U2040, U2053/63 and L2050/60 X-Series USB/LAN Wide Dynamic Range Power Sensors





Accurately measure any modulated signal with the Keysight Technologies, Inc U2040, U2053/63 and L2050/60 X-Series USB/LAN wide dynamic range power sensor. With LAN connectivity, a first in the industry, and USB connectivity, the U2040, U2053/63 and LAN connectivity, the L2050/60 X-Series comes with the world's widest dynamic range in a power sensor, covering a range of –70 to +26 dBm. And because the U2049XA LAN power sensor is thermal vacuum qualified, you can get the same accuracy and performance even in thermal vacuum chambers.

X-Series Power Sensor Comparison Table

| USB model | LAN model | Description | Frequency range | Power range | Supported measurements | Connector type |
|-----------|-------------|---|------------------|----------------|---|----------------|
| U2041XA | L2051XA | Wide dynamic range average power sensor | 10 MHz to 6G Hz | -70 to +26 dBm | Average, time selectivity in average mode | N-type (male) |
| U2042XA | L2061XA | Wide dynamic range peak and average power sensor | 10 MHz to 6G Hz | -70 to +26 dBm | Peak, average, peak-to-average power, time-gated and free run mode, pulse parameters analysis, pulse profiling | N-type (male) |
| U2043XA | L2052XA | Wide dynamic range average power sensor | 10 MHz to 18 GHz | -70 to +26 dBm | Average, time selectivity in average mode | N-type (male) |
| U2044XA | L2062XA | Wide dynamic range peak and average power sensor | 10 MHz to 18 GHz | -70 to +26 dBm | Peak, average, peak-to-average power, time-gated and free run mode, pulse parameters analysis, pulse profiling | N-type (male) |
| U2053XA | L2053XA | Wide dynamic range average power sensor | 10 MHz to 33 GHz | -70 to +26 dBm | Average, time selectivity in average mode | 3.5 mm (male) |
| U2063XA | L2063XA | Wide dynamic range peak and average power sensor | 10 MHz to 33 GHz | -70 to +26 dBm | Peak, average, peak-to-average power, time-gated and free run mode, pulse parameters analysis, pulse profiling | 3.5 mm (male) |
| | U2049XA | Wide dynamic range peak and average power sensor | 10 MHz to 33 GHz | -70 to +20 dBm | Peak, average, peak-to-average power, time-gated and free | 3.5 mm (male) |
| | U2049XA-TVA | Wide dynamic range peak and average power sensor with thermal vacuum option | 10 MHz to 33 GHz | -70 to +20 dBm | run mode, pulse parameters analysis, pulse profiling | 3.5 mm (male) |

X-Series selection guide

| Measurement types | USB/LAN wide dynamic range average power sensor U2041/43/53 and L2051/52/53XA | USB/LAN wide dynamic range peak and average Power Sensor U2042/44/49/63 and L2061/62/63XA | | |
|--|---|---|--|--|
| CW power | | | | |
| Wideband average power (example: 100 MHz bandwidth) | Yes | | | |
| Time selectivity in average mode | | | | |
| Time gated average power | | | | |
| Pulse profiling (power vs time display) | | | | |
| Peak power or peak-to-average power < 5 MHz bandwidth | No | Yes | | |
| Pulse parameter analysis ≥ 100 ns rise time (example: rise/fall time, duty cycle, pulse width, etc.) | | | | |

X-Series Power Sensor Key Features

Widest dynamic range power sensor

The X-Series power sensor are power sensors with the widest dynamic range of 96 dB (-70 dBm to +26 dBm). The 96 dB dynamic range enables accurate power measurements of very low signal levels for a broad range of applications such as wireless chipset, power amplifier and module manufacturing, satellite payload testing, test system or instrument calibration, and radar pulse parameter measurements. The U2042/44/63 and L2061/62/63XA X-Series peak and average power sensors are able to support up to 4 pairs of gate power measurements.

Super-fast measurement speed

The X-Series power sensor takes up to 50,000 super-fast readings per second (in fast/buffer mode/ average mode), a ten times improvement over Keysight's previous sensor offerings, allowing test engineers to increase test throughput capacity and reduce cost of test especially in high volume manufacturing environments such as mobile chipset manufacturing.

This measurement speed is fast enough to measure every continuous pulse without leaving time gaps in between measurement acquisitions. While conventional sensors only provide a snapshot of continuous pulses, leaving dead time where a glitch could slip by unnoticed, the X-Series power sensor measures continuously in real time and keeps pace with very fast pulses, up to 10 kHz PRF. Users are also able to fully control which portion of the signal is measured and what throughput they can expect because the aperture duration precisely defines the maximum measurement speed as 1/aperture duration. For example, setting the aperture duration to 20 μs offers 20 μs of measurement time per reading, equaling a measurement speed of 50,000 readings per second.



Figure 1. The X-Series power sensor offers real time measurement by measuring every consecutive pulse without dead time.

Broadband coverage for any modulated signal formats

The X-Series power sensor makes accurate average or time-selective average power measurements of any modulated signal, and covers all common wireless signals such as LTE, LTE-Advanced with 100 MHz bandwidth, and WLAN 802.11ac with 80/160 MHz bandwidth. A 4-path diode stack design with parallel data acquisition paths offers seamless range transition with high accuracy and repeatability. This design enables all the diodes to operate in their square law region, allowing the X-Series power sensor to function like thermocouple power sensors to provide accurate average or RMS power for broadband modulated signals.

Time selectivity in average mode with variable aperture duration

The X-Series power sensor offers a new feature called average mode time selectivity, whereby users are able to configure the aperture duration of measurement capture with reference to immediate trigger or external trigger. The aperture duration can be set from 20 μ s to 200 ms with a resolution of 100 ns, a resolution low enough to cover any radio format.

This new feature allows users to control which portions of the waveform to be measured, giving the same results as time-gated power measurements made in the conventional normal/peak mode. The key benefits of this feature is that it enables the sensor to measure both average and time-selective average power measurements across the full 96 dB dynamic range, and offers real time measurements of up to 50,000 readings per second. This is a significant improvement when compared to conventional power sensors; a conventional sensor's time gated power dynamic ranges is typically clipped at around 50 dB with maximum speed of 1000 readings per second.

Internal zero and calibration

Save time and reduce measurement uncertainty with the internal zero and calibration function. Each X-Series power sensor comes with technology that integrates a DC reference source and switching circuits into the body of the sensor so you can calibrate the sensor while it is connected to a device-under-test. This feature removes the need for connection and disconnection from an external calibration source, speeding up testing and reducing connector wear and tear.

This internal zero and calibration function allows continuous long distance and remote measurements by maintaining the accuracy of the sensor, and is useful in manufacturing and automated test environments where each second and each connection counts.

Built-in trigger in and out

An external trigger enables accurate triggering of low level signals close to the sensor's noise floor. The X-Series power sensor come with built-in trigger in/out connection, allowing you to connect an external trigger signal from a signal source or the device-under-test in order to achieve precise triggering timing. Once the trigger output is enabled, a TTL trigger output signal will be generated on every triggered measurement. The built-in trigger in and out is particularly useful when users need to synchronize the measurement acquisition of a series of daisy-chain power sensors.



Figure 2. The external trigger input and output ports on the U2044XA.

20 automatic pulse parameter measurements

The U2042/44/49/63 and L2061/62/63 X-Series peak and average power sensor offers simultaneous pulse parameter characterization of up to 20 pulses within a single capture. Individual pulse duration, period, duty cycle, rise time, fall time and other pulse parameters can be queried through the following SCPI codes: TRACe:MEASurement:PULSe[1-20], and TRACe:MEASurement:TRANsition[1-20].

