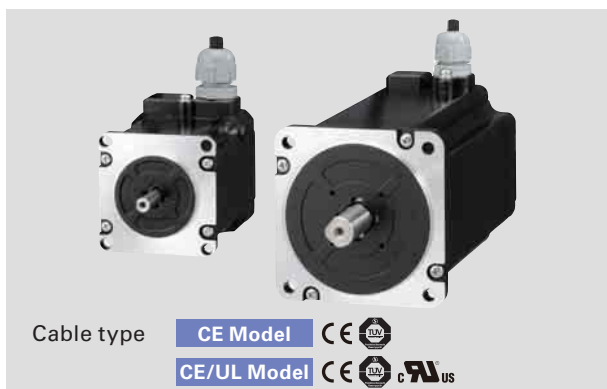


IP65 Splash and Dust Proof Stepping Motors



Cable type

CE Model



CE/UL Model



Connector type

CE Model



Features

- These IP65 rated motors* have superior water and dust resistance, and can be safely utilized in harsh or wet environments such as in food processing machines.
※ Except for the shaft and the cable end.
- The input voltage range of the motors is up to AC 250 V.
- Brake, encoder, and oil seal can be combined.

Safety standards

The CE model (Cable or Connector type) and the CE/UL model (Cable type) are available.

Specifications

	56 mm sq. (2.20 in sq.)		86 mm sq. (3.39 in sq.)	
	CE Model	CE/UL Model	CE Model	CE/UL Model
Motor model number	SP256 □ T-5 □ □ 0	SP256 □ -5 □ 60	SP286 □ T-5 □ □ 0	SP286 □ -5 □ 60
Type	S1 (continuous operation)			
Operating ambient temperature	- 10°C to + 40°C			
Conversation temperature	- 20°C to + 60°C			
Operating ambient humidity	95%MAX. : 40°C MAX., 57%MAX. : 50°C MAX.			
Conversation humidity	35%MAX. : 60°C MAX. (no condensation)			
Operation altitude	1000m (3280 feet) MAX above sea level			
Vibration resistance	Vibration frequency 10 to 500 Hz, total amplitude 1.52 mm (10 to 70 Hz), vibration acceleration 147m/s ² (70 to 500 Hz), sweep time 15 min/cycle, 12 sweeps in each X, Y and Z direction.			
Impact resistance	500m/s ² of acceleration for 11 ms with half-sine wave applying three times for X, Y and Z axes each, 18 times in total.			
Insulation class	Class F (+155°C)			
Withstand voltage	At normal temperature and humidity, no failure with 1500 V AC @50/60 Hz applied for one minute between motor winding and frame.			
Insulation resistance	At normal temperature and humidity, not less than 100MΩ between winding and frame by DC500V megger.			
Protection grade	IP65 (Except for the shaft and the cable end)			
Winding temperature rise	100K MAX. (Based on Sanyo Denki standard)			
Static angle error	± 0.054°		± 0.09°	
Axial play	0.075 mm (0.003 in) MAX. (load: 10N (2.25 lbs))			
Radial play	0.025 mm (0.001 in) MAX. (load: 5N (1.12 lbs))			
Shaft runout	0.025 mm (0.001 in)			
Concentricity of mounting pilot relative to shaft	φ 0.075 mm (φ 0.003 in)			
Squareness of mounting surface relative to shaft	0.1 mm (0.004 in)	0.1 mm (0.004 in)	0.15 mm (0.006 in)	0.15 mm (0.006 in)

Safety standards

CE	Standard category	Standard code	
	Low-voltage directives	EN60034-1, EN60034-5	
UL	Acquired standards	Standard code	File No.
	UL	UL1004-1,	E179832
	UL for Canada (c-UL)	UL1004-6	

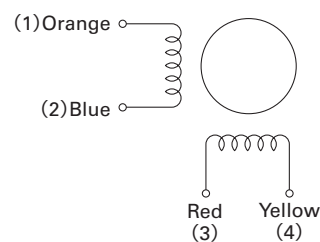
Model No. differs when the motor is equipped with a brake or oil seal.
Model No. and vibration resistance levels differ when the motor is equipped with a brake or oil seal.

