

Data Sheet July 15, 2005 FN3369.4

850MHz, Output Limiting, Low Distortion Current Feedback Operational Amplifier

The HFA1130 is a high speed wideband current feedback amplifier featuring programmable output limits. Built with Intersil's proprietary complementary bipolar UHF-1 process, it is the fastest monolithic amplifier available from any semiconductor manufacturer.

This amplifier is the ideal choice for high frequency applications requiring output limiting, especially those needing ultra fast overdrive recovery times. The output limiting function allows the designer to set the maximum positive and negative output levels, thereby protecting later stages from damage or input saturation. The sub-nanosecond overdrive recovery time quickly returns the amplifier to linear operation, following an overdrive condition.

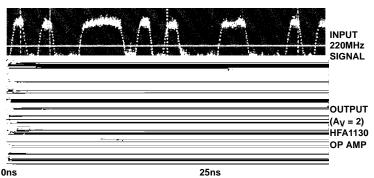
The HFA1130 offers significant performance improvements over the CLC500/501/502.

Ordering Information

PART NUMBER (BRAND)	TEMP. RANGE (°C)	PACKAGE	PKG. DWG. #
HFA1130IB (H1130I)	-40 to 85	8 Ld SOIC	M8.15
HFA1130IBZ (Note) (H1130IBZ)	-40 to 85	8 Ld SOIC (Pb-free)	M8.15
HFA1130IBZ-T (Note) (H1130IBZ)	-40 to 85	8 Ld SOIC (Pb-free)	M8.15
HFA11XXEVAL	DIP Evaluation Amps	Board for High-Speed	d Op

NOTE: Intersil Pb-free plus anneal products employ special Pb-free material sets; molding compounds/die attach materials and 100% matte tin plate termination finish, which are RoHS compliant and compatible with both SnPb and Pb-free soldering operations. Intersil Pb-free products are MSL classified at Pb-free peak reflow temperatures that meet or exceed the Pb-free requirements of IPC/JEDEC J STD-020.

The Op Amps with Fastest Edges



Features

User Programmable Output Voltage Limits
• Low Distortion (30MHz, HD2)56dBc
• -3dB Bandwidth
• Very Fast Slew Rate
• Fast Settling Time (0.1%)
 Excellent Gain Flatness (100MHz)
Overdrive Recovery

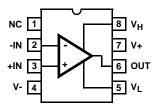
· Pb-Free Plus Anneal Available (RoHS Compliant)

Applications

- · Residue Amplifier
- · Video Switching and Routing
- · Pulse and Video Amplifiers
- · Wideband Amplifiers
- · RF/IF Signal Processing
- · Flash A/D Driver
- · Medical Imaging Systems
- · Related Literature
 - AN9420, Current Feedback Theory
 - AN9202, HFA11XX Evaluation Fixture

Pinout

HFA1130 (SOIC) TOP VIEW



Absolute Maximum Ratings T_A = 25°C

Voltage Between V+ and V 12V Input Voltage V_{SUPPLY} Differential Input Voltage 5V Output Current (50% Duty Cycle) 60mA

Thermal Information

Thermal Resistance (Typical, Note 1)	θ_{JA} (°C/W)	θ _{JC} (°C/W)
SOIC Package	170	N/A
Maximum Junction Temperature (Plastic F	ackage)	150°C
Maximum Storage Temperature Range	65°C to	T _A to 150°C
Maximum Lead Temperature (Soldering 10	0s)	300°C
(SOIC - Lead Tips Only)		

Operating Conditions

CAUTION: Stresses above those listed in "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress only rating and operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied.

NOTE:

1. θ_{JA} is measured with the component mounted on an evaluation PC board in free air.

