

# Product data sheet

Specifications



## Variable speed drive, Altivar Process ATV600, ATV630, 18.5kW/25 hp, 500V/690 V, IP00

ATV630D18Y6

### Main

|   |  |
|---|--|
| <b>Range of product</b>                   | Altivar Process ATV600   |
| <b>Product or component type</b>          | Variable speed drive   |
| <b>Product specific application</b>       | Process and utilities  |
| <b>Device short name</b>                  | ATV630   |
| <b>Variant</b>                            | Standard version   |
| <b>Product destination</b>                | Synchronous motors<br>Asynchronous motors  |
| <b>EMC filter</b>                         | Integrated with 25 m conforming to EN/IEC 61800-3 category C3  |
| <b>IP degree of protection</b>            | IP00 conforming to IEC 61800-5-1<br>IP00 conforming to IEC 60529<br>IP20 (with kit VW3A9705) conforming to IEC 61800-5-1<br>IP20 (with kit VW3A9705) conforming to IEC 60529 |
| <b>[Us] rated supply voltage</b>          | 500...690 V  |
| <b>Type of cooling</b>                    | Forced convection  |
| <b>Supply frequency</b>                   | 50...60 Hz - 5...5 %   |
| <b>[Us] rated supply voltage</b>          | 500...690 V - 15...10 %  |
| <b>Motor power kW</b>                     | 15 kW at 500 V (normal duty)<br>11 kW at 500 V (heavy duty)<br>18.5 kW at 690 V (normal duty)<br>15 kW at 690 V (heavy duty)   |
| <b>Motor power hp</b>                     | 20 hp at 500 V normal duty<br>15 hp at 500 V heavy duty<br>25 hp at 690 V normal duty<br>20 hp at 690 V heavy duty   |
| <b>Line current</b>                       | 23.1 A at 500 V (normal duty)<br>23 A at 690 V (normal duty)<br>18.4 A at 500 V (heavy duty)<br>19.2 A at 690 V (heavy duty)   |
| <b>Prospective line I<sub>sc</sub></b>    | 70 kA  |
| <b>Apparent power</b>                     | 27.5 kVA at 690 V (normal duty)<br>22.9 kVA at 690 V (heavy duty)  |
| <b>Continuous output current</b>          | 18 A at 4 kHz for heavy duty<br>24 A at 4 kHz for normal duty  |
| <b>Maximum transient current</b>          | 27 A during 60 s (heavy duty)<br>26.4 A during 60 s (normal duty)  |
| <b>Asynchronous motor control profile</b> | Optimized torque mode<br>Variable torque standard<br>Constant torque standard  |

|  |   |
|--|---|
| <b>Synchronous motor control profile</b> | Permanent magnet motor<br>Synchronous reluctance motor  |
| <b>Speed drive output frequency</b>      | 0.1...500 Hz  |
| <b>Nominal switching frequency</b>       | 4 kHz   |
| <b>Switching frequency</b>               | 2...8 kHz adjustable<br>4...8 kHz with derating factor  |
| <b>Safety function</b>                   | STO (safe torque off) SIL 3   |
| <b>Discrete input logic</b>              | 16 preset speeds  |
| <b>Communication port protocol</b>       | Ethernet<br>Modbus serial<br>Modbus TCP   |
| <b>Option card</b>                       | Slot A: communication module, Profibus DP V1<br>Slot A: communication module, Profinet<br>Slot A: communication module, DeviceNet<br>Slot A: communication module, Modbus TCP/EtherNet/IP<br>Slot A: communication module, CANopen daisy chain RJ45<br>Slot A: communication module, CANopen SUB-D 9<br>Slot A: communication module, CANopen screw terminals<br>Slot A/slot B: digital and analog I/O extension module<br>Slot A/slot B: output relay extension module<br>Slot A: communication module, Ethernet IP/Modbus TCP/MD-Link<br>Communication module, BACnet MS/TP<br>Communication module, Ethernet Powerlink |

