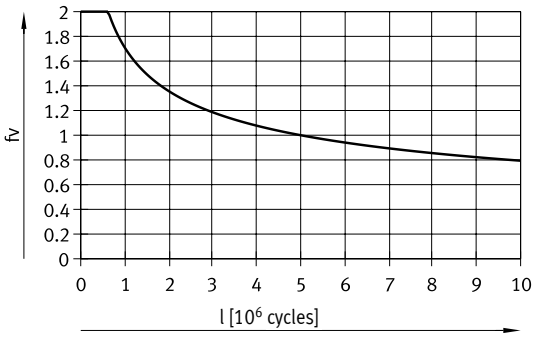
Calculating the service life

The service life of the guide depends on the load. To be able to make a statement as to the service life of the guide, the graph below plots the load comparison factor fv against the service life.

These values are only theoretical. You must consult your local Festo contact for a load comparison factor fv greater than 1.

Load comparison factor fv as a function of service life l

Example:
A user wants to move an x kg load. Using the formula (➔ page 14) gives a value of 1.5 for the load comparison factor fv. According to the graph, the guide has a service life of approx. 1.5x 10^6 cycles. Reducing the acceleration reduces the My and Mz values. A load comparison factor fv of 1 now gives a service life of 5 x 10^6 cycles.



Comparison of the characteristic load values for 5 x 10^6 cycles with dynamic forces and torques of recirculating ball bearing guides

The characteristic load values of the bearing guides are standardised to ISO and JIS using dynamic and static forces and torques. These forces and torques are based on an expected service life of the guide system of 100 km to ISO or 50 km to JIS.
As the characteristic load values are dependent on the service life, the maximum permissible forces and torques for a 5000 km service life cannot be compared with the dynamic forces and torques of bearing guides to ISO/JIS.

To make it easier to compare the guide capacity of mini slides EGSC with bearing guides, the table below lists the theoretically permissible forces and torques for a calculated service life of 100 km. This corresponds to the dynamic forces and torques to ISO.
These 100 km values have been calculated mathematically and are only to be used for comparing with dynamic forces and torques to ISO. The drives must not be loaded with these characteristic values as this could damage the axes.

Max. permissible forces and torques for a theoretical service life of 100 km (from a guide perspective only)
Application: mass m on the slide

Size		25	32	45	60
$Fy_{max.}$	[N]	1310	2135	3240	13400
$Fz_{max.}$	[N]	1310	2135	3240	13400
$Mx_{max.}$	[Nm]	5	10	20	107
$My_{max.}$	[Nm]	4	7	17	117
$Mz_{max.}$	[Nm]	4	7	17	117

Service life of the motor

The service life of the motor at nominal power is 20000 h.

Datasheet

Sizing example

Application data:

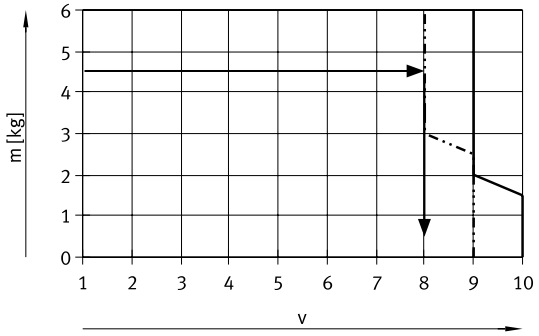
- Payload: 4 kg
- Mounting position: vertical
- Motor mounting position: axial
- Stroke: 100 mm
- Max. permitted positioning time: 1 s (one direction)

Step 1: Selecting the smallest possible size from the table ➔ page 10

Mechanical data				
Size		32	45	60
Max. payload				
Horizontal	[kg]	2	6	10
Vertical	[kg]	2	6	10

➔ Smallest possible size: EGSS-BS-KF-45

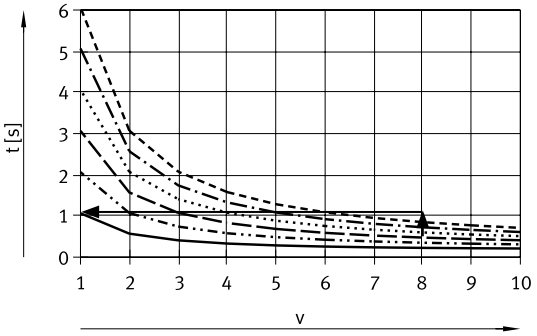
Step 2: Selecting the max. speed level v for payload m



Horizontal
Vertical

➔ Max. speed level for payload: level 8

Step 3: Reading off the min. positioning time t for stroke l



l = 25 mm
l = 50 mm
l = 75 mm
l = 100 mm
l = 125 mm
l = 150 mm

➔ Min. positioning time for 100 mm at level 8: 0.6 s

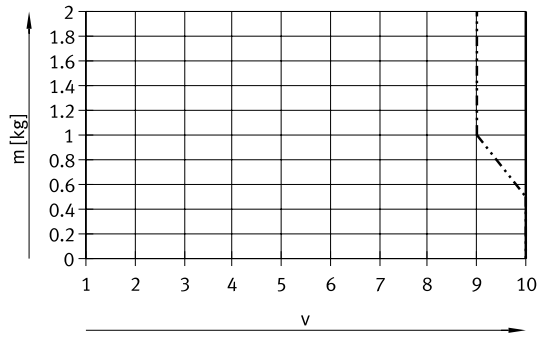
Result

The application can be implemented using EGSS-BS-KF-45-100. A minimum positioning time (one direction) of 0.6 s is achieved. Longer positioning times can be selected at any time using a lower speed level.

