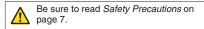
Flat Inductive Proximity Sensor

TL-W

Standard Flat Sensors in Many Different Variations

- Only 6 mm thick yet provides a sensing distance of 3 mm (TL-W3MC1).
- Aluminum die-cast models also available.





Ordering Information

DC 2-Wire Models

Appearance	Sen	Sensing distance		Model Operation mode	
				NO	NC
	5 n	nm		TL-W5MD1 *1	TL-W5MD2 *1

DC 3-Wire Models

Appearance	Sen	ensing distance			Output configuration	Model Operation mode	
						NO	NC
	1 .5 m	ım				TL-W1R5MC1 *1 *2	
Unshielded	🔲 3 mi	m				TL-W3MC1 *1 *2	TL-W3MC2
	5 r	nm			DC 3-wire, NPN	TL-W5MC1 ^{*1} *2	TL-W5MC2
			20 mm	mm		TL-W20ME1 *1	TL-W20ME2 *1
Shielded	-				DC 3-wire, NPN	TL-W5E1	TL-W5E2
5 mm		nm			DC 3-wire, PNP	TL-W5F1	TL-W5F2

*1. Models with a different frequency are also available to prevent mutual interference. The model numbers are TL-W□M□□5 (e.g., TL-W5MD15). *2. Models with robotics cables are also available. The model numbers are TL-W□MC1-R (e.g., TL-W1R5MC1-R).

Ratings and Specifications

DC 2-Wire Models

Item	Model	TL-W5MD			
Sensing	g distance	5 mm ±10%			
Set dist	ance	0 to 4 mm			
Differen	ntial travel	10% max. of sensing distance			
Detecta	ble object	Ferrous metal (The sensing distance decreases with non-ferrous metal. Refer to <i>Engineering Data</i> on page 5.)			
Standar	rd sensing object	Iron, $18 \times 18 \times 1$ mm			
Respon	se frequency *	500 Hz			
	supply voltage ing voltage range)	12 to 24 VDC (10 to 30 VDC), ripple (p-p): 10% max.			
Leakage	e current	0.8 mA max.			
Con-	Load current	3 to 100 mA			
trol output	Residual voltage	3.3 V max. (under load current of 100 mA with cable length of 2 m)			
Indicators		D1 Models: Operation indicator (red), Setting indicator (green) D2 Models: Operation indicator (red)			
Operation mode (with sensing object approaching)		D1 Models: NO Refer to the timing charts under <i>I/O Circuit Diagrams</i> on page 6 for details. D2 Models: NC			
Protecti	ion circuits	Load short-circuit protection, Surge suppressor			
Ambien	t temperature range	Operating/Storage: -25 to 70°C (with no icing or condensation)			
Ambien	t humidity range	Operating/Storage: 35% to 95% (with no condensation)			
Tempera	ature influence	$\pm 10\%$ max. of sensing distance at 23°C in the temperature range of –25 to 70°C			
Voltage	influence	$\pm 2.5\%$ max. of sensing distance at rated voltage in the rated voltage $\pm 15\%$ range			
Insulatio	on resistance	50 M Ω min. (at 500 VDC) between current-carrying parts and case			
Dielectr	ric strength	1,000 VAC for 1 min between current-carrying parts and case			
Vibratio	on resistance	Destruction: 10 to 55 Hz, 1.5-mm double amplitude for 2 hours each in X, Y, and Z directions			
Shock resistance		Destruction: 500 m/s ² 3 times each in X, Y, and Z directions			
Degree of protection		IEC 60529 IP67, in-house standards: oil-resistant			
Connec	tion method	Pre-wired Models (Standard cable length: 2 m)			
Weight	(packed state)	Approx. 45 g			
Material	Case	Heat-resistant ABS			
material	Sensing surface				
Accesso	ories	Instruction manual			

* The response frequency is an average value. Measurement conditions are as follows: standard sensing object, a distance of twice the standard sensing object, and a set distance of half the sensing distance.

