# Grove - 3-Axis Digital Accelerometer 200g (ADXL372)



#### You can find a variety of 3-axis accelerometers

[https://www.seeedstudio.com/tag/accelerometer.html] on our website that can meet different scenarios and needs. This time, we bring you the industrial grade, high stability, high precision and low power ADI ADXL series three-axis accelerometers.

## The Grove - 3-Axis Digital Accelerometer ±200g (ADXL372) is a ultralow power digital output MEMS

[https://www.seeedstudio.com/tag/MEMS.html] Accelerometer, it can provide a 12-bit output at 100 mg/LSB scale factor. The most notable feature of this sensor is its ultra-low power consumption(only 22µA in measurment mode) and large measurement range(±200g). All the data output via the Grove I2C port, the I2C address is changeable. In order to meet a wider range of measurement needs, the sampling rate can be selected from 400Hz/800Hz/1600Hz/3200Hz/6400Hz, and the bandwidth can be selected from 200Hz/400Hz/800Hz/1600Hz/3200Hz. In addition to being used as an acceleration measurement, you can also use this module to do impact and shock detection.

The ADI ADXL Series Accelerometer includes four products that will meet your different range and output needs:

Product	Measurement Range	Output Port	Pov Con
Grove - 3-Axis Analog Accelerometer ±20g (ADXL356B) [https://www.seeedstudio.com/Grove- 3-Axis-Analog-Accelerometer-20g- ADXL356B-p-4004.html]	±10 ±20g	Analog	mea moo star moo
Grove - 3-Axis Analog Accelerometer ±40g (ADXL356C) [https://www.seeedstudio.com/Grove- 3-Axis-Analog-Accelerometer-40g- ADXL356C-p-4006.html]	±10g ±40g	Analog	mea moo star moo
Grove - 3-Axis Digital Accelerometer ±40g (ADXL357) [https://www.seeedstudio.com/Grove- 3-Axis-Digital-Accelerometer-40g- ADXL357-p-4005.html]	±10g@51200 LSB/g ±20g@25600 LSB/g ±40g@12800 LSB/g	Digital I2C	mea moo
Grove - 3-Axis Digital Accelerometer ±200g (ADXL372) [https://www.seeedstudio.com/Grove- 3-Axis-Digital-Accelerometer-200g- ADXL372-p-4003.html]	±200g	Digital I2C	mea mou

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## Get One Now 📜

[https://www.seeedstudio.com/Grove-3-Axis-Digital-Accelerometer-200g-ADXL372-p-4003.html]

### Features

- Large measuring range: ±200g
- Ultralow power consumption: 22 µA at 3200 Hz ODR
- Selectable oversampling ratio and bandwidth
- Deep embedded FIFO to minimize host processor load
- Build-in 12-bit analog-to-digital converter (ADC)

## APPLICATIONS

- Portable Internet of Things (IoT) edge nodes
- Concussion and head trauma detection
- Impact and shock detection
- Asset health assessment

## Pinout





## Specification

Parameter	Value
Supply voltage	3.3V / 5V
Operating ambient temperature	-40 – 125°C
Sensitivity at $X_{OUT}$ , $Y_{OUT}$ , $Z_{OUT}$ (Ratiometric to $V_{1P8ANA}$ )	±50mg/°C(Nowmal Operation.) ±35mg/°C(Low Noise Mode.)
Sensitivity Change due to Temperature	±0.01%/°C (TA = -40°C to +125°C)
0g OFFSET	±1g(.Typ)
Output interface	Digital

## Platforms Supported



In addition, you can consider our new Seeeduino Lotus M0+ [https://www.seeedstudio.com/Seeeduino-Lotus-Cortex-M0-p-2896.html], which is equivalent to the combination of Seeeduino V4.2 and Baseshield.

#### Note

1 Please plug the USB cable gently, otherwise you may damage the port. Please use the USB cable with 4 wires inside, the 2 wires cable can't transfer data. If you are not sure about the wire you have, you can click here [https://www.seeedstudio.com/Micro-USB-Cable-48cm-p-1475.html] to buy

**2** Each Grove module comes with a Grove cable when you buy. In case you lose the Grove cable, you can click here

[https://www.seeedstudio.com/Grove-Universal-4-Pin-Buckled-20cm-Cable-%285-PCs-pack%29-p-936.html] to buy.

#### **Hardware Connection**

- Step 1. Connect the Grove 3-Axis Analog Accelerometer ±200g (ADXL372) to the l2c port of the Base Shield.
- Step 2. Plug Grove Base Shield into Seeeduino.
- **Step 3.** Connect Seeeduino to PC via a USB cable.



#### Software

#### Attention If this is the first time you work with Arduino, we strongly recommend you to see Getting Started with Arduino [https://wiki.seeedstudio.com/Getting\_Started\_with\_Arduino/] before the start.