Together with a system's rise time and fall time of 100 ns and video bandwidth of 5 MHz, the X-Series peak and average power sensor enables a minimum measurable pulse width of 250 ns with its sampling interval of 50 ns. Users can quickly and accurately measure the output power and pulse parameters of pulses for radar pulse component design or manufacturing.



| Pulse parameter | SCPI command |
|---|-------------------------------|
| Duty cycle | TRAC:MEAS:PULS[1-20]:DCYC? |
| Pulse duration | TRAC:MEAS:PULS[1-20]:DUR? |
| Pulse period | TRAC:MEAS:PULS[1-20]:PER? |
| Pulse separation | TRAC:MEAS:PULS[1-20]:SEP? |
| Negative transition duration (fall time) | TRAC:MEAS:TRAN[1-20]:NEG:DUR? |
| Occurrence of a negative transition relative to trigger instant | TRAC:MEAS:TRAN[1-20]:NEG:OCC? |
| Positive transition duration (rise time) | TRAC:MEAS:TRAN[1-20]:POS:DUR? |
| Occurrence of a positive transition relative to trigger instant | TRAC:MEAS:TRAN[1-20]:POS:OCC? |

Figure 3. The X-Series peak and average power sensor offers simultaneous analysis of up to 20 pulses within a single capture.

Auto burst detection

Auto burst detection helps the measurement setup of the trace of gate positions and sizes. This feature also helps set up triggering parameters on a large variety of complex modulated signals by synchronizing to the RF bursts. After a successful auto-scaling, the triggering parameters, such as trigger level, delay and hold-off, are automatically adjusted for optimum operation. The trace settings are also adjusted to align the RF burst to the center of the trace display.

Built-in radar and wireless presets

Begin testing faster; the X-Series power sensor comes with built-in radar and wireless presets for common signals such as DME, GSM, EDGE, WCDMA, WLAN and LTE.

Gamma correction

In an ideal measurement scenario, the reference impedance of the power sensor and device-under-test (DUT) impedance should equal the reference impedance (Z0); however, this is rarely the case in practice. The mismatch in impedance values results in a portion of the signal voltage being reflected, and this reflection is quantified by the reflection coefficient, gamma.

Using the gamma correction function, users can simply input the DUT's gamma into the X-Series power sensor using SCPI commands or the Keysight BenchVue software. This will remove the mismatch error, yielding more accurate measurements.

S-parameter correction

Additional errors are often caused by components that are inserted between the DUT and the power sensor, such as in base station testing where a high power attenuator is connected between the sensor and base station to reduce the output power to the measurable power range of the sensor. The S-parameters of these components can be obtained with a vector network analyzer in the touchstone format, and inputted into the sensor using SCPI commands or through the Keysight BenchVue software. This error can now be corrected using the X-Series power sensor's S-parameter correction function. The sensor will behave as though it is connected directly to the DUT, giving users highly accurate power measurements.

Compact and portable form factor

The X-Series power sensor are standalone sensors that operate without the need of a power meter or an external power supply. The sensors draw power from a USB/LAN port and do not need additional triggering modules to operate, making them portable and lightweight solutions for field applications such as base station testing. Simply plug the sensor to the USB/LAN port of your PC or laptop with Keysight BenchVue software's BV0007B Power Meter/Power Sensor Control and Analysis app and start your power measurements.

U2049XA and L2050/60 X-Series LAN Power Sensor: The Ideal Solution for Remote Monitoring of Satellite Systems

Get the same accuracy and performance in thermal vacuum (TVAC) chambers with the world's first TVAC qualified power sensor. With best-in-class long term drift performance, a frequency range of 10 MHz to 33 GHz and a dynamic range spanning 90 dB, the U2049XA LAN power sensor is ideal for fault detection and monitoring of satellite systems. And with LAN/power over Ethernet (PoE) connectivity, a first in the industry, you can perform long distance, remote monitoring of satellite systems with ease and confidence.



Figure 4. U2049XA Option 100.

LAN/Power over ethernet connectivity

Overcome the cable length limitations associated with USB connectivity. With Power over Ethernet (PoE)/LAN connectivity, the LAN power sensor is capable of long distance remote monitoring of up to 100 meters. The PoE connectivity is also compliant to the IEEE 802.3af or



Note that the typical LAN port found on a PC or Keysight instruments will not be able to power up the LAN power sensor. A typical LAN port is only used for data transfer and communication. The LAN power sensor must connect to a PoE port, which can be used to supply the DC power required to power up the sensor and to transfer data.

Thermal vacuum option

The U2049XA LAN power sensor comes with a thermal vacuum option (Option-TVA) for use within a thermal vacuum chamber. This option has been meticulously designed by selecting components with minimum outgassing properties. Each of the sensors is also subject to temperature cycling in a vacuum chamber to stabilize the materials and to remove outgassing particles.

Performance Specifications

Specification definitions

There are two types of product specifications:

- Warranted specifications are specifications which are covered by the product warranty and apply over a range of 0 to 55 °C unless otherwise noted. Warranted specifications include measurement uncertainty calculated with a 95% confidence.
- Characteristic specifications are specifications that are not warranted.
 They describe product performance that is useful in the application of the product. These characteristics are shown in italics.

Characteristic information is representative of the product. In many cases, it may also be supplemental to a warranted specification. Characteristics specifications are not verified on all units. These are several types of characteristic specifications. They can be divided into two groups:

One group of characteristic types describes 'attributes' common to all products of a given model or option. Examples of characteristics that describe 'attributes' are the product weight and '50-ohm input Type-N connector'. In these examples, product weight is an 'approximate' value and a 50-ohm input is 'nominal'. These two terms are most widely used when describing a product's 'attributes'.

The second group describes 'statistically' the aggregate performance of the population of products. These characteristics describe the expected behavior of the population of products. They do not guarantee the performance of any individual product. No measurement uncertainty value is accounted for in the specification. These specifications are referred to as 'typical'.

The power sensor will meet its specifications when:

- Stored for a minimum of two hours at a stable temperature within the operating temperature range, and turned on for at least 30 minutes
- The power sensor is within its recommended calibration period, and
- Used in accordance to the information provided in the User's Guide
- For power measurements below -60 dBm, it is recommended to turn on the power sensor for 1.5 hours (with the X-Series power sensor connected to the device-under-test)

Specifications

Key specifications

U2041/43/53 and L2051/52/53XA wide dynamic range average power sensor

| | U2041/43XA | U2053 and L2053XA | L2051/52XA | | | | | |
|---|--|---|--|--|--|--|--|--|
| Frequency | U2041XA: 10 MHz to 6 GHz | U2053XA: 10 MHz to 33 GHz | L2051XA: 10 MHz to 6 GHz | | | | | |
| | U2043XA: 10 MHz to 18 GHz | L2053XA: 10 MHz to 33 GHz | L2052XA: 10 MHz to 18 GHz | | | | | |
| Average power power range (Average only mode) | | –70 dBm to +26 dBm | | | | | | |
| Maximum power (Damage level) | | Average: +29 dBm | | | | | | |
| | Peak: +32 dBm for < 10 μs duration | | | | | | | |
| | Voltage: ≤ 20 VDC Voltage: ≤ 10 VDC | | | | | | | |
| Zero and calibration | | Internal zero and calibration supported | | | | | | |
| Maximum sampling rate | 2 | O Msamples/second continuous samplii | ng | | | | | |
| Power linearity at 5 dB step ¹ | | Average mode: < 1.0% | | | | | | |
| Basic accuracy of average power | ≤ ± 0.21 dB or ± 4.7% for < 30 MHz | ≤ ± 0.20 dB or ± 4.6% for < 30 MHz | ≤ ± 0.20 dB or ± 4.5% for < 30 MHz | | | | | |
| measurement ² | \leq ± 0.18 dB or ± 4.1% for ≥ 30 MHz to \leq 10 GHz | \leq ± 0.22 dB or ± 5.0% for \geq 30 MHz to \leq 26.5 GHz | ≤ ± 0.18 dB or ± 4.0% for ≥ 30 MHz to ≤ 10 GHz | | | | | |
| | \leq ± 0.19 dB or ± 4.3% for > 10 GHz to 18 GHz | \leq ± 0.26 dB or ± 5.8% for > 26.5 GHz to \leq 33 GHz | z \leq ± 0.18 dB or ± 4.1% for > 10 GHz to 18 GHz | | | | | |

^{1.} Any relative power measurement of up to 5 dB will have <1% error, excluding zero set, zero drift and noise effects. With default aperture and averaging, for power levels above -50 dBm, zero set, zero drift and noise effects can be disregarded.