Electrical Specifications $V_{SUPPLY} = \pm 5V$, $A_V = +1$, $R_F = 510\Omega$, $R_L = 100\Omega$, Unless Otherwise Specified

PARAMETER	TEST CONDITIONS	(NOTE 2) TEST LEVEL	TEMP. (°C)	MIN	TYP	MAX	UNITS
INPUT CHARACTERISTICS	<u>'</u>	'	1		1	'	•
Input Offset Voltage (Note 3)		Α	25	-	2	6	mV
		Α	Full	-	-	10	mV
Input Offset Voltage Drift		С	Full	-	10	-	μV/°C
V _{IO} CMRR	$\Delta V_{CM} = \pm 2V$	Α	25	40	46	-	dB
		Α	Full	38	-	-	dB
V _{IO} PSRR	$\Delta V_S = \pm 1.25V$	А	25	45	50	-	dB
		Α	Full	42	-	-	dB
Non-Inverting Input Bias Current	+IN = 0V	Α	25	-	25	40	μА
(Note 3)		Α	Full	-	-	65	μА
+I _{BIAS} Drift		С	Full	-	40	-	nA/°C
+I _{BIAS} CMS	$\Delta V_{CM} = \pm 2V$	Α	25	-	20	40	μ A /V
		Α	Full	-	-	50	μ A /V
Inverting Input Bias Current (Note 3)	-IN = 0V	А	25	-	12	50	μА
		Α	Full	-	-	60	μА
-I _{BIAS} Drift		С	Full	-	40	-	nA/°C
-I _{BIAS} CMS	$\Delta V_{CM} = \pm 2V$	Α	25	-	1	7	μ A /V
		Α	Full	-	-	10	μ A /V
-I _{BIAS} PSS	$\Delta V_S = \pm 1.25 V$	Α	25	-	6	15	μ A /V
		Α	Full	-	-	27	μ A /V
Non-Inverting Input Resistance		Α	25	25	50	-	kΩ
Inverting Input Resistance		С	25	-	20	30	Ω
Input Capacitance (Either Input)		В	25	-	2	-	pF
Input Common Mode Range		С	Full	±2.5	±3.0	-	V
Input Noise Voltage (Note 3)	100kHz	В	25	-	4	-	nV/√ Hz
+Input Noise Current (Note 3)	100kHz	В	25	-	18	-	pA/√Hz
-Input Noise Current (Note 3)	100kHz	В	25	-	21	-	pA/√ Hz
TRANSFER CHARACTERISTICS AV	= +2, Unless Otherwise	Specified	 		1	1	-1
Open Loop Transimpedance (Note 3)		В	25	-	300	-	kΩ

intersil FN3369.4 July 15, 2005 **Electrical Specifications** $V_{SUPPLY} = \pm 5V$, $A_V = +1$, $R_F = 510\Omega$, $R_L = 100\Omega$, Unless Otherwise Specified (Continued)

PARAMETER	TEST CONDITIONS	(NOTE 2) TEST LEVEL	TEMP.	MIN	TYP	MAX	UNITS
-3dB Bandwidth (Note 3)	V _{OUT} = 0.2V _{P-P} , A _V = +1	В	25	530	850	-	MHz
-3dB Bandwidth	$V_{OUT} = 0.2V_{P-P},$ $A_V = +2, R_F = 360\Omega$	В	25	-	670	-	MHz
Full Power Bandwidth	4V _{P-P} , A _V = -1	В	Full	-	300	-	MHz
Gain Flatness (Note 3)	To 100MHz	В	25	-	±0.14	-	dB
Gain Flatness	To 50MHz	В	25	-	±0.04	-	dB
Gain Flatness	To 30MHz	В	25	-	±0.01	-	dB
Linear Phase Deviation (Note 3)	DC to 100MHz	В	25	-	0.6	-	Degrees
Differential Gain	NTSC, $R_L = 75\Omega$	В	25	-	0.03	-	%
Differential Phase	NTSC, $R_L = 75\Omega$	В	25	-	0.05	-	Degrees
Minimum Stable Gain		Α	Full	1	-	-	V/V
OUTPUT CHARACTERISTICS A _V =	+2, Unless Otherwise Spec	cified			1		
Output Voltage (Note 3)	A _V = -1	Α	25	±3.0	±3.3	-	V
		Α	Full	±2.5	±3.0	-	V
Output Current	$R_L = 50\Omega, A_V = -1$	Α	25, 85	50	60	-	mA
		Α	-40	35	50	-	mA
DC Closed Loop Output Impedance (Note 3)		В	25	-	0.07	-	Ω
2nd Harmonic Distortion (Note 3)	30MHz, $V_{OUT} = 2V_{P-P}$	В	25	-	-56	-	dBc
3rd Harmonic Distortion (Note 3)	30MHz, V _{OUT} = 2V _{P-P}	В	25	-	-80	-	dBc
3rd Order Intercept (Note 3)	der Intercept (Note 3) 100MHz		25	20	30	-	dBm
1dB Compression 100MHz		В	25	15	20	-	dBm
TRANSIENT RESPONSE A _V = +2, U	Inless Otherwise Specified		-		+	+	+
Rise Time	V _{OUT} = 2.0V Step	В	25	-	900	-	ps
Overshoot (Note 3)	V _{OUT} = 2.0V Step	В	25	-	10	-	%
Slew Rate	$A_V = +1,$ $V_{OUT} = 5V_{P-P}$	В	25	-	1400	-	V/µs
	$A_V = +2$, $V_{OUT} = 5V_{P-P}$	В	25	1850	2300	-	V/µs
0.1% Settling Time (Note 3)	V _{OUT} = 2V to 0V	В	25	-	11	-	ns
0.2% Settling Time (Note 3) V _{OUT} = 2V to 0V		В	25	-	7	-	ns
POWER SUPPLY CHARACTERISTIC	S						
Supply Voltage Range		В	Full	±4.5	-	±5.5	V
Supply Current (Note 3)		Α	25	-	21	26	mA
		Α	Full	-	-	33	mA
LIMITING CHARACTERISTICS A _V =	+2, V _H = +1V, V _L = -1V, U	nless Other	wise Speci	fied	•	•	
Clamp Accuracy	$V_{1N} = \pm 2V, A_{V} = -1$	Α	25	-	60	±125	mV
Clamped Overshoot	lamped Overshoot $V_{IN} = \pm 1V$, Input $t_R/t_F = 2ns$		25	-	4	-	%
Overdrive Recovery Time	V _{IN} = ±1V	В	25	-	0.75	1.5	ns

