

SRM50-HWV0-K22

SRS/SRM50

MOTOR FEEDBACK SYSTEMS ROTARY HIPERFACE®





Ordering information

Туре	Part no.
SRM50-HWV0-K22	1037098

Other models and accessories → www.sick.com/SRS_SRM50

Illustration may differ



Detailed technical data

Performance

Sine/cosine periods per revolution	1,024
Number of the absolute ascertainable revolutions	4,096
Total number of steps	134,217,728
Measuring step	$0.3{\rm ''}$ For interpolation of the sine/cosine signals with, e. g., 12 bits
Integral non-linearity	Typ. ± 45 ", Error limits for evaluating sine/cosine period
Differential non-linearity	± 7 "
Operating speed	\leq 6,000 min ⁻¹ , up to which the absolute position can be reliably produced
Available memory area	1,792 Byte
System accuracy	± 52 "

Interfaces

Type of code for the absolute value	Binary
Code sequence	Increasing, when turning the shaft For clockwise rotation, looking in direction "A" (see dimensional drawing), For clockwise shaft rotation, looking in direction "A" (see dimensional drawing)
Communication interface	HIPERFACE [®]

Electrical data

Connection type	Cable, 8-wire, radial, 1.5 m
Supply voltage	7 V DC 12 V DC
Recommended supply voltage	8 V DC
Current consumption	80 mA ¹⁾
Output frequency for sine/cosine signals	≤ 200 kHz
MTTF: mean time to dangerous failure	235 years (EN ISO 13849) ²⁾

¹⁾ Without load

²⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 60 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Mechanical data

Shaft version	Solid shaft
Shaft diameter	10 mm
Flange type / stator coupling	Face mount flange, stator coupling
Dimensions	See dimensional drawing
Weight	≤ 0.2 kg
Moment of inertia of the rotor	25 gcm ²
Operating speed	≤ 6,000 min ⁻¹
Angular acceleration	≤ 200,000 rad/s²
Operating torque	1 Ncm
Start up torque	+ 1.5 Ncm
Permissible shaft loading	40 N (radial) 20 N (axial)
Life of ball bearings	3.6 x 10 ⁹ revolutions

Ambient data

Operating temperature range	-30 °C +85 °C
Storage temperature range	-30 °C +90 °C, without package
Relative humidity/condensation	90 %, Condensation not permitted
Resistance to shocks	100 g, 10 ms, 10 ms (according to EN 60068-2-27)
Frequency range of resistance to vibrations	20 g, 10 Hz 2,000 Hz (EN 60068-2-6)
EMC	According to EN 61000-6-2 and EN 61000-6-3 1)
Enclosure rating	IP65, with mating connector inserted (IEC 60529)

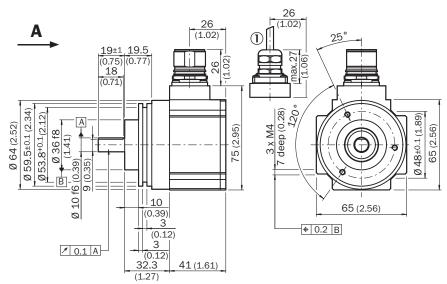
¹⁾ The EMC according to the standards quoted is achieved when the motor feedback system is mounted in an electrically conductive housing, which is connected to the central earthing point of the motor controller via a cable screen. The GND-(0 V) connection of the supply voltage is also grounded here. If other shielding concepts are used, users must perform their own tests.

Classifications

ECLASS 5.0	27270590
ECLASS 5.1.4	27270590
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270590
ECLASS 8.0	27270590
ECLASS 8.1	27270590
ECLASS 9.0	27270590
ECLASS 10.0	27273805
ECLASS 11.0	27273901
ECLASS 12.0	27273901
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))

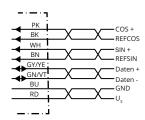
Solid shaft, servo flange, stand-alone



General tolerances according to ISO 2768-mk

① R = min. bending radius 40 mm

PIN assignment





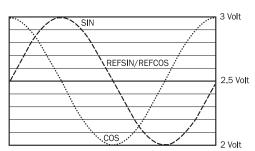
Ansicht Steckseite

Schirmanschluss am Steckergehäuse

N. C. = Not connected

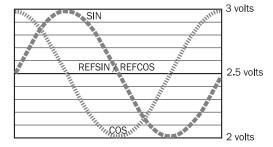
Diagrams

Signal specification of the process channel



Signal diagram for clockwise rotation of the shaft looking in direction "A" (see dimensional drawing)1 period = 360 °: 1024

Signal diagram for clockwise rotation of the shaft looking in direction "A" (see dimensional drawing)1 period = $360 \degree : 1024$



Recommended accessories

Other models and accessories → www.sick.com/SRS_SRM50

	Brief description	Туре	Part no.
Programming and configuration tools			
600	SVip® LAN programming tool for all motor feedback systems	PGT-11-S LAN	1057324
Spare parts			
	BEF-MK-S02	BEF-MK-S02	2074582
Plug connecto	ors and cables		
	 Connection type head A: Female connector, M23, 12-pin, straight Connection type head B: Flying leads Signal type: HIPERFACE[®] Cable: 3 m, 8-wire, PUR, halogen-free Description: HIPERFACE[®], shielded 	DOL-2308-G03MJB2	2031070
	Connection type head A: Female connector, M23, 12-pin, straight Connection type head B: Flying leads Signal type: HIPERFACE® Cable: 5 m, 8-wire, PUR, halogen-free Description: HIPERFACE®, shielded	DOL-2308-G05MJB2	2031071
	Connection type head A: Female connector, M23, 12-pin, straight Connection type head B: Flying leads Signal type: HIPERFACE® Cable: 10 m, 8-wire, PUR, halogen-free Description: HIPERFACE®, shielded	DOL-2308-G10MJB2	2031072
	 Connection type head A: Female connector, M23, 12-pin, straight Connection type head B: Flying leads Signal type: HIPERFACE[®] Cable: 15 m, 8-wire, PUR, halogen-free Description: HIPERFACE[®], shielded 	DOL-2308-G15MJB2	2031073
	 Connection type head A: Female connector, M23, 12-pin, straight Connection type head B: Flying leads Signal type: HIPERFACE[®] Cable: 1.5 m, 8-wire, PUR, halogen-free Description: HIPERFACE[®], shielded 	DOL-2308-G1M5JB2	2031069

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We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

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For us, that is "Sensor Intelligence."

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