Internal wiring and rotation direction

Bipolar winding

Internal wire connection

() : connector pin number



Direction of motor rotation

The output shaft shall rotate clockwise as seen from the shaft side, when excited by DC in the following order.

Lead wire color	Red	Blue	Yellow	Orange
Connector pin number	3	2	4	1
Exciting order	1	-	-	+
	2	+	-	+
	3	+	+	-
	4	-	+	-

56 mm sq. (2.20 inch sq.)

1.8° /step

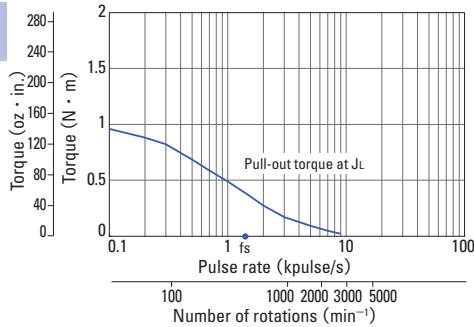
Bipolar winding

Safety standards	Model number		Holding torque at 2-phase energization [N·m (oz·in) MIN.]	Rated current A/phase	Winding resistance Ω /phase	Winding inductance mH/phase	Rotor inertia [×10 ⁻⁴ kg·m ² (oz·in ²)]	Mass (Weight) [kg (lbs)]
	Cable type	Connector type						
CE Model	SP2563T-5060	SP2563T-5000	1 (141.6)	1	5.7	29	0.21 (1.15)	0.9 (2)
	SP2563T-5160	SP2563T-5100	1 (141.6)	2	1.5	7.3	0.21 (1.15)	0.9 (2)
	SP2563T-5260	SP2563T-5200	1 (141.6)	3	0.7	3.4	0.21 (1.15)	0.9 (2)
	SP2566T-5060	SP2566T-5000	1.7 (240.7)	1	7.7	35.4	0.36 (1.97)	1.2 (2.65)
	SP2566T-5160	SP2566T-5100	1.7 (240.7)	2	2	9.2	0.36 (1.97)	1.2 (2.65)
	SP2566T-5260	SP2566T-5200	1.7 (240.7)	3	0.94	4.4	0.36 (1.97)	1.2 (2.65)
CE/UL Model	SP2563-5060	—	1 (141.6)	1	5.8	29	0.21 (1.15)	0.9 (2)
	SP2563-5160	—	1 (141.6)	2	1.5	7.3	0.21 (1.15)	0.9 (2)
	SP2563-5260	—	1 (141.6)	3	0.75	3.4	0.21 (1.15)	0.9 (2)
	SP2566-5060	—	1.7 (240.7)	1	7.8	35.4	0.36 (1.97)	1.2 (2.65)
	SP2566-5160	—	1.7 (240.7)	2	2	9.2	0.36 (1.97)	1.2 (2.65)
	SP2566-5260	—	1.7 (240.7)	3	1	4.4	0.36 (1.97)	1.2 (2.65)

· The Model No., rotor inertia and mass differ when the motor is equipped with brake, encoder or oil seal.

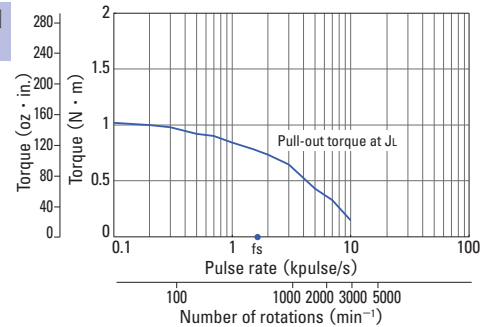
Characteristics diagram

SP2563T-50 □□
SP2563-5060



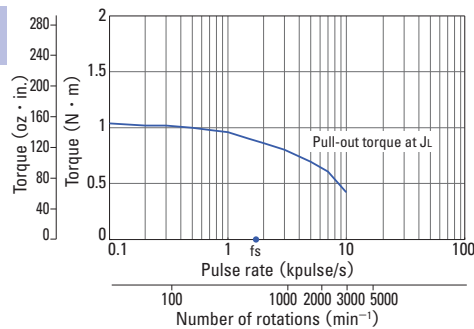
Constant current circuit
Source voltage : AC100V · operating current : 1A/phase,
2-phase energization (full-step)
J_L=[2.6 × 10⁻⁴kg·m² (14.22 oz·in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SP2563T-51 □□
SP2563-5160