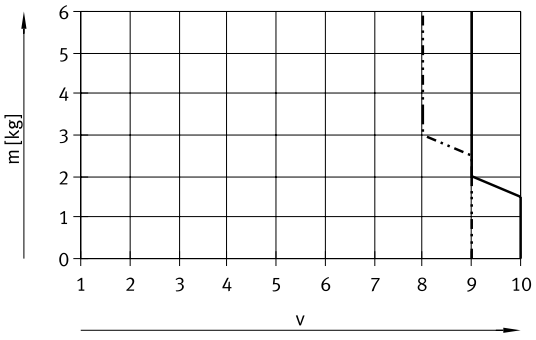
Datasheet

Mass m as a function of speed level v
With axial kit

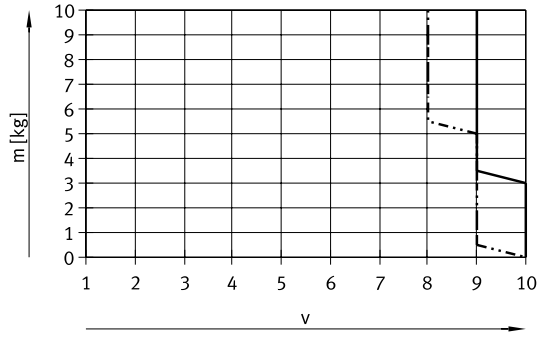
Size 32



Size 45



Size 60



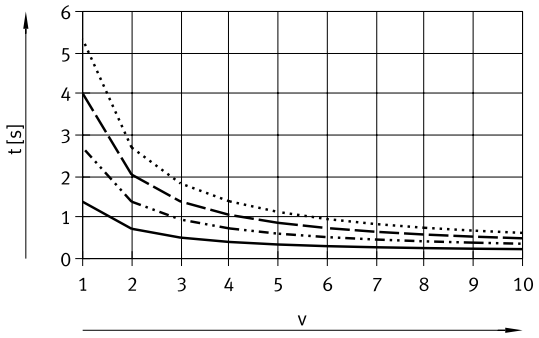
Horizontal
Vertical

Note:
The lines represent the maximum values. The lower speed levels can be set at any time.

Datasheet

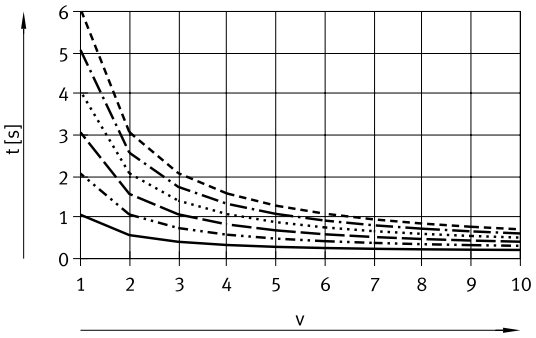
Positioning time t as a function of speed level v and stroke l
With axial kit

Size 32



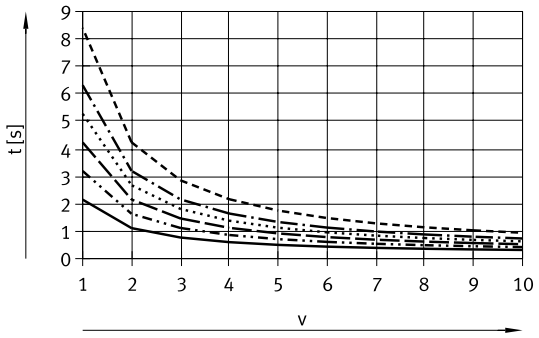
- l = 25 mm
- l = 50 mm
- l = 75 mm
- l = 100 mm

Size 45



- l = 25 mm
- l = 50 mm
- l = 75 mm
- l = 100 mm
- l = 125 mm
- l = 150 mm

Size 60

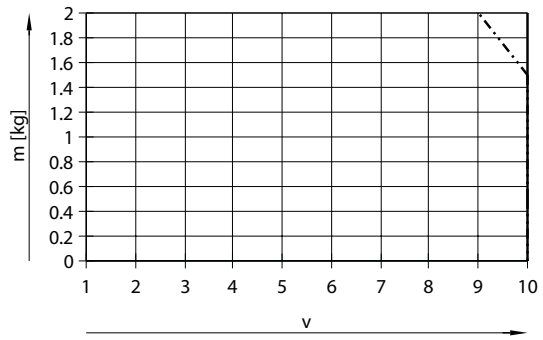


- l = 50 mm
- l = 75 mm
- l = 100 mm
- l = 125 mm
- l = 150 mm
- l = 200 mm

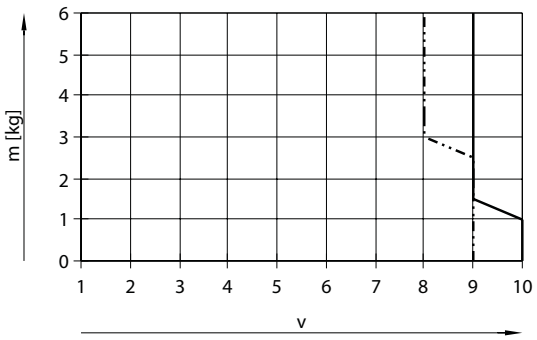
Datasheet

Mass m as a function of speed level v
With parallel kit

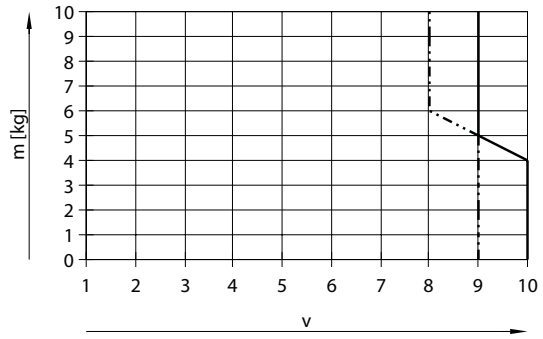
Size 32



Size 45



Size 60



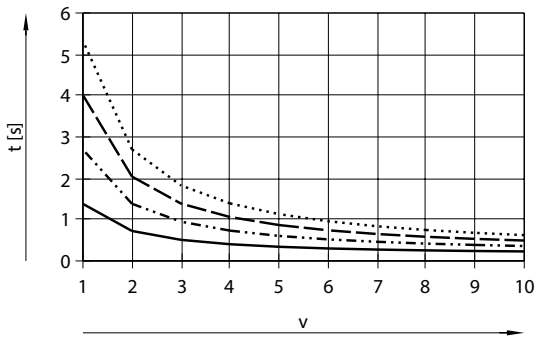
Horizontal
Vertical

Note:
The lines represent the maximum values. The lower speed levels can be set at any time.

