⋗

Converters

March 2002

8085, Z80 $^{\ensuremath{\text{e}}}$, and other popular microprocessors. A deposited silicon-chromium R-2R resistor ladder network divides the reference current and provides the circuit with excellent temperature tracking characteristics (0.05% of Full Scale Range maximum linearity error over temperature). The cir-

cuit uses CMOS current switches and control logic to achieve low power consumption and low output leakage current errors. Special circuitry provides TTL logic input voltage level compatibility.

The DAC0830 is an advanced CMOS/Si-Cr 8-bit multiplying

DAC designed to interface directly with the 8080, 8048,

Double buffering allows these DACs to output a voltage corresponding to one digital word while holding the next digital word. This permits the simultaneous updating of any number of DACs.

The DAC0830 series are the 8-bit members of a family of microprocessor-compatible DACs (MICRO-DAC™).

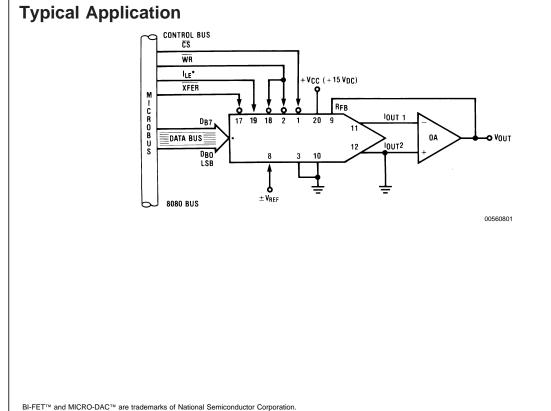
Features

8-Bit µP Compatible, Double-Buffered D to A Converters

- Double-buffered, single-buffered or flow-through digital data inputs
- Easy interchange and pin-compatible with 12-bit DAC1230 series
- Direct interface to all popular microprocessors
- Linearity specified with zero and full scale adjust only-NOT BEST STRAIGHT LINE FIT.
- Works with ±10V reference-full 4-guadrant multiplication
- Can be used in the voltage switching mode
- Logic inputs which meet TTL voltage level specs (1.4V logic threshold)
- Operates "STAND ALONE" (without µP) if desired
- Available in 20-pin small-outline or molded chip carrier package

Key Specifications

- Current settling time: 1 µs
- Resolution: 8 bits
- Linearity: 8, 9, or 10 bits (guaranteed over temp.)
- Gain Tempco: 0.0002% FS/°C
- Low power dissipation: 20 mW
- Single power supply: 5 to 15 V_{DC}

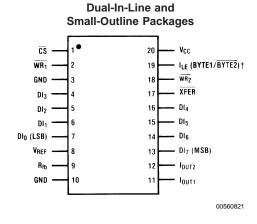


Z80® is a registered trademark of Zilog Corporation

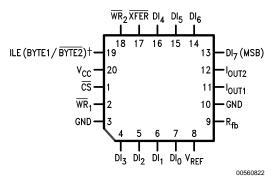
DAC0830/DAC0832

General Description

Connection Diagrams (Top Views)



Molded Chip Carrier Package



www.national.com

Absolute	Maximum	Ratings	(Notes	1,
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2)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

Supply Voltage (V _{CC})	$17 V_{DC}$
Voltage at Any Digital Input	$V_{\rm CC}$ to GND
Voltage at V _{REF} Input	±25V
Storage Temperature Range	–65°C to +150°C
Package Dissipation	
at T _A =25°C (Note 3)	500 mW
DC Voltage Applied to	
I _{OUT1} or I _{OUT2} (Note 4)	–100 mV to $V_{\rm CC}$
ESD Susceptability (Note 4)	800V
Lead Temperature (Soldering, 10 sec.)	

Dual-In-Line Package (plastic)	260°C
Dual-In-Line Package (ceramic)	300°C
Surface Mount Package	
Vapor Phase (60 sec.)	215°C
Infrared (15 sec.)	220°C

Operating Conditions

Temperature Range	T _{MIN} ≤T _A ≤T _{MAX}
Part numbers with "LCN" suffix	0°C to +70°C
Part numbers with "LCWM" suffix	0°C to +70°C
Part numbers with "LCV" suffix	0°C to +70°C
Part numbers with "LCJ" suffix	–40°C to +85°C
Part numbers with "LJ" suffix	–55°C to +125°C
Voltage at Any Digital Input	V _{CC} to GND

Electrical Characteristics

 V_{REF} =10.000 V_{DC} unless otherwise noted. Boldface limits apply over temperature, $T_{MIN} \le T_A \le T_{MAX}$. For all other limits T_A =25°C.

Parameter	Conditions	See	V_{CC} = 4.75 V_{DC} V_{CC} = 15.75 V_{DC}		$V_{CC} = 5 V_{DC} \pm 5\%$ $V_{CC} = 12 V_{DC} \pm 5\%$ to 15 V _{DC} ±5%	Limit
		Note	Typ (Note 12)	Tested Limit (Note 5)	Design Limit (Note 6)	Units
CONVERTER CHARACT	ERISTICS					
Resolution			8	8	8	bits
Linearity Error Max	Zero and full scale adjusted −10V≤V _{REF} ≤+10V	4, 8				
DAC0830LJ & LCJ				0.05	0.05	% FSR
DAC0832LJ & LCJ				0.2	0.2	% FSR
DAC0830LCN, LCWM & LCV				0.05	0.05	% FSR
DAC0831LCN				0.1	0.1	% FSR
DAC0832LCN, LCWM & LCV				0.2	0.2	% FSR
Differential Nonlinearity Max	Zero and full scale adjusted −10V≤V _{REF} ≤+10V	4, 8				
DAC0830LJ & LCJ				0.1	0.1	% FSR
DAC0832LJ & LCJ				0.4	0.4	% FSR
DAC0830LCN, LCWM & LCV				0.1	0.1	% FSR
DAC0831LCN				0.2	0.2	% FSR
DAC0832LCN, LCWM & LCV				0.4	0.4	% FSR
Monotonicity	-10V≤V _{REF} LJ & LCJ ≤+10V LCN, LCWM & LCV	4		8 8	8 8	bits bits
Gain Error Max	Using Internal R _{fb} −10V≤V _{REF} ≤+10V	7	±0.2	±1	±1	% FS
Gain Error Tempco Max	Using internal R _{fb}		0.0002		0.0006	%

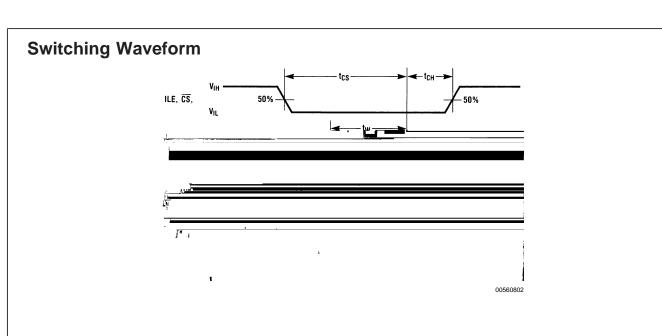
Electrical Characteristics (Continued) V_{REF} =10.000 V_{DC} unless otherwise noted. Boldface limits apply over temperature, $T_{MIN} \le T_A \le T_{MAX}$. For all other limits $T_A = 25$ °C.