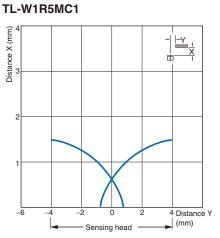


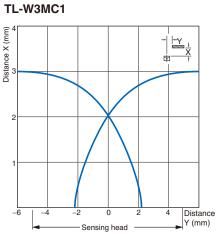
DC 3-Wire Models

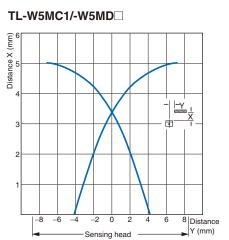
Item	Model	TL-W1R5MC1	TL-W3MC	TL-W5MC	TL-W5E1, TL-W5E2 TL-W5F1, TL-W5F2	TL-W20ME1 TL-W20ME2	
Sensing o	distance	1.5 mm ±10%	3 mm ±10%	5 mm ±10%		20 mm ±10%	
Set distar	nce	0 to 1.2 mm	0 to 2.4 mm	0 to 4 mm		0 to 16 mm	
Differentia	al travel	10% max. of sensing	distance	1		1% to 15% of sensing distance	
Detectabl	e object	Ferrous metal (The se	ensing distance decreas	ses with non-ferrous me	etal. Refer to <i>Engineering Data</i> on	page 5.)	
Standard sensing object Iron, 8 × 8		Iron, $8 \times 8 \times 1$ mm	mm Iron, $12 \times 12 \times 1$ mm Iron, $18 \times 18 \times 1$ mm			Iron, $50 \times 50 \times$ 1 mm	
Response frequency		1 kHz min.	600 Hz min.	500 Hz min.	300 Hz min.	40 Hz min.	
age (oper age range	pply volt- ating volt- e)	12 to 24 VDC (10 to 3	0 VDC), ripple (p-p): 10)% max.	12 to 24 VDC (10 to 30 VDC), ripple (p-p): 20% max.	12 to 24 VDC (10 to 30 VDC), ripple (p-p): 10% max.	
Current consump	tion	15 mA max. at 24 VD	C (no-load)	10 mA max.	15 mA max. at 24 VDC (no-load)	8 mA at 12 VDC, 15 mA at 24 VDC	
Control output	Load current	NPN open collector 100 mA max. at 30 VDC max.		NPN open collector 50 mA max. at 12 VDC (30 VDC max.) 100 mA max. at 24 VDC (30 VDC max.)	200 mA	100 mA max. at 12 VDC 200 mA max. at 24 VDC	
	Residual voltage			1 V max. (under load current of 50 mA with cable length of 2 m)	2 V max. (under load current of 200 mA with cable length of 2 m)	1 V max. (under load current of 200 mA with ca- ble length of 2 m	
Indicators	S	Detection indicator (re	ed)	1	-	1	
Operatior (with sens	sing ob-	NO	C1 Models: NO C2/B2 Models: NC	E1/F1 Models: NO E2/F2 Models: NC			
ject approaching)		Refer to the timing charts under <i>I/O Circuit Diagrams</i> on page 6 for details. Reverse polarity protection, Surge suppressor					
Protection Ambient temperatu			25 to 70°C (with no icing				
Ambient humidity		Operating/Storage: 35	5% to 95% (with no con	densation)			
Temperat influence		±10% max. of sensing	distance at 23°C in the	e temperature range of	–25 to 70°C		
Voltage influence ±2.5% max. of sensing d age in the rated voltage			sensing distance at rated volt- d voltage ±10% range±2.5% max. of sensi- ing distance at rated voltage in the rated voltage ±20% range±2.5% max. of sensing distance at rated the rated voltage ±10% range			at rated voltage in	
Insulatior resistance		50 M Ω min. (at 500 VDC) between current-carrying parts and case					
Dielectric	-	1,000 VAC, 50/60 Hz	for 1 minute between c	urrent-carrying parts ar	nd case		
Vibration resistanc		Destruction: 10 to 55	Hz, 1.5-mm double am	plitude for 2 hours each	n in X, Y, and Z directions		
Shock resistance Destruction: 500 m/s ²		² 3 times each in X, Y, and Z directions			Destruction: 500 m/s ² 10 times each in X, Y, and Z direc- tions		
Degree of IEC 60529 IP67, in-house standards: oil-res			ouse standards: oil-resis	sistant			
Connection method	on	Pre-wired Models (Sta	andard cable length: 2 r	n)			
Weight (packed s	state)	Approx. 30 g		Approx. 45 g	Approx. 70 g	Approx. 180 g	
Materi-	Case	Heat-resistant ABS			Aluminum die-cast	Heat-resistant ABS	
als	Sensing surface	Heat-resistant ABS					
Accessor	ies	Mounting Bracket, Ins	truction manual	Instruction manual			

Engineering Data (Typical)