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reaches a voltage equal to Q_{P5} 's base + $2V_{BE}$ (Q_{P5} and Q_{N5}). Thus, Q_{P5} clamps node Z whenever Z reaches V_H . R_1 provides a pull-up network to ensure functionality with the clamp inputs floating. A similar description applies to the symmetrical low clamp circuitry controlled by V_I .

When the output is clamped, the negative input continues to source a slewing current (I_{CLAMP}) in an attempt to force the output to the quiescent voltage defined by the input. Q_{P5} must sink this current while clamping, because the -IN current is always mirrored onto the high impedance node. The clamping current is calculated as (V_{-IN} - V_{OUT})/R_F. As an example, a unity gain circuit with V_{IN} = 2V, V_H = 1V, and R_F = 510 Ω would have I_{CLAMP} = (2-1)/510 Ω = 1.96mA. Note that I_{CC} will increase by I_{CLAMP} when the output is clamp limited.

Clamp Accuracy

The clamped output voltage will not be exactly equal to the voltage applied to V_H or V_I . Offset errors, mostly due to V_{RF} mismatches, necessitate a clamp accuracy parameter which is found in the device specifications. Clamp accuracy is a function of the clamping conditions. Referring again to Figure 1, it can be seen that one component of clamp accuracy is the V_{BF} mismatch between the Q_{X6} transistors, and the Q_{X5} transistors. If the transistors always ran at the same current level there would be no V_{BF} mismatch, and no contribution to the inaccuracy. The Q_{X6} transistors are biased at a constant current, but as described earlier, the current through QX5 is equivalent to I_{CLAMP}. V_{BE} increases as I_{CLAMP} increases, causing the clamped output voltage to increase as well. ICI AMP is a function of the overdrive level (V_{-IN} -V_{OUTCLAMPED}) and R_F, so clamp accuracy degrades as the overdrive increases, or as RF decreases. As an example, the specified accuracy of ± 60 mV for a 2X overdrive with R_F = 510Ω degrades to ± 220 mV for $R_F = 240\Omega$ at the same overdrive, or to ± 250 mV for a 3X overdrive with $R_F = 510\Omega$.

Consideration must also be given to the fact that the clamp voltages have an effect on amplifier linearity. The "Nonlinearity Near Clamp Voltage" curve in the data sheet illustrates the impact of several clamp levels on linearity.

Clamp Range

Unlike some competitor devices, both V_H and V_L have usable ranges that cross 0V. While V_H must be more positive than V_L , both may be positive or negative, within the range restrictions indicated in the specifications. For example, the HFA1130 could be limited to ECL output levels by setting $V_H = -0.8V$ and $V_L = -1.8V$. V_H and V_L may be connected to the same voltage (GND for instance) but the result won't be in a DC output voltage from an AC input signal. A 150 - 200mV AC signal will still be present at the output.