Parameter		Conditions		See Note -	V _{CC} = 4 V _{CC} = 15		$V_{CC} = 5 V_{DC} \pm 5\%$ $V_{CC} = 12 V_{DC}$ $\pm 5\%$ to 15 $V_{DC} \pm 5\%$	Limit
			Typ (Note 12)		Tested Limit (Note 5)	Design Limit (Note 6)	Units	
CONVERTER O	HARACI	TERISTICS					1	
Power Supply F	Poinction	All digital ipp	uts latched high					FS/°C
Fower Supply F	ejection	$V_{\rm CC}$ =14.5V to	-		0.0002	0.0025		%
		11.5V to			0.0002	0.0025		FSR/V
		4.5V to			0.0008	0.015		FSK/V
Reference	Мах	4.5 % 10	5.57		15	20	20	kΩ
Input	Min				15	10	10	kΩ
Output Feedthro		V _{REF} =20 Vp-	n f_100 k∐ z		15	10	10	K32
Error	Jugn	All data input			3			mVp-p
Output	I _{OUT1}	All data input		10		100	100	nA
Leakage	10011		LCN, LCWM &	10		50	100	10.0
Current Max			LCV			00		
	I _{OUT2}	All data input				100	100	nA
	10012	latched high	LCN, LCWM &			50	100	
		l	LCV					
Output	I _{OUT1}	All data input	S		45			pF
Capacitance	I _{OUT2}	latched low			115			-
·	I _{OUT1}	All data input	S		130			pF
	I _{OUT2}	latched			30			-
		high						
DIGITAL AND I		ACTERISTICS						
Digital Input	Max	Logic Low	LJ: 4.75V			0.6		
Voltages			LJ: 15.75V			0.8		
			LCJ: 4.75V			0.7		V_{DC}
			LCJ: 15.75V			0.8		
			LCN, LCWM, LCV			0.95	0.8	
	Min	Logic High	LJ & LCJ			2.0	2.0	V _{DC}
			LCN, LCWM, LCV			1.9	2.0	-
Digital Input	Max	Digital inputs	<0.8V					
Currents			LJ & LCJ		-50	-200	-200	μΑ
			LCN, LCWM, LCV			-160	-200	μA
		Digital inputs	>2.0V					
			LJ & LCJ		0.1	+10	+10	μA
			LCN, LCWM, LCV			+8	+10	
Supply Current	Max		LJ & LCJ		1.2	3.5	3.5	mA
Drain			LCN, LCWM, LCV			1.7	2.0	

Electrical Characteristics

 $V_{\text{REF}}{=}10.000~V_{\text{DC}}$





Definition of Package Pinouts

Control Signals

(All control signals level actuated)

- $\overline{\text{CS:}} \qquad \text{Chip Select (active low). The } \overline{\text{CS}} \text{ in combination} \\ \text{with ILE will enable } \overline{\text{WR}}_1.$
- ILE: Input Latch Enable (active high). The ILE in combination with \overline{CS} enables \overline{WR}_1 .
- \overline{WR}_1 : Write 1. The active low \overline{WR}_1 is used to load the digital input data bits (DI) into the input latch. The data in the input latch is latched when \overline{WR}_1 is high. To update the input latch- \overline{CS} and \overline{WR}_1 must be low while ILE is high.
- WR₂: Write 2 (active low). This signal, in combination with XFER, causes the 8-bit data which is available in the input latch to transfer to the DAC register.
- **XFER:** Transfer control signal (active low). The \overline{XFER} will enable \overline{WR}_2 .

Other Pin Functions

- DI_0 - DI_7 : Digital Inputs. DI_0 is the least significant bit (LSB) and DI_7 is the most significant bit (MSB).
- **I**_{OUT1}: **DAC Current Output 1.** I_{OUT1} is a maximum for a digital code of all 1's in the DAC register, and is zero for all 0's in DAC register.
- R_{fb}: Feedback Resistor. The feedback resistor is provided on the IC chip for use as the shunt feedback

Linearity Error

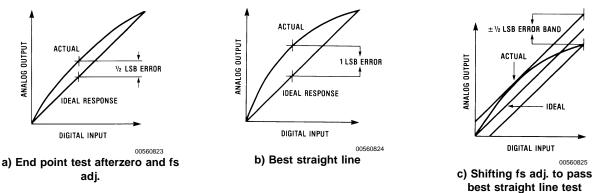
resistor for the external op amp which is used to provide an output voltage for the DAC. This on-chip resistor should always be used (not an external resistor) since it matches the resistors which are used in the on-chip R-2R ladder and tracks these resistors over temperature.

- V_{REF}: Reference Voltage Input. This input connects an external precision voltage source to the internal R-2R ladder. V_{REF} can be selected over the range of +10 to –10V. This is also the analog voltage input for a 4-quadrant multiplying DAC application.
- $$\label{eq:Vcc:Digital Supply Voltage} \begin{split} \textbf{V_{cc}:} \quad & \textbf{Digital Supply Voltage}. \ \text{This is the power supply} \\ & \text{pin for the part. } V_{CC} \ \text{can be from +5 to +15V}_{DC}. \\ & \text{Operation is optimum for +15V}_{DC} \end{split}$$
- **GND:** The pin 10 voltage must be at the same ground potential as I_{OUT1} and I_{OUT2} for current switching applications. Any difference of potential (V_{OS} pin 10) will result in a linearity change of



For example, if V_{REF} = 10V and pin 10 is 9mV offset from I_{OUT1} and I_{OUT2} the linearity change will be 0.03%.

Pin 3 can be offset ±100mV with no linearity change, but the logic input threshold will shift.



Definition of Terms

Resolution: Resolution is directly related to the number of switches or bits within the DAC. For example, the DAC0830 has 2^8 or 256 steps and therefore has 8-bit resolution.