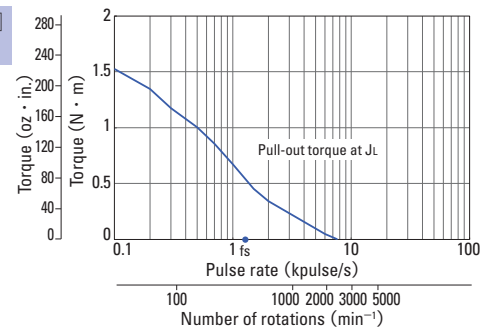
Constant current circuit
Source voltage : AC100V · operating current : 2A/phase,
2-phase energization (full-step)
J_L=[2.6 × 10⁻⁴kg·m² (14.22 oz·in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SP2563T-52 □□
SP2563-5260



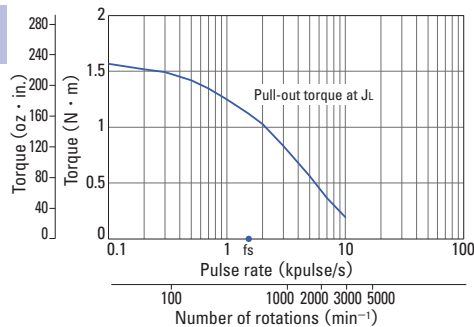
Constant current circuit
Source voltage : AC100V · operating current : 3A/phase,
2-phase energization (full-step)
J_L=[2.6 × 10⁻⁴kg·m² (14.22 oz·in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SP2566T-50 □□
SP2566-5060



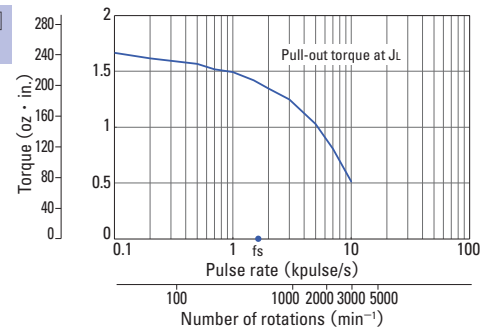
Constant current circuit
Source voltage : AC100V · operating current : 1A/phase,
2-phase energization (full-step)
J_L=[7.4 × 10⁻⁴kg·m² (40.46 oz·in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SP2566T-51 □□
SP2566-5160



Constant current circuit
Source voltage : AC100V · operating current : 2A/phase,
2-phase energization (full-step)
J_L=[7.4 × 10⁻⁴kg·m² (40.46 oz·in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SP2566T-52 □□
SP2566-5260