Datasheet

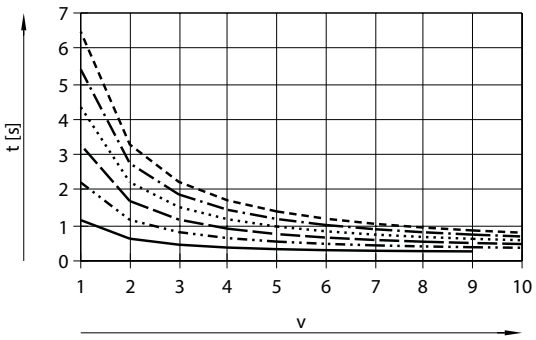
Positioning time t as a function of speed level v and stroke l
With parallel kit

Size 32



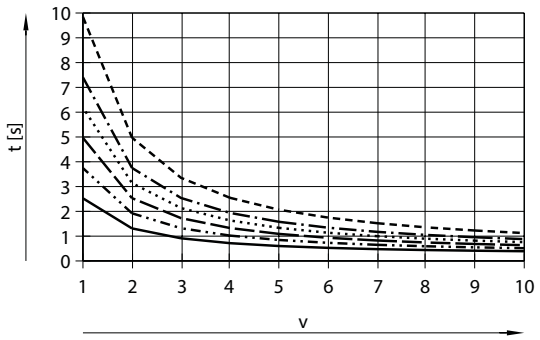
- l = 25 mm
- l = 50 mm
- l = 75 mm
- l = 100 mm

Size 45



- l = 25 mm
- l = 50 mm
- l = 75 mm
- l = 100 mm
- l = 125 mm
- l = 150 mm

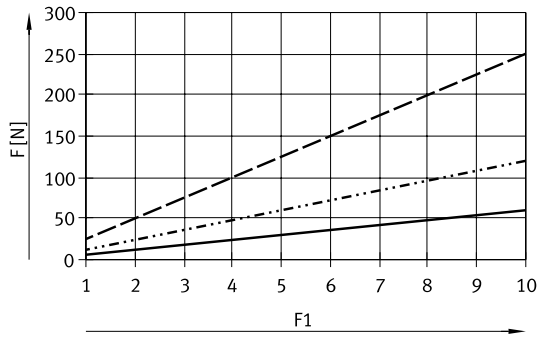
Size 60



- l = 50 mm
- l = 75 mm
- l = 100 mm
- l = 125 mm
- l = 150 mm
- l = 200 mm

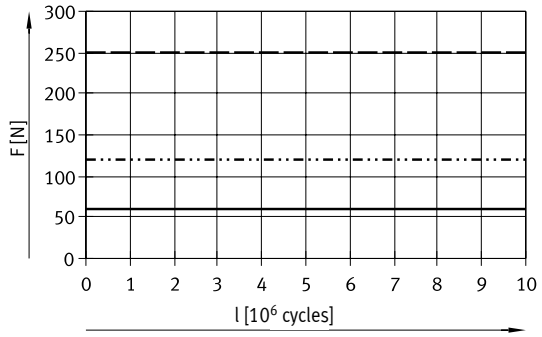
Datasheet

Feed force F as a function of force level F1



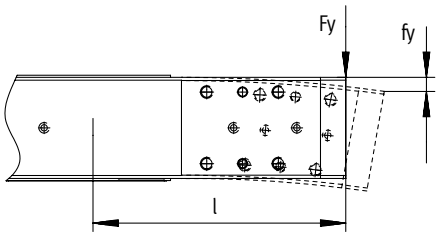
EGSS-BS-32
EGSS-BS-45
EGSS-BS-60

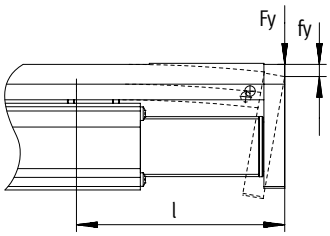
Feed force F as a function of service life l



EGSS-BS-32
EGSS-BS-45
EGSS-BS-60

Deflection f of the guide rail as a function of stroke l





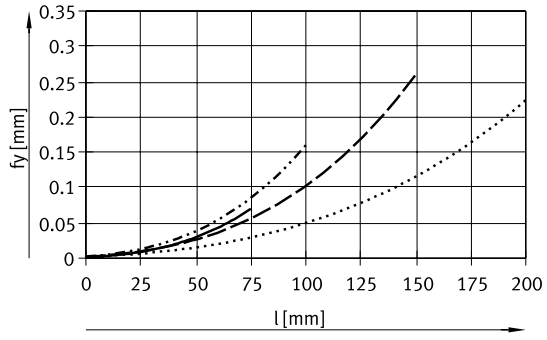
Fy/Fz at which the characteristic curves were determined

EGSS-BS-32: 10 N

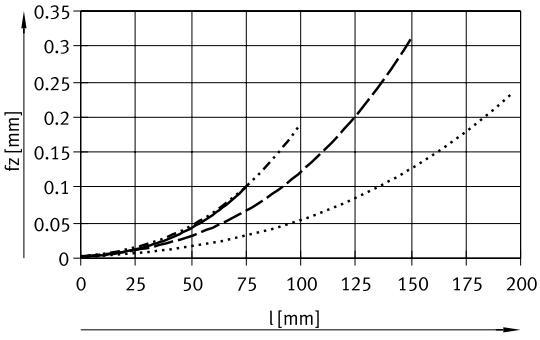
EGSS-BS-45: 10 N

EGSS-BS-60: 10 N

Deflection fy



Deflection fz



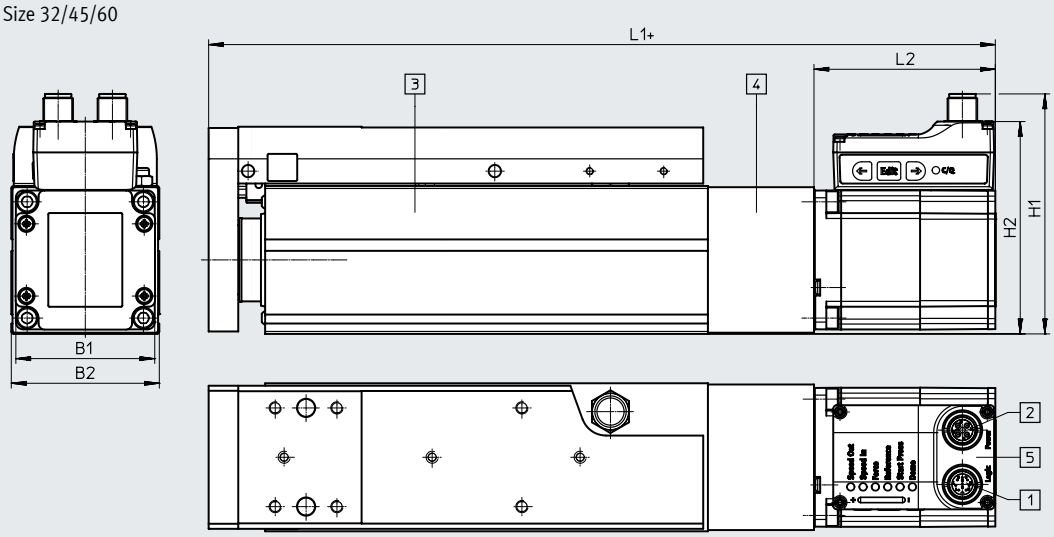
EGSS-BS-32
EGSS-BS-45
EGSS-BS-60

Datasheet

Dimensions – With axial motor mounting

Download CAD data ➔ www.festo.com

Size 32/45/60



[1] Connection to logic interface
[2] Connection to power supply
[3] Mini slides
[4] Axial kit
[5] Motor
+ = plus stroke length