^{2.} For all USB/LAN peak and average power sensor except U2049XA, specification is valid over a range of -45 to +26 dBm, DUT Max SWR < 1.2. For U2049XA, specification is valid over a range of -45 to +20 dBm, DUT Max SWR < 1.2. For all models, averaging set to 32, in Free Run mode. For power levels below -45 dBm, the effect of zero drift, zero set and measurement noise have to be considered separately base on the uncertainty calculation method shown in Appendix A.

Specifications (Continued)

Key specifications (Continued)

U2042/44/49/63 and L2061/62/63XA wide dynamic range peak and average power sensor

| | U2042/44XA | U2049XA | U2063XA | L2061/62/63XA | | | | |
|--------------------------------|--------------------------------|-------------------------------------|----------------------------|--------------------------------|--|--|--|--|
| Frequency | U2042XA: 10 MHz to 6 GHz | U2049XA: 10 MHz to 33 GHz | U2063XA: 10 MHz to 33 GHz | L2061XA: 10 MHz to 6 GHz | | | | |
| | U2044XA: 10 MHz to 18 GHz | | | L2062XA: 10 MHz to 18 GHz | | | | |
| Average power power | -70 dBm to +26 dBm | -70 dBm to +20 dBm | -70 dBm to +26 dBm | | | | | |
| range (Average only mode) | | | | | | | | |
| Normal mode power range | Off: -40 to +26 dBm | Off: -40 to +20 dBm | Off: -40 to +26 dBm | | | | | |
| (Peak mode) | High/5 MHz: -40 to +26 dBm | High/5 MHz: -40 to +20 dBm | High/5 MHz: - | -40 to +26 dBm | | | | |
| | Medium/1.5 MHz: -45 to | Medium/1.5 MHz: -45 to | Medium/1.5 MHz | z: –45 to +26 dBm | | | | |
| | +26 dBm | +20 dBm | | | | | | |
| | Low/300 kHz: -45 to | Low/300 kHz: -45 to | Low/300 kHz: | -45 to +26 dBm | | | | |
| | +26 dBm | +20 dBm | | | | | | |
| Maximum power (Damage | | | +29 dBm | | | | | |
| level) | | r < 10 μs duration | | | | | | |
| | Voltage: | Voltage: ≤ 20 VDC Voltage: ≤ 10 VDC | | | | | | |
| Zero and calibration | | Internal zero and ca | alibration supported | | | | | |
| Rise/fall time ³ | | ≤ 10 | 00 ns | | | | | |
| Maximum sampling rate | | 20 Msamples/second | d continuous sampling | | | | | |
| Power linearity at 5 dB | | Average mode: < 1.0% | | | | | | |
| step ¹ | Normal mode: < 1.3% | Normal mode: < 1.0% | Normal mode: < 1.3% | | | | | |
| Basic accuracy of average | ≤ ± 0.21 dB or ± 4.7% for | \leq ± 0.30 dB or ± 6.6% for | ≤ ± 0.20 dB or ± 4.6% for | \leq ± 0.20 dB or ± 4.5% for | | | | |
| power measurement ² | < 30 MHz | < 30 MHz | < 30 MHz | < 30 MHz | | | | |
| | \leq ± 0.18 dB or ± 4.1% for | \leq ± 0.23 dB or ± 5.2% for | ≤ ± 0.22 dB or ± 5.0% for | \leq ± 0.18 dB or ± 4.0% for | | | | |
| | ≥ 30 MHz to ≤ 10 GHz | ≥ 30 MHz to ≤ 26.5 GHz | ≥ 30 MHz to ≤ 26.5 GHz | ≥ 30 MHz to ≤ 10 GHz | | | | |
| | ≤ ± 0.19 dB or ± 4.3% for | ≤ ± 0.27 dB or ± 5.9% for | ≤ ± 0.26 dB or ± 5.8% for | \leq ± 0.18 dB or ± 4.1% for | | | | |
| | > 10 GHz to 18 GHz | > 26.5 GHz to ≤ 33 GHz | > 26.5 GHz to ≤ 33 GHz | > 10 GHz to 18 GHz | | | | |
| Signal bandwidth | | | ower: ≤ 5 MHz ⁴ | | | | | |
| | | Wideband av | verage power | | | | | |
| Single shot bandwidth | | | ЛНZ | | | | | |
| Minimum pulse width | | | O ns | | | | | |
| Maximum capture length | | | cimated) | | | | | |
| | | | sampling rate) | | | | | |
| Maximum pulse repetition rate | | 2 MHz (based on 1 | 10 samples/period) | | | | | |
| 140 | I | , | | | | | | |

^{1.} Any relative power measurement of up to 5 dB will have <1% error, excluding zero set, zero drift and noise effects. With default aperture and averaging, for power levels above -50 dBm, zero set, zero drift and noise effects can be disregarded.

^{2.} For all USB/LAN peak and average power sensor except U2049XA, specification is valid over a range of -45 to +26 dBm, DUT Max SWR < 1.2. For U2049XA, specification is valid over a range of-45 to +20 dBm, DUT Max SWR < 1.2. For all models, averaging set to 32, in Free Run mode. For power levels below -45 dBm, the effect of zero drift, zero set and measurement noise have to be considered separately base on the uncertainty calculation method shown in Appendix A.

^{3.} With video bandwidth OFF setting and carrier frequency ≥ 300 MHz.

^{4.} Five MHz video bandwidth is applicable for carrier frequency ≥ 300 MHz. For carrier frequency < 300 MHz, video bandwidth of LOW/MED is 90 kHz, video bandwidth of HIGH/OFF is 240 kHz. Refer to Characteristic peak flatness section for details.

Specifications (Continued)

Noise and drift

U2041/42/43/44/49XA

| Mode | VBW setting | Zero set ¹ | | Zero drift ² | Measurement noise | Noise per sample | |
|---------------------|-------------|------------------------|---------------|-------------------------|----------------------|------------------|--|
| | | External zero | Internal zero | | | | |
| Normal ³ | LOW/MED | ± 16 nW | ± 23 nW | ± 10 nW | ± 10 nW ⁴ | ± 0.15 μW | |
| | HIGH/OFF | ± 50 nW | ± 60 nW | ± 15 nW | ± 32 nW ⁴ | ± 0.8 μW | |
| Average | - | ± 100 pW for < 300 MHz | ±1 nW | ± 25 pW | ± 80 pW ⁵ | _ | |
| | | ± 70 pW for >= 300 MHz | | | | | |

- After 1 hour of warm up and at a constant temperature.
- After 1 hour of warm up and at a constant temperature, measurements taken over a period of 4 hours after zeroing. Drift is calculated based on the average difference of any two measurements 1 hour apart.
- Only applicable to U2042/44/49XA.
- 4. Noise defined for 1 average at free run mode.5. Noise defined for 16 averages at 50 ms aperture.