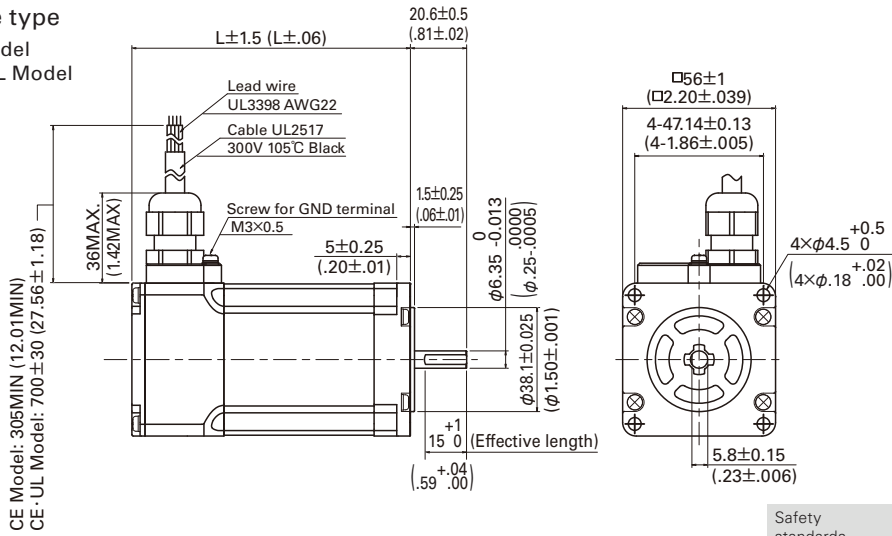


Constant current circuit
Source voltage : AC100V · operating current : 3A/phase,
2-phase energization (full-step)
J_L=[7.4 × 10⁻⁴kg·m² (40.46 oz·in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

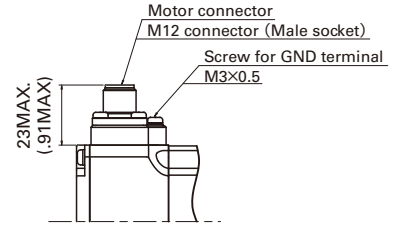
IP65 Splash and Dust Proof Stepping Motors [Unit: mm (inch)]

56 mm sq. (2.20 inch sq.)

Cable type
CE Model
CE · UL Model



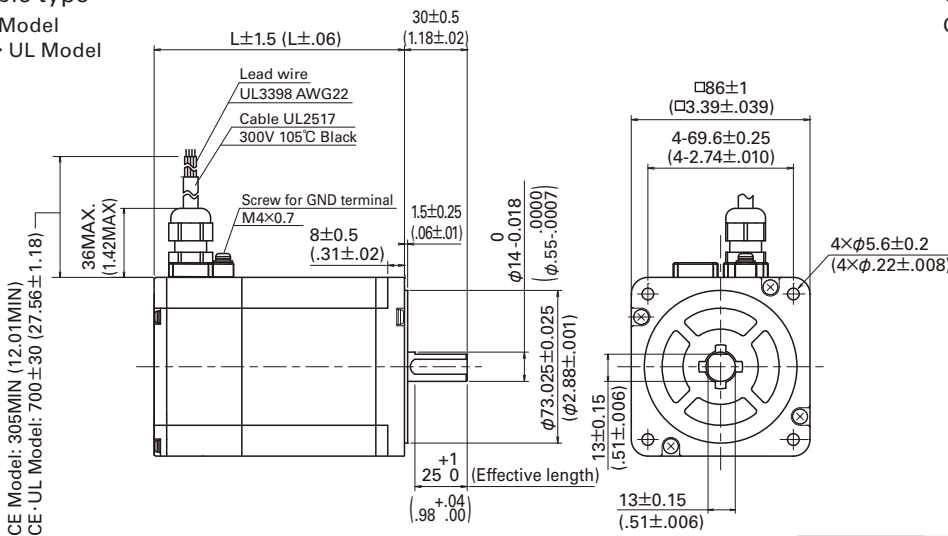
Connector type
CE Model



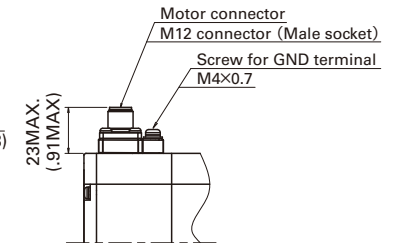
Safety standards	Model number		Motor length (L)
	Cable type	Connector type	
CE Model	SP2563T-5 □ 60	SP2563T-5 □ 00	80 (3.15)
	SP2566T-5 □ 60	SP2566T-5 □ 00	102 (4.02)
CE · UL Model	SP2563-5 □ 60	—	80 (3.15)
	SP2566-5 □ 60	—	102 (4.02)

86 mm sq. (3.39 inch sq.)

