#### Rotary Measuring Technology Incremental hollow shaft encoder



#### Hollow shaft version economy Type 3720



Mechanical characteristics:

Rotors moment of inertia: Starting torque:

Protection acc. to EN 60 529:

Working temperature:
Operating temperature:

Speed:

Weight:

Materials:

- Economical version
- Compact unit size only ø 37 x 32 mm
- Very easy mounting. The encoder is mounted directly on the drive shaft without couplings. This saves up to 30 % cost and 60 % clearance compared to shaft versions.
- Temperature and ageing compensation
- Short circuit proof outputs
- Resolution up to 1024 ppr
- Protection up to IP 67
- (Ex) available as explosion proof zone 2

and 22	
max. 6000 min <sup>-1</sup>	
approx. $1.4 \times 10^{-6} \text{ kgm}^2$	

< 0.01 Nm
approx. 0.1 kg
bearing, shaft: IP 65
cable outlet: IP 67
-20° C up to +70 °C1/3/4/
-20° C up to +80 °C2/3/4/

shaft: stainless steel; housing, bracket: composite PPA, 40% KF (carbon fibre) cable: PVC

Shock resistance acc. to DIN-IEC 68-2-27:  $1000 \text{ m/s}^2$ , 6 ms Vibration resistance acc. to DIN-IEC 68-2-6:  $100 \text{ m/s}^2$ ,  $10 \dots 2000 \text{ Hz}$ 

### • Bracket and cover made from a new High-Tech-Material (composite material)

- High component integration leads to low profile design, high performance and economical pricing
- "Tube Tech<sup>®</sup>" cable outlet guarantees 10x higher strain relief than traditional cabling methods plus higher IP-Protection.
- 1 ½" (37 mm) diameter housing suitable for replacing resolvers

#### Pulse rates available at short notice:

10, 50, 100, 180, 200, 250, 300, 360, 400, 500, 512, 600, 1000, 1024

Other pulse rates available on request

#### **Electrical characteristics:**

Output circuit:	RS 422	Push-pull	Push-pull				
	(TTL-compatible)	(7272) <sup>3)</sup>	(7272) <sup>3)</sup>				
Supply voltage:	5 V (±5%)	5 30 V DC	10 30 V DC				
Power consumption (no load)	typ. 40 mA /	typ.50 mA/	typ.50 mA/				
with inverted signal:	max. 90 mA	max.100 mA	max.100 mA				
Permissible load/channel:	max. ±20 mA	max. ±20 mA	max. ±20 mA				
Pulse frequency:	max. 250 kHz	max. 250 kHz	max. 250 kHz				
Signal level high:	min. 2.5 V	min. U <sub>B</sub> -2.5 V	min. U <sub>B</sub> -2.5 V				
Signal level low:	max. 0.5 V	max. 0.5 V	max. 0.5 V				
Rise time t <sub>r</sub>	max. 200 ns	max. 1 μs	max. 1 μs				
Fall time t <sub>f</sub>	max. 200 ns	max. 1 μs	max. 1 μs				
Short circuit proof outputs <sup>1)</sup> :	yes <sup>2)</sup>	yes	yes				
Reverse connection protection at $U_B$ :	no	no	yes				
Conforms to CE requirements acc. to EN 61000-6-1, EN 61000-6-4 and EN 61000-6-3							

<sup>1)</sup> If supply voltage correctly applied

3) Max. recommended cable length

2) Only one channel allowed to be shorted-out: (at  $U_B = 5 \text{ V}$  short circuit to channel, 0 V, or  $+U_B$  is permitted)

#### Applications:

- Substitute for resolversPackaging machines
- Electrical machines
- Vehicles
- Conveyers, elevators

- Semiconductor machines
   e.g. pick & place, cutting ...
- Material handling
- Special machines

<sup>1)</sup> At push pull output and Supply voltage > 15 V DC: max. 55 °C

<sup>3)</sup> Higher temperatures up to 100 °C on request

<sup>2)</sup> At push pull output and Supply voltage >15 V DC: max. 60  $^{\circ}$ C <sup>4)</sup> Non-condensing

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#### **Terminal assignment**

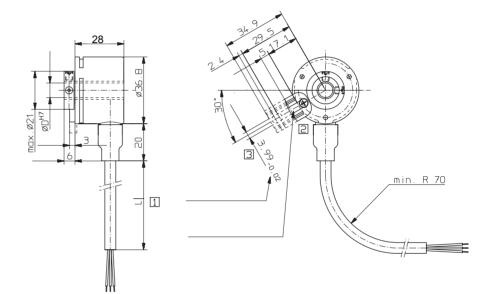
Signal:	0 V	+U <sub>B</sub>	Α	A	В	В	0	0	Shield
Colour:	WH	BN	GN	YE	GY	PK	BU	RD	

Using RS 422 outputs and long cable distances, a wave impedance has to be applied at each cable end.

Insulate unused outputs before initial startup.

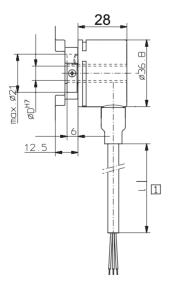
#### Dimension

Short torque stop version; Long torque stop version is dashed

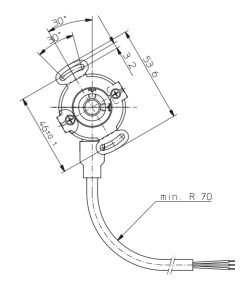


#### Stator coupling version

66



- 1 cable length 1, 2, 3 or 5 m
- 2 Slot for support torque, 3 mm deep
- Recommended pin for long torque stop Cyl. pin acc. to DIN 7 ø 4 mm



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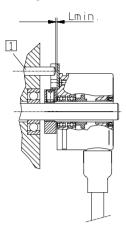
# Rotary Measurement Technology Incremental Encoders

## Rotary Measuring Technology Incremental hollow shaft encoder



#### Hollow shaft version economy Type 3720

#### Mounting advice:



1 Cyl.-pin to DIN 7 ø 4 mm

#### Mounting advice:

- The brackets and shafts of the encoder and drive should not both be rigidly coupled together at the same time.
- 2) When mounting a hollow shaft encoder, we recommend using a torque stop pin or a stator coupling.
- 3) When mounting the encoder ensure the dimension Lmin. is larger than the maximum axial play of the drive.

