

ENC Series

Wheel type of Incremental Rotary encoder

Features

- Suitable for measuring the length or speed of target moving successively by wheel type
- The output waveform according to measuring distance is proportional to the unit of International Measurement type (Meter or inch)
- Power supply : 5VDC, 12–24VDC ±5%



Applications

- Various packing machine, sheet manufacturing, textile machinery, and general industrial machinery etc.

⚠ Please read "Caution for your safety" in operation manual before using.



Ordering information

| ENC | 1 | 1 | N | 24 | |
|------------|----------------|---|--|-----------------------------------|---|
| Series | Output phase | Min. measuring unit | Output | Power supply | Cable |
| Wheel type | 1 : A, B phase | 1 : 1mm 2 : 1cm 3 : 1m 4 : 0.01yd 5 : 0.1yd 6 : 1yd | T : Totem pole output N : NPN open collector output V : Voltage output | 5 : 5VDC ±5% 24 : 12–24VDC ±5% | No mark : Normal type C : Cable outgoing connector type(*) |

*Cable length : 250mm

Specifications

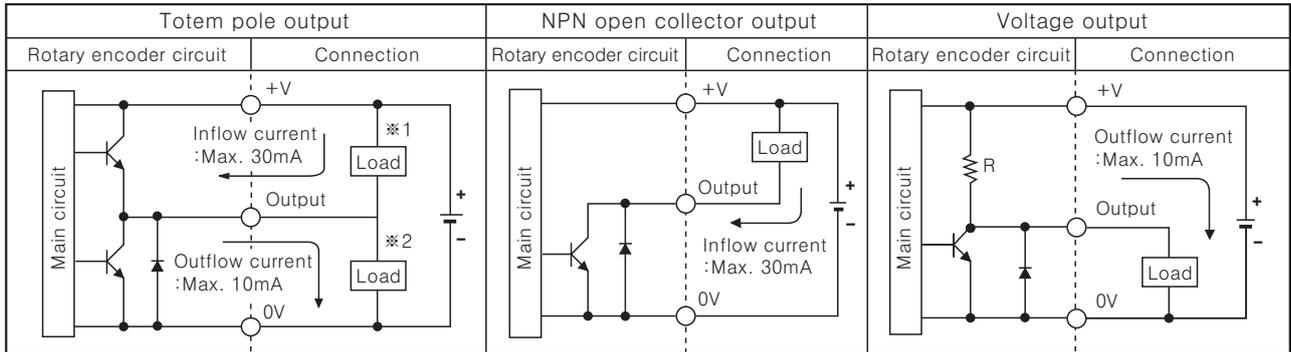
| Item | Wheel type of incremental rotary encoder | | |
|--------------------------|---|--|---|
| Resolution(P/R) | Refer to resolution(Next page) | | |
| Electrical specification | Output phase | A, B phase | |
| | Phase difference of output | Phase difference between A and B : $\frac{T}{4} \pm \frac{T}{8}$ (T=1cycle of A phase) | |
| | Control output | Totem pole output | <ul style="list-style-type: none"> • Low \Rightarrow Load current : Max. 30mA, Residual voltage : Max. 0.4VDC • High \Rightarrow Load current : Max. 10mA, Output voltage (Power supply 5VDC) : Min. (Power supply–2.0)VDC, Output voltage (Power supply 12–24VDC) : Min. (Power supply–3.0)VDC |
| | | NPN open collector output | Load current : Max. 30mA, Residual voltage : Max. 0.4VDC |
| | | Voltage output | Load current : Max. 10mA, Residual voltage : Max. 0.4VDC |
| | Response time (Rise/Fall) | Totem pole output | Max. 1 μ s (Cable length : 2m, I sink = 20mA) |
| | | NPN open collector output | |
| | | Voltage output | |
| | Max. Response frequency | 180kHz | |
| | Power supply | 5VDC ±5% (Ripple P–P : Max. 5%), 12–24VDC ±5% (Ripple P–P : Max. 5%) | |
| | Current consumption | Max. 80mA (disconnection of the load) | |
| Insulation resistance | Min. 100M Ω (at 500VDC megger between all terminals and case) | | |
| Dielectric strength | 750VAC 50/60Hz for 1 minute (Between all terminals and case) | | |
| Connection | Cable outgoing type, 250mm cable outgoing connector type | | |
| Mechanical specification | Starting torque | Depend on coefficient of friction | |
| | Max. allowable revolution | (Note1) 5000rpm | |
| Vibration | 1.5mm amplitude at frequency of 10 to 55Hz (for 1 min.) in each of X, Y, Z directions for 2 hours | | |
| Shock | Max. 75G | | |
| Ambient temperature | –10 to 70 $^{\circ}$ C (at non–freezing status), Storage : –25 to 85 $^{\circ}$ C | | |
| Ambient humidity | 35 to 85%RH, Storage : 35 to 90%RH | | |
| Cable | ϕ 5mm, 5P, Length: 2m, Shield cable (AWG 24, Core wire diameter: 0.08mm, No. of core wire: 40, Insulator out diameter: ϕ 1mm) | | |
| Protection | IP50 (IEC standard) | | |
| Approval | CE | | |
| Unit weight | Approx. 494g | | |

