

Innovative Xsens sensor fusion algorithm

- Superior heading tracking using Active Heading Stabilization (AHS)
- In-run Compass Calibration (ICC)
- State-of-the-art sensor fusion algorithm
- Selectable filter profiles for range of applications
- Tuned for performance under vibrations and magnetic distortions

Best-in-class hardware design

- Highest quality industrial grade components
- Vibration-rejecting gyroscopes and accelerometers
- Low latency for real-time applications
- 10 kHz simultaneous sampling, 2 kHz SDI algorithm with coning/sculling compensation
- Wide array of synchronization options

Easy software integration

- Extensive suite of configurable output formats, calculated onboard the MTi
- MT Software Suite with intuitive GUI
- Complete SDK for all operating systems (Linux/Windows)
- Support for Robotic Operating System (ROS)
- Xsens Xbus protocol or ASCII (NMEA)
- Access to BASE (by Xsens), an extensive knowledge base and community forum

Specification highlights

- Available as IP67 encased MTi or OEM board
- Choice of several interfaces and onboard USB
- All Xsens products are fully interchangeable
- Cost-effective system integrator solution
- Internal low-noise barometer
- True North without requiring a magnetic field
- Position, velocity and orientation outputs

Product overview

	MTi-100 IMU	MTi-200 VRU	MTi-300 AHRS	MTi-G-710 GNSS/INS
Calibrated Sensor Data	yes	yes	yes	yes
Roll/pitch (Static)	-	0.2°	0.2°	0.2°
Roll/pitch (Dynamic)	-	0.3°	0.3°	0.3°
Yaw	-	Active Heading Stabilization (AHS)	1.0°	0.8°

Position and velo	city

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Horizontal position	1σ STD		1.0 m
Vertical position	1σ STD		2.0 m
Velocity accuracy	1σ RMS		0.05 m/s

All above specifications based on typical application scenarios



MTi 100-series Development Kit: MTi, software and cabling



MTi encased: 57x42x23.5 mm, 52g, 9-pins push-pull connector



MTi OEM: 37x33x12 mm, 11g, 16-pins header



System specifications



Sensor specification

	Gyroscopes	Accelerometers
Standard full range *	+/- 450 °/s	+/- 20 g
Initial bias erro	0.2 °/s	5 mg
In-run bias stability	10 °/h	15 µg
Bandwidth (-3 dB)	415 Hz	375 Hz
Noise density	0.01 °/s/√Hz	60 µg/√Hz
g-sensitivity (calibrated)	0.003 °/s/g	N/A
Non-orthogonality	0.05 deg	0.05 deg
Non-linearity	0.01%	0.1%
	Magnetometer	Barometer
Standard full range	+/-8G	300-1100 hPa
Total RMS noise	0.5 mG	3.6 Pa
Non-linearity	0.2%	N/A
Resolution	0.25 mG	8 cm (sea level, 15 °C)

GNSS receiver

Receiver type	72-channel, 4 Hz GPS/QZSS L1 C/A, GLONASS L10F, BeiDou B1, SBAS L1 C/A: WAAS, EGNOS, MSAS	Horizontal accuracy (CEP)	2.0 m (SBAS) 2.5 m (Autonomous)
Start-up time cold start	26 s	Velocity accuracy (@30 m/s)	0.05 m/s
Tracking sensitivity	-167 dBm		

* Optional +/- 1000 °/s available on reques



ABOUT XSENS

Xsens is the leading innovator in 3D motion tracking technology and products. Its sensor fusion technologies enable a seamless interaction between the physical and the digital world in applications such as industrial control and stabilization, health, sports and 3D character animation. Clients and partners include Electronic Arts, NBC Universal, Daimler, Autodesk, ABB, Siemens and various other leading institutes and companies throughout the world. Xsens is part of mCube, the provider of the world's smallest MEMS motion sensors, key enablers for the Internet of Moving Things. Xsens has offices in Enschede, Los Angeles, Shanghai and Hong Kong.

Visit xsens.com/distributors for an overview of Xsens' worldwide distributor network



Xsens Netherlands

Xsens Technologies B.V. P.O. Box 559 7500 AN Enschede The Netherlands

Phone: +31 88 97367 00 Fax: +31 88 97367 01 Email: info@xsens.com

Xsens North America Inc

101 N. Pacific Coast Hwy, Suite 306 El Segundo, CA 90245 North America

Phone: 310-481-1800 Fax: 310-416-9044 Email: info@xsens.com

Xsens AsiaPad

Unit 208, Bldg 16W Hong Kong Science Park Shatin Hong Kong

Phone: +852 3618 9080 Fax: +852 3705 8994 Email: info@xsens.com Building 1, 2nd Floor No.333 Huangqing Road PRC 201899 Shanghai

Phone: +86 021 31760067 Fax: +86 021 31760067 Email: china@xsens.com

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