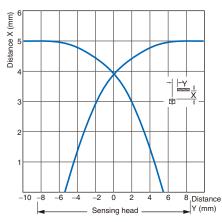
Sensing Area



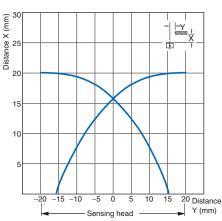






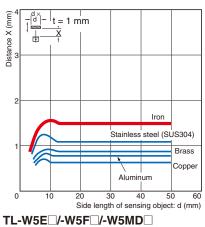


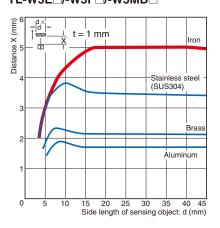


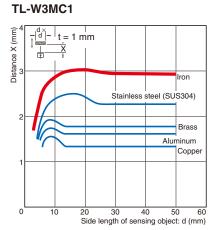


Influence of Sensing Object Size and Material

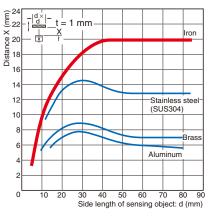
TL-W1R5MC1



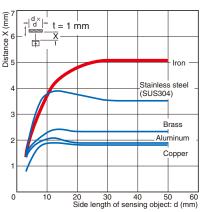








TL-W5MC1



I/O Circuit Diagrams

DC 2-Wire Models

Operation mode	Model	Timing chart	Output circuit
NO	TL-W5MD1	Unstable Set position sensing i Stable sensing object 00 80 (TYP) 0 (%) Tated sensing i GN GFF Setting indicator (green) ON OFF Operation indicator (red) ON OFF Control output	Proximity Sensor main circuit Blue
NC	TL-W5MD2	Non-sensing area Sensing area Proximity Sensor Sensing indicator 100 0 (%) 100 0 Rated sensing distance ON OFF Operation indicator (red) ON OFF OFF Control output	Note: The load can be connected to either the +V or 0 V side.

DC 3-Wire Models

Operation mode	Model	Timing chart	Output circuit
NO	TL-W1R5MC1 TL-W3MC1 TL-W5MC1	Sensing object Present Not present Output transistor ON (load) OFF Detection indicator (red) ON OFF	Proximity Sensor → H → H → H → H → H → H → H → H → H →
NC	TL-W3MC2 TL-W5MC2	Sensing object Present Not present Output transistor ON OFF Detection indicator OFF OFF	* Load current: 100 mA max.
NO	TL-W5E1 TL-W20ME1	Sensing object Present Not present Load (between brown and black leads) Operate Reset Output voltage (between black and blue leads) High Low Detection indicator (red) ON OFF	Proximity Sensor main 2.2 Ω Output
NC	TL-W5E2 TL-W20ME2	Sensing object Present Not present Load (between brown and black leads) Operate Reset Output voltage (between black and blue leads) High Low Detection indicator (red) ON OFF	*1. Load current: 200 mA max. *2. When a transistor is connected.
NO	TL-W5F1	Sensing object Present Not present Load (between blue and black leads) Operate Reset Output voltage (between blue and black leads) High Low Detection indicator (red) ON OFF	Proximity Sensor main circuit 2.2 Ω Output
NC	TL-W5F2	Sensing object Present Not present Load (between blue and black leads) Operate Reset Output voltage (between blue and black leads) High Low Detection indicator (red) ON OFF	 4.7 kΩ 100 Ω Blue 0 V *1. Load current: 200 mA max. *2. When a transistor is connected.

Safety Precautions

Refer to Warranty and Limitations of Liability.

<u> WARNING</u>

This product is not designed or rated for ensuring safety of persons either directly or indirectly. Do not use it for such purposes.



Precautions for Correct Use

Do not use this product under ambient conditions that exceed the ratings.

• Design

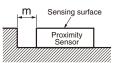
Model

TL-W1R5MC1

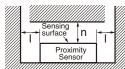
Influence of Surrounding Metal

When mounting the Sensor within a metal panel, ensure that the clearances given in the following table are maintained. Failure to maintain these distances may cause deterioration in the performance of the Sensor.

Metal on a Single Side (Not Exceeding the Height of the Sensor Surface)



Metals on Both Sides and in Front of the Sensor



Influence of Surrounding Metal

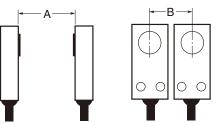
Di

nding Metal (Unit: mr			
stance	I	m	n
	2		8

TL-W3MC	3	0	12
TL-W5MD	5	0	20
TL-W5MC1			20
TL-W20ME	25	16	100
TL-W5E /-W5F	0	0	20

Mutual Interference

When installing Sensors face-to-face or side-by-side, ensure that the minimum distances given in the following table are maintained.