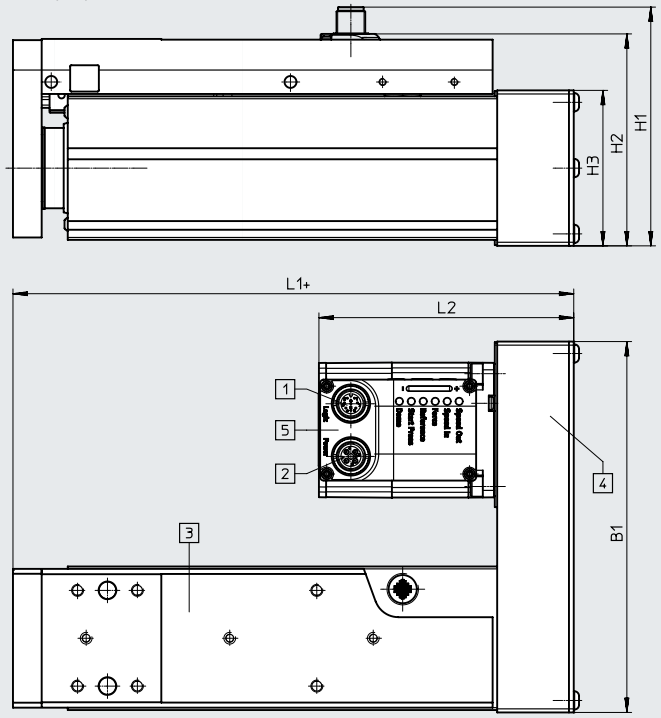
Size	B1	B2	H1	H2	L1	L2
32	42.3	32	81.1	69.9	167	65
45	42.3	45	82.6	71.4	178.8	65
60	56.6	60	97.3	86.1	218.9	73.5

Datasheet

Dimensions – With parallel motor mounting

Download CAD data ➔ www.festo.com

Size 32/45/60



[1] Connection to logic interface
[2] Connection to power supply
[3] Mini slides
[4] Parallel kit
[5] Motor
+ = plus stroke length

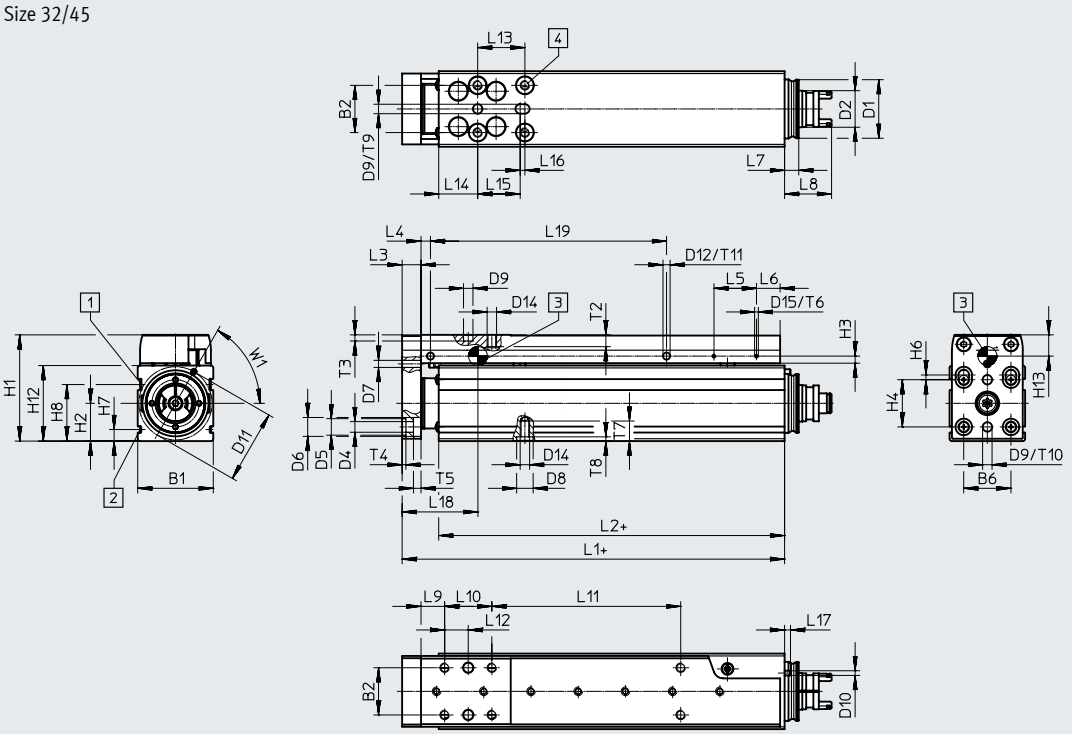
Dimensions for other motor mounting variants ➔ CAD data.

Size	B1	H1	H2	H3	L1	L2
32	111	83	72	45	86	93
45	111	83	72	45	97.8	93
60	155	100	90	65	134.4	106.5

