GPS Receiver Module LS-40CM

LS-40CM

Fast Acquisition Enhanced Sensitivity 12 Channel GPS Sensor Module

FEATURES

- 12 parallel channel GPS receiver
- 4000 simultaneous time-frequency search bins
- SBAS (WAAS, EGNOS) support
- On-board switch circuitry to support direct connection to active antenna
- High Sensitivity:
  - -137dBm acquisition sensitivity
  - -145dBm tracking sensitivity
- Fast Acquisition:
  - < 10 second hot start
  - < 45 second cold start
- 5m CEP accuracy

The LS-40CM is a compact all-in-one GPS module solution intended for a broad range of Original Equipment Manufacturer (OEM) products, where fast and easy system integration and minimal development risk is required.

The receiver continuously tracks all satellites in view and provides accurate satellite positioning data. The LS-40CM is optimized for applications requiring good performance, low cost, and maximum flexibility; suitable for a wide range of OEM configurations including handhelds, sensors, asset tracking, PDA-centric personal navigation system, and vehicle navigation products.

Its 12 parallel channels and 4000 search bins provide fast satellite signal acquisition and short startup time. Acquisition sensitivity of –137dBm and tracking sensitivity of –145dBm offers good navigation performance even in urban canyons having limited sky view.

Satellite-based augmentation systems, such as WAAS and EGNOS, are supported to yield improved accuracy.

The onboard patch antenna provides good signal reception. Under situations where the LS-40CM is integrated into an application where the patch antenna has limited view of the sky, external active antenna may be directly connected via the MMCX connector to provide improved signal reception.

Both the LVTTL-level and RS232-level serial interface are provided on the interface connector. Supply voltage of 3.3V, or 3.8V~12V are supported.

Ordering Information

Part Number	Description
LS-40CM	GPS Module, 12 Channel, onboard Antenna & RF Connector
GPSANT-MMCX	GPS Antenna with MMCX Connection
CBA-LS-40M	Cable assembly for LS-40xM modules

Tel 01273 898000 Fax 01273 480661

TECHNICAL SPECIFICATIONS

Receiver Type	12 parallel channel, L1 C/A code
Accuracy	Position 5m CEP Velocity 0.1m/sec
Startup Time	< 10sec hot start < 35sec warm start < 45sec cold start
Signal Reacquisition	1s
Sensitivity	-137dBm acquisition -145dBm tracking
Update Rate	1Hz
Dynamics	4G (39.2m/sec^2)
Operational Limits	Altitude < 18,000m or velocity < 515m/s (COCOM limit, either may be exceeded but not both)
Serial Interface	LVTTL level and RS-232 level
Protocol	NMEA-0183 V3.01 GPGGA, GPGLL, GPGSA, GPGSV, GPRMC, GPVTG, GPZDA 4800 baud, 8, N, 1
Datum	Default WGS-84 User definable
RF Connector	MMCX
Interface Connector	Two 1.0mm pitch WTB S/R wafer 87213 SMT R/A type connector
Cable Assembly	SIL socket to tinned wires, 150mm
Input Voltage	3.3V DC +/-100mV 3.8V ~ 12.0V
Current Consumption	90 ~ 110mA
Dimension	43mm L x 42mm W x 13mm H
Weight:	24g
Operating Temperature	-40^{o}C ~ +85^{o}C
Humidity	5% ~ 95%

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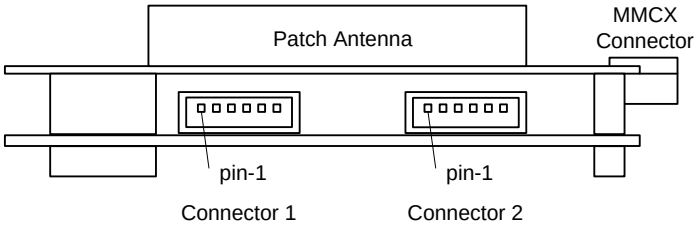

LS-40CM Lateral View

PINOUT DESCRIPTION

Connector 1

Used for systems that have supply voltage higher than 3.3V, and requires RS-232 level serial output interface.

Pin Number	Signal Name	Description
1	Serial Data Out 1	Asynchronous serial output at LVTTL level, to output NMEA message
2	Serial Data In 1	Asynchronous serial input at LVTTL level, to input configuration commands
3	Serial Data Out 2	Asynchronous serial output at RS-232 level, to output NMEA message
4	Serial Data In 2	Asynchronous serial input at RS-232 level, to input configuration commands
5	Power 1	3.8V ~ 12.0V DC input
6	Ground	Power and signal ground

Connector 2

Used for systems that have supply voltage of 3.3V, and requires 3.3V LVTTL serial output interface.

