

# ESCON Overview

The ESCON servo controllers are small-sized, powerful 4-quadrant PWM servo controller for the highly efficient control of permanent magnet-activated DC motors.

The featured operating modes – speed control (closed loop), speed control (open loop), and current control – meet the highest requirements. The ESCON servo controllers are designed being commanded by an analog set value and

features extensive analog and digital I/O functionality and are being configured via USB interface using the graphical user interface «ESCON Studio» for Windows PCs.

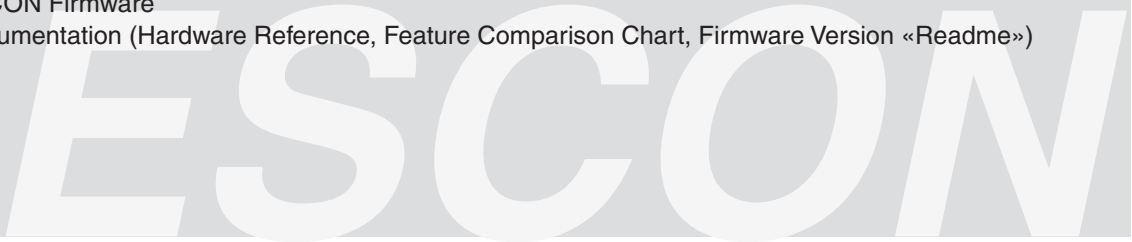
## // ESCON Setup


### Full version, including...

[escon.maxonmotor.com](http://escon.maxonmotor.com)



- ESCON Studio
- ESCON Firmware
- Documentation (Hardware Reference, Feature Comparison Chart, Firmware Version «Readme»)





**ESCON 36/2 DC**

- Feature Comparison Chart
- Hardware Reference
- Firmware
- Firmware Version «Readme»

403112



**ESCON 50/5**

- Feature Comparison Chart
- Hardware Reference
- Firmware
- Firmware Version «Readme»

409510

Depending on the ESCON variant, the following **motor types** can be operated

- **DC motor:** Permanent-magnet DC motor
- **EC motor:** Brushless, electronically commutated permanent-magnet DC motor (BLDC) with Hall sensors.

Various **operating modes** allow an adaptable use in a wide range of drive systems

- **Current controller:** The current controller compares the actual motor current (torque) with the applied set value. In case of deviation, the motor current is dynamically readjusted.
- **Speed controller (closed loop):** The closed loop speed controller compares the actual speed signal with the applied set value. In case of deviation, the speed is dynamically readjusted.

- **Speed controller (open loop):** The open loop speed controller feeds the motor with a voltage proportional to the applied speed set value. Changes in load are compensated using the IxR methodology.

#### Speed measurement by

- **Digital incremental encoder:** The encoders deliver simple square signals for further processing. Their impulses are counted to determine the speed. Channels A and B are phase-shifted signals, which are being compared to determine the sense of rotation.
- **DC tacho:** The DC tacho delivers a speed-proportional analog voltage.
- **Available Hall sensors:** The Hall sensors deliver six different combinations of switching impulses per electrical turn which are counted to determine speed. They also deliver phase-

shifted signals that are being compared to determine the sense of rotation.

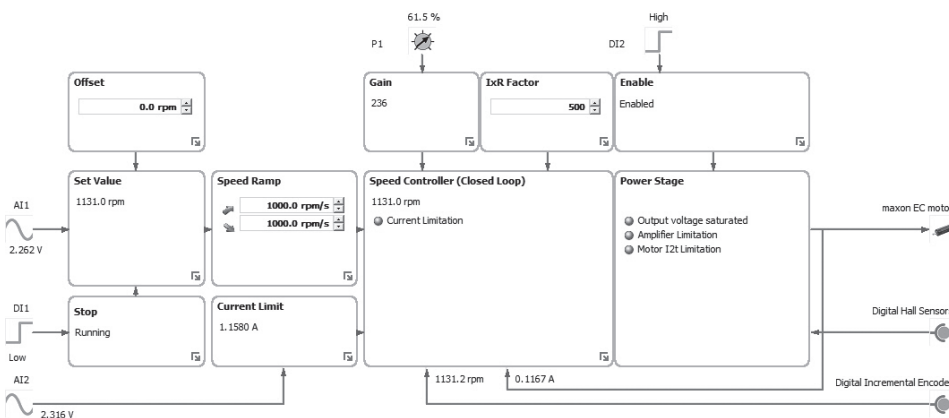
To the numerous **inputs** and **outputs**, various functionalities can be assigned to.