Linearity Error: Linearity Error is the maximum deviation from a *straight line passing through the endpoints of the DAC transfer characteristic.* It is measured after adjusting for zero and full-scale. Linearity error is a parameter intrinsic to the device and cannot be externally adjusted.

National's linearity "end point test" (a) and the "best straight line" test (b,c) used by other suppliers are illustrated above. The "end point test" greatly simplifies the adjustment procedure by eliminating the need for multiple iterations of checking the linearity and then adjusting full scale until the linearity is met. The "end point test" guarantees that linearity is met after a single full scale adjust. (One adjustment vs. multiple iterations of the adjustment.) The "end point test" uses a standard zero and F.S. adjustment procedure and is a much more stringent test for DAC linearity.

Power Supply Sensitivity: Power supply sensitivity is a measure of the effect of power supply changes on the DAC full-scale output.

Settling Time: Settling time is the time required from a code transition until the DAC output reaches within $\pm \frac{1}{2}$ LSB of the final output value. Full-scale settling time requires a zero to full-scale or full-scale to zero output change.

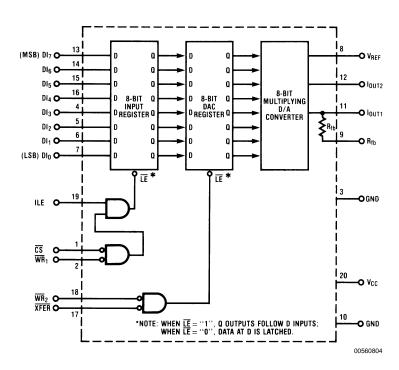
Full Scale Error: Full scale error is a measure of the output error between an ideal DAC and the actual device output.

Definition of Terms (Continued)

Ideally, for the DAC0830 series, full scale is V_{REF} –1LSB. For V_{REF} = 10V and unipolar operation, $V_{FULL-SCALE}$ = 10,0000V–39mV 9.961V. Full-scale error is adjustable to zero.

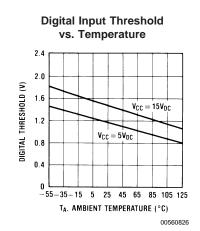
Differential Nonlinearity: The difference between any two consecutive codes in the transfer curve from the theoretical 1 LSB to differential nonlinearity.

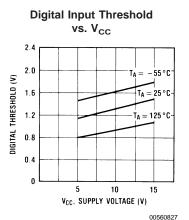
Monotonic: If the output of a DAC increases for increasing digital input code, then the DAC is monotonic. An 8-bit DAC which is monotonic to 8 bits simply means that increasing digital input codes will produce an increasing analog output.



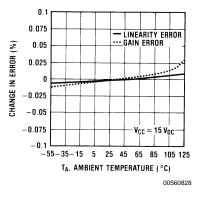


Typical Performance Characteristics

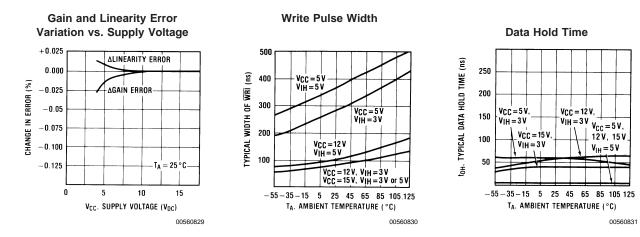




Gain and Linearity Error Variation vs. Temperature

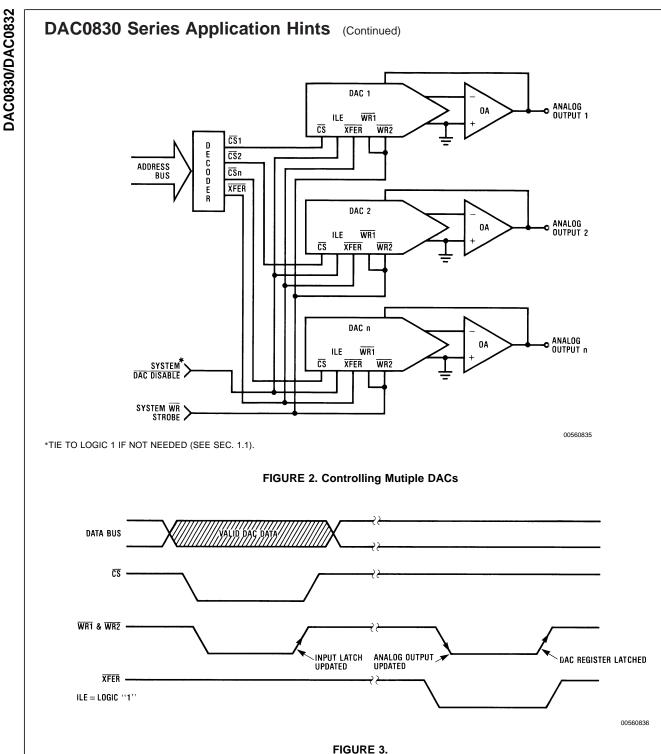


Typical Performance Characteristics (Continued)



DAC0830 Series Application Hints

These DAC's are the industry's first microprocessor compatible, double-buffered 8-bit multiplying D to A converters. Double-buffering allows the utmost application flexibility from



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The ILE pin is an active high chip select which can be decoded from the address bus as a qualifier for the normal \overline{CS} signal generated during a write operation. This can be used to provide a higher degree of decoding unique control signals for a particular DAC, and thereby create a more efficient addressing scheme.

Another useful application of the ILE pin of each DAC in a multiple DAC system is to tie these inputs together and use this as a control line that can effectively "freeze" the outputs of all the DAC's at their present value. Pulling this line low latches the input register and prevents new data from being written to the DAC. This can be particularly useful in multiprocessing systems to allow a processor other than the one controlling the DAC's to take over control of the data bus and control lines. If this second system were to use the same addresses as those decoded for DAC control (but for a different purpose) the ILE function would prevent the DAC's from being erroneously altered.

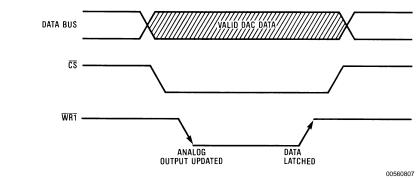
In a "Stand-Alone" system the control signals are generated by discrete logic. In this case double-buffering can be controlled by simply taking \overline{CS} and \overline{XFER} to a logic "0", ILE to a logic "1" and pulling \overline{WR}_1 low to load data to the input latch.

DAC0830/DAC0832

DAC0830 Series Application Hints

(Continued)

Pulling $\overline{\rm WR}_2$ low will then update the analog output. A logic "1" on either of these lines will prevent the changing of the analog output.