Mutual Interference

(Unit: mm)

Model Distance	А	В	
TL-W1R5MC1	75 (50)	25 (8)	
TL-W3MC	90 (60)	30 (10)	
TL-W5MD	120 (80)	60 (30)	
TL-W5MC1	120 (80)	00 (30)	
TL-W20ME	200 (100)	200 (100)	
TL-W5E /-W5F	50	35	

Note: Values in parentheses apply to Sensors operating at different frequencies.

Mounting

- Use M3 flat-head screws to mount the TL-W1R5MC1 and TL-W3MC1.
- Do not exceed the torque in the following table when tightening the resin cover screws.

Model	Torque
TL-W1R5MC1	
TL-W3MC	0.98 N⋅m
TL-W5MD	
TL-W20M	1.5 N⋅m

Adjustment

Turning ON the Power

An error pulse will occur (approximately 1 ms) if adjustments are made when turning ON the power or making AND connections.

Applicable e-CON Connector Models and Manufacturers

The companies and model number of e-CON connections that can be used with Sensor cables are listed in the following table. Confirm applicability when purchasing e-CON connectors for connection to Pre-wired Sensors.

Model	Tyco Electronics AMP K.K.
TL-W1R5□/-W3□	1-1473562-4 (red)

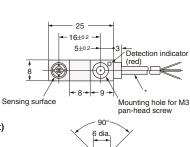
TL-W

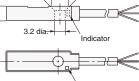
(Unit: mm)

Dimensions

TL-W1R5MC1





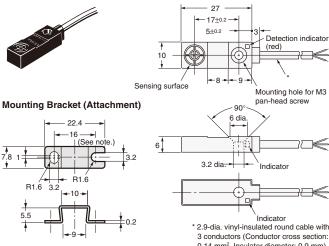


Indicator 2.9-dia. vinyl-insulated round cable with 3 conductors (Conductor cross section: 0.14 mm², Insulator diameter: 0.9 mm), Standard length: 2 m

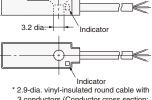
TL-W5E

TL-W5F





Note: Mounting hole dimension: 17 \pm 0.20. Material: Stainless steel (SUS304)



3 conductors (Conductor cross section: 0.14 mm², Insulator diameter: 0.9 mm), Standard length: 2 m

Material: Stainless steel (SUS304)

Mounting Bracket (Attachment)

22.4

B1.6

Note: Mounting hole dimension: 17 \pm 0.2.

+8-

5.5

32

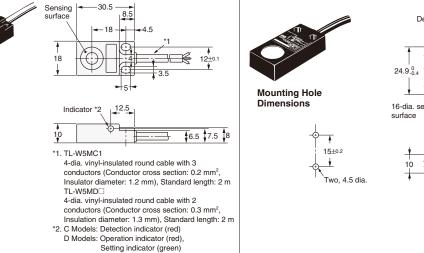
0.2

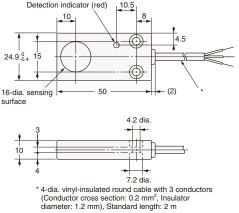
TL-W5MC TL-W5MD

₹ 7.8 1:

R1.6

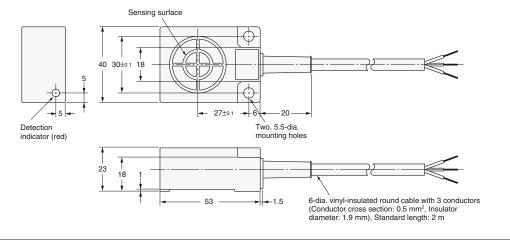
3.2





TL-W20ME





Proximity Sensors Technical Guide

General Precautions For precautions on individual products, refer to the Safety Precautions in individual product information.

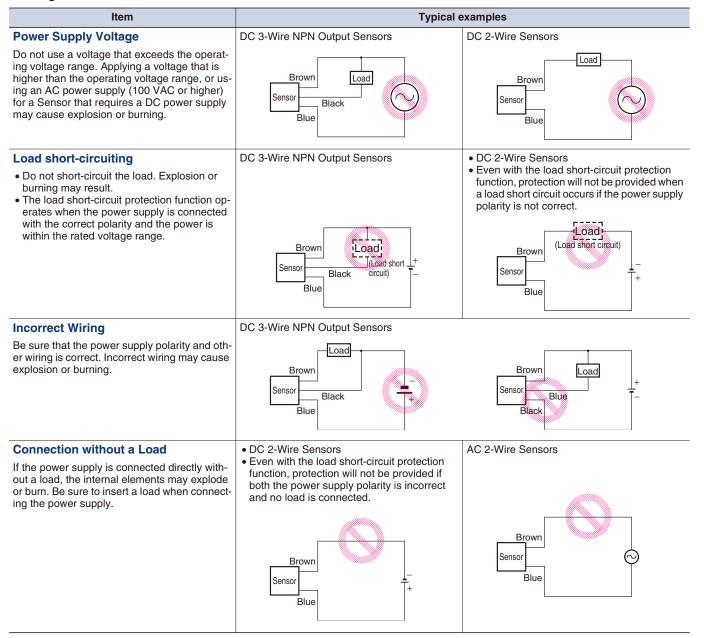


Precautions for Safe Use

To ensure safety, always observe the following precautions.

