

# DLS40E-BDGV00100

DLS40

**INCREMENTAL ENCODERS** 





## Ordering information

Туре	Part no.
DLS40E-BDGV00100	1132514

Illustration may differ





#### Detailed technical data

## Performance

Pulses per revolution	100
Measuring step	90°, electric/pulses per revolution
Duty cycle	≤ 0.5 ± 10 %

#### Interfaces

Communication interface	Incremental
Communication Interface detail	HTL / Push pull
Number of signal channels	3 channel
Output frequency	≤ 150 kHz
Load current	≤ 30 mA
Power consumption	≤ 2 W (without load)

#### Electrical data

Connection type	Cable, 5-wire, radial, 2 m
Supply voltage	10 27 V
Reference signal, number	1
Reverse polarity protection	✓
Short-circuit protection of the outputs	<b>✓</b> ¹)
MTTFd: mean time to dangerous failure	600 years (EN ISO 13849-1) <sup>2)</sup>

<sup>1)</sup> Protection against short circuit to GND and U<sub>S.</sub> Short-circuit resistance is only guaranteed when Us and GND are connected correctly.

#### Mechanical data

Mechanical design	Blind hollow shaft
Shaft diameter	10 mm
Weight	Approx. 170 g <sup>1)</sup>
Shaft material	Stainless steel
Flange material	Aluminum

 $<sup>^{1)}</sup>$  Relates to encoders with 2 m cable connection.

<sup>&</sup>lt;sup>2)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

 $<sup>^{2)}</sup>$  Allow for self-heating of 1.3 K per 1,000 rpm when designing the operating temperature range.

 $<sup>^{</sup>m 3)}$  No permanent operation. Decreasing signal quality.

Housing material	Aluminum
Material, cable	PVC
Start up torque	0.5 Ncm
Operating torque	0.3 Ncm
Permissible movement static	± 0.3 mm (radial) ± 0.5 mm (axial)
Permissible movement dynamic	± 0.1 mm (radial) ± 0.2 mm (axial)
Operating speed	6,000 min <sup>-1 2)</sup>
Maximum operating speed	≤ 8,000 min <sup>-1 3)</sup>
Moment of inertia of the rotor	24.6 gcm <sup>2</sup>
Bearing lifetime	2.0 x 10^9 revolutions
Angular acceleration	≤ 500,000 rad/s²

 $<sup>^{1)}</sup>$  Relates to encoders with 2 m cable connection.

## Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-10 °C +70 °C
Storage temperature range	-25 °C +85 °C
Resistance to shocks	100 g, 6 ms (EN 60068-2-27)
Resistance to vibration	20 g, 10 Hz 2,000 Hz (EN 60068-2-6)

## Classifications

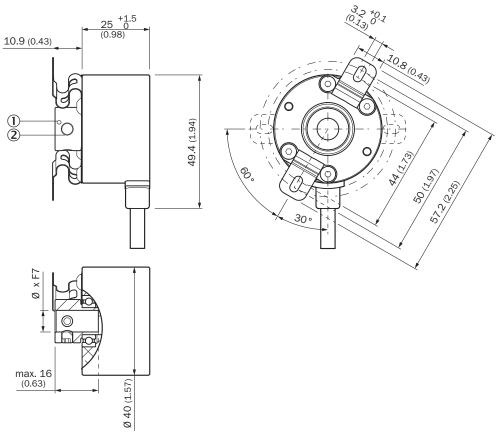
eCl@ss 5.0	27270501
eCl@ss 5.1.4	27270501
eCl@ss 6.0	27270590
eCl@ss 6.2	27270590
eCl@ss 7.0	27270501
eCl@ss 8.0	27270501
eCl@ss 8.1	27270501
eCl@ss 9.0	27270501
eCl@ss 10.0	27270501
eCl@ss 11.0	27270501
eCl@ss 12.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

<sup>&</sup>lt;sup>2)</sup> Allow for self-heating of 1.3 K per 1,000 rpm when designing the operating temperature range.

<sup>3)</sup> No permanent operation. Decreasing signal quality.

## Dimensional drawing (Dimensions in mm (inch))

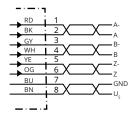
Blind hollow shaft



- ① Start position of the Z-pulse

Type Blind hollow shaft	Shaft diameter XF7
DLS40E-BAxxxxxxx	6 mm
DLS40E-BBxxxxxxx	8 mm
DLS40E-BDxxxxxxx	10 mm
DLS40E-BExxxxxxx	12 mm

## PIN assignment

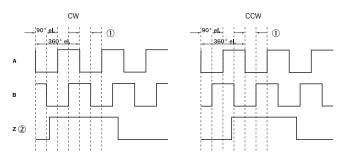


Wire colors (ca- ble connection)	Signal	Description	Туре
Brown	U <sub>S</sub>	Supply voltage	DLS40E-*

Wire colors (ca- ble connection)	Signal	Description	Туре
Blue	GND	Ground connection	DLS40E-*
Black	A	Signal cable	DLS40E-*
White	В	Signal cable	DLS40E-*
Orange	Z	Signal cable	DLS40E-*
Red	A-	Signal cable	DLS40E-AV*
Gray	B-	Signal cable	DLS40E-AV*
Yellow	Z-	Signal cable	DLS40E-AV*

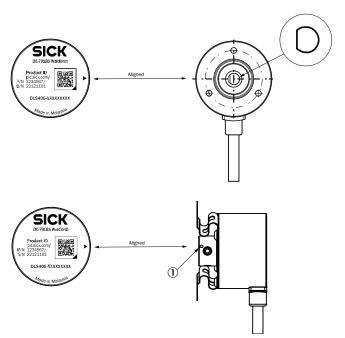
## Diagrams

HTL/Push pull



- ① Measuring step
- ② Only as reference

## Operation note



You can see the position with the mark on the rear side of the encoder 1 Zero pulse mark on housing

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