## Complementary

|  |  |
|--|--|
| <b>Mounting mode</b>                       | Wall mount   |
| <b>Network number of phases</b>            | 3 phases   |
| <b>Discrete output number</b>              | 0  |
| <b>Discrete output type</b>                | Relay outputs R1A, R1B, R1C 250 V AC 3000 mA<br>Relay outputs R1A, R1B, R1C 30 V DC 3000 mA<br>Relay outputs R2A, R2C 250 V AC 5000 mA<br>Relay outputs R2A, R2C 30 V DC 5000 mA<br>Relay outputs R3A, R3C 250 V AC 5000 mA<br>Relay outputs R3A, R3C 30 V DC 5000 mA  |
| <b>Output voltage</b>                      | <= power supply voltage  |
| <b>Permissible temporary current boost</b> | 1.1 x I <sub>n</sub> during 60 s (normal duty)<br>1.5 x I <sub>n</sub> during 60 s (heavy duty)  |
| <b>Motor slip compensation</b>             | Adjustable<br>Not available in permanent magnet motor law<br>Can be suppressed<br>Automatic whatever the load  |
| <b>Acceleration and deceleration ramps</b> | Linear adjustable separately from 0.01...9999 s<br>S, U or customized  |
| <b>Physical interface</b>                  | Ethernet<br>2-wire RS 485  |
| <b>Braking to standstill</b>               | By DC injection  |
| <b>Protection type</b>                     | Thermal protection: motor<br>Safe torque off: motor<br>Motor phase break: motor<br>Thermal protection: drive<br>Safe torque off: drive<br>Overheating: drive<br>Overcurrent between output phases and earth: drive<br>Overload of output voltage: drive<br>Short-circuit protection: drive<br>Motor phase break: drive<br>Overvoltages on the DC bus: drive<br>Line supply overvoltage: drive<br>Line supply undervoltage: drive<br>Line supply phase loss: drive<br>Overspeed: drive<br>Break on the control circuit: drive |
| <b>Transmission rate</b>                   | 10, 100 Mbits<br>4800 bps, 9600 bps, 19200 bps, 38.4 Kbps  |
| <b>Frequency resolution</b>                | Display unit: 0.1 Hz<br>Analog input: 0.012/50 Hz  |