Datasheet

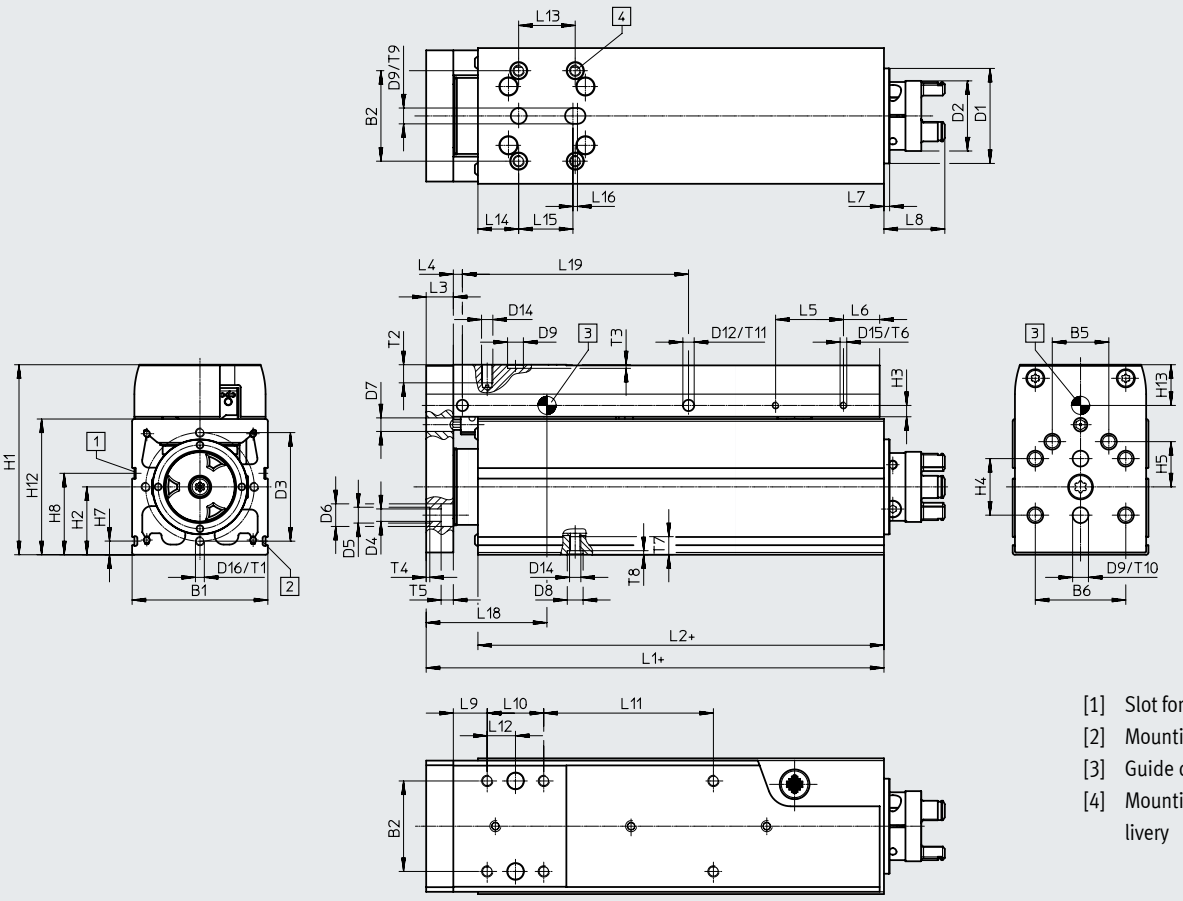
Dimensions – Mechanical system Download CAD data ➔ www.festo.com

Size 32/45



[1] Slot for sensor bracket
[2] Mounting slot
[3] Guide centre
[4] Mounting thread sealed on delivery

Size 60



[1] Slot for sensor bracket
[2] Mounting slot
[3] Guide centre
[4] Mounting thread sealed on delivery

Datasheet

Size	B1 ±0.15	B2	B5	B6	D1 Ø	D2 Ø	D3 Ø	D4 Ø H13	D5 Ø H7	D6 Ø H13	D7 Ø	D8 Ø H7	D9 Ø H8	D10 Ø	D11 Ø
32	32	20	–	20	25	16.5	–	4.5	7	8	3	7	4	2	31
45	45	25	–	25	32	16.5	–	5.5	7	10	3	7	5	3	41
60	60	40	25	40	42	31	48	5.5	7	10	6	7	7	–	–

Size	D12 Ø	D13	D14	D15	D16	H1	H2	H3	H4	H5	H6	H7	H8	H12 ±0.15	H13
32	3	–	M4	M1.6	–	45	16	3	20	–	2	4.9	24	32	8.4
45	3	–	M5	M2	–	60.5	22.5	3	25	–	–	6.1	28.5	45	10.7
60	5	M4	M5	M3	M4	84	30	5	25	20	–	6.1	36	60	16.4

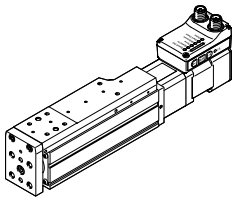
Size	L1	L2	L3 +0.2	L4	L5 ±0.1	L6	L7	L8	L9	L10	L12	L13	L14	L15	L16
32	62	46.5	8	4	18	10	6	19.9	10	20	10	20	16.5	18	2
45	73.8	54.5	10	4	24	12	6	19.9	15	25	12.5	25	17.5	24	2
60	102.4	79.5	12	4	30	16	2.5	26.9	15	25	12.5	25	30	24	2

Size	L17	L18	T1	T2	T3 +0.1	T4 +0.1	T5	T6	T7	T8 +0.1	T9 +0.1	T10 +0.1	T11 −0.2	W1	⫧ 1
32	2.5	31.8	–	5	2.6	1.6	3.2	1.5	8.5	1.8	2.6	2.6	1.5	60°	6
45	2	37.3	–	6	1.3	1.6	5.4	4	7	1.8	1.3	1.3	5	60°	12
60	–	53.4	10	8	1.6	1.6	5.4	6	8	1.8	1.6	1.6	5	–	15

Size	Stroke [mm]	L19	L11
32	25	25	0
	50	50	30
	75	75	55
	100	100	80
45	25	25	0
	50	50	25
	75	75	50
	100	100	75
	125	125	100
	150	150	125
60	50	50	25
	75	75	50
	100	100	75
	125	125	100
	150	150	125
	200	200	175

Ordering data

Ordering data

	Size	Spindle pitch	Stroke	Part no.	Type
	32	8	25	**8083801**	**EGSS-BS-KF-32-25-8P-ST-M-H1-PLK-AA**
			50	**8083802**	**EGSS-BS-KF-32-50-8P-ST-M-H1-PLK-AA**
			75	**8083803**	**EGSS-BS-KF-32-75-8P-ST-M-H1-PLK-AA**
			100	**8083804**	**EGSS-BS-KF-32-100-8P-ST-M-H1-PLK-AA**
	45	10	25	**8083814**	**EGSS-BS-KF-45-25-10P-ST-M-H1-PLK-AA**
			50	**8083815**	**EGSS-BS-KF-45-50-10P-ST-M-H1-PLK-AA**
			75	**8083816**	**EGSS-BS-KF-45-75-10P-ST-M-H1-PLK-AA**
			100	**8083817**	**EGSS-BS-KF-45-100-10P-ST-M-H1-PLK-AA**
			125	**8083818**	**EGSS-BS-KF-45-125-10P-ST-M-H1-PLK-AA**
			150	**8083819**	**EGSS-BS-KF-45-150-10P-ST-M-H1-PLK-AA**
	60	12	50	**8083716**	**EGSS-BS-KF-60-50-12P-ST-M-H1-PLK-AA**
			75	**8083717**	**EGSS-BS-KF-60-75-12P-ST-M-H1-PLK-AA**
			100	**8083718**	**EGSS-BS-KF-60-100-12P-ST-M-H1-PLK-AA**
			125	**8083719**	**EGSS-BS-KF-60-125-12P-ST-M-H1-PLK-AA**
			150	**8083720**	**EGSS-BS-KF-60-150-12P-ST-M-H1-PLK-AA**
			200	**8083721**	**EGSS-BS-KF-60-200-12P-ST-M-H1-PLK-AA**