Pin Number	Signal Name	Description
1	Ground	Power and signal ground
2	Ground	Power and signal ground
3	NC	No connection
4	Serial Data In 1	Asynchronous serial input at LVTTL level, to input configuration commands
5	Serial Data Out 1	Asynchronous serial output at LVTTL level, to output NMEA message
6	Power 2	3.3V DC input

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NMEA Messages

The serial interface protocol is based on the National Marine Electronics Association's NMEA 0183 ASCII interface specification. This standard is fully define in "NMEA 0183, Version 3.01" The standard may be obtained from NMEA, www.nmea.org

GGA - GPS FIX DATA
Time, position and position-fix related data (number of satellites in use, HDOP, etc.).

Format:
$GPGGA,<1>,<2>,<3>,<4>,<5>,<6>,<7>,<8>,<9>,M,<10>,M,<11>,<12>,*<13><CR><LF>

Example:
$GPGGA,104549.04,2447.2038,N,12100.4990,E,1,06,01.7,00078.8,M,0016.3,M,,*5C<CR><LF>

Field	Example	Description
1	104549.04	UTC time in hhmmss.ss format, 000000.00 ~ 235959.99
2	2447.2038	Latitude in ddmm.mmmm format Leading zeros transmitted
3	N	Latitude hemisphere indicator, 'N' = North, 'S' = South
4	12100.4990	Longitude in dddmm.mmmm format Leading zeros transmitted
5	E	Longitude hemisphere indicator, 'E' = East, 'W' = West
6	1	Position fix quality indicator 0: position fix unavailable 1: valid position fix, SPS mode 2: valid position fix, differential GPS mode
7	06	Number of satellites in use, 00 ~ 12
8	01.7	Horizontal dilution of precision, 00.0 ~ 99.9
9	00078.8	Antenna height above/below mean sea level, -9999.9 ~ 17999.9
10	0016.3	Geoidal height, -999.9 ~ 9999.9
11		Age of DGPS data since last valid RTCM transmission in xxx format (seconds) NULL when DGPS not used
12		Differential reference station ID, 0000 ~ 1023 NULL when DGPS not used
13	5C	Checksum

Note: The checksum field starts with a '*' and consists of 2 characters representing a hex number. The checksum is the exclusive OR of all characters between '$' and '*'.

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GLL - LATITUDE AND LONGITUDE, WITH TIME OF POSITION FIX AND STATUS
Latitude and longitude of current position, time, and status.

Format:
$GPGLL,<1>,<2>,<3>,<4>,<5>,<6>,<7>*<8><CR><LF>

Example:
$GPGLL,2447.2073,N,12100.5022,E,104548.04,A,A*65<CR><LF>

Field	Example	Description
1	2447.2073	Latitude in ddmm.mmmm format Leading zeros transmitted
2	N	Latitude hemisphere indicator, ‘N’ = North, ‘S’ = South
3	12100.5022	Longitude in dddmm.mmmm format Leading zeros transmitted
4	E	Longitude hemisphere indicator, 'E' = East, 'W' = West
5	104548.04	UTC time in hhmmss.ss format, 000000.00 ~ 235959.99
6	A	Status, ‘A’ = valid position, ‘V’ = navigation receiver warning
7	A	Mode indicator ‘N’ = Data invalid ‘A’ = Autonomous ‘D’ = Differential ‘E’ = Estimated
8	65	Checksum

GSA - GPS DOP AND ACTIVE SATELLITES
GPS receiver operating mode, satellites used for navigation, and DOP values.

Format:
$GPGSA,<1>,<2>,<3>,<3>,<3>,<3>,<3>,<3>,<3>,<3>,<3>,<3>,<3>,<3>,<3>,<4>,<5>,<6>*<7><CR><LF>

Example:
$GPGSA,A,3,26,21,,,09,17,,,,,,,10.8,02.1,10.6*07<CR><LF>

Field	Example	Description
1	A	Mode, ‘M’ = Manual, ‘A’ = Automatic
2	3	Fix type, 1 = not available, 2 = 2D fix, 3 = 3D fix
3	26,21,,,09,17,,,,,,	PRN number, 01 to 32, of satellite used in solution, up to 12 transmitted
4	10.8	Position dilution of precision, 00.0 to 99.9
5	02.1	Horizontal dilution of precision, 00.0 to 99.9
6	10.6	Vertical dilution of precision, 00.0 to 99.9
7	07	Checksum

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GSV - GPS SATELLITE IN VIEW
Number of satellites in view, PRN number, elevation angle, azimuth angle, and C/No. Only up to four satellite details are transmitted per message. Additional satellite in view information is sent in subsequent GSV messages.