※ (**★Note1**) Make sure that max. response revolution should be lower than or equal to max. allowable revolution when selecting the resolution.

$$\text{[Max. response revolution (rpm) = } \frac{\text{Max. response frequency}}{\text{Resolution}} \times 60 \text{ sec.]}$$

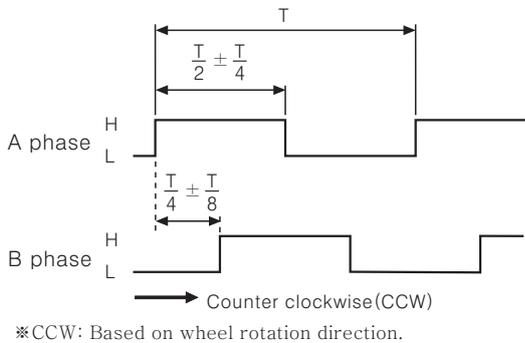
Incremental Wheel Type

Control output diagram



- The output circuits of A, B phase are the same.
- Totem pole output type can be used for NPN open collector type(*1) or voltage output type(*2).

Output waveform

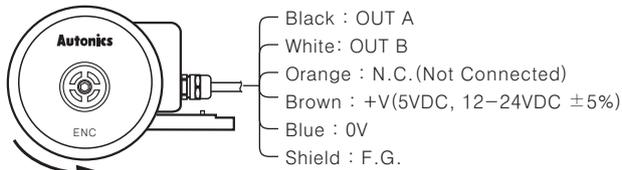


Resolution

| No | The number of encoder pulse | Gear ratio | Wheel circumference | Moving distance per 1pulse |
|----|-----------------------------|------------|---------------------|----------------------------|
| 1 | 250Pulse | 1 : 1 | 250mm | 1mm/Pulse |
| 2 | 100Pulse | 4 : 1 | 250mm | 1cm/Pulse |
| 3 | 1Pulse | 4 : 1 | 250mm | 1m/Pulse |
| 4 | 100Pulse | 4 : 1 | 228.6mm (0.25/yd) | 0.01yd/Pulse |
| 5 | 10Pulse | 4 : 1 | 228.6mm (0.25/yd) | 0.1yd/Pulse |
| 6 | 1Pulse | 4 : 1 | 228.6mm (0.25/yd) | 1yd/Pulse |

Connections

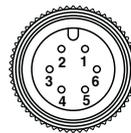
Normal type



Counter clockwise (CCW)

- *Unused wires must be insulated.
- *The metal case and shield wire of encoder must be grounded (F.G.)

Cable outgoing connector type

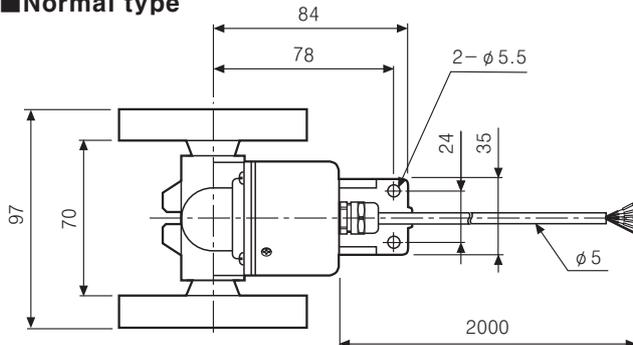


| Pin No | Cable color | Function |
|--------|-------------|----------|
| 1 | Black | OUT A |
| 2 | White | OUT B |
| 3 | Orange | N.C. |
| 4 | Brown | +V |
| 5 | Blue | GND |
| 6 | Shield | F.G. |

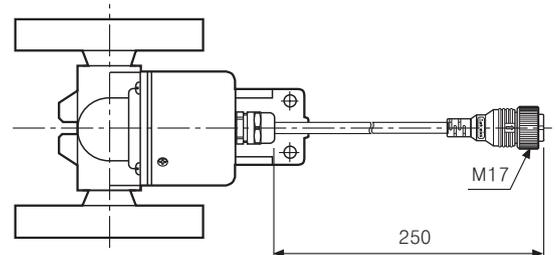
*F.G. (Field Ground) : It must be grounded separately.

Dimensions

Normal type



Cable outgoing connector type



(Unit:mm)

- *The wheel circumference is changed according to model (φ), please refer to resolution chart.
- *Connector cable is sold separately and see G-6 for specifications.

| Cable for normal type | Cable for Cable outgoing connector type |
|--|---|
| φ 5mm, 5P, Length : 2000mm, Shield cable | φ 5mm, 5P, Length : 250mm, Shield cable |

(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

(F) Rotary encoder

(G) Connector/Socket

(H) Temp. controller

(I) SSR/Power controller

(J) Counter

(K) Timer

(L) Panel meter

(M) Tacho/Speed/Pulse meter

(N) Display unit

(O) Sensor controller

(P) Switching power supply

(Q) Stepping motor & Driver & Controller

(R) Graphic/Logic panel

(S) Field network device

(T) Production stoppage models & replacement