|                                  |  |
|----------------------------------|--|
| <b>Transmission frame</b>        | RTU  |
| <b>Electrical connection</b>     | Control: removable screw terminals 0.5...1.5 mm <sup>2</sup> /AWG 20...AWG 16<br>Motor: screw terminal 6...10 mm <sup>2</sup> /AWG 10...AWG 8<br>Line side: screw terminal 6...10 mm <sup>2</sup> /AWG 10...AWG 8  |
| <b>Connector type</b>            | RJ45 (on the remote graphic terminal) for Ethernet/Modbus TCP<br>RJ45 (on the remote graphic terminal) for Modbus serial   |
| <b>Data format</b>               | 8 bits, configurable odd, even or no parity  |
| <b>Type of polarization</b>      | No impedance   |
| <b>Exchange mode</b>             | Half duplex, full duplex, autonegotiation Ethernet/Modbus TCP  |
| <b>Number of addresses</b>       | 1...247 for Modbus serial  |
| <b>Method of access</b>          | Slave Modbus TCP   |
| <b>Supply</b>                    | External supply for digital inputs: 24 V DC (19...30 V), <1.25 mA, protection type: overload and short-circuit protection<br>Internal supply for reference potentiometer (1 to 10 kOhm): 10.5 V DC +/- 5 %, <10 mA, protection type: overload and short-circuit protection<br>Internal supply for digital inputs and STO: 24 V DC (21...27 V), <200 mA, protection type: overload and short-circuit protection |
| <b>Local signalling</b>          | 3 LEDs for local diagnostic<br>3 LEDs (dual colour) for embedded communication status<br>4 LEDs (dual colour) for communication module status<br>1 LED (red) for presence of voltage   |
| <b>Width</b>                     | 246 mm   |
| <b>Height</b>                    | 420 mm   |
| <b>Depth</b>                     | 242 mm   |
| <b>Net weight</b>                | 22 kg  |
| <b>Analogue input number</b>     | 3  |
| <b>Analogue input type</b>       | AI1, AI2, AI3 software-configurable voltage: 0...10 V DC, impedance: 31.5 kOhm, resolution 12 bits<br>AI1, AI2, AI3 software-configurable current: 0...20 mA, impedance: 250 Ohm, resolution 12 bits<br>AI2 voltage analog input: - 10...10 V DC, impedance: 31.5 kOhm, resolution 12 bits   |
| <b>Discrete input number</b>     | 8  |
| <b>Discrete input type</b>       | DI7, DI8 programmable as pulse input: 0...30 kHz, 24 V DC (<= 30 V)  |
| <b>Input compatibility</b>       | DI1...DI6: discrete input level 1 PLC conforming to EN/IEC 61131-2<br>DI5, DI6: discrete input level 1 PLC conforming to IEC 65A-68<br>STOA, STOB: discrete input level 1 PLC conforming to EN/IEC 61131-2   |
| <b>Discrete input logic</b>      | Positive logic (source) (DI1...DI8), < 5 V (state 0), > 11 V (state 1)<br>Negative logic (sink) (DI1...DI8), > 16 V (state 0), < 10 V (state 1)  |
| <b>Analogue output number</b>    | 2  |
| <b>Analogue output type</b>      | Software-configurable voltage AQ1, AQ2: 0...10 V DC impedance 470 Ohm, resolution 10 bits<br>Software-configurable current AQ1, AQ2: 0...20 mA, resolution 10 bits<br>Software-configurable current DQ-, DQ+: 30 V DC<br>Software-configurable current DQ-, DQ+: 100 mA  |
| <b>Sampling duration</b>         | 2 ms +/- 0.5 ms (DI1...DI4) - discrete input<br>5 ms +/- 1 ms (DI5, DI6) - discrete input<br>5 ms +/- 0.1 ms (AI1, AI2, AI3) - analog input<br>10 ms +/- 1 ms (AO1) - analog output  |
| <b>Accuracy</b>                  | +/- 0.6 % AI1, AI2, AI3 for a temperature variation 60 °C analog input<br>+/- 1 % AO1, AO2 for a temperature variation 60 °C analog output   |
| <b>Linearity error</b>           | AI1, AI2, AI3: +/- 0.15 % of maximum value for analog input<br>AO1, AO2: +/- 0.2 % for analog output   |
| <b>Relay output number</b>       | 3  |
| <b>Relay output type</b>         | Configurable relay logic R1: fault relay NO/NC electrical durability 100000 cycles<br>Configurable relay logic R2: sequence relay NO electrical durability 100000 cycles<br>Configurable relay logic R3: sequence relay NO electrical durability 100000 cycles   |
| <b>Refresh time</b>              | Relay output (R1, R2, R3): 5 ms (+/- 0.5 ms)   |
| <b>Minimum switching current</b> | Relay output R1, R2, R3: 5 mA at 24 V DC   |
| <b>Maximum switching current</b> | Relay output R1, R2, R3 on resistive load, cos phi = 1: 3 A at 250 V AC<br>Relay output R1, R2, R3 on resistive load, cos phi = 1: 3 A at 30 V DC<br>Relay output R1, R2, R3 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC<br>Relay output R1, R2, R3 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC   |

|                                 |                                     |
|---------------------------------|-------------------------------------|
| <b>Isolation</b>                | Between power and control terminals |
| <b>Maximum output frequency</b> | 500 kHz                             |
| <b>Maximum input current</b>    | 23.1 A                              |
| <b>Quantity per set</b>         | 1                                   |
| <b>Enclosure mounting</b>       | Wall mounted                        |