Recovery from Overdrive

The output voltage remains at the clamp level as long as the overdrive condition remains. When the input voltage drops below the overdrive level (V_{CLAMP}/A_{VCL}) the amplifier will

return to linear operation. A time delay, known as the Overdrive Recovery Time, is required for this resumption of linear operation. The plots of "Unclamped Performance" and "Clamped Performance" highlight the HFA1130's subnanosecond recovery time. The difference between the unclamped and clamped propagation delays is the overdrive recovery time. The appropriate propagation delays are 4.0ns for the unclamped pulse, and 4.8ns for the clamped (2X overdrive) pulse yielding an overdrive recovery time of 800ps. The measurement uses the 90% point of the output transition to ensure that linear operation has resumed. Note: The propagation delay illustrated is dominated by the fixturing. The delta shown is accurate, but the true HFA1130 propagation delay is 500ps.

Use of Die in Hybrid Applications

This amplifier is designed with compensation to negate the package parasitics that typically lead to instabilities. As a result, the use of die in hybrid applications results in overcompensated performance due to lower parasitic capacitances. Reducing R_F below the recommended values for packaged units will solve the problem. For $A_V = +2$ the recommended starting point is 300Ω , while unity gain applications should try 400Ω .

PC Board Layout

The frequency performance of this amplifier depends a great deal on the amount of care taken in designing the PC board. The use of low inductance components such as chip resistors and chip capacitors is strongly recommended, while a solid ground plane is a must!

Attention should be given to decoupling the power supplies. A large value ($10\mu F$) tantalum in parallel with a small value chip ($0.1\mu F$) capacitor works well in most cases.

Terminated microstrip signal lines are recommended at the input and output of the device. Output capacitance, such as that resulting from an improperly terminated transmission line will degrade the frequency response of the amplifier and may cause oscillations. In most cases, the oscillation can be avoided by placing a resistor in series with the output.

Care must also be taken to minimize the capacitance to ground seen by the amplifier's inverting input. The larger this capacitance, the worse the gain peaking, resulting in pulse overshoot and possible instability. To this end, it is recommended that the ground plane be removed under traces connected to pin 2, and connections to pin 2 should be kept as short as possible.

An example of a good high frequency layout is the Evaluation Board shown below.

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Evaluation Board

An evaluation board is available for the HFA1130, (Part Number HFA11XXEVAL). Please contact your local sales office for information.

Note: The SOIC version may be evaluated in the DIP board by using a SOIC-to-DIP adapter such as Aries Electronics Part Number 08-350000-10.

The layout and schematic of the board are shown here:

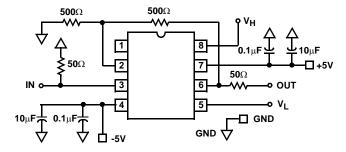
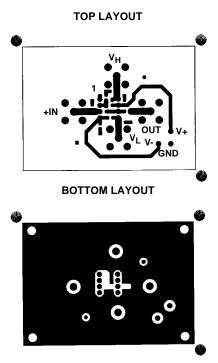


FIGURE 2. BOARD SCHEMATIC



 $\textbf{Typical Performance Curves} \quad \text{V_{SUPPLY} = ± 5V, R_F = 510Ω, T_A = 25°C, R_L = 100Ω, Unless Otherwise Specified and the support of the support of$

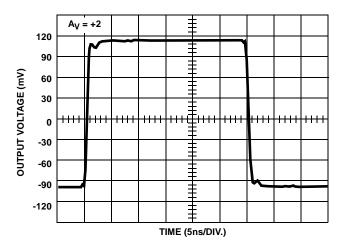


FIGURE 3. SMALL SIGNAL PULSE RESPONSE

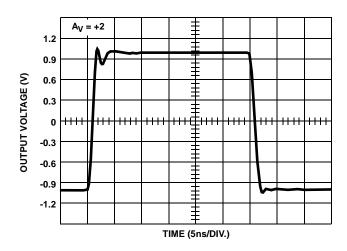


FIGURE 4. LARGE SIGNAL PULSE RESPONSE

$\textbf{\textit{Typical Performance Curves}} \quad V_{SUPPLY} = \pm 5 \text{V}, \ R_F = 510 \Omega, \ T_A = 25 ^{\circ}\text{C}, \ R_L = 100 \Omega, \ Unless \ Otherwise \ Specified \ \textbf{(Continued)}$