Wiring Considerations

life.



Operating Environment

Do not use the Sensor in an environment where there are explosive or combustible gases.

Precautions for Correct Use

The following conditions must be considered to understand the conditions of the application and location as well as the relation to control equipment.

Model Selection

Item		Points of conside	eration
	Check the relation between the sensing object and the Proximity Sensor.	Specific condi- tions of object	Direction of ob- Peripheral metal Sensing distance ject movement
Sensing object and operating condition of Proximity Sensor	Sensing object Surrounding Metals Proximity Sensor	beam, grooved), shielded Sensor	Transit interval, Material, distance Fluctuation in tran- speed, existence to Sensor, orien-sit point, allowable of vibration, etc. tation, etc. error, etc. stance, shape of Sensor (rectangular, cylindrical, through- , influence of peripheral metal (Shielded Sensors, Non- 's), response speed (response frequency), influence of luence of voltage, etc.
	Verify the electrical conditions of the control syste to be used and the electrical performance of the Proximity Sensor.	Power pacity supply AC (vol	or S3D2 Controller
Electrical conditions		Load – Inducti • Stea • Ope Lamp I • Stea	ve load - Non-contact control system ve load - Relay, solenoid, etc. dy-state current, inrush current rating, reset voltage (current) load dy-state current, inrush current close frequency Selecting the power supply type DC DC + S3D2 Controlle AC - Control output Maximum current (voltage) - Leakage current - Residual load voltage
Environ- mental conditions	The environmental tolerance is better than that of other type investigate carefully before us under harsh temperatures or Temperature Highest or low and humidity values, existe of direct sunlig etc. Atmosphere —Water, oil, iron powder, or oth special chemi Vibration and—Size, duration shock	es of Sensors. However sing a Proximity Sen in special atmospher high-temperature in low temperature low temperature need for shade her - Need for water tance or oil res need for explo proof structure	 ver, sor res. Ambient Conditions To maintain reliability of operation, do not use the filuence, Sensor outside the specified temperature range or ure use, outdoors. Even though the Proximity Sensor has a water-resistant structure, it must be covered to prevent direct contact with water or water-soluble cutting oil. Do not use the Sensor in atmospheres with chemical vapors, in particular, strong alkalis or acids (nitrisistance, acid, chromic acid, or hot concentrated sulfuric acid sion- Explosive Atmospheres
Mounting conditions	Wiring method, existence of in- ductance surges Connection	rictions due to mech and inspection, and pe, length, oil-resista shielded cable, robot	Installation location — Ease of maintenance and Linspection, mounting space
Influence of external electromag- netic fields	The influence within a DC magnetic field is 20 r	nT* max. Do not use cause malfunction. D	Do not use the Sensor for applications that involve turning a

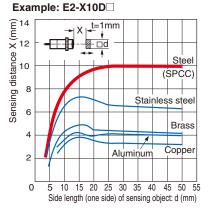
 * mT (millitesla) is a unit for expressing magnetic flux density. One tesla is the equivalent of 10,000 gauss.

Design

Sensing Object Material

The sensing distance varies greatly depending on the material of the sensing object. Study the engineering data for the influence of sensing object material and size and select a distance with sufficient leeway.

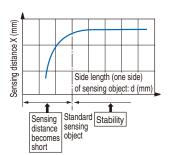
 In general, if the sensing object is a nonmagnetic metal (for example, aluminum), the sensing distance decreases.



Size of Sensing Object

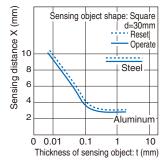
In general, if the object is smaller than the standard sensing object, the sensing distance decreases.

- Design the setup for an object size that is the same or greater than the standard sensing object size from the graphs showing the sensing object size and sensing distance.
- When the size of the standard sensing object is the same or less than the size of the standard sensing object, select a sensing distance with sufficient leeway.



Thickness of Sensing Object

- The thickness of ferrous metals (iron, nickel, etc.) must be 1 mm or greater.
- When the coating thickness is 0.01 mm or less, a sensing distance equivalent to a magnetic body can be obtained. When the coating is extremely thin and is not conductive, such as a vacuum deposited film, detection is not possible.
- Influence of Plating If the sensing object is plated, the sensing distance will change (see the table below).