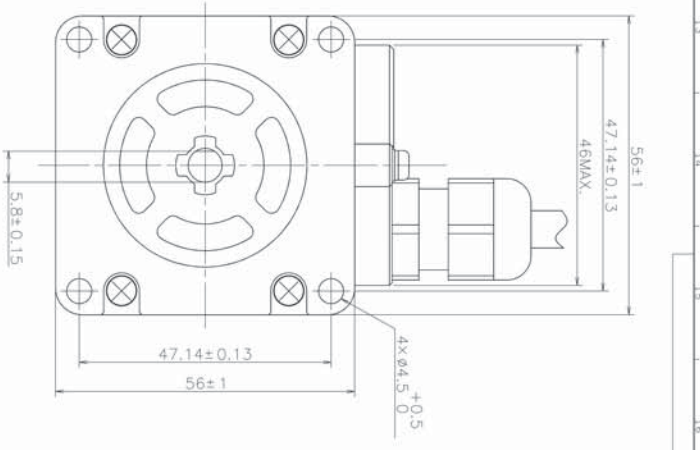
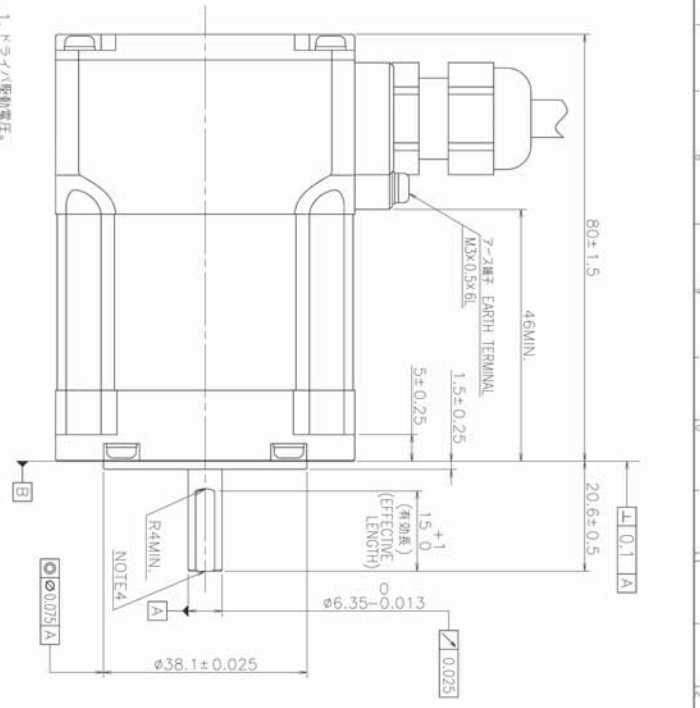
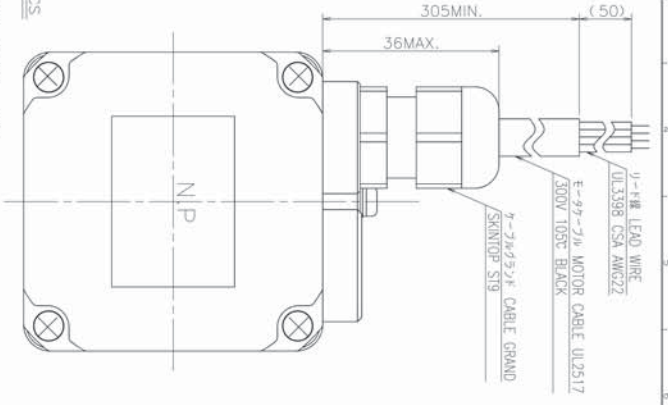
Cable type
CE Model
CE · UL Model



Connector type
CE Model



Safety standards	Model number		Motor length (L)
	Cable type	Connector type	
CE Model	SP2862T-5 □ 60	SP2862T-5 □ 00	120 (4.72)
	SP2863T-5 □ 60	SP2863T-5 □ 00	150 (5.91)
CE · UL Model	SP2862-5 □ 60	—	120 (4.72)
	SP2863-5 □ 60	—	150 (5.91)



定格特性・RATED CHARACTERISTICS

注1. 駆動電圧
NOTE1. POWER INPUT 250 V(AC) MAX.