Format:
$GPGSV,<1>,<2>,<3>,<4>,<5>,<6>,<7>,…,<4>,<5>,<6>,<7> *<8><CR><LF>

Example:
$GPGSV,2,1,08,26,50,016,40,09,50,173,39,21,43,316,38,17,41,144,42*7C<CR><LF>
$GPGSV,2,2,08,29,38,029,37,10,27,082,32,18,22,309,24,24,09,145,*7B<CR><LF>

Field	Example	Description
1	2	Total number of GSV messages to be transmitted
2	1	Number of current GSV message
3	08	Total number of satellites in view, 00 ~ 12
4	26	Satellite PRN number, GPS: 01 ~ 32, SBAS: 33 ~ 64 (33 = PRN120)
5	50	Satellite elevation number, 00 ~ 90 degrees
6	016	Satellite azimuth angle, 000 ~ 359 degrees
7	40	C/No, 00 ~ 99 dB Null when not tracking
8	7C	Checksum

RMC - RECOMMANDED MINIMUM SPECIFIC GPS/TRANSIT DATA
Time, date, position, course and speed data.

Format:
$GPRMC,<1>,<2>,<3>,<4>,<5>,<6>,<7>,<8>,<9>,<10>,<11>,<12>*<13><CR><LF>

Example:
$GPRMC,104549.04,A,2447.2038,N,12100.4990,E,016.0,221.0,250304,003.3,W,A*22<CR><LF>

Field	Example	Description
1	104549.04	UTC time in hhmmss.ss format, 000000.00 ~ 235959.99
2	A	Status, ‘V’ = navigation receiver warning, ‘A’ = valid position
3	2447.2038	Latitude in dddmm.mmmm format Leading zeros transmitted
4	N	Latitude hemisphere indicator, ‘N’ = North, ‘S’ = South
5	12100.4990	Longitude in dddmm.mmmm format Leading zeros transmitted
6	E	Longitude hemisphere indicator, 'E' = East, 'W' = West
7	016.0	Speed over ground, 000.0 ~ 999.9 knots
8	221.0	Course over ground, 000.0 ~ 359.9 degrees
9	250304	UTC date of position fix, ddmmyy format
10	003.3	Magnetic variation, 000.0 ~ 180.0 degrees
11	W	Magnetic variation direction, ‘E’ = East, ‘W’ = West
12	A	Mode indicator ‘N’ = Data invalid ‘A’ = Autonomous ‘D’ = Differential

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		'E' = Estimated
13	22	Checksum

VTG - COURSE OVER GROUND AND GROUND SPEED
Velocity is given as course over ground (COG) and speed over ground (SOG).

Format:
GPVTG,<1>,T,<2>,M,<3>,N,<4>,K,<5>*<6><CR><LF>

Example:

$GPVTG,221.0,T,224.3,M,016.0,N,0029.6,K,A*1F<CR><LF>

Field	Example	Description
1	221.0	True course over ground, 000.0 ~ 359.9 degrees
2	224.3	Magnetic course over ground, 000.0 ~ 359.9 degrees
3	016.0	Speed over ground, 000.0 ~ 999.9 knots
4	0029.6	Speed over ground, 0000.0 ~ 1800.0 kilometers per hour
5	A	Mode indicator 'N' = Data invalid 'A' = Autonomous 'D' = Differential 'E' = Estimated
6	1F	Checksum

ZDA TIME AND DATE

Format:
$GPZDA,<1>,<2>,<3>,<4>,<5>,<6>*<7><CR><LF>

Example:

$GPZDA,104548.04,25,03,2004,,*6C<CR><LF>

Field	Example	Description
1	104548.04	UTC time in hhmmss.ss format, 000000.00 ~ 235959.99
2	25	UTC time: day (01 ... 31)
3	03	UTC time: month (01 ... 12)
4	2004	UTC time: year (4 digit year)
5		Local zone hour Not being output by the receiver (NULL)
6		Local zone minutes Not being output by the receiver (NULL)
7	6C	Checksum

Binary Messages

See *Binary Message Protocol User's Guide* for detailed descriptions.

