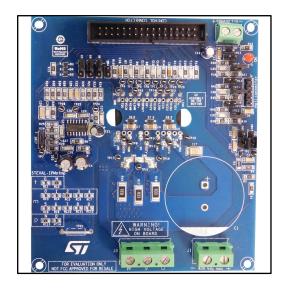


## STEVAL-IPMnM2N

# Motor control power board based on the SLLIMM-nano 2<sup>nd</sup> series

Data brief



#### **Features**

- Input voltage: from 125 to 400 V<sub>DC</sub>
- Nominal power: up to 100 W
- Nominal current: up to 1.2 A<sub>rms</sub>
- Input auxiliary voltage: up to 20 V<sub>DC</sub>
- Single- or three-shunt resistors for current sensing (with sensing network)
- Three options for current sensing: dedicated external op-amps, internal SLLIMM-nano op-amp (single) or via MCU
- Overcurrent hardware protection
- IPM temperature monitoring and protection
- Hall sensor or encoder input
- IGBT intelligent power module:
  - 2<sup>nd</sup> series SLLIMM-nano IPM MOSFETbased (STIPN2M50T-H – full molded package)
- Motor control connector (32 pins) interfacing with ST MCU boards
- Universal design for further evaluation with bread board and testing pins
- Very compact size

RoHS compliant

### Description

The STEVAL-IPMnM2N is a compact motor drive power board based on SLLIMM™-nano (small low-loss intelligent molded module) 2<sup>nd</sup> series MOSFET-based product (STIPN2M50T-H) . It provides an affordable and easy-to-use solution for driving high power motors in a wide range of applications such as power white goods, air conditioning, compressors, power fans and 3-phase inverters for motor drives in general.

The IPM itself consists of short-circuit rugged MOSFETs and a wide range of features like undervoltage lockout, smart shutdown, internal temperature sensor and NTC, overcurrent protection and internal op-amp.

The main characteristics of this evaluation board are small size, minimal BOM and high efficiency. It features an interface circuit (BUS and  $V_{\rm CC}$  connectors), bootstrap capacitors, snubber capacitor, hardware short-circuit protection, fault event signal and temperature monitoring. It is designed to work in single- or three-shunt configuration and with triple current sensing options: three dedicated on-board op-amps, opamps embedded on MCU or single internal IPM op-amp. The Hall/Encoder part completes the circuit.

The system is designed to achieve accurate and fast conditioning of current feedback to satisfy the typical requirements for field oriented control (FOC).

The STEVAL-IPMnM2N is compatible with ST's control board based on STM32, providing a complete platform for motor control.

# **Schematic diagrams**

Figure 1: STEVAL-IPMnM2N circuit schematic (1 of 5)

