

# Incremental Shaft Encoder

## OPE1275S Single Channel (Tachometer)

## OPE2275S Dual Channel



### Features:

- Body O.D. = 28mm [1.10"]
- Shaft Diameter 6.35 mm [0.25"]
- 3/8"-32 UNF Thread
- Pulses per revolution 256 maximum
- Analog Output
- 100 - 5,000 RPM



### Description:

The **OPE1275S** and **OPE2275S** are designed for small shaft motors. The **OPE1275S** provides a single channel analog output for speed of rotation while the **OPE2275S** provides a dual channel analog output for speed and direction of rotation.

The output of the **OPE1275S** provides a rise and fall pulse providing the designer two slopes for each pulse doubling the count capability. The **OPE2275S** provides quadrature rise and fall pulse patterns providing the design engineer 4 times the pulse per revolution count.

Power requirements are 5 volts  $\pm$  .5 volts.

Electrical connection is achieved with a 4-pin Molex 53048-0410 connector providing V+, Ground and Output pins. The mating connector is a 4-pin Molex 51021-0400 (Terminal pin 50058 or 50079) or equivalent.

Frequency response is from DC to 25 kHz providing a maximum of 256 cycles per revolution (CPR) and 1024 quadrature states per revolution (PPR).

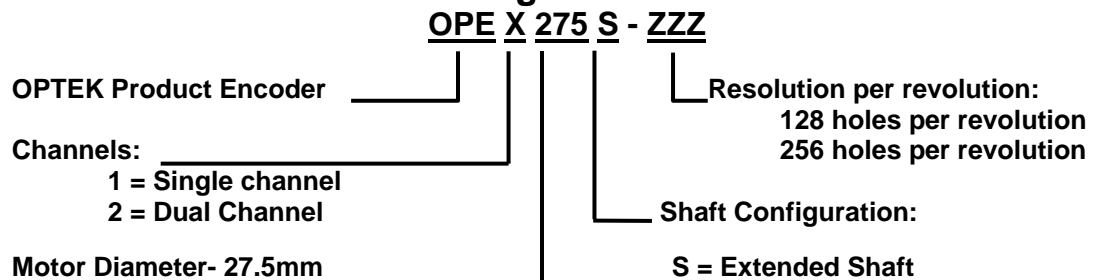
This product is designed for general encoding for low-speed applications.

The **OPE1275S** and **OPE2275S** are fully assembled and ready to be connected to your application.

### Applications:

- Printer motors
- Machine automation
- Machine safety

### Ordering Information

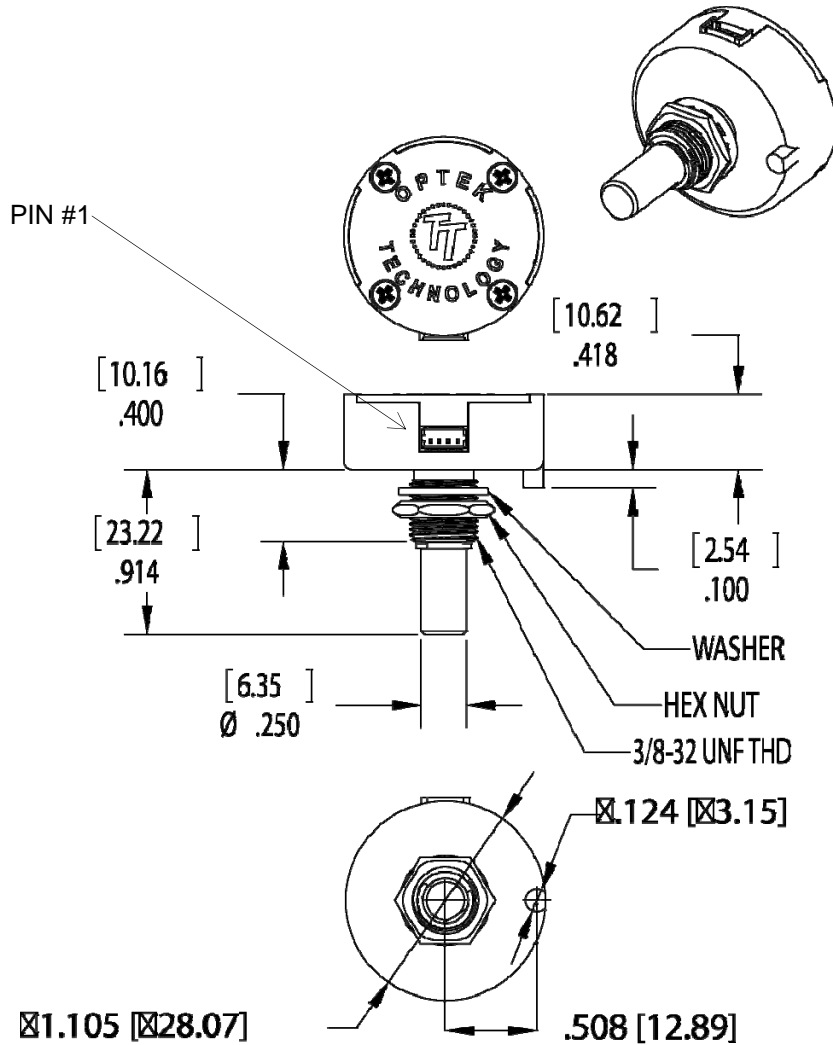


**RoHS**

OPTEK reserves the right to make changes at any time in order to improve design and to supply the best product possible.