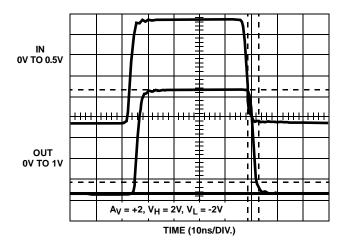
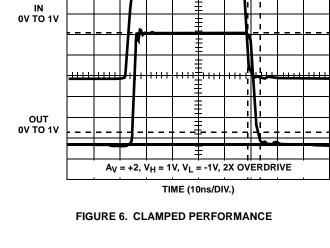


FIGURE 5. UNCLAMPED PERFORMANCE

V_{OUT} = 200mV_{P-P}

PHASE

NORMALIZED GAIN (dB)



PHASE (DEGREES)

FIGURE 7. NON-INVERTING FREQUENCY RESPONSE

FREQUENCY (MHz)

10

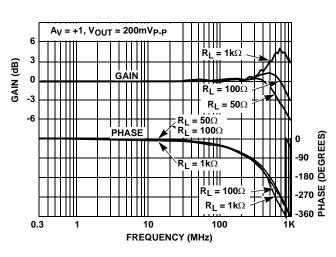


FIGURE 9. FREQUENCY RESPONSE FOR VARIOUS LOAD RESISTORS

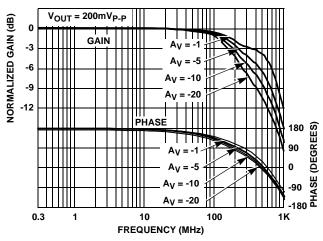


FIGURE 8. INVERTING FREQUENCY RESPONSE

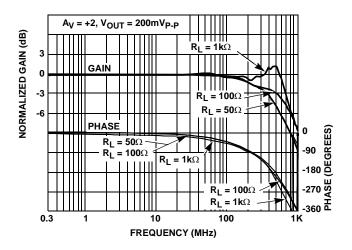


FIGURE 10. FREQUENCY RESPONSE FOR VARIOUS LOAD RESISTORS

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$\textbf{Typical Performance Curves} \ \ V_{SUPPLY} = \pm 5 V, \ R_F = 510 \Omega, \ T_A = 25 ^{\circ}C, \ R_L = 100 \Omega, \ Unless \ Otherwise \ Specified \ \textbf{(Continued)}$