**Set value** (speed or current), **current** limitation, as well as **offset** can be assigned as follows.

- **Analog value:** The value is defined by an analog voltage set via external or internal potentiometer.
- **PWM value:** The value is defined by fixed frequency and amplitude. The desired change is achieved by variation of the duty cycle of 10...90%.
- **Fixed value:** The value is defined by a fixed preset value.
- **2 fixed values:** Value 1 is defined by a fixed preset value 1. Value 2 is defined by a fixed preset value 2. A digital input is used to switch between the two preset values.

Various functionalities are available to **enable** the power stage.

- **Enable:** Enables or disables the power stage.
- **Enable & Direction:** Enables or disables the power stage and determines the motor shaft's direction of rotation.
- **Enable CW:** Enables or disables the power stage in direction of rotation-dependent sense. The rotor can only turn clockwise (CW).
- **Enable CCW:** Enables or disables the power stage in direction of rotation-dependent sense. The rotor can only turn counterclockwise (CCW).
- **Enable CW & CCW:** Enables or disables the power stage in direction of rotation-dependent



ESCON Studio (Controller Monitor)

sense. The rotor can only turn in defined direction. The signals are interlocked against each other.

The **ramp function** permits controlled acceleration/deceleration of the motor shaft in both, open loop and closed loop speed controller mode.

- **Analog ramp:** The ramp is defined by a variable analog value.
- **Fixed ramp:** The ramp is defined by a fixed preset value.

**Stop:** The motor shaft decelerates with preset speed ramp until complete standstill.

**Ready:** The Ready signal can be used to transmit the operational status (respectively fault) to a superior control.

**Speed comparator:** The digital output is set as soon as the preset speed is reached.

- **Limit:** The digital output is set as soon as the preset speed is reached. It will continue set as long as the overspeed remains.
- **Range:** The digital output is set as soon as the preset speed range is reached. It will continue set as long as the speed remains in range.
- **Deviation:** The digital output is set as soon as the preset speed variation (based on the speed set value) is reached.

With the integrated **potentiometers** the additional following functions can be adjusted

- **Current Gain:** Adjustment of the current controller gain.
- **Speed Gain:** Adjustment of the speed controller gain.
- **IxR Factor:** The voltage drop caused by terminal resistance will be compensated in the range of [0...1000...2000].

Analog outputs allow monitoring of

- **Actual current:** Actually measured motor winding current.
- **Actual current averaged:** Actually measured motor winding current filtered by first order digital low-pass filter with a cut-off frequency of 5 Hz.
- **Actual speed:** Actually measured motor speed.
- **Actual speed averaged:** Actually measured motor speed filtered by 1st order digital low-pass filter with a cut-off frequency of 5 Hz.
- **Demand Current:** Demanded motor winding current.
- **Demand Speed:** Demanded motor speed.
- **Temperature Power Stage:** Actually measured power stage temperature.
- **Fixed value:** The output voltage is said fixed to the preset value.

### Easy startup

Startup and parameterization are performed using the intuitive graphical user interface «ESCON Studio» with the help of simple to use, menu-guided wizards. The following wizards are available: Startup, Regulation Tuning, Firmware Update, Controller Monitor, Parameters, Data Recording, and Diagnostics.

### Protective equipment

The servo controller has protective circuits against overcurrent, excess temperature, under- and overvoltage, against voltage transients, and against short-circuits in the motor cable. Furthermore it is equipped with protected digital inputs and outputs and an adjustable current limitation for protecting the motor and the load. The motor current and the actual speed of the motor shaft can be monitored by means of the analog output voltage.

### Comprehensive documentation

Using the «Feature Comparison Chart», the appropriate ESCON servo controller can be easily found. In the «Hardware Reference», the complete hardware is specified in detail. In the document «Firmware Version», the changes and improvements of the firmware are documented. The graphical user interface «ESCON Studio» also has a comprehensive online help.