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OPE1275S  
 OPE2275S



| Pin Out         |      |      |     |
|-----------------|------|------|-----|
| 1               | 2    | 3    | 4   |
| V <sub>CC</sub> | CH A | CH B | GND |

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### Absolute Maximum Ratings ( $T_A=25^\circ\text{C}$ unless otherwise noted)

|                                  | Maximum           | Units                |
|----------------------------------|-------------------|----------------------|
| Storage Temperature Range        | -40° C to +85°    | C                    |
| Operating Temperature Range      | 0° C to +85°      | C                    |
| Power Supply Voltage $V_{CC}$    | 4.5 to 5.5        | $V_{DC}$             |
| Power Dissipation <sup>(2)</sup> | 250               | mW                   |
| Vibration (5 Hz to 2 kHz)        | 20                | g                    |
| Shaft Axial Play                 | ± 0.51 mm [0.02"] |                      |
| Off-Axis Mounting Tolerance      | 0.254 mm [0.01"]  |                      |
| Acceleration                     | 250,000           | rad/sec <sup>2</sup> |

### Mechanical Specifications:

|                   | Dimensions            | Units                |
|-------------------|-----------------------|----------------------|
| Moment of Inertia | $6.48 \times 10^{-5}$ | OZ-IN-S <sup>2</sup> |
| Shaft Length      | 0.3 to 0.7            | Inches               |

### Electrical Characteristics ( $T_A = 25^\circ\text{C}$ unless otherwise noted — for reference only)

| SYMBOL   | PARAMETER  | MIN          | TYP | MAX | UNITS   | TEST CONDITIONS                  |
|----------|--|--------------|-----|-----|---------|----------------------------------|
| $V_{CC}$ | Supply Voltage   | 4.5          | 5.0 | 5.5 | V       |                                  |
| $I_{CC}$ | Supply Current   | -            | 21  | 27  | mA      | $V_{CC} = 5.0$ volts             |
| $V_{OH}$ | High Level Output Voltage                              | $V_{CC}-0.5$ | -   | -   | V       | $I_C = 100 \mu\text{A}$          |
| $V_{OL}$ | Low Level Output Voltage                               | -            | -   | 0.4 | V       | $I_C = 20$ mA                    |
| TR       | Rise Time  | -            | 500 | -   | ns      | 10% to 90%, $V_{CC} = 5.0$ volts |
| TF       | Fall Time  | -            | 100 | -   | ns      | 10% to 90%, $V_{CC} = 5.0$ volts |
| FR       | Frequency Response                                     | -            | -   | 60  | kHz     |                                  |
| H.S.     | Hole Size  | 0.10         | -   | -   | inch    |                                  |
| Rotation | Maximum speed of rotation with 1024 holes per rotation | -            | -   | 100 | rev/sec |                                  |

### Encoding Characteristics:

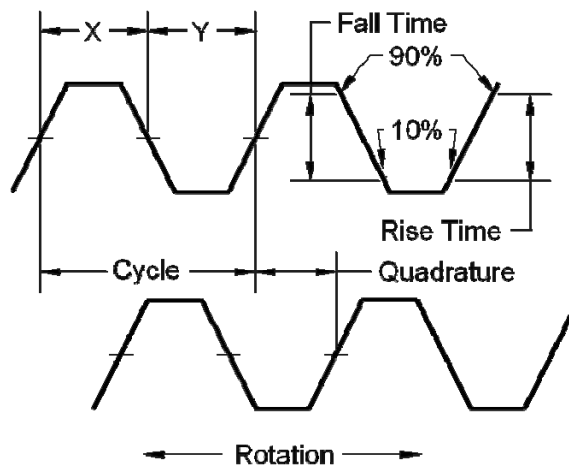
|    |                               | 0 | 16 | 75 | °e |  |
|----|-------------------------------|---|----|----|----|--|
| SE | Symmetry Error                | 0 | 16 | 75 |    |  |
| QE | Quadrature Error—OPE2275 only | 0 | 12 | 60 |    |  |

#### Notes:

- All parameters measured using pulse technique,  $V_{CC} = 5.0$  volts and  $T_A = 25^\circ\text{C}$ .

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**Timing Diagram:**



**Timing Definitions:**

**PPR** = Pulses Per Revolution

**Electrical Degree** ( $^{\circ}e$ ) = 1/360th of 1 cycle

**Cycle** = 360 electrical degrees ( $^{\circ}e$ )

**Symmetry** = Relationship between X & Y in electrical degrees ( $^{\circ}e$ ).

**Position Error** = The difference between the actual shaft position and the position indicated by the encoder cycle count.

**Quadrature:** The lead or lag difference between channels "A" and "B" in electrical degrees (normally  $90^{\circ}e$ )

**Cycle Error** = The difference between the actual shaft rotational position and the cycle count rotational position.

**Rise Time** = Time required to switch between 10% and 90% of the highest to lowest signal levels.

**Fall Time** = Time required to switch between 90% and 10% of the highest to lowest signal levels.

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