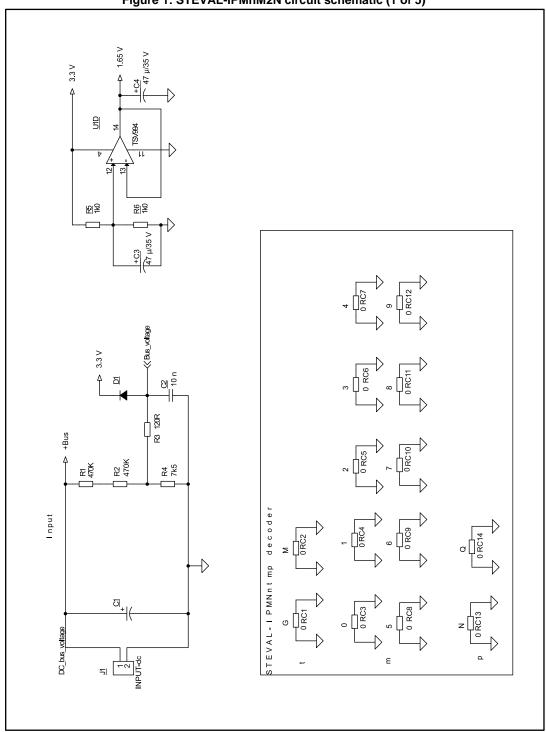
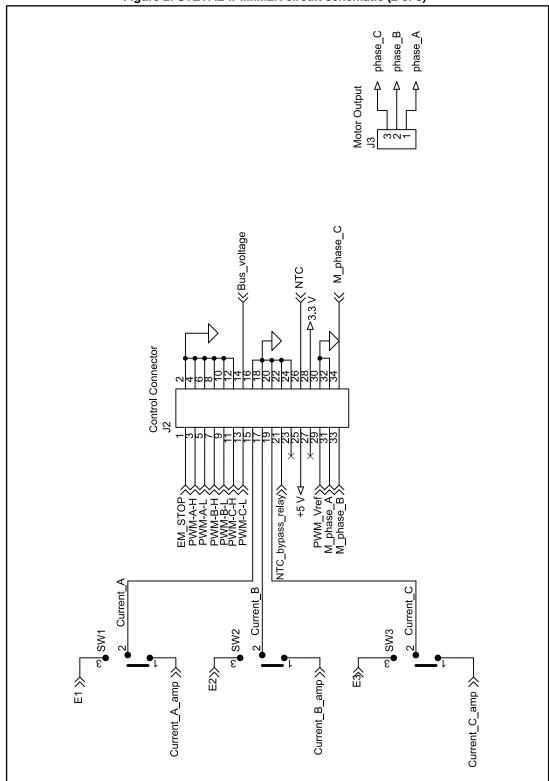


Figure 2: STEVAL-IPMnM2N circuit schematic (2 of 5)



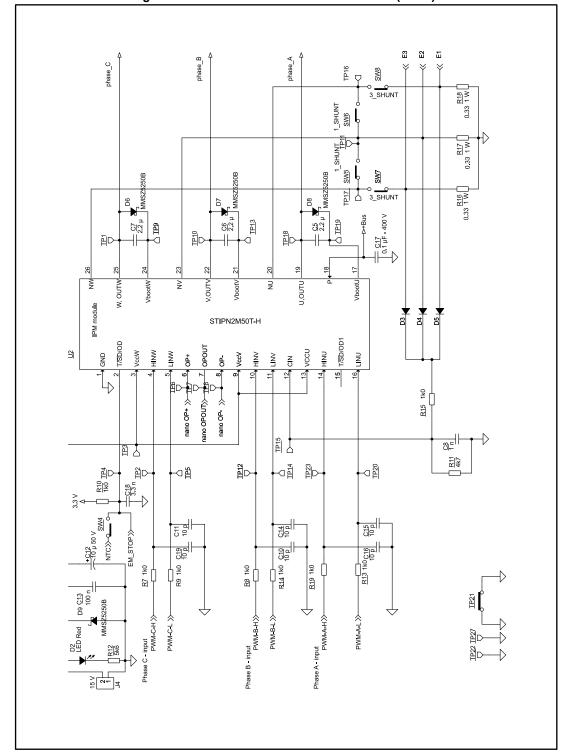


Figure 3: STEVAL-IPMnM2N circuit schematic (3 of 5)

3.3 V Nano OPOUT≫ 110 R43 | ≠ R25 1k9 1k9 19/19/19/19 140 1k0 R26 1.65 V R27 330p 330p 33 ∨ 3.3 V R22 R31 100 n C21 4.7 μ 50 V + | + | + | + | TSV994 U1A U1B R33 1k9 R28 1k9 R20 1k9 R24 1k9 100 p 1k0 R32 R21 R23 1.65 V

Figure 4: STEVAL-IPMnM2N circuit schematic (4 of 5)

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R42 4k7 SW15 ( 表 7 SW14 0 5 R40 4K7 SW13 O C37 10 p R36 4k7 R35 4k7 10 p Hall/Encoder 10 p ₹ 7 2k4 2k4 R37 100 n ω SW16 6MS ω Encoder/Hall -0e4g 3.3 V

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Figure 5: STEVAL-IPMnM2N circuit schematic (5 of 5)

STEVAL-IPMnM2N Revision history

## **Revision history**

Table 1: Document revision history

Date	Version	Changes
05-Sep-2017	1	Initial release.

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