最大許容トルク
MAXIMUM PERMISSIBLE TORQUE 0.85 N·m

最大回転数
MAXIMUM SPEED 3000 min⁻¹ (10,000 pulse/s at 2 PHASE EXCITATION)

相数
PHASES 2
基本ステップ角
FUNDAMENTAL STEP ANGLE 1.8°

定格電圧
RATED VOLTAGE 3 V(DC)

定格電流
RATED CURRENT 2 A/PHASE

巻線抵抗
WINDING RESISTANCE 1.5 Ω±10% at 25 °C

巻線インダクタンス
WINDING INDUCTANCE 7.3 mH±20% at 1 kHz 1 V(rms)

保持トルク
HOLDING TORQUE 1.0 N·m MIN. at 1=2 A/PHASE 2 PHASE EXCITATION
2相励磁

注2. 押し出しトルク
NOTE2. PULL-OUT TORQUE 0.8 N·m MIN. at 200 pulse/s

注2. 最大自起動動数
NOTE2. MAXIMUM STARTING PULSE RATE 1400 pulse/s MIN. at NO LOAD

注2. 最大連続動作電流
NOTE2. MAXIMUM SLEWING PULSE RATE 2600 pulse/s MIN. at NO LOAD

注3. 位置精度
NOTE3. POSITIONAL ACCURACY ±0.054° (0.108° SPREAD MAX.) 2 PHASE EXCITATION

注3. 温度上昇
NOTE3. TEMPERATURE RISE 80 K MAX.

注3. 慣性
NOTE3. ROTOR INERTIA 0.21×10⁻⁴ kg·m² NOMINAL

注3. 絶縁等級
NOTE3. INSULATION CLASS F

注3. 質量
NOTE3. MASS 0.9 Kg

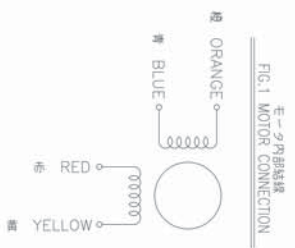
注3. 許容 thrust 荷重
NOTE3. ALLOWABLE THRUST LOAD 15 N

注3. 許容 radial 荷重
NOTE3. ALLOWABLE RADIAL LOAD 52 N

注5. 許容電圧等級
NOTE5. IP RATING IP65 EN60034-5

注5. 許容電圧等級
NOTE5. IP RATING IP65 EN60034-5 (EXCEPT FOR THE CAP BETWEEN THE SHAFT AND THE FLANGE)

- Note)
1. ドライバ/駆動電圧。
2. 仕様書2相励磁回路による。E=100 V(AC), I=2 A/相 (設定値)
SANVO STANDARD 2PHASE EXCITATION DRIVE CIRCUIT WAS USED. E=100 V(AC), I=2 A/PHASE (SET VALUE)
3. 温度上昇は、E-2φを160X160X61アルミ放熱板に設置し、2相励磁=2 A/相を連続通電し、抵抗法にて測定した時の値。
MOUNT A MOTOR ON 160X160X61 ALUMINIUM HEAT SINK AND CONTINUOUSLY ENERGIZE A COIL.
4. シフトレゾナンスの有無及び形状は、製造上の都合により任意とする。
CENTER HOLE ON THE SHAFT END IS NOT ALWAYS MADE.
5. IP65はEN60034-5の試験条件により、水に対して保証するものではありません。
IP65 IS FOR WATER PROTECTION ACCORDING TO THE TEST CONDITION OF EN60034-5.



下記の順に巻線接続した場合、回転方向は正面より見て時計方向回転のこと。
WHEN A MOTOR IS SEQUENCED AS SHOWN IN THE TABLE BELOW,
THE SHAFT ROTATION MUST BE CLOCKWISE WHEN YOU SEE FROM SURFACE "F" SIDE.

巻線順序 WINDING ORDER 順 NO	回転方向・DIRECTION OF ROTATION			
	赤 RED	青 BLUE	黄 YELLOW	橙 ORANGE
1	+	-	-	+
2	+	+	-	+
3	+	-	-	+
4	+	+	+	-

LEADS COLOR
赤 RED 青 BLUE 黄 YELLOW 橙 ORANGE

STEPING MOTOR
ステップモーター

山洋電気株式会社
SANVO DENKI CO., LTD.

SP2563-5160(A)