## Environment


|  |  |
|--|--|
| <b>Insulation resistance</b>                 | > 1 MOhm 500 V DC for 1 minute to earth  |
| <b>Noise level</b>                           | 52 dB conforming to 86/188/EEC   |
| <b>Power dissipation in W</b>                | Natural convection: 124 W at 500 V, switching frequency 4 kHz<br>Forced convection: 376 W at 500 V, switching frequency 4 kHz  |
| <b>Volume of cooling air</b>                 | 330 m <sup>3</sup> /h  |
| <b>Operating position</b>                    | Vertical +/- 10 degree   |
| <b>Maximum THDI</b>                          | <48 % with external line choke conforming to IEC 61000-3-12  |
| <b>Electromagnetic compatibility</b>         | Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2<br>Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3<br>Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4<br>1.2/50 $\mu$ s - 8/20 $\mu$ s surge immunity test level 3 conforming to IEC 61000-4-5<br>Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6 |
| <b>Pollution degree</b>                      | 2 conforming to EN/IEC 61800-5-1   |
| <b>Vibration resistance</b>                  | 1.5 mm peak to peak (f= 2...13 Hz) conforming to IEC 60068-2-6<br>1 gn (f= 13...200 Hz) conforming to IEC 60068-2-6  |
| <b>Shock resistance</b>                      | 15 gn for 11 ms conforming to IEC 60068-2-27   |
| <b>Relative humidity</b>                     | 5...95 % without condensation conforming to IEC 60068-2-3  |
| <b>Ambient air temperature for operation</b> | -15...50 °C (without derating)<br>50...60 °C (with derating factor)  |
| <b>Ambient air temperature for storage</b>   | -40...70 °C  |
| <b>Operating altitude</b>                    | <= 1000 m without derating<br>1000...4800 m with current derating 1 % per 100 m  |
| <b>Standards</b>                             | UL 508C<br>EN/IEC 61800-3<br>Environment 2 category C3 EN/IEC 61800-3<br>EN/IEC 61800-5-1<br>IEC 61000-3-12<br>IEC 60721-3<br>IEC 61508<br>IEC 13849-1   |
| <b>Product certifications</b>                | CSA<br>UL<br>TÜV   |
| <b>Marking</b>                               | CE   |
| <b>Standards</b>                             | UL 508C<br>EN/IEC 61800-3<br>EN/IEC 61800-3 environment 2 category C3<br>EN/IEC 61800-5-1<br>IEC 61000-3-12<br>IEC 60721-3<br>IEC 61508<br>IEC 13849-1   |
| <b>Overvoltage category</b>                  | III  |
| <b>Regulation loop</b>                       | Adjustable PID regulator   |
| <b>Noise level</b>                           | 58 dB  |
| <b>Pollution degree</b>                      | 2  |

## Packing Units

|                               |     |
|-------------------------------|-----|
| <b>Unit Type of Package 1</b> | PCE |
|-------------------------------|-----|

|                                     |         |
|-------------------------------------|---------|
| <b>Number of Units in Package 1</b> | 1       |
| <b>Package 1 Weight</b>             | 21 kg   |
| <b>Package 1 Height</b>             | 24.2 cm |
| <b>Package 1 width</b>              | 24.6 cm |
| <b>Package 1 Length</b>             | 42 cm   |