Effect of Plating (Typical)

(nelefence values. reicent of non-plated sensing distance)			
Thickness and base material of plating	Steel	Brass	
No plating	100	100	
Zn 5 to 15 μ m	90 to 120	95 to 105	
Cd 5 to 15 μm	100 to 110	95 to 105	
Ag 5 to 15 μ m	60 to 90	85 to 100	
Cu 10 to 20 μm	70 to 95	95 to 105	
Cu 5 to 15 μm	-	95 to 105	
Cu (5 to 10 μm) + Ni (10 to 20 μm)	70 to 95	-	
Cu (5 to 10 μm) + Ni (10 μm) + Cr (0.3 μm)	75 to 95	-	

(Reference values: Percent of non-plated sensing distance)

Mutual Interference

- Mutual interference refers to a state where a Sensor is affected by magnetism (or static capacitance) from an adjacent Sensor and the output is unstable.
- One means of avoiding interference when mounting Proximity Sensors close together is to alternate Sensors with different frequencies. The model tables indicate whether different frequencies are available. Please refer to the tables.
- When Proximity Sensors with the same frequency are mounted together in a line or face-to-face, they must be separated by a minimum distance. For details, refer to *Mutual Interference* in the *Safety Precautions* for individual Sensors.

Power Reset Time

A Sensor is ready for detection within 100 ms after turning ON the power. If the load and Sensor are connected to separate power supplies, design the system so that the Sensor power turns ON first.

http://www.ia.omron.com/

Turning OFF the Power

An output pulse may be generated when the power is turned OFF, so design the system so that the load or load line power turns OFF first.

Influence of Surrounding Metal

The existence of a metal object other than the sensing object near the sensing surface of the Proximity Sensor will affect detection performance, increase the apparent operating distance, degrade temperature characteristics, and cause reset failures. For details, refer to the influence of surrounding metal table in *Safety Precautions* for individual Sensors.

The values in the table are for the nuts provided with the Sensors. Changing the nut material will change the influence of the surrounding metal.

Power Transformers

Be sure to use an insulated transformer for a DC power supply. Do not use an auto-transformer (single-coil transformer).

Precautions for AC 2-Wire/DC 2-Wire Sensors

Surge Protection

Although the Proximity Sensor has a surge absorption circuit, if there is a device (motor, welder, etc.) that causes large surges near the Proximity Sensor, insert a surge absorber near the source of the surges.

Influence of Leakage Current

Even when the Proximity Sensor is OFF, a small amount of current runs through the circuit as leakage current.

For this reason, a small current may remain in the load (residual voltage in the load) and cause load reset failures. Verify that this voltage is lower than the load reset voltage (the leakage current is less than the load reset current) before using the Sensor.

Using an Electronic Device as the Load for an AC 2-Wire Sensor

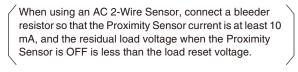
When using an electronic device, such as a Timer, some types of devices use AC half-wave rectification. When a Proximity Sensor is connected to a device using AC half-wave rectification, only AC half-wave power will be supplied to the Sensor. This will cause the Sensor operation to be unstable. Also, do not use a Proximity Sensor to turn the power supply ON and OFF for electronic devices that use DC half-wave rectification. In such a case, use a relay to turn the power supply ON and OFF, and check the system for operating stability after connecting it.

Examples of Timers that Use AC Half-wave Rectification Timers: H3Y, H3YN, H3RN, H3CA-8, RD2P, and H3CR (-A, -A8, -AP, -F, -G)

Countermeasures for Leakage Current (Examples)

AC 2-Wire Sensors

Connect a bleeder resistor to bypass the leakage current flowing in the load so that the current flowing through the load is less than the load reset current.





Calculate the bleeder resistance and allowable power using the following equation.

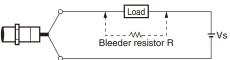
$$R \leq \frac{Vs}{10 - I} (k\Omega)$$
 $P > \frac{Vs^2}{R} (mW)$

- P : Watts of bleeder resistance (the actual number of watts used should be several times this number)
- I : Load current (mA)

It is recommend that leeway be included in the actual values used. For 100 VAC, use 10 k Ω or less and 3 W (5 W) or higher, and for 200 VAC, use 20 k Ω or less and 10 W (20 W) or higher. If the effects of heat generation are a problem, use the number of watts in parentheses () or higher.