U2053/63 and L2051/52/53/61/62/63XA

| Mode | VBW setting | Zero set ¹ | | Zero drift ² | Measurement noise | Noise per sample | |
|---------------------|-------------|------------------------|---------------|-------------------------|----------------------|------------------|--|
| | | External zero | Internal zero | | | | |
| Normal ³ | LOW/MED | ± 12 nW | ± 15 nW | ± 10 nW | ± 10 nW ⁴ | ± 0.15 μW | |
| | HIGH/OFF | ± 27 nW | ± 30 nW | ± 15 nW | ± 32 nW ⁴ | ± 0.8 μW | |
| Average | - | ± 90 pW for < 300 MHz | ±1 nW | ± 25 pW | ± 80 pW ⁵ | _ | |
| | | ± 70 pW for >= 300 MHz | | | | | |

- After 1 hour of warm up and at a constant temperature.
- After 1 hour of warm up and at a constant temperature, measurements taken over a period of 4 hours after zeroing. Drift is calculated based on the average difference of any two measurements 1 hour apart.
- Only applicable to U2063 and L2061/62/63XA.
- Noise defined for 1 average at free run mode. Noise defined for 16 averages at 50 ms aperture.

Noise multipliers

The measurement noise for the X-Series power sensor is dependent on the measurement mode and the time for the measurement. In general, average only mode is lower noise than normal mode, and the longer a measurement takes the lower the noise is. We will define three measurement modes and how the noise can be adjusted.

Average-only mode

The measurement noise due to the X-Series power sensor is dependent on the measurement time. In general, the longer a measurement takes the lower the noise is. The measurement noise specification is defined for 16 averages with an aperture of 50 ms, or a total time of 800 ms. Noise will reduce or increase with the square root ratio of the measurement time to the specification measurement time. Thus a noise multiplier factor can be derived for any combination of averaging and aperture:

$$N_{\text{mult}} = \sqrt{\frac{0.8}{N_{\text{ave}} \times t_{\text{a}}}}$$

Increasing measurement time will reduce noise at this rate until around 3 seconds. As the measurement time increases beyond 3.2 seconds the noise reduction exponent changes from 0.5 to 0.2.

$$N_{\text{mult}} = 0.89 \times \left(\frac{1}{N_{\text{ave}} \times t_{\text{a}}}\right)^{0.5}$$
, for $N_{\text{ave}} \times t_{\text{a}} \le 3.2$

$$N_{mult} = 0.63 \times \left(\frac{1}{N_{ave} \times t_a}\right)^{0.2}$$
, for $N_{ave} \times t_a > 3.2$

$$Noise_{actual} = N_{mult} \times Noise_{spec}$$

Where $N_{ave} \stackrel{\text{def}}{=} number$ of averages and $t_a \stackrel{\text{def}}{=} aperture$ in seconds.

Free-run normal mode

The measurement noise specification is defined for 1 average. Although the noise will reduce with increased averaging, it will not have a significant impact on the measurement uncertainty, and the figure of 32 nW (High/Off VBW) or 10 nW (Low/Med VBW) without any multiplier should be used in the uncertainty calculations. (Refer to the measurement noise in the noise and drift table above.)

Gated-average normal mode

The measurement noise on a time-gated average power measurement in normal mode will depend on the time gate length. 20 averages are carried out every 1 µs of gate length. The noise-per-sample contribution in this mode can be reduced by approximately $\underbrace{\text{gate length}}_{\textbf{50 ns}} \text{ to a limit of 32 nW. (Refer to the noise and drift table above for the noise-per-sample.)}$

Maximum SWR

| Frequency band | U2041/42XA | | U2043/44XA | | L2051/61XA | | L2052/62XA | |
|-------------------|---------------------|-------------------|---------------------|-------------------|-------------------|---------------------|-------------------|---------------------|
| Power level | –70 to < +15 dBm | +15 to +26 dBm | –70 to < +15 dBm | +15 to +26 dBm | -70 to +15 dBm | > +15 to +26 dBm | -70 to +15 dBm | > +15 to +26 dBm |
| 10 MHz to 6 GHz | < 1.2 | < 1.29 | < 1.20 | < 1.29 | < 1.15 | < 1.24 | < 1.15 | < 1.24 |
| > 6 GHz to 18 GHz | | | < 1.26 | < 1.30 | | | < 1.26 | < 1.30 |

| Frequency band | U2049XA | |
|-----------------------|------------------|----------------|
| Power level | -70 to < +15 dBm | +15 to +20 dBm |
| 10 MHz to 30 MHz | < 2.18 | < 2.21 |
| > 30 MHz to 50 MHz | < 1.35 | < 1.37 |
| > 50 MHz to 100 MHz | < 1.22 | < 1.24 |
| > 100 MHz to 11.5 GHz | < 1.17 | < 1.21 |
| > 11.5 GHz to 30 GHz | < 1.29 | < 1.33 |
| > 30 GHz to 33 GHz | < 1.33 | < 1.36 |

| Frequency band | U2053/63XA and L2053/63XA | |
|----------------------|---------------------------|------------------|
| Power level | -70 to +15 dBm | > +15 to +26 dBm |
| 10 MHz to 6 GHz | < 1.16 | < 1.24 |
| > 6 GHz to 16 GHz | < 1.24 | < 1.27 |
| > 16 GHz to 26.5 GHz | < 1.33 | < 1.40 |
| > 26.5 GHz to 33 GHz | < 1.41 | < 1.53 |

Calibration uncertainty

Definition: Uncertainty resulting from non-linearity in the X-Series power sensor detection and correction process. This can be considered as a combination of traditional linearity, calibration factor and temperature specifications and the uncertainty associated with the internal calibration process.

Average mode

| Frequency band | U2041/42XA | U2043/44 | U2049XA | L2051/61XA | L2052/62XA | U2053/63 and L2053/63XA |
|----------------------|------------|----------|---------|------------|------------|----------------------------|
| 10 MHz to 30 MHz | 4.40% | 4.40% | 4.50% | 4.30% | 4.30% | 4.40% |
| > 30 MHz to 500 MHz | 3.70% | 3.70% | 3.90% | 3.50% | 3.50% | 3.90% |
| > 500 MHz to 1 GHz | 3.70% | 3.70% | 3.80% | 3.50% | 3.50% | 3.90% |
| > 1 GHz to 6 GHz | 3.70% | 3.70% | 3.90% | 3.50% | 3.50% | 3.90% |
| > 6 GHz to 10 GHz | _ | 3.70% | 4.00% | _ | 3.60% | 4.00% |
| > 10 GHz to 18 GHz | _ | 4.00% | 4.20% | _ | 3.70% | 4.20% |
| > 18 GHz to 26.5 GHz | _ | _ | 4.90% | _ | _ | 4.50% |
| > 26.5 GHz to 33 GHz | _ | _ | 5.60% | _ | - | 5.10% |

Normal mode

| Frequency | VBW OFF/HIGH | | | VBW MED/LOW | | VBW OFF/HIGH | | | VBW MED/LOW | | | |
|-------------------------|----------------------|----------------------|---------|-------------|---------|--------------|---------|---------|-------------------------|---------|---------|-------------------------|
| band | U2042XA ¹ | U2044XA ¹ | U2049XA | U2042XA | U2044XA | U2049XA | L2061XA | L2062XA | U2063 and L2063XA | L2061XA | L2062XA | U2063 and L2063XA |
| 10 MHz to 30 MHz | 5.70% | 5.70% | 4.50% | 4.40% | 4.40% | 4.50% | 4.30% | 4.30% | 4.40% | 4.50% | 4.50% | 4.30% |
| > 30 MHz to 500 MHz | 5.20% | 5.20% | 4.10% | 3.70% | 3.70% | 3.90% | 3.60% | 3.60% | 4.10% | 3.80% | 3.80% | 4.00% |
| > 500 MHz to 1 GHz | 5.20% | 5.20% | 3.90% | 3.70% | 3.70% | 3.90% | 3.60% | 3.60% | 4.10% | 3.80% | 3.80% | 4.00% |
| > 1 GHz to 6 GHz | 5.30% | 5.30% | 4.00% | 3.70% | 3.70% | 4.00% | 3.60% | 3.60% | 4.10% | 3.70% | 3.70% | 4.00% |
| > 6 GHz to 10 GHz | _ | 5.30% | 4.10% | _ | 3.70% | 4.10% | _ | 3.60% | 4.10% | - | 3.70% | 4.10% |
| > 10 GHz to 18 GHz | _ | 5.40% | 4.30% | _ | 4.00% | 4.20% | _ | 3.80% | 4.30% | - | 3.80% | 4.30% |
| > 18 GHz to 26.5 GHz | - | - | 5.00% | _ | _ | 4.90% | - | - | 4.60% | - | _ | 4.50% |
| > 26.5 GHz to 33 GHz | _ | _ | 5.70% | _ | _ | 5.60% | _ | _ | 5.20% | _ | _ | 5.20% |

^{1.} Specification valid for environment up to 70% relative humidity. Additional 1.6% to be included for environment up to 95% relative humidity.