Ordering data – Modular product system

Ordering table

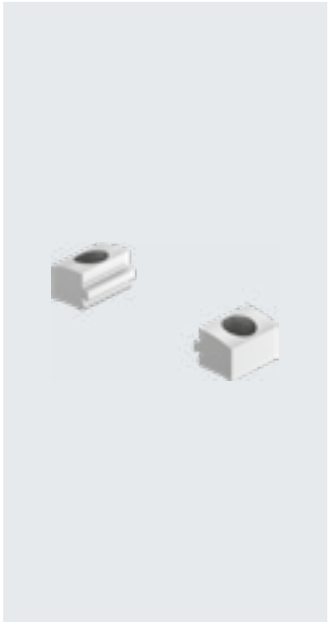
Size	32	45	60	Conditions	Code		Enter code
Module no.	8083800	8083813	8083713				
Series	EGSS				**EGSS**	-	EGSS
Drive system	Ball screw				**-BS**		-BS
Guide	Recirculating ball bearing guide				**-KF**		-KF
Size	32	45	60		**-...**		
Stroke [mm]	25, 50, 75, 100	25, 50, 75, 100, 125, 150	50, 75, 100, 125, 150, 200		**-...**		
Spindle pitch [mm]	8P	10P	12P		**-...**		
Motor type	Stepper motor ST				**-ST**		-ST
Controllers	Integrated				**-M**		-M
Operator panel	Integrated				**-H1**		-H1
Bus protocol/control	NPN and IO-Link				**-NLK**		
	PNP and IO-Link				**-PLK**		
End-position sensing	With integrated end-position sensing				**-AA**		-AA
Cable outlet direction	Standard			[1]			
	Left			[2]	**-L**		
	Underneath			[3]	**-D**		
	Right			[4]	**-R**		
Motor attachment position	Axial (standard)						
	Parallel, left			[5]	**-PL**		
	Parallel, right			[6]	**-PR**		
	Parallel, underneath			[7]	**-PD**		
	Parallel, top			[8]	**-PT**		
Electrical accessories	None						
	Adapter for operation as IO device				**+L1**		

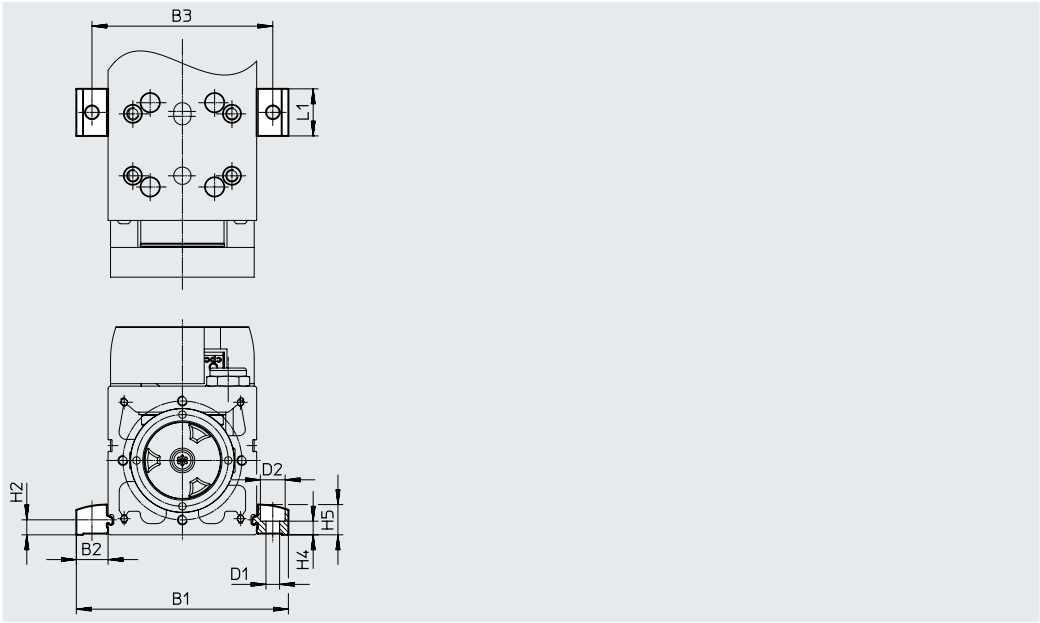
[1] Not with motor mounting position PR; PD
[2] Not with motor mounting position PR
[3] Not with motor mounting position PT
[4] Not with motor mounting position PL
[5] Not in combination with cable outlet direction R
[6] Not in combination with cable outlet direction standard or L
[7] Not in combination with cable outlet direction standard
[8] Not in combination with cable outlet direction D

Accessories

Profile mounting EAHF-L2-...-P-S
Material:
Anodised wrought aluminium alloy
RoHS-compliant

- For mounting the slide on the side of the profile





Dimensions and ordering data

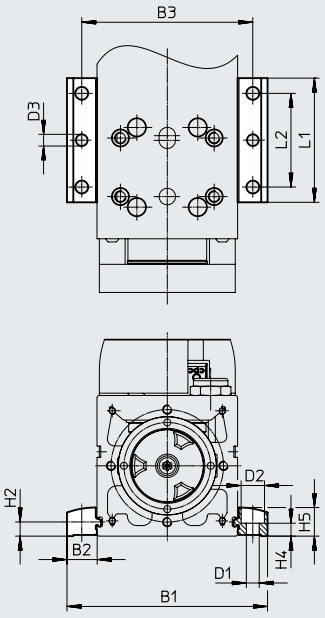
For size	B1	B2	B3	D1 ø H13	D2 ø H13	H2
32	51.4	9.7	42	4.5	8	4.9
45	70.6	12.8	58	5.5	10	6.1
60	85.6	12.8	73	5.5	10	6.1

For size	H4 ±0.1	H5	L1	Weight [g]	Part no.	Type
32	4.2	9	19	4	**5183153**	**EAHF-L2-25-P-S**
45	5.5	12.2	19	6	**5184133**	**EAHF-L2-45-P-S**
60	5.5	12.2	19	6	**5184133**	**EAHF-L2-45-P-S**

Accessories

Profile mounting EAHF-L2-...-P
Material:
Anodised wrought aluminium alloy
RoHS-compliant

- For mounting the slide on the side of the profile.
  The profile mounting can be attached to the mounting surface using the drilled hole in the centre