DC 2-Wire Sensors

Connect a bleeder resistor to bypass the leakage current flowing in the load, and design the load current so that (leakage current) \times (load input impedance) < reset voltage.



Calculate the bleeder resistance and allowable power using the following equation.

$$R \leq \frac{Vs}{i_{R} - i_{OFFR}} (k\Omega) \qquad P > \frac{Vs^{2}}{R} (mW$$

- P : Watts of bleeder resistance (the actual number of watts used should be several times this number)
 - : Leakage current of Proximity Sensor (mA)
- iOFF : Load reset current (mA)

İR

It is recommend that leeway be included in the actual values used. For 12 VDC, use 15 k Ω or less and 450 mW or higher, and for 24 VDC, use 30 k Ω or less and 0.1 W or higher.

Loads with Large Inrush Current

Loads, such as lamps or motors, that cause a large inrush current* will weaken or damage the switching element. In this situation, use a relay.

* E2K, TL-N Y: 1 A or higher

Mounting

Mounting the Sensor

When mounting a Sensor, do not tap it with a hammer or otherwise subject it to excessive shock. This will weaken water resistance and may damage the Sensor. If the Sensor is being secured with bolts, observe the allowable tightening torque. Some models require the use of toothed washers.

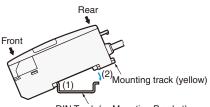
For details, refer to the mounting precautions in *Precautions for Correct Use* in individual product information.

Mounting/Removing Using DIN Track

(Example for E2CY)

<Mounting>

- (1)Insert the front of the Sensor into the special Mounting Bracket (included) or DIN Track.
- (2)Press the rear of the Sensor into the special Mounting Bracket or DIN Track.



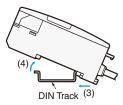
DIN Track (or Mounting Bracket)

• When mounting the side of the Sensor using the special Mounting Bracket, first secure the Amplifier Unit to the special Mounting Bracket, and then mount the special Mounting Bracket with M3 screws and flat washers with a diameter of 6 mm maximum.



<Removing>

• While pressing the Amplifier Unit in the direction of (3), lift the fiber plug in the direction of (4) for easy removal without a screwdriver.



Set Distance

The sensing distance may vary due to fluctuations in temperature and voltage. When mounting the Sensor, it is recommend that installation be based on the set distance.

•Wiring Considerations AND/OR Connections for Proximity Sensors

Model	Type of connection	Connection	Description
DC 2-Wire	AND (series connection)		$\label{eq:second} \begin{array}{l} \mbox{Keep the number of connected Sensors (N) within the range of the following equation.} \\ Vs - N \times V_R \geq \mbox{Operating load voltage} \\ \begin{tabular}{lllllllllllllllllllllllllllllllllll$
	OR (parallel connection)		$\label{eq:constraint} \begin{array}{l} \mbox{Keep the number of connected Sensors (N) within the range of the following equation.} \\ N \times i \leq \mbox{Load reset current} \\ \hline N: \mbox{Number of Sensors that can be connected} \\ i: \mbox{Leakage current of Proximity Sensor} \\ \hline \mbox{Example: When an MY (24-VDC) Relay is used as the load, the maximum number of Sensors that can be connected is 4.} \end{array}$
AC 2-wire	AND (series connection)	Vs Vs Vs Vs Vs Vs Vs Vs Vs Vs	<pre><tl-ny, e2k-□my□,="" tl-my,="" tl-t□y=""> The above Proximity Sensors cannot be used in a sereis connection. If need- ed, connect through relays. </tl-ny,></pre> <e2e-x□y> For the above Proximity Sensors, the voltage VL that can be applied to the load when ON is VL = Vs - (Output residual voltage × Number of Sensors), for both 100 VAC and 200 VAC. The load will not operate unless VL is higher than the load operating voltage. This must be verified before use. When using two or more Sensors in series with an AND circuit, the limit is three Sensors. (Be careful of the VS value in the diagram at left.)</e2e-x□y>
	OR (parallel connection)	(A) (A) (A) (A) (A) (B) (B) (B) (C) (C) (C) (C) (C) (C) (C) (C	In general it is not possible to use two or more Proximity Sensors in parallel with an OR circuit. A parallel connection can be used if A and B will not be operated simultaneously and there is no need to hold the load. The leakage current, however, will be n times the value for each Sensor and reset failures will frequently occur. ("n" is the number of Proximity Sensors.) If A and B will be operated simultaneously and the load is held, a parallel connection is not possible. If A and B operate simultaneously and the load is held, the voltages of both A and B will fall to about 10 V when A turns ON, and the load current will flow through A causing random operation. When the sensing object approaches B, the voltage of both therminals of B is too low at 10 V and the switching element of B will not operate. When A turns OFF again, the voltages of both A and B rise to the power supply voltage and B is finally able to turn ON. During this period, there are times when A and B both turn OFF (approximately 10 ms) and the loads are momentarily restored. In cases where the load is to be held in this way, use a relay as shown in the diagram at left.