Timebase and Trigger Specifications

| Timebase | U2042/44/49XA | U2063 and L2061/62/63XA | | |
|------------------------------------|--|-------------------------------|--|--|
| Range | 2 ns to 1 | 100 ms/div | | |
| Accuracy | ± 25 ppm | ± 2.0 ppm ¹ | | |
| Jitter | ٠ ک | 1 ns | | |
| Trigger | | | | |
| Internal trigger range | U2042/44XA: -25 to +26 dBm | -25 to +26 dBm | | |
| | U2049XA: -2 | 25 to +20 dBm | | |
| Resolution | 0.1 | 1 dB | | |
| Level accuracy | ± 0. | .5 dB | | |
| Latency | 1.5 μs ± 50 ns | 1.95 μs ± 50 ns | | |
| Jitter | ≤ 5 r. | ns rms | | |
| External TTL trigger input | · | | | |
| High | > 2 | 2.4 V | | |
| Low | < (| 0.7 V | | |
| Latency | 500 ns ± 50 ns | 950 ns +- 50ns | | |
| Minimum trigger pulse width | 150 ns (ave | erage mode) | | |
| | 50 ns (noi | rmal mode) | | |
| Minimum trigger repetition period | 300 ns (ave | erage mode) | | |
| | 100 ns (normal mode) | | | |
| Maximum trigger voltage input | 5 V EMF from 50 Ω DC (current < 100 mA) or | | | |
| | 5 V EMF from 50 Ω pulse wi | idth < 1 s (current < 100 mA) | | |
| Impedance | 100 kΩ (de | efault), 50 Ω | | |
| Jitter | ≤ 15 / | ns rms | | |
| External TTL trigger output | • | | | |
| High | > 2 | 2.4 V | | |
| Low | < 0 |).7 V | | |
| Latency | 500 ns ± 50 ns | 950 ns +- 50ns | | |
| Impedance | > 2 | 2.4 V | | |
| Jitter | ≤ 15 / | ns rms | | |
| Trigger delay | · | | | |
| Range | Normal mo | ode: ± 1.0 s | | |
| | Average only mode: –1.6 ms to +1 s | | | |
| Resolution | 1% of delay setting, 50 ns minimum | | | |
| Trigger hold off | | | | |
| Range | 1 μs to 400 ms | | | |
| Resolution | 1% of selected value (| (to a minimum of 50 ns) | | |
| Trigger level threshold hysteresis | • | | | |
| Range | ± 3 | 3 dB | | |
| Resolution | | 15 dB | | |

^{1.} \pm 2.0 ppm for first year. Typically \pm 2.7 ppm after first year.

General Specifications

| Inputs/Outputs | |
|---|---|
| | 100 4 40 40 40 4 475 1004 1 1 1 1 1 500 1 |
| Current requirement | U2041/42/43/44/53/63XA: Approximately < 500 mA |
| | U2049 and L2051/52/53/61/62/63XA: 3W, 802.3af or 802.3at Type 1 standard |
| Trigger input | Input has TTL compatible logic levels and uses a SMB connector |
| Trigger output | Output provides TTL compatible logic levels and uses a SMB connector |
| Remote programming | |
| Interface | U2041/42/43/44/53/63XA: USB 2.0 interface USB-TMC compliance |
| | U2049 and L2051/52/53/61/62/63XA: 10/100 Mbps RJ-45 Power Over Ethernet port, transfers |
| | data and power on one single cable, 802.3af or 802.3 at Type 1 compliant |
| Command language | SCPI standard interface commands, IVI-COM, IVI-C drivers |
| Maximum measurement speed (Applicable for | USB & LAN socket connectivity) |
| Free run trigger measurement | 25,000 readings per second ¹ |
| External trigger time-gated measurement | 20,000 readings per second ² |
| Average mode real time measurement | 50,000 readings per second ³ |

^{1.} Tested under normal mode and fast mode, with buffer mode trigger count of 100, output in binary format, unit in watt, auto-zeroing, auto-calibration, and step detect disabled.

Mechanical Characteristic

Mechanical characteristics such as center conductor protrusion and pin depth are not performance specifications. They are, however, important supplemental characteristics related to electrical performance. At no time should the pin depth of the connector be protruding.

^{2.} Tested under normal mode and fast mode, with buffer mode trigger count of 100, pulsed signal with PRF of 20 kHz, and pulse width at 15 µs.

^{3.} Tested under average only mode and fast mode, with buffer mode trigger count of 200, aperture duration of 20 µs, data format set to real, external trigger or immediate trigger setting. For LAN socket connectivity, network traffic might affect the measurement speed intermediately. Direct LAN connection to computer via PoE injector would provide the fastest measurement speed.

General Characteristics

| Environmental complia | ance | | | | |
|-----------------------|---------------------------|---|----------------------------|------------------------------|-------------------------|
| Temperature | | All models except U2049XA-TVA: | | | |
| | | - Operating condition: 0 to 55 °C | | | |
| | | Storage condition: | | | |
| | | For U2049XA-TVA: | | | |
| | | Operating Condition | n: 0 to 55 °C | | |
| | | | on TVA, this operating cor | ndition is applicable for bo | th standard Atmospheric |
| | | environment and t | nermal vacuum environme | ent. | · |
| | | Storage condition: | -40 to 70 °C | | |
| | | 40 to 100 °C (for | U2049XA Option TVA) | | |
| Humidity | | Operating condition: Ma | aximum 95% at 40 °C (nor | n-condensing) | |
| | | Storage condition: Up to | o 90% at 65 °C (non-cond | ensing) | |
| Altitude | | Operating condition: Up to 3,000 m (9,840 ft) | | | |
| | | Storage condition: Up to 15,420 m (50,000 ft) | | | |
| Regulatory compliance | e | | | | |
| · · | with the following safety | IEC 61010-1:2001/EN61010-1:2001 (2nd edition) | | | |
| and EMC requirements | | IEC 61326:2002/EN 61326:1997 + A1:1998 +A3:2003 | | | |
| | | Canada: ICES-001:2004 | | | |
| | | Australia/New Zealand: AS/NZS CISPR11:2004 | | | |
| | | Canada: ICES-001:2004 | | | |
| | | Australia/New Zealand: | AS/NZS CISPR11:2004 | | |
| Others | U2041/42/43/44XA | U2053/63XA | L2051/52/61/62XA | L2053/63XA | U2049XA |
| Dimensions (Length x | 168 mm x 46 mm x | 148 mm x 44 mm x | 180 mm x 46 mm x | 169 mm x 46 mm x | 197 mm x 40 mm x |
| Width x Height) | 35 mm | 35 mm | 36 mm | 36 mm | 24 mm |
| Net weight | | ≥ (|).3 kg | | ≤ 0.37 kg |
| Shipping weight | | ₹, | 1.3 kg | | ≤ 1.4 kg |
| Recommended | | | 1 year | | |
| calibration interval | | | | | |

Additional Specifications for U2042/44/49/63 and L2061/62/63XA X-Series Peak and Average Power Sensor

Measured rise time percentage error versus signal-under-test rise time

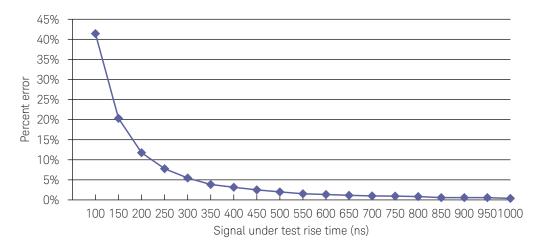


Figure 6. Measured rise time percentage error versus signal under test rise time.