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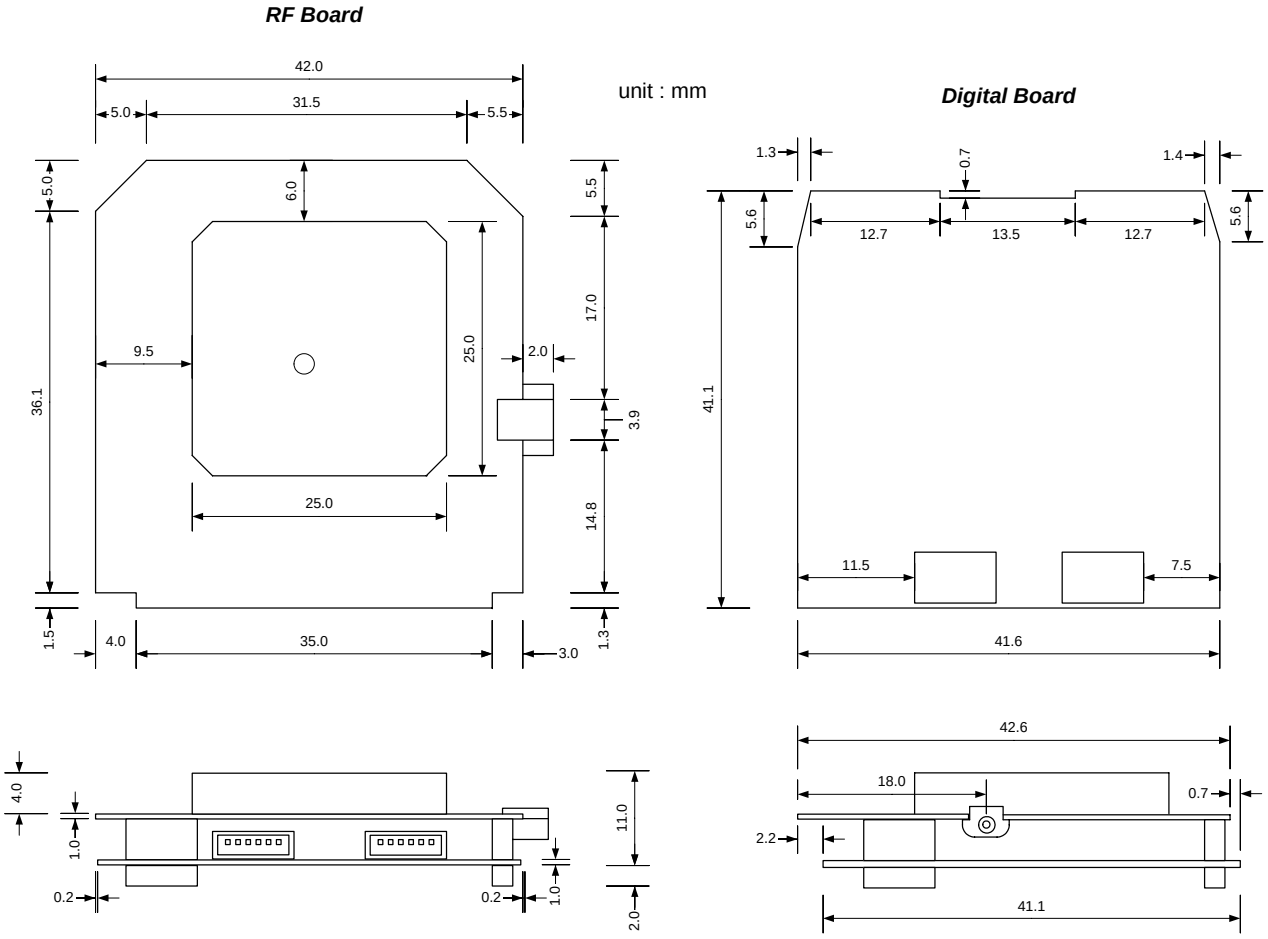
MECHANICAL CHARACTERISTICS



RF Solutions Ltd.,
Unit 21, Cliffe Industrial Estate,
South Street, Lewes, E Sussex, BN8 6JL. England
Tel +44 (0)1273 898 000 Fax +44 (0)1273 480 661
Email sales@rfsolutions.co.uk http://www.rfsolutions.co.uk