Note: When AND/OR connections are used with Proximity Sensors, the effects of erroneous pulses or leakage current may prevent use. Verify that there are no problems before use.

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Model	Type of connection	Connection	Description
DC 3-wire	AND (series connection)		Keep the number of connected Sensors (N) within the range of the following equation. iL + (N - 1) × i ≤ Upper limit of Proximity Sensor control output Vs - N × VR ≥ Operating load voltage (N : Number of Sensors that can be connected) NR: Residual output voltage of Sensor Vs: Power supply voltage i : Current consumption of Sensor iL: Load current Note: When an AND circuit is connected, the operation of Proximity Sensor B causes power to be supplied to Proximity Sensor A, and thus erroneous pulses (approximately 1 ms) may be generated in A when the power is turned ON. For this reason, take care when the load has a high response speed because malfunction may result.
	OR (parallel connection)	Vs	For Sensors with a current output, a minimum of three OR connections is pos- sible. Whether or not four or more connections is possible depends on the model.

Note: When AND/OR connections are used with Proximity Sensors, the effects of erroneous pulses or leakage current may prevent use. Verify that there are no problems before use.

Extending Cable Length

The cable of a Built-in Amplifier Sensor can be extended to a maximum length of 200 m with each of the standard cables (excluding some models).

For Separate Amplifier Sensors (E2C-EDA, E2C, E2J, E2CY), refer to the specific precautions for individual products.

Bending the Cable

If you need to bend the cable, we recommend a bend radius that is at least 3 times the outer diameter of the cable (with the exception of coaxial and shielded cables).

Cable Tensile Strength

In general, do not subject the cable to a tension greater than that indicated in the following table.

Cable diameter	Tensile strength
Less than 4 mm	30 N max.
4 mm min.	50 N max.

Note: Do not subject a shielded cable or coaxial cable to tension.

Separating High-voltage Lines

Using Metal Conduits

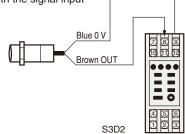
If a power line is to be located near the Proximity Sensor cable, use a separate metal conduit to prevent malfunction or damage. (Same for DC models.)

Example of Connection with S3D2 Sensor Controller

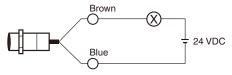
DC 2-Wire Sensors

Using the S3D2 Sensor Controller

Operation can be reversed with the signal input switch on the S3D2.



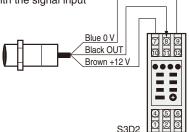
Connecting to a Relay Load



Note: DC 2-Wire Sensors have a residual voltage of 3 V. Check the operating voltage of the relay before use. The residual voltage of the E2E-XD-M1J-T is 5 V.

DC 3-Wire Sensors

Operation can be reversed with the signal input switch on the S3D2.



Operating Environment

Water Resistance

Do not use the Sensor in water, rain, or outdoors.

Ambient Conditions

Do not use the Sensor in the following environments.

Doing so may cause malfunction or failure of the Sensor.

- To maintain operational reliability and service life, use the Sensor only within the specified temperature range and do not use it outdoors.
- 2. The Sensor has a water resistant structure, however, attaching a cover to prevent direct contact with water will help improve reliability and prolong product life.
- Avoid using the Sensor where there are chemical vapors, especially strong alkalis or acids (nitric acid, chromic acid, or hot concentrated sulfuric acid).

Maintenance and inspection

Periodic Inspection

To ensure long-term stable operation of the Proximity Sensor, inspect for the following on a regular basis. Conduct these inspections also for control devices.

- 1. Shifting, loosening, or deformation of the sensing object and Proximity Sensor mounting
- 2. Loosening, bad contact, or wire breakage in the wiring and connections
- 3. Adherence or accumulation of metal powder
- 4. Abnormal operating temperature or ambient conditions
- 5. Abnormal indicator flashing (on setting indicator types)

Disassembly and Repair

Do not under any circumstances attempt to disassemble or repair the product.

Quick Failure Check

You can conveniently check for failures by connecting the E39-VA Handy Checker to check the operation of the Sensor.



Please read and understand this catalog before purchasing the products. Please consult your OMRON representative if you have any questions or comments.

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- · Systems, machines, and equipment that could present a risk to life or property.

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