Although the rise time specification is \leq 100 ns, this does not mean that the U2042/44/49/63 and L2061/62/63XA X-Series peak and average power sensor can accurately measure a signal with a known rise time of 100 ns. The measured rise time is the root sum squares (RSS) of the signal-under-test (SUT) rise time and the system rise time:

Measured rise time = $\sqrt{[(SUT \text{ rise time})^2 + (system \text{ rise time})^2]}$

And the % error is:

% error =
$$\left[\frac{\text{measured rise time} - \text{SUT rise time}}{\text{SUT rise time}}\right] \times 100^{\circ}$$

Video bandwidth

The video bandwidth in the normal mode of the X-Series peak and average power sensor can be set to High (5 MHz), Medium (1.5 MHz), Low (300 KHz), and Off. The video bandwidths stated below are not the 3 dB bandwidths, as the video bandwidths are corrected for optimal flatness (except the Off filter). Refer to Figure 6, "Characteristic peak flatness," for information on the flatness response. The Off video bandwidth setting provides the warranted rise time and fall time specifications and is the recommended setting for minimizing overshoot on pulse signals.

Additional Specifications for U2042/44/49/63 and L2061/62/63XA X-Series Peak and Average Power Sensor (Continued)

U2042/44/49XA

| Video bandwidt (Normal mode) | h setting | LOW | MED | HIGH | OFF |
|---------------------------------|-----------|--------|--------|--------|--------|
| Rise/fall time | < 300 MHz | 6.9 µs | 6.9 µs | 2.0 μs | 2.0 μs |
| | ≥ 300 MHz | 0.6 μs | 0.3 μs | 0.1 μs | 0.1 μs |
| Overshoot 1 | < 300 MHz | 2% | 2% | 3% | 4% |
| | ≥ 300 MHz | 12% | 15% | 9% | 5% |

U2063 and L2061/62/63XA

| Video bandwidth s (Normal mode) | etting | LOW | MED | HIGH | OFF |
|------------------------------------|-----------|--------|---------|--------|--------|
| Rise/fall time ² | < 300 MHz | 5.3 µs | 5.4 μs | 1.8 µs | 1.8 µs |
| | ≥ 300 MHz | 0.6 μs | 0.64 μs | 0.1 μs | 0.1 μs |
| Overshoot ¹ | < 300 MHz | 2% | 2% | 3% | 4% |
| | ≥ 300 MHz | 12% | 15% | 9% | 5% |

The average mode of the X-Series peak and average power sensor provide accurate average power measurements for broadband modulated signals similar to a thermocouple sensor. This is due to the X-Series power sensor' four path diode design, which enables all the diodes to operate in their square-law region.

- 1. Specification is based on pulse signal with \geq 80 ns rise time.
- 2. Specification is based on pulse signal with 5 ns rise time.

Characteristic peak flatness

The peak flatness is the flatness of a peak-to-average ratio measurement for various tone separations of an equal two-tone RF input. Figure 5 below refers to the relative error in peak-to-average ratio measurements as the tone separation is varied. The measurements were performed at -10 dBm and applicable for carrier frequency ≥ 300 MHz.

Additional Specifications for U2042/44/49/63 and L2061/62/63XA X-Series Peak and Average Power Sensor (Continued)

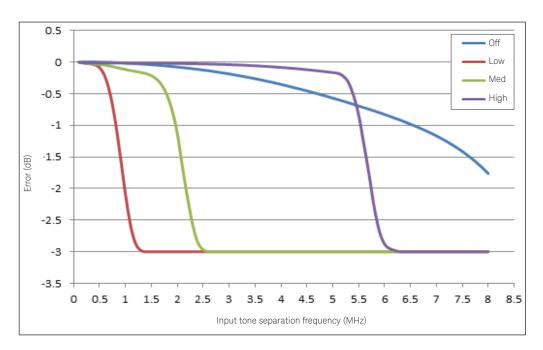


Figure 7. U2042/44/49XA error in peak-to-average ratio measurements for a two-tone input (High, Medium, Low and Off video bandwidth settings).

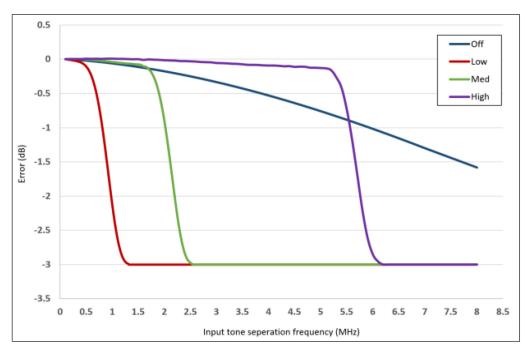


Figure 8 U2063 and L2061/62/63XA error in peak-to-average ratio measurements for a two-tone input (High, Medium, Low and Off video bandwidth settings).

Using the X-Series Power Sensor with the BenchVue Software

Keysight BenchVue software for the PC accelerates testing by providing intuitive, multiple instrument measurement visibility and data capture with no programming necessary. You can derive answers faster than ever by easily viewing, capturing and exporting measurement data and screen shots. The X-Series power sensor is supported by the Keysight BenchVue software and BV0007B power meter/sensor control and analysis app. Once you plug the X-Series power sensor into a PC and run the software you can see measurement results in a wide array of display formats and log data without any programming.

For more information, www.keysight.com/find/BenchVue

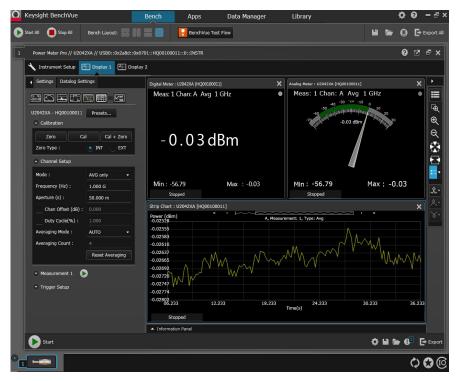


Figure 8. Digital meter, analog meter and datalog view.

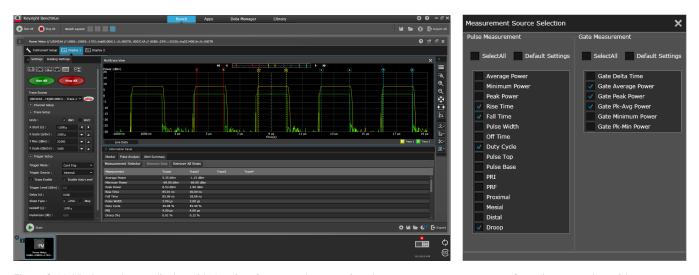


Figure 9. Multi-channel trace display with 4-pairs of gates and automatic pulse parameters measurement (sample screen shot with two U2042XAs).