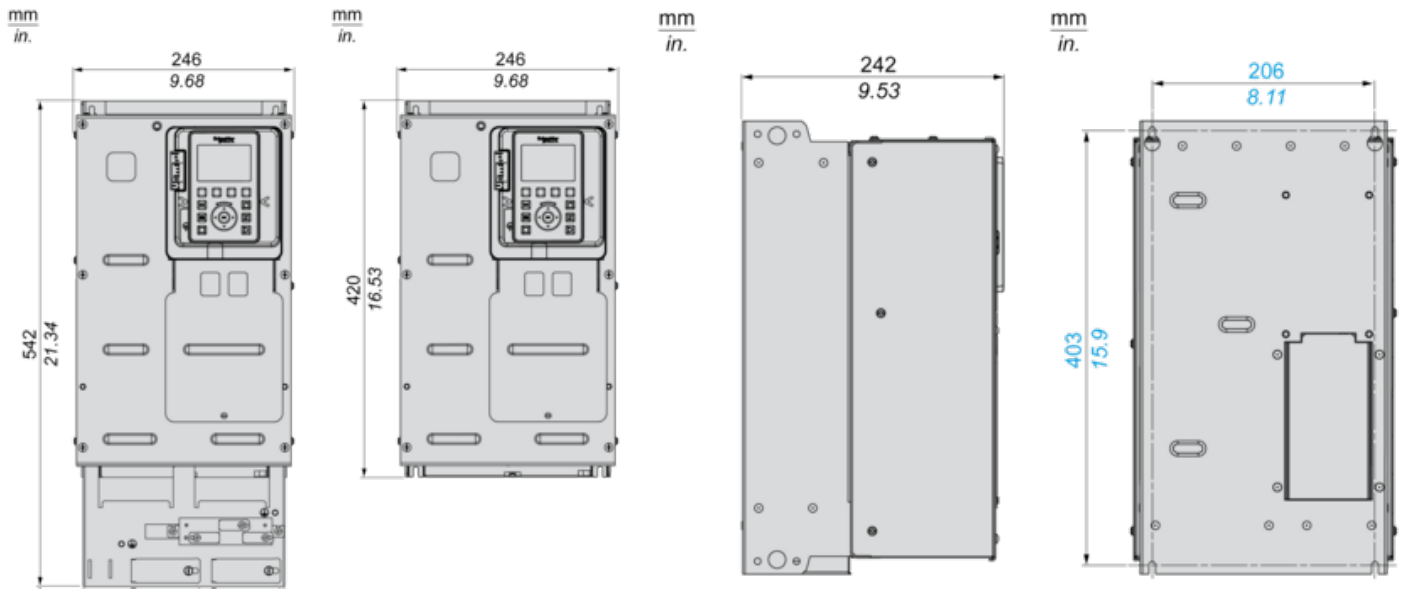
## Offer Sustainability

|                                   |   |
|-----------------------------------|---|
| <b>Sustainable offer status</b>   | Green Premium product   |
| <b>REACH Regulation</b>           | <a href="#">REACH Declaration</a>   |
| <b>EU RoHS Directive</b>          | Pro-active compliance (Product out of EU RoHS legal scope)<br><a href="#">EU RoHS Declaration</a>   |
| <b>Mercury free</b>               | Yes   |
| <b>RoHS exemption information</b> | <a href="#">Yes</a>   |
| <b>China RoHS Regulation</b>      | <a href="#">China RoHS declaration</a>  |
| <b>Environmental Disclosure</b>   | <a href="#">Product Environmental Profile</a>   |
| <b>Circularity Profile</b>        | <a href="#">End of Life Information</a>   |
| <b>WEEE</b>                       | The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins   |
| <b>California proposition 65</b>  | WARNING: This product can expose you to chemicals including: Lead and lead compounds, which is known to the State of California to cause cancer and birth defects or other reproductive harm. For more information go to <a href="http://www.P65Warnings.ca.gov">www.P65Warnings.ca.gov</a> |
| <b>Upgradeability</b>             | <a href="#">Upgraded components available</a>    |