- Step 1. Download the Seeed\_ADXL\_372 library [https://github.com/Seeed-Studio/Accelerometer\_ADXL372] from Github.
- Step 2. Refer to How to install library
   [https://github.com/Seeed Studio/Multi\_Channel\_Relay\_Arduino\_Library] to install library
   for Arduino.



```
1
2
3
    #include "Wire.h"
    #include "adx1372.h"
4
5
    #ifdef ARDUINO SAMD VARIANT COMPLIANCE
6
      #define SERIAL SERIALUSB
7
8
      #define SYS VOL
                         3.3
9
    #else
      #define SERIAL Serial
10
      #define SYS VOL
11
    #endif
12
13
14
15
    float cali data[3];
16
17
    #define CALI BUF LEN
                                     15
    #define CALI_INTERVAL_TIME
18
                                     250
19
20
    float cali_buf[3][CALI_BUF_LEN];
21
```

https://wiki.seeedstudio.com/Grove-3-Axis\_Digital\_Accelerometer\_200g-ADXL372/

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```
22
23
    ADXL372 acc;
24
    xyz_t xyz;
25
26
    float deal_cali_buf(float *buf)
27
28
         float cali val = 0;
29
30
         for(int i = 0;i < CALI_BUF_LEN;i++)</pre>
31
32
             cali_val += buf[i];
33
34
         cali_val = cali_val/CALI_BUF_LEN;
         return (float)cali val;
35
36
37
38
39
    void calibration(void)
40
41
         SERIAL.println("Please Place the module horizontall
42
         delay(1000);
         SERIAL.println("Start calibration.....");
43
44
45
46
         for(int i=0;i<CALI BUF LEN;i++)</pre>
47
             while (!(acc.status() & DATA_READY));
48
49
             acc.read(&xyz);
50
             cali buf[0][i] = xyz.x;
             cali buf[1][i] = xyz.y;
51
             cali_buf[2][i] = xyz.z;
52
             delay(CALI INTERVAL TIME);
53
54
             SERIAL.print('.');
55
         SERIAL.println('.');
56
        for(int i=0;i<3;i++)</pre>
57
58
             cali_data[i] = deal_cali_buf(cali_buf[i]);
59
             if(2 == i){
60
61
                 cali_data[i] -= 10;
62
```

```
63
64
             SERIAL.println(cali data[i]);
65
         SERIAL.println("Calibration OK!!");
66
67
68
69
70
     void setup() {
71
       SERIAL.begin(115200);
72
73
       acc.begin();
74
75
       SERIAL.println(acc.id(), HEX);
       acc.timing ctrl(RATE 400);
76
77
       acc.measurement_ctrl(BW_200, true);
78
      acc.power ctrl(MEASUREMENT MODE);
79
       acc.setActiveTime(10);
80
81
       calibration();
82
83
84
     void loop() {
       if (acc.status() & DATA READY) {
85
         acc.read(&xyz);
86
         SERIAL.print("X position acc = ");
87
         SERIAL.print((xyz.x - cali_data[0]) / 10.0);
88
         SERIAL.println(" g ");
89
         SERIAL.print("Y position acc = ");
90
         SERIAL.print((xyz.y - cali_data[1]) / 10.0);
91
         SERIAL.println(" g ");
92
         SERIAL.print("Z position acc = ");
93
         SERIAL.print((xyz.z - cali_data[2]) / 10.0);
94
         SERIAL.println(" mg ");
95
96
       SERIAL.println("
97
                          ");
       SERIAL.println(" ");
98
       delay(1000);
99
100
```

- Step 4. Upload the demo. If you do not know how to upload the code, please check How to upload code
   [https://wiki.seeedstudio.com/Upload\_Code/].
- Step 5. Open the Serial Monitor of Arduino IDE by click Tool-> Serial Monitor. Or tap the Ctrl+Shift+M key at the same time. Set the baud rate to 115200.
- **Step 6. Calibration** wait for calibration, just few seconds the calibration will be finished
- **Step 7.** Now you can use this sensor, and the output will be like this:



## Schematic Online Viewer

#### Resources

 [ZIP] Grove-3-Axis\_Digital\_Accelerometer-200g-ADXL372
 Schematic file [https://files.seeedstudio.com/wiki/Grove-3-Axis\_Digital\_Accelerometer-200g-ADXL372/res/Grove%20-%203 Axis%20Digital%20Accelerometer%20%C2%B1200g%20(ADXL3 72).zip]

#### • [PDF] ADXL 372 Datasheet

[https://files.seeedstudio.com/wiki/Grove-3-Axis\_Digital\_Accelerometer-200g-ADXL372/res/Grove%20-%203-

Axis%20Digital%20Accelerometer%20%C2%B1200g%20(ADXL3 72).zip]

## Tech Support

#### Please submit any technical issue into our forum

[https://forum.seeedstudio.com/]



[https://www.seeedstudio.com/act-4.html? utm\_source=wiki&utm\_medium=wikibanner&utm\_campaign=newpr oducts]