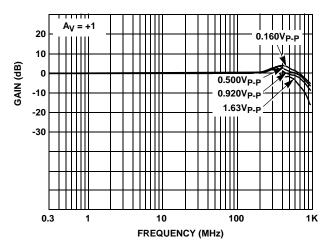


FIGURE 11. FREQUENCY RESPONSE FOR VARIOUS OUTPUT VOLTAGES

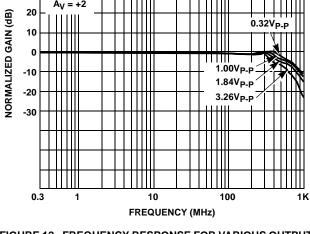


FIGURE 12. FREQUENCY RESPONSE FOR VARIOUS OUTPUT VOLTAGES

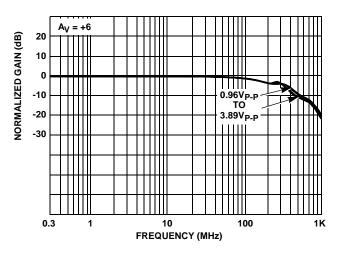


FIGURE 13. FREQUENCY RESPONSE FOR VARIOUS OUTPUT VOLTAGES

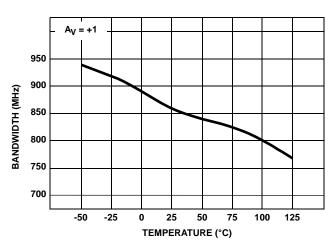


FIGURE 14. -3dB BANDWIDTH vs TEMPERATURE

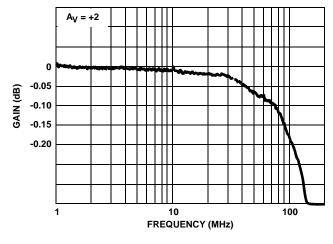


FIGURE 15. GAIN FLATNESS

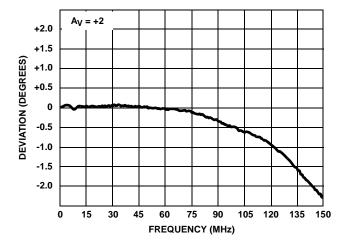


FIGURE 16. DEVIATION FROM LINEAR PHASE

$\textbf{\textit{Typical Performance Curves}} \quad V_{SUPPLY} = \pm 5 \text{V}, \ R_F = 510 \Omega, \ T_A = 25 ^{\circ}\text{C}, \ R_L = 100 \Omega, \ \text{Unless Otherwise Specified} \quad \text{\textbf{(Continued)}}$

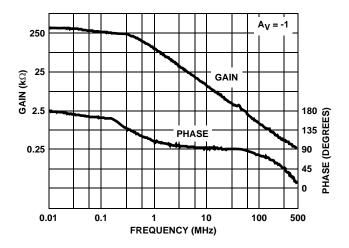


FIGURE 17. OPEN LOOP TRANSIMPEDANCE

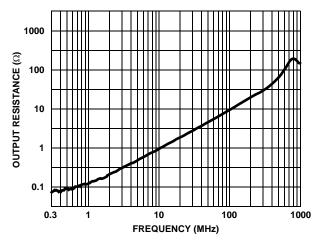


FIGURE 19. CLOSED LOOP OUTPUT RESISTANCE

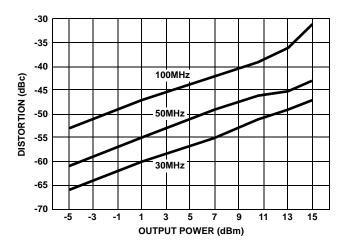


FIGURE 21. 2nd HARMONIC DISTORTION vs POUT

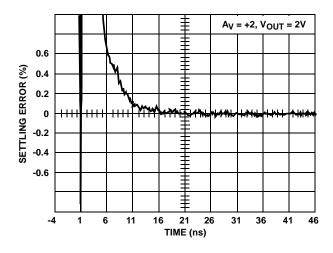


FIGURE 18. SETTLING RESPONSE

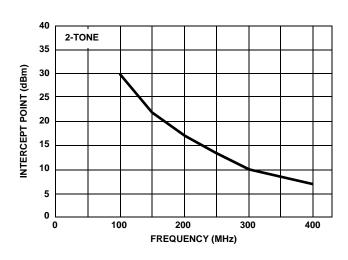


FIGURE 20. 3rd ORDER INTERMODULATION INTERCEPT

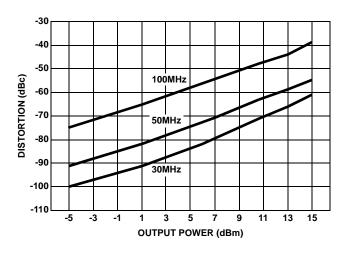


FIGURE 22. 3rd HARMONIC DISTORTION vs POUT

 $\textbf{Typical Performance Curves} \ \ V_{SUPPLY} = \pm 5 V, \ R_F = 510 \Omega, \ T_A = 25 ^{\circ}C, \ R_L = 100 \Omega, \ Unless \ Otherwise \ Specified \ \textbf{(Continued)}$