ILE=LOGIC "1"; WR2 and XFER GROUNDED

FIGURE 4.

1.2 Single-Buffered Operation

In a microprocessor controlled system where maximum data throughput to the DAC is of primary concern, or when only one DAC of several needs to be updated at a time, a single-buffered configuration can be used. One of the two internal registers allows the data to flow through and the other register will serve as the data latch.

Digital signal feedthrough (see Section 1.5) is minimized if the input register is used as the data latch. Timing for this mode is shown in *Figure 4*.

Single-buffering in a "stand-alone" system is achieved by strobing \overline{WR}_1 low to update the DAC with $\overline{CS}, \overline{WR}_2$ and \overline{XFER} grounded and ILE tied high.

1.3 Flow-Through Operation

Though primarily designed to provide microprocessor interface compatibility, the MICRO-DAC's can easily be configured to allow the analog output to continuously reflect the state of an applied digital input. This is most useful in applications where the DAC is used in a continuous feedback control loop and is driven by a binary up-down counter, or in function generation circuits where a ROM is continuously providing DAC data.

Simply grounding \overline{CS} , \overline{WR}_1 , \overline{WR}_2 , and \overline{XFER} and tying ILE high allows both internal registers to follow the applied digital inputs (flow-through) and directly affect the DAC analog output.

1.4 Control Signal Timing

When interfacing these MICRO-DAC to any microprocessor, there are two important time relationships that must be considered to insure proper operation. The first is the minimum WR strobe pulse width which is specified as 900 ns for all valid operating conditions of supply voltage and ambient temperature, but typically a pulse width of only 180ns is adequate if V_{CC} =15 V_{DC} . A second consideration is that the guaranteed minimum data hold time of 50ns should be met

or erroneous data can be latched. This hold time is defined as the length of time data must be held valid on the digital inputs *after* a qualified (via \overline{CS}) \overline{WR} strobe makes a low to high transition to latch the applied data.

If the controlling device or system does not inherently meet these timing specs the DAC can be treated as a slow memory or peripheral and utilize a technique to extend the write strobe. A simple extension of the write time, by adding a wait state, can simultaneously hold the write strobe active and data valid on the bus to satisfy the minimum \overline{WR} pulsewidth. If this does not provide a sufficient data hold time at the end of the write cycle, a negative edge triggered one-shot can be included between the system write strobe and the \overline{WR} pin of the DAC. This is illustrated in *Figure 5* for an exemplary system which provides a 250ns \overline{WR} strobe time with a data hold time of less than 10ns.

The proper data set-up time prior to the latching edge (LO to HI transition) of the \overline{WR} strobe, is insured if the \overline{WR} pulsewidth is within spec and the data is valid on the bus for the duration of the DAC \overline{WR} strobe.

1.5 Digital Signal Feedthrough

When data is latched in the internal registers, but the digital inputs are changing state, a narrow spike of current may flow out of the current output terminals. This spike is caused by the rapid switching of internal logic gates that are responding to the input changes.

There are several recommendations to minimize this effect. When latching data in the DAC, always use the input register as the latch. Second, reducing the V_{CC} supply for the DAC from +15V to +5V offers a factor of 5 improvement in the magnitude of the feedthrough, but at the expense of internal logic switching speed. Finally, increasing C_C (*Figure 8*) to a value consistent with the actual circuit bandwidth requirements can provide a substantial damping effect on any output spikes.

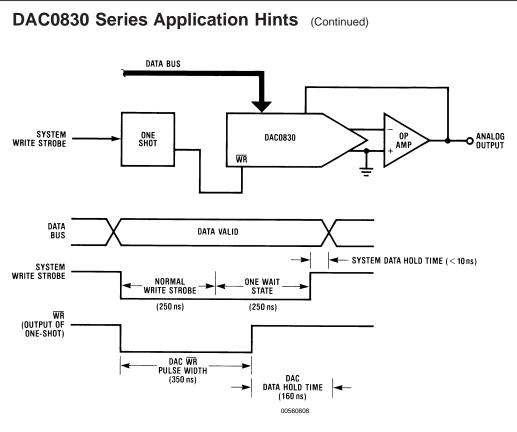


FIGURE 5. Accommodating a High Speed System

2.0 ANALOG CONSIDERATIONS

The fundamental purpose of any D to A converter is to provide an accurate analog output quantity which is representative of the applied digital word. In the case of the DAC0830, the output, I_{OUT1} , is a current directly proportional to the product of the applied reference voltage and the digital input word. For application versatility, a second output, I_{OUT2} , is provided as a current directly proportional to the complement of the digital input. Basically:

$$I_{OUT1} = \frac{V_{REF}}{15 \text{ k}\Omega} \times \frac{\text{Digital Input}}{256};$$
$$I_{OUT2} = \frac{V_{REF}}{15 \text{ k}\Omega} \times \frac{255 - \text{Digital Input}}{256}$$

where the digital input is the decimal (base 10) equivalent of the applied 8-bit binary word (0 to 255), V_{REF} is the voltage at pin 8 and 15 k Ω is the nominal value of the internal resistance, R, of the R-2R ladder network (discussed in Section 2.1).

Several factors external to the DAC itself must be considered to maintain analog accuracy and are covered in subsequent sections.

2.1 The Current Switching R-2R Ladder

The analog circuitry, *Figure 6*, consists of a silicon-chromium (SiCr or Si-chrome) thin film R-2R ladder which is deposited on the surface oxide of the monolithic chip. As a result, there are no parasitic diode problems with the ladder (as there may be with diffused resistors) so the reference voltage, V_{REF} , can range –10V to +10V even if V_{CC} for the device is $5V_{DC}$.

The digital input code to the DAC simply controls the position of the SPDT current switches and steers the available ladder current to either I_{OUT1} or I_{OUT2} as determined by the logic input level ("1" or "0") respectively, as shown in *Figure 6*. The MOS switches operate in the current mode with a small voltage drop across them and can therefore switch currents of either polarity. This is the basis for the 4-quadrant multiplying feature of this DAC.

2.2 Basic Unipolar Output Voltage

To maintain linearity of output current with changes in the applied digital code, it is important that the voltages at both of the current output pins be as near ground potential ($0V_{DC}$) as possible. With V_{REF} =+10V every millivolt appearing at either I_{OUT1} or I_{OUT2} will cause a 0.01% linearity error. In most applications this output current is converted to a voltage by using an op amp as shown in *Figure 7*.