**Dimensions**

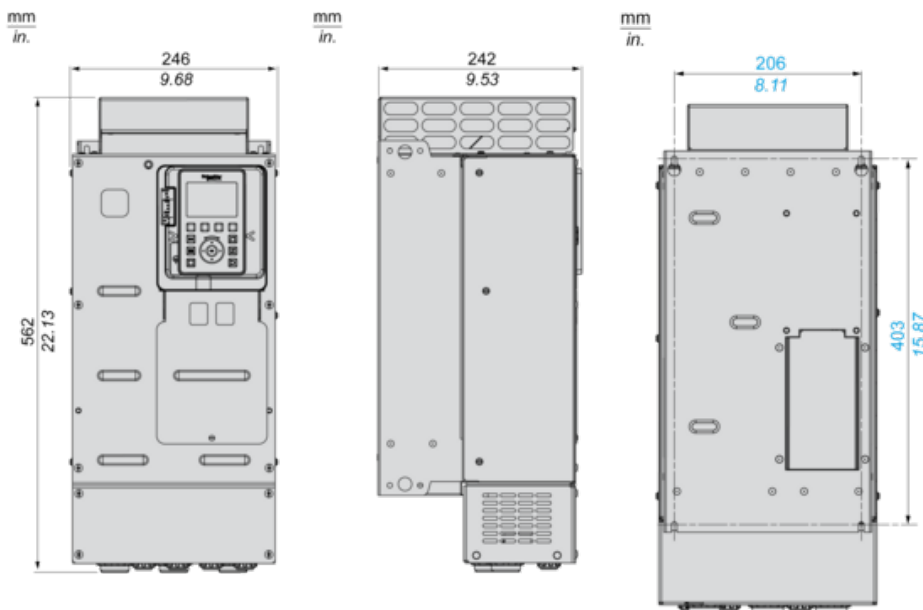
**Drives without Top Cover**

Front View with EMC Plate, Front, Left and Rear Views without EMC Plate



**Drives with IP20 Top Cover**

Front, Left and Rear Views



**Clearances**



| X1                  | X2                  | X3                 |
|---------------------|---------------------|--------------------|
| ≥ 100 mm (3.94 in.) | ≥ 100 mm (3.94 in.) | ≥ 10 mm (0.39 in.) |

**Mounting Types**

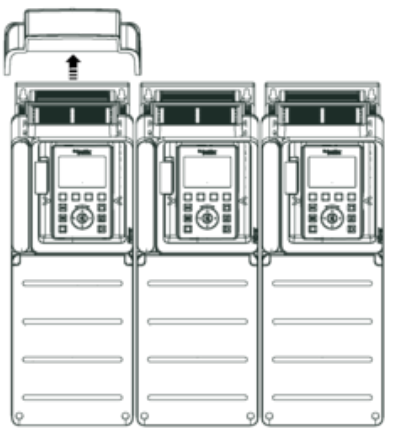
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**Mounting Type A: Individual IP21**

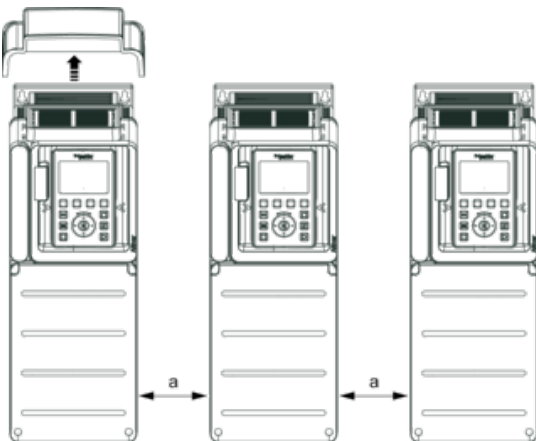


$a \geq 0$

**Mounting Type B: Side by Side IP20**



**Mounting Type C: Individual IP20**



$a \geq 0$



**Three-Phase Power Supply with Upstream Breaking via Line Contactor**

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1



(1) Line choke if used

(2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.

A1 : Drive

KM1 : Line Contactor

Q2, Q3 : Circuit breakers

S1, S2 : Pushbuttons

T1 : Transformer for control part

**Three-Phase Power Supply with Downstream Breaking via Contactor**

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1



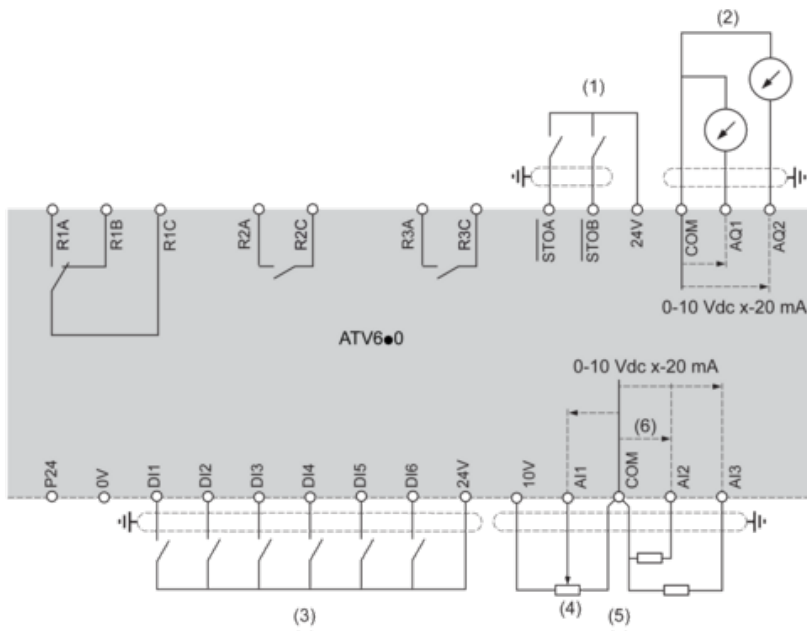
(1) Line choke if used

(2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.