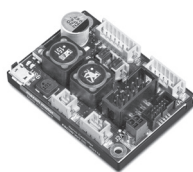


### Software

Installation Program	ESCON Setup
Graphical User Interface	ESCON Studio
Startup Wizard	✓
Regulation Tuning	✓
Diagnostic	✓
Firmware Update	✓
Controller Monitor	✓
Parameters	✓
Data Recording	✓
Online Help	✓
Language	German, English, French, Italian, Spanish, Japanese, Chinese
Operating System	Windows 7, Windows XP SP3
Communication interface	USB 2.0 (full speed)

Accessories (not included in delivery)	ESCON 36/2 DC	ESCON 50/5
404404 ESCON 36/2 DC Connector Set	✓	—
403964 ESCON Analog I/O Cable	✓	—
403962 ESCON DC Motor Cable	✓	—
403965 ESCON Digital I/O Cable	✓	—
275934 ESCON Encoder Cable	optional	optional
403957 ESCON Power Cable	✓	—
409286 ESCON USB Stick	✓	✓
403968 USB 2.0 Type A micro-B Cable	✓	✓

# ESCON Feature Comparison Chart



**NEW**

**NEW**

	<b>ESCON 36/2 DC</b>	<b>ESCON 50/5</b>
DC motors up to	72 W	250 W
EC motors up to	–	250 W
<b>Sensors</b>		
	Digital Incremental Encoder (2 channel with or without Line Driver)	Digital Incremental Encoder (2 channel with or without Line Driver)
	DC Tacho	DC Tacho
	–	Digital Hall Sensors (EC motors)
<b>Operating Mode</b>		
	Current controller (torque control), Speed controller (closed and open loop)	Current controller (torque control), Speed controller (closed and open loop)
<b>Electrical Data</b>		
Nominal operating voltage $V_{CC}$	10 - 36 VDC	10 - 50 VDC
Max. output voltage	$0.98 \times V_{CC}$	$0.98 \times V_{CC}$
Max. output current	4 A (<60 s)	15 A (<20 s)
Continuous output current	2 A	5 A
Pulse width modulation frequency	53.6 kHz	53.6 kHz
Sampling rate PI current controller	53.6 kHz	53.6 kHz
Sampling rate PI speed controller	5.36 kHz	5.36 kHz
Max. efficiency	95%	95%
Max. speed (DC)	limited by max. permissible speed (motor) and max. output voltage (controller)	limited by max. permissible speed (motor) and max. output voltage (controller)
Max. speed (EC; 1 pole pair)	–	150 000 rpm
Built-in motor choke	300 $\mu$ H / 2 A	3 x 30 $\mu$ H / 5 A
<b>Inputs/Outputs</b>		
Hall sensor signals	–	H1, H2, H3
Encoder signals	A, A\, B, B\	A, A\, B, B\
Max. encoder input frequency differential (single-ended)	1 MHz (100 kHz)	1 MHz (100 kHz)
Potentiometers	1	2
Digital inputs	2	2
Digital inputs/outputs	2	2
Analog inputs	2	2
Resolution, Range, Circuit	12-bit, -10...+10 V, differential	12-bit, -10...+10 V, differential
Analog outputs	2	2
Resolution, Range	12-bit, -4...+4 V	12-bit, -4...+4 V
Auxiliary voltage output	+5 VDC (IL $\leq$ 10 mA)	+5 VDC (IL $\leq$ 10 mA)
Hall sensor supply voltage	–	+5 VDC (IL $\leq$ 30 mA)
Encoder supply voltage	+5 VDC (IL $\leq$ 70 mA)	+5 VDC (IL $\leq$ 70 mA)
Status Indicators	Operation: green LED / Error: red LED	Operation: green LED / Error: red LED
<b>Environmental Conditions</b>		
Temperature – Operation	-30...+45°C	-30...+45°C
Temperature – Extended range	+45...+81°C; Derating: -0.056 A/°C	+45...+85°C; Derating: -0.113 A/°C
Temperature – Storage	-40...+85°C	-40...+85°C
Humidity (condensation not permitted)	20...80%	20...80%
<b>Mechanical Data</b>		
Weight	Approx. 30 g	Approx. 204 g
Dimensions (L x W x H)	55 x 40 x 16.1 mm	115 x 75.5 x 24 mm
Mounting holes	for screws M2.5	for screws M4
<b>Article numbers</b>		
	<b>403112 ESCON 36/2 DC</b>	<b>409510 ESCON 50/5</b>
	Order accessories separately, from page 321	Order accessories separately, from page 321