Using the X-Series Power Sensor with the BenchVue Software (Continued)

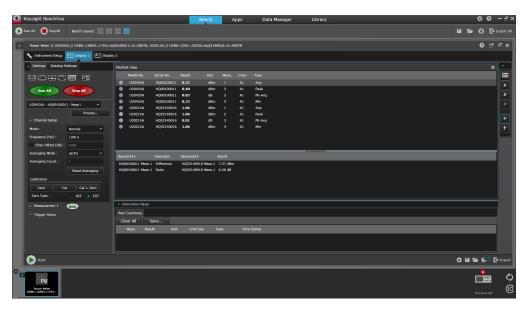


Figure 10. Multi-list view with ratio/difference function.

| Supported functionality | |
|----------------------------------|---|
| Measurement displays | Digital meter |
| | Analog meter |
| | Data log view |
| | Trace view (up to 4 channels or traces on one graph) |
| | Multilist with ratio/delta function |
| | Compact mode display |
| Graph functions | Single marker (up to 5 markers per graph) |
| | Dual marker (up to 2 sets of markers per graph) |
| | Graph autoscaling |
| | Graph zooming |
| | Gate measurement analysis (up to 4-pair of gates) |
| Pulse characterization functions | 17-point automatic pulse parameters characterization |
| Instrument settings | Save and recall instrument state including graph settings |
| | Instrument preset settings (DME, GSM, WCDMA, WLAN, LTE, etc.) |
| | FDO tables |
| | Gamma and S-parameters tables |
| | Full instrumentation control include frequency/average/trigger settings, zero and calibration, etc. |
| Limit and alert function | Sensors Limit and alert notification |
| | Alert summary |
| Export data or screen shots | Data logging (HDF5/MATLAB/Microsoft Excel/Microsoft Word/CSV) |
| | Save screen capture (PNG/JPEG/BMP) |

System and Installation Requirements

| PC operating system | |
|--------------------------------------|--|
| Windows 10, 8 and 7 | Windows 10 32-bit and 64-bit (Professional, Enterprise, Education, Home versions) |
| | Windows 8 32-bit and 64-bit (Core, Professional, Enterprise) |
| | Windows 7 SP1 and later 32-bit and 64-bit (Professional, Enterprise, Ultimate) |
| Computer hardware | Professor: 1 GHz or faster (2 GHz or greater recommended) |
| | RAM: 1 GB (32-bit) or 2 GB (64-bit) (3 GB or greater recommended) |
| Windows XP SP3 32-bit (Professional) | Processor: 600 MHz or faster (1 GHz or greater recommended) |
| | RAM: 1 GB (2 GB or greater recommended) |
| Interfaces | USB, GPIB, LAN, RS-232 |
| Display resolution | 1024 x 768 minimum for single instrument view (higher resolutions are recommended for multiple |
| | instrument view) |

Additional requirements

Software: BenchVue requires a VISA (Keysight or National Instruments) when used to connect to physical instruments. Keysight IO Libraries, which contains the necessary VISA, will be installed automatically when BenchVue is installed. IO Libraries information is available at: **www.keysight.com/find/iosuite**.

Ordering Information

| Model | Description |
|---|---|
| U4241XA | USB wide dynamic range average power sensor, 10 MHz to 6 GHz |
| U4242XA | USB peak and average power sensor, 10 MHz to 6 GHz |
| U2043XA | USB wide dynamic range average power sensor, 10 MHz to 18 GHz |
| U2044XA | USB peak and average power sensor, 10 MHz to 18 GHz |
| U2049XA, Option 100 | LAN peak and average power sensor, 10 MHz to 33 GHz |
| U2049XA, Option TVA | LAN peak and average power sensor, 10 MHz to 33 GHz, thermal vacuum option |
| U2053XA | USB wide dynamic range average power sensor, 10 MHz to 33 GHz |
| U2063XA | USB wide dynamic range peak and average power sensor, 10 MHz to 33 GHz |
| L2051XA | LAN wide dynamic range average power sensor, 10 MHz to 6 GHz |
| L2052XA | LAN wide dynamic range average power sensor, 10 MHz to 18 GHz |
| L2053XA | LAN wide dynamic range average power sensor, 10 MHz to 33 GHz |
| L2061XA | LAN wide dynamic range peak and average power sensor, 10 MHz to 6 GHz |
| L2062XA | LAN wide dynamic range peak and average power sensor, 10 MHz to 18 GHz |
| L2063XA | LAN wide dynamic range peak and average power sensor, 10 MHz to 33 GHz |
| Standard shipped items | |
| U2041/42/43/44/53/63XA USB power sensor | USB cable 5 ft (1.5 m), default cable length |
| | BNC male to SMB female trigger cable, 50Ω , $1.5 m$ (Quantity: 2) |
| | Certificate of calibration |
| | Documentation CD-ROM |
| | Keysight Instrument Control DVD |
| | - 10 libraries suite |
| | - Command expert |
| | - BenchVue software platform |
| | - 30-day free trial of BenchVue power meter/sensor control and analysis app |
| U2049 and L2051/52/53/61/62/63XA LAN | LAN cable 5 ft (1.5 m), default cable length |
| power sensor | Standard LAN cable |
| | BNC male to SMB female trigger cable, 50Ω , $1.5 m$ (Quantity: 2) |
| | Certificate of calibration |
| | Documentation CD-ROM |
| | Keysight Instrument Control DVD |
| | - 10 libraries suite |
| | - Command expert |
| | - BenchVue software platform |
| | - 30-day free trial of BenchVue power meter/sensor control and analysis app |

Ordering Information (Continued)

U2041/42/43/44/53/63XA USB power sensor options

| Options | Description |
|--|--|
| Accessories | |
| U2000A-201 | Transit case |
| U2000A-202 | Soft carrying case |
| U2000A-203 | Holster |
| U2000A-204 | Soft carrying pouch |
| Cables (selectable during sensor purchase) | |
| U2000A-301 | USB cable 5 ft (1.5 m) – default selection |
| U2000A-302 | USB cable 10 ft (3 m) |
| U2000A-303 | USB cable 16.4 ft (5 m) |
| Cables (ordered standalone) | |
| U2031A | USB cable 5 ft (1.5 m) |
| U2031B | USB cable 10 ft (3 m) |
| U2031C | USB cable 16.4 ft (5 m) |
| U2032A | BNC male to SMB female trigger cable, 50 Ω, 1.5 m |
| Software | |
| BV0007B | BenchVue power meter/sensor control and analysis app license |
| Calibration | |
| UK6 | Commercial calibration with test data |

U2049 and L2051/52/53/61/62/63XA LAN power sensor options $^{\rm 1}$

| Options | Description | | | |
|--|--|--|--|--|
| Standard LAN cables (selectable during sensor purchase and orderable standalone) | | | | |
| U2034A | LAN cable 5 ft (1.5 m) – default selection Options 100 and TVA | | | |
| U2034B | LAN cable 10 ft (3 m) | | | |
| U2034C | LAN cable 16.4 ft (5 m) | | | |
| U2034D | LAN cable 50 ft (15.2 m) | | | |
| U2034E | LAN cable 100 ft (30.5 m) | | | |
| U2034F | LAN cable 200 ft (61 m) | | | |
| Trigger cable | | | | |
| U2032A | Standard trigger cable BNC Male to SMB female, 50 Ω , 1.5 m | | | |
| Software | | | | |
| BV0007B | BenchVue power meter/sensor control and analysis app license | | | |
| Calibration | | | | |
| UK6 | Commercial calibration with test data | | | |

^{1.} PoE injector is not included. A commercially-available general PoE injector can be used with the U2049, L2051/52/53/61/62/63XA.