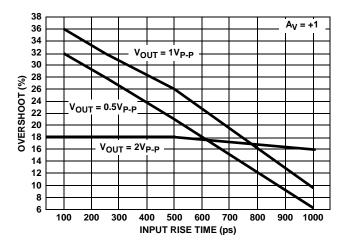


FIGURE 23. OVERSHOOT vs INPUT RISE TIME

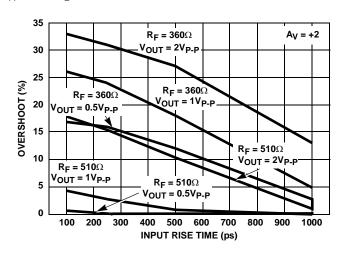


FIGURE 24. OVERSHOOT vs INPUT RISE TIME

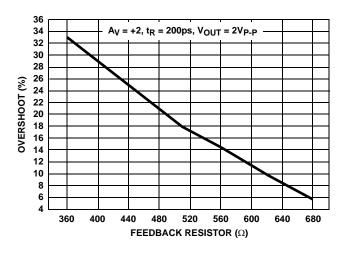


FIGURE 25. OVERSHOOT vs FEEDBACK RESISTOR

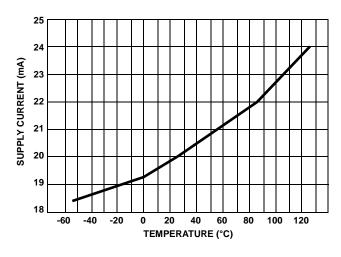


FIGURE 26. SUPPLY CURRENT vs TEMPERATURE

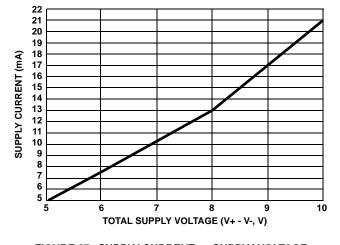


FIGURE 27. SUPPLY CURRENT vs SUPPLY VOLTAGE

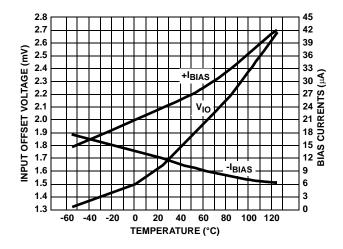
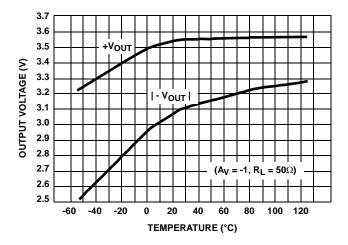


FIGURE 28. $V_{\mbox{\scriptsize IO}}$ AND BIAS CURRENTS vs TEMPERATURE

$\textbf{\textit{Typical Performance Curves}} \quad V_{SUPPLY} = \pm 5 V, \ R_F = 510 \Omega, \ T_A = 25 ^{\circ}C, \ R_L = 100 \Omega, \ Unless \ Otherwise \ Specified \ \textbf{(Continued)}$



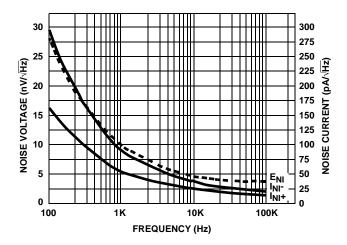


FIGURE 29. OUTPUT VOLTAGE vs TEMPERATURE

FIGURE 30. INPUT NOISE vs FREQUENCY

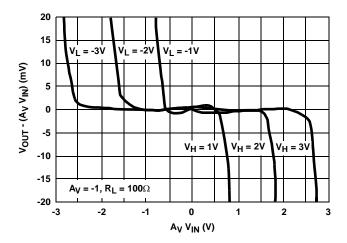


FIGURE 31. NON-LINEARITY NEAR CLAMP VOLTAGE

Die Characteristics

DIE DIMENSIONS:

63 mils x 44 mils x 19 mils $1600\mu m$ x $1130\mu m$

METALLIZATION:

Type: Metal 1: AlCu(2%)/TiW Thickness: Metal 1: 8kÅ ±0.4kÅ

Type: Metal 2: ALCu(2%)

Thickness: Metal 2: 16kÅ ±0.8kÅ

PASSIVATION:

Type: Nitride

Thickness: 4kÅ ±0.5kÅ

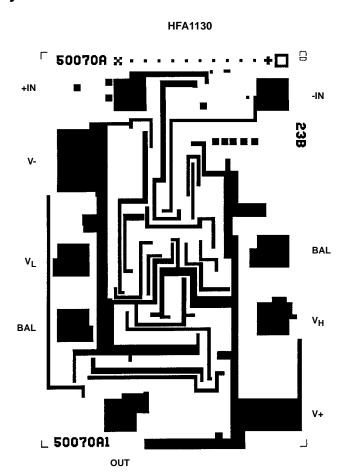
TRANSISTOR COUNT:

52

SUBSTRATE POTENTIAL (Powered Up):

Floating (Recommend Connection to V-)

Metallization Mask Layout



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