Dimensions and ordering data

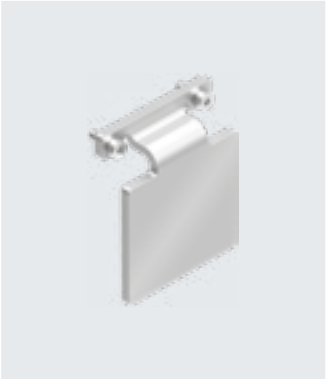
For size	B1	B2	B3	D1 ø H13	D2 ø H13	D3 ø	H2
32	51.4	9.7	42	4.5	8	4	4.9
45	70.6	12.8	58	5.5	10	5	6.1
60	85.6	12.8	73	5.5	10	5	6.1

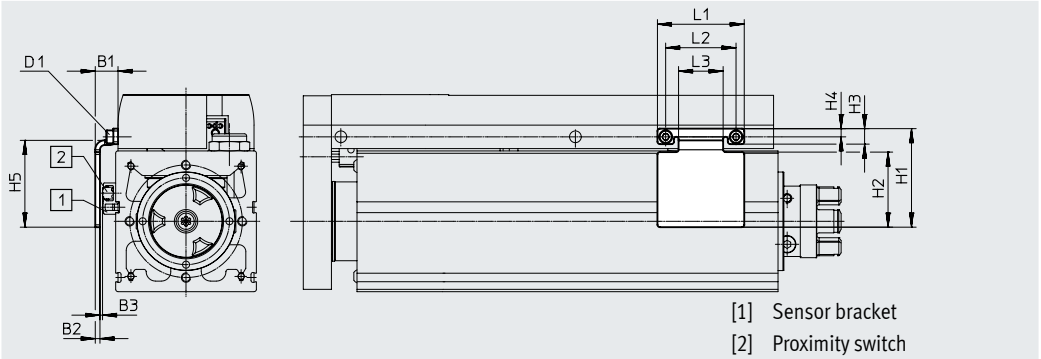
For size	H4 ±0.1	H5	L1	L2	Weight [g]	Part no.	Type
32	4.2	9	53	40	19	**4835684**	**EAHF-L2-25-P**
45	5.5	12.2	53	40	35	**4835728**	**EAHF-L2-45-P**
60	5.5	12.2	53	40	35	**4835728**	**EAHF-L2-45-P**

Accessories

Switch lug EAPM-...-SLS
For sensing using inductive proximity switches SIES-8M

Material:
Galvanised steel
RoHS-compliant





[1] Sensor bracket
[2] Proximity switch

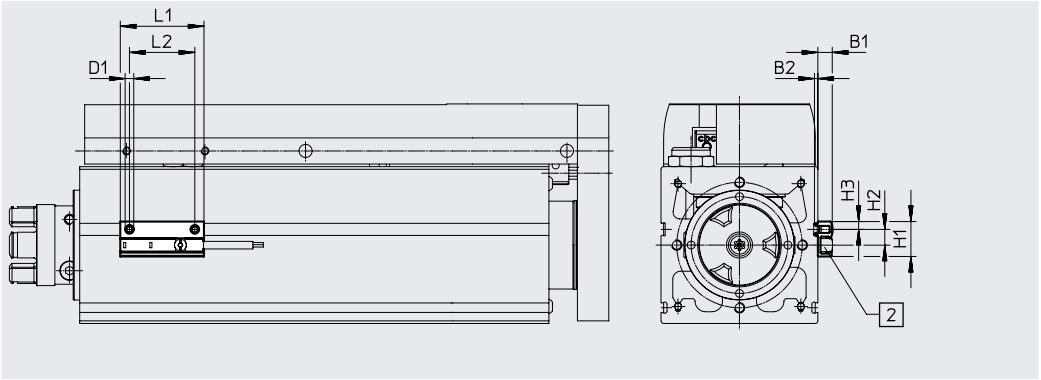
Dimensions and ordering data

For size	B1	B2	B3	D1	H1	H2	H3	H4
32	9.2	2	1.0±0.26	M1.6	27	19	4.3	2.5
45	9.4	2	0.7±0.26	M2	37	28	5.5	3.3
60	9.7	2	0.7±0.31	M3	42	32	6.6	3.5

For size	H5	L1	L2	L3	Weight [g]	Part no.	Type
32	24	22	18	10	10	**8067259**	**EAPM-L2-32-SLS**
45	33	30	24	14	18	**8067260**	**EAPM-L2-45-SLS**
60	37	37	30	19	27	**8067261**	**EAPM-L2-60-SLS**

Sensor bracket EAPM-L2

Material:
Anodised wrought aluminium alloy
RoHS-compliant



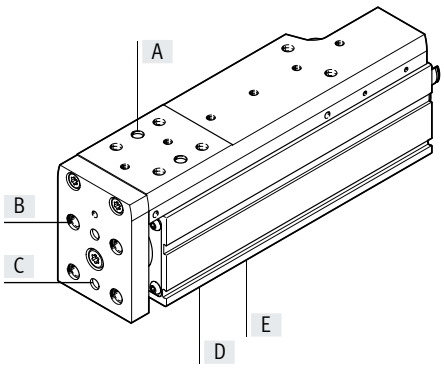
Dimensions and ordering data

For size	B1	B2	D1	H1	H2
32, 45, 60	5.5	1.3	M4	13.4	6

For size	H3	L1	L2	Weight [g]	Part no.	Type
32, 45, 60	3	32	25	4	**4759852**	**EAPM-L2-SH**

Accessories

Ordering data – Centring sleeve



	For size	Position	Part no.	Type	PU[1]
	32	A	**562959**	**ZBS-4**	10
		B	**8146544**	**ZBH-7-B**	
		C	**562959**	**ZBS-4**	
		D	**8146544**	**ZBH-7-B**	
		E	**562959**	**ZBS-4**	
	45	A	**8146543**	**ZBH-5-B**	
		B	**8146544**	**ZBH-7-B**	
		C	**8146543**	**ZBH-5-B**	
		D	**8146544**	**ZBH-7-B**	
		E	**8146543**	**ZBH-5-B**	
	60	A	**8146544**	**ZBH-7-B**	
		B	**8146544**	**ZBH-7-B**	
		C	**8146544**	**ZBH-7-B**	
		D	**8146544**	**ZBH-7-B**	
		E	**8146544**	**ZBH-7-B**	

1) Packaging unit

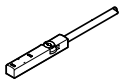
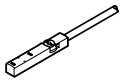
Ordering data – Push-in fitting for sealing air connection