Appendix A

Uncertainty calculations for a power measurement (settled, average power)

(Specification values from this document are in **bold italic**, values calculated on this page are underlined.)

| Proce | SS | |
|-------|--|----|
| | | |
| 1. | Measured power level | W |
| 2. | Frequency of measured signal (use to get calibration uncertainty and SWR) | Hz |
| 3. | Calculate sensor uncertainty: | |
| | Calculate noise contribution (from page 11) | |
| | - Average-only mode: Noise = Measurement noise x average-only-mode noise multiplier | |
| | - Free-run normal mode: <u>Noise</u> = Measurement noise for video bandwidth setting | |
| | Gated-average normal mode (Trigger normal mode), Noise = Noise-per-sample x noise-per-sample multiplier | |
| | Convert noise contribution to a relative term 1 = Noise/Power | % |
| | Convert zero drift to relative term = Drift/Power = | % |
| | RSS of above terms = | % |
| 4. | Zero uncertainty | |
| | (Mode and frequency dependent) = Zero set/Power = | % |
| 5. | Sensor calibration uncertainty (from page 12) | |
| | (Sensor, measurement mode, frequency, and humidity dependent) = | % |
| 6. | System contribution, coverage factor of $2 \ge sys_{rss} = \dots$ | % |
| | (RSS three terms from steps 3, 4 and 5) | |
| 7. | Standard uncertainty of mismatch | |
| | Max SWR (frequency dependent) = | |
| | Convert to reflection coefficient, ρ_{Sensor} = (SWR-1)/(SWR+1) = | |
| | Max DUT SWR (frequency dependent) = | |
| | Convert to reflection coefficient, ρ_{DUT} = (SWR-1)/(SWR+1) = | |
| 8. | Combined measurement uncertainty @ k = 1 | |
| | $U_{C} = \sqrt{\left(\frac{Max(\mathbf{p}_{DUT}) \cdot Max(\mathbf{p}_{Sensor})}{\sqrt{2}}\right)^{2} + \left(\frac{SyS_{rss}}{2}\right)^{2}}$ | % |

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Expanded uncertainty, k = 2, = UC · 2 =

^{1.} The noise to power ratio for average only mode is capped at 0.01% for MU calculation purposes.

Worked Example for U2041XA

Uncertainty calculations for a power measurement (settled, average power)

(Specification values from this document are in **bold italic**, values calculated on this page are underlined.)

| Proce | SS | |
|-------|---|------------|
| | | |
| 1. | Measured power level | 1 mW |
| 2. | Frequency of measured signal (use to get calibration uncertainty and SWR) | 1 GHz |
| 3. | Calculate sensor uncertainty: In Free Run, auto zero mode average = 1 | |
| | Calculate noise contribution, assuming 50 ms aperture (default) (from page 11) | |
| | Average-only mode: Noise = Measurement noise x average-only-mode noise multiplier = 80 pW x 4.0 = 0.32 nW | |
| | - Free-run normal mode: <u>Noise</u> = Measurement noise for video bandwidth setting | |
| | Gated-average normal mode (Trigger normal mode), <u>Noise</u> = Noise-per-sample x noise-per-sample multiplier | |
| | Convert noise contribution to a relative term 1 = Noise/Power = 0.32 nW/1 mW = 0.000032%, value clipped to 0.01% = | 0.01% |
| | Convert zero drift to relative term = Drift/Power = 25 pW/1 mW | 0.0000025% |
| | RSS of above terms = | 0.01% |
| 4. | Zero uncertainty | |
| | (Mode and frequency dependent) = Zero set/Power = 70 pW/1 mW | 0.000007% |
| 5. | Sensor calibration uncertainty (from page 12) | |
| | (Sensor, measurement mode, frequency, and humidity dependent) = | 3.7% |
| 6. | System contribution, coverage factor of 2 ≥ sys _{rss} = | 3.7% |
| | (RSS three terms from steps 3, 4 and 5) | |
| 7. | Standard uncertainty of mismatch | |
| | Max SWR (frequency dependent) = | 1.20 |
| | Convert to reflection coefficient, $ \rho_{Sensor} = (SWR-1)/(SWR+1) =$ | 0.091 |
| | Max DUT SWR (frequency dependent) = | 1.26 |
| | Convert to reflection coefficient, $ \rho_{DUT} = (SWR-1)/(SWR+1) =$ | 0.115 |
| 8. | Combined measurement uncertainty @ k = 1 | |
| | | |
| | $U_{C} = \sqrt{\left(\frac{Max \left(\mathbf{p}_{DUT}\right) \cdot Max \left(\mathbf{p}_{Sensor}\right)}{\sqrt{2}}\right)^{2} + \left(\frac{sys_{rss}}{2}\right)^{2}} U_{C} = \sqrt{\left(\frac{0.091 \cdot 0.155}{\sqrt{2}}\right)^{2} + \left(\frac{0.037}{2}\right)^{2}}$ | 1.99% |

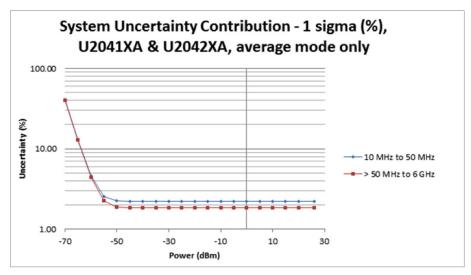
Expanded uncertainty, k = 2, = UC · 2 =....

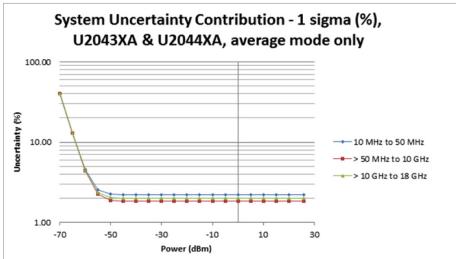
3.98%

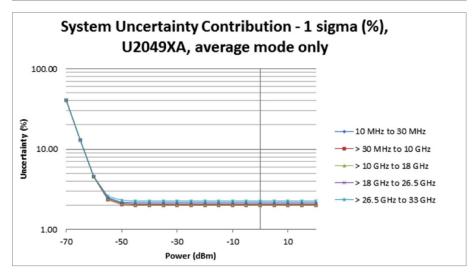
^{1.} The noise to power ratio for average only mode is capped at 0.01% for measurement uncertainty calculation purposes.

Graphical Example

A. System contribution to measurement uncertainty versus power level (equates to step 6 result/2)



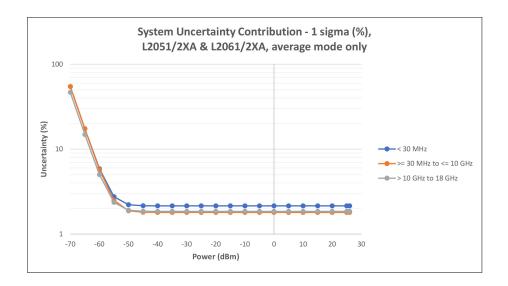


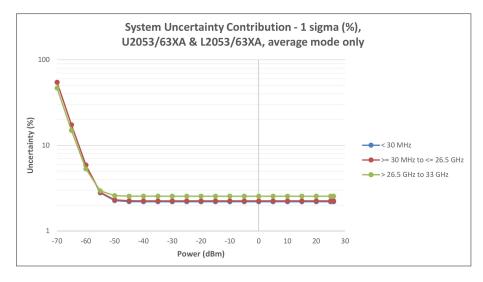


Note: The above graph is valid for conditions of free-run operation, with a signal within the video bandwidth setting on the system. Humidity < 70 %.

Graphical Example (Continued)

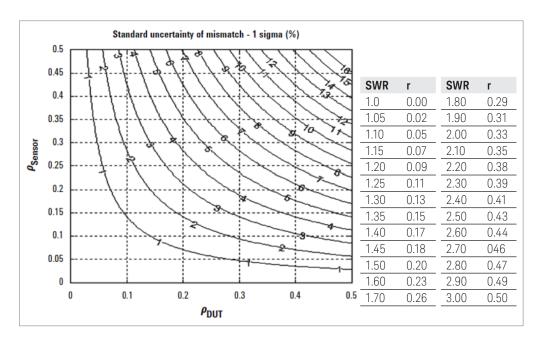
A. System contribution to measurement uncertainty versus power level (equates to step 6 result/2 (Continued)





Graphical Example (Continued)

B. Standard uncertainty of mismatch



Note: The above graph shows the Standard Uncertainty of Mismatch = ρ DUT. ρ Sensor / $\sqrt{2}$, rather than the Mismatch Uncertainly Limits. This term assumes that both the Source and Load have uniform magnitude and uniform phase probability distributions.

C. Combine A and B

 $U_{c} = \sqrt{(Value from Graph A)^{2} + (Value from Graph B)^{2}}$

Expanded uncertainty, k = 2, $= U_C \cdot 2 = \dots$ ± %

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