A1 : Drive

KM1 : Contactor

**Control Block Wiring Diagram**



- (1) Safe Torque Off
  - (2) Analog Output
  - (3) Digital Input
  - (4) Reference potentiometer
  - (5) Analog Input
- R1A, R1B, R1C** : Fault relay  
**R2A, R2C** : Sequence relay  
**R3A, R3C** : Sequence relay

**Sensor Connection**

It is possible to connect either 1 or 3 sensors on terminals AI2 or AI3.

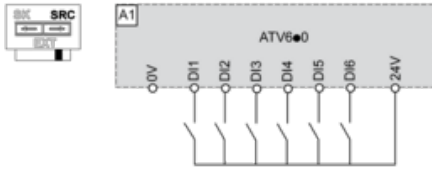


## Sink / Source Switch Configuration

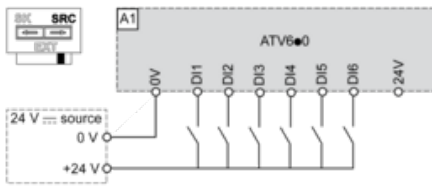
The switch is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs.

- Set the switch to Source (factory setting) if using PLC outputs with PNP transistors.
- Set the switch to Ext if using PLC outputs with NPN transistors.

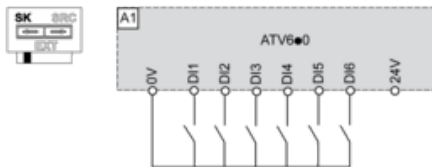
### Switch Set to SRC (Source) Position Using the Output Power Supply for the Digital Inputs



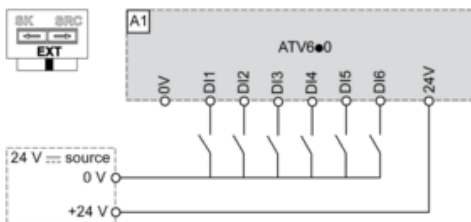
### Switch Set to SRC (Source) Position and Use of an External Power Supply for the DIs



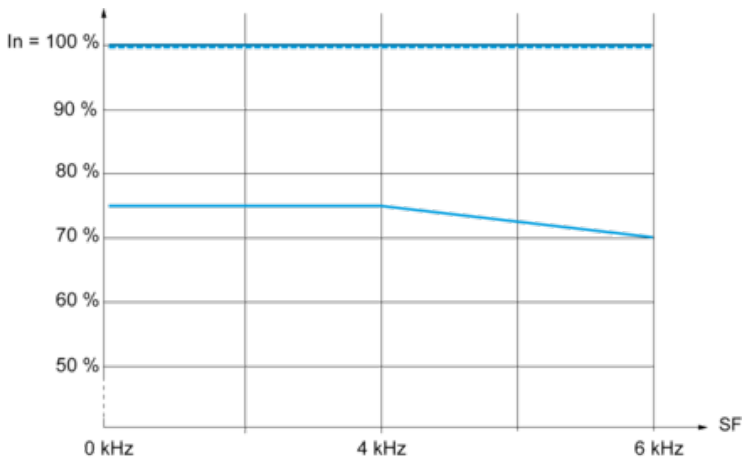
### Switch Set to SK (Sink) Position Using the Output Power Supply for the Digital Inputs



### Switch Set to EXT Position Using an External Power Supply for the DIs



Derating Curves



- 40 °C (104 °F) - Mounting type A, B and C
- - - 50 °C (122 °F) - Mounting type A, B and C
- 60 °C (140 °F) - Mounting type B and C

In : Nominal Drive Current

SF : Switching Frequency