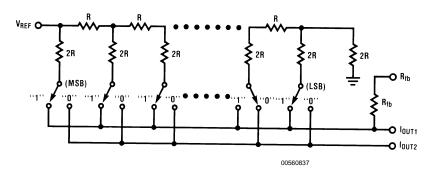
The inverting input of the op amp is a "virtual ground" created by the feedback from its output through the internal 15 k Ω resistor, $R_{\rm fb}$. All of the output current (determined by the digital input and the reference voltage) will flow through $R_{\rm fb}$ to the output of the amplifier. Two-quadrant operation can be obtained by reversing the polarity of $V_{\rm REF}$ thus causing $I_{\rm OUT1}$ to flow into the DAC and be sourced from the output of the amplifier. The output voltage, in either case, is always equal to $I_{\rm OUT1}xR_{\rm fb}$ and is the opposite polarity of the reference voltage.

The reference can be either a stable DC voltage source or an AC signal anywhere in the range from -10V to +10V. The DAC can be thought of as a digitally controlled attenuator: the output voltage is always less than or equal to the applied reference voltage. The V_{REF} terminal of the device presents a nominal impedance of 15 k Ω to ground to external circuitry.

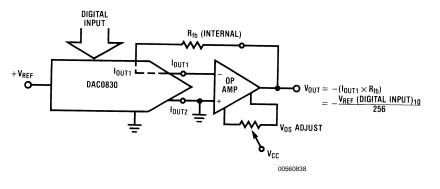
DAC0830 Series Application Hints

(Continued)

Always use the internal $R_{\rm fb}$ resistor to create an output voltage since this resistor matches (and tracks with temperature) the value of the resistors used to generate the output current (I_{OUT1}).









2.3 Op Amp Considerations

The op amp used in *Figure 7* should have offset voltage nulling capability (See Section 2.5).

The selected op amp should have as low a value of input bias current as possible. The product of the bias current times the feedback resistance creates an output voltage error which can be significant in low reference voltage applications. BI-FET[™] op amps are highly recommended for use with these DACs because of their very low input current.

Transient response and settling time of the op amp are important in fast data throughput applications. The largest stability problem is the feedback pole created by the feedback resistance, R_{fb} , and the output capacitance of the DAC. This appears from the op amp output to the (–) input and includes the stray capacitance at this node. Addition of a lead capacitance, C_C in *Figure 8*, greatly reduces overshoot and ringing at the output for a step change in DAC output current.

Finally, the output voltage swing of the amplifier must be greater than V_{REF} to allow reaching the full scale output voltage. Depending on the loading on the output of the amplifier and the available op amp supply voltages (only ±12 volts in many development systems), a reference voltage less than 10 volts may be necessary to obtain the full analog output voltage range.

2.4 Bipolar Output Voltage with a Fixed Reference

The addition of a second op amp to the previous circuitry can be used to generate a bipolar output voltage from a fixed reference voltage. This, in effect, gives sign significance to the MSB of the digital input word and allows two-quadrant multiplication of the reference voltage. The polarity of the reference can also be reversed to realize full 4-quadrant multiplication: $\pm V_{\text{REF}} x \pm \text{Digital Code} = \pm V_{\text{OUT}}$. This circuit is shown in *Figure 9*.

This configuration features several improvements over existing circuits for bipolar outputs with other multiplying DACs. Only the offset voltage of amplifier 1 has to be nulled to preserve linearity of the DAC. The offset voltage error of the second op amp (although a constant output voltage error) has no effect on linearity. It should be nulled only if absolute output accuracy is required. Finally, the values of the resistors around the second amplifier do not have to match the internal DAC resistors, they need only to match and temperature track each other. A thin film 4-resistor network available from Beckman Instruments, Inc. (part no. 694-3-R10K-D) is ideally suited for this application. These resistors are matched to 0.1% and exhibit only 5 ppm/°C resistance tracking temperature coefficient. Two of the four available 10 k Ω resistors can be paralleled to form R in Figure 9 and the other two can be used independently as the resistances labeled 2R.

DAC0830 Series Application Hints

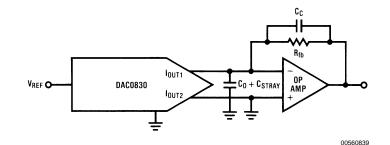
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2.5 Zero Adjustment

For accurate conversions, the input offset voltage of the output amplifier must always be nulled. Amplifier offset errors create an overall degradation of DAC linearity.

The fundamental purpose of zeroing is to make the voltage appearing at the DAC outputs as near $0V_{\rm DC}$ as possible.

This is accomplished for the typical DAC — op amp connection (*Figure 7*) by shorting out R_{fb}, the amplifier feedback resistor, and adjusting the V_{OS} nulling potentiometer of the op amp until the output reads zero volts. This is done, of course, with an applied digital code of all zeros if I_{OUT1} is driving the op amp (all one's for I_{OUT2}). The short around R_{fb} is then removed and the converter is zero adjusted.



 ts

 OP Amp
 Cc
 (O to Full Scale)

 LF356
 22 pF
 4 μs

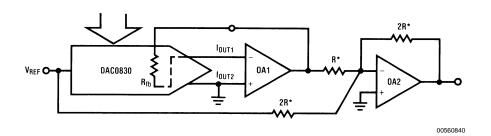
 LF351
 22 pF
 5 μs

 LF357*
 10 pF
 2 μs

*2.4 $k\Omega$ RESISTOR ADDED FROM-INPUT TO GROUND TO INSURE STABILITY

FIGURE 8.

DAC0830 Series Application Hints (Continued)





 $1 \text{ LSB} = \frac{|V_{\text{REF}}|}{128}$

		Ir	nput	t Co	de			IDEAL V _{OUT}						
Μ	SB					L	SB	+V _{REF}	–V _{REF}					
1	1	1	1	1	1	1	1	V _{REF} -1 LSB	- V _{REF} +1 LSB					
1	1	0	0	0	0	0	0	V _{REF} /2	- V _{REF} /2					
1	0	0	0	0	0	0	0	0	0					
0	1	1	1	1	1	1	1		+1 LSB $ V_{REF} $ + 1 LSP					
0	0	1	1	1	1	1	1	$-\frac{ V_{REF} }{2}$ - 1 LSB	2+1 LSB					
0	0	0	0	0	0	0	0	$- V_{REF} $	$+ V_{REF} $					

*THESE RESISTORS ARE AVAILABLE FROM BECKMAN INSTRUMENTS, INC. AS THEIR PART NO. 694-3-R10K-D

FIGURE 9.

2.6 Full-Scale Adjustment

In the case where the matching of R_{fb} to the R value of the R-2R ladder (typically ±0.2%) is insufficient for full-scale accuracy in a particular application, the V_{REF} voltage can be adjusted or an external resistor and potentiometer can be added as shown in *Figure 10* to provide a full-scale adjustment.