	For size	Part no.	Type	PU[1]
	32	**133003**	**QSM-M5-3-I-R**	10
		133004	**QSM-M5-4-I-R**	
	45	**186266**	**QSM-G1/8-4-I**	
		186267	**QSM-G1/8-6-I**	
	60	**186108**	**QS-G1/4-6-I**	
		186110	**QS-G1/4-8-I**	

1) Packaging unit

Ordering data – Proximity switches for T-slot, inductive

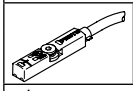
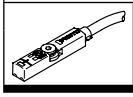
Datasheets → Internet: sies

	Type of mounting	Switching output	Electrical connection	Cable length [m]	Part no.	Type
N/O						
	Inserted in the slot from above, flush with the cylinder profile	PNP	Cable, 3-wire	7.5	**551386**	**SIES-8M-PS-24V-K-7.5-OE**
			Plug M8x1, 3-pin	0.3	**551387**	**SIES-8M-PS-24V-K-0.3-M8D**
		NPN	Cable, 3-wire	7.5	**551396**	**SIES-8M-NS-24V-K-7.5-OE**
			Plug M8x1, 3-pin	0.3	**551397**	**SIES-8M-NS-24V-K-0.3-M8D**
N/C						
	Inserted in the slot from above, flush with the cylinder profile	PNP	Cable, 3-wire	7.5	**551391**	**SIES-8M-PO-24V-K-7.5-OE**
			Plug M8x1, 3-pin	0.3	**551392**	**SIES-8M-PO-24V-K-0.3-M8D**
		NPN	Cable, 3-wire	7.5	**551401**	**SIES-8M-NO-24V-K-7.5-OE**
			Plug M8x1, 3-pin	0.3	**551402**	**SIES-8M-NO-24V-K-0.3-M8D**

Accessories

Ordering data – Proximity switch for T-slot, magneto-resistive

Datasheets → Internet: smt

	Type of mounting	Switching output	Electrical connection	Cable length [m]	Part no.	Type
N/O						
	Inserted in the slot from above, flush with the cylinder profile, short design	PNP	Cable, 3-wire	2.5	**574335**	**SMT-8M-A-PS-24V-E-2.5-OE**
			Plug M8x1, 3-pin	0.3	**574334**	**SMT-8M-A-PS-24V-E-0.3-M8D**
N/C						
	Inserted in the slot from above, flush with the cylinder profile, short design	PNP	Cable, 3-wire	7.5	**574340**	**SMT-8M-A-PO-24V-E-7.5-OE**

Ordering data – Connecting cables

Datasheets → Internet: nebu

	Electrical connection, left	Electrical connection, right	Cable length [m]	Part no.	Type
	Straight socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	**541333**	**NEBU-M8G3-K-2.5-LE3**
			5	**541334**	**NEBU-M8G3-K-5-LE3**
	Angled socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	**541338**	**NEBU-M8W3-K-2.5-LE3**
			5	**541341**	**NEBU-M8W3-K-5-LE3**

Note

For sizes 45 and 60, inductive proximity switches SIES-8M must be used for strokes greater than 100 mm.

Proximity switches are optional and only required in order to sense any intermediate positions.

Ordering data – IO-Link master USB

Datasheets → Internet: cdsu

	Description	Cable length [m]	Part no.	Type
	• For using the unit with IO-Link • An external power supply plug is also required (not included in the scope of delivery)	0.3	**8091509**	**CDSU-1**

Ordering data – Adapter

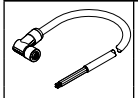
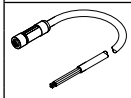
Datasheets → Internet: nefc

	Electrical connection, left	Electrical connection, right	Cable length [m]	Part no.	Type
	Straight socket, M12x1, 8-pin	Straight plug, M12x1, 5-pin	0.3	**8080777**	**NEFC-M12G8-0.3-M12G5-LK**

Accessories

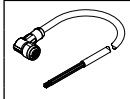
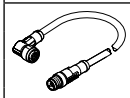
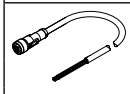
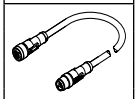
Ordering data – Supply cables

Datasheets → Internet: nebl

	Electrical connection, left	Electrical connection, right	Cable length [m]	Part no.	Type
	Angled socket, M12x1, 4-pin	Cable, open end, 4-wire	2	**8080778**	**NEBL-T12W4-E-2-N-LE4**
			5	**8080779**	**NEBL-T12W4-E-5-N-LE4**
			10	**8080780**	**NEBL-T12W4-E-10-N-LE4**
			15	**8080781**	**NEBL-T12W4-E-15-N-LE4**
	Straight socket, M12x1, 4-pin	Cable, open end, 4-wire	2	**8080790**	**NEBL-T12G4-E-2-N-LE4**
			5	**8080791**	**NEBL-T12G4-E-5-N-LE4**
			10	**8080792**	**NEBL-T12G4-E-10-N-LE4**
			15	**8080793**	**NEBL-T12G4-E-15-N-LE4**

Ordering data – Connecting cables

Datasheets → Internet: nebc

	Electrical connection, left	Electrical connection, right	Cable length [m]	Part no.	Type
	Angled socket, M12x1, 8-pin	Cable, open end, 8-wire	2	**8094476**	**NEBC-M12W8-E-2-N-B-LE8**
			5	**8094478**	**NEBC-M12W8-E-5-N-B-LE8**
			10	**8094481**	**NEBC-M12W8-E-10-N-B-LE8**
			15	**8094479**	**NEBC-M12W8-E-15-N-B-LE8**
		Straight plug, M12x1, 8-pin	2	**8080786**	**NEBC-M12W8-E-2-N-M12G8**
			5	**8080787**	**NEBC-M12W8-E-5-N-M12G8**
			10	**8080788**	**NEBC-M12W8-E-10-N-M12G8**
			15	**8080789**	**NEBC-M12W8-E-15-N-M12G8**
	Straight socket, M12x1, 8-pin	Cable, open end, 8-wire	2	**8094480**	**NEBC-M12G8-E-2-N-B-LE8**
			5	**8094477**	**NEBC-M12G8-E-5-N-B-LE8**
			10	**8094482**	**NEBC-M12G8-E-10-N-B-LE8**
			15	**8094475**	**NEBC-M12G8-E-15-N-B-LE8**
		Straight plug, M12x1, 8-pin	2	**8080782**	**NEBC-M12G8-E-2-N-M12G8**
			5	**8080783**	**NEBC-M12G8-E-5-N-M12G8**
			10	**8080784**	**NEBC-M12G8-E-10-N-M12G8**
			15	**8080785**	**NEBC-M12G8-E-15-N-M12G8**

Note

The cables are positioned at a 45° angle to the axis.