The temperature coefficients of the resistors used for this adjustment are of an important concern. To prevent degradation of the gain error temperature coefficient by the external resistors, their temperature coefficients ideally would have to match that of the internal DAC resistors, which is a highly impractical constraint. For the values shown in *Figure 10*, if the resistor and the potentiometer each had a temperature coefficient of ± 100 ppm/°C maximum, the overall gain

error temperature coefficent would be degraded a maximum of 0.0025%/°C for an adjustment pot setting of less than 3% of $\rm R_{fb}.$

2.7 Using the DAC0830 in a Voltage Switching Configuration

The R-2R ladder can also be operated as a voltage switching network. In this mode the ladder is used in an inverted manner from the standard current switching configuration. The reference voltage is connected to one of the current output terminals (I_{OUT1} for true binary digital control, I_{OUT2} is for complementary binary) and the output voltage is taken from the normal V_{REF} pin. The converter output is now a voltage in the range from 0V to 255/256 V_{REF} as a function of the applied digital code as shown in *Figure 11*.

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DAC0830/DAC0832

DAC0830 Series Application Hints (Continued)

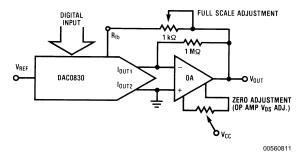
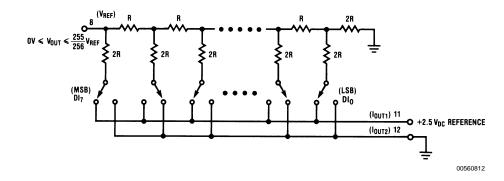


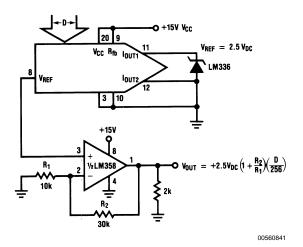
FIGURE 10. Adding Full-Scale Adjustment





This configuration offers several useful application advantages. Since the output is a voltage, an external op amp is not necessarily required but the output impedance of the DAC is fairly high (equal to the specified reference input resistance of 10 k Ω to 20 k Ω) so an op amp may be used for buffering purposes. Some of the advantages of this mode are illustrated in *Figures 12, 13, 14, 15*.

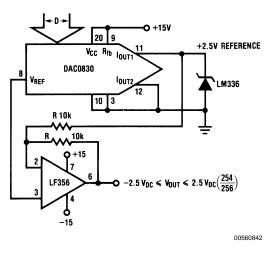
There are two important things to keep in mind when using this DAC in the voltage switching mode. The applied reference voltage must be positive since there are internal parasitic diodes from ground to the I_{OUT1} and I_{OUT2} terminals which would turn on if the applied reference went negative. There is also a dependence of conversion linearity and gain error on the voltage difference between $V_{\rm CC}$ and the voltage applied to the normal current output terminals. This is a result of the voltage drive requirements of the ladder switches. To ensure that all 8 switches turn on sufficiently (so as not to add significant resistance to any leg of the ladder and thereby introduce additional linearity and gain errors) it is recommended that the applied reference voltage be kept less than +5V_{DC} and V_{CC} be at least 9V more positive than $V_{\text{REF}}.$ These restrictions ensure less than 0.1% linearity and gain error change. Figures 16, 17, 18 characterize the effects of bringing V_{REF} and V_{CC} closer together as well as typical temperature performance of this voltage switching configuration.



- Voltage switching mode eliminates output signal inversion and therefore a need for a negative power supply.
- Zero code output voltage is limited by the low level output saturation voltage of the op amp. The 2 kΩ pull-down resistor helps to reduce this voltage.
- V_{OS} of the op amp has no effect on DAC linearity.

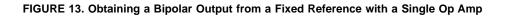
FIGURE 12. Single Supply DAC

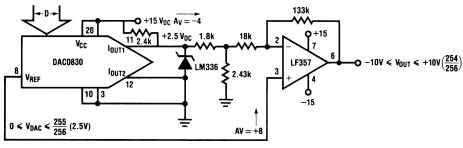
DAC0830 Series Application Hints (Continued)



•
$$V_{OUT} = 2.5V \left(\frac{D}{128} - 1\right)$$

 \bullet Slewing and settling time for a full scale output change is \approx 1.8 μs



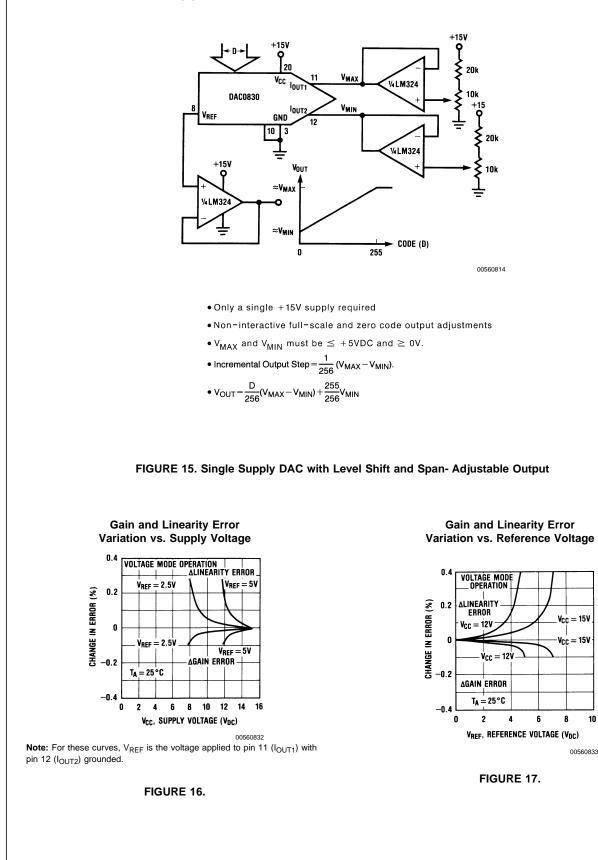


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FIGURE 14. Bipolar Output with Increased Output Voltage Swing

DAC0830 Series Application Hints (Continued)

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DAC0830 Series Application Hints

(Continued)

Gain and Linearity Error Variation vs. Temperature

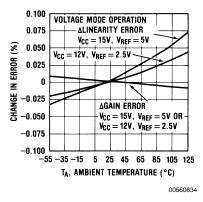


FIGURE 18.

2.8 Miscellaneous Application Hints

These converters are CMOS products and reasonable care should be exercised in handling them to prevent catastrophic failures due to static discharge.

Conversion accuracy is only as good as the applied reference voltage so providing a stable source over time and temperature changes is an important factor to consider.

A "good" ground is most desirable. A single point ground distribution technique for analog signals and supply returns keeps other devices in a system from affecting the output of the DACs.

During power-up supply voltage sequencing, the –15V (or –12V) supply of the op amp may appear first. This will cause the output of the op amp to bias near the negative supply potential. No harm is done to the DAC, however, as the on-chip 15 k Ω feedback resistor sufficiently limits the current flow from I_{OUT1} when this lead is internally clamped to one diode drop below ground.

Careful circuit construction with minimization of lead lengths around the analog circuitry, is a primary concern. Good high frequency supply decoupling will aid in preventing inadvertant noise from appearing on the analog output.

Overall noise reduction and reference stability is of particular concern when using the higher accuracy versions, the DAC0830 and DAC0831, or their advantages are wasted.

3.0 GENERAL APPLICATION IDEAS

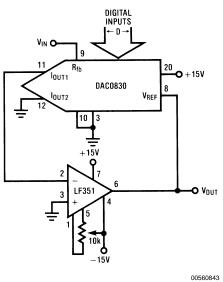
The connections for the control pins of the digital input registers are purposely omitted. Any of the control formats discussed in Section 1 of the accompanying text will work with any of the circuits shown. The method used depends on the overall system provisions and requirements.

The digital input code is referred to as D and represents the decimal equivalent value of the 8-bit binary input, for example:

		В	inary	/ Inpi			D	
Pin	13					Pin 7		Decimal
M	SB					LS	6B	Equivalent
1	1	1	1	1	1	1	1	255
1	0	0	0	0	0	0	0	128
0	0	0	1	0	0	0	0	16
0	0	0	0	0	0	1	0	2
0	0	0	0	0	0	0	0	0

Applications



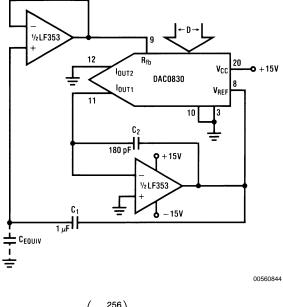


• $V_{OUT} = \frac{-V_{IN} (256)}{D}$

- When D=0, the amplifier will go open loop and the output will saturate.
- Feedback impedance from the -input to the output varies from 15 k Ω to ∞ as the input code changes from full-scale to zero.

Applications (Continued)

Capacitance Multiplier



$$C_{EQUIV} = C_1 \left(1 + \frac{256}{D} \right)$$

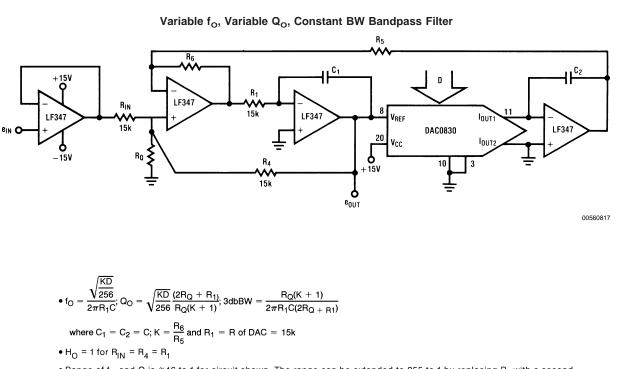
• Maximum voltage across the equivalent capacitance is

limited to
$$\frac{V_{O MAX} \text{ (op amp)}}{1 + \frac{256}{D}}$$

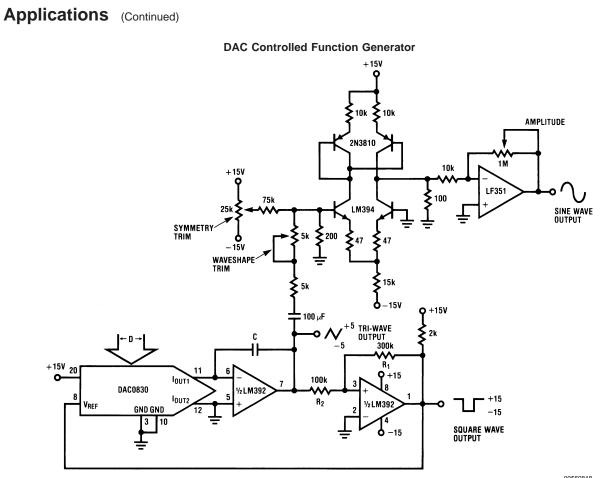
 \bullet C2 is used to improve settling time of op amp.

Applications (Continued)

DAC0830/DAC0832



- Range of f_0 and Q is \approx 16 to 1 for circuit shown. The range can be extended to 255 to 1 by replacing R_1 with a second DAC0830 driven by the same digital input word.
- Maximum $f_{O}x$ Q product should be \leq 200 kHz.



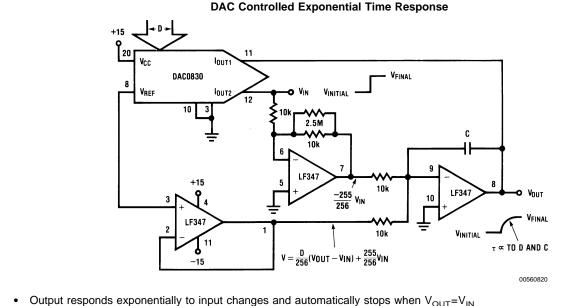
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- DAC controls the frequency of sine, square, and triangle outputs.
- f = $\frac{D}{256(20k)C}$ for V_{OMAX} = V_{OMIN} of square wave output and R₁ = 3 R₂.
- 255 to 1 linear frequency range; oscillator stops with D = 0
- Trim symmetry and wave-shape for minimum sine wave distortion.

DAC0830/DAC0832

Applications (Continued) Two Terminal Floating 4 to 20 mA Current Loop Controller INPUT IN4001 LM334 **20**Ω 39k ~ 50 **500**Ω Vcc IOUT 19 LM10 DAC0830 92PE37B ILE OP AME LM329D Толта VREF GND GND 3 10 LM329D REI 500k R₃ 10Ω R2 10k 2500 150 M 10 REF AM $4 \text{ mA} \leq I_{\text{OUT}} \leq 20 \text{ mA}$ P2 00560819 $I_{OUT} = V_{REF} \left[\frac{1}{R_1} + \frac{D}{256 R_{fb}} \right] \left[1 + \frac{R_2}{R_3} \right]$ DAC0830 linearly controls the current flow from the input terminal to the output terminal to be 4 mA (for D=0) to 19.94 mA (for ٠ D=255).

- Circuit operates with a terminal voltage differential of 16V to 55V.
- P_2 adjusts the magnitude of the output current and P_1 adjusts the zero to full scale range of output current.
- Digital inputs can be supplied from a processor using opto isolators on each input or the DAC latches can flow-through (connect control lines to pins 3 and 10 of the DAC) and the input data can be set by SPST toggle switches to ground (pins 3 and 10).



Output responds exponentially to input changes and automatically stops when $V_{OUT} = V_{IN}$

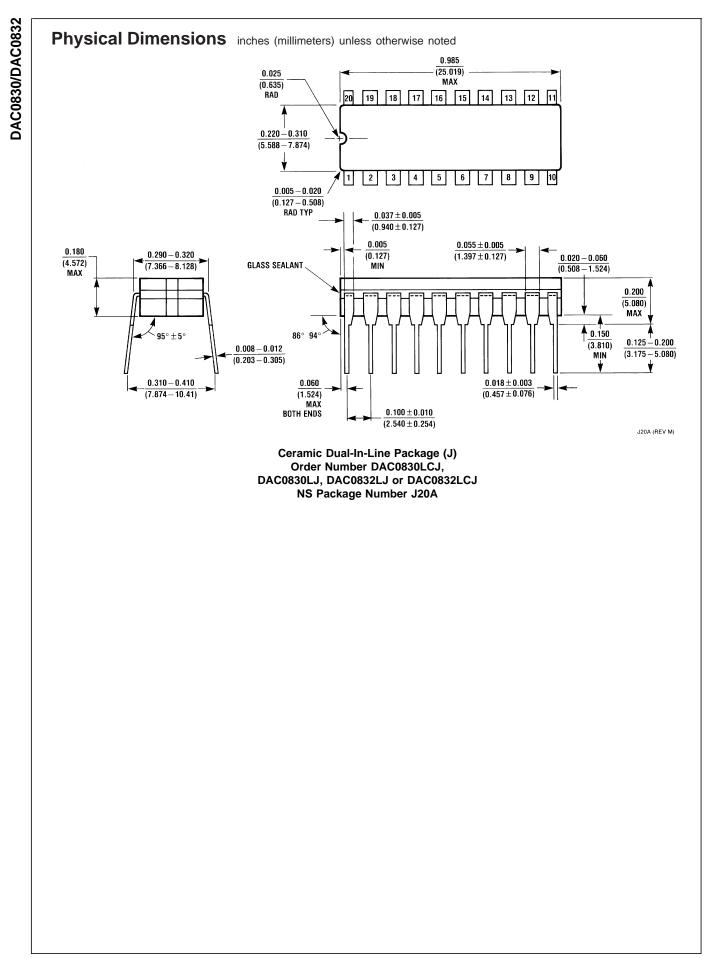
Applications (Continued)

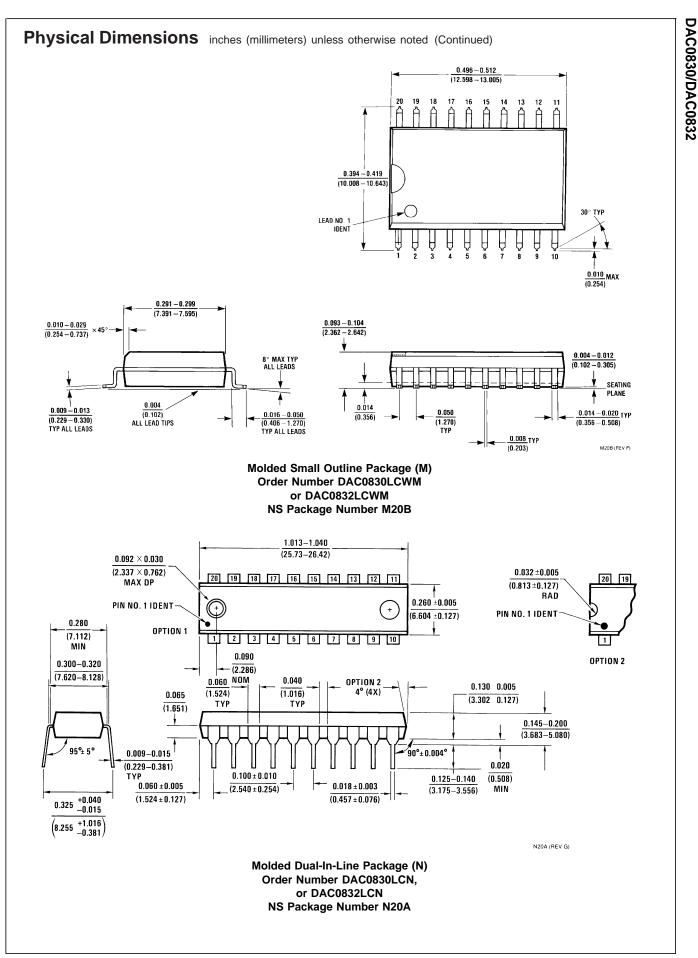
- Output time constant is directly proportional to the DAC input code and capacitor C
- Input voltage must be positive (See section 2.7)

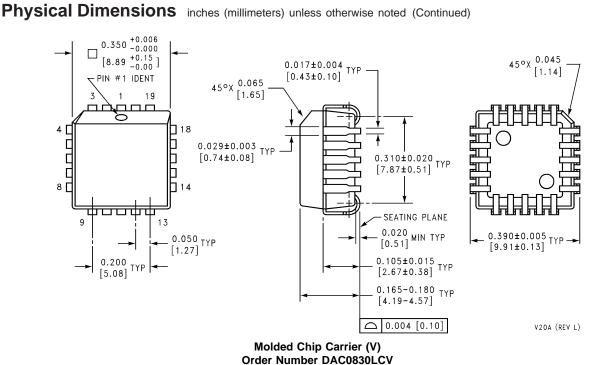
Ordering Information

Temperat	ure Range		0°C to +70°	–40°C to +85°C	–55°C to +125°C	
Non	0.05%	DAC0830LCN	DAC0830LCWM	DAC0830LCV	DAC0830LCJ	DAC0830LJ
NOIT	FSR					
Linearity	0.1% FSR	DAC0831LCN				
	0.2% FSR	DAC0832LCN	DAC0832LCWM	DAC0832LCV	DAC0832LCJ	DAC0832LJ
Package	e Outline	N20A—Molded	M20B Small Outline	V20A Chip Carrier	J20A—C	eramic DIP
		DIP				

DAC0830/DAC0832







Order Number DAC0830LCV or DAC0